

# Introduction to the Discrete Fourier Transform (DFT)

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## 1 Prior knowledge

Euler's formula:

$$e^{ix} = \cos x + i \sin x \quad (1)$$

Cross-correlation at lag 0:

$$f * g (0) = \int_{-\infty}^{\infty} f^*(t)g(t)dt \quad (2)$$

$$f * g [0] = \sum_{n=-\infty}^{\infty} f^*[n]g[n] \quad (3)$$

## 2 Fourier series (FS)

$$S_{FS}[k] = \int_{-N/2}^{N/2} s(t) \cdot e^{-i2\pi \frac{k}{N}t} dt, \quad \forall k \in \mathbb{Z}, t \in \mathbb{R} \quad (4)$$

$$s_{FS}(t) = \sum_{k=-\infty}^{\infty} S_{FS}[k] \cdot e^{i2\pi \frac{k}{N}t}, \quad \forall k \in \mathbb{Z}, t \in \mathbb{R} \quad (5)$$

$$s_{FS}(t) = A_0 + \sum_{k=1}^{\infty} \left( A_n \cos(2\pi \frac{k}{N}t) + B_n \sin(2\pi \frac{k}{N}t) \right), \quad \forall t \in \mathbb{R}, k \in \mathbb{Z} \quad (6)$$

## 3 Fourier transform (FT)

$$S_{FT}(f) = \int_{-\infty}^{\infty} s(t) \cdot e^{-i2\pi ft} dt, \quad t, f, \in \mathbb{R} \quad (7)$$

$$s(t) = \int_{-\infty}^{\infty} S_{FT}(f) \cdot e^{i2\pi ft} dt, \quad t, f, \in \mathbb{R} \quad (8)$$

## 4 Discrete Time Fourier Transform (DTFT)

Sampling of  $s(t)$  with finite time interval  $T$ :

$$dt \approx T \Rightarrow t_n = Tn \Rightarrow s(t) \cdot dt = s(Tn) \cdot T, \quad n \in \mathbb{Z} \quad (9)$$

Let  $s[n] = s(Tn) \cdot T$ :

$$S_{DTFT}(f) = \sum_{n=-\infty}^{\infty} s[n] \cdot e^{-i2\pi f T n} \quad (10)$$

## 5 Discrete Fourier Transform (DFT)

Assumption: Signal is periodic with period  $N$ :

$$s[n + mN] = s[n] \quad m \in \mathbb{Z} \quad (11)$$

The evenly sampled frequency range is given by  $fT = \frac{k}{N}$

$$S_{DFT}[k] = \sum_{n=0}^{N-1} s[n] \cdot e^{-i2\pi \frac{k}{N} n}, \quad k \in 0, 1, \dots, N-1 \quad (12)$$

## 6 Matrix form

In Equation 12 we see two running indices:  $n \in 0, 1, \dots, N-1$  (time-domain) and  $k \in 0, 1, \dots, N-1$  (frequency domain). This suggests that we can formulate the computation in matrix form:

$$\begin{bmatrix} S_{DFT}[k=0] \\ S_{DFT}[k=1] \\ \dots \\ S_{DFT}[k=N-1] \end{bmatrix} = \quad (13)$$

$$\begin{bmatrix} s[0] \cdot e^{-i2\pi \frac{0}{N} 0}, & s[1] \cdot e^{-i2\pi \frac{0}{N} 1}, & \dots, & s[N-1] \cdot e^{-i2\pi \frac{0}{N} (N-1)} \\ s[0] \cdot e^{-i2\pi \frac{1}{N} 0}, & s[1] \cdot e^{-i2\pi \frac{1}{N} 1}, & \dots, & s[N-1] \cdot e^{-i2\pi \frac{1}{N} (N-1)} \\ \dots, & \dots, & \dots, & \dots \\ s[0] \cdot e^{-i2\pi \frac{N-1}{N} 0}, & s[1] \cdot e^{-i2\pi \frac{N-1}{N} 1}, & \dots, & s[N-1] \cdot e^{-i2\pi \frac{N-1}{N} (N-1)} \end{bmatrix} \quad (14)$$

$$= \begin{bmatrix} e^{-i2\pi \frac{0}{N} 0}, & e^{-i2\pi \frac{0}{N} 1}, & \dots, & e^{-i2\pi \frac{0}{N} (N-1)} \\ e^{-i2\pi \frac{1}{N} 0}, & e^{-i2\pi \frac{1}{N} 1}, & \dots, & e^{-i2\pi \frac{1}{N} (N-1)} \\ \dots, & \dots, & \dots, & \dots \\ e^{-i2\pi \frac{N-1}{N} 0}, & e^{-i2\pi \frac{N-1}{N} 1}, & \dots, & e^{-i2\pi \frac{N-1}{N} (N-1)} \end{bmatrix} \cdot \begin{bmatrix} s[0] \\ s[1] \\ \dots \\ s[N-1] \end{bmatrix} \quad (15)$$

$$\bar{\mathbf{S}}_{\mathbf{DFT}} = \mathbf{D}\bar{\mathbf{s}}, \quad (16)$$

where  $\bar{\mathbf{S}}_{\mathbf{DFT}} \in [\mathbb{C}^N \times 1]$ ,  $\bar{\mathbf{s}} \in [\mathbb{R}^N \times 1]$ ,  $\mathbf{D} \in [\mathbb{C}^N \times \mathbb{C}^N]$

Inverse transform matrix:

$$\mathbf{D}^{-1} = \frac{1}{N}\mathbf{D}^* \quad (17)$$

$$\mathbf{D}^{-1}\mathbf{D} = \mathbf{I} \quad (18)$$

## 7 Properties

Lossless transform:

$$\mathcal{F}^{-1}(\mathcal{F}(s_t)) = s_t \quad (19)$$

$$\mathcal{F}(\mathcal{F}^{-1}(S_f)) = S_f \quad (20)$$

Linearity:

$$a + b = \mathcal{F}(a) + \mathcal{F}(b) \quad (21)$$

Convolution theorem:

$$a * b = \mathcal{F}(a) \cdot \mathcal{F}(b) \quad (22)$$

$$a \cdot b = \mathcal{F}(a) * \mathcal{F}(b) \quad (23)$$

Direct form representation:

$$S_{FT}(f) = A_f + iB_f, \quad \forall A_f, B_f \in \mathbb{R} \quad (24)$$

Magnitude-phase form representation:

$$S_{FT}(f) = M_f \cdot e^{i\phi_f}, \quad \forall M_f, \phi_f \in \mathbb{R} \quad (25)$$