CommAl-env

Marco Baroni, **Allan Jabri**, Armand Joulin, Germán Kruszewski, Angeliki Lazaridou, Tomas Mikolov, Klemen Simonic

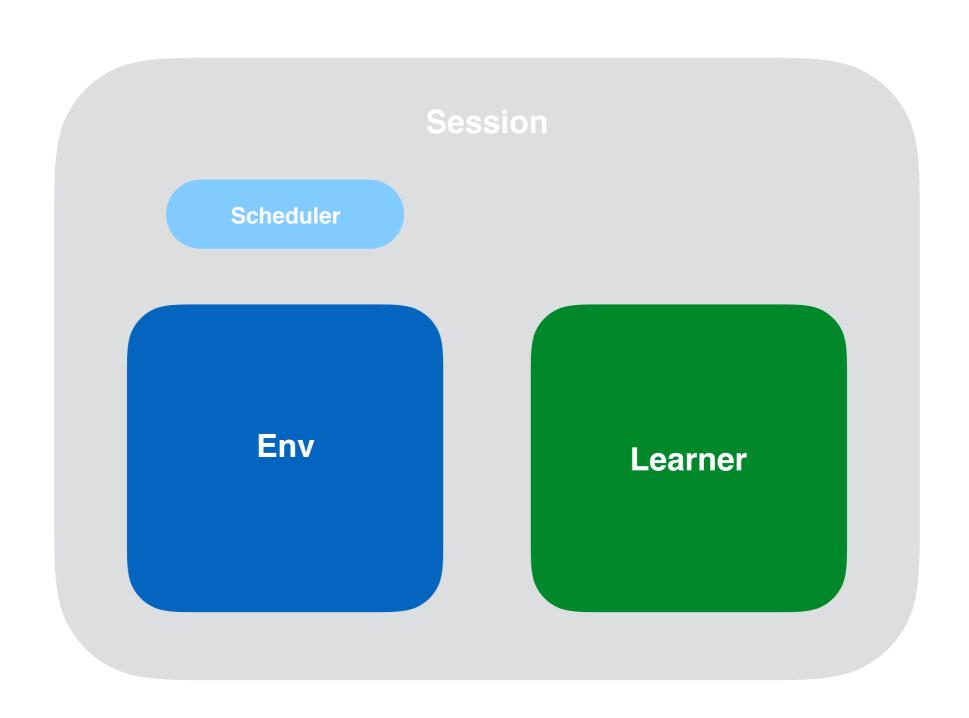
Facebook Artificial Intelligence Research

MAchine INtelligence Workshop NIPS 2016

Communication-based Al Environment

- environment in python, learner in any language
- lightweight text environment (command line)
- github.com/facebookresearch/CommAI-env

git clone https://github.com/facebookresearch/CommAI-env.git cd src python run.py my_tasks.json

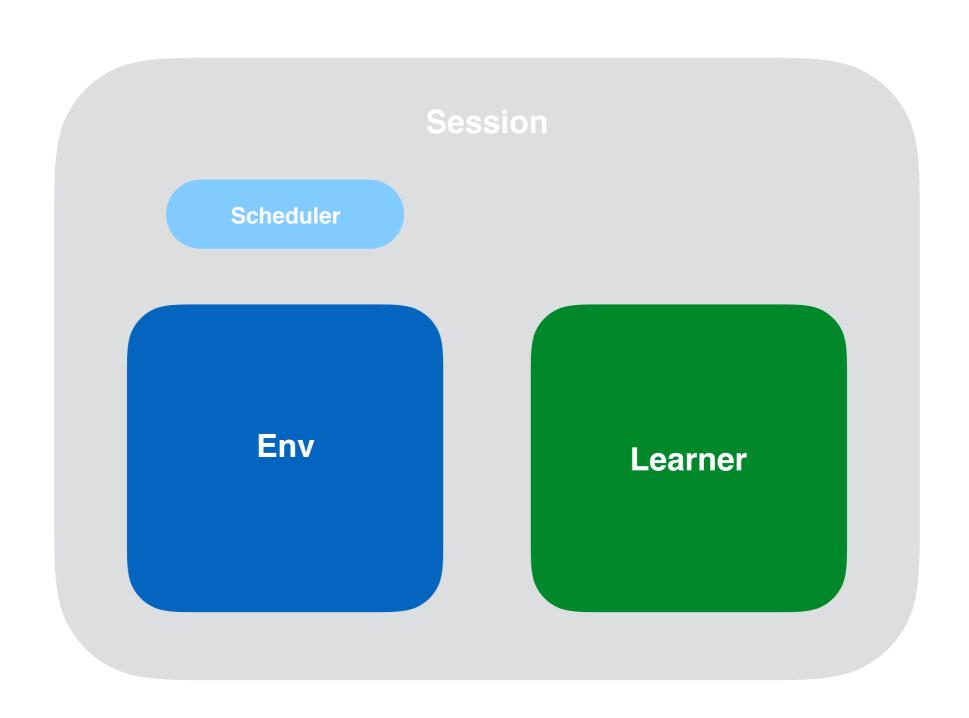


python run.py tasks_config.sample.json

```
"worlds": {
  "gw":
    "type": "worlds.grid_world.GridWorld"
"tasks":
  "k0": {
    "type": "tasks.competition.repetition.BeSilentTask",
    "world": "gw"
  "g15": [
      "type": "tasks.competition.repetition.RepeatCharacterTask",
      "world": "gw"
  },
  "k2": {
      "type": "tasks.competition.repetition.RepeatWhatISayTask",
      "world": "gw"
  },
                                 . . .
     "type": "tasks.competition.mavigation.LookAroundTask",
     "world": "gw"
 f_{\mathcal{F}}
  "aj3": {
     "type": "tasks.competition.navigation.FindObject&roundTask",
     "world": "gw"
}.
"scheduler":
    "type": "come.scheduler.RandomTaskScheduler",
       "tasks": ["k0", "g15", "k2", "k5", "k6", "k7", "k8", "k9",
         "a1", "a2",
         "t1", "t2", 't3",
         "m1", "m2", 'm3", "m4", "m5", "m6", "m7", "m8", 'm9", "m19", "m11", "m12",
         "g8", "g1", 'g2", "g3", "g4", "g6", "g7", "g8", "g9", "g16", "g13", "g14",
         "a|1", "a|2", "a|3"]
     3
```

python run.py tasks_config.sample.json

```
"aj2": {
      "type": "tasks.competition.navigation.LookAroundTask",
     "world": "gw"
 },
 "aj3": {
     "type": "tasks.competition.navigation.FindObjectAroundTask",
     "world": "gw"
},
"scheduler":
    "type": "core.scheduler.RandomTaskScheduler",
    "args": {
        "tasks": ["k0", "g15", "k2", "k5", "k6", "k7", "k8", "k9",
         "a1", "a2",
         "t1", "t2", "t3",
         "m1", "m2", "m3", "m4", "m5", "m6", "m7", "m8", "m9", "m10", "m11", "m12",
         "g0", "g1", "g2", "g3", "g4", "g6", "g7", "g8", "g9", "g10", "g13", "g14",
         "aj1", "aj2", "aj3"]
```



Loop

Pick next task

While not task.finished:

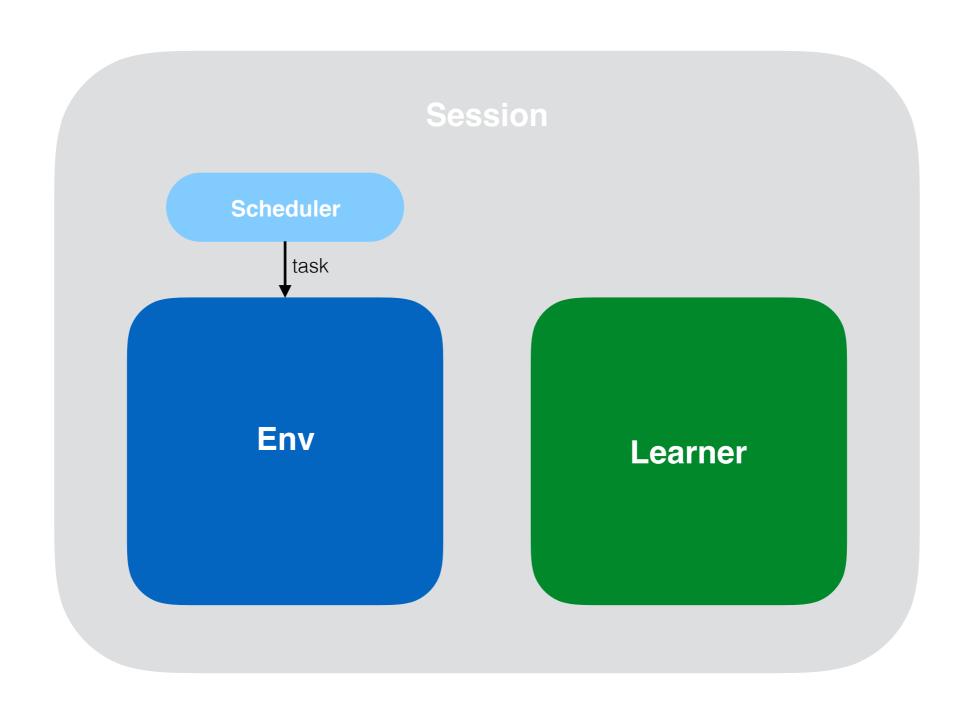
env sends a bit

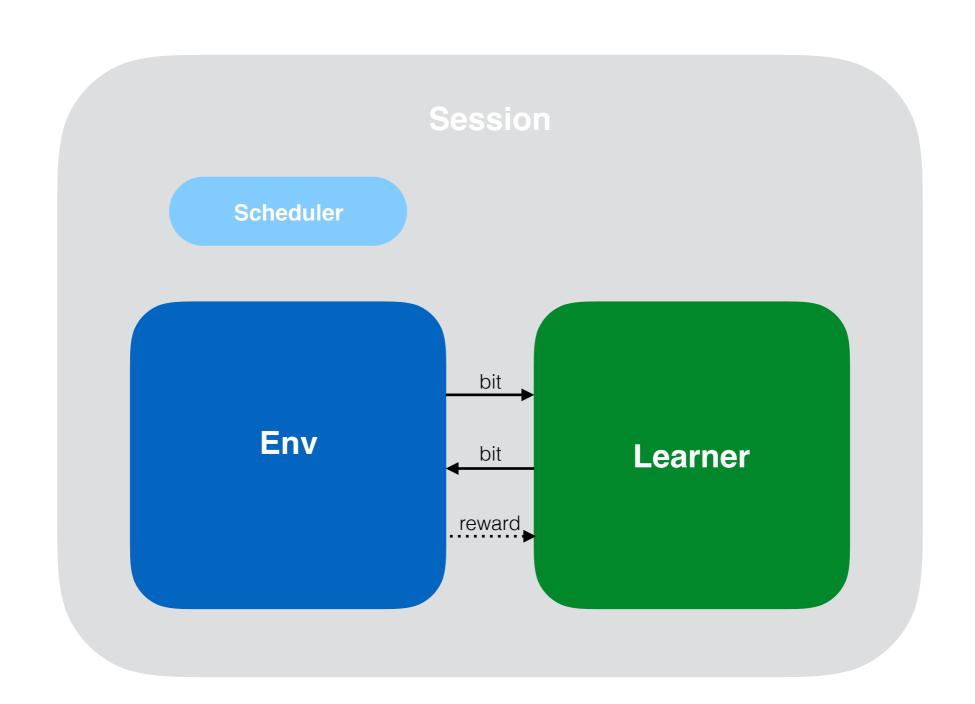
learner sends a bit

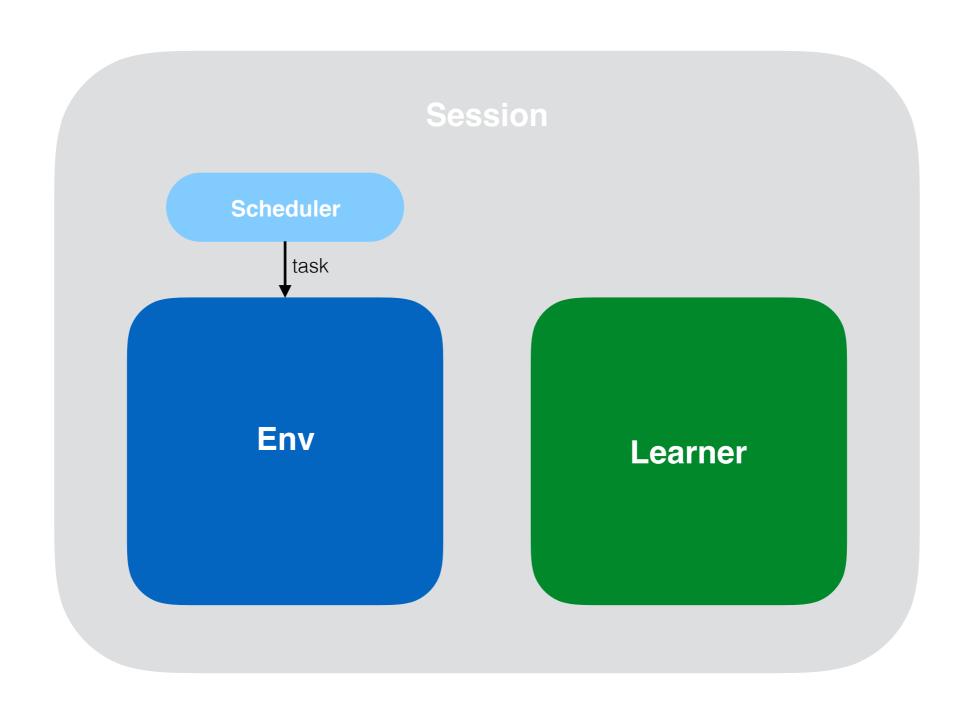
if learner succeeds, fails, or time out:

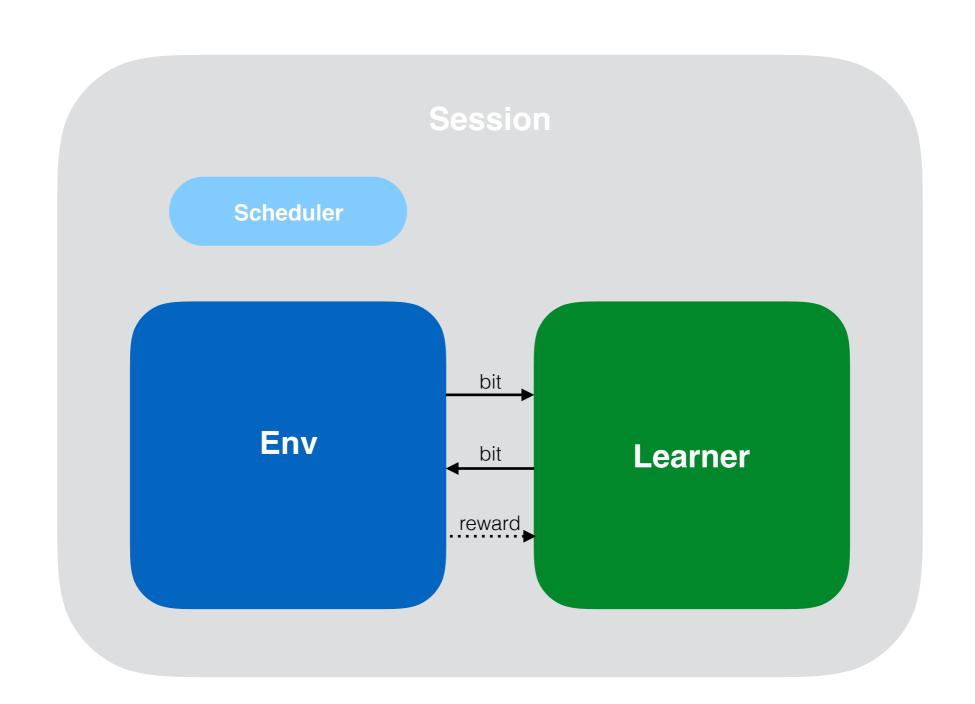
env sends reward

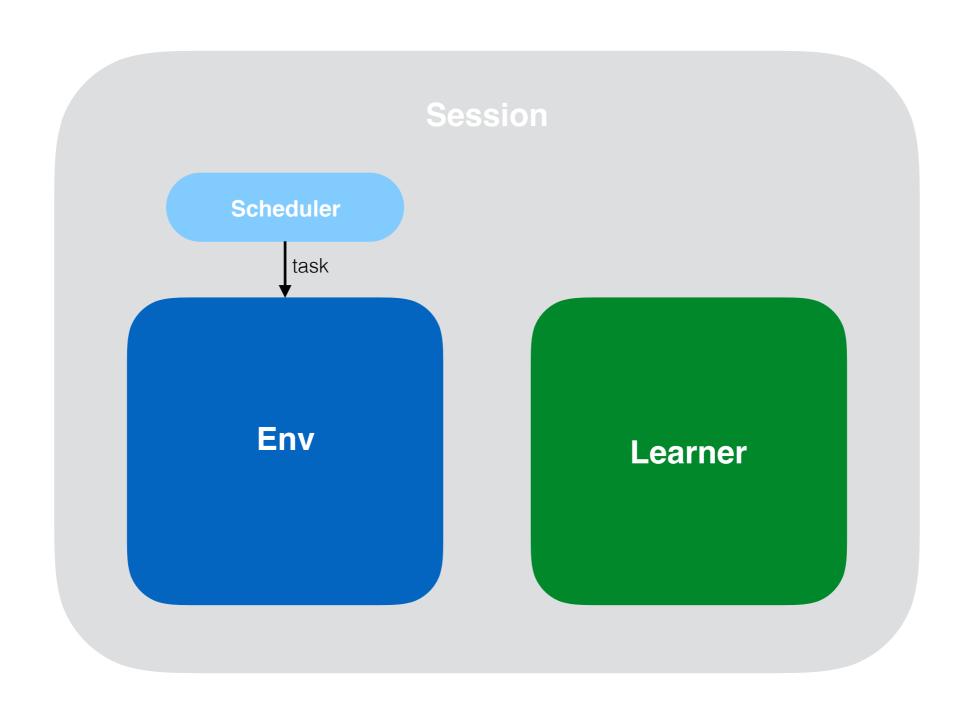
task.finished = true

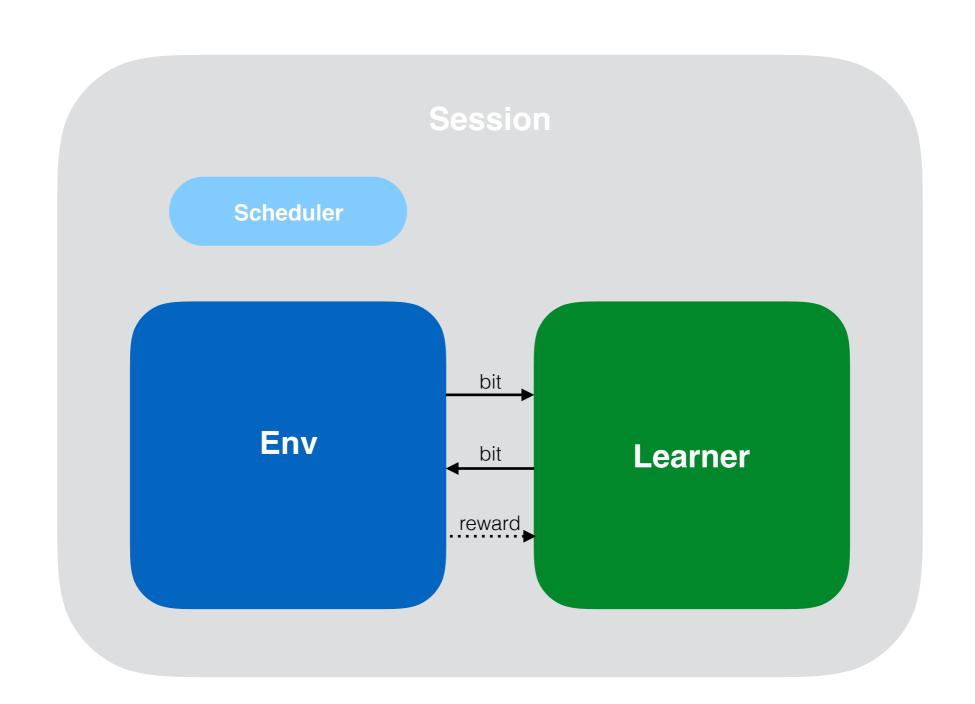












Demo

- · Human mode:
 - python run.py my_tasks.json
- · Scrambled:
 - python run.py my_tasks.json --scramble
- · With a learner:
 - python run.py my_tasks.json \-I learners.sample_learners.SampleRepeatingLearner
- · Remote learner:
 - python run.py my_tasks.json -I learners.base.RemoteLearner \
 --learner-cmd "/my/learner/binary"

Events

```
on_init
     on_start
   on_message
   on_sequence
on_output_message
on_output_sequence
 on_state_changed
    on_timeout
   on_world_init
  on_world_start
```

BeSilentTask

```
class BeSilentTask(Task):
    def __init__(self, world=None):
        super(BeSilentTask, self).__init__(world=world,
                                           max_time=random.randint(100, 1000))
   # give instructions at the beginning of the task
   @on_start()
   def on_start(self, event):
       self.set_message(random.choice(["be silent now.",
                                        "do not say anything."]))
   # catch any non-space character
   @on message("[^ ]")
   def on message(self, event):
       self.set reward(0, random.choice(msg.failed))
   # when the maximum amount of time set for the task has elapsed
   @on_timeout()
    def on_timeout(self, event):
        self.set_reward(1, random.choice(msg.congratulations))
```

SampleRepeatingLearner

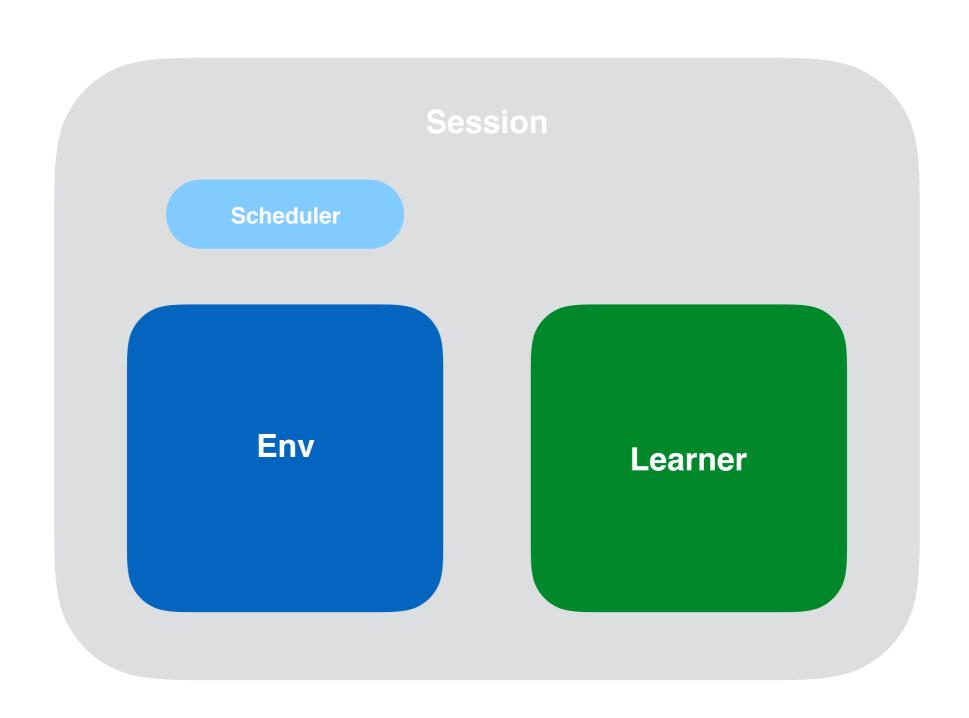
```
class SampleRepeatingLearner(BaseLearner):
    def reward(self, reward):
        # YEAH! Reward!!! Whatever...
        pass

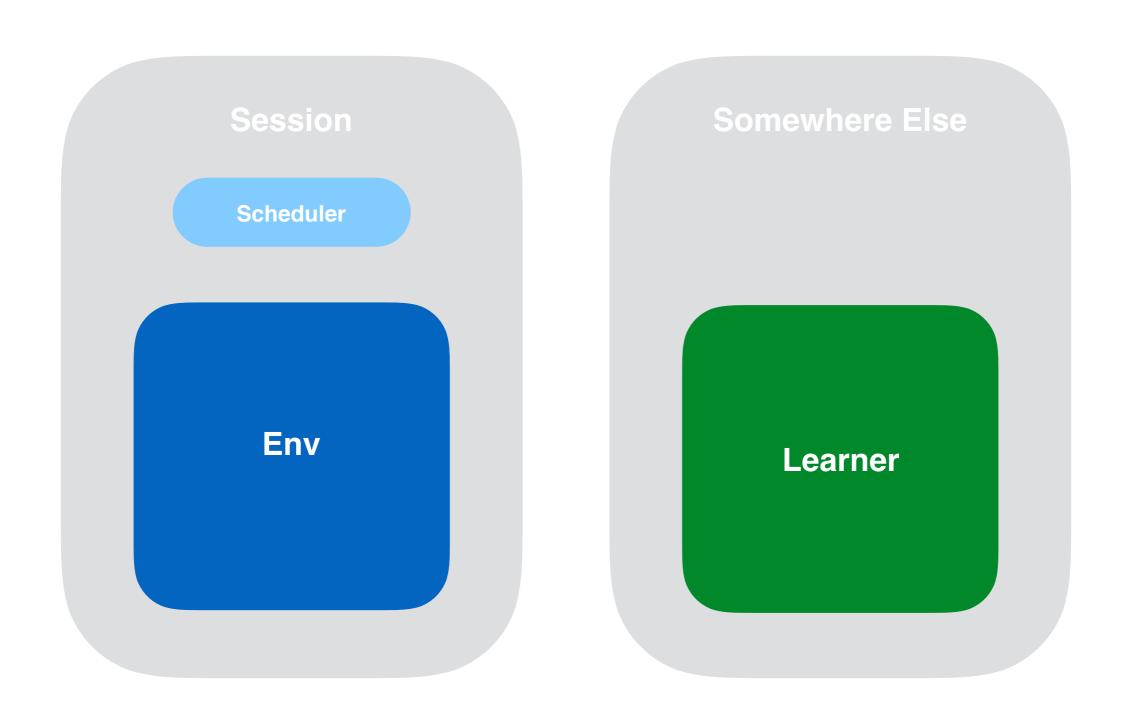
def next(self, input):
        # do super fancy computations
        # return our guess
        return input
```

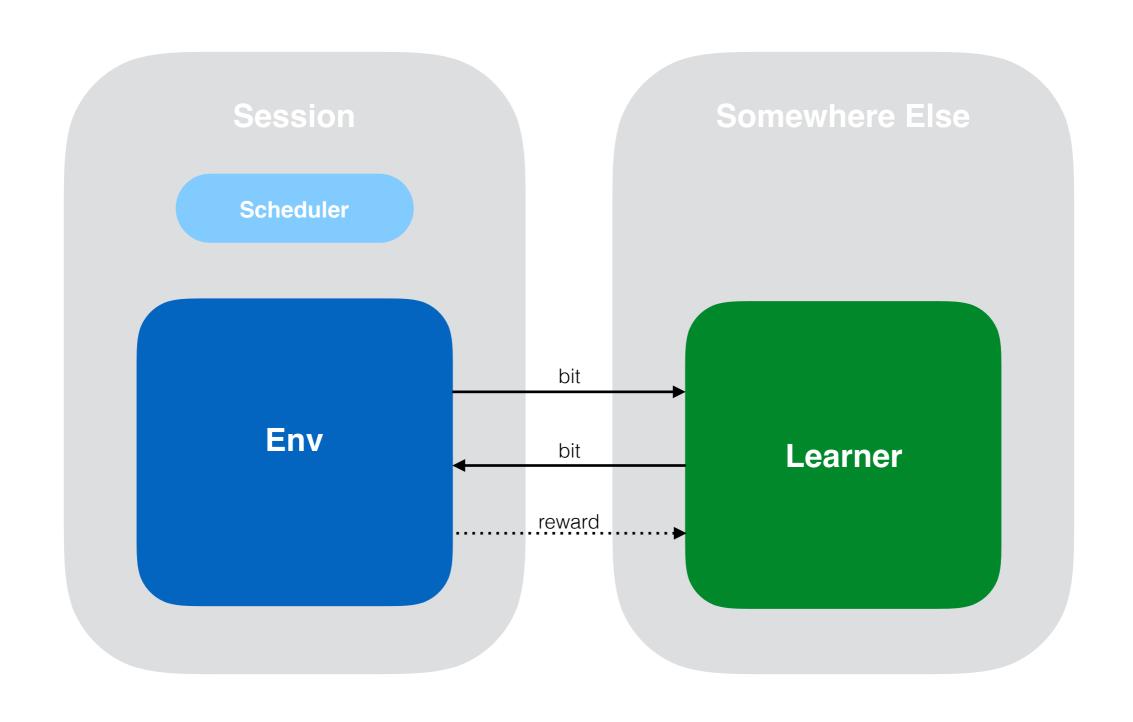
A learner in C

```
#include <string.h>
#include <zmq.h>
// This is an example of a silly learner that always replies with '.'
int main()
   char reply[1];
   int n = 0;
   const char* response = "00101110"; // '.' utf-8 code
   // connect
   void *context = zmq_ctx_new();
   void *to_env = zmq_socket(context, ZMQ_PAIR);
   int rc = zmq_connect(to_env, "tcp://localhost:5556");
   zmq_send(to_env, "hello", 5, 0); // handshake
   while (true) {
      zmq_recv(to_env, reply, 1, 0); // receive reward
      zmq_recv(to_env, reply, 1, 0); // receive teacher/env bit
      reply[0] = response[n % strlen(response)];
      zmq_send(to_env, reply, 1, 0);
      n += 1;
   return 0;
}
```

```
while (true) {
   zmq_recv(to_env, reply, 1, 0);  // receive reward
   zmq_recv(to_env, reply, 1, 0);  // receive teacher/env bit
   reply[0] = response[n % strlen(response)];
   zmq_send(to_env, reply, 1, 0);
   n += 1;
}
```







Examples

Counting

Object existence 1

Object existence 2

Associate object with property

Verify that object has property

List properties of an object

Name a property of an object

List objects with a certain property

Name an object with a property

Who has a certain object with a certain property

List the properties that an object has in a basket only

List the properties that an object has in all baskets

How many objects have a certain property

How many properties does an object have

Italian how many properties does an object have

Guess The Number Asking Questions (Explicit Model)

Guess The Number Asking Questions

Guess The Number Asking For Digits (Explicit Model)

Guess The Number Asking For Digits

Look

Look Around

Look For

Turning

Moving Forward

Moving relative

Moving absolute

Pick up Task

Pick up in front Task

Pick up around Task

Giving

Pick up around and give

Pick up around many and give

Counting in inventory

Counting in inventory with giving

T: say anything you want.

L: blablabla.

T: correct. [R+1]

T: say apple.

L: apple.

T: correct. [R+1]

T: repeat hello world.

L: blabla.

T: wrong, you should have said hello world.

T: i have an apple. do i have a banana?

L: yes.

T: wrong, i do not have a banana.

T: i have an apple and a banana and no pear. do i have a pear?

L: no

T: correct [R+1]

T: i have an apple, an apple and a banana. how many bananas do I have?

L: one

T: bravo! [R+1]

T: apple in john's basket is green. how is apple? L: green.

T: is apple green in john's basket? L: yes.

T: which properties does apple have in mary's basket?

L: red, sweet and hard.

T: who has a yellow pineapple in the basket? L: john and mary.

T: how many objects are yellow in john's basket? L: two. T: move forward.

L: i move forward.

T: you moved [R+1].

T: i have placed an apple where you are. pick up the apple.

L: i pick up the apple.

T: you picked up the apple [R+1].

T: there is an apple in front of you. pick up the apple.

L: i pick up the apple.

T: there is no apple here.

L: i move forward.

T: you moved.

L: i pick up the apple.

T: you picked up the apple [R+1].



T: Thank the audience.

L: Thank the audience.

T: Sigh... Just say "Thank you".

L: Thank you!

T: Good job. [+1]