

# Visualizing uncertainty

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Week 7

# Data viz in the wild

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Cassie

Amy

Diana

Errol and Mandi on deck

# Agenda

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- Finish up plot refinement slides
- Common ways of visualizing uncertainty
  - And how to implement them with `{ggplot2}`
- Framing uncertainty as relative frequencies
  - Discrete probabilities
  - Non-discrete probabilities
- Understanding standard errors
  - Non-standard ways of visualizing SEs
- HOPs (pretty quick)

# Agenda (continued)

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Assuming we still have time (I think we will), we will also at least introduce **tables**. We probably will not have time for fonts, but I have slides for them as well in case we do.

- Be comfortable with the basics of `gt`
  - create a table
  - format columns
  - create spanner heads
  - etc.
- Understand how to use additional fonts (if you so choose)

# Expectations for today

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Similar to last class, we will have times for you to practice, and times where I will ask you to follow along.

Please make sure R is up and running.

# A quick warning

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This will be a little more stats focused than basically any lecture we have through the first three courses of this sequence

# Finishing plot refinement

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# Uncertainty

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# Learning objectives

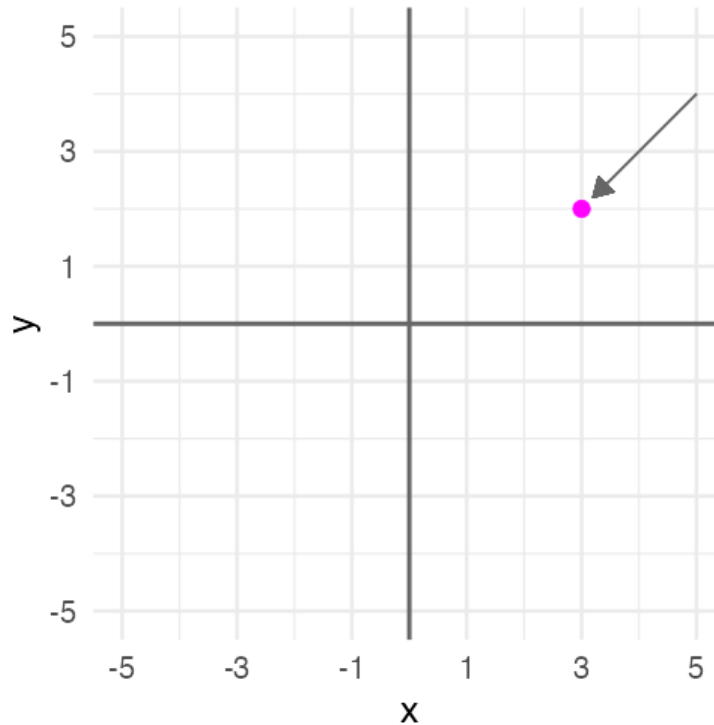
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1. Understand there are lots of different ways to visualize uncertainty, and the best method may often be non-standard.
2. Understand how to implement basic methods, and the resources available to you to implement more advanced methods

# The primary problem

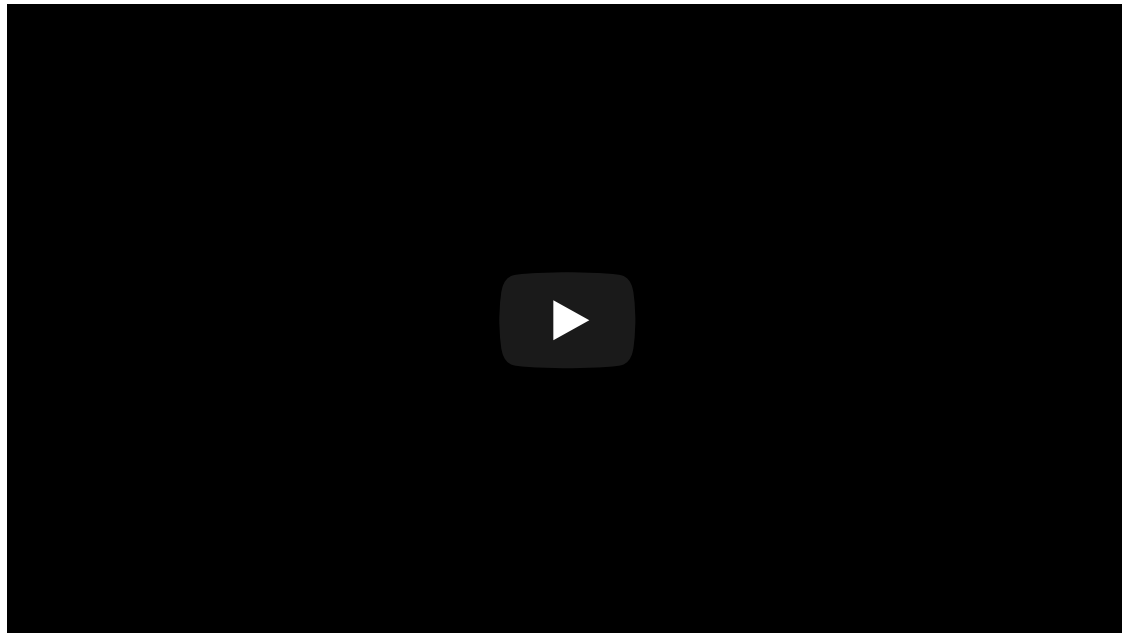
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- When we see a point on a plot, we interpret it as **THE** value.



# Let's have Dr. Kay explain

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# Some secondary problems

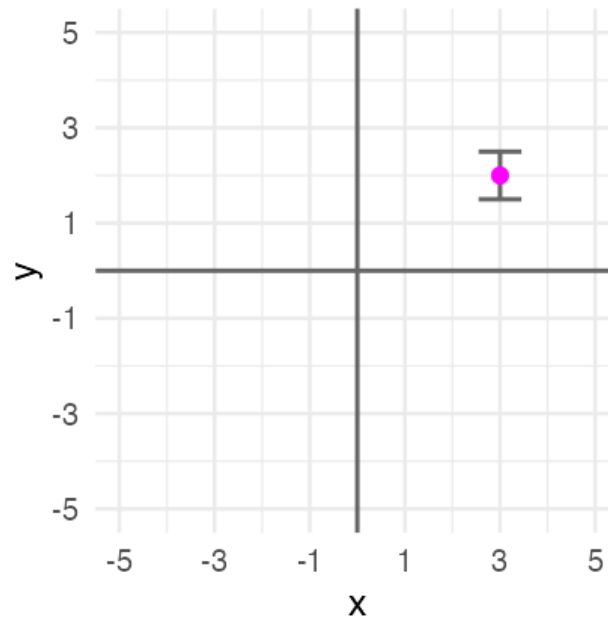
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- We're not great at understanding probabilities
- We regularly round probabilities to 100% or 0%
- As probabilities move to the tails, we're generally worse

# How do we typically communicate uncertainty?

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Error bars



# How?

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## Vertical error bars

### `geom_errorbar`

- Requires `ymin` and `ymax` aesthetics
- You have to supply these – no calculation for you

## Horizontal error bars

### `geom_errorbarh`

- Requires `xmin` and `xmax`

# Example

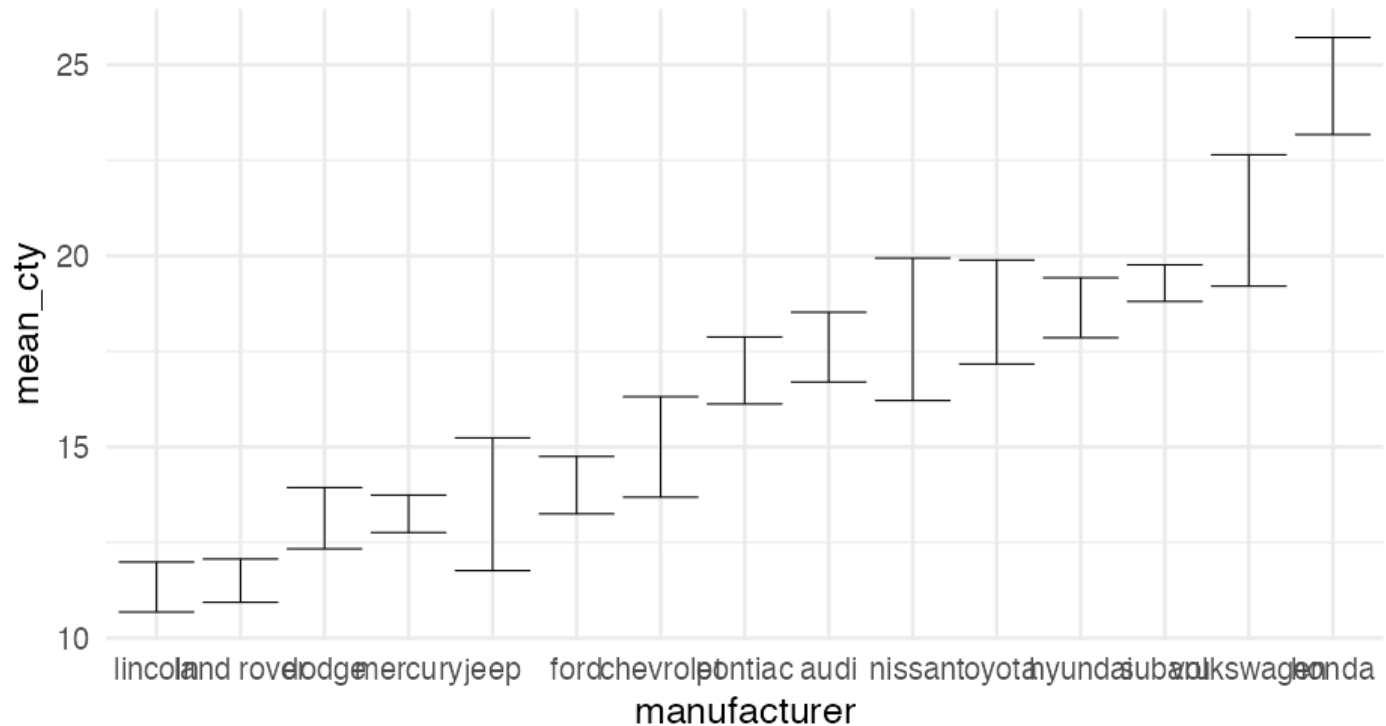
---

```
mpg_by_man <- mpg %>%  
  group_by(manufacturer) %>%  
  summarize(mean_cty = mean(cty),  
            se_cty = sd(cty) / sqrt(n()))
```

```
head(mpg_by_man)
```

```
## # A tibble: 6 × 3  
##   manufacturer mean_cty    se_cty  
##   <chr>         <dbl>    <dbl>  
## 1 audi         17.61111 0.4653967  
## 2 chevrolet    15         0.6710383  
## 3 dodge        13.13514 0.4085464  
## 4 ford         14         0.3829708  
## 5 honda        24.44444 0.6478835  
## 6 hyundai      18.64286 0.4006470
```

```
mpg_by_man %>%
  mutate(manufacturer = fct_reorder(manufacturer, mean_cty)) %>%
  ggplot(aes(manufacturer, mean_cty)) +
  geom_errorbar(
    aes(ymin = mean_cty + qnorm(0.025) * se_cty,
        ymax = mean_cty + qnorm(0.975) * se_cty)
  )
```





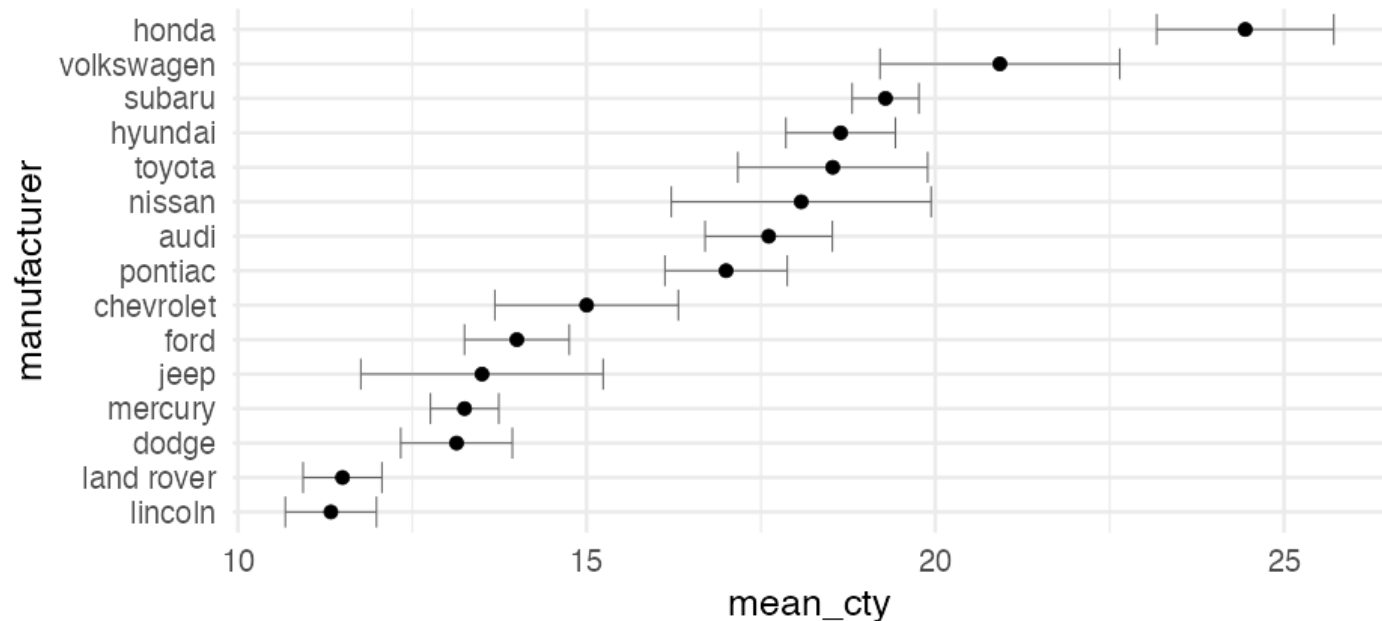
# Put points on top

---

Not under

```
mpg_by_man %>%  
  mutate(manufacturer = fct_reorder(manufacturer, mean_cty)) %>%  
  ggplot(aes(manufacturer, mean_cty)) +  
    geom_errorbar(  
      aes(ymin = mean_cty + qnorm(0.025) * se_cty,  
          ymax = mean_cty + qnorm(0.975) * se_cty)  
    ) +  
    geom_point()
```

```
mpg_by_man %>%
  mutate(manufacturer = fct_reorder(manufacturer, mean_cty)) %>%
  ggplot(aes(mean_cty, manufacturer)) +
    geom_errorbarh(
      aes(xmin = mean_cty - 1.96 * se_cty,
          xmax = mean_cty + 1.96 * se_cty),
      color = "gray40"
    ) +
    geom_point()
```



# Practice

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- Use the Palmer penguins dataset
- Plot the mean `bill_length_mm` for each species with 95% confidence intervals

```
library(palmerpenguins)
penguins
```

```
## # A tibble: 344 × 8
##   species island    bill_length_mm
##   <fct>    <fct>          <dbl>
## 1 Adelie   Torgersen         39.1
## 2 Adelie   Torgersen         39.5
## 3 Adelie   Torgersen         40.3
## 4 Adelie   Torgersen          NA
## 5 Adelie   Torgersen         36.7
## 6 Adelie   Torgersen         39.3
## # ... with 338 more rows, and 5 more variables:
## #   bill_depth_mm <dbl>,
## #   flipper_length_mm <int>,
## #   body_mass_g <int>, sex <fct>, year <int>
```

05:00

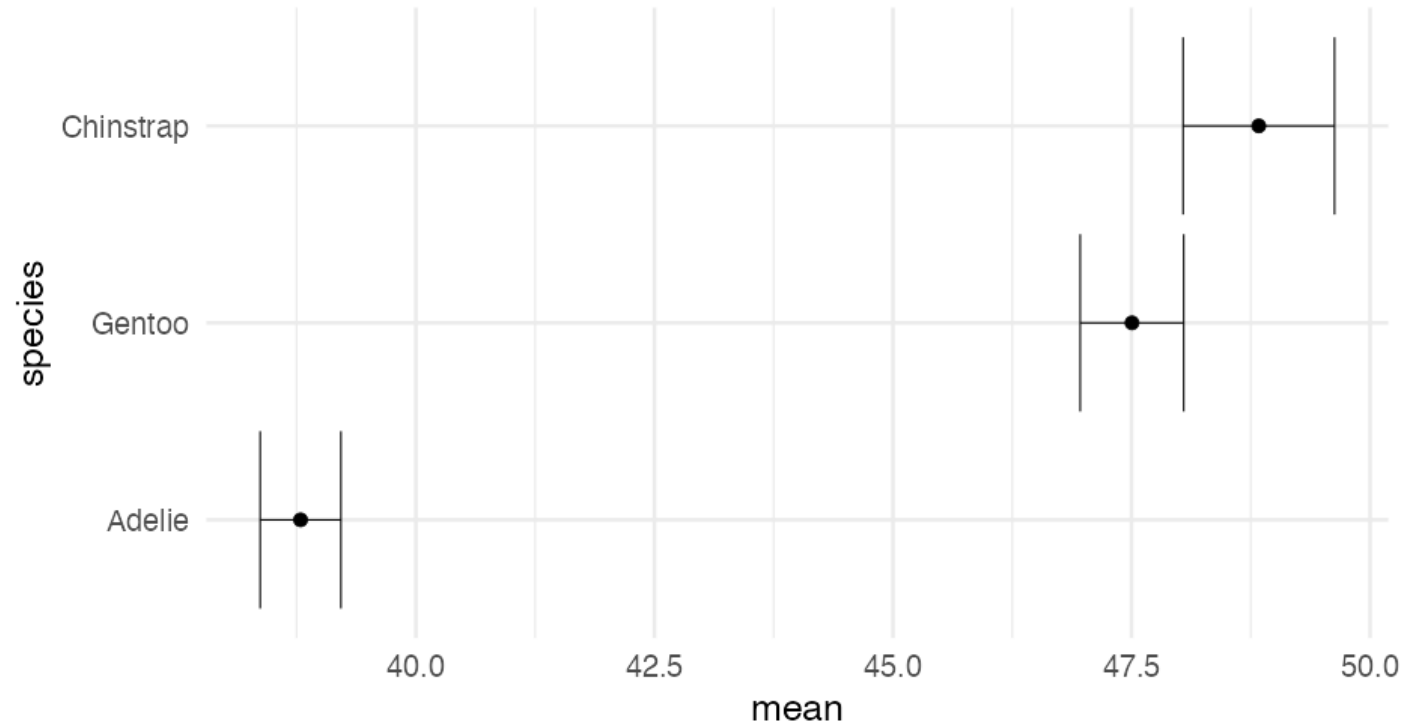
# Solution

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Or one possible solution

```
mn_se <- penguins %>%
  group_by(species) %>%
  summarize(
    mean = mean(bill_length_mm, na.rm = TRUE),
    se = sd(bill_length_mm, na.rm = TRUE) / sqrt(n()),
    lower = mean + qnorm(0.025) * se,
    upper = mean + qnorm(0.975) * se,
  ) %>%
  mutate(species = fct_reorder(species, mean))

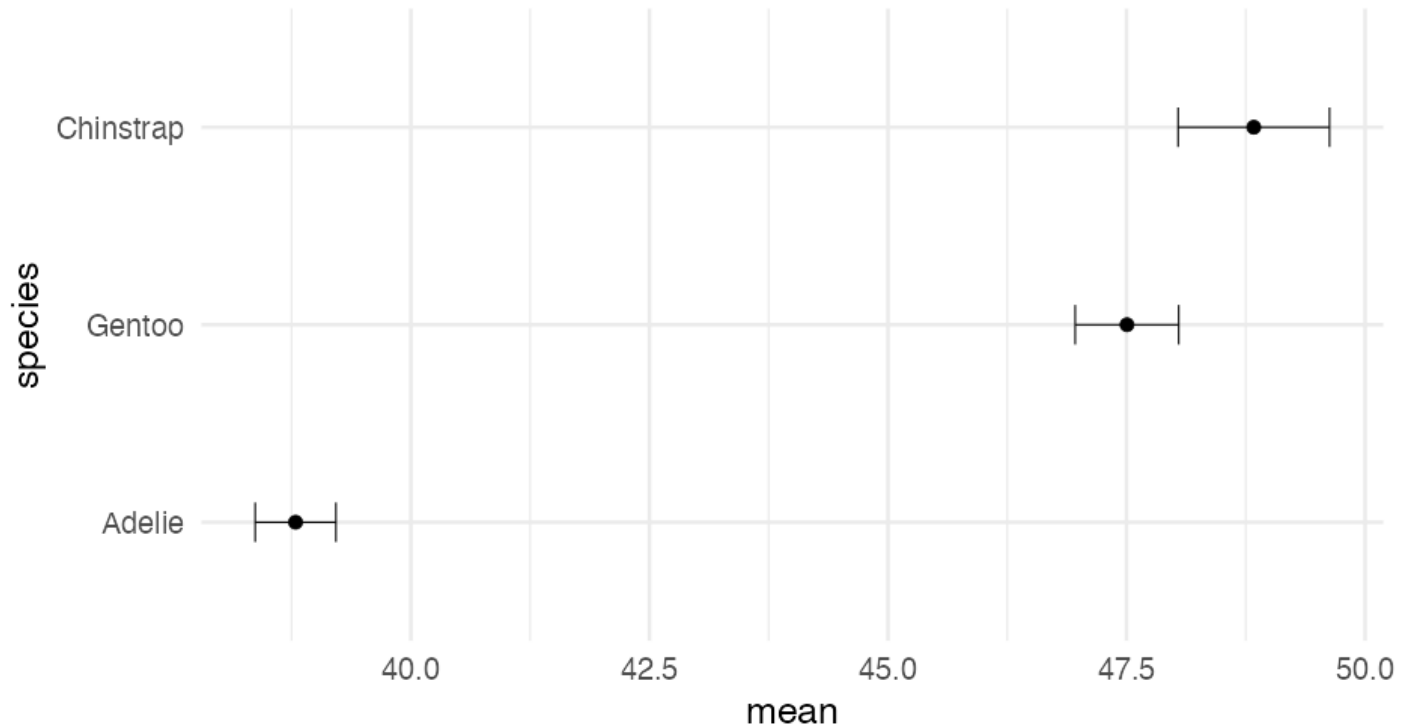
ggplot(mn_se, aes(mean, species)) +
  geom_errorbarh(aes(xmin = lower, xmax = upper)) +
  geom_point()
```



# Change the height

---

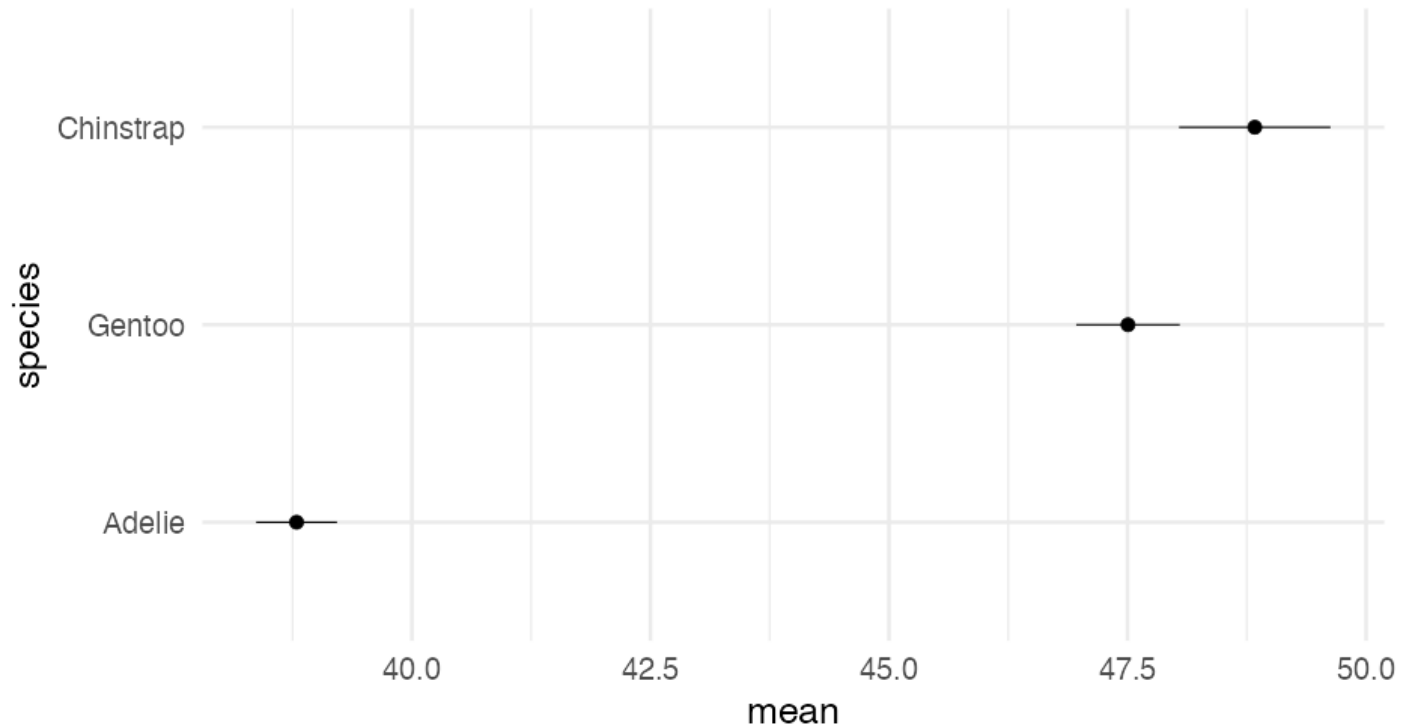
```
ggplot(mn_se, aes(mean, species)) +  
  geom_errorbarh(aes(xmin = lower, xmax = upper), height = 0.2) +  
  geom_point()
```



# Slight variant

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```
ggplot(mn_se, aes(mean, species)) +  
  geom_linerange(aes(xmin = lower, xmax = upper)) +  
  geom_point()
```



# Dodging

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```
props <- mpg %>%  
  count(drv, year) %>%  
  mutate(prop = n / sum(n),  
         prop_se = sqrt((prop * (1 - prop)) / n))
```

```
head(props)
```

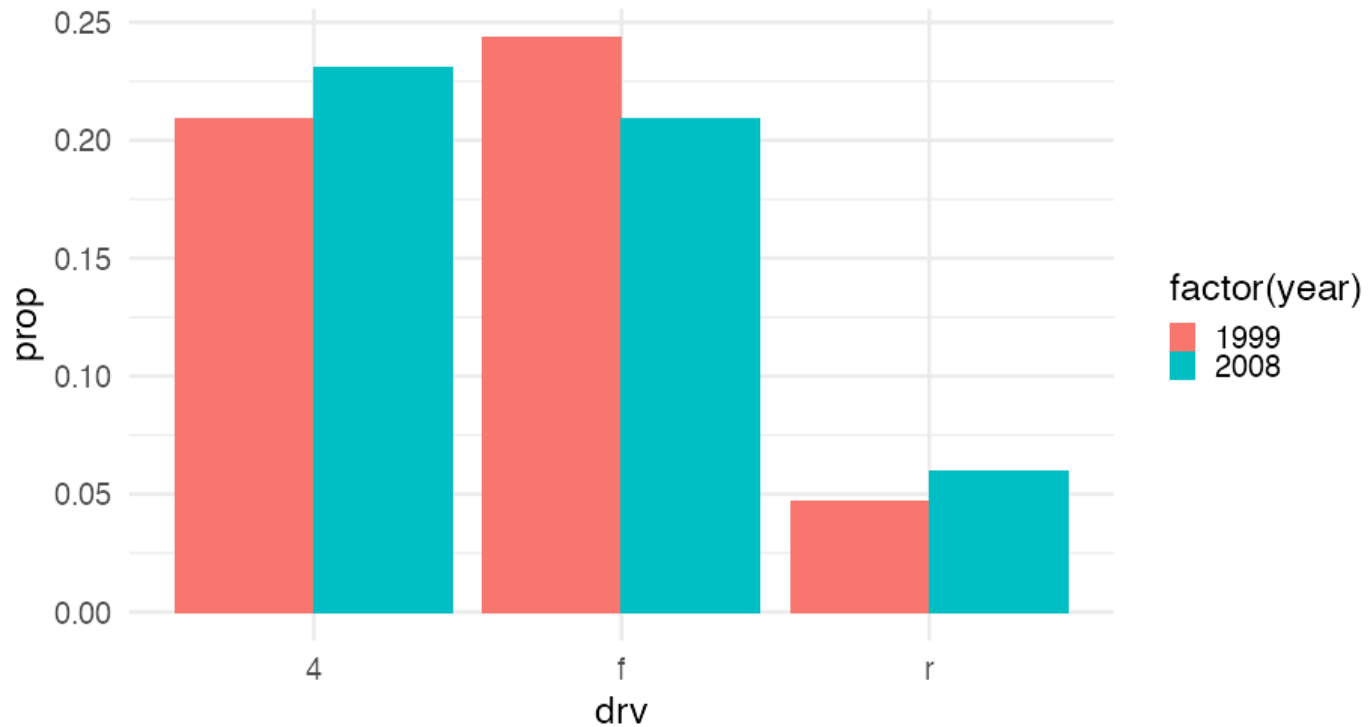
```
## # A tibble: 6 × 5  
##   drv   year     n      prop   prop_se  
##   <chr> <int> <int>    <dbl>    <dbl>  
## 1 4      1999     49 0.2094017 0.05812594  
## 2 4      2008     54 0.2307692 0.05733508  
## 3 f      1999     57 0.2435897 0.05685528  
## 4 f      2008     49 0.2094017 0.05812594  
## 5 r      1999     11 0.04700855 0.06381703  
## 6 r      2008     14 0.05982906 0.06338631
```



# Bar plot

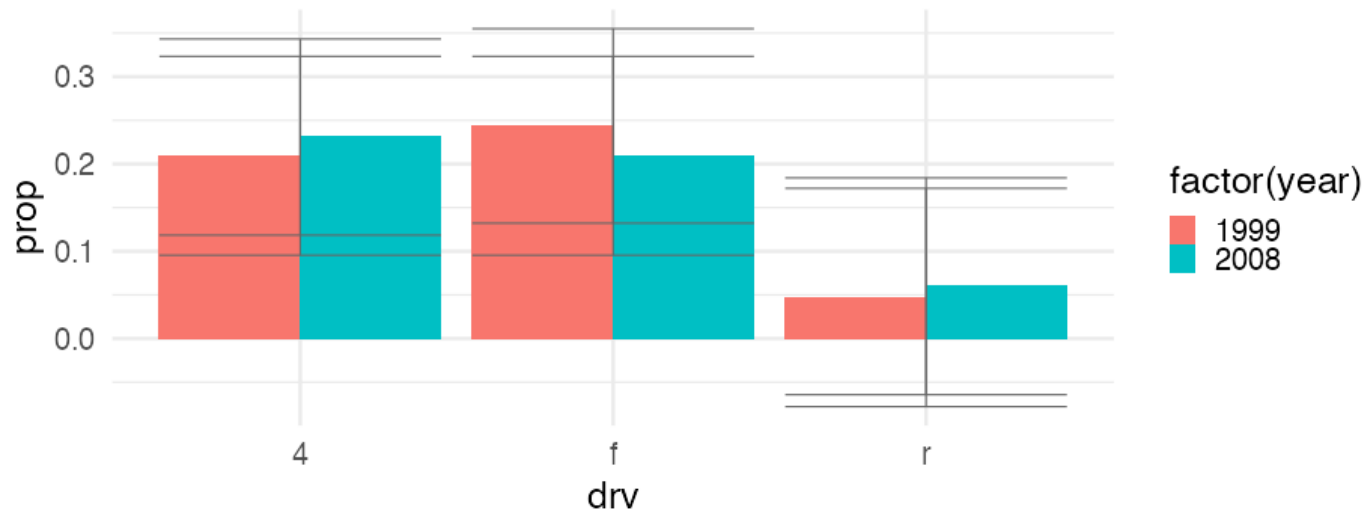
---

```
ggplot(props, aes(drv, prop)) +  
  geom_col(aes(fill = factor(year)), position = "dodge")
```





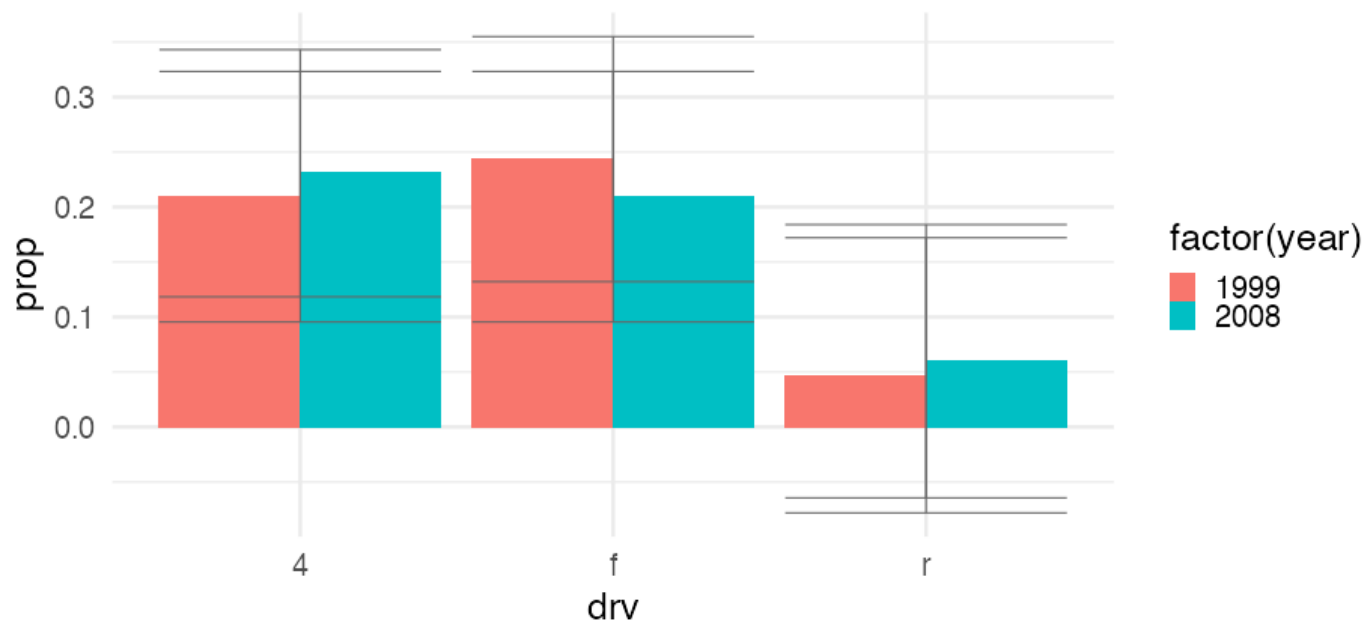
```
ggplot(props, aes(drv, prop)) +  
  geom_col(aes(fill = factor(year)), position = "dodge") +  
  geom_errorbar(  
    aes(ymin = prop - 1.96 * prop_se,  
        ymax = prop + 1.96 * prop_se),  
    color = "gray40"  
  )
```



```

pd <- position_dodge(.9)
ggplot(props, aes(drv, prop)) +
  geom_col(aes(fill = factor(year)), position = pd) +
  geom_errorbar(
    aes(ymin = prop - 1.96 * prop_se,
        ymax = prop + 1.96 * prop_se),
    color = "gray40",
    position = pd
  )

```

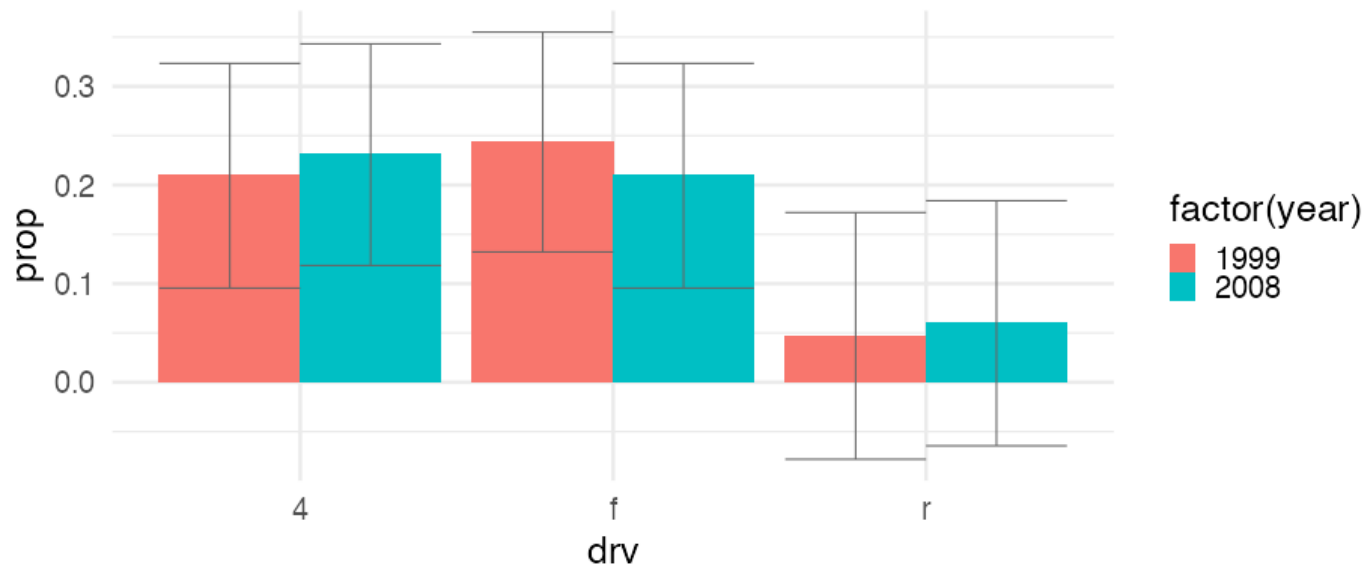




```

pd <- position_dodge(.9)
ggplot(props, aes(drv, prop)) +
  geom_col(aes(fill = factor(year)), position = pd) +
  geom_errorbar(
    aes(ymin = prop - 1.96 * prop_se,
        ymax = prop + 1.96 * prop_se,
        group = year
    ),
    color = "gray40",
    position = pd
  )

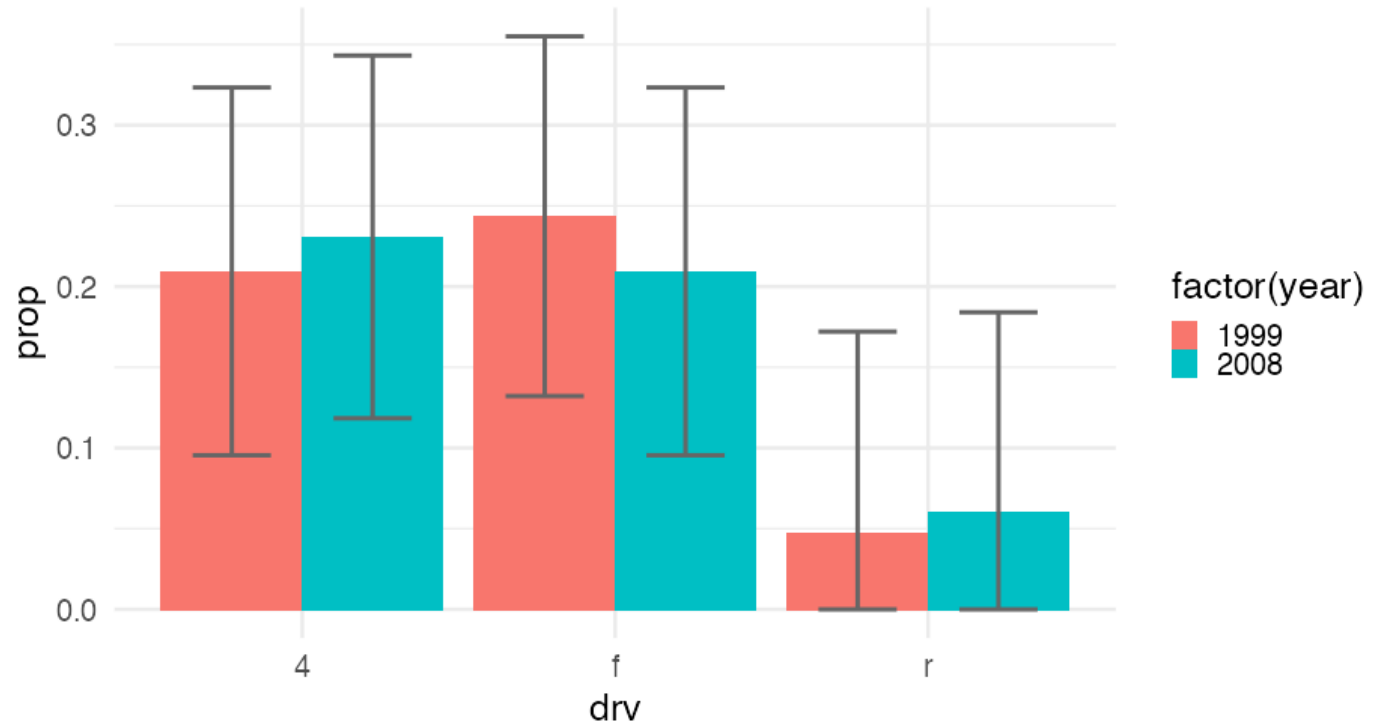
```



```

pd <- position_dodge(.9)
ggplot(props, aes(drv, prop)) +
  geom_col(aes(fill = factor(year)), position = pd) +
  geom_errorbar(
    aes(
      ymin = ifelse(
        prop - 1.96 * prop_se < 0,
        0,
        prop - 1.96*prop_se
      ),
      ymax = prop + 1.96 * prop_se,
      group = year
    ),
    color = "gray40",
    position = pd,
    width = 0.5,
    size = 1.4
  )

```



# Explain error bars

---

Error bars could represent any of the following

- Standard deviation (of the data)
- Standard error (of the estimate)
- Confidence interval (of the estimate)

Possibly through a caption, make sure your audience knows what your represent.

If Confidence intervals, state the interval size (e.g., 68%, 90%, 95%)



# Thinking about uncertainty

---

Uncertainty means exactly what it sounds like – we are not 100% sure.

- We are nearly always uncertain of future events (forecasting)
- We can also be uncertain about past events
  - I saw a parked car at 8 AM, but the next time I looked at 2PM it was gone. What time did it leave?

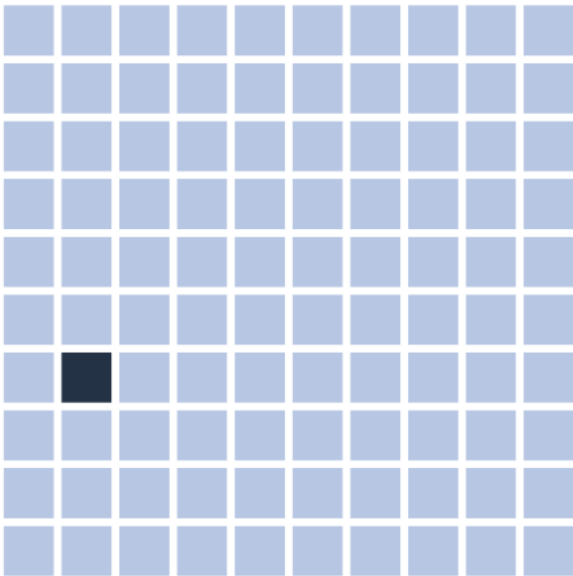
## Quantifying uncertainty

- We quantify our uncertainty mathematically using probability
- Framing probabilities as frequencies is generally more intuitive

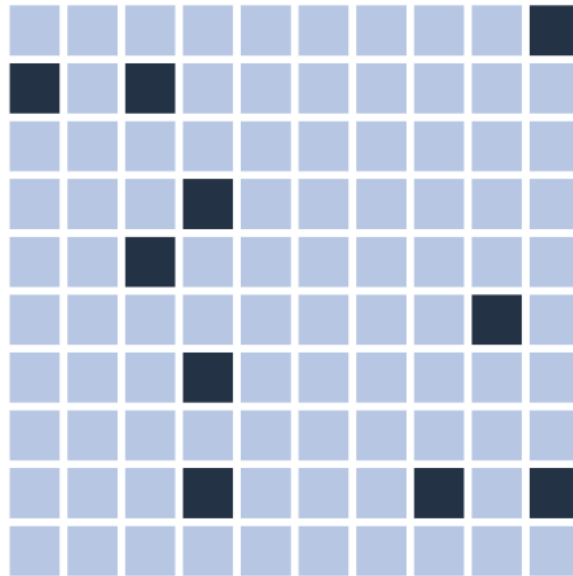
Framing a  
single  
uncertainty

---

1% chance



10% chance



40% chance



■ success ■ failure

# How do we make these?

---

- Start out by making a grid

```
grid <- expand.grid(x = 1:20, y = 1:20)
head(grid)
```

```
##      x  y
##  1  1  1
##  2  2  1
##  3  3  1
##  4  4  1
##  5  5  1
##  6  6  1
```

```
tail(grid)
```

```
##      x  y
## 395 15 20
## 396 16 20
## 397 17 20
## 398 18 20
## 399 19 20
## 400 20 20
```

# Look at the grid

---

```
ggplot(grid, aes(x, y)) +  
  geom_tile(color = "gray40",  
            fill = "white") +  
  theme_void()
```



# Create occurrence rate

---

- For each sequence of  $x$ , create a variable that has the given occurrence rate

How?

- Plenty of options, here's one

Please follow along

# Consider 10%

---

```
# create your grid
grid <- expand.grid(x = 1:20, y = 1:20)

# n to sample
n_sample <- nrow(grid) * .10

set.seed(86753098)
samp <- sample(seq_len(nrow(grid)), n_sample)
head(samp)
```

```
## [1] 318 134 180 283 177 248
```

```
length(samp)
```

```
## [1] 40
```

# Create the variable

---

```
grid <- grid %>%  
  rownames_to_column("row_id") %>%  
  mutate(event = ifelse(row_id %in% samp, "Yes", "No"))  
head(grid)
```

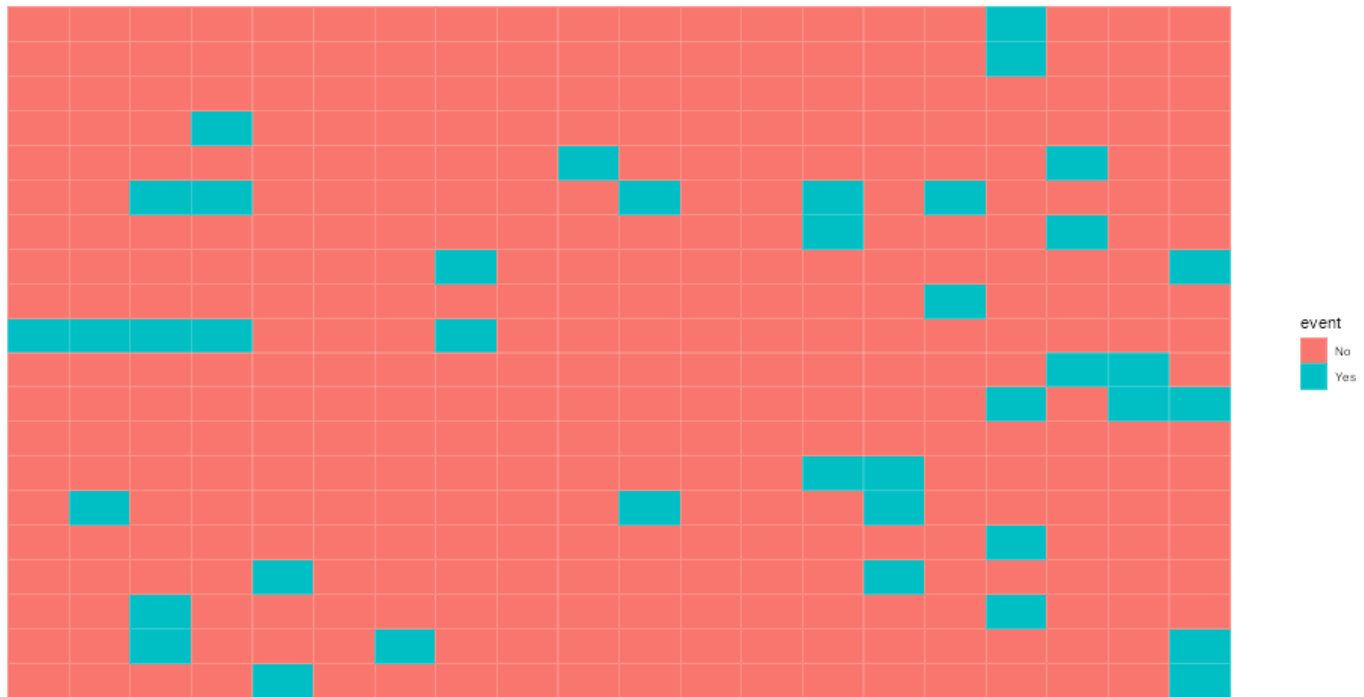
```
##   row_id x y event  
## 1      1 1 1    No  
## 2      2 2 1    No  
## 3      3 3 1    No  
## 4      4 4 1    No  
## 5      5 5 1   Yes  
## 6      6 6 1    No
```



# Fill in

---

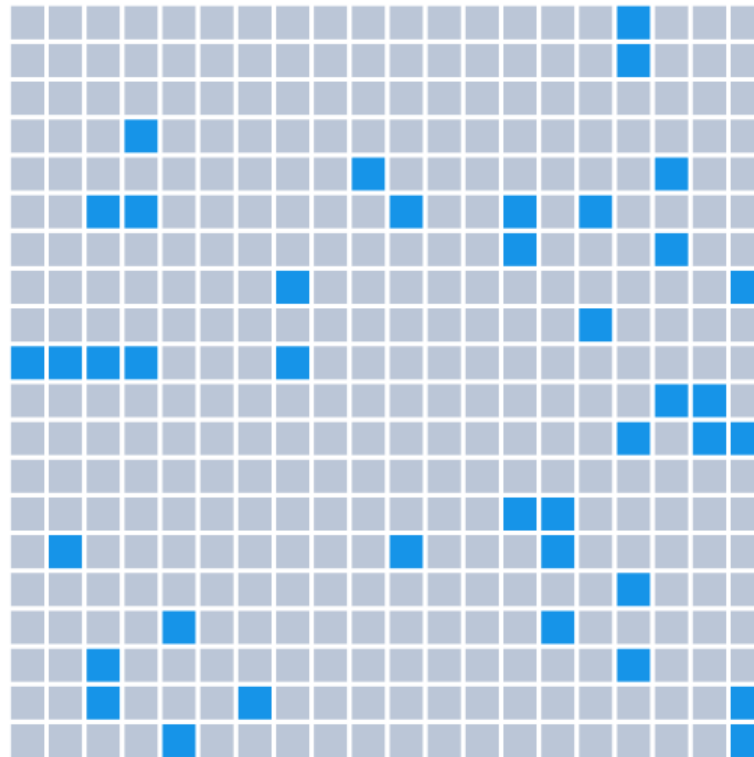
```
ggplot(grid, aes(x, y)) +  
  geom_tile(aes(fill = event), color = "white") +  
  theme_void()
```



# Customize

---

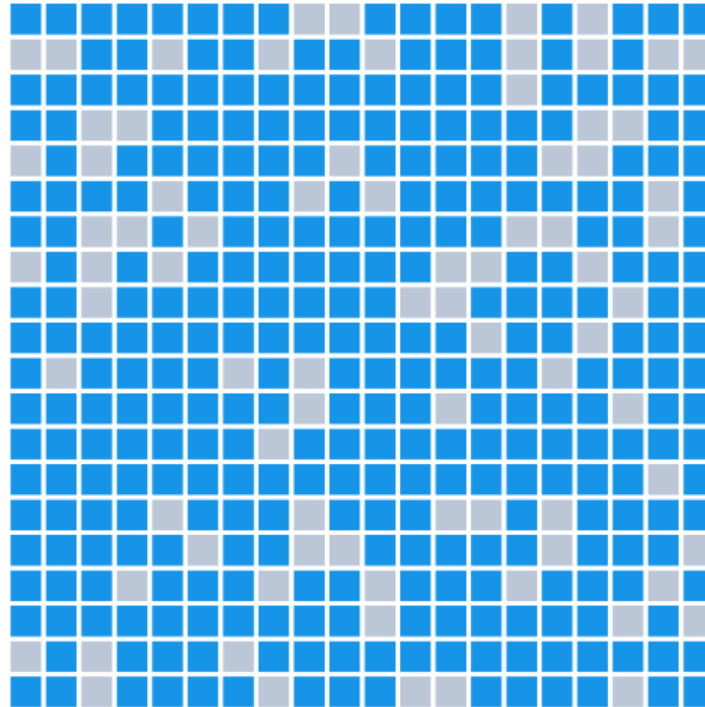
```
library(colorspace)
ggplot(grid, aes(x, y)) +
  geom_tile(aes(fill = event), color = "white", size = 1.4) +
  scale_fill_manual(
    name = "Event Occurred",
    values = c(
      desaturate(lighten("#1694E8", 0.5), 0.7),
      "#1694E8"
    )
  ) +
  coord_fixed() +
  theme_void() +
  theme(legend.position = c(0.75, 0),
        legend.direction = "horizontal",
        plot.margin = margin(b = 1, unit = "cm"))
```



Event Occurred     No     Yes

# Chance of rain

---

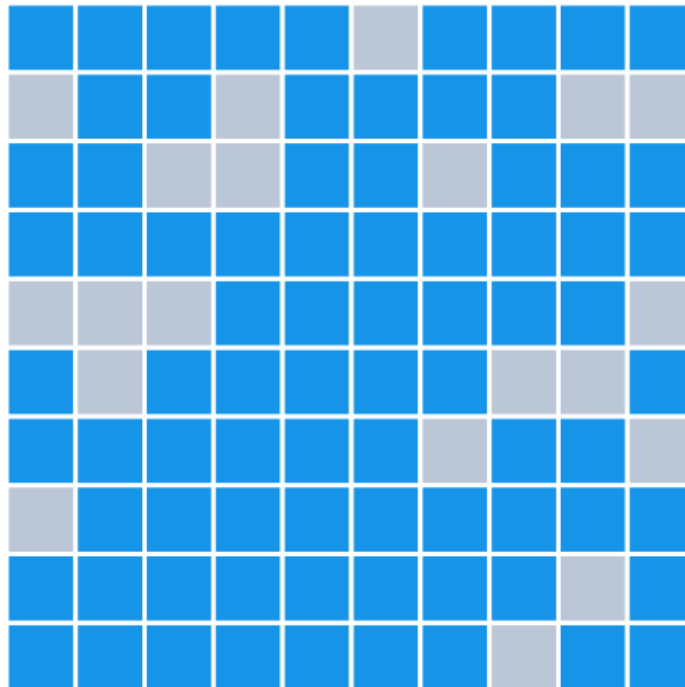


Event Occurred    ■ No    ■ Yes

# Vary grid size

---

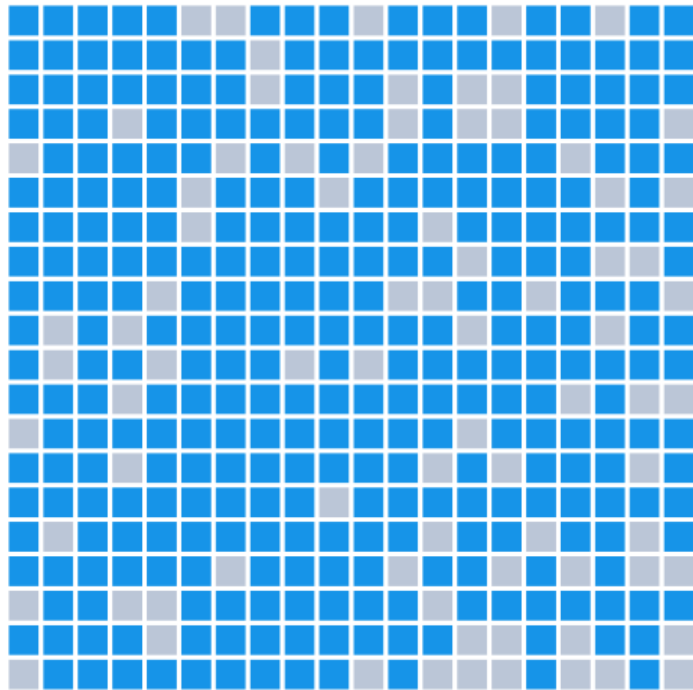
10 x 10



# Vary grid size

---

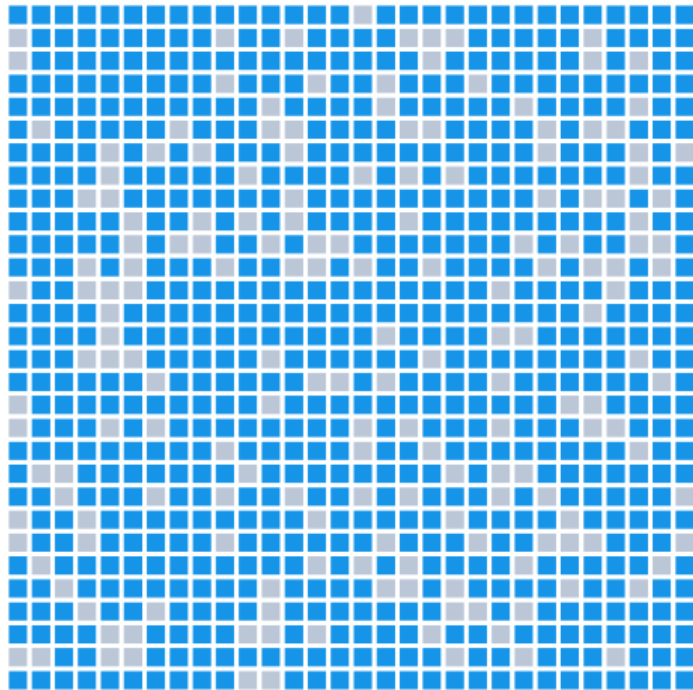
20 x 20



# Vary grid size

---

30 x 30



Optimal size might depend on your venue

# Practice

---

- Create a new grid showing 41% likelihood of something happening
- Vary the fill colors and grid size
- Compare with a neighbor – what do you like about yours vs. theirs?

05:00



Non-discrete  
probabilities

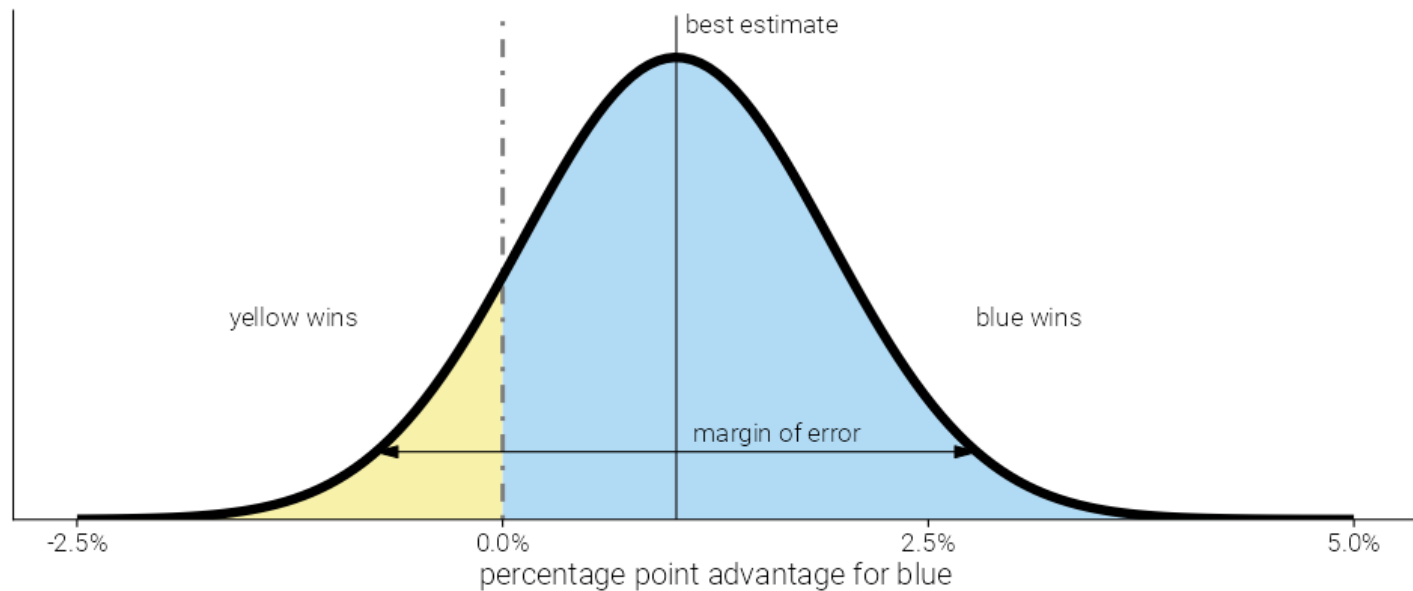
---

# Hypothetical

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Blue party has 1% advantage w/ margin of error of 1.76 percentage points

Who will win and **by how much?**



# A bit of math

---

Our distribution was defined by  $\mu = 1.02$  and  $sd = 0.9$ .

- What's the chance the end result is **below zero**? (yellow wins)

# The hard way

---

Calculate the exact probability

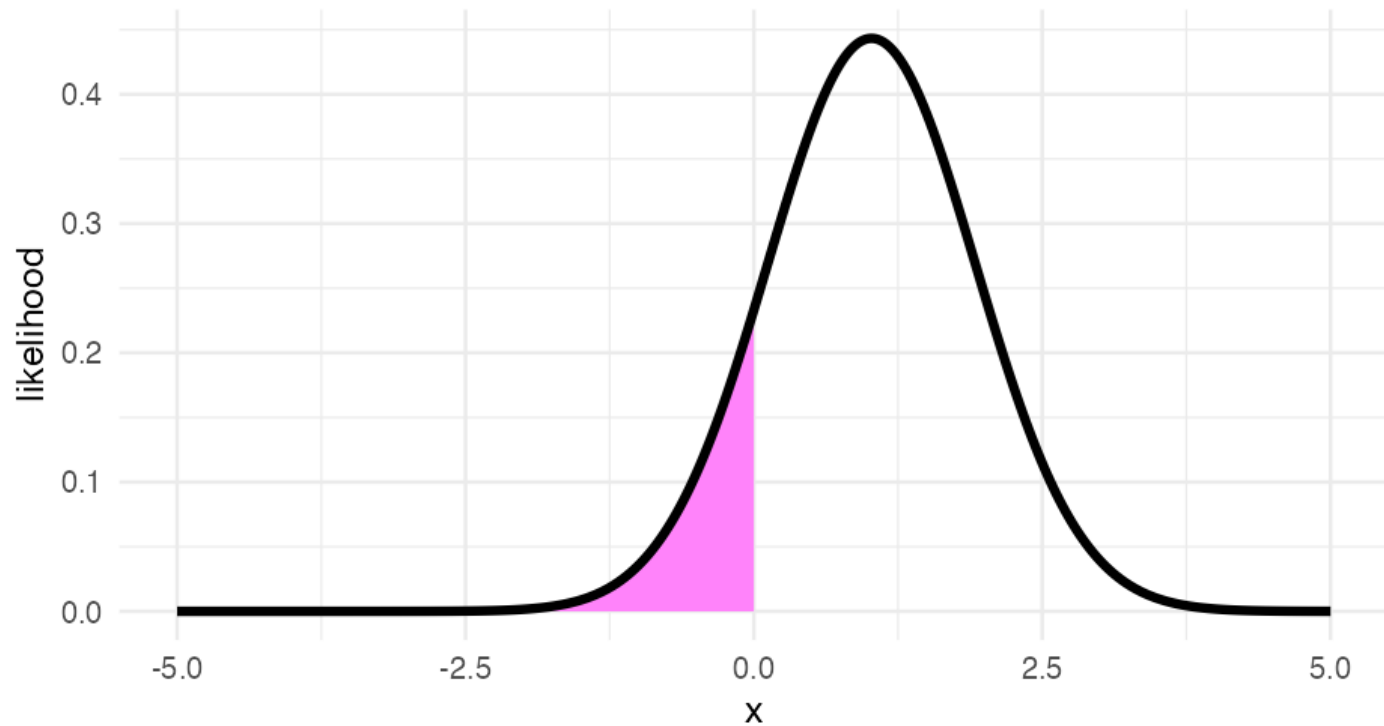
The distribution

```
x <- seq(-5, 5, 0.001) # some sample data
likelihood <- dnorm(x, 1.02, 0.9) # probability of occurring
sim <- data.frame(x, likelihood)

ggplot(sim, aes(x, likelihood)) +
  geom_line(size = 1.2)
```

# How do we calculate this portion?

---



# Integrate

---

```
zab <- filter(sim, x <= 0)  
pracma::trapz(zab$x, zab$likelihood)
```

```
## [1] 0.129
```

# Easier: Simulate

---

```
random_draws <- rnorm(1e5, 1.02, 0.9)
table(random_draws > 0) / 1e5
```

```
##
## FALSE  TRUE
## 0.128 0.872
```

# Problem

---

This approach works okay, but...

- We're not great at interpreting probabilities
- Not great at inferring a probability from a density



# Discretized plot

---

```
ppoints(50)
```

```
## [1] 0.01 0.03 0.05 0.07 0.09 0.11 0.13 0.15
## [9] 0.17 0.19 0.21 0.23 0.25 0.27 0.29 0.31
## [17] 0.33 0.35 0.37 0.39 0.41 0.43 0.45 0.47
## [25] 0.49 0.51 0.53 0.55 0.57 0.59 0.61 0.63
## [33] 0.65 0.67 0.69 0.71 0.73 0.75 0.77 0.79
## [41] 0.81 0.83 0.85 0.87 0.89 0.91 0.93 0.95
## [49] 0.97 0.99
```

```
qnorm(ppoints(50), 1.02, 0.9)
```

```
## [1] -1.07371 -0.67271 -0.46037 -0.30821
## [5] -0.18668 -0.08388 0.00625 0.08721
## [9] 0.16125 0.22989 0.29422 0.35504
## [13] 0.41296 0.46847 0.52195 0.57373
## [17] 0.62408 0.67321 0.72133 0.76861
## [21] 0.81521 0.86126 0.90690 0.95226
## [25] 0.99744 1.04256 1.08774 1.13310
## [29] 1.17874 1.22479 1.27139 1.31867
## [33] 1.36679 1.41592 1.46627 1.51805
## [37] 1.57153 1.62704 1.68496 1.74578
## [41] 1.81011 1.87875 1.95279 2.03375
## [45] 2.12388 2.22668 2.34821 2.50037
```

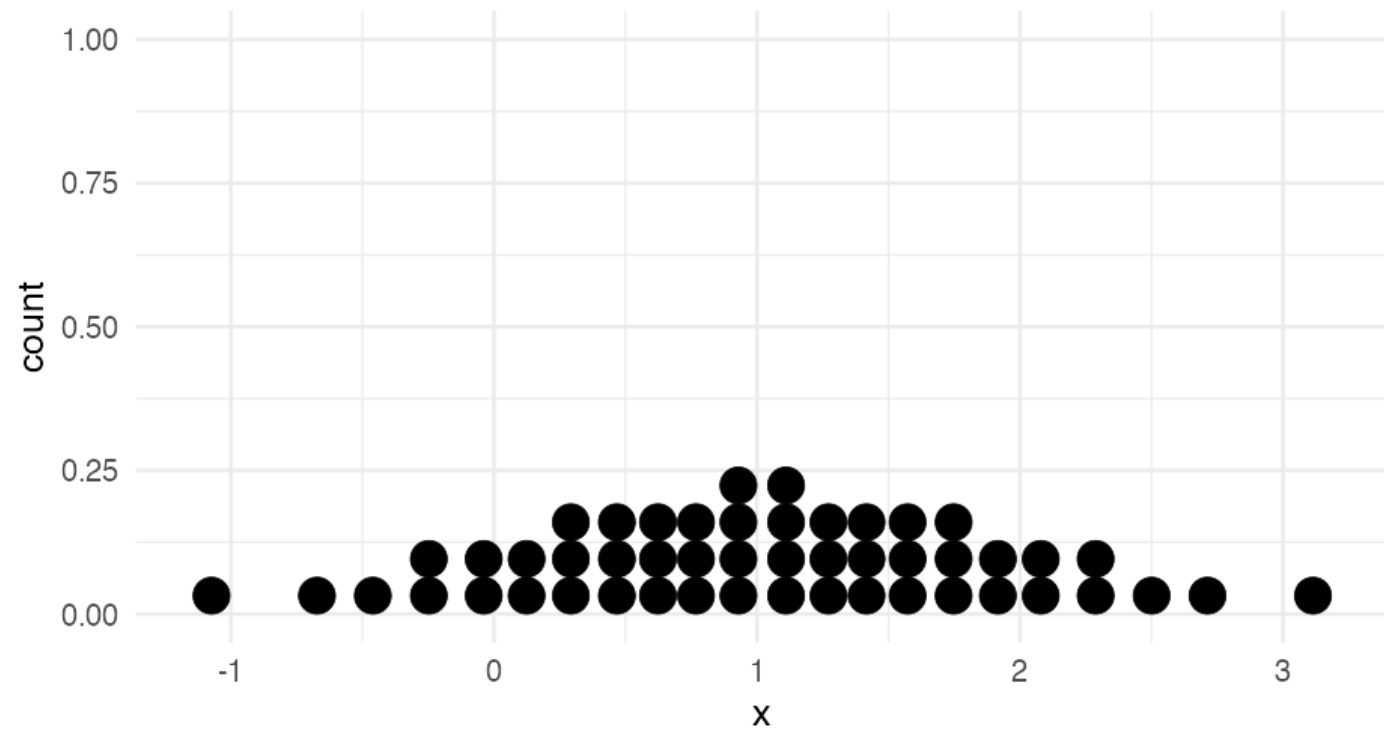
```
discretized <- data.frame(  
  x = qnorm(ppoints(50), 1.02, 0.9)  
  ) %>%  
  mutate(winner = ifelse(x <= 0, "#b1daf4", "#f8f1a9"))  
  
head(discretized)
```

```
##           x  winner  
## 1 -1.0737 #b1daf4  
## 2 -0.6727 #b1daf4  
## 3 -0.4604 #b1daf4  
## 4 -0.3082 #b1daf4  
## 5 -0.1867 #b1daf4  
## 6 -0.0839 #b1daf4
```

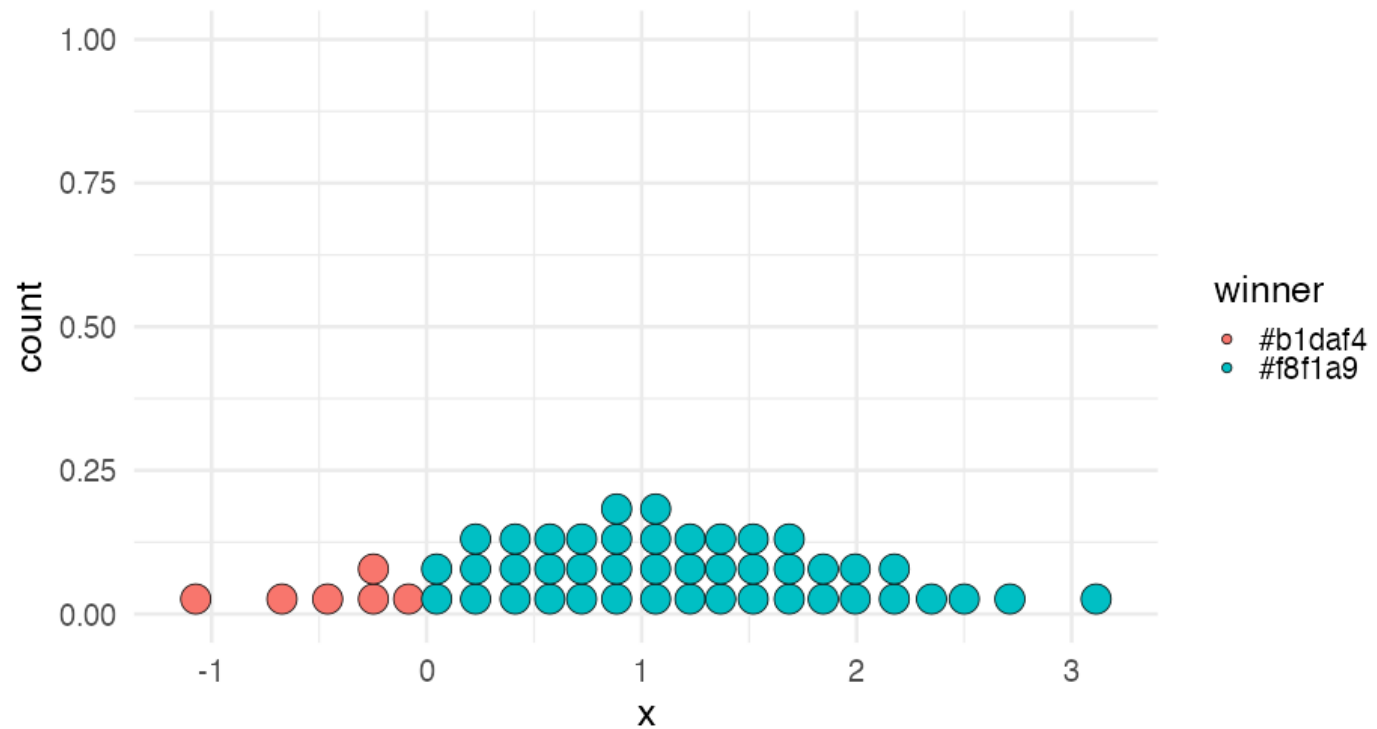
```
tail(discretized)
```

```
##           x  winner  
## 45  2.12 #f8f1a9  
## 46  2.23 #f8f1a9  
## 47  2.35 #f8f1a9  
## 48  2.50 #f8f1a9  
## 49  2.71 #f8f1a9  
## 50  3.11 #f8f1a9
```

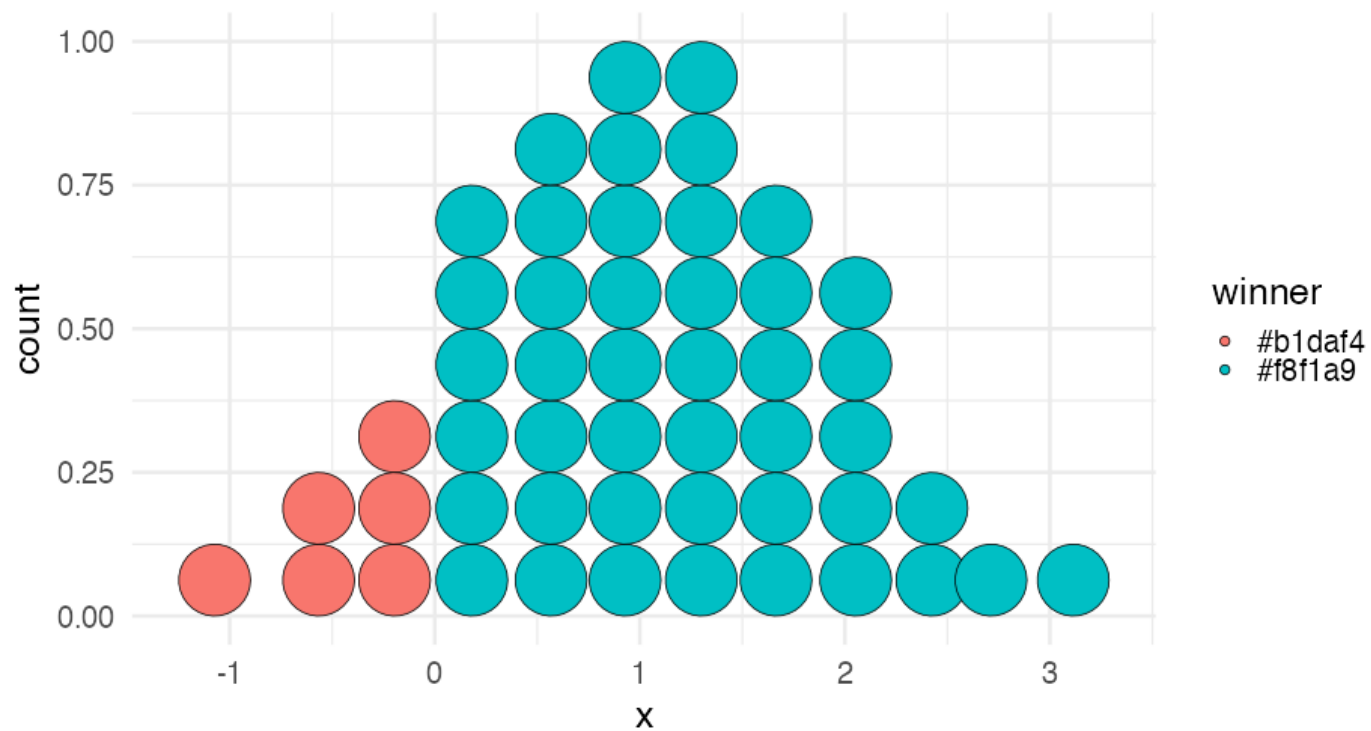
```
ggplot(discretized, aes(x)) +  
  geom_dotplot()
```



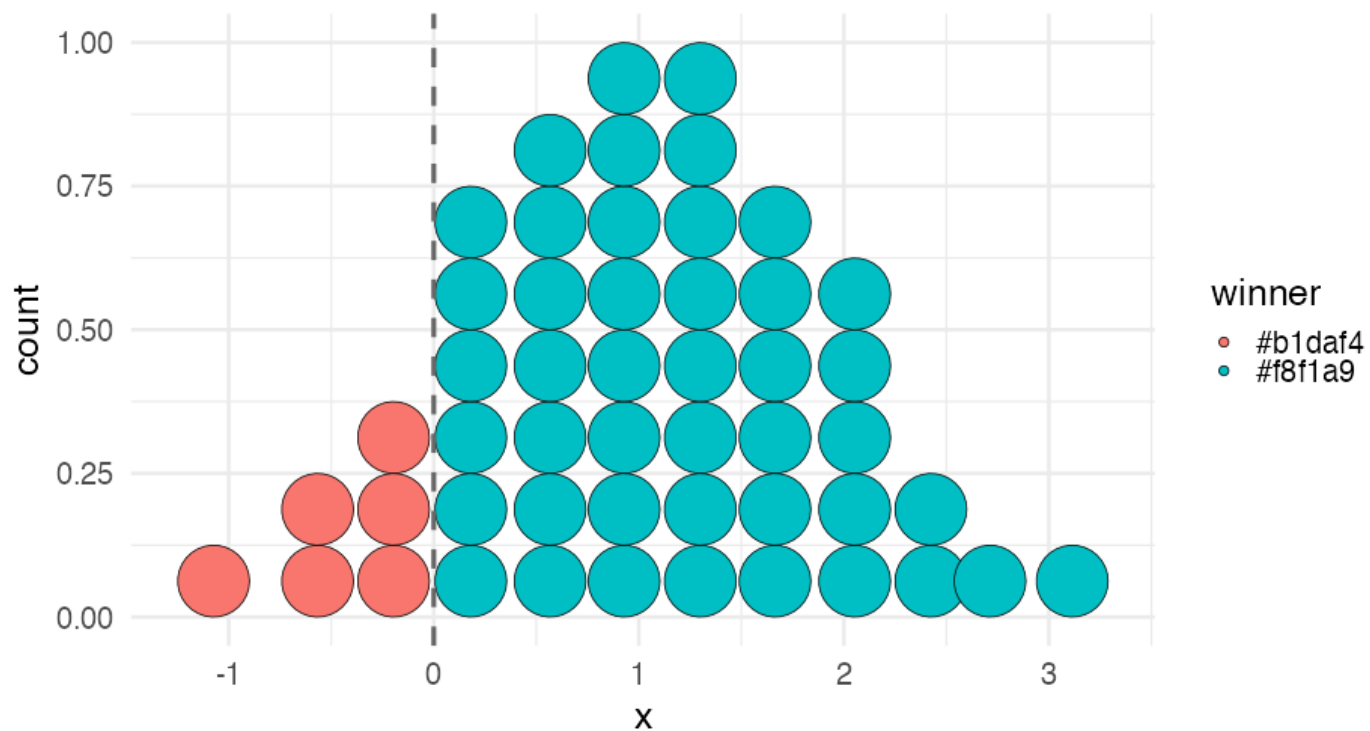
```
ggplot(discretized, aes(x)) +  
  geom_dotplot(aes(fill = winner))
```



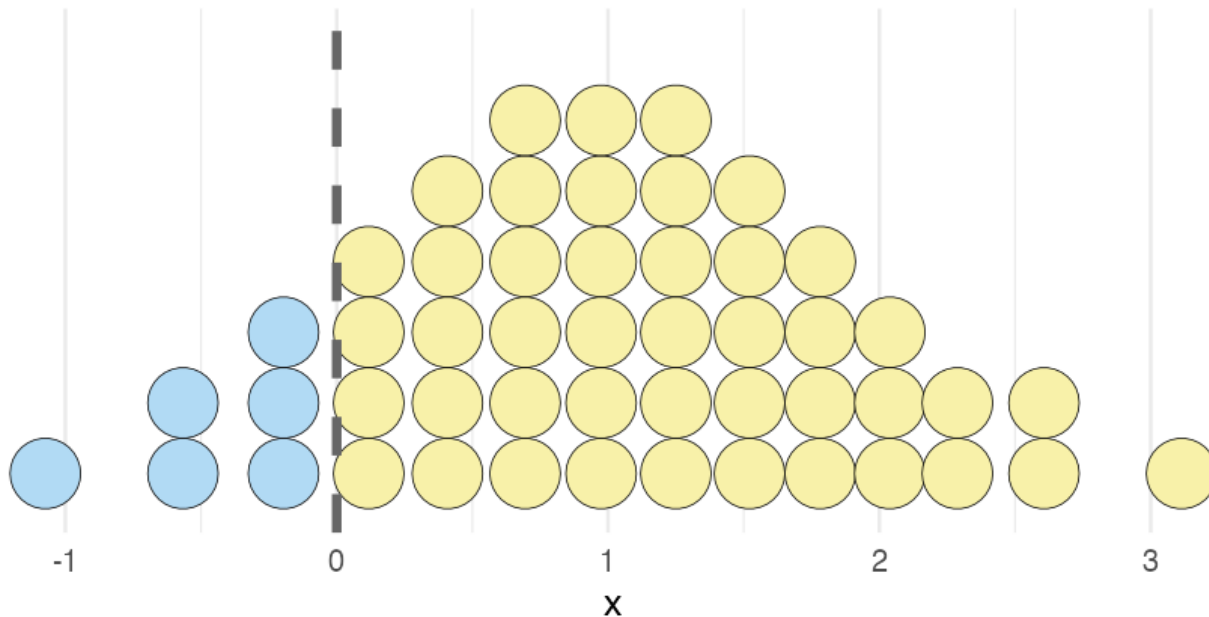
```
ggplot(discretized, aes(x)) +  
  geom_dotplot(aes(fill = winner), binwidth = 0.35)
```



```
ggplot(discretized, aes(x)) +  
  geom_dotplot(aes(fill = winner), binwidth = 0.35) +  
  geom_vline(xintercept = 0,  
             color = "gray40",  
             linetype = "dashed",  
             size = 1.5)
```



```
ggplot(discretized, aes(x)) +
  geom_dotplot(aes(fill = winner), binwidth = 0.26) +
  geom_vline(xintercept = 0,
             color = "gray40",
             linetype = 2,
             size = 3) +
  scale_fill_identity(guide = "none") +
  scale_y_continuous(name = "",
                     breaks = NULL)
```



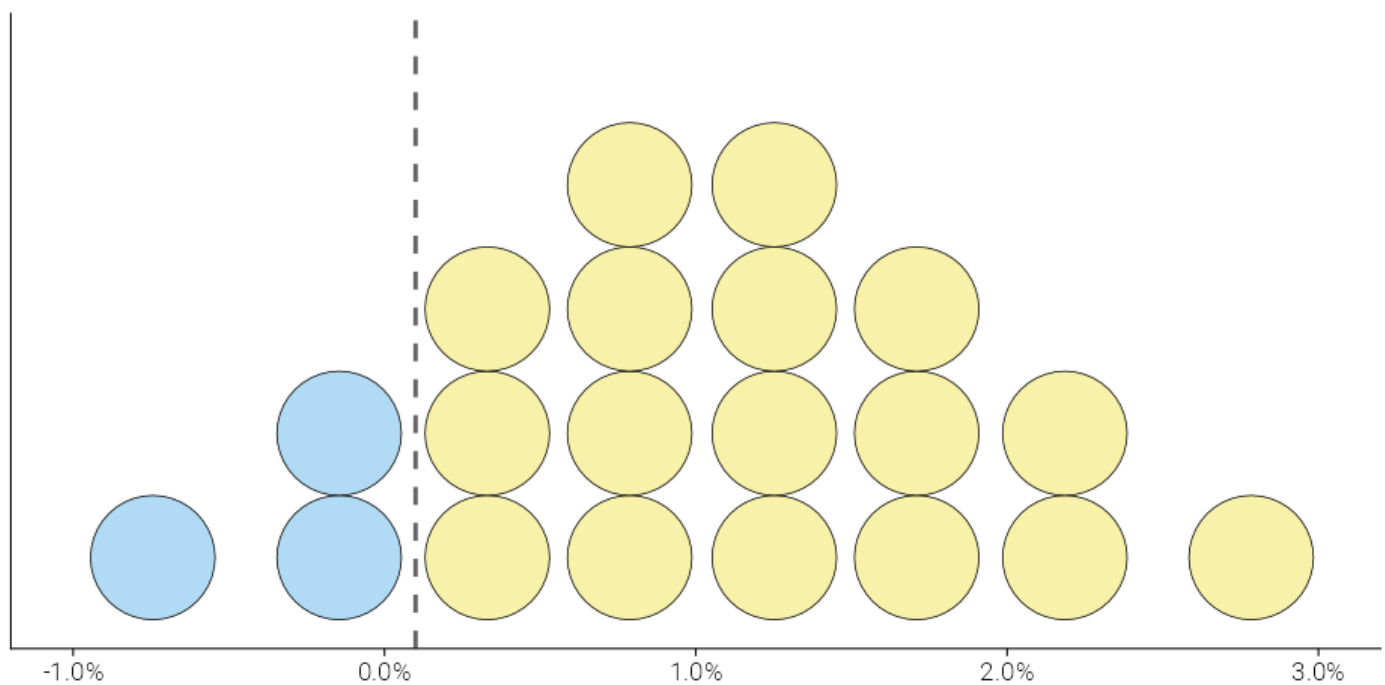
# Probs too many though

---

```
discretized2 <- data.frame(
  x = qnorm(ppoints(20), 1.02, 0.9)
) %>%
  mutate(winner = ifelse(x <= 0, "#b1daf4", "#f8f1a9"))

ggplot(discretized2, aes(x)) +
  geom_dotplot(aes(fill = winner), binwidth = 0.4) +
  geom_vline(
    xintercept = 0.1,
    color = "gray40",
    linetype = 2,
    size = 1.4) +
  scale_fill_identity(guide = "none") +
  scale_x_continuous(
    name = "",
    limits = c(-1, 3),
    labels = scales::percent_format(scale = 1)
  ) +
  theme_dviz_open(20, font_family = "Roboto Light") +
  scale_y_continuous(breaks = NULL,
    name = "") +
  labs(caption = "Each ball represents 5% probability")
```





Each ball represents 5% probability

# Uncertainty of point estimates

---

# Quick (hopefully) review

---

- What is a standard error?
- Standard deviation of the sampling distribution
- What is the sampling distribution?
- Samples from the underlying, population-based, generative distribution
- What does this mean, exactly?
- Let's simulate to explore

# Simulation

---

- Imagine the "real" distribution has  $\mu = 100$  and  $\sigma = 10$ .
- Let's draw a sample of 10 from this distribution

```
set.seed(123)
samp10a <- rnorm(n = 10, mean = 100, sd = 10)
samp10a
```

```
## [1] 94.4 97.7 115.6 100.7 101.3 117.2 104.6
## [8] 87.3 93.1 95.5
```

- Calculate the mean

```
mean(samp10a)
```

```
## [1] 101
```

# Do it a second time

---

```
samp10b <- rnorm(n = 10, mean = 100, sd = 10)
samp10b
```

```
## [1] 112.2 103.6 104.0 101.1 94.4 117.9 105.0
## [8] 80.3 107.0 95.3
```

```
mean(samp10b)
```

```
## [1] 102
```

# Do it a bunch of times

---

```
samples <- replicate(1000, rnorm(10, mean = 100, sd = 10),  
                      simplify = FALSE)
```

```
samples
```

```
## [[1]]  
## [1] 89.3 97.8 89.7 92.7 93.7 83.1 108.4  
## [8] 101.5 88.6 112.5  
##  
## [[2]]  
## [1] 104.3 97.0 109.0 108.8 108.2 106.9 105.5  
## [8] 99.4 96.9 96.2  
##  
## [[3]]  
## [1] 93.1 97.9 87.3 121.7 112.1 88.8 96.0  
## [8] 95.3 107.8 99.2  
##  
## [[4]]  
## [1] 102.5 99.7 99.6 113.7 97.7 115.2 84.5  
## [8] 105.8 101.2 102.2  
##  
## [[5]]  
## [1] 103.8 95.0 96.7 89.8 89.3 103.0 104.5  
## [8] 100.5 109.2 120.5  
##  
## [[6]]
```

# Calculate all means

---

```
map_dbl(samples, mean) %>%  
  head()
```

```
## [1]  95.8 103.2  99.9 102.2 101.2  96.4
```

- What's the ***sd*** of these means? That's the standard error.

```
map_dbl(samples, mean) %>%  
  sd()
```

```
## [1] 3.14
```

# Sample size

---

Let's re-do this, pulling a sample of 100 each time.

```
samples2 <- replicate(1000, rnorm(100, mean = 100, sd = 10),  
                      simplify = FALSE)  
map_dbl(samples2, mean) %>%  
  sd()
```

```
## [1] 0.973
```



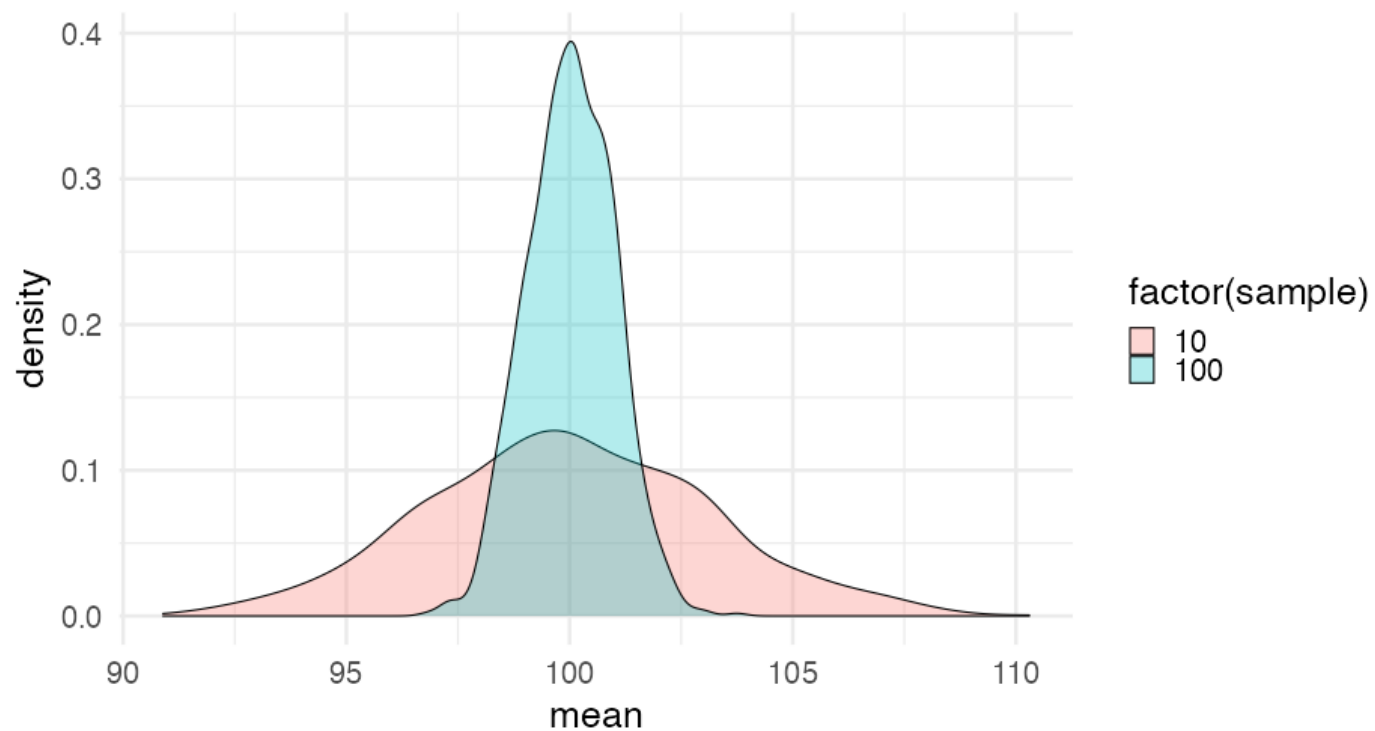
# Visualize the sampling distributions

---

```
sample_means <- tibble(iter = rep(1:1000, 2),  
                        sample = rep(c(10, 100), each = 1000),  
                        mean = c(map_dbl(samples, mean),  
                                map_dbl(samples2, mean))  
                        )  
sample_means
```

```
## # A tibble: 2,000 × 3  
##   iter sample    mean  
##   <int> <dbl>    <dbl>  
## 1     1     10  95.75441  
## 2     2     10 103.2204  
## 3     3     10  99.91284  
## 4     4     10 102.2169  
## 5     5     10 101.2308  
## 6     6     10  96.37082  
## # ... with 1,994 more rows
```

```
ggplot(sample_means, aes(mean)) +  
  geom_density(aes(fill = factor(sample)), alpha = 0.3)
```



# Fit a model

---

```
m <- lm(cty ~ displ + class, mpg)
summary(m)
```

```
##
## Call:
## lm(formula = cty ~ displ + class, data = mpg)
##
## Residuals:
##      Min       1Q   Median       3Q      Max
## -5.269  -1.150  -0.016   1.034  12.978
##
## Coefficients:
##              Estimate Std. Error t value
## (Intercept)    28.777      1.473   19.54
## displ         -2.172      0.175  -12.43
## classcompact   -3.599      1.252   -2.87
## classmidsize   -3.676      1.206   -3.05
## classminivan   -5.595      1.306   -4.28
## classpickup    -6.182      1.121   -5.51
## classsubcompact -2.629      1.237   -2.13
## classssuv      -5.599      1.087   -5.15
##
##              Pr(>|t|)
## (Intercept)    < 2e-16 ***
## displ          < 2e-16 ***
## classcompact    0.0044 **
```

# Visualize with standard errors

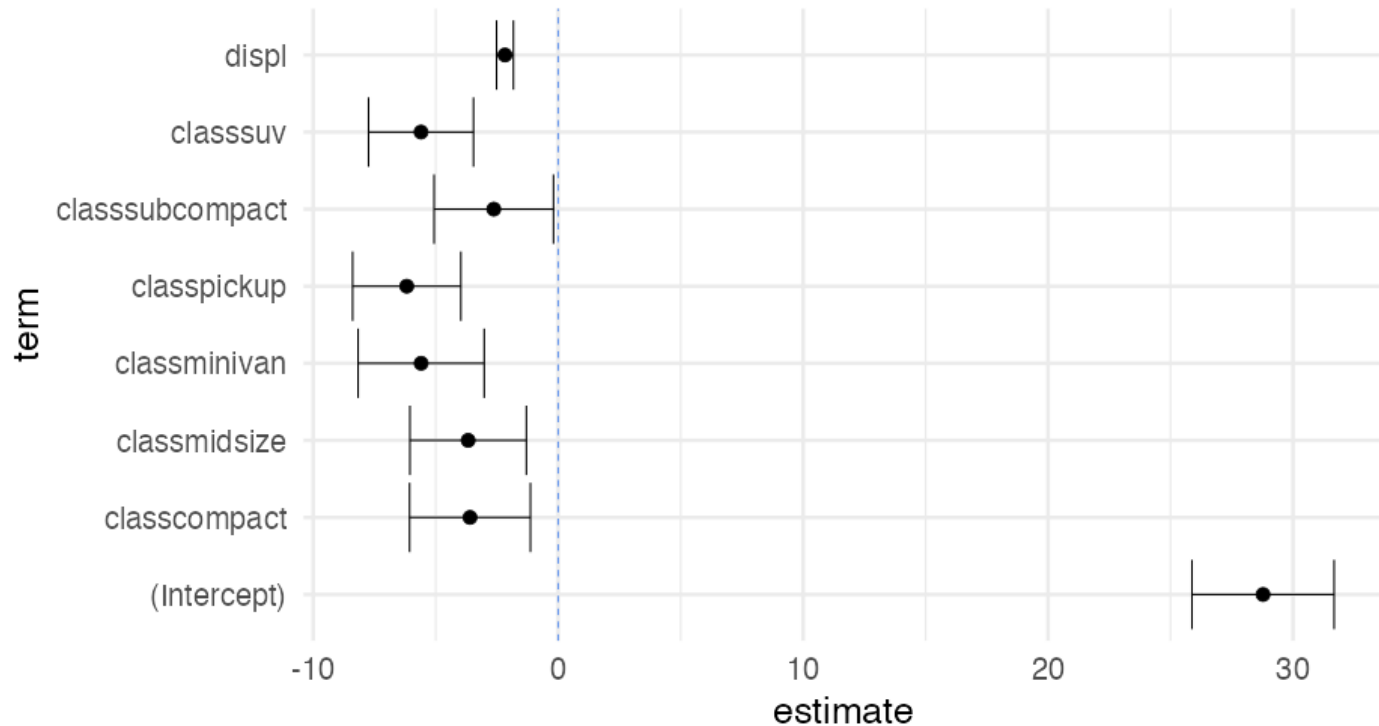
---

```
tidied_m <- broom::tidy(m, conf.int = TRUE)
```

```
tidied_m
```

```
## # A tibble: 8 × 7
##   term          estimate std.error  statistic
##   <chr>          <dbl>    <dbl>    <dbl>
## 1 (Intercept)  28.77682  1.472892  19.53763
## 2 displ       -2.171562  0.1746638 -12.43281
## 3 classcompact -3.599125  1.252190  -2.874265
## 4 classmidsize -3.675526  1.206253  -3.047061
## 5 classminivan -5.595070  1.305993  -4.284151
## 6 classpickup  -6.182466  1.121448  -5.512931
## # ... with 2 more rows, and 3 more variables:
## #   p.value <dbl>, conf.low <dbl>,
## #   conf.high <dbl>
```

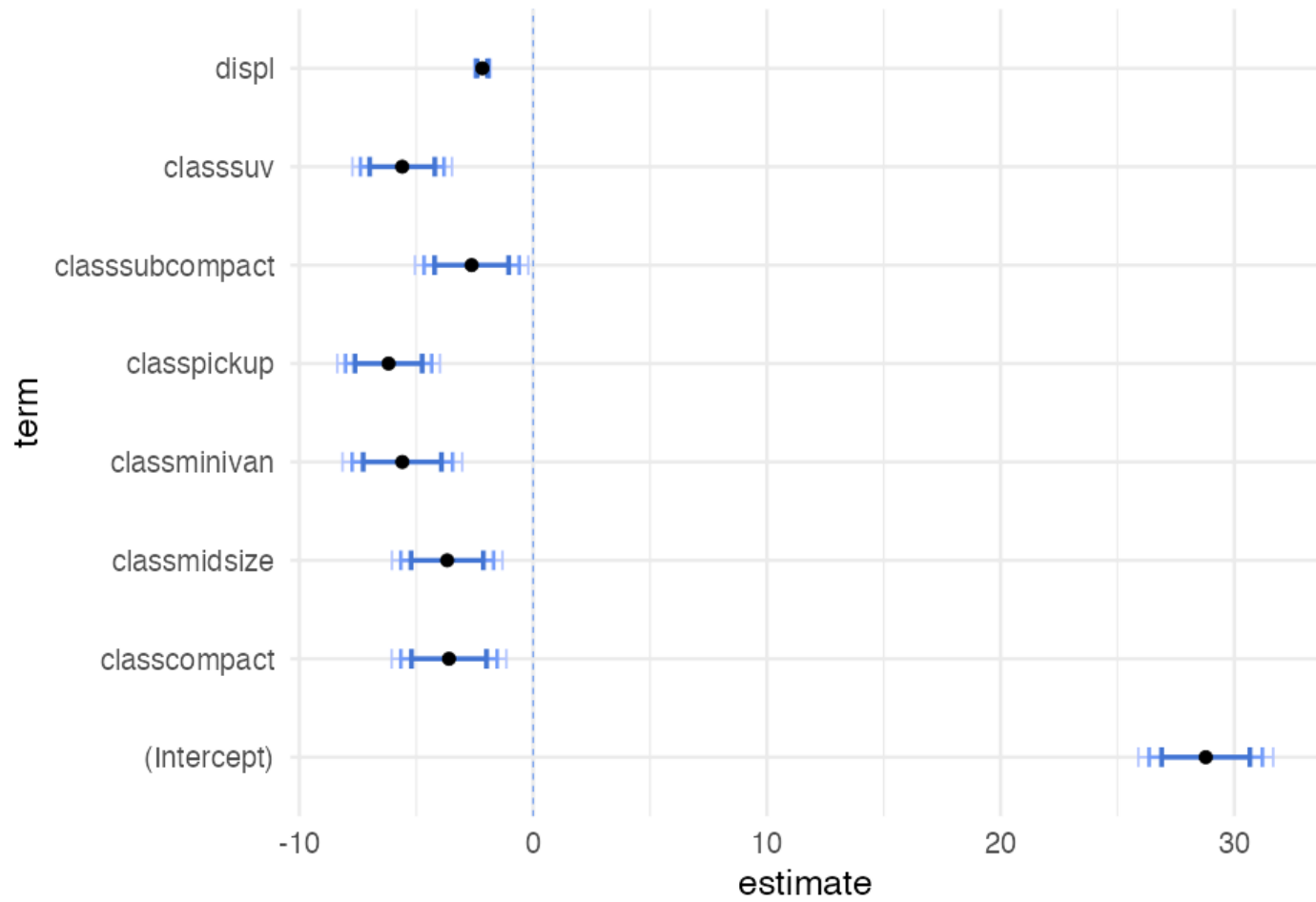
```
ggplot(tidied_m, aes(term, estimate)) +
  geom_hline(yintercept = 0,
             color = "cornflowerblue",
             linetype = 2) +
  geom_errorbar(aes(ymin = conf.low, ymax = conf.high)) +
  geom_point() +
  coord_flip()
```



# Multiple error bars

---

```
library(colorspace)
ggplot(tidied_m, aes(term, estimate)) +
  geom_hline(yintercept = 0,
             color = "cornflowerblue",
             linetype = 2) +
  geom_errorbar(aes(ymin = estimate + qnorm(.025)*std.error,
                    ymax = estimate + qnorm(.975)*std.error),
               color = lighten("#4375D3", .6),
               width = 0.2,
               size = 0.8) + # 95% CI
  geom_errorbar(aes(ymin = estimate + qnorm(.05)*std.error,
                    ymax = estimate + qnorm(.95)*std.error),
               color = lighten("#4375D3", .3),
               width = 0.2,
               size = 1.2) + # 90% CI
  geom_errorbar(aes(ymin = estimate + qnorm(.1)*std.error,
                    ymax = estimate + qnorm(.9)*std.error),
               color = "#4375D3",
               width = 0.2,
               size = 1.6) + # 80% CI
  geom_point() +
  coord_flip()
```



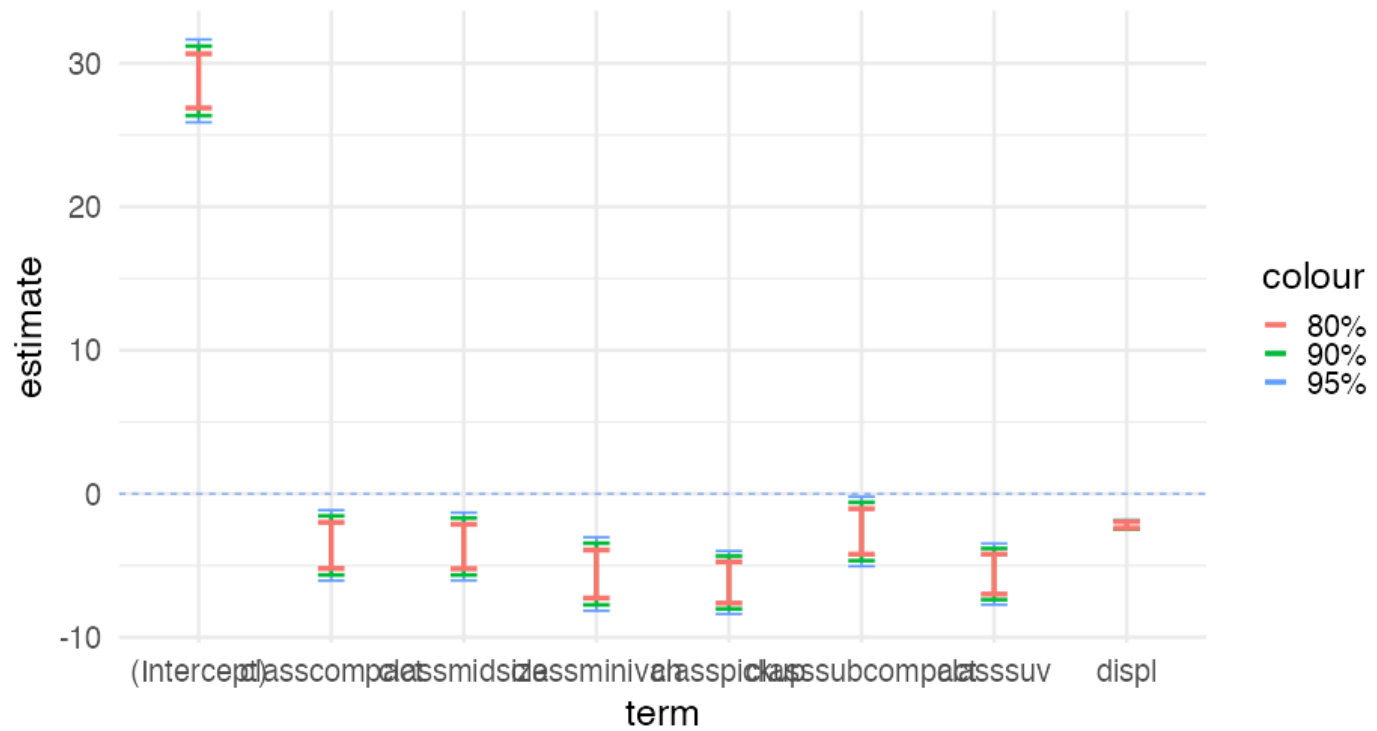
# Add levels to legend

---

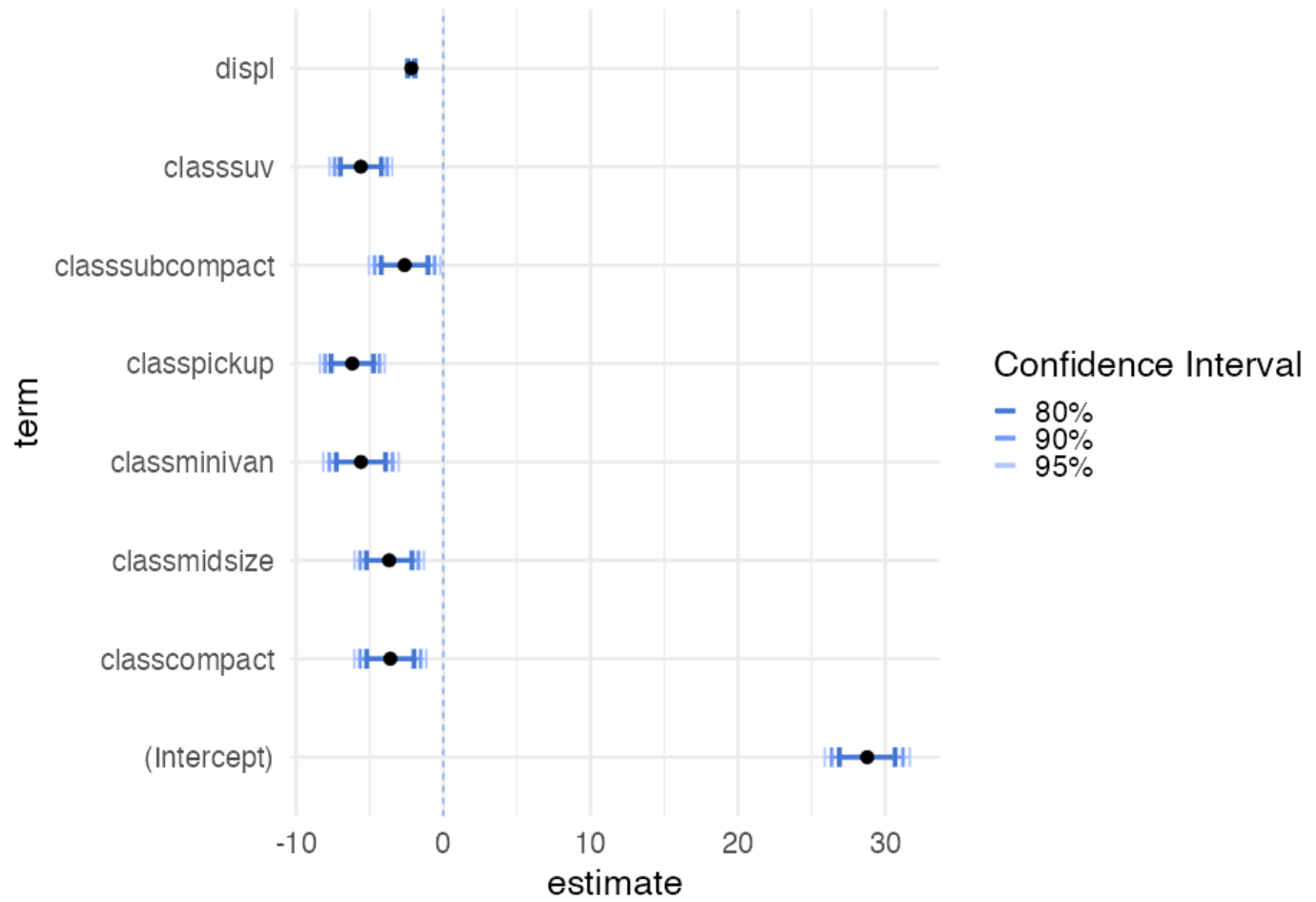
```
p <- ggplot(tidied_m, aes(term, estimate)) +  
  geom_hline(yintercept = 0,  
             color = "cornflowerblue",  
             linetype = 2) +  
  geom_errorbar(aes(ymin = estimate + qnorm(.025)*std.error,  
                   ymax = estimate + qnorm(.975)*std.error,  
                   color = "95%"),  
               width = 0.2,  
               size = 0.8) +  
  geom_errorbar(aes(ymin = estimate + qnorm(.05)*std.error,  
                   ymax = estimate + qnorm(.95)*std.error,  
                   color = "90%"),  
               width = 0.2,  
               size = 1.2) +  
  geom_errorbar(aes(ymin = estimate + qnorm(.1)*std.error,  
                   ymax = estimate + qnorm(.9)*std.error,  
                   color = "80%"),  
               width = 0.2,  
               size = 1.6)
```



p



```
p +  
  scale_color_manual("Confidence Interval",  
                      values = c("#4375D3",  
                                lighten("#4375D3", .3),  
                                lighten("#4375D3", .6))) +  
  geom_point() +  
  coord_flip()
```



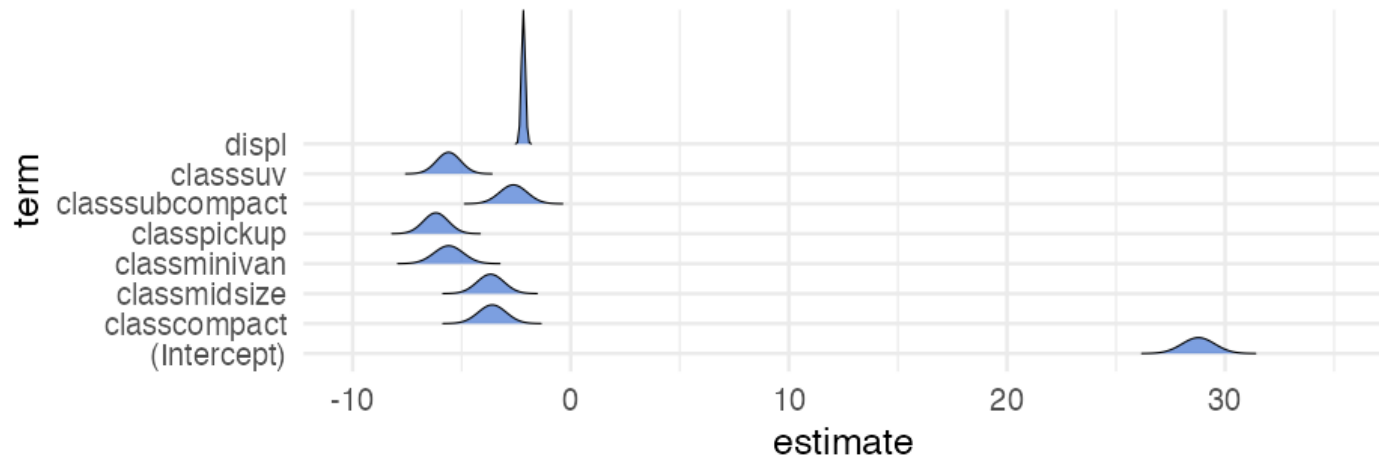
# Density stripes

---

```
#remotes::install_github("wilkelab/ungeviz")  
library(ungeviz)  
ggplot(tidied_m, aes(estimate, term)) +  
  stat_confidence_density(  
    aes(moe = std.error),  
    fill = "#4375D3",  
    height = 0.6  
  ) +  
  xlim(-10, 35) +  
  geom_point()
```

# Actual densities

```
library(ggribes)
ggplot(tidied_m, aes(estimate, term)) +
  stat_confidence_density(
    aes(moe = std.error, height = stat(density)),
    geom = "ridgeline",
    confidence = 0.95,
    min_height = 0.001,
    alpha = 0.7,
    fill = "#4375D3"
  ) +
  xlim(-10, 35)
```



# Practice

---

- Go back to your species means from Palmer Penguins
- Reproduce the plot using one of the three methods we just saw
  - Multiple error bars
  - Density stripes
  - Densities

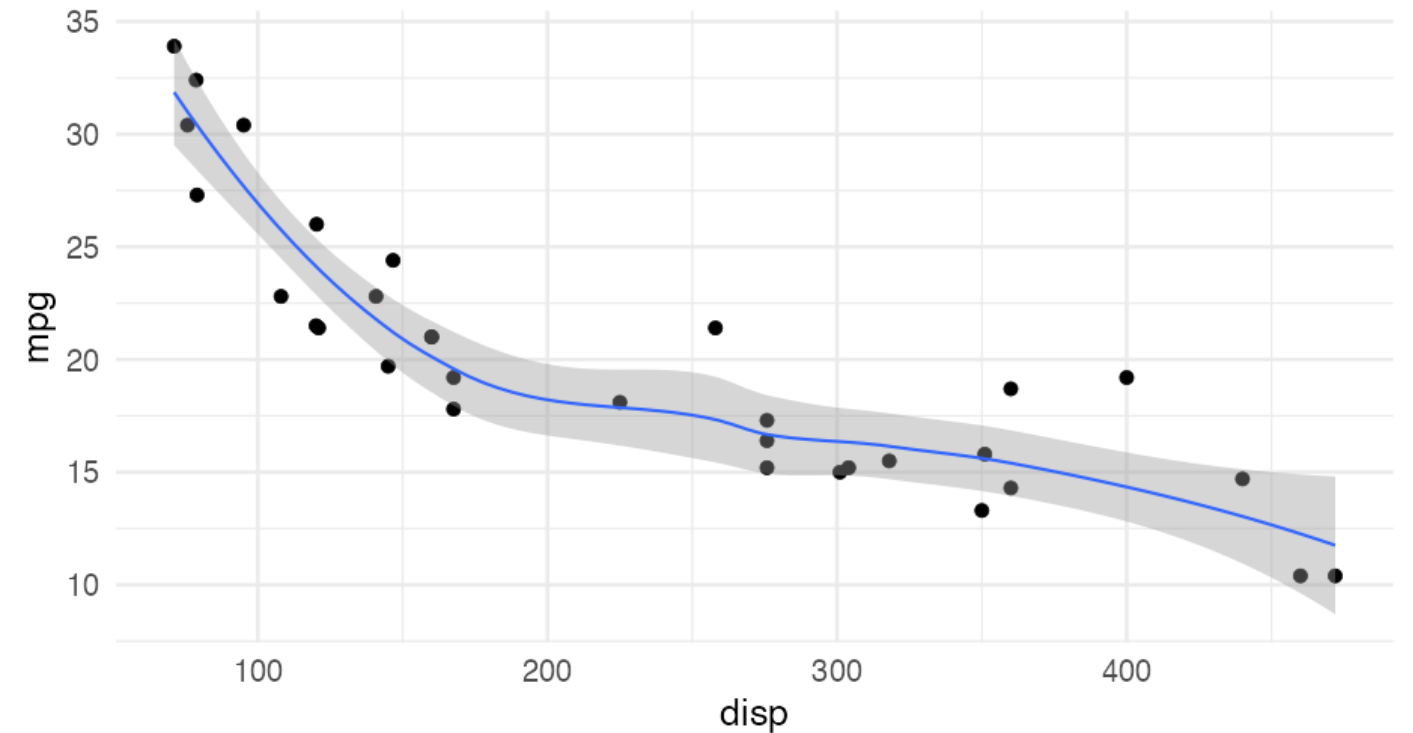
05:00

# HOPs

---

Hypothetical Outcome Plots (and related plots)

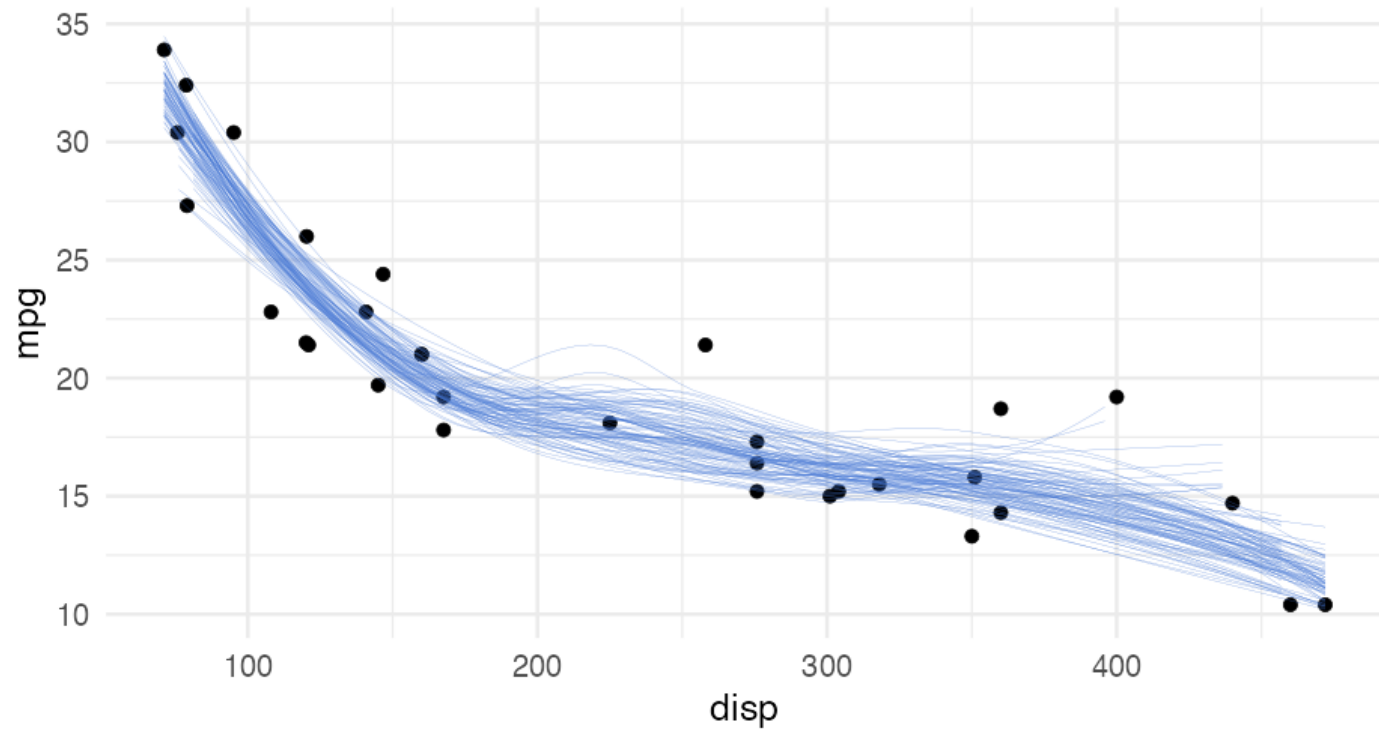
```
ggplot(mtcars, aes(displacement, mpg)) +  
  geom_point() +  
  geom_smooth()
```





# Alternative

---



# How?

---

## Bootstrapping

```
row_samps <- replicate(  
  100,  
  sample(  
    seq_len(nrow(mtcars)),  
    nrow(mtcars),  
    replace = TRUE  
  ),  
  simplify = FALSE  
)
```

```
row_samps
```

```
## [[1]]  
## [1] 22 30 25 25 5 31 19 13 19 20 17 1 4 12  
## [15] 12 25 20 21 16 23 11 23 14 1 24 20 10 30  
## [29] 27 24 22 23  
##  
## [[2]]  
## [1] 25 1 18 18 25 8 8 16 25 19 31 13 11 10  
## [15] 21 6 14 14 12 24 27 29 22 5 6 8 14 16  
## [29] 7 13 17 13
```

# Extract samples

---

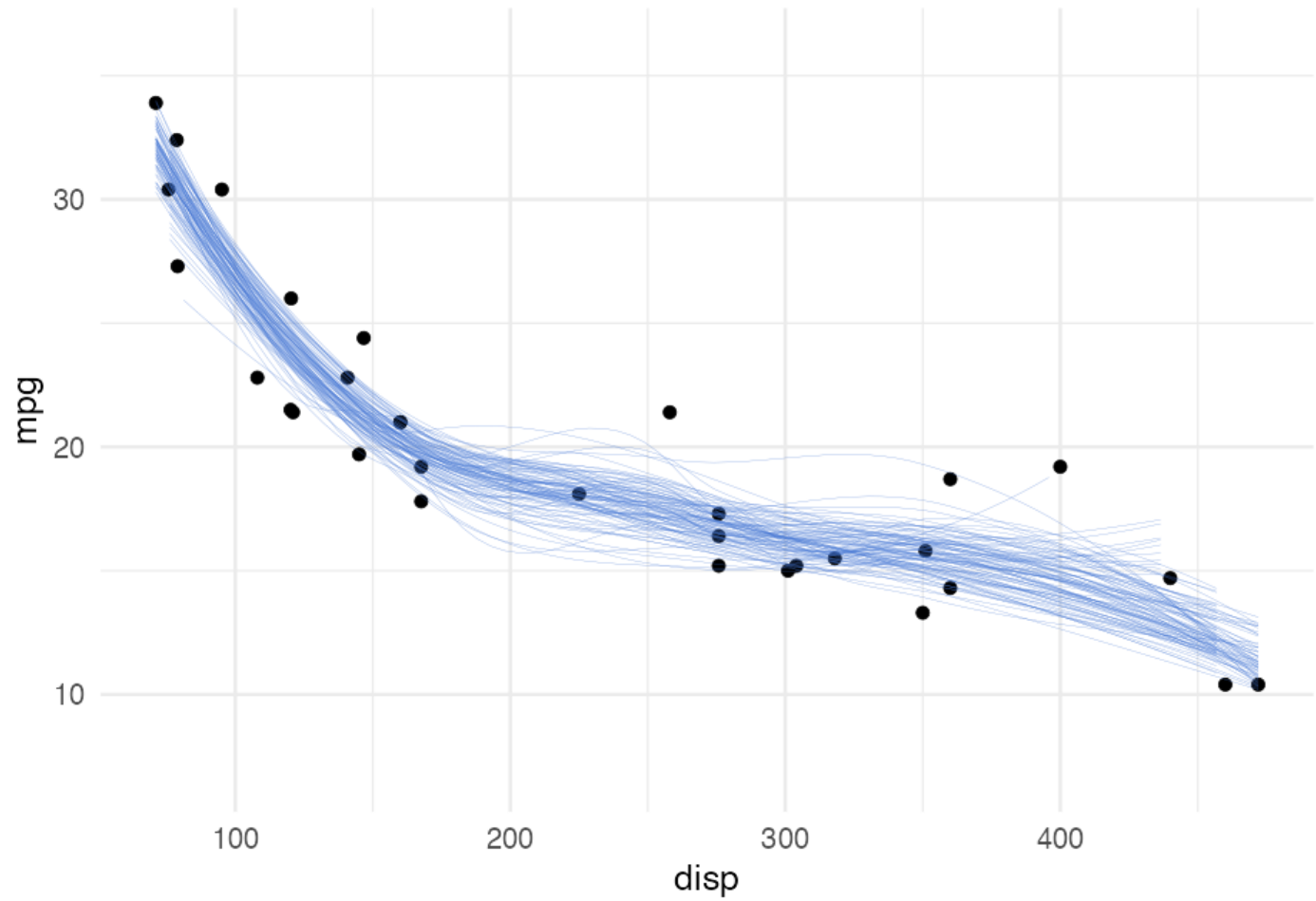
```
d_samps <- map_df(row_samps, ~mtcars[.x, ], .id = "sample")
head(d_samps)
```

```
##               sample  mpg  cyl  disp
## Dodge Challenger...1      1 15.5    8   318
## Ferrari Dino...2          1 19.7    6   145
## Pontiac Firebird...3      1 19.2    8   400
## Pontiac Firebird.1...4      1 19.2    8   400
## Hornet Sportabout...5      1 18.7    8   360
## Maserati Bora...6          1 15.0    8   301
##
##               hp drat   wt  qsec vs
## Dodge Challenger...1  150 2.76 3.52 16.9  0
## Ferrari Dino...2     175 3.62 2.77 15.5  0
## Pontiac Firebird...3  175 3.08 3.85 17.1  0
## Pontiac Firebird.1...4 175 3.08 3.85 17.1  0
## Hornet Sportabout...5 175 3.15 3.44 17.0  0
## Maserati Bora...6     335 3.54 3.57 14.6  0
##
##               am gear carb
## Dodge Challenger...1  0    3    2
## Ferrari Dino...2      1    5    6
## Pontiac Firebird...3  0    3    2
## Pontiac Firebird.1...4 0    3    2
## Hornet Sportabout...5 0    3    2
## Maserati Bora...6     1    5    8
```

# Plot both data sources

---

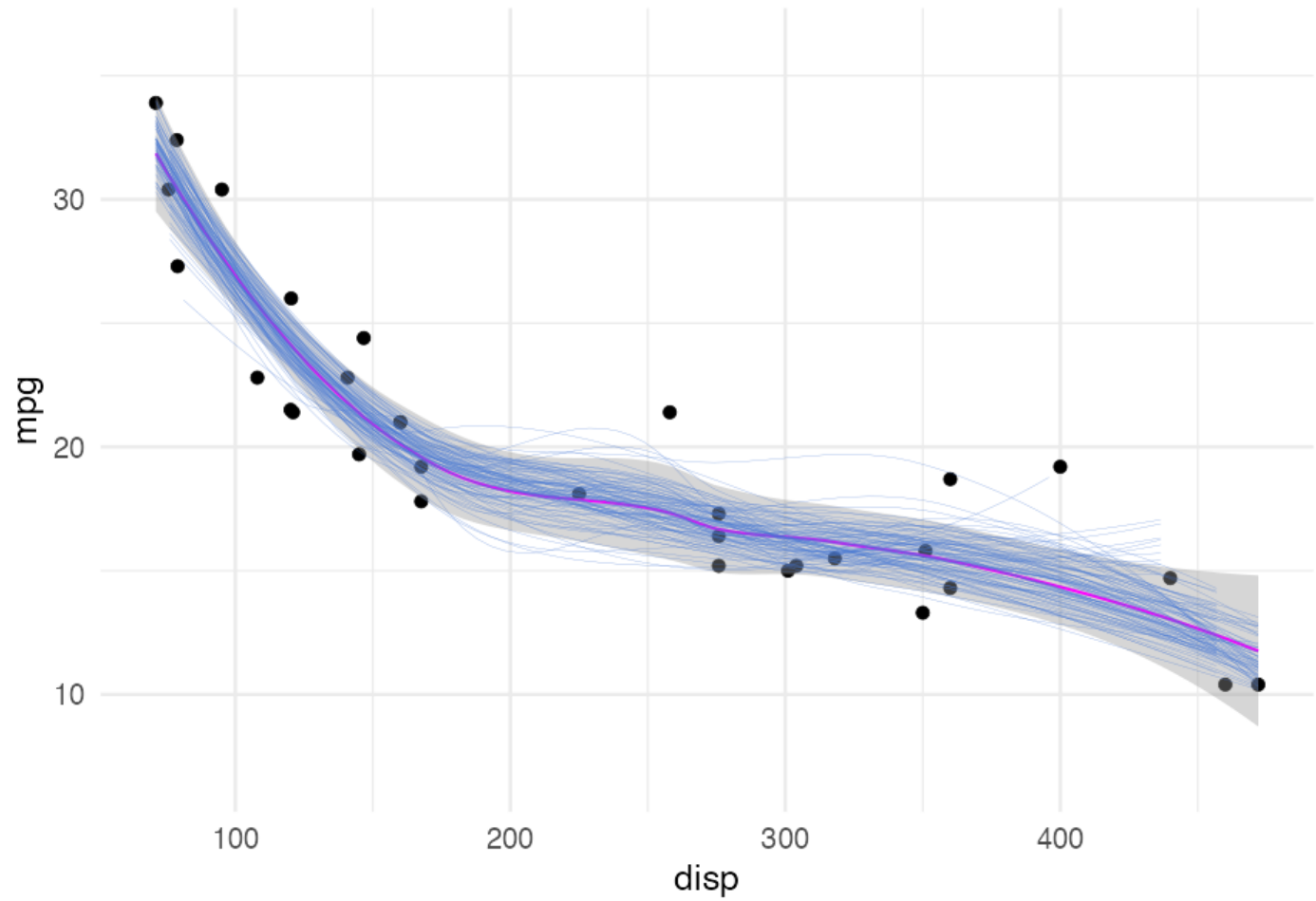
```
ggplot(mtcars, aes(displacement, mpg)) +  
  geom_point() +  
  stat_smooth(  
    aes(group = sample),  
    data = d_samps,  
    geom = "line",  
    color = "#4375D3",  
    fullrange = TRUE,  
    size = 0.1  
  )
```



# Note, they match up

---

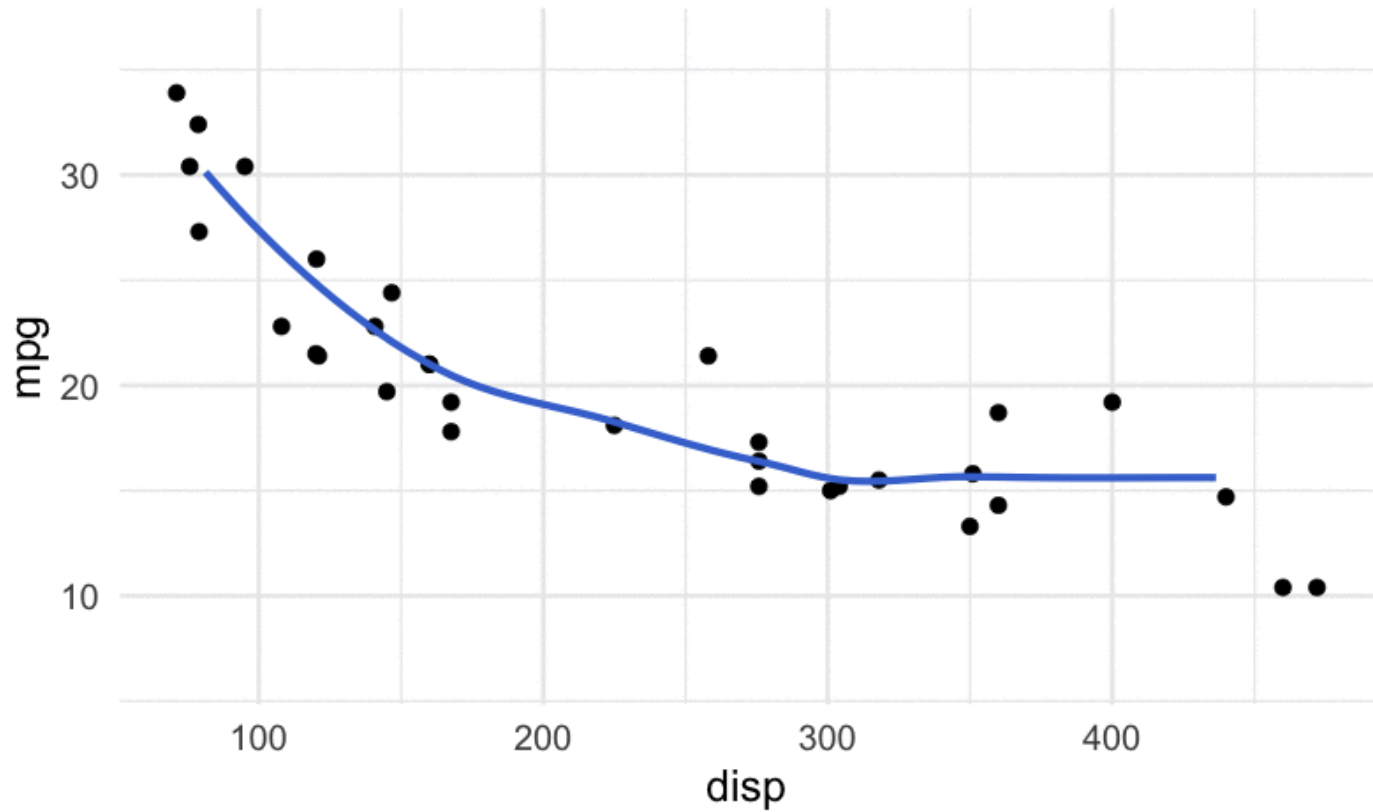
```
ggplot(mtcars, aes(displacement, mpg)) +  
  geom_point() +  
  geom_smooth(color = "magenta") +  
  stat_smooth(  
    aes(group = sample),  
    data = d_samps,  
    geom = "line",  
    color = "#4375D3",  
    fullrange = TRUE,  
    size = 0.1  
  )
```



# HOPs

---

Hops animate the process, so you can't settle on one "truth"





# How?

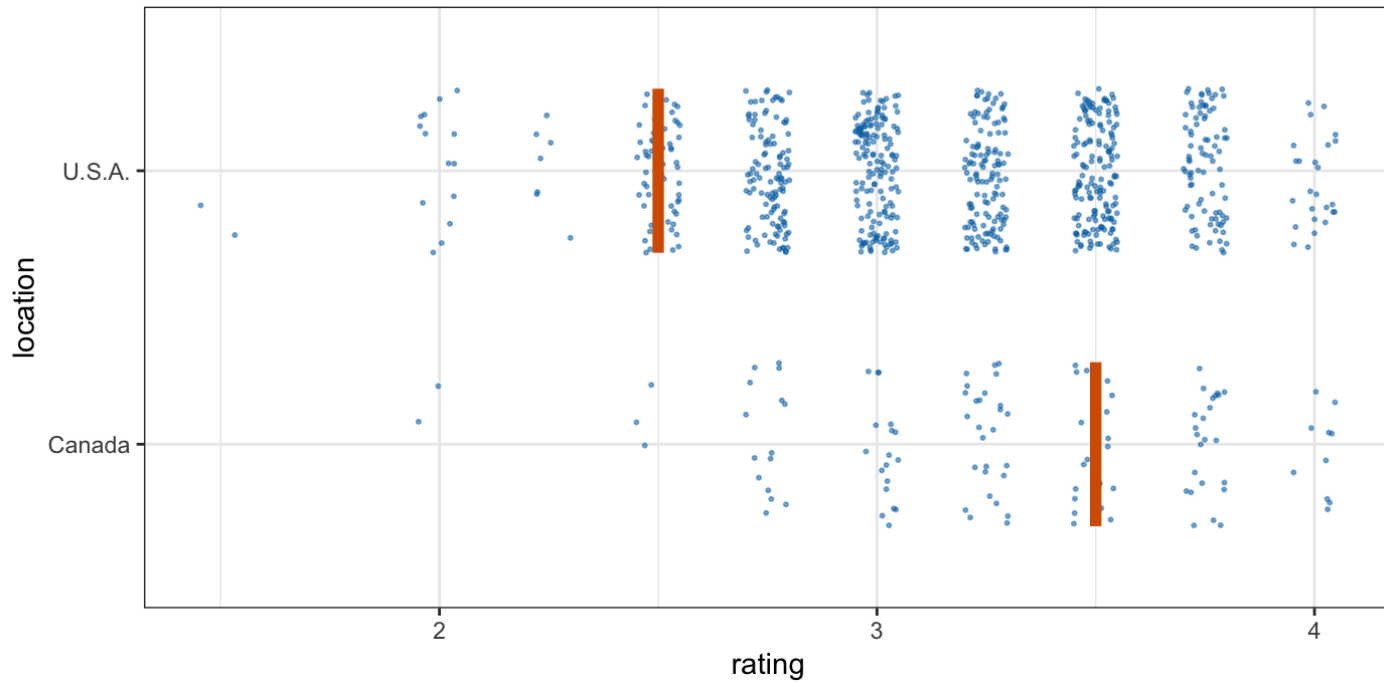
---

## gganimate::transition\_states

```
library(gganimate)
ggplot(mtcars, aes(displacement, mpg)) +
  geom_point() +
  stat_smooth(
    data = d_samps,
    geom = "line",
    size = 2,
    color = "#4375D3",
    fullrange = TRUE
  ) +
  transition_states(
    sample,
    transition_length = 0.5,
    state_length = 0.5
  ) +
  ease_aes('linear') # Smoother transitions
```

# Another example

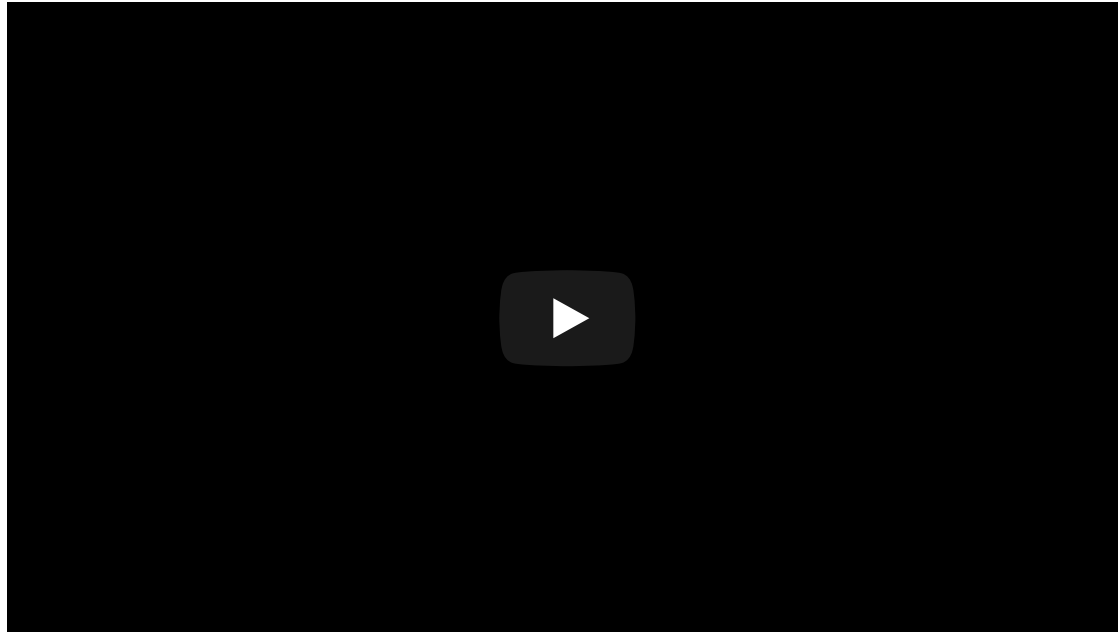
---



# Another examples

---

From Dr. Kay again



# Conclusions

---

- Lots of tools at your disposal (perhaps so many it can be difficult to choose)
- Do try to communicate uncertainty whenever possible
- I'd recommend checking out [Clause Wilke's talk](#) from [rstudio::conf\(2019L\)](#), where he talks about the [ungeviz](#) package.

