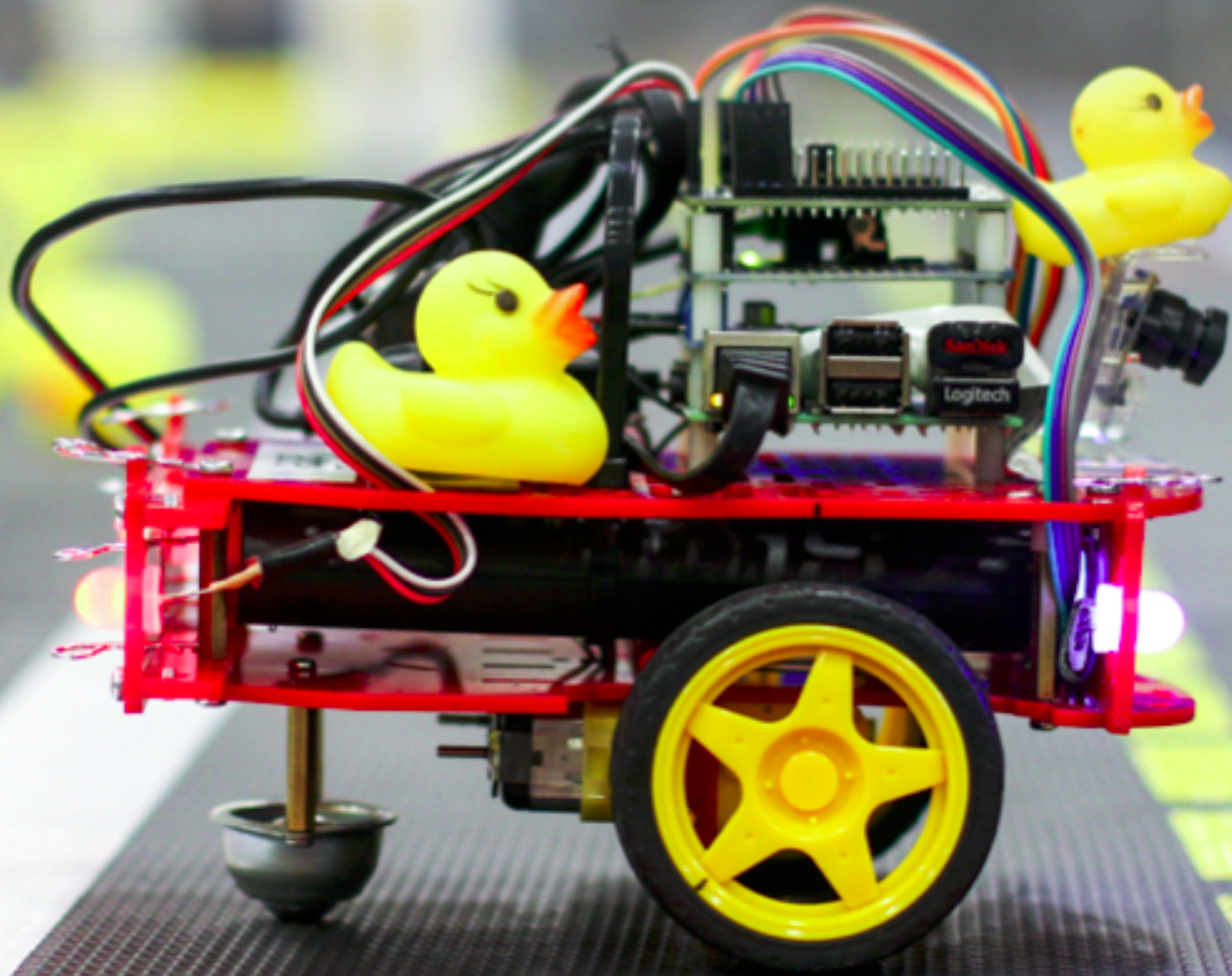


MISE Foundation Summer School Robotics





Welcome!

My name: Vincent Mai

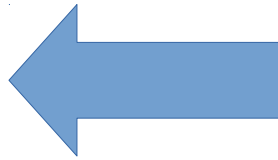
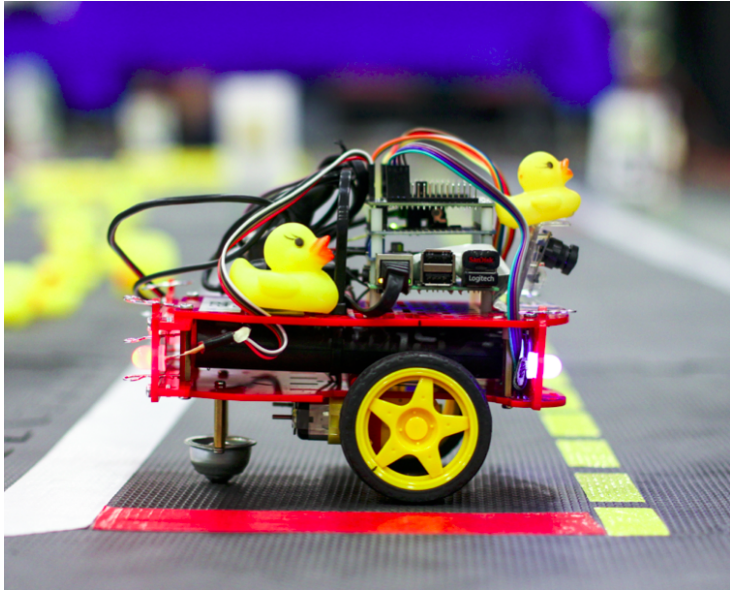
I am from: Canada



I am a PhD student in Robotics at Université de Montréal.

And you, who are you?
Tell me about you.





This is a DuckieBot.
I have one here. Its name is Moose.

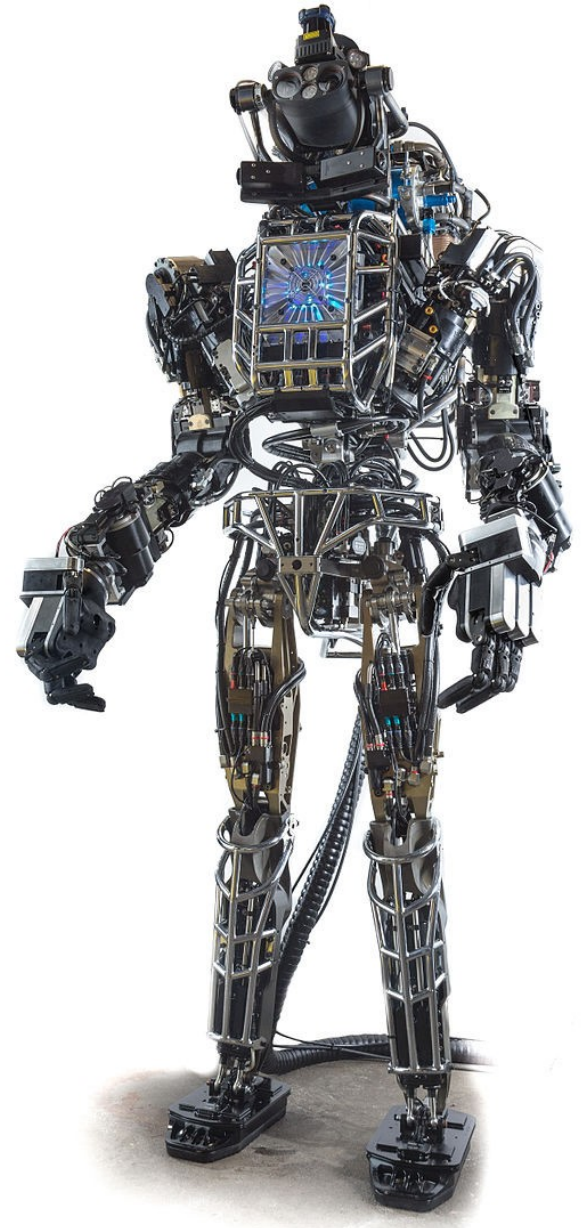
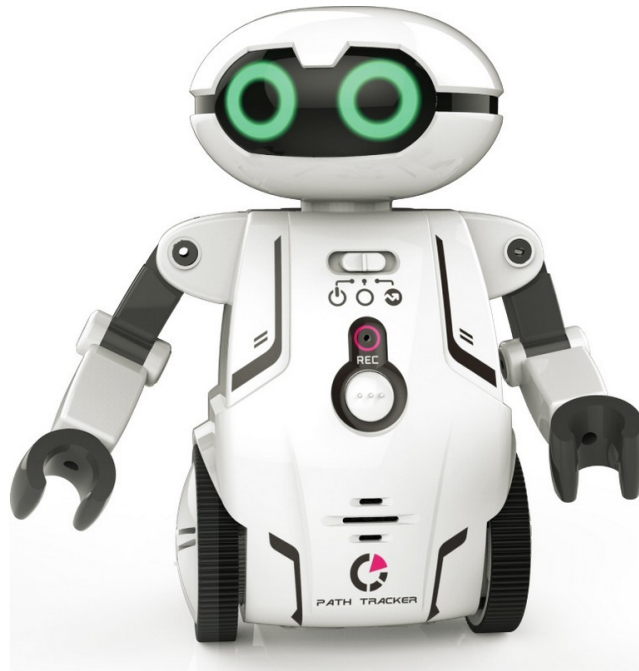
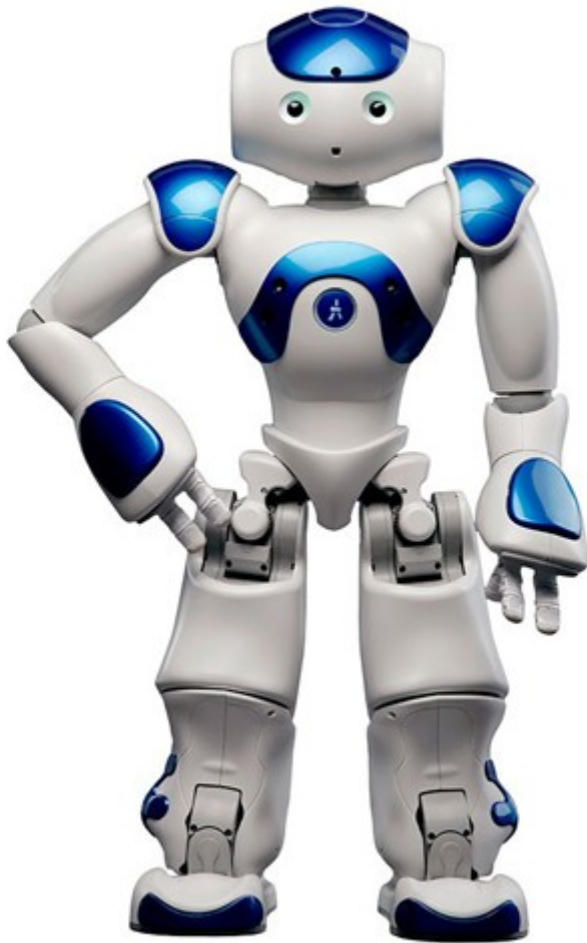
Question: according to you, what is Moose?

- A. a toy
- B. a miniature car
- C. a robot

Answer: all of them!

What is a robot?

According to Google Images...



But also...



What is a robot?

“A machine capable of carrying out a complex series of actions automatically, especially one programmable by a computer.”

- Oxford dictionary

How does a robot work?

1) Sensors

Get information from the environment.



2) Processor

Understand this information and take decisions



3) Actuators

Act the decisions upon the real world



Your turn!



Which sensors and actuators can you find on this drone?

Robotic hand: actuator or sensor?



Your turn!

Name all the existing sensors you can think of!

Button, joystick

Camera

Infrared sensor

Light sensor

Lidar

Sonar

GPS

Accelerometer

Gyroscope

Ultrasound

Radio

Magnetometer

Thermometer

Pressure sensor

Barometer

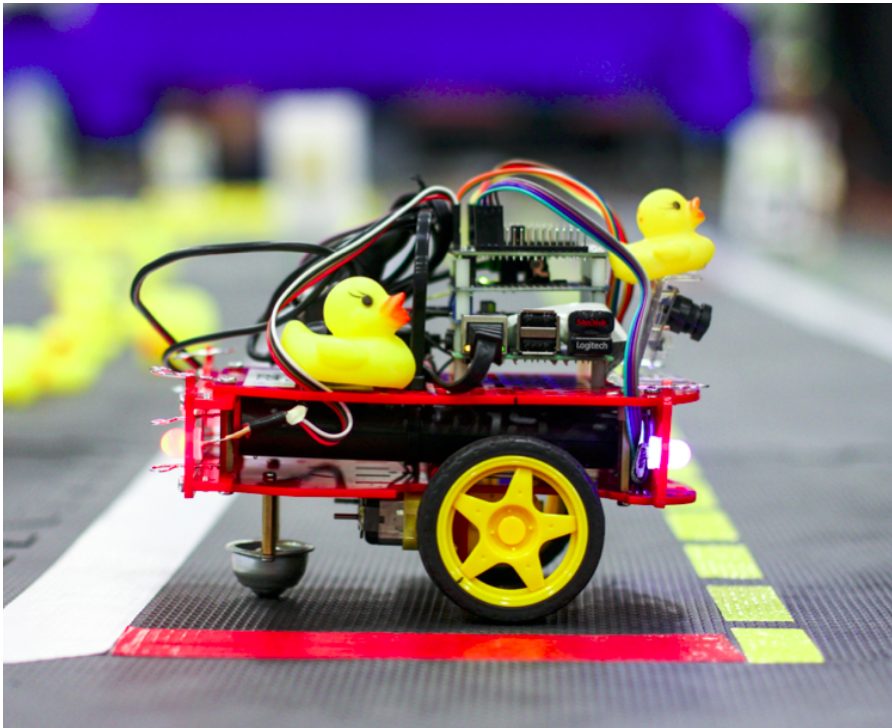
Voltmeter

Pedometer

Wheel encoder

...

Back to the DuckieBot



Sensors?

1 camera

Actuators?

2 wheel motors

Processor?

1 Raspberry Pi

What will we do during two weeks?

Objective: lane following for Moose

- 1) Maths & physics prerequisites
- 2) Computer science for robotics
- 3) 1st application: drive Moose with a joystick
- 4) 2nd application: lane following for Moose