

# Comparative Analysis of Neural Video Super-Resolution Methods for Object Detection on Mobile Devices

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Mai Elshazly

mai.elshazly@stud.uni-goettingen.de

Supervisors: Prof. Dr. Xiaoming Fu, Dr. Tingting Yuan & Dr. Weijun Wang

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# Relevant Background

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- Adding more pixels to an image to enhance its quality is called **Super-Resolution (SR)**.
- We refer to quality by the vertical number of pixels (i.e. height) of an image.
- Neural super-resolution uses a **Deep Neural Network (DNN)** to achieve improved quality.
- Applying neural super-resolution to every frame of a video is called **Per-Frame Super-Resolution (Per-Frame SR)**.

Quality
1080p <sup>HD</sup>
720p
480p
360p
240p
144p

Size: 240p



Chunk0000 – Frame 0000



Size: 2160p



Chunk0000 – Frame 0000

# Related Work

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Some advances in enhancing video streaming using neural SR:

- M. Dasari, A. Bhattacharya, S. Vargas, P. Sahu, A. Balasubramanian, and S. R. Das. 2020. Streaming 360° Videos using Super-resolution. In Proceedings of the IEEE International Conference on Computer Communications (INFOCOM).
- Pan Hu, Rakesh Misra, and Sachin Katti. 2019. Dejavu: Enhancing Videoconferencing with Prior Knowledge. In Proceedings of the 20th International Workshop on Mobile Computing Systems and Applications. ACM, 63-68.
- Hyunho Yeo, Youngmok Jung, Jaehong Kim, Jinwoo Shin, and Dongsu Han. 2018. Neural adaptive content-aware internet video delivery. In 13th {USENIX } Symposium on Operating Systems Design and Implementation ( {OSDI } 18). 645- 661.
- **H. Yeo, C. J. Chong, Y. Jung, J. Ye and D. Han, "NEMO: Enabling neural-enhanced video streaming on commodity mobile devices", Proc. 26th Annu. Int. Conf. Mobile Comput. Netw. (MobiCom), pp. 1-14, 2020.**

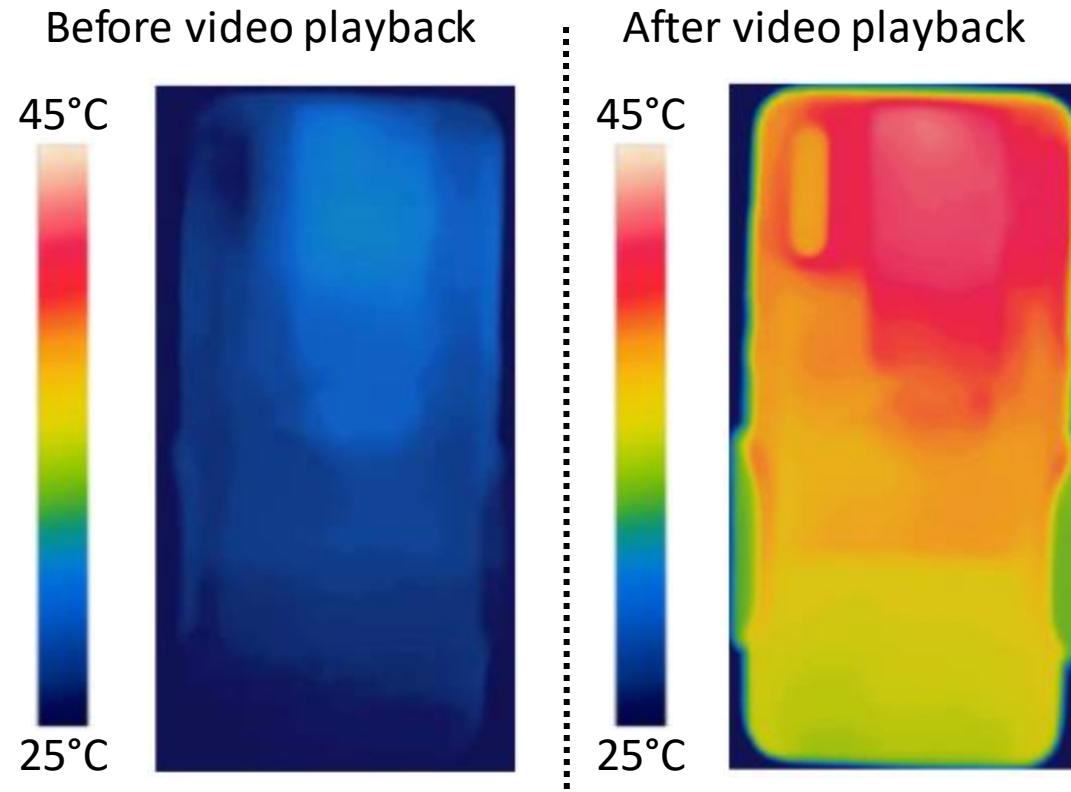
# Motivation

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- Smartphone/tablet video streaming accounts for 62% of viewership, and mobile devices account for more than 70% of YouTube video consumption\*.
- Neural SR relies on client-side computation\*, which makes per-frame SR impractical on mobile devices.
- Per-frame SR causes bad experiences for mobile users also due to high battery consumption and rise in device temperature.

\* H. Yeo, C. J. Chong, Y. Jung, J. Ye and D. Han, "NEMO: Enabling neural-enhanced video streaming on commodity mobile devices", *Proc. 26th Annu. Int. Conf. Mobile Comput. Netw. (MobiCom)*, pp. 1-14, 2020.

## Infrared thermal images of heat dissipation on a smartphone caused by per-frame DNN inference<sup>\*</sup>

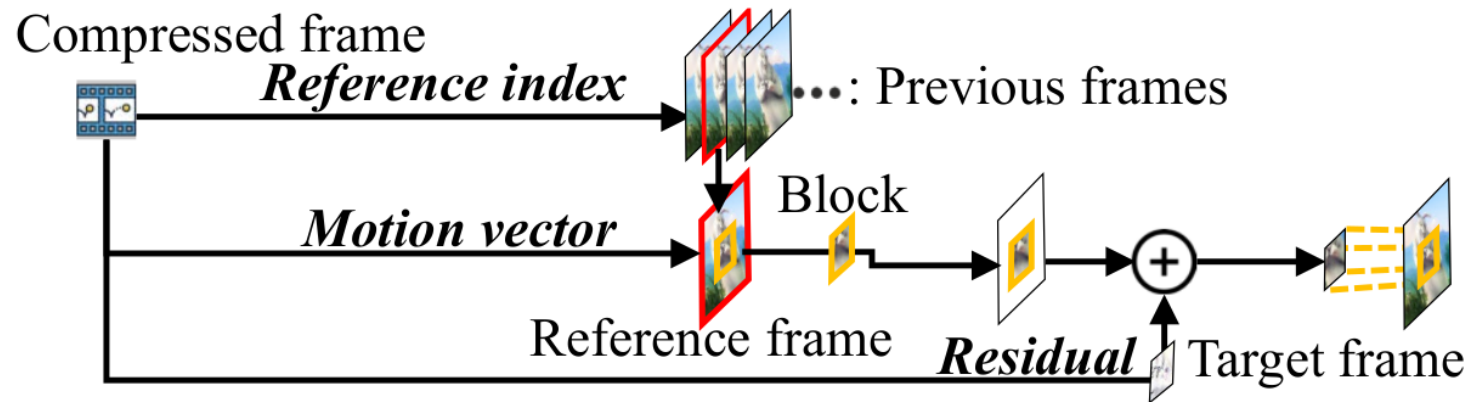


<sup>\*</sup> H. Yeo, C. J. Chong, Y. Jung, J. Ye and D. Han, "NEMO: Enabling neural-enhanced video streaming on commodity mobile devices", *Proc. 26th Annu. Int. Conf. Mobile Comput. Netw. (MobiCom)*, pp. 1-14, 2020.

# NEMO – Neural-Enhanced Video Streaming on Mobile Devices

- NEMO selects only a few frames for neural SR; these frames are called **Anchor Points (APs)** while other frames are called **Non-Anchor Points**.
- NEMO uses a codec to get dependencies among frames so that non-APs benefit from APs.

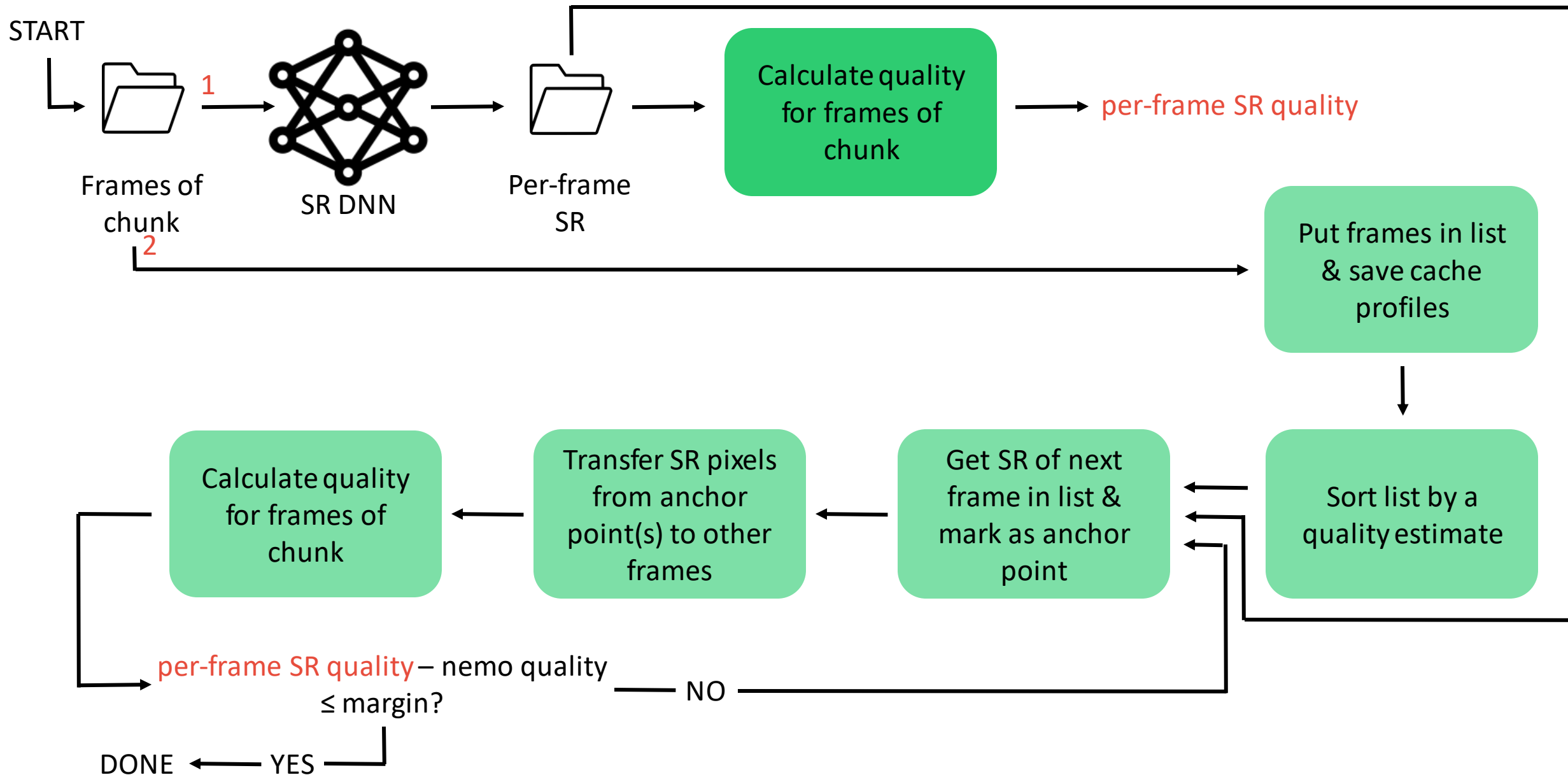
Frame dependencies processed in a codec\*



\* H. Yeo, C. J. Chong, Y. Jung, J. Ye and D. Han, "NEMO: Enabling neural-enhanced video streaming on commodity mobile devices", *Proc. 26th Annu. Int. Conf. Mobile Comput. Netw. (MobiCom)*, pp. 1-14, 2020.



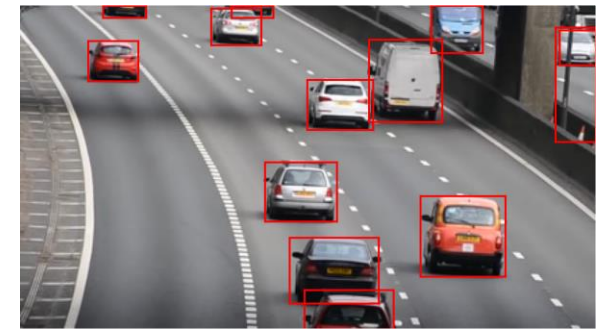
# Anchor Point Selection in a Video Chunk in NEMO



# Introduction to this Research Project

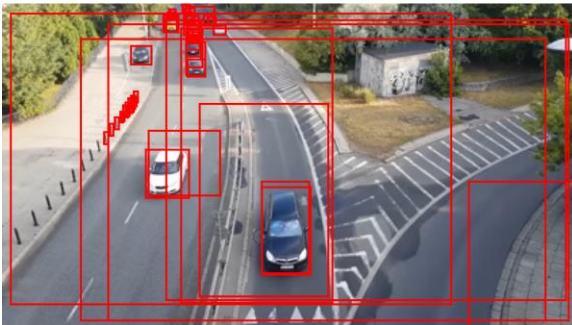
- **Objective:** Creation of ground truth bounding boxes (BBs) from upscaled video on mobile devices for further object detection.
- **Target Metrics:**
  - SR DNN time required (seconds)
  - Accuracy against per-frame SR (f1-score)
- **Questions to investigate:**
  - Can NEMO achieve the objective?
  - Does **applying SR DNN only to objects in APs (per-bb SR)** instead of complete APs achieve the objective with shorter time?
  - How about investigating only small objects in APs? What are small objects?

Chunk0009 – Frame 0059



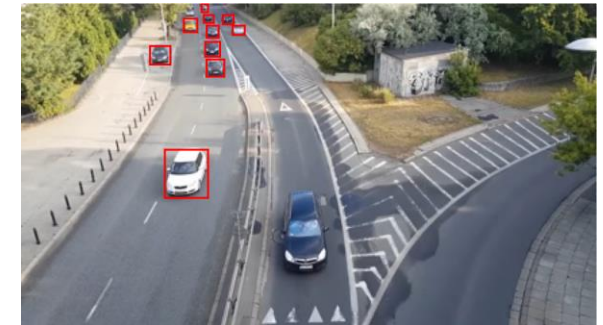
# Object Detector

- Faster R-CNN with ResNet50 pretrained on COCO as backbone (weights found on Kaggle\*).
- Can detect:
  - **Vehicle** – car, bus, train, truck
  - **Persons** – person, bicycle, motorcycle
  - **Roadside-objects** – traffic light, fire hydrant, stop sign, parking meter



Chunk0020 – Frame 0022

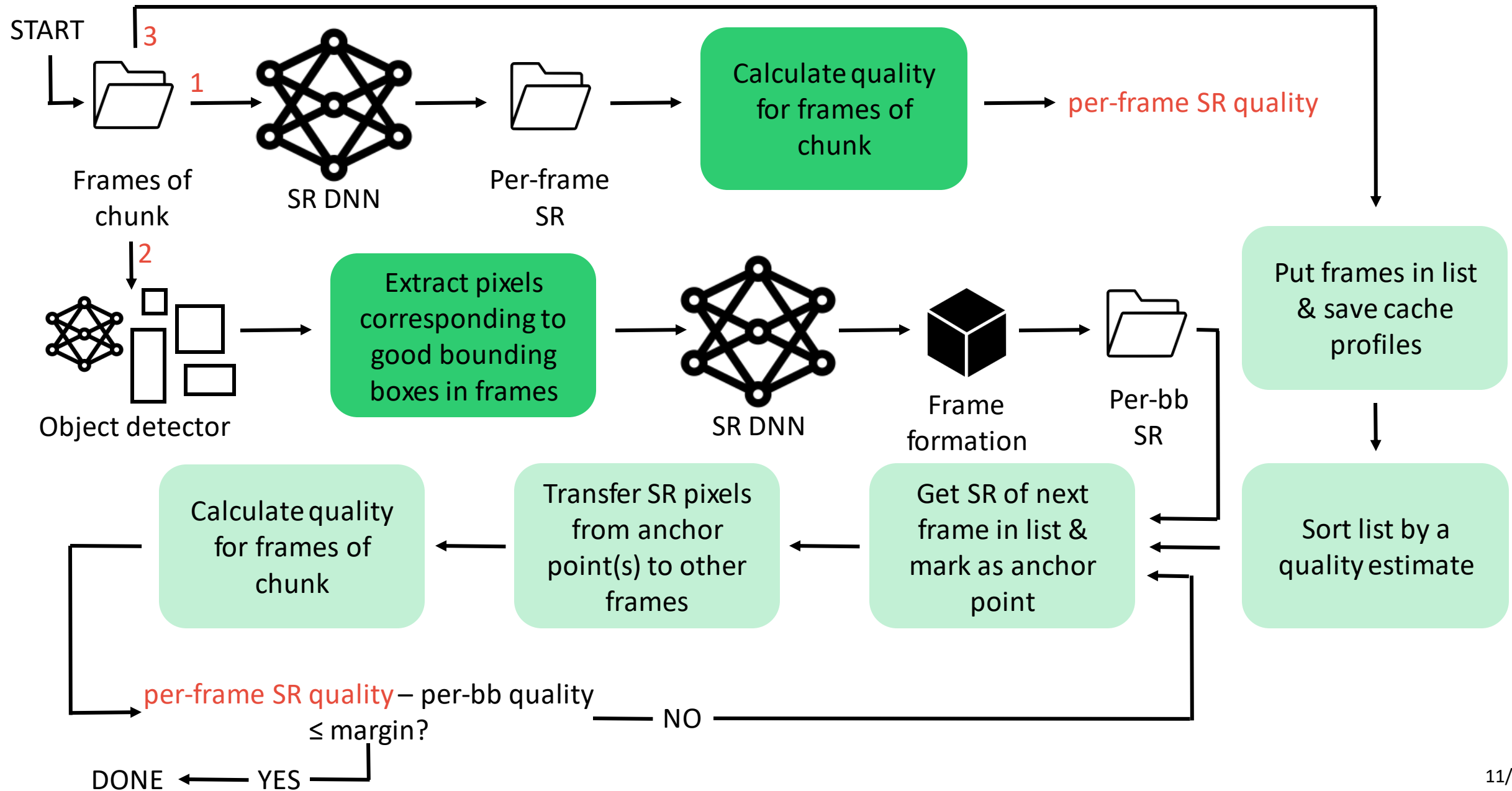
Filter with BBs with 50% confidence



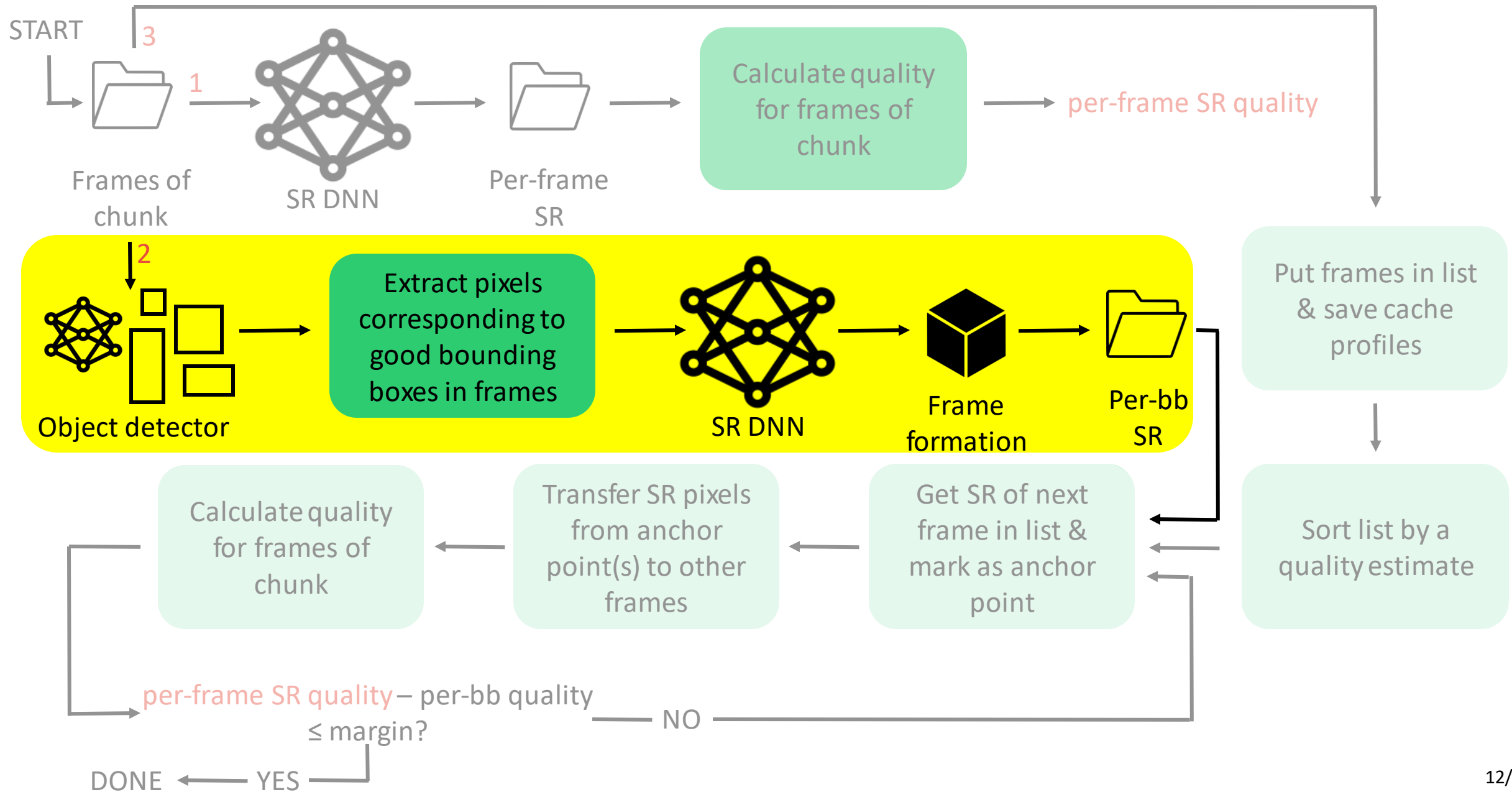
Chunk0020 – Frame 0022

\* <https://www.kaggle.com/datasets/n1t1nk/fasterrcnn-resnet50-fpn-coco?resource=download>

# Anchor Point Selection in a Video Chunk in Our Method

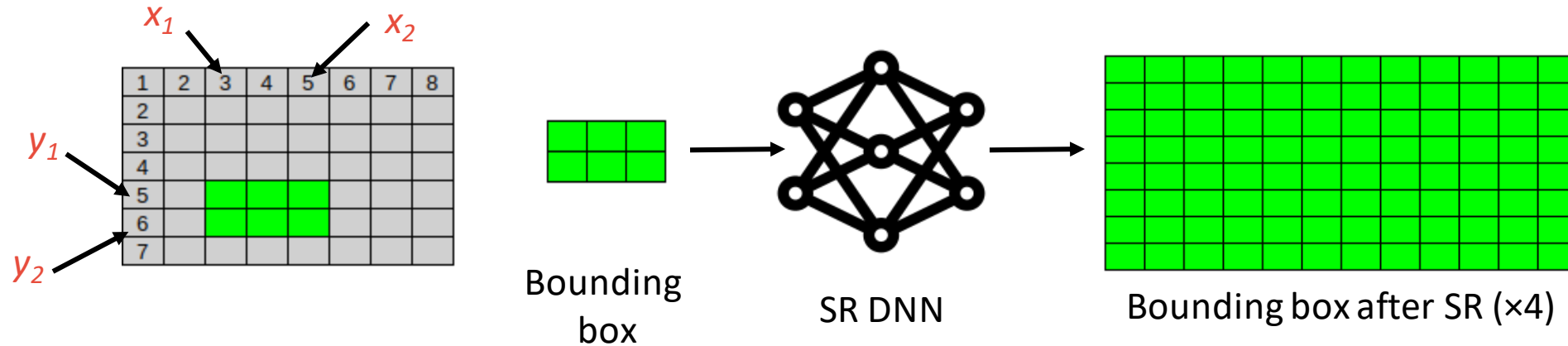


# Anchor Point Selection in a Video Chunk in Our Method





# Frame Formation as a Tensor



**0-based indices of BB in upscaled tensor:**

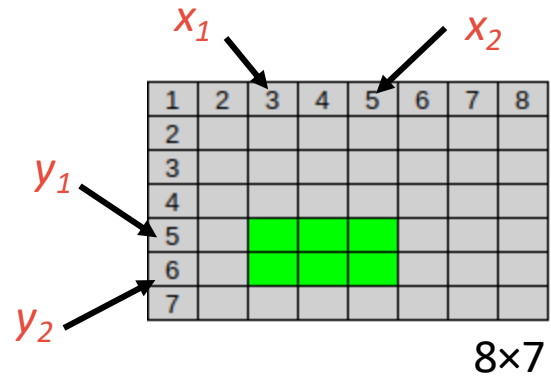
$$\begin{aligned} r_1 &= (y_1 - 1) \times scale \\ &= (5 - 1) \times 4 = 16 \end{aligned}$$

$$\begin{aligned} r_2 &= r_1 - 1 + ((y_2 - y_1 + 1) \times scale) \\ &= 16 - 1 + ((6 - 5 + 1) \times 4) = 23 \end{aligned}$$

$$\begin{aligned} c_1 &= (x_1 - 1) \times scale \\ &= (3 - 1) \times 4 = 8 \end{aligned}$$

$$\begin{aligned} c_2 &= c_1 - 1 + ((x_2 - x_1 + 1) \times scale) \\ &= 8 - 1 + ((5 - 3 + 1) \times 4) = 19 \end{aligned}$$

# Frame Formation as a Tensor continue



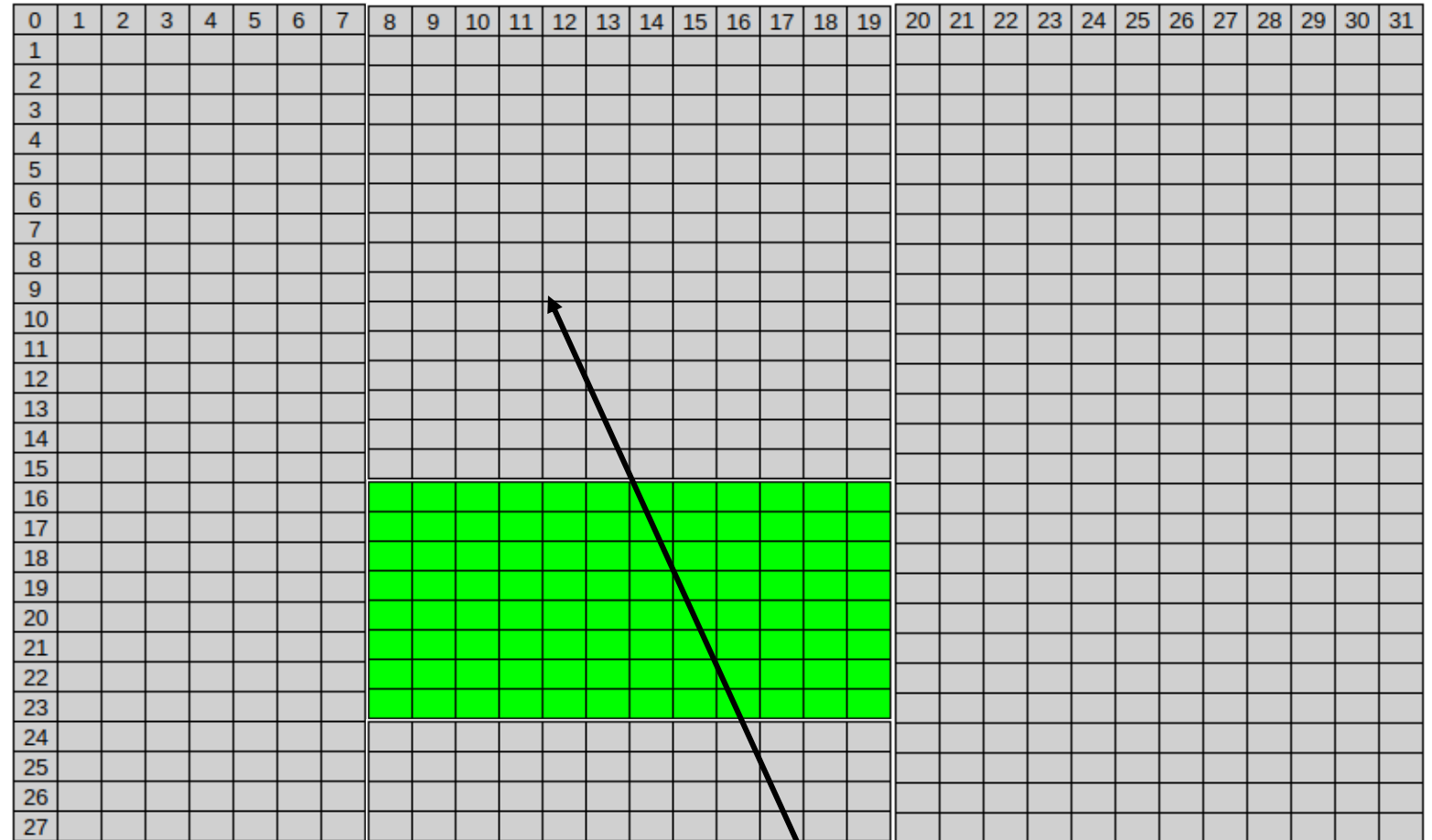
**0-based indices of BB in upscaled tensor:**

$$\begin{aligned} r_1 &= (y_1 - 1) \times scale \\ &= (5 - 1) \times 4 = 16 \end{aligned}$$

$$\begin{aligned} r_2 &= r_1 - 1 + ((y_2 - y_1 + 1) \times scale) \\ &= 16 - 1 + ((6 - 5 + 1) \times 4) = 23 \end{aligned}$$

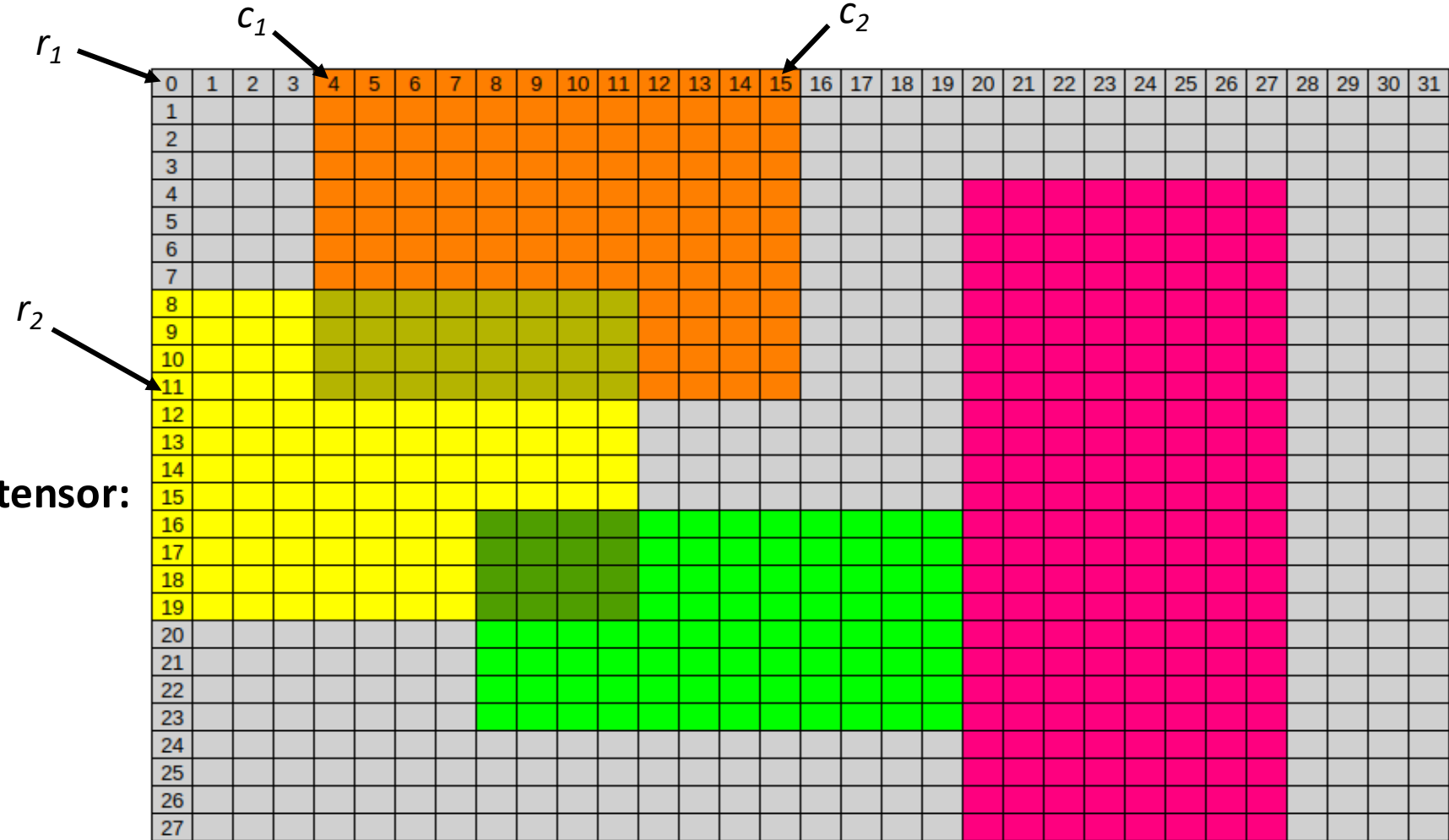
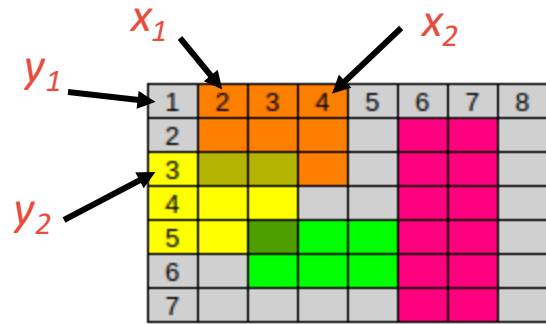
$$\begin{aligned} c_1 &= (x_1 - 1) \times scale \\ &= (3 - 1) \times 4 = 8 \end{aligned}$$

$$\begin{aligned} c_2 &= c_1 - 1 + ((x_2 - x_1 + 1) \times scale) \\ &= 8 - 1 + ((5 - 3 + 1) \times 4) = 19 \end{aligned}$$



Upscaled by  
bilinear  
interpolation

# Frame Formation as a Tensor continue



**0-based indices of BB in upscaled tensor:**

$$\begin{aligned} r_1 &= (y_1 - 1) \times scale \\ &= (1 - 1) \times 4 = 0 \end{aligned}$$

$$\begin{aligned} r_2 &= r_1 - 1 + ((y_2 - y_1 + 1) \times scale) \\ &= 0 - 1 + ((3 - 1 + 1) \times 4) = 11 \end{aligned}$$

$$\begin{aligned} c_1 &= (x_1 - 1) \times scale \\ &= (2 - 1) \times 4 = 4 \end{aligned}$$

$$\begin{aligned} c_2 &= c_1 - 1 + ((x_2 - x_1 + 1) \times scale) \\ &= 4 - 1 + ((4 - 2 + 1) \times 4) = 15 \end{aligned}$$

# Size: 1080p – Per-Frame SR



Chunk0001 – Frame 0018



# Size: 1080p – Anchor Point in Per-BB SR





# Size: 1080p – Non-Anchor Point in Per-BB SR



Chunk0001 – Frame 0010

# Quality, Anchor Points, and DNN Latency Results

Chunk	Per-Frame SR		AP SR (NEMO)			AP Per-BB SR (Our Method)		
	PSNR (dB)	Time (s)	PSNR (dB)	APs Count	Time (s)	PSNR (dB)	APs Count	Time (s)
0	30.03	57.23	29.56	6	2.86	26.87	8	4.16
1	31.19	54.85	30.77	3	1.37	27.68	8	2.91
2	32.02	54.63	31.61	2	0.91	28.35	8	2.46
3	32.53	54.62	32.23	1	0.46	29.11	8	3.20
4	32.56	54.67	32.45	6	2.73	29.85	8	4.68
5	32.08	54.52	31.93	2	0.91	29.30	8	3.58
6	31.71	54.56	31.51	5	2.27	28.93	8	4.55
7	31.68	55.61	31.49	1	0.46	29.11	8	5.13

120 frames/chunk, 25 chunks in total

# Per-BB SR Yields Very Low PSNR Unlike NEMO

Chunk	Per-Frame SR		AP SR (NEMO)			AP Per-BB SR (Our Method)		
	PSNR (dB)	Time (s)	PSNR (dB)	APs Count	Time (s)	PSNR (dB)	APs Count	Time (s)
0	30.03	57.23	29.56	6	2.86	26.87	8	4.16
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6	31.71	54.56	31.51	5	2.27	28.93	8	4.55
7	31.68	55.61	31.49	1	0.46	29.11	8	5.13

difference = 0.47

difference = 3.16

manually limited

Allowed quality margin = 0.5

# DNN Latency of Per-BB SR is Longer Than Expected

Chunk	Per-Frame SR		AP SR (NEMO)			AP Per-BB SR (Our Method)		
	PSNR (dB)	Time (s)	PSNR (dB)	APs Count	Time (s)	PSNR (dB)	APs Count	Time (s)
0	30.03	57.23	29.56	6	2.86	26.87	8	4.16
1	31.19	54.85	30.77	3	1.37	27.68	8	2.91
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6	31.71	54.56	31.51	5	2.27	28.93	8	4.55
7	31.68	55.61	31.49	1	0.46	29.11	8	5.13

APs of per-bb SR are not much more in chunk 0

time(NEMO) << time(per-bb SR)

# DNN Latency in Per-BB SR Includes Additional Processing

Chunk	BBs Count	AP Per-BB SR Raw DNN Time (s)	AP Per-BB SR Total Processing Time (s)
0	1623	2.83	4.16
1	1134	1.86	2.91
2	953	1.56	2.46
3	1365	2.19	3.20
4	2225	3.35	4.68
5	1353	2.30	3.58
6	1922	3.38	4.55
7	2519	3.82	5.13

8 anchor points each

BBs wait in a queue to get SR applied; can't be processed in batches

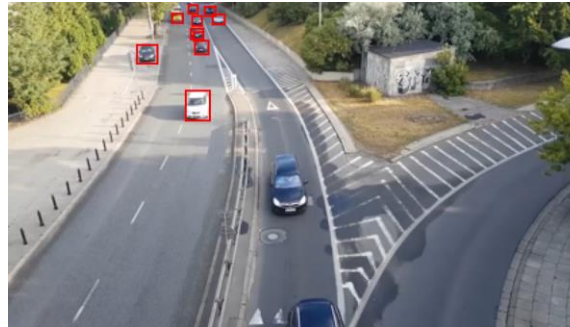


# F1-Scores of Bounding Boxes Against Per-Frame-SR

Chunk	240p	AP SR (NEMO)	AP Per-BB SR (Our Method)
0	0.66	0.88	0.66
1	0.85	0.92	0.85
2	0.80	0.91	0.82
3	0.85	0.89	0.86
4	0.86	0.89	0.86
5	0.78	0.87	0.80
6	0.74	0.84	0.77
7	0.81	0.87	0.86

# How About Per-Small-BB SR? What is a Small BB?

- In COCO\*, a bounding box with area  $< 32^2$  is considered small. Such BBs occupy 41% of objects.
- This should be interpreted in a way that suits our frames.
- In our frames, a bounding box with area  $< 20^2$  is considered small. Such BBs occupy 59.01% of objects.



Chunk0020 – Frame 0000

Try the code here to set your own threshold and see how much % its BBs occupy: [https://drive.google.com/drive/folders/1QIUvpVJsWzHyT0R0wNeW4yP3VnjjqfJF?usp=share\\_link](https://drive.google.com/drive/folders/1QIUvpVJsWzHyT0R0wNeW4yP3VnjjqfJF?usp=share_link)

\* <https://cocodataset.org/#detection-eval>

# Size: 1080p – Per-Frame SR



Chunk0020 – Frame 0000



# Size: 1080p – Anchor Point in Per-Small-BB SR



Chunk0020 – Frame 0000

# Size: 1080p – Anchor Point in Per-BB SR



Chunk0020 – Frame 0000

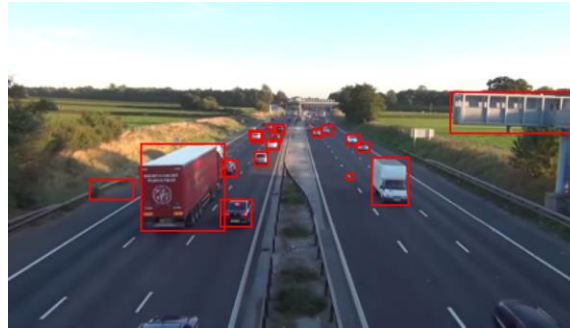


# DNN Latency in Per-Small-BB SR as Compared to Per-BB SR

Chunk	Small BBs Count	AP Per-Small-BB SR Total Processing Time (s)	AP Per-BB SR Total Processing Time (s)
0	938	2.35	4.16
1	863	1.86	2.91
2	734	1.50	2.46
3	1060	1.79	3.20
4	1616	2.40	4.68
5	873	1.88	3.58
6	1203	2.19	4.55
7	1731	2.59	5.13

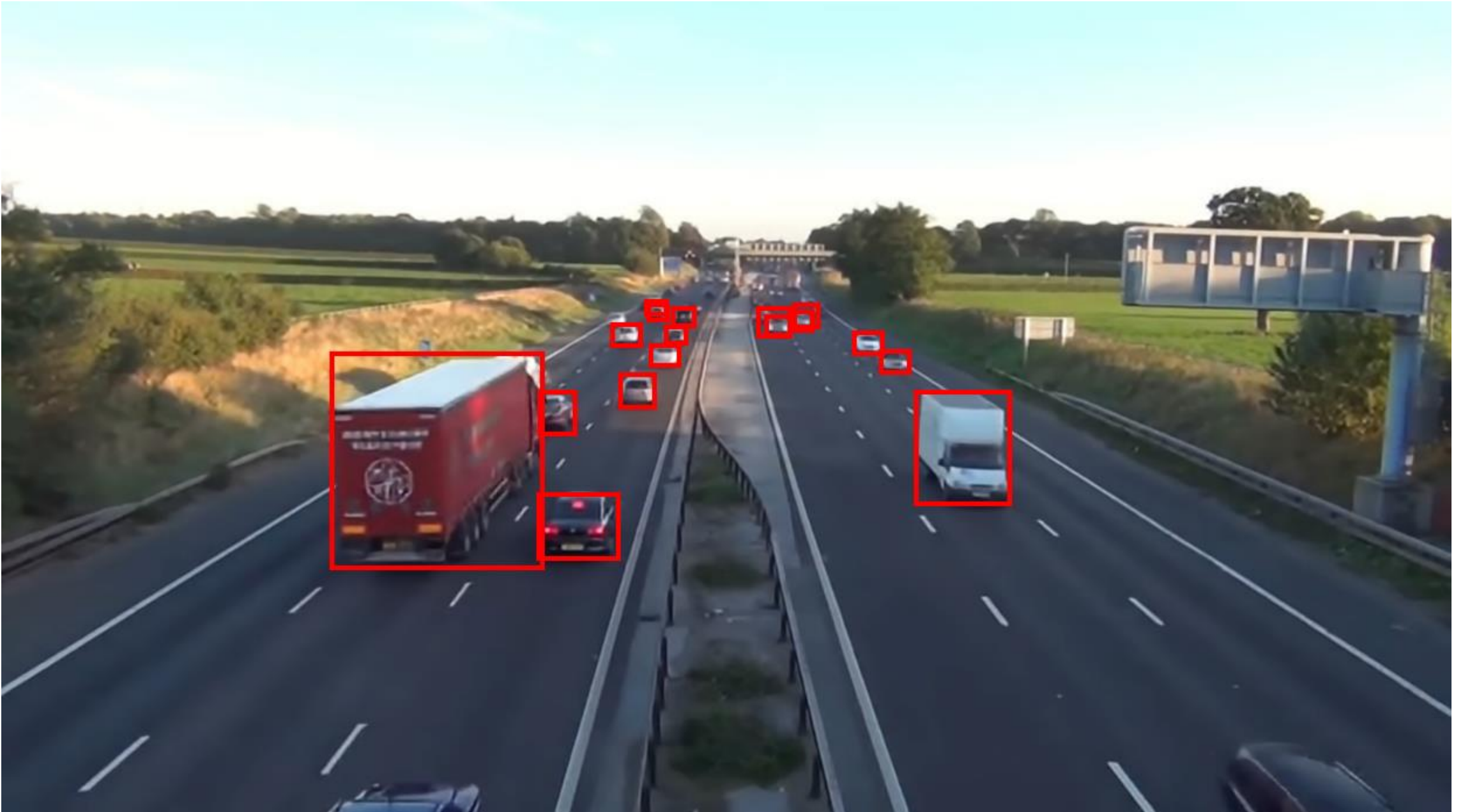
# Size: 240p – Input Frame with Bounding Boxes

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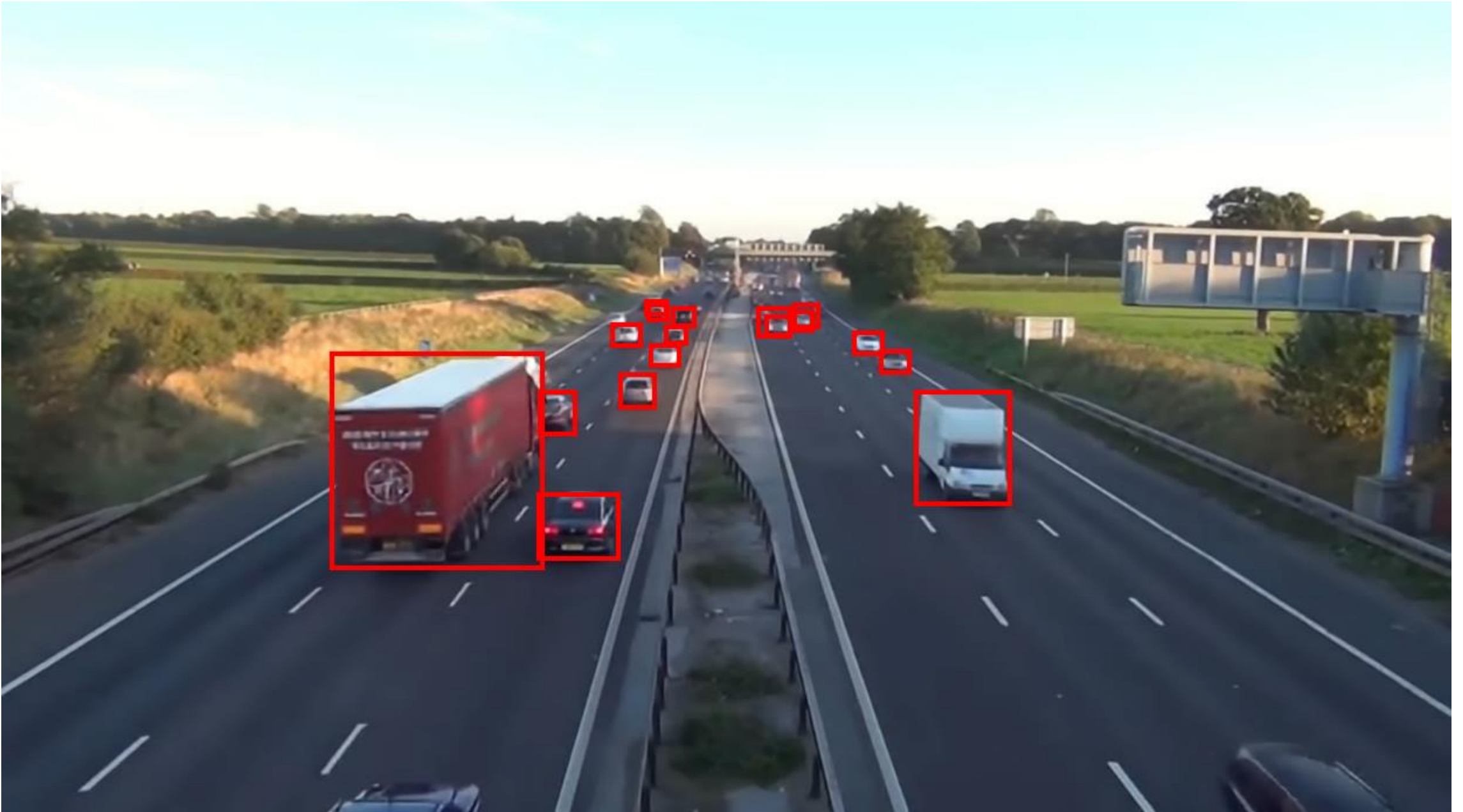
Chunk0004 – Frame 0012

# Size: 1080p – BBs After Per-Frame SR



Chunk0004 – Frame 0012

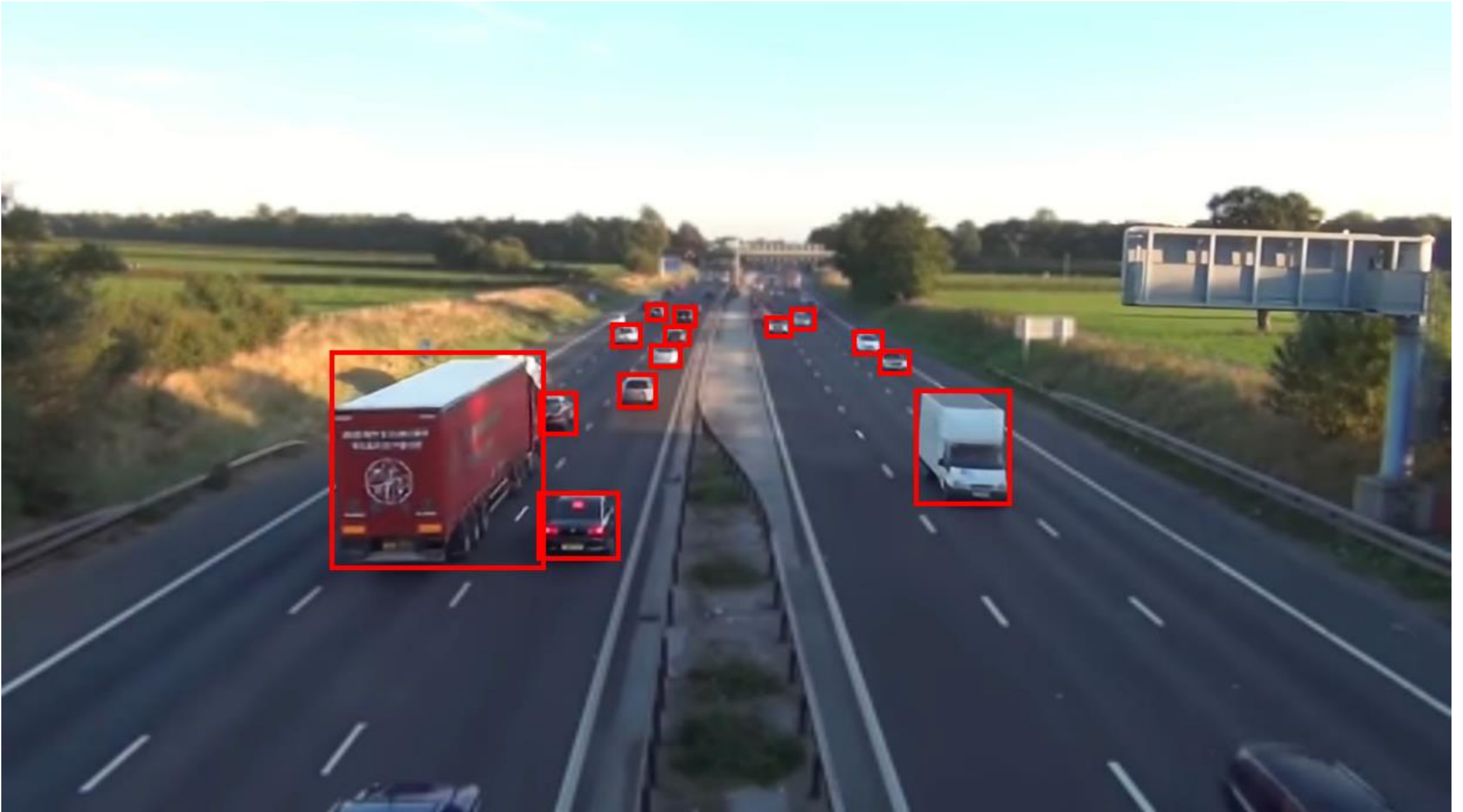
# Size: 1080p – BBs After NEMO



Chunk0004 – Frame 0012

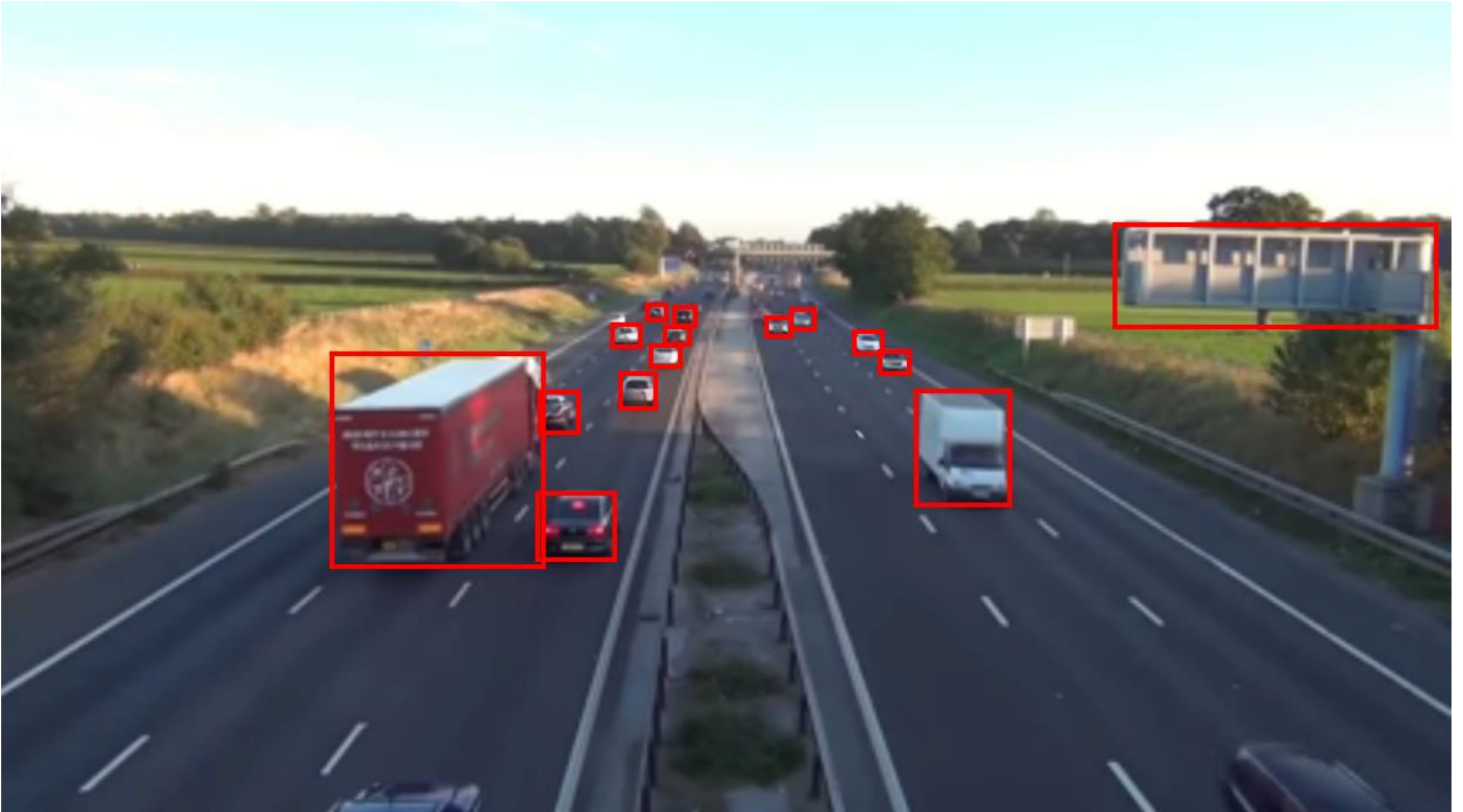


# Size: 1080p – BBs After Per-BB SR



Chunk0004 – Frame 0012

# Size: 1080p – BBs After Per-Small-BB SR



Chunk0004 – Frame 0012



# F1-Scores of Bounding Boxes Against Per-Frame-SR

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Method	Average F1-Score in Video
240p	0.84
AP SR (NEMO)	0.90
AP Per-BB SR (Our Main Method)	0.87
AP Per-Small-BB SR (Additional Method)	0.86

# Conclusion

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- NEMO achieves ground truth BBs with high accuracy and within acceptable DNN latency.
- Per-bb SR takes longer time than NEMO since BBs wait in a queue to get neural SR applied.
- BBs cannot be processed in a batch due to their different sizes.
- Per-small-bb SR takes way shorter time than per-bb SR with close accuracy.
- **Suggestions for future work for per-bb SR DNN time:**
  - Change anchor points limit
  - Change quality margin
  - Change threshold of confidence score
  - Choose a fixed size for BBs and work on them as a batch

Thank you

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