

# Liam Telenko

telenkol@mcmaster.ca | linkedin.com/in/liamtelenko

## Education

---

### McMaster University | Hamilton, ON

Bachelor of Engineering in Computer Engineering, GPA 10.3

September 2019 – Present

Expected Graduation, May 2024

## Experience

---

### Synopsys | Mississauga, ON

April 2022 – September 2023

#### Digital Verification Engineering Intern / Solutions Group

- Implemented and maintained constrained-random SystemVerilog UVM testbenches
- Debugged and documented mixed-signal simulation failures from daily regressions
- Wrote and implemented verification testplans

### McMaster University | Hamilton, ON

July 2020 – April 2022

#### Web & Desktop Applications Assistant / Office of the Registrar

- Developed multiple full stack software solutions in Python for internal tasks resulting in improved efficiency of recurring processes
- Maintained technical and end-user documentation for support tickets and internally developed software
- Provided remote and in-person desktop and application support for users in a variety of production environments

## Projects

---

### Hardware Image Decompressor

December 2021

#### Digital Systems Design / 3DQ5

The goal of the project was to decompress a proprietary image format using a hardware implementation. The project was team-based and completed in groups of two.

- Implemented colour space conversion, interpolation, and inverse-signal transformation on FPGA hardware in SystemVerilog
- Designed modules to efficiently compute matrix operations and manage data in embedded and external memory
- Completed unit tests by verifying the operation of individual modules in ModelSim

### 3D Visualization of Time-of-Flight Data

April 2021

#### Microprocessor Systems Project / 2DX4

The goal of the project was to design a system which can collect and interpret data from a time-of-flight sensor. The project was completed individually.

- Developed embedded software for an ARM Cortex platform in C and assembly; wrote visualization software in Python
- Utilized the I<sup>2</sup>C and UART protocols to transfer data between the time-of-flight sensor, microcontroller, and data visualization software

## Extra Curriculars

---

### McMaster Formula Electric | Hamilton, ON

October 2020 – March 2022

#### Dashboard Team Lead

- Worked with previous team leads to design the structure of the software to meet hardware and competition constraints
- Utilized RTOS queue and task components to integrate the GUI with the CAN bus on the STM32 based platform