

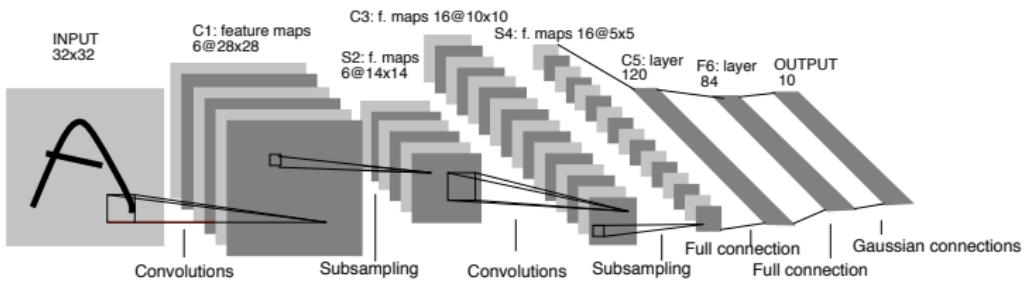
Lecture 6 - All about Convolutional Networks

DD2424

April 12, 2021

Convolutional Neural Networks (ConvNets)

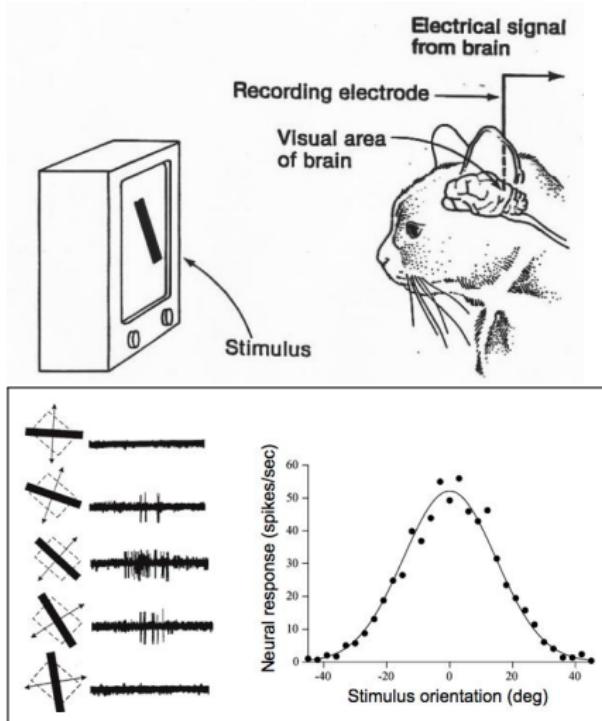
Convolutional Neural Networks



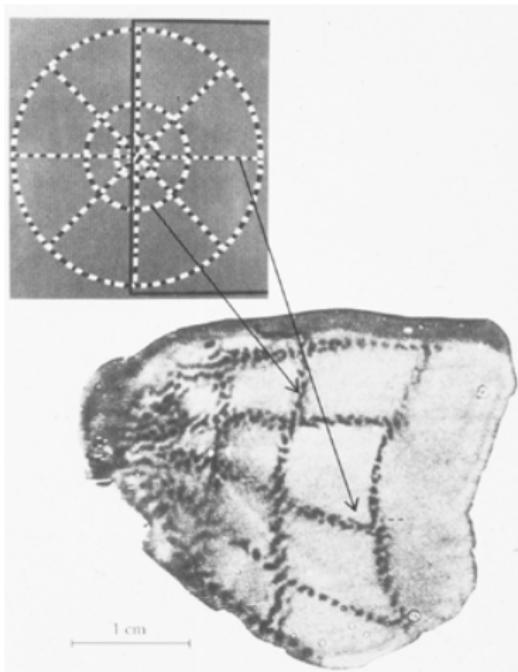
LeNet-5 (LeCun '98)

ConvNets: Some history

Hubel & Wiesel cat experiments 1968

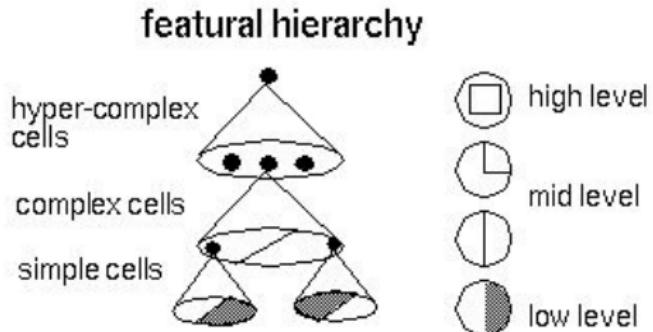
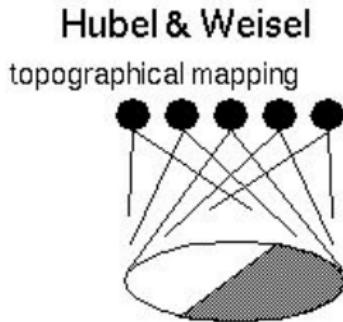


- Discovered *visual cortex* consists of a hierarchy of simple, complex, and hyper-complex cells.
(Experiments in 50's & 60's)
- Hubel & Wiesel won the Nobel prize (1981).



Topographical mapping in the cortex: nearby cells in cortex represented nearby regions in the visual field.

Hierarchical organization



Neocognitron: A Self-organizing Neural Network Model for a Mechanism of Pattern Recognition Unaffected by Shift in Position by Kunihiko Fukushima, 1980.

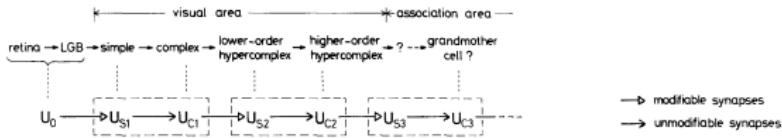
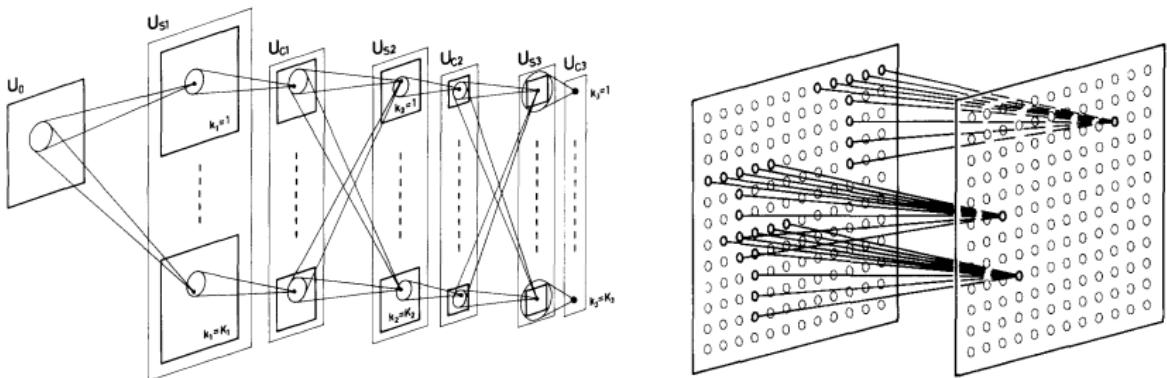


Fig. 1. Correspondence between the hierarchy model by Hubel and Wiesel, and the neural network of the neocognitron

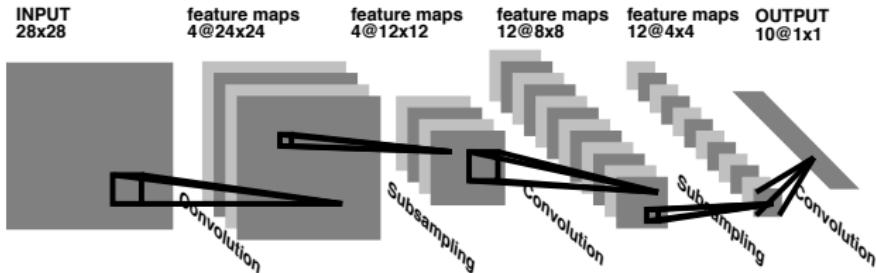
Inspired by Hubel & Wiesel model



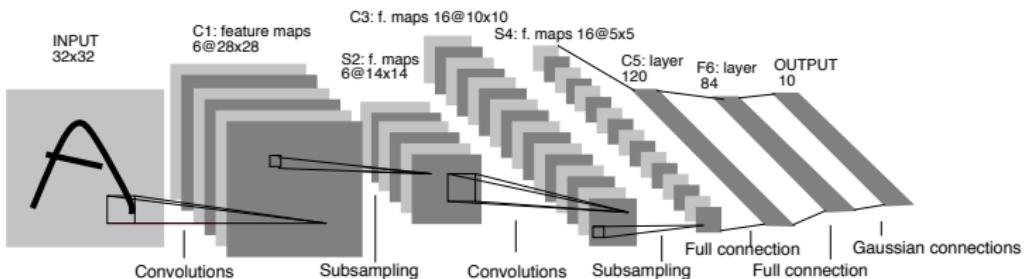
sandwich architecture (SCSCSC...)

simple cells: modifiable parameters, **complex cells:** perform pooling

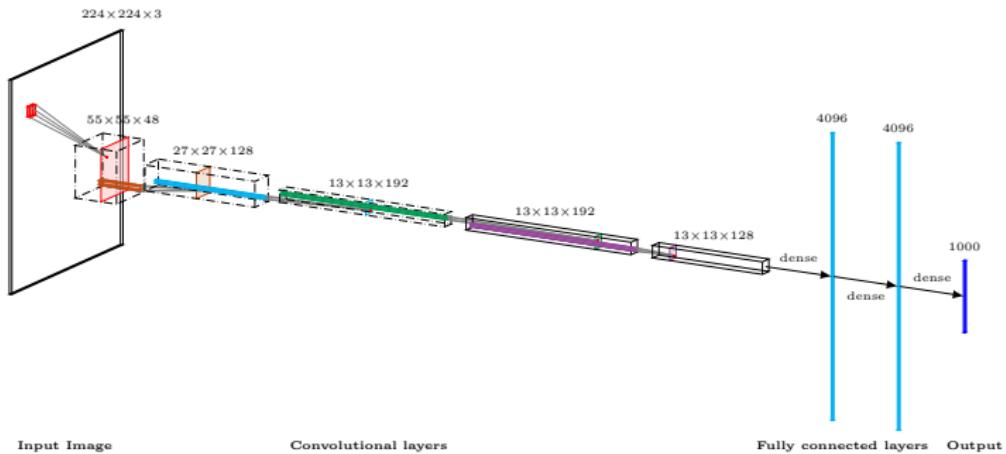
LeCun's LeNet ConvNets



LeNet 1 '90



LeNet 5 '95



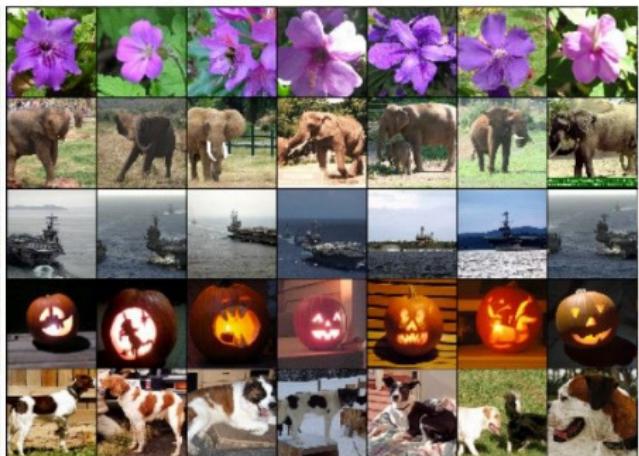
ImageNet Classification with Deep Convolutional Neural Networks by Krizhevsky, Sutskever, Hinton, 2012

Fast-forward to today: ConvNets are everywhere

Classification



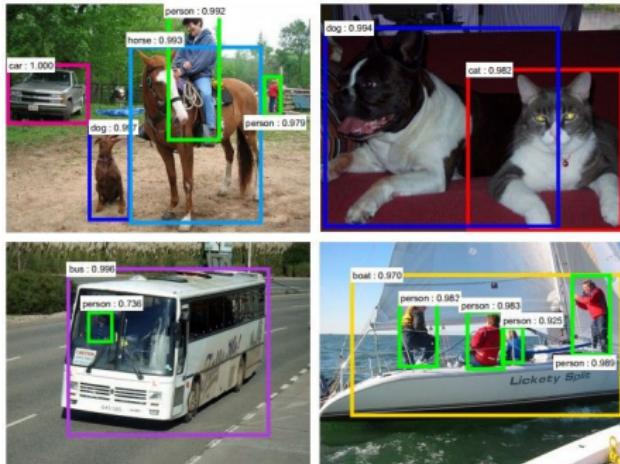
Retrieval



[Krizhevsky 2012]

Fast-forward to today: ConvNets are everywhere

Detection



[Faster R-CNN: Ren, He, Girshick, Sun 2015]

Segmentation



[Farabet et al., 2012]

Fast-forward to today: ConvNets are everywhere



self-driving cars



NVIDIA Tegra X1

Fast-forward to today: ConvNets are everywhere

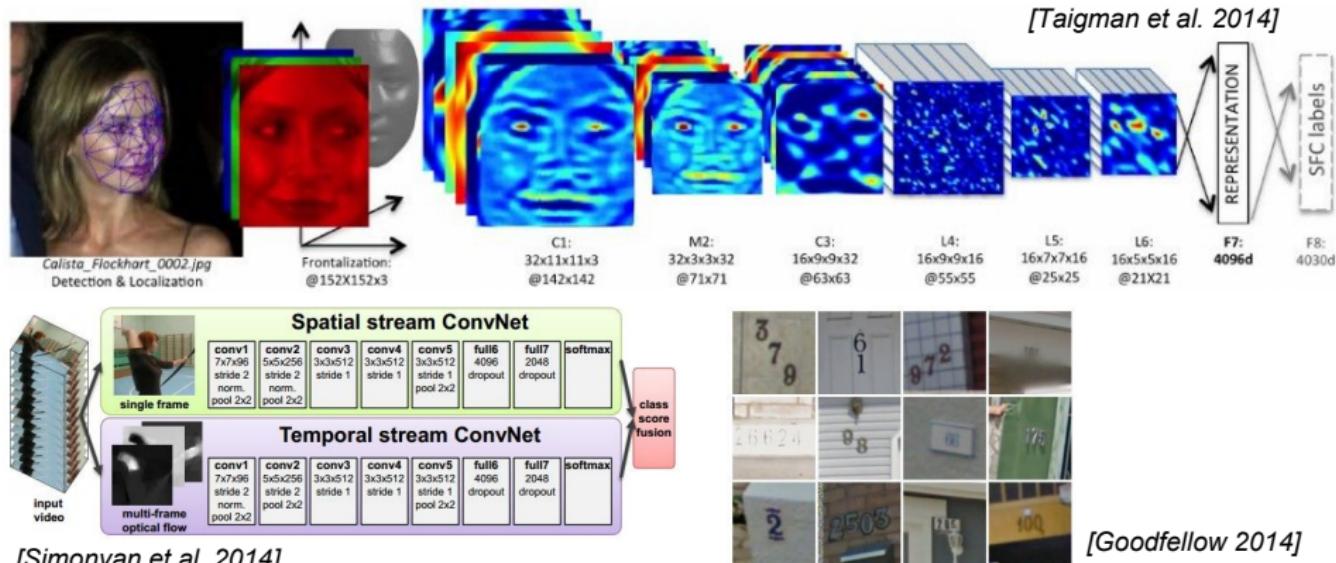


Image Captioning

Describes without errors



A person riding a motorcycle on a dirt road.

Describes with minor errors



Two dogs play in the grass.

Somewhat related to the image



A skateboarder does a trick on a ramp.

Unrelated to the image



A dog is jumping to catch a frisbee.



A group of young people playing a game of frisbee.



Two hockey players are fighting over the puck.



A little girl in a pink hat is blowing bubbles.



A refrigerator filled with lots of food and drinks.



A herd of elephants walking across a dry grass field.



A close up of a cat laying on a couch.



A red motorcycle parked on the side of the road.



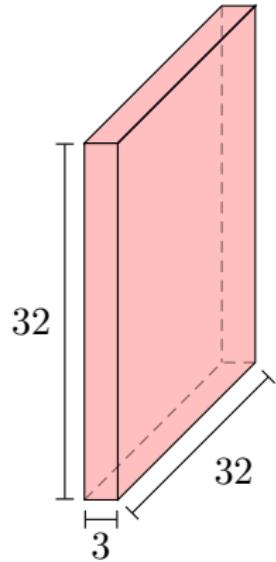
A yellow school bus parked in a parking lot.

[Vinyals et al., 2015]

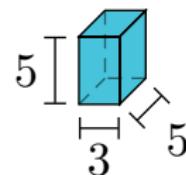
ConvNets for RGB Images: **The Convolution Layer**

Convolution Layer

Input Image



Filter

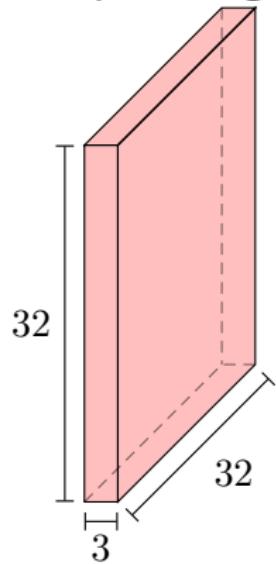


\mathbf{X} is $32 \times 32 \times 3$

\mathbf{F} is $5 \times 5 \times 3$

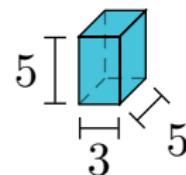
Convolution Layer

Input Image



\mathbf{X} is $32 \times 32 \times 3$

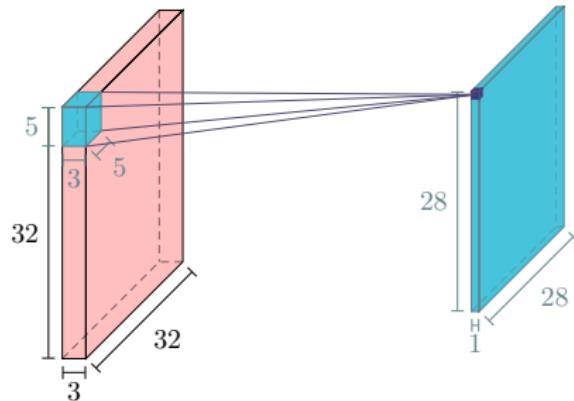
Filter



\mathbf{F} is $5 \times 5 \times 3$

Note: Filter & input image generally have the same depth.

Convolution Layer



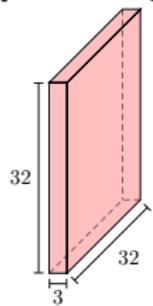
Convolve the image, \mathbf{X} , with the filter \mathbf{F} .

- Slide filter over all spatial locations in image.
- At each location output 1 number:

compute dot product between \mathbf{F} and a $5 \times 5 \times 3$ chunk of \mathbf{X}

Convolution Layer

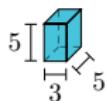
Input Image



X

Size: $32 \times 32 \times 3$

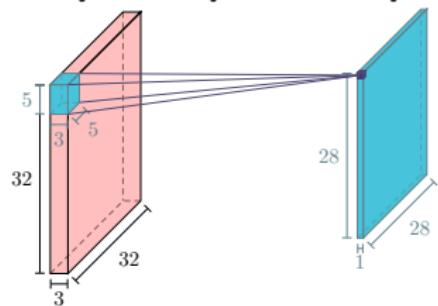
Filter



F

Size: $5 \times 5 \times 3$

Output response map



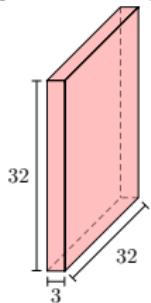
$S = \mathbf{X} * \mathbf{F}$

Size: $28 \times 28 \times 1$

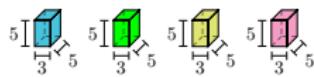
Convolution Layer

Can apply multiple filters.

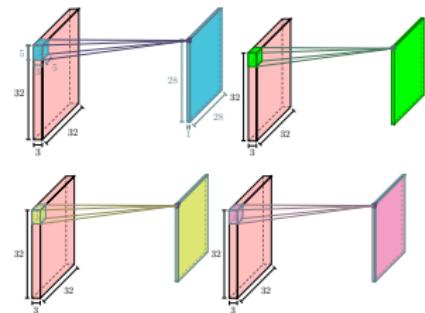
Input Image



Filters



Output response maps



X

Size: $32 \times 32 \times 3$

$\mathbf{F}_1, \mathbf{F}_2, \mathbf{F}_3, \mathbf{F}_4$

Size \mathbf{F}_i : $5 \times 5 \times 3$

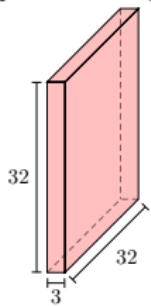
$$S_i = \mathbf{X} * \mathbf{F}_i$$

Size S_i : 28×28

Convolution Layer

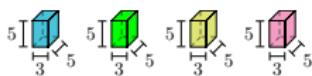
Apply multiple filters and get multiple response maps

Input Image



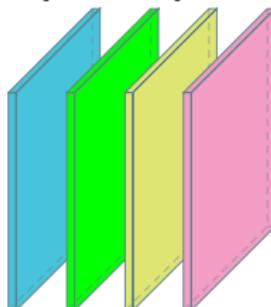
X

Filters



$\mathbf{F}_1, \mathbf{F}_2, \mathbf{F}_3, \mathbf{F}_4$

Output response maps

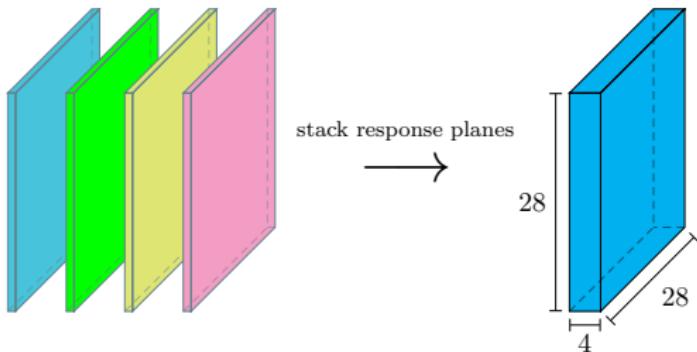


S_1, S_2, S_3, S_4

Each $S_i = \mathbf{X} * \mathbf{F}_i$

Convolution Layer

- Stack the multiple response maps to get a *new image S*.
- In our example
 - $S = \{S_1, S_2, S_3, S_4\}$ and
 - S has size $28 \times 28 \times 4$



Convolution Layer

- Apply the non-linear activation function to each element of \mathbf{S} .

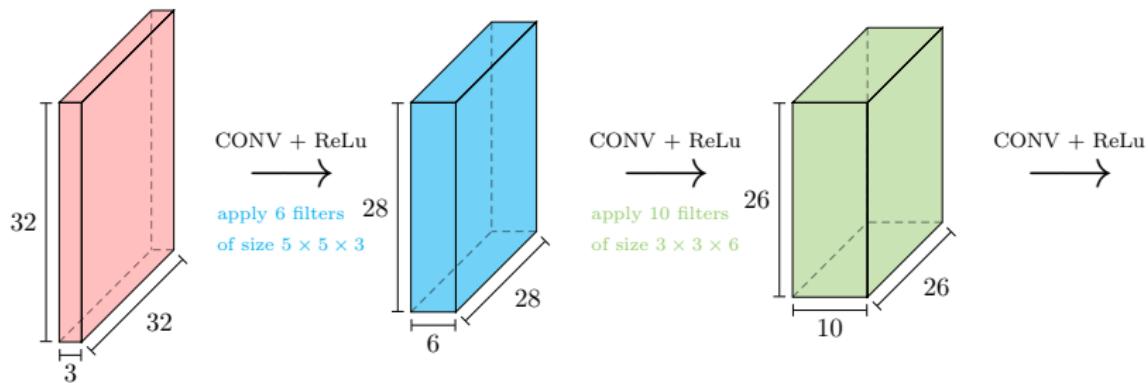
$$\mathbf{H} = \max(0, \mathbf{S})$$



Most basic Convolutional Network layers

Basic **ConvNet** is a composition of

- Convolution Layer
- Activation function



How do we produce final probs for C class labels?

- Add **fully connected layer(s)** after the convolutional layers.
- Example network:
1 convolutional layer + 1 fully connected layer

$$S_i = \mathbf{X} * \mathbf{F}_i + b_i \quad \text{for } i = 1, \dots, n_F \quad \leftarrow \text{apply convolution filters}$$

$$\mathbf{S} = \{S_1, \dots, S_{n_F}\} \quad \leftarrow \text{stack response maps, get new 3D image}$$

$$\mathbf{H} = \max(0, \mathbf{S}) \quad \leftarrow \text{apply ReLu}$$

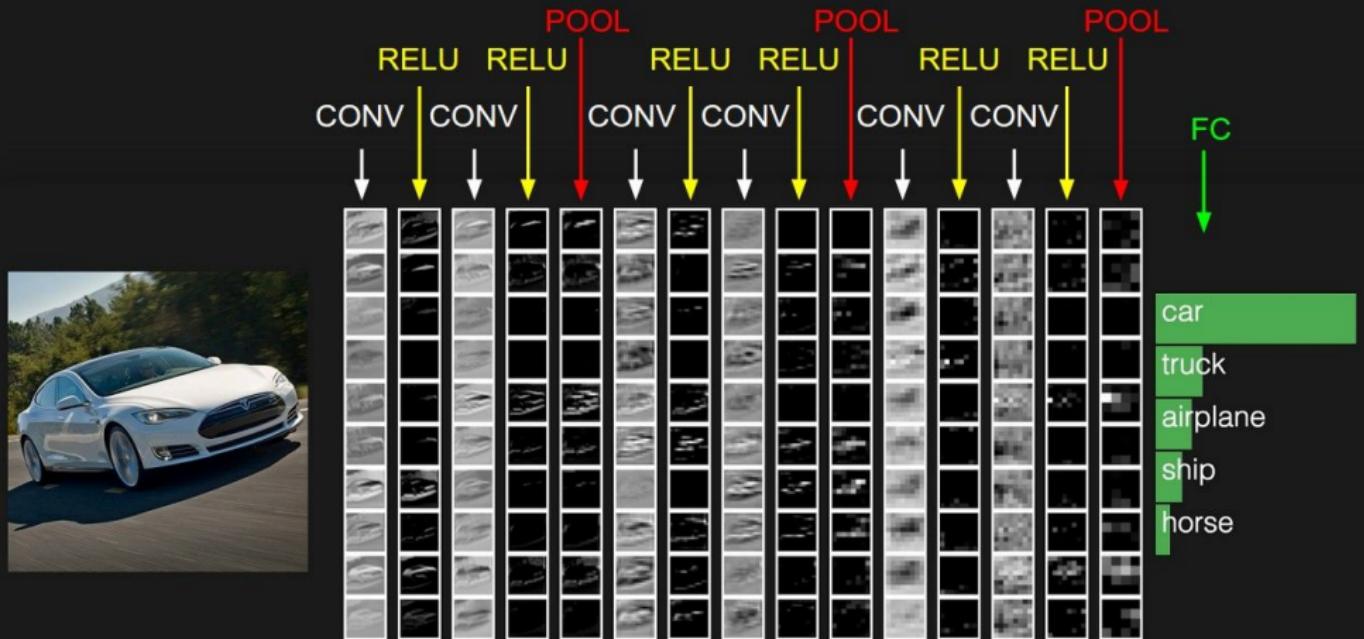
$$\mathbf{s} = W \text{vec}(\mathbf{H}) + \mathbf{b} \quad \leftarrow \text{fully-connected layer to get } C \text{ scores}$$

$$\mathbf{p} = \text{SoftMax}(\mathbf{s}) \quad \leftarrow \text{turn scores into probabilities}$$

- Dimensions of inputs, outputs and parameters:

- \mathbf{X} is $w \times h \times 3$
- Each \mathbf{F}_i is $f \times f \times 3$ and b_i is a scalar
- Each S_i is $(w - f + 1) \times (h - f + 1)$
- \mathbf{S} and \mathbf{H} are $(w - f + 1) \times (h - f + 1) \times n_F$
- W is $C \times (w - f + 1)(h - f + 1)n_F$
- \mathbf{b}, \mathbf{s} and \mathbf{p} are $C \times 1$

preview:



Questions??

How do we learn the parameters of the network?

- Add **fully connected layer(s)** after the convolutional layers.
- Example network:
1 convolutional layer + 1 fully connected layer

$$S_i = \mathbf{X} * \mathbf{F}_i + b_i \quad \text{for } i = 1, \dots, n_F \quad \leftarrow \text{apply convolution filters}$$

$$\mathbf{S} = \{S_1, \dots, S_{n_F}\} \quad \leftarrow \text{stack response maps, get new 3D image}$$

$$\mathbf{H} = \max(0, \mathbf{S}) \quad \leftarrow \text{apply ReLu}$$

$$\mathbf{s} = W \text{vec}(\mathbf{H}) + \mathbf{b} \quad \leftarrow \text{fully-connected layer to get } C \text{ scores}$$

$$\mathbf{p} = \text{SoftMax}(\mathbf{s}) \quad \leftarrow \text{turn scores into probabilities}$$

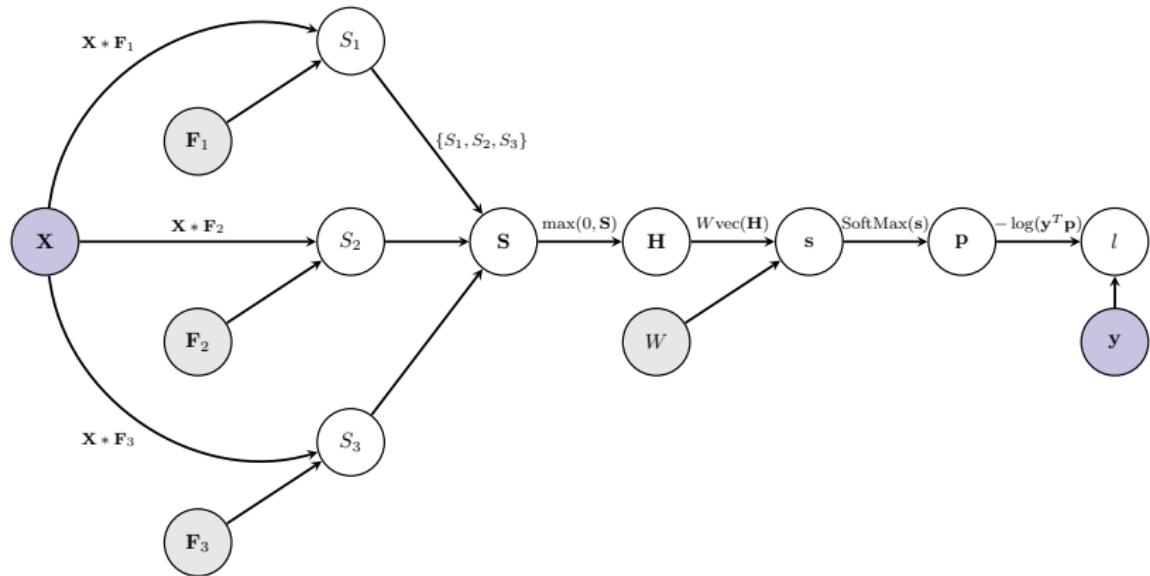
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 - \mathbf{X} is $w \times h \times 3$
 - $\mathbf{Each F}_i$ is $f \times f \times 3$ and b_i is a scalar
 - Each S_i is $(w - f + 1) \times (h - f + 1)$
 - \mathbf{S} and \mathbf{H} are $(w - f + 1) \times (h - f + 1) \times n_F$
 - W is $C \times (w - f + 1)(h - f + 1)n_F$
 - \mathbf{b} , \mathbf{s} and \mathbf{p} are $C \times 1$.

How do we learn the parameters of the network?

- Optimize the usual cross-entropy loss (+ L_2 regularization term) on the training data.
- Use mini-batch gradient descent to perform optimization.
- \implies need to compute the gradient of the loss w.r.t. the convolutional parameters....

Gradient Computations for one Convolutional layer

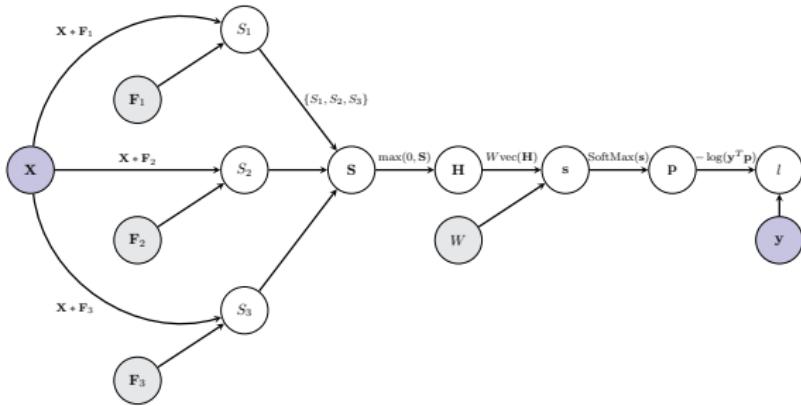
Computational Graph for our simple network



Notes about the above figure

- Apply 3 filters in the convolutional layer ($n_F = 3$).
- $\mathbf{X} = \{X_1, X_2, X_3\}$ and each X_i has size $w \times h$
- Each $\mathbf{F}_i = \{F_{i1}, F_{i2}, F_{i3}\}$ and has size $f \times f \times 3$
- Have omitted the bias weights for clarity.

Computational Graph for our simple network



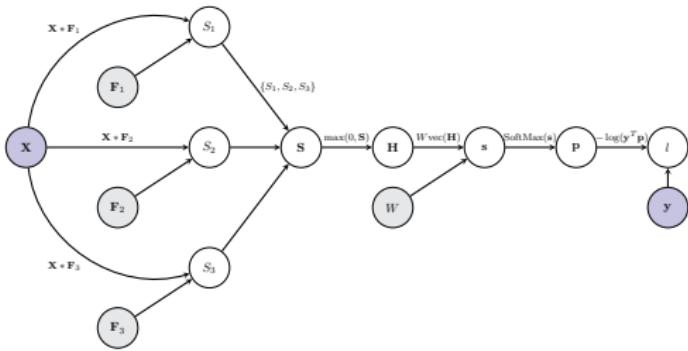
From previous lectures know that

$$\frac{\partial l}{\partial \mathbf{s}} = -(\mathbf{y} - \mathbf{p})^T$$

$$\frac{\partial l}{\partial \text{vec}(\mathbf{H})} = \frac{\partial l}{\partial \mathbf{s}} W$$

$$\frac{\partial l}{\partial \text{vec}(\mathbf{S})} = \frac{\partial l}{\partial \text{vec}(\mathbf{H})} \text{diag}(\text{Ind}(\text{vec}(\mathbf{S}) > 0))$$

Computational Graph for our simple network

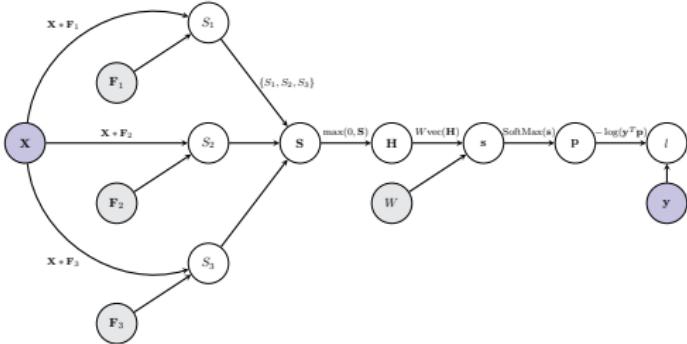


From reading the computational graph we can see that

$$\begin{aligned}\frac{\partial l}{\partial \text{vec}(\mathbf{F}_i)} &= \frac{\partial l}{\partial \text{vec}(S_i)} \frac{\partial \text{vec}(S_i)}{\partial \text{vec}(\mathbf{F}_i)} \\ &= \frac{\partial l}{\partial \text{vec}(\mathbf{S})} \frac{\partial \text{vec}(\mathbf{S})}{\partial \text{vec}(S_i)} \frac{\partial \text{vec}(S_i)}{\partial \text{vec}(\mathbf{F}_i)}\end{aligned}$$

for $i = 1, 2, 3$.

Computational Graph for our simple network



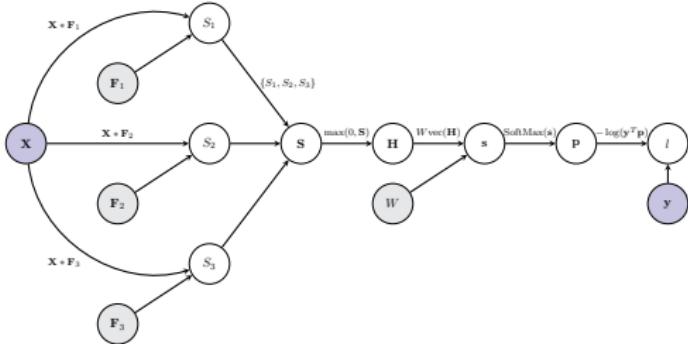
From reading the computational graph we can see that

$$\frac{\partial l}{\partial \text{vec}(F_i)} = \frac{\partial l}{\partial \text{vec}(S)} \frac{\partial \text{vec}(S)}{\partial \text{vec}(S_i)} \frac{\partial \text{vec}(S_i)}{\partial \text{vec}(\mathbf{F}_i)}$$

\uparrow
already know

for $i = 1, 2, 3$.

Computational Graph for our simple network



From reading the computational graph we can see that

$$\frac{\partial l}{\partial \text{vec}(\mathbf{F}_i)} = \frac{\partial l}{\partial \text{vec}(\mathbf{S})} \frac{\partial \text{vec}(\mathbf{S})}{\partial \text{vec}(S_i)} \frac{\partial \text{vec}(S_i)}{\partial \text{vec}(\mathbf{F}_i)}$$

\uparrow
calculate now

for $i = 1, 2, 3$.

Jacobian of $\text{vec}(S)$ w.r.t. $\text{vec}(S_i)$

- Have $\mathbf{S} = \{S_1, S_2, S_3\} \implies$

$$\text{vec}(\mathbf{S}) = \begin{pmatrix} \text{vec}(S_1) \\ \text{vec}(S_2) \\ \text{vec}(S_3) \end{pmatrix}$$

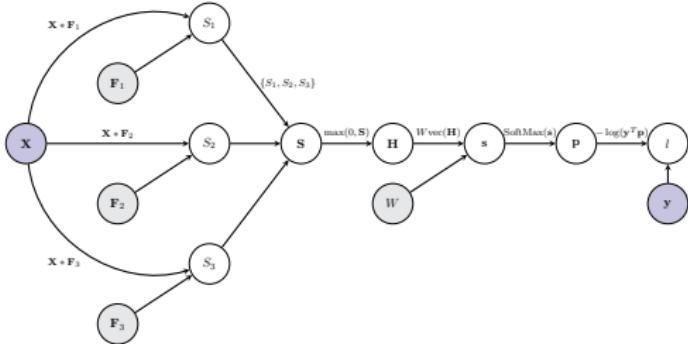
- Then

$$\frac{\partial \text{vec}(\mathbf{S})}{\partial \text{vec}(S_1)} = \begin{pmatrix} I_t \\ 0_{t \times t} \\ 0_{t \times t} \end{pmatrix}, \quad \frac{\partial \text{vec}(\mathbf{S})}{\partial \text{vec}(S_2)} = \begin{pmatrix} 0_{t \times t} \\ I_t \\ 0_{t \times t} \end{pmatrix}, \quad \frac{\partial \text{vec}(\mathbf{S})}{\partial \text{vec}(S_3)} = \begin{pmatrix} 0_{t \times t} \\ 0_{t \times t} \\ I_t \end{pmatrix}$$

where $t = (w - f + 1) \times (h - f + 1)$ and each $0_{t \times t}$ denotes a matrix of zeros of size $t \times t$.

- Each $\frac{\partial \text{vec}(\mathbf{S})}{\partial \text{vec}(S_i)}$ has size $3t \times t$

Computational Graph for our simple network



From reading the computational graph we can see that

$$\frac{\partial l}{\partial \text{vec}(\mathbf{F}_i)} = \frac{\partial l}{\partial \text{vec}(\mathbf{S})} \frac{\partial \text{vec}(\mathbf{S})}{\partial \text{vec}(S_i)} \frac{\partial \text{vec}(S_i)}{\partial \text{vec}(\mathbf{F}_i)}$$

↑
calculate now

for $i = 1, 2, 3$.

Jacobian of $\text{vec}(S_i)$ w.r.t. $\text{vec}(\mathbf{F}_i)$

- Have for $i = 1, 2, 3$:

$$S_i = \mathbf{X} * \mathbf{F}_i$$

- Can write a convolution (in a very memory in-efficient way) as a matrix multiplication

$$\text{vec}(S_i) = M_{\mathbf{X}} \text{vec}(\mathbf{F}_i)$$

- $M_{\mathbf{X}}$ has size $(w - f + 1)(h - f + 1) \times (3f^2)$
- What are the entries of $M_{\mathbf{X}}$?

Writing a convolution as a matrix multiplication

Simple Example

- Have an input image X of size 6×6 .
- Have a filter F of size 3×3 .
- Convolve X by F gives a response map of size 4×4

$$S = X * F$$

- Each entry of S can be written as

$$S_{lm} = \sum_{i=1}^3 \sum_{j=1}^3 X_{l+i-1, m+j-1} F_{ij}$$

Writing a convolution as a matrix multiplication

Simple Example

Want to write this convolution as a matrix multiplication:

$$S = \begin{pmatrix} X_{11} & X_{12} & X_{13} & X_{14} & X_{15} & X_{16} \\ X_{21} & X_{22} & X_{23} & X_{24} & X_{25} & X_{26} \\ X_{31} & X_{32} & X_{33} & X_{34} & X_{35} & X_{36} \\ X_{41} & X_{42} & X_{43} & X_{44} & X_{45} & X_{46} \\ X_{51} & X_{52} & X_{53} & X_{54} & X_{55} & X_{56} \\ X_{61} & X_{62} & X_{63} & X_{64} & X_{65} & X_{66} \end{pmatrix} * \begin{pmatrix} F_{11} & F_{12} & F_{13} \\ F_{21} & F_{22} & F_{23} \\ F_{31} & F_{32} & F_{33} \end{pmatrix}$$

One Solution:

$$S_{11} = (\textcolor{red}{X_{11}} \quad \textcolor{red}{X_{12}} \quad \textcolor{red}{X_{13}} \quad \textcolor{red}{X_{21}} \quad \textcolor{red}{X_{22}} \quad \textcolor{red}{X_{23}} \quad \textcolor{red}{X_{31}} \quad \textcolor{red}{X_{32}} \quad \textcolor{red}{X_{33}}) \begin{pmatrix} F_{11} \\ F_{12} \\ F_{13} \\ F_{21} \\ F_{22} \\ F_{23} \\ F_{31} \\ F_{32} \\ F_{33} \end{pmatrix}$$

new row corresponds to

$$\begin{pmatrix} X_{11} & X_{12} & X_{13} & X_{14} & X_{15} & X_{16} \\ \textcolor{red}{X_{21}} & \textcolor{red}{X_{22}} & \textcolor{red}{X_{23}} & X_{24} & X_{25} & X_{26} \\ \textcolor{red}{X_{31}} & \textcolor{red}{X_{32}} & \textcolor{red}{X_{33}} & X_{34} & X_{35} & X_{36} \\ X_{41} & X_{42} & X_{43} & X_{44} & X_{45} & X_{46} \\ X_{51} & X_{52} & X_{53} & X_{54} & X_{55} & X_{56} \\ X_{61} & X_{62} & X_{63} & X_{64} & X_{65} & X_{66} \end{pmatrix}$$

Writing a convolution as a matrix multiplication

Simple Example

Want to write this convolution as a matrix multiplication:

$$S = \begin{pmatrix} X_{11} & X_{12} & X_{13} & X_{14} & X_{15} & X_{16} \\ X_{21} & X_{22} & X_{23} & X_{24} & X_{25} & X_{26} \\ X_{31} & X_{32} & X_{33} & X_{34} & X_{35} & X_{36} \\ X_{41} & X_{42} & X_{43} & X_{44} & X_{45} & X_{46} \\ X_{51} & X_{52} & X_{53} & X_{54} & X_{55} & X_{56} \\ X_{61} & X_{62} & X_{63} & X_{64} & X_{65} & X_{66} \end{pmatrix} * \begin{pmatrix} F_{11} & F_{12} & F_{13} \\ F_{21} & F_{22} & F_{23} \\ F_{31} & F_{32} & F_{33} \end{pmatrix}$$

One Solution:

$$\begin{pmatrix} S_{11} \\ S_{12} \end{pmatrix} = \begin{pmatrix} \textcolor{red}{X_{11}} & \textcolor{red}{X_{12}} & \textcolor{red}{X_{13}} & \textcolor{red}{X_{21}} & \textcolor{red}{X_{22}} & \textcolor{red}{X_{23}} & \textcolor{red}{X_{31}} & \textcolor{red}{X_{32}} & \textcolor{red}{X_{33}} \\ \textcolor{teal}{X_{12}} & \textcolor{teal}{X_{13}} & \textcolor{teal}{X_{14}} & \textcolor{teal}{X_{22}} & \textcolor{teal}{X_{23}} & \textcolor{teal}{X_{24}} & \textcolor{teal}{X_{32}} & \textcolor{teal}{X_{33}} & \textcolor{teal}{X_{34}} \end{pmatrix} \begin{pmatrix} F_{11} \\ F_{12} \\ F_{13} \\ F_{21} \\ F_{22} \\ F_{23} \\ F_{31} \\ F_{32} \\ F_{33} \end{pmatrix}$$

new row corresponds to

$$\begin{pmatrix} X_{11} & X_{12} & X_{13} & X_{14} & X_{15} & X_{16} \\ X_{21} & \textcolor{teal}{X_{22}} & \textcolor{teal}{X_{23}} & \textcolor{teal}{X_{24}} & X_{25} & X_{26} \\ X_{31} & \textcolor{teal}{X_{32}} & \textcolor{teal}{X_{33}} & \textcolor{teal}{X_{34}} & X_{35} & X_{36} \\ X_{41} & X_{42} & X_{43} & X_{44} & X_{45} & X_{46} \\ X_{51} & X_{52} & X_{53} & X_{54} & X_{55} & X_{56} \\ X_{61} & X_{62} & X_{63} & X_{64} & X_{65} & X_{66} \end{pmatrix}$$

Writing a convolution as a matrix multiplication

Simple Example

Want to write this convolution as a matrix multiplication:

$$S = \begin{pmatrix} X_{11} & X_{12} & X_{13} & X_{14} & X_{15} & X_{16} \\ X_{21} & X_{22} & X_{23} & X_{24} & X_{25} & X_{26} \\ X_{31} & X_{32} & X_{33} & X_{34} & X_{35} & X_{36} \\ X_{41} & X_{42} & X_{43} & X_{44} & X_{45} & X_{46} \\ X_{51} & X_{52} & X_{53} & X_{54} & X_{55} & X_{56} \\ X_{61} & X_{62} & X_{63} & X_{64} & X_{65} & X_{66} \end{pmatrix} * \begin{pmatrix} F_{11} & F_{12} & F_{13} \\ F_{21} & F_{22} & F_{23} \\ F_{31} & F_{32} & F_{33} \end{pmatrix}$$

One Solution:

$$\begin{pmatrix} S_{11} \\ S_{12} \\ S_{13} \end{pmatrix} = \begin{pmatrix} \textcolor{red}{X_{11}} & \textcolor{red}{X_{12}} & \textcolor{red}{X_{13}} & \textcolor{red}{X_{21}} & \textcolor{red}{X_{22}} & \textcolor{red}{X_{23}} & \textcolor{red}{X_{31}} & \textcolor{red}{X_{32}} & \textcolor{red}{X_{33}} \\ \textcolor{blue}{X_{12}} & \textcolor{blue}{X_{13}} & \textcolor{blue}{X_{14}} & \textcolor{blue}{X_{22}} & \textcolor{blue}{X_{23}} & \textcolor{blue}{X_{24}} & \textcolor{blue}{X_{32}} & \textcolor{blue}{X_{33}} & \textcolor{blue}{X_{34}} \\ \textcolor{green}{X_{13}} & \textcolor{green}{X_{14}} & \textcolor{green}{X_{15}} & \textcolor{green}{X_{23}} & \textcolor{green}{X_{24}} & \textcolor{green}{X_{25}} & \textcolor{green}{X_{33}} & \textcolor{green}{X_{34}} & \textcolor{green}{X_{35}} \end{pmatrix} \begin{pmatrix} F_{11} \\ F_{12} \\ F_{13} \\ F_{21} \\ F_{22} \\ F_{23} \\ F_{31} \\ F_{32} \\ F_{33} \end{pmatrix}$$

new row corresponds to

$$\begin{pmatrix} X_{11} & X_{12} & X_{13} & X_{14} & X_{15} & X_{16} \\ X_{21} & X_{22} & X_{23} & \textcolor{red}{X_{24}} & \textcolor{blue}{X_{25}} & X_{26} \\ X_{31} & X_{32} & X_{33} & \textcolor{red}{X_{34}} & \textcolor{blue}{X_{35}} & X_{36} \\ X_{41} & X_{42} & X_{43} & X_{44} & X_{45} & X_{46} \\ X_{51} & X_{52} & X_{53} & X_{54} & X_{55} & X_{56} \\ X_{61} & X_{62} & X_{63} & X_{64} & X_{65} & X_{66} \end{pmatrix}$$

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One Solution:

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One Solution:

$$\begin{pmatrix} S_{11} \\ S_{12} \\ S_{13} \\ S_{14} \\ S_{21} \\ \vdots \\ \vdots \\ S_{44} \end{pmatrix} = \begin{pmatrix} X_{11} & X_{12} & X_{13} & X_{21} & X_{22} & X_{23} & X_{31} & X_{32} & X_{33} \\ X_{12} & X_{13} & X_{14} & X_{22} & X_{23} & X_{24} & X_{32} & X_{33} & X_{34} \\ X_{13} & X_{14} & X_{15} & X_{23} & X_{24} & X_{25} & X_{33} & X_{34} & X_{35} \\ X_{14} & X_{15} & X_{16} & X_{24} & X_{25} & X_{26} & X_{34} & X_{35} & X_{36} \\ X_{21} & X_{22} & X_{23} & X_{31} & X_{32} & X_{33} & X_{41} & X_{42} & X_{43} \\ & & & & \vdots & & & & \\ & & & & & \vdots & & & \\ X_{44} & X_{45} & X_{46} & X_{54} & X_{55} & X_{56} & X_{64} & X_{65} & X_{66} \end{pmatrix} \begin{pmatrix} F_{11} \\ F_{12} \\ F_{13} \\ F_{21} \\ F_{22} \\ F_{23} \\ F_{31} \\ F_{32} \\ F_{33} \end{pmatrix}$$

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One Solution:

$$\begin{pmatrix} S_{11} \\ S_{12} \\ S_{13} \\ S_{14} \\ S_{21} \\ \vdots \\ \vdots \\ S_{44} \end{pmatrix} = \underbrace{\begin{pmatrix} X_{11} & X_{12} & X_{13} & X_{21} & X_{22} & X_{23} & X_{31} & X_{32} & X_{33} \\ X_{12} & X_{13} & X_{14} & X_{22} & X_{23} & X_{24} & X_{32} & X_{33} & X_{34} \\ X_{13} & X_{14} & X_{15} & X_{23} & X_{24} & X_{25} & X_{33} & X_{34} & X_{35} \\ X_{14} & X_{15} & X_{16} & X_{24} & X_{25} & X_{26} & X_{34} & X_{35} & X_{36} \\ X_{21} & X_{22} & X_{23} & X_{31} & X_{32} & X_{33} & X_{41} & X_{42} & X_{43} \\ \vdots & \vdots \\ X_{44} & X_{45} & X_{46} & X_{54} & X_{55} & X_{56} & X_{64} & X_{65} & X_{66} \end{pmatrix}}_{M_X \text{ size } 16 \times 9} \underbrace{\begin{pmatrix} F_{11} \\ F_{12} \\ F_{13} \\ F_{21} \\ F_{22} \\ F_{23} \\ F_{31} \\ F_{32} \\ F_{33} \end{pmatrix}}_{\text{new row corresponds to}} \begin{pmatrix} X_{11} & X_{12} & X_{13} & X_{14} & X_{15} & X_{16} \\ X_{21} & X_{22} & X_{23} & X_{24} & X_{25} & X_{26} \\ X_{31} & X_{32} & X_{33} & X_{34} & X_{35} & X_{36} \\ X_{41} & X_{42} & X_{43} & X_{44} & X_{45} & X_{46} \\ X_{51} & X_{52} & X_{53} & X_{54} & X_{55} & X_{56} \\ X_{61} & X_{62} & X_{63} & X_{64} & X_{65} & X_{66} \end{pmatrix}$$

$$\text{vec}(S) = M_X \text{vec}(F)$$

Questions??

Multiple planes: Convolution → Matrix multiplication

- What about when \mathbf{X} and \mathbf{F} have multiple planes?
- Say $\mathbf{X} = \{X_1, X_2, X_3, X_4\}$ has size $6 \times 6 \times 4$,
- $\mathbf{F} = \{F_1, F_2, F_3, F_4\}$ has size $3 \times 3 \times 4$.
- Have

$$S = \mathbf{X} * \mathbf{F} = \sum_{i=1}^4 X_i * F_i \quad (S \text{ has size } 4 \times 4)$$

- Then

$$\text{vec}(S) = \sum_{i=1}^4 M_{X_i} \text{vec}(F_i) = M_{\mathbf{X}} \text{vec}(\mathbf{F})$$

where

$$M_{\mathbf{X}} = \begin{pmatrix} M_{X_1} & M_{X_2} & M_{X_3} & M_{X_4} \end{pmatrix}, \quad \text{vec}(\mathbf{F}) = \begin{pmatrix} \text{vec}(F_1) \\ \text{vec}(F_2) \\ \text{vec}(F_3) \\ \text{vec}(F_4) \end{pmatrix}.$$

$M_{\mathbf{X}}$ has size 16×36 and $\text{vec}(\mathbf{F})$ has size 36×1 .

Back to: Jacobian of $\text{vec}(S_i)$ w.r.t. $\text{vec}(\mathbf{F}_i)$

- Have for $i = 1, 2, 3$:

$$S_i = \mathbf{X} * \mathbf{F}_i$$

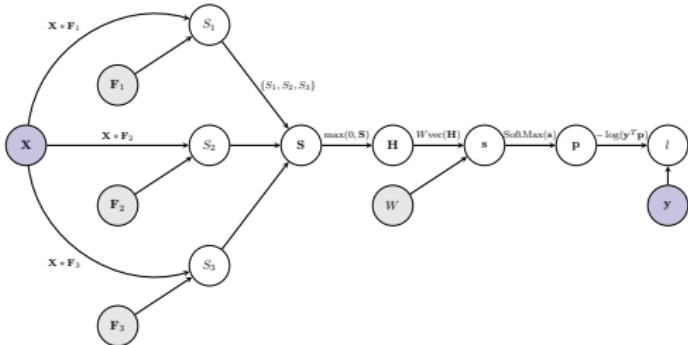
- Can write a convolution (in a very memory inefficient way) as a matrix multiplication

$$\text{vec}(S_i) = M_{\mathbf{X}} \text{vec}(\mathbf{F}_i)$$

- $M_{\mathbf{X}}$ has size $(w - f + 1)(h - f + 1) \times (3f^2)$
- Thus

$$\frac{\partial \text{vec}(S_i)}{\partial \text{vec}(\mathbf{F}_i)} = M_{\mathbf{X}}$$

Gradient of the loss w.r.t. $\text{vec}(\mathbf{F}_i)$



Thus

$$\begin{aligned}
 \frac{\partial l}{\partial \text{vec}(\mathbf{F}_1)} &= \frac{\partial l}{\partial \text{vec}(\mathbf{S})} \frac{\partial \text{vec}(\mathbf{S})}{\partial \text{vec}(S_1)} \frac{\partial \text{vec}(S_1)}{\partial \text{vec}(\mathbf{F}_1)} = \frac{\partial l}{\partial \text{vec}(\mathbf{S})} \begin{pmatrix} I_t \\ 0_{t \times t} \\ 0_{t \times t} \end{pmatrix} M_{\mathbf{X}} \\
 &= \left(\frac{\partial l}{\partial \text{vec}(S_1)} \quad \frac{\partial l}{\partial \text{vec}(S_2)} \quad \frac{\partial l}{\partial \text{vec}(S_3)} \right) \begin{pmatrix} M_{X_1} & M_{X_2} & M_{X_3} \\ 0_{t \times f^2} & 0_{t \times f^2} & 0_{t \times f^2} \\ 0_{t \times f^2} & 0_{t \times f^2} & 0_{t \times f^2} \end{pmatrix} \\
 &= \left(\frac{\partial l}{\partial \text{vec}(S_1)} M_{X_1}, \frac{\partial l}{\partial \text{vec}(S_1)} M_{X_2}, \frac{\partial l}{\partial \text{vec}(S_1)} M_{X_3} \right)
 \end{aligned}$$

Gradient of the loss w.r.t. \mathbf{F}_i

- May want expression for $\frac{\partial l}{\partial \mathbf{F}_i}$ instead of $\frac{\partial l}{\partial \text{vec}(\mathbf{F}_i)}$.
- **Option 1:**

Reshape $\frac{\partial l}{\partial \text{vec}(\mathbf{F}_i)}$ (size $1 \times 3f^2$) to $\frac{\partial l}{\partial \mathbf{F}_i}$ (size $f \times f \times 3$).

Gradient of the loss w.r.t. \mathbf{F}_i

- May want expression for $\frac{\partial l}{\partial \mathbf{F}_i}$ instead of $\frac{\partial l}{\partial \text{vec}(\mathbf{F}_i)}$.
- **Option 2:**

Return to our simple example ...

Gradient of loss w.r.t. F as opposed to $\text{vec}(F)$

Return to Simple Example

Consider the case

$$\begin{pmatrix} v_1 & v_2 & \cdots & v_9 \end{pmatrix} = \begin{pmatrix} g_1 & g_2 & \cdots & g_{16} \end{pmatrix} \underbrace{\begin{pmatrix} X_{11} & X_{12} & X_{13} & X_{21} & X_{22} & X_{23} & X_{31} & X_{32} & X_{33} \\ X_{12} & X_{13} & X_{14} & X_{22} & X_{23} & X_{24} & X_{32} & X_{33} & X_{34} \\ X_{13} & X_{14} & X_{15} & X_{23} & X_{24} & X_{25} & X_{33} & X_{34} & X_{35} \\ X_{14} & X_{15} & X_{16} & X_{24} & X_{25} & X_{26} & X_{34} & X_{35} & X_{36} \\ X_{21} & X_{22} & X_{23} & X_{31} & X_{32} & X_{33} & X_{41} & X_{42} & X_{43} \\ & & & & & \vdots & & & \\ & & & & & \vdots & & & \\ X_{44} & X_{45} & X_{46} & X_{54} & X_{55} & X_{56} & X_{64} & X_{65} & X_{66} \end{pmatrix}}_{M_X \text{ size } 16 \times 9}$$

Gradient of loss w.r.t. F as opposed to $\text{vec}(F)$

Return to Simple Example

Consider the case

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where red column in M_X corresponds to this red block in X

$$\begin{pmatrix} X_{11} & X_{12} & X_{13} & X_{14} & X_{15} & X_{16} \\ X_{21} & X_{22} & X_{23} & X_{24} & X_{25} & X_{26} \\ X_{31} & X_{32} & X_{33} & X_{34} & X_{35} & X_{36} \\ X_{41} & X_{42} & X_{43} & X_{44} & X_{45} & X_{46} \\ X_{51} & X_{52} & X_{53} & X_{54} & X_{55} & X_{56} \\ X_{61} & X_{62} & X_{63} & X_{64} & X_{65} & X_{66} \end{pmatrix}$$

Gradient of loss w.r.t. F as opposed to $\text{vec}(F)$

Return to Simple Example

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Gradient of loss w.r.t. F as opposed to $\text{vec}(F)$

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Return to Simple Example

Consider the case

$$(v_1 \quad v_2 \quad v_3 \quad v_4 \quad \cdots \quad v_9) = (g_1 \quad g_2 \quad \cdots \quad g_{16}) \underbrace{\begin{pmatrix} X_{11} & X_{12} & X_{13} & \textcolor{red}{X_{21}} & X_{22} & X_{23} & X_{31} & X_{32} & X_{33} \\ X_{12} & X_{13} & X_{14} & \textcolor{red}{X_{22}} & X_{23} & X_{24} & X_{32} & X_{33} & X_{34} \\ X_{13} & X_{14} & X_{15} & \textcolor{red}{X_{23}} & X_{24} & X_{25} & X_{33} & X_{34} & X_{35} \\ X_{14} & X_{15} & X_{16} & \textcolor{red}{X_{24}} & X_{25} & X_{26} & X_{34} & X_{35} & X_{36} \\ X_{21} & X_{22} & X_{23} & \textcolor{red}{X_{31}} & X_{32} & X_{33} & X_{41} & X_{42} & X_{43} \\ & & & \vdots & & & & & \\ & & & \vdots & & & & & \\ X_{44} & X_{45} & X_{46} & \textcolor{red}{X_{54}} & X_{55} & X_{56} & X_{64} & X_{65} & X_{66} \end{pmatrix}}_{M_X \text{ size } 16 \times 9}$$

where red column in M_X corresponds to this red block in X

$$\begin{pmatrix} X_{11} & X_{12} & X_{13} & X_{14} & X_{15} & X_{16} \\ \textcolor{red}{X_{21}} & \textcolor{red}{X_{22}} & \textcolor{red}{X_{23}} & \textcolor{red}{X_{24}} & X_{25} & X_{26} \\ \textcolor{red}{X_{31}} & X_{32} & X_{33} & \textcolor{red}{X_{34}} & X_{35} & X_{36} \\ \textcolor{red}{X_{41}} & X_{42} & X_{43} & \textcolor{red}{X_{44}} & X_{45} & X_{46} \\ \textcolor{red}{X_{51}} & \textcolor{red}{X_{52}} & \textcolor{red}{X_{53}} & \textcolor{red}{X_{54}} & X_{55} & X_{56} \\ X_{61} & X_{62} & X_{63} & X_{64} & X_{65} & X_{66} \end{pmatrix}$$

Gradient of loss w.r.t. F as opposed to $\text{vec}(F)$

Return to Simple Example

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Gradient of loss w.r.t. F as opposed to $\text{vec}(F)$

Return to Simple Example

Consider the case

$$(v_1 \quad v_2 \quad v_3 \quad v_4 \quad \cdots \quad v_9) = (g_1 \quad g_2 \quad \cdots \quad g_{16}) \underbrace{\begin{pmatrix} X_{11} & X_{12} & X_{13} & X_{21} & X_{22} & X_{23} & X_{31} & X_{32} & \textcolor{red}{X_{33}} \\ X_{12} & X_{13} & X_{14} & X_{22} & X_{23} & X_{24} & X_{32} & X_{33} & \textcolor{red}{X_{34}} \\ X_{13} & X_{14} & X_{15} & X_{23} & X_{24} & X_{25} & X_{33} & X_{34} & \textcolor{red}{X_{35}} \\ X_{14} & X_{15} & X_{16} & X_{24} & X_{25} & X_{26} & X_{34} & X_{35} & \textcolor{red}{X_{36}} \\ X_{21} & X_{22} & X_{23} & X_{31} & X_{32} & X_{33} & X_{41} & X_{42} & \textcolor{red}{X_{43}} \\ & & & & & \vdots & & & \\ & & & & & \vdots & & & \\ X_{44} & X_{45} & X_{46} & X_{54} & X_{55} & X_{56} & X_{64} & X_{65} & \textcolor{red}{X_{66}} \end{pmatrix}}_{M_X \text{ size } 16 \times 9}$$

where red column in M_X corresponds to this red block in X

$$\begin{pmatrix} X_{11} & X_{12} & X_{13} & X_{14} & X_{15} & X_{16} \\ X_{21} & X_{22} & X_{23} & X_{24} & X_{25} & X_{26} \\ X_{31} & X_{32} & \textcolor{red}{X_{33}} & \textcolor{red}{X_{34}} & \textcolor{red}{X_{35}} & \textcolor{red}{X_{36}} \\ X_{41} & X_{42} & \textcolor{red}{X_{43}} & \textcolor{red}{X_{44}} & \textcolor{red}{X_{45}} & \textcolor{red}{X_{46}} \\ X_{51} & X_{52} & \textcolor{red}{X_{53}} & \textcolor{red}{X_{54}} & \textcolor{red}{X_{55}} & \textcolor{red}{X_{56}} \\ X_{61} & X_{62} & \textcolor{red}{X_{63}} & \textcolor{red}{X_{64}} & \textcolor{red}{X_{65}} & \textcolor{red}{X_{66}} \end{pmatrix}$$

Gradient of loss w.r.t. F as opposed to $\text{vec}(F)$

Return to Simple Example

Consider the case

$$(v_1 \quad v_2 \quad v_3 \quad v_4 \quad \cdots \quad v_9) = (g_1 \quad g_2 \quad \cdots \quad g_{16}) \underbrace{\begin{pmatrix} X_{11} & X_{12} & X_{13} & X_{21} & X_{22} & X_{23} & X_{31} & X_{32} & \textcolor{red}{X_{33}} \\ X_{12} & X_{13} & X_{14} & X_{22} & X_{23} & X_{24} & X_{32} & X_{33} & \textcolor{red}{X_{34}} \\ X_{13} & X_{14} & X_{15} & X_{23} & X_{24} & X_{25} & X_{33} & X_{34} & \textcolor{red}{X_{35}} \\ X_{14} & X_{15} & X_{16} & X_{24} & X_{25} & X_{26} & X_{34} & X_{35} & \textcolor{red}{X_{36}} \\ X_{21} & X_{22} & X_{23} & X_{31} & X_{32} & X_{33} & X_{41} & X_{42} & \textcolor{red}{X_{43}} \\ & & & & & \vdots & & & \\ & & & & & \vdots & & & \\ X_{44} & X_{45} & X_{46} & X_{54} & \underbrace{X_{55}}_{M_X \text{ size } 16 \times 9} & X_{56} & X_{64} & X_{65} & \textcolor{red}{X_{66}} \end{pmatrix}}$$

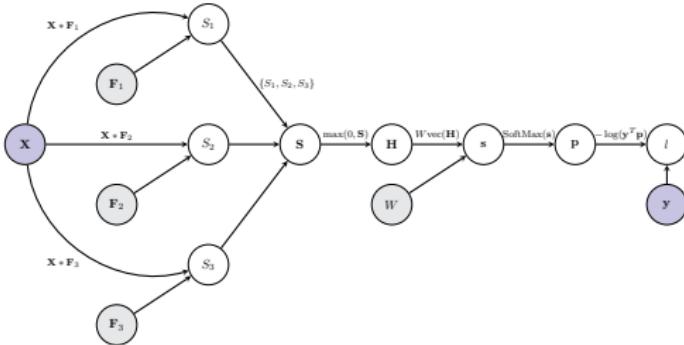
where red column in M_X corresponds to this red block in X

$$\begin{pmatrix} X_{11} & X_{12} & X_{13} & X_{14} & X_{15} & X_{16} \\ X_{21} & X_{22} & X_{23} & X_{24} & X_{25} & X_{26} \\ X_{31} & X_{32} & \textcolor{red}{X_{33}} & \textcolor{red}{X_{34}} & \textcolor{red}{X_{35}} & \textcolor{red}{X_{36}} \\ X_{41} & X_{42} & \textcolor{red}{X_{43}} & \textcolor{red}{X_{44}} & \textcolor{red}{X_{45}} & \textcolor{red}{X_{46}} \\ X_{51} & X_{52} & \textcolor{red}{X_{53}} & \textcolor{red}{X_{54}} & \textcolor{red}{X_{55}} & \textcolor{red}{X_{56}} \\ X_{61} & X_{62} & \textcolor{red}{X_{63}} & \textcolor{red}{X_{64}} & \textcolor{red}{X_{65}} & \textcolor{red}{X_{66}} \end{pmatrix}$$

Thus

$$\begin{pmatrix} v_1 & v_2 & v_3 \\ v_4 & v_5 & v_6 \\ v_7 & v_8 & v_9 \end{pmatrix} = X * \begin{pmatrix} g_1 & g_2 & g_3 & g_4 \\ g_5 & g_6 & g_7 & g_8 \\ g_9 & g_{10} & g_{11} & g_{12} \\ g_{13} & g_{14} & g_{15} & g_{16} \end{pmatrix}$$

Back to Gradient of the loss w.r.t. \mathbf{F}_i



Know

$$\frac{\partial l}{\partial \text{vec}(\mathbf{F}_i)} = \left(\frac{\partial l}{\partial \text{vec}(S_1)} M_{X_1}, \frac{\partial l}{\partial \text{vec}(S_2)} M_{X_2}, \frac{\partial l}{\partial \text{vec}(S_3)} M_{X_3} \right)$$

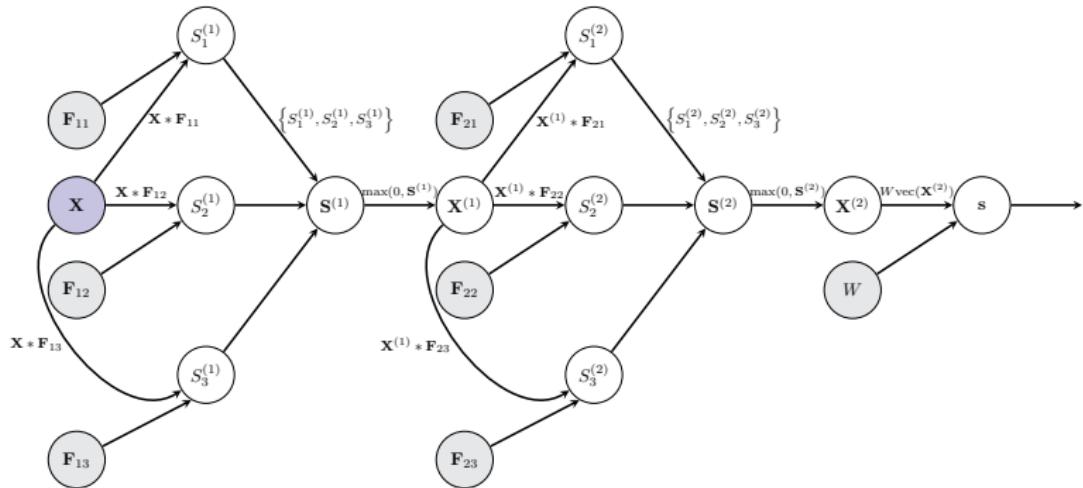
but our simple example \implies

$$\frac{\partial l}{\partial \mathbf{F}_i} = \left\{ X_1 * \frac{\partial l}{\partial S_i}, X_2 * \frac{\partial l}{\partial S_i}, X_3 * \frac{\partial l}{\partial S_i} \right\}$$

Questions??

Gradient Computations for two Convolutional layers

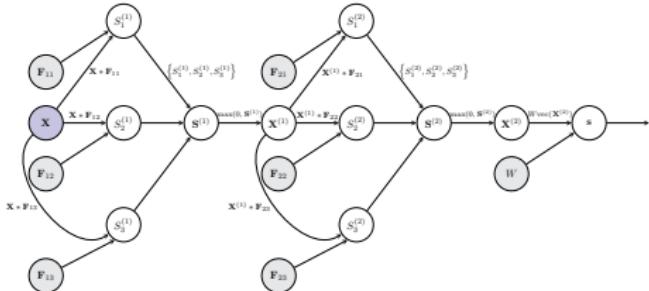
Computational Graph: two convolutional layers



Notes about the figure

- Apply 3 filters at each convolutional layer.
- Have omitted the bias weights for clarity.

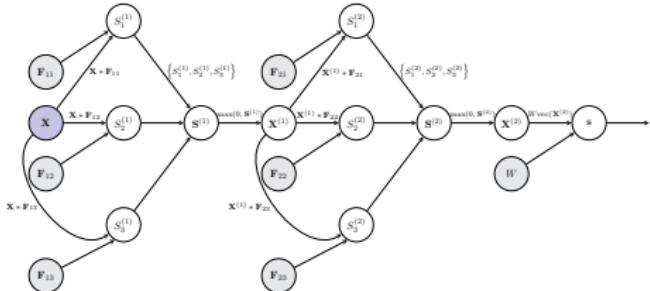
How do we back-propagate the gradient to node $\mathbf{X}^{(1)}$?



- Children of node $\mathbf{X}^{(1)}$ are $S_1^{(2)}, S_2^{(2)}$ and $S_3^{(2)}$
- Thus

$$\frac{\partial l}{\partial \text{vec}(\mathbf{X}^{(1)})} = \sum_{i=1}^3 \frac{\partial l}{\partial \text{vec}(S_i^{(2)})} \frac{\partial \text{vec}(S_i^{(2)})}{\partial \text{vec}(\mathbf{X}^{(1)})}$$

How do we back-propagate the gradient to node $\mathbf{X}^{(1)}$?

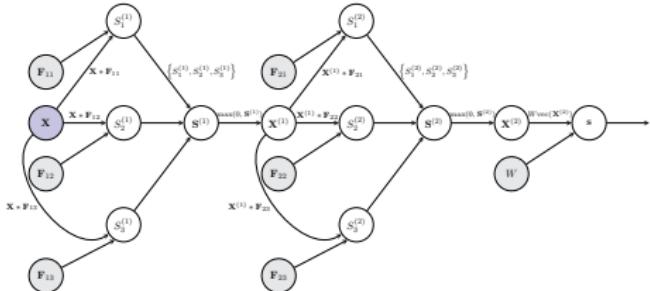


- Children of node $\mathbf{X}^{(1)}$ are $S_1^{(2)}, S_2^{(2)}$ and $S_3^{(2)}$
- Thus

$$\frac{\partial l}{\partial \text{vec}(\mathbf{X}^{(1)})} = \sum_{i=1}^3 \frac{\partial l}{\partial \text{vec}(S_i^{(2)})} \frac{\partial \text{vec}(S_i^{(2)})}{\partial \text{vec}(\mathbf{X}^{(1)})}$$

\uparrow
already know

How do we back-propagate the gradient to node $\mathbf{X}^{(1)}$?



- Children of node $\mathbf{X}^{(1)}$ are $S_1^{(2)}, S_2^{(2)}$ and $S_3^{(2)}$
- Thus

$$\frac{\partial l}{\partial \text{vec}(\mathbf{X}^{(1)})} = \sum_{i=1}^3 \frac{\partial l}{\partial \text{vec}(S_i^{(2)})} \frac{\partial \text{vec}(S_i^{(2)})}{\partial \text{vec}(\mathbf{X}^{(1)})}$$

↑
calculate now

Jacobian of $\text{vec}(S_i^{(2)})$ w.r.t. $\text{vec}(\mathbf{X}^{(1)})$

- Have for $i = 1, 2, 3$:

$$S_i^{(2)} = \mathbf{X}^{(1)} * \mathbf{F}_{2i}$$

- Can write a convolution (in a very memory in-efficient way) as a matrix multiplication

$$\text{vec}(S_i^{(2)}) = M_{\mathbf{F}_{2i}}^{\text{filter}} \text{vec}(\mathbf{X}^{(1)})$$

- $M_{F_{2i}}$ has size $(w - f + 1)(h - f + 1) \times 3wh$ (assuming $\mathbf{X}^{(1)}$ has size $w \times h \times 3$ and \mathbf{F}_{2i} has size $f \times f \times 3$.)
- What are the entries of $M_{\mathbf{F}_{2i}}^{\text{filter}}$?

Writing convolution as a matrix multiplication II

Writing convolution as a matrix multiplication II

Simple Example

- Have an input image X of size 6×6 .
- Have a filter F of size 3×3 .
- Convolve X by F gives a response map of size 4×4

$$S = X * F$$

- Each entry of S can be written as

$$S_{lm} = \sum_{i=1}^3 \sum_{j=1}^3 X_{l+i-1, m+j-1} F_{ij}$$

Writing convolution as a matrix multiplication

Simple Example

Write this convolution as a matrix multiplication involving $\text{vec}(X)$

$$S = \begin{pmatrix} X_{11} & X_{12} & X_{13} & X_{14} & X_{15} & X_{16} \\ X_{21} & X_{22} & X_{23} & X_{24} & X_{25} & X_{26} \\ X_{31} & X_{32} & X_{33} & X_{34} & X_{35} & X_{36} \\ X_{41} & X_{42} & X_{43} & X_{44} & X_{45} & X_{46} \\ X_{51} & X_{52} & X_{53} & X_{54} & X_{55} & X_{56} \\ X_{61} & X_{62} & X_{63} & X_{64} & X_{65} & X_{66} \end{pmatrix} * \begin{pmatrix} F_{11} & F_{12} & F_{13} \\ F_{21} & F_{22} & F_{23} \\ F_{31} & F_{32} & F_{33} \end{pmatrix}$$

Solution:

$$S_{11} = (\underbrace{F_{11} & F_{12} & F_{13} & 0 & 0 & 0}_{\text{entries corresponding to row 1 of } X} \quad \underbrace{F_{21} & F_{22} & F_{23} & 0 & 0 & 0}_{\text{row 2 of } X} \quad \underbrace{F_{31} & F_{32} & F_{33} & 0 & 0 & 0}_{\text{row 3 of } X} \quad \dots) \text{ vec}(X)$$

S_{11} is the dot product between F and red entries of X :

$$\begin{pmatrix} \color{red}{X_{11}} & X_{12} & X_{13} & X_{14} & X_{15} & X_{16} \\ X_{21} & \color{red}{X_{22}} & X_{23} & X_{24} & X_{25} & X_{26} \\ X_{31} & X_{32} & \color{red}{X_{33}} & X_{34} & X_{35} & X_{36} \\ X_{41} & X_{42} & X_{43} & \color{red}{X_{44}} & X_{45} & X_{46} \\ X_{51} & X_{52} & X_{53} & X_{54} & \color{red}{X_{55}} & X_{56} \\ X_{61} & X_{62} & X_{63} & X_{64} & X_{65} & X_{66} \end{pmatrix}$$

Writing convolution as a matrix multiplication

Simple Example

Write this convolution as a matrix multiplication involving $\text{vec}(X)$

$$S = \begin{pmatrix} X_{11} & X_{12} & X_{13} & X_{14} & X_{15} & X_{16} \\ X_{21} & X_{22} & X_{23} & X_{24} & X_{25} & X_{26} \\ X_{31} & X_{32} & X_{33} & X_{34} & X_{35} & X_{36} \\ X_{41} & X_{42} & X_{43} & X_{44} & X_{45} & X_{46} \\ X_{51} & X_{52} & X_{53} & X_{54} & X_{55} & X_{56} \\ X_{61} & X_{62} & X_{63} & X_{64} & X_{65} & X_{66} \end{pmatrix} * \begin{pmatrix} F_{11} & F_{12} & F_{13} \\ F_{21} & F_{22} & F_{23} \\ F_{31} & F_{32} & F_{33} \end{pmatrix}$$

Solution:

$$\begin{pmatrix} S_{11} \\ S_{12} \end{pmatrix} = \left(\underbrace{\begin{matrix} F_{11} & F_{12} & F_{13} & 0 & 0 & 0 \\ 0 & F_{11} & F_{12} & F_{13} & 0 & 0 \end{matrix}}_{\text{entries corresponding to row 1 of } X} \underbrace{\begin{matrix} F_{21} & F_{22} & F_{23} & 0 & 0 & 0 \\ 0 & F_{21} & F_{22} & F_{23} & 0 & 0 \end{matrix}}_{\text{row 2 of } X} \underbrace{\begin{matrix} F_{31} & F_{32} & F_{33} & 0 & 0 & 0 \\ 0 & F_{31} & F_{32} & F_{33} & 0 & 0 \end{matrix}}_{\text{row 3 of } X} \dots \right) \text{vec}(X)$$

S_{12} is the dot product between F and red entries of X :

$$\begin{pmatrix} X_{11} & \color{red}{X_{12}} & X_{13} & \color{red}{X_{14}} & X_{15} & X_{16} \\ X_{21} & \color{red}{X_{22}} & X_{23} & \color{red}{X_{24}} & X_{25} & X_{26} \\ X_{31} & \color{red}{X_{32}} & X_{33} & \color{red}{X_{34}} & X_{35} & X_{36} \\ X_{41} & X_{42} & X_{43} & X_{44} & X_{45} & X_{46} \\ X_{51} & X_{52} & X_{53} & X_{54} & X_{55} & X_{56} \\ X_{61} & X_{62} & X_{63} & X_{64} & X_{65} & X_{66} \end{pmatrix}$$

Writing convolution as a matrix multiplication

Simple Example

Write this convolution as a matrix multiplication involving $\text{vec}(X)$

$$S = \begin{pmatrix} X_{11} & X_{12} & X_{13} & X_{14} & X_{15} & X_{16} \\ X_{21} & X_{22} & X_{23} & X_{24} & X_{25} & X_{26} \\ X_{31} & X_{32} & X_{33} & X_{34} & X_{35} & X_{36} \\ X_{41} & X_{42} & X_{43} & X_{44} & X_{45} & X_{46} \\ X_{51} & X_{52} & X_{53} & X_{54} & X_{55} & X_{56} \\ X_{61} & X_{62} & X_{63} & X_{64} & X_{65} & X_{66} \end{pmatrix} * \begin{pmatrix} F_{11} & F_{12} & F_{13} \\ F_{21} & F_{22} & F_{23} \\ F_{31} & F_{32} & F_{33} \end{pmatrix}$$

Solution:

$$\begin{pmatrix} S_{11} \\ S_{12} \\ S_{13} \end{pmatrix} = \left(\begin{array}{cccccc|cccccc|cccccc|c} \text{entries corresponding to row 1 of } X & & & & & & \text{row 2 of } X & & & & & & & \text{row 3 of } X & & & & \dots \\ F_{11} & F_{12} & F_{13} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & F_{31} & F_{32} & F_{33} & 0 & 0 & 0 & \dots \\ 0 & F_{11} & F_{12} & F_{13} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & F_{31} & F_{32} & F_{33} & 0 & 0 & 0 & \dots \\ 0 & 0 & F_{11} & F_{12} & F_{13} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & F_{31} & F_{32} & F_{33} & 0 & 0 & 0 & \dots \end{array} \right) \text{vec}(X)$$

S_{13} is the dot product between F and red entries of X :

$$\begin{pmatrix} X_{11} & X_{12} & \color{red}{X_{13}} & \color{red}{X_{14}} & \color{red}{X_{15}} & X_{16} \\ X_{21} & X_{22} & \color{red}{X_{23}} & \color{red}{X_{24}} & \color{red}{X_{25}} & X_{26} \\ X_{31} & X_{32} & \color{red}{X_{33}} & \color{red}{X_{34}} & \color{red}{X_{35}} & X_{36} \\ X_{41} & X_{42} & X_{43} & X_{44} & X_{45} & X_{46} \\ X_{51} & X_{52} & X_{53} & X_{54} & X_{55} & X_{56} \\ X_{61} & X_{62} & X_{63} & X_{64} & X_{65} & X_{66} \end{pmatrix}$$

Writing convolution as a matrix multiplication

Simple Example

Write this convolution as a matrix multiplication involving $\text{vec}(X)$

$$S = \begin{pmatrix} X_{11} & X_{12} & X_{13} & X_{14} & X_{15} & X_{16} \\ X_{21} & X_{22} & X_{23} & X_{24} & X_{25} & X_{26} \\ X_{31} & X_{32} & X_{33} & X_{34} & X_{35} & X_{36} \\ X_{41} & X_{42} & X_{43} & X_{44} & X_{45} & X_{46} \\ X_{51} & X_{52} & X_{53} & X_{54} & X_{55} & X_{56} \\ X_{61} & X_{62} & X_{63} & X_{64} & X_{65} & X_{66} \end{pmatrix} * \begin{pmatrix} F_{11} & F_{12} & F_{13} \\ F_{21} & F_{22} & F_{23} \\ F_{31} & F_{32} & F_{33} \end{pmatrix}$$

Solution:

$$\begin{pmatrix} S_{11} \\ S_{12} \\ S_{13} \\ S_{14} \end{pmatrix} = \left(\begin{array}{cccccc|cccccc|cccccc|cccccc|c} \text{entries corresponding to row 1 of } X & & & & & & \text{row 2 of } X & & & & & & & \text{row 3 of } X & & & & & & & \cdots \\ \hline F_{11} & F_{12} & F_{13} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & F_{31} & F_{32} & F_{33} & 0 & 0 & 0 & \cdots \\ 0 & F_{11} & F_{12} & F_{13} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & F_{31} & F_{32} & F_{33} & 0 & 0 & 0 & \cdots \\ 0 & 0 & F_{11} & F_{12} & F_{13} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & F_{31} & F_{32} & F_{33} & 0 & 0 & 0 & \cdots \\ 0 & 0 & 0 & F_{11} & F_{12} & F_{13} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & F_{31} & F_{32} & F_{33} & 0 & 0 & 0 & \cdots \end{array} \right) \text{vec}(X)$$

S_{14} is the dot product between F and red entries of X :

$$\begin{pmatrix} X_{11} & X_{12} & X_{13} & \color{red}{X_{14}} & \color{red}{X_{15}} & \color{red}{X_{16}} \\ X_{21} & X_{22} & X_{23} & \color{red}{X_{24}} & \color{red}{X_{25}} & \color{red}{X_{26}} \\ X_{31} & X_{32} & X_{33} & \color{red}{X_{34}} & \color{red}{X_{35}} & \color{red}{X_{36}} \\ X_{41} & X_{42} & X_{43} & X_{44} & X_{45} & X_{46} \\ X_{51} & X_{52} & X_{53} & X_{54} & X_{55} & X_{56} \\ X_{61} & X_{62} & X_{63} & X_{64} & X_{65} & X_{66} \end{pmatrix}$$

Writing convolution as a matrix multiplication

Simple Example

Write this convolution as a matrix multiplication involving $\text{vec}(X)$

$$S = \begin{pmatrix} X_{11} & X_{12} & X_{13} & X_{14} & X_{15} & X_{16} \\ X_{21} & X_{22} & X_{23} & X_{24} & X_{25} & X_{26} \\ X_{31} & X_{32} & X_{33} & X_{34} & X_{35} & X_{36} \\ X_{41} & X_{42} & X_{43} & X_{44} & X_{45} & X_{46} \\ X_{51} & X_{52} & X_{53} & X_{54} & X_{55} & X_{56} \\ X_{61} & X_{62} & X_{63} & X_{64} & X_{65} & X_{66} \end{pmatrix} * \begin{pmatrix} F_{11} & F_{12} & F_{13} \\ F_{21} & F_{22} & F_{23} \\ F_{31} & F_{32} & F_{33} \end{pmatrix}$$

Solution:

$$\begin{pmatrix} S_{11} \\ S_{12} \\ S_{13} \\ S_{14} \\ S_{21} \end{pmatrix} = \begin{pmatrix} \underbrace{F_{11} & F_{12} & F_{13} & 0 & 0 & 0}_{\text{entries corresponding to row 1 of } X} & \underbrace{F_{21} & F_{22} & F_{23} & 0 & 0 & 0}_{\text{row 2 of } X} & \underbrace{F_{31} & F_{32} & F_{33} & 0 & 0 & 0}_{\text{row 3 of } X} & \dots \\ 0 & F_{11} & F_{12} & F_{13} & 0 & 0 & 0 & F_{31} & F_{32} & F_{33} & 0 & 0 & \dots \\ 0 & 0 & F_{11} & F_{12} & F_{13} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & F_{31} & F_{32} & F_{33} & 0 & 0 & \dots \\ 0 & 0 & 0 & F_{11} & F_{12} & F_{13} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & F_{31} & F_{32} & F_{33} & \dots \\ 0 & 0 & 0 & 0 & 0 & 0 & F_{11} & F_{12} & F_{13} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & \dots \end{pmatrix} \text{vec}(X)$$

S_{21} is the dot product between F and red entries of X :

$$\begin{pmatrix} X_{11} & X_{12} & X_{13} & X_{14} & X_{15} & X_{16} \\ \textcolor{red}{X_{21}} & \textcolor{red}{X_{22}} & \textcolor{red}{X_{23}} & X_{24} & X_{25} & X_{26} \\ \textcolor{red}{X_{31}} & \textcolor{red}{X_{32}} & \textcolor{red}{X_{33}} & X_{34} & X_{35} & X_{36} \\ \textcolor{red}{X_{41}} & \textcolor{red}{X_{42}} & \textcolor{red}{X_{43}} & X_{44} & X_{45} & X_{46} \\ X_{51} & X_{52} & X_{53} & X_{54} & X_{55} & X_{56} \\ X_{61} & X_{62} & X_{63} & X_{64} & X_{65} & X_{66} \end{pmatrix}$$

Writing convolution as a matrix multiplication

Simple Example

Write this convolution as a matrix multiplication involving $\text{vec}(X)$

$$S = \begin{pmatrix} X_{11} & X_{12} & X_{13} & X_{14} & X_{15} & X_{16} \\ X_{21} & X_{22} & X_{23} & X_{24} & X_{25} & X_{26} \\ X_{31} & X_{32} & X_{33} & X_{34} & X_{35} & X_{36} \\ X_{41} & X_{42} & X_{43} & X_{44} & X_{45} & X_{46} \\ X_{51} & X_{52} & X_{53} & X_{54} & X_{55} & X_{56} \\ X_{61} & X_{62} & X_{63} & X_{64} & X_{65} & X_{66} \end{pmatrix} * \begin{pmatrix} F_{11} & F_{12} & F_{13} \\ F_{21} & F_{22} & F_{23} \\ F_{31} & F_{32} & F_{33} \end{pmatrix}$$

Solution:

Writing convolution as a matrix multiplication

Simple Example

Write this convolution as a matrix multiplication involving $\text{vec}(X)$

$$S = \begin{pmatrix} X_{11} & X_{12} & X_{13} & X_{14} & X_{15} & X_{16} \\ X_{21} & X_{22} & X_{23} & X_{24} & X_{25} & X_{26} \\ X_{31} & X_{32} & X_{33} & X_{34} & X_{35} & X_{36} \\ X_{41} & X_{42} & X_{43} & X_{44} & X_{45} & X_{46} \\ X_{51} & X_{52} & X_{53} & X_{54} & X_{55} & X_{56} \\ X_{61} & X_{62} & X_{63} & X_{64} & X_{65} & X_{66} \end{pmatrix} * \begin{pmatrix} F_{11} & F_{12} & F_{13} \\ F_{21} & F_{22} & F_{23} \\ F_{31} & F_{32} & F_{33} \end{pmatrix}$$

Solution:

$$\left(\begin{array}{c} S_{11} \\ S_{12} \\ S_{13} \\ S_{14} \\ S_{21} \\ \vdots \\ \vdots \end{array} \right) = \left(\begin{array}{cccccc} F_{11} & F_{12} & F_{13} & 0 & 0 & 0 \\ 0 & F_{11} & F_{12} & F_{13} & 0 & 0 \\ 0 & 0 & F_{11} & F_{12} & F_{13} & 0 \\ 0 & 0 & 0 & F_{11} & F_{12} & F_{13} \\ 0 & 0 & 0 & 0 & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \end{array} \right) \underbrace{\begin{array}{cccccc} F_{21} & F_{22} & F_{23} & 0 & 0 & 0 \\ 0 & F_{21} & F_{22} & F_{23} & 0 & 0 \\ 0 & 0 & F_{21} & F_{22} & F_{23} & 0 \\ 0 & 0 & 0 & F_{21} & F_{22} & F_{23} \\ 0 & 0 & 0 & 0 & F_{21} & F_{22} \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \end{array}}_{M_F^{\text{filter}}} \underbrace{\begin{array}{cccccc} F_{31} & F_{32} & F_{33} & 0 & 0 & 0 \\ 0 & F_{31} & F_{32} & F_{33} & 0 & 0 \\ 0 & 0 & F_{31} & F_{32} & F_{33} & 0 \\ 0 & 0 & 0 & F_{31} & F_{32} & F_{33} \\ 0 & 0 & 0 & 0 & F_{31} & F_{32} \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \end{array}}_{\text{row } 3 \text{ of } X} \cdots \right) \underbrace{\text{entries corresponding to row } 1 \text{ of } X}_{\text{row } 2 \text{ of } X} \underbrace{\text{row } 3 \text{ of } X}_{\text{vec}(X)}$$

Thus

$$\text{vec}(S) = M_F^{\text{filter}} \text{vec}(X)$$

Multiple planes: Convolution → Matrix multiplication

- What about when \mathbf{X} and \mathbf{F} have multiple planes?
- $\mathbf{X} = \{X_1, X_2, X_3, X_4\}$ has size $6 \times 6 \times 4$
- $\mathbf{F} = \{F_1, F_2, F_3, F_4\}$ has size $3 \times 3 \times 4$
- Have

$$S = \mathbf{X} * \mathbf{F} = \sum_{i=1}^4 X_i * F_i$$

- Then

$$\text{vec}(S) = \sum_{i=1}^4 M_{F_i}^{\text{filter}} \text{vec}(X_i) = M_{\mathbf{F}}^{\text{filter}} \text{vec}(\mathbf{X})$$

where

$$M_{\mathbf{F}}^{\text{filter}} = \begin{pmatrix} M_{F_1}^{\text{filter}} & M_{F_2}^{\text{filter}} & M_{F_3}^{\text{filter}} & M_{F_4}^{\text{filter}} \end{pmatrix}, \quad \text{vec}(\mathbf{X}) = \begin{pmatrix} \text{vec}(X_1) \\ \text{vec}(X_2) \\ \text{vec}(X_3) \\ \text{vec}(X_4) \end{pmatrix}.$$

$M_{\mathbf{F}}^{\text{filter}}$ has size 16×144 and $\text{vec}(\mathbf{X})$ size 144×1

Back to: Jacobian of $\text{vec}(S_i^{(2)})$ w.r.t. $\text{vec}(\mathbf{X}^{(1)})$

- Have for $i = 1, 2, 3$:

$$S_i^{(2)} = \mathbf{X}^{(1)} * \mathbf{F}_{2i}$$

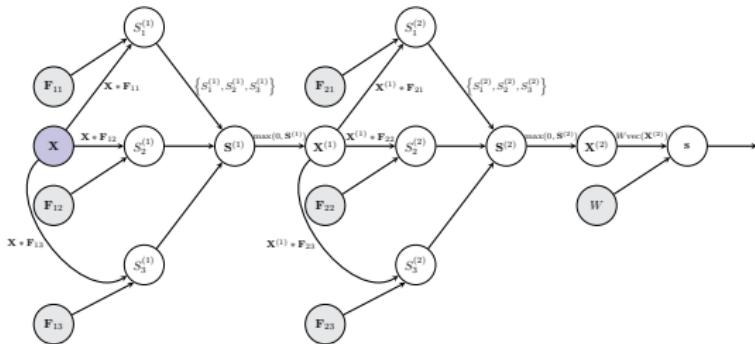
- Can write a convolution (in a very memory in-efficient way) as a matrix multiplication

$$\text{vec}(S_i^{(2)}) = M_{\mathbf{F}_{2i}}^{\text{filter}} \text{vec}(\mathbf{X}^{(1)})$$

- $M_{\mathbf{F}_{2i}}^{\text{filter}}$ has size $(w' - f + 1)(h' - f + 1) \times 3w'h'$ (where $w' = w - f + 1$ and $h' = h - f + 1$).
- Thus

$$\frac{\partial \text{vec}(S_i^{(2)})}{\partial \text{vec}(\mathbf{X}^{(1)})} = M_{\mathbf{F}_{2i}}^{\text{filter}}$$

Gradient of the loss w.r.t. $\text{vec}(\mathbf{X}^{(1)})$



- Thus

$$\begin{aligned}\frac{\partial l}{\partial \text{vec}(\mathbf{X}^{(1)})} &= \sum_{i=1}^3 \frac{\partial l}{\partial \text{vec}(S_i^{(2)})} \frac{\partial \text{vec}(S_i^{(2)})}{\partial \text{vec}(\mathbf{X}^{(1)})} \\ &= \sum_{i=1}^3 \frac{\partial l}{\partial \text{vec}(S_i^{(2)})} M_{F_{2i}}^{\text{filter}}\end{aligned}$$

Gradient of the loss w.r.t. $\mathbf{X}^{(1)}$

- May want expression for $\frac{\partial l}{\partial \mathbf{X}^{(1)}}$ instead of $\frac{\partial l}{\partial \text{vec}(\mathbf{X}^{(1)})}$.
- **Option 1:**

Reshape $\frac{\partial l}{\partial \text{vec}(\mathbf{X}^{(1)})}$ (size $1 \times 3w'h'$) to $\frac{\partial l}{\partial \mathbf{X}^{(1)}}$ (size $w' \times h' \times 3$).

Gradient of the loss w.r.t. $\mathbf{X}^{(1)}$

- May want expression for $\frac{\partial l}{\partial \mathbf{X}^{(1)}}$ instead of $\frac{\partial l}{\partial \text{vec}(\mathbf{X}^{(1)})}$.
- **Option 2:**

Return to our simple example ...

Remember the simple example

- Have an input image X of size 6×6 .
- Have a filter F of size 3×3 .
- Convolve X by F gives a response map of size 4×4

$$S = X * F$$

- Each entry of S can be written as

$$S_{lm} = \sum_{i=1}^3 \sum_{j=1}^3 X_{l+i-1, m+j-1} F_{ij}$$

- Can re-write the convolution as a matrix multiplication

$$\text{vec}(S) = M_F^{\text{filter}} \text{vec}(X)$$

Propagate the gradient through the convolution

- Have input image X size 6×6 and filter F size 3×3
- Convolve X with F . Can write as

$$\text{vec}(S) = M_F^{\text{filter}} \text{vec}(X)$$

- If this operation part of some network, then the gradient of the loss w.r.t. $\text{vec}(X)$ is given by

$$\frac{\partial l}{\partial \text{vec}(X)} = \frac{\partial l}{\partial \text{vec}(S)} \frac{\partial \text{vec}(S)}{\partial \text{vec}(X)} = \frac{\partial l}{\partial \text{vec}(S)} M_F^{\text{filter}}$$

- Streamlining notation let

$$\mathbf{v} = \mathbf{g} M_F^{\text{filter}}$$

where

$$\mathbf{v} = \frac{\partial l}{\partial \text{vec}(X)}, \quad \mathbf{g} = \frac{\partial l}{\partial \text{vec}(S)}$$

Examine back-prop eqn thru the convolution in more detail

Have

Examine back-prop eqn thru the convolution in more detail

$$\begin{pmatrix}
 F_{11} & F_{12} & F_{13} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & F_{31} & F_{32} & F_{33} & 0 & 0 & 0 & \dots \\
 0 & F_{11} & F_{12} & F_{13} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & F_{31} & F_{32} & F_{33} & 0 & 0 & \dots \\
 0 & 0 & F_{11} & F_{12} & F_{13} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & F_{31} & F_{32} & F_{33} & 0 & 0 & \dots \\
 0 & 0 & 0 & F_{11} & F_{12} & F_{13} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & F_{31} & F_{32} & F_{33} & 0 & 0 & \dots \\
 0 & 0 & 0 & 0 & 0 & 0 & F_{11} & F_{12} & F_{13} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & \dots \\
 \vdots & \vdots \\
 \vdots & \vdots
 \end{pmatrix}$$

$(v_1 \ v_2 \ \dots \ v_{36}) = (g_1 \ g_2 \ \dots \ g_{16})$

$$v_1 = g_1 F_{11}$$

Examine back-prop eqn thru the convolution in more detail

$$(v_1 \ v_2 \ \dots \ v_{36}) = (g_1 \ g_2 \ \dots \ g_{16}) \begin{pmatrix} F_{11} & \textcolor{red}{F_{12}} & F_{13} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & F_{31} & F_{32} & F_{33} & 0 & 0 & 0 & \dots \\ 0 & \textcolor{red}{F_{11}} & F_{12} & F_{13} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & F_{31} & F_{32} & F_{33} & 0 & 0 & \dots \\ 0 & 0 & F_{11} & F_{12} & F_{13} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & F_{31} & F_{32} & F_{33} & 0 & 0 & \dots \\ 0 & 0 & 0 & F_{11} & F_{12} & F_{13} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & F_{31} & F_{32} & F_{33} & 0 & 0 & \dots \\ 0 & 0 & 0 & 0 & 0 & 0 & F_{11} & F_{12} & F_{13} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & \dots \\ \vdots & \vdots \\ \vdots & \vdots \end{pmatrix}$$

$$v_1 = g_1 F_{11}$$

$$v_2 = \textcolor{red}{g_1 F_{12} + g_2 F_{11}}$$

Examine back-prop eqn thru the convolution in more detail

$$(v_1 \ v_2 \ \dots \ v_{36}) = (g_1 \ g_2 \ \dots \ g_{16}) \begin{pmatrix} F_{11} & F_{12} & \textcolor{red}{F_{13}} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & F_{31} & F_{32} & F_{33} & 0 & 0 & 0 & \dots \\ 0 & F_{11} & \textcolor{red}{F_{12}} & F_{13} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & F_{31} & F_{32} & F_{33} & 0 & 0 & \dots \\ 0 & 0 & \textcolor{red}{F_{11}} & F_{12} & F_{13} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & F_{31} & F_{32} & F_{33} & 0 & 0 & \dots \\ 0 & 0 & 0 & \textcolor{red}{F_{11}} & F_{12} & F_{13} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & F_{31} & F_{32} & F_{33} & 0 & 0 & \dots \\ 0 & 0 & 0 & 0 & 0 & 0 & F_{11} & F_{12} & F_{13} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & F_{31} & F_{32} & F_{33} & \dots \\ \vdots & \vdots \\ \vdots & \vdots \end{pmatrix}$$

$$v_1 = g_1 F_{11}$$

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$$\textcolor{red}{v_3 = g_1 F_{13} + g_2 F_{12} + g_3 F_{11}}$$

Examine back-prop eqn thru the convolution in more detail

$$(v_1 \ v_2 \ \dots \ v_{36}) = (g_1 \ g_2 \ \dots \ g_{16}) \begin{pmatrix} F_{11} & F_{12} & F_{13} & \color{red}{0} & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & F_{31} & F_{32} & F_{33} & 0 & 0 & 0 & \dots \\ 0 & F_{11} & F_{12} & \color{red}{F_{13}} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & F_{31} & F_{32} & F_{33} & 0 & 0 & \dots \\ 0 & 0 & F_{11} & \color{red}{F_{12}} & F_{13} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & F_{31} & F_{32} & F_{33} & 0 & 0 & \dots \\ 0 & 0 & 0 & \color{red}{F_{11}} & F_{12} & F_{13} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & F_{31} & F_{32} & F_{33} & 0 & 0 & \dots \\ 0 & 0 & 0 & 0 & \color{red}{0} & 0 & F_{11} & F_{12} & F_{13} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & \dots \\ \vdots & \vdots \\ \vdots & \vdots \end{pmatrix}$$

$$v_1 = g_1 F_{11}$$

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$$v_3 = g_1 F_{13} + g_2 F_{12} + g_3 F_{11}$$

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Examine back-prop eqn thru the convolution in more detail

$$(v_1 \ v_2 \ \dots \ v_{36}) = (g_1 \ g_2 \ \dots \ g_{16}) \begin{pmatrix} F_{11} & F_{12} & F_{13} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & F_{31} & F_{32} & F_{33} & 0 & 0 & 0 & \dots \\ 0 & F_{11} & F_{12} & F_{13} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & F_{31} & F_{32} & F_{33} & 0 & 0 & \dots \\ 0 & 0 & F_{11} & F_{12} & F_{13} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & F_{31} & F_{32} & F_{33} & 0 & 0 & \dots \\ 0 & 0 & 0 & F_{11} & F_{12} & F_{13} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & F_{31} & F_{32} & F_{33} & 0 & 0 & \dots \\ 0 & 0 & 0 & 0 & 0 & 0 & F_{11} & F_{12} & F_{13} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & \dots \\ \vdots & \vdots \\ \vdots & \vdots \end{pmatrix}$$

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$$v_4 = g_2 F_{13} + g_3 F_{12} + g_4 F_{11}$$

$$v_5 = g_3 F_{13} + g_4 F_{12}$$

$$v_6 = g_4 F_{13}$$

$$v_7 = g_1 F_{21} + g_5 F_{11}$$

$$v_8 = g_1 F_{22} + g_2 F_{21} + g_5 F_{12} + g_6 F_{11}$$

$$v_9 = g_1 F_{23} + g_2 F_{22} + g_3 F_{21} + g_5 F_{13} + g_6 F_{12} + g_7 F_{11}$$

$$v_{10} = g_2 F_{23} + g_3 F_{22} + g_4 F_{21} + g_6 F_{13} + g_7 F_{12} + g_8 F_{11}$$

$$v_{11} = g_3 F_{23} + g_4 F_{22} + g_7 F_{13} + g_8 F_{12}$$

$$v_{12} = g_4 F_{23} + g_8 F_{13}$$

$$v_{13} = g_1 F_{31} + g_5 F_{21} + g_9 F_{11}$$

$$v_{14} = g_1 F_{32} + g_2 F_{31} + g_5 F_{22} + g_6 F_{21} + g_9 F_{12} + g_{10} F_{11}$$

$$v_{15} = g_1 F_{33} + g_2 F_{32} + g_3 F_{31} + g_5 F_{23} + g_6 F_{22} + g_7 F_{21} + g_9 F_{13} + g_{10} F_{12} + g_{11} F_{11}$$

⋮

Examine back-prop eqn thru the convolution in more detail

$$(v_1 \ v_2 \ \dots \ v_{36}) = (g_1 \ g_2 \ \dots \ g_{16}) \begin{pmatrix} F_{11} & F_{12} & F_{13} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & F_{31} & F_{32} & F_{33} & 0 & 0 & 0 & \dots \\ 0 & F_{11} & F_{12} & F_{13} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & F_{31} & F_{32} & F_{33} & 0 & 0 & 0 & \dots \\ 0 & 0 & F_{11} & F_{12} & F_{13} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & F_{31} & F_{32} & F_{33} & 0 & 0 & 0 & \dots \\ 0 & 0 & 0 & F_{11} & F_{12} & F_{13} & 0 & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & F_{31} & F_{32} & F_{33} & \dots \\ 0 & 0 & 0 & 0 & 0 & 0 & F_{11} & F_{12} & F_{13} & 0 & 0 & 0 & F_{21} & F_{22} & F_{23} & 0 & 0 & 0 & \dots \\ \vdots & \vdots \\ \vdots & \vdots \end{pmatrix}$$

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$$v_5 = g_3 F_{13} + g_4 F_{12}$$

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$$v_{13} = g_1 F_{31} + g_5 F_{21} + g_9 F_{11}$$

$$v_{14} = g_1 F_{32} + g_2 F_{31} + g_5 F_{22} + g_6 F_{21} + g_9 F_{12} + g_{10} F_{11}$$

$$v_{15} = g_1 F_{33} + g_2 F_{32} + g_3 F_{31} + g_5 F_{23} + g_6 F_{22} + g_7 F_{21} + g_9 F_{13} + g_{10} F_{12} + g_{11} F_{11}$$

:

There is a pattern here!

Write back-prop eqn through convolution as a convolution

- Reshape vectors \mathbf{g} and \mathbf{v} into matrices

$$G = \begin{pmatrix} g_1 & g_2 & g_3 & g_4 \\ g_5 & g_6 & g_7 & g_8 \\ g_9 & g_{10} & g_{11} & g_{12} \\ g_{13} & g_{14} & g_{15} & g_{16} \end{pmatrix}, \quad V = \begin{pmatrix} v_1 & v_2 & v_3 & v_4 & v_5 & v_6 \\ v_7 & v_8 & v_9 & v_{10} & v_{11} & v_{12} \\ v_{13} & v_{14} & v_{15} & v_{16} & v_{17} & v_{18} \\ v_{19} & v_{20} & v_{21} & v_{22} & v_{23} & v_{24} \\ v_{25} & v_{26} & v_{27} & v_{28} & v_{29} & v_{30} \\ v_{31} & v_{32} & v_{33} & v_{34} & v_{35} & v_{36} \end{pmatrix}$$

- Let

$$G_{\text{zero-pad}} = \begin{pmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & g_1 & g_2 & g_3 & g_4 & 0 & 0 \\ 0 & 0 & g_5 & g_6 & g_7 & g_8 & 0 & 0 \\ 0 & 0 & g_9 & g_{10} & g_{11} & g_{12} & 0 & 0 \\ 0 & 0 & g_{13} & g_{14} & g_{15} & g_{16} & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}, \quad F^{\text{rot180}} = \begin{pmatrix} F_{33} & F_{32} & F_{31} \\ F_{23} & F_{22} & F_{21} \\ F_{13} & F_{12} & F_{11} \end{pmatrix}$$

- Then

$$V = G_{\text{zero-pad}} * F^{\text{rot180}} \implies \frac{\partial l}{\partial X} = \left(\frac{\partial l}{\partial S} \right)_{\text{zero-pad}} * F^{\text{rot180}}$$

Multiple planes: Write back-prop eqn as a convolution

- $\mathbf{X} = \{X_1, X_2, X_3, X_4\}$ has size $6 \times 6 \times 4$
- $\mathbf{F} = \{F_1, F_2, F_3, F_4\}$ has size $3 \times 3 \times 4$
- Have

$$S = \mathbf{X} * \mathbf{F} \implies \text{vec}(S) = M_{\mathbf{F}}^{\text{filter}} \text{vec}(\mathbf{X})$$

where

- S is 4×4 ,
- $\text{vec}(S)$ is 16×1 ,
- $M_{\mathbf{F}}^{\text{filter}} = (M_{F_1}^{\text{filter}}, M_{F_2}^{\text{filter}}, M_{F_3}^{\text{filter}}, M_{F_4}^{\text{filter}})$ is 16×144 and
- $\text{vec}(\mathbf{X}) = \begin{pmatrix} \text{vec}(X_1) \\ \vdots \\ \text{vec}(X_4) \end{pmatrix}$ is 144×1 .

- Now

$$\frac{\partial l}{\partial \text{vec}(\mathbf{X})} = \left(\frac{\partial l}{\partial \text{vec}(X_1)}, \frac{\partial l}{\partial \text{vec}(X_2)}, \frac{\partial l}{\partial \text{vec}(X_3)}, \frac{\partial l}{\partial \text{vec}(X_4)} \right)$$

Multiple planes: Write back-prop eqn as a convolution

- Now

$$\begin{aligned}\frac{\partial l}{\partial \text{vec}(\mathbf{X})} &= \left(\frac{\partial l}{\partial \text{vec}(X_1)}, \frac{\partial l}{\partial \text{vec}(X_2)}, \frac{\partial l}{\partial \text{vec}(X_3)}, \frac{\partial l}{\partial \text{vec}(X_4)} \right) \\ &= \left(\frac{\partial l}{\partial \text{vec}(S)} M_{F_1}, \frac{\partial l}{\partial \text{vec}(S)} M_{F_2}, \frac{\partial l}{\partial \text{vec}(S)} M_{F_3}, \frac{\partial l}{\partial \text{vec}(S)} M_{F_4} \right)\end{aligned}$$

- Remember for a single plane have

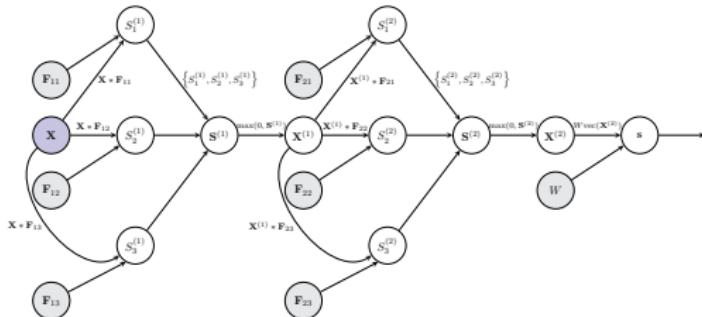
$$\frac{\partial l}{\partial X_i} = G_{\text{zero-pad}} * F_i^{\text{rot180}}$$

where $G_{\text{zero-pad}}$ is the zero-padded version of $\frac{\partial l}{\partial S}$.

- Thus

$$\frac{\partial l}{\partial \mathbf{X}} = \left\{ G_{\text{zero-pad}} * F_1^{\text{rot180}}, G_{\text{zero-pad}} * F_2^{\text{rot180}}, G_{\text{zero-pad}} * F_3^{\text{rot180}}, G_{\text{zero-pad}} * F_4^{\text{rot180}} \right\}$$

Back to gradient of the loss w.r.t. $\mathbf{X}^{(1)}$



Have applied multiple filters with multiple planes and know

$$\frac{\partial l}{\partial \text{vec}(\mathbf{X}^{(1)})} = \sum_{i=1}^3 \frac{\partial l}{\partial \text{vec}(S_i^{(2)})} M_{\mathbf{F}_{2i}}^{\text{filter}}$$

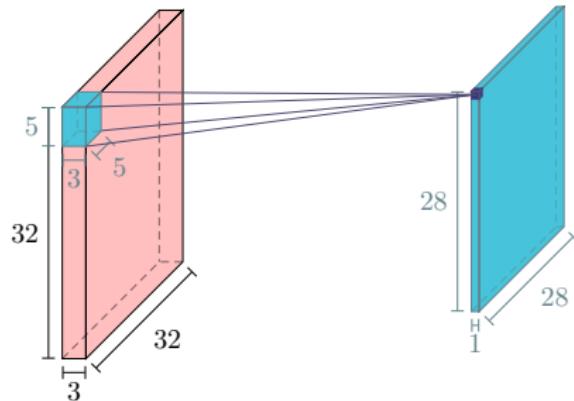
then

$$\frac{\partial l}{\partial X^{(1)}} = \left\{ \sum_{i=1}^3 G_i^{\text{zero-pad}} * F_{2i,1}^{\text{rot180}}, \sum_{i=1}^3 G_i^{\text{zero-pad}} * F_{2i,2}^{\text{rot180}}, \sum_{i=1}^3 G_i^{\text{zero-pad}} * F_{2i,3}^{\text{rot180}} \right\}$$

where $G_i = \frac{\partial l}{\partial S_i^{(2)}}$ and $\mathbf{F}_{2i} = \{F_{2i,1}, F_{2i,2}, F_{2i,3}\}$.

More details on the Convolution layers: **Striding & Zero Padding**

Convolution Layer

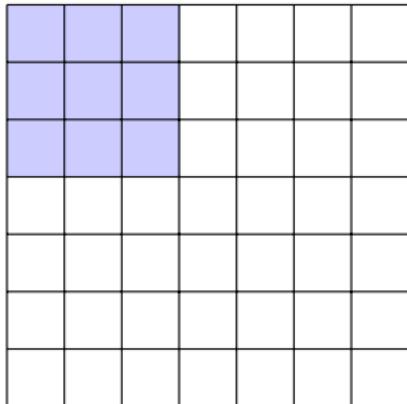


Convolve the image, \mathbf{X} , with the filter \mathbf{F} .

- Slide filter over all spatial locations in image.
- At each location output 1 number:

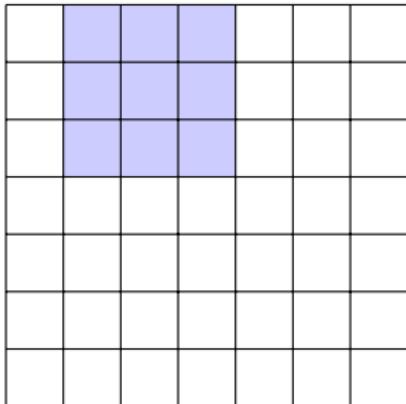
compute dot product between \mathbf{F} and a $5 \times 5 \times 3$ chunk of \mathbf{X}

A closer look at the spatial dimensions



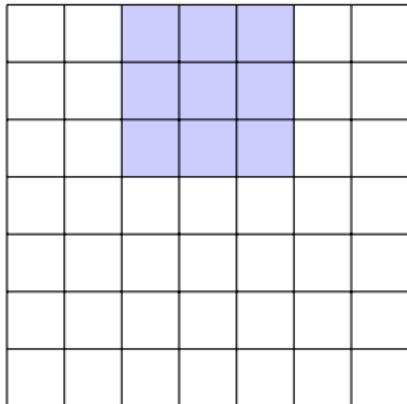
- $7 \times 7 \times D$ input (just display one plane).
- Have $3 \times 3 \times D$ filter.

A closer look at the spatial dimensions



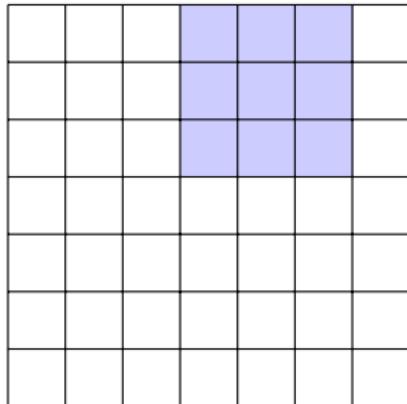
- $7 \times 7 \times D$ input (just display one plane).
- Have $3 \times 3 \times D$ filter.

A closer look at the spatial dimensions



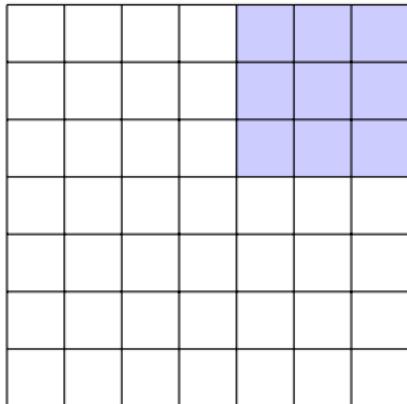
- $7 \times 7 \times D$ input (just display one plane).
- Have $3 \times 3 \times D$ filter.

A closer look at the spatial dimensions



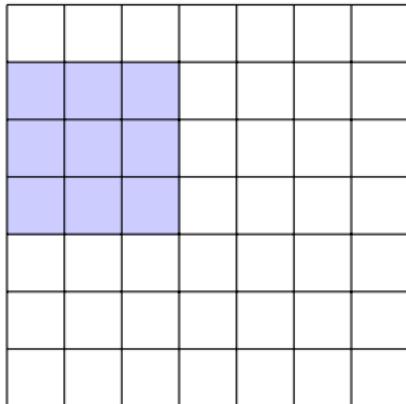
- $7 \times 7 \times D$ input (just display one plane).
- Have $3 \times 3 \times D$ filter.

A closer look at the spatial dimensions



- $7 \times 7 \times D$ input (just display one plane).
- Have $3 \times 3 \times D$ filter.

A closer look at the spatial dimensions

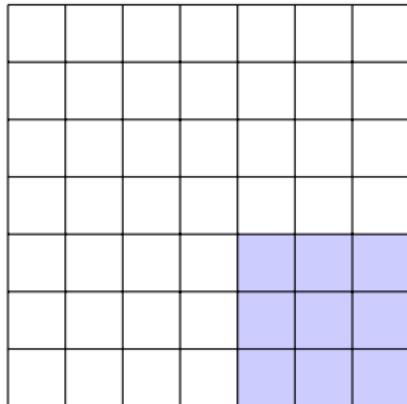


- $7 \times 7 \times D$ input (just display one plane).
- Have $3 \times 3 \times D$ filter.

A closer look at the spatial dimensions

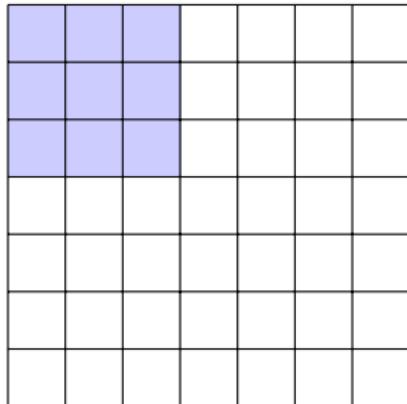
• • •

A closer look at the spatial dimensions



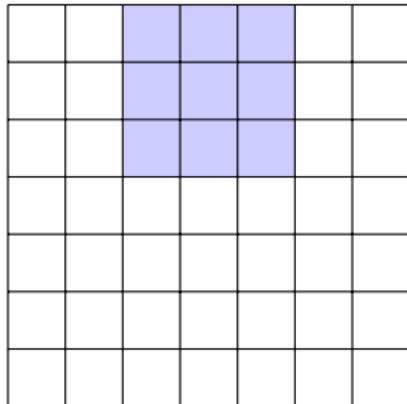
- $7 \times 7 \times D$ input (just display one plane).
- Have $3 \times 3 \times D$ filter.
- $\Rightarrow 5 \times 5$ output.

A closer look at the spatial dimensions



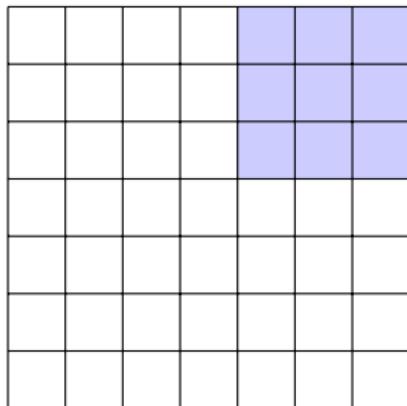
- $7 \times 7 \times D$ input (just display one plane).
- Have $3 \times 3 \times D$ filter.
- Apply with **stride** 2.

A closer look at the spatial dimensions



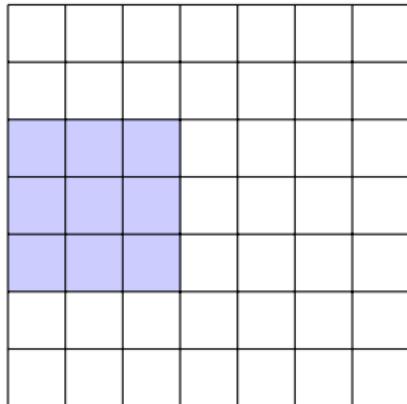
- $7 \times 7 \times D$ input (just display one plane).
- Have $3 \times 3 \times D$ filter.
- Apply with **stride 2**.

A closer look at the spatial dimensions



- $7 \times 7 \times D$ input (just display one plane).
- Have $3 \times 3 \times D$ filter.
- Apply with **stride 2**.

A closer look at the spatial dimensions

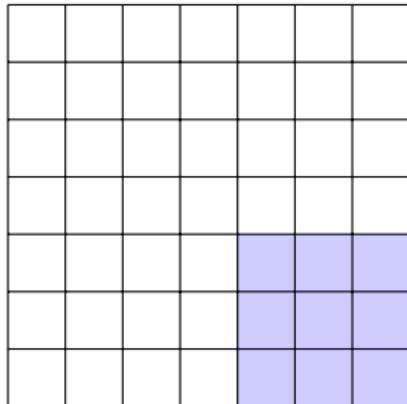


- $7 \times 7 \times D$ input (just display one plane).
- Have $3 \times 3 \times D$ filter.
- Apply with **stride 2**.

A closer look at the spatial dimensions

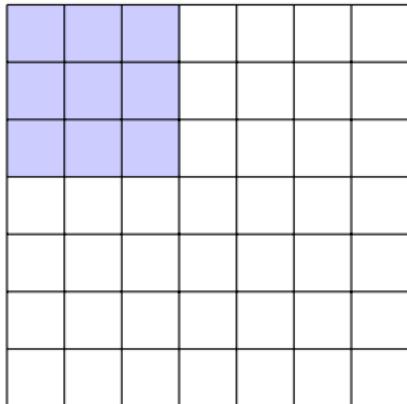
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A closer look at the spatial dimensions



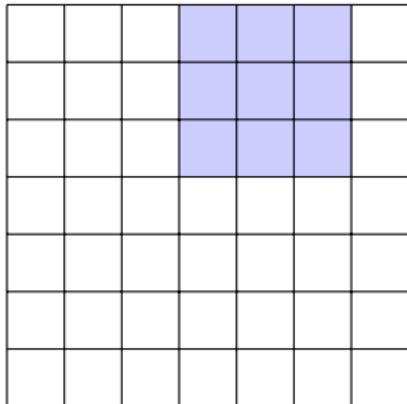
- $7 \times 7 \times D$ input (just display one plane).
- Have $3 \times 3 \times D$ filter.
- Apply with **stride 2**.
- $\Rightarrow 3 \times 3$ output.

A closer look at the spatial dimensions



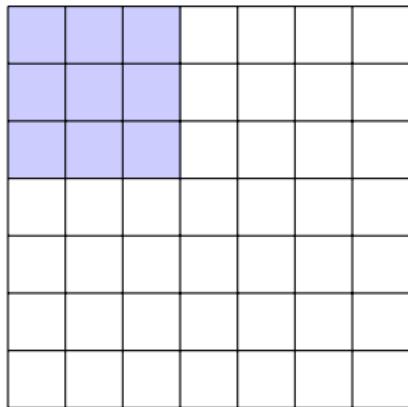
- $7 \times 7 \times D$ input (just display one plane).
- Have $3 \times 3 \times D$ filter.
- Apply with **stride 3**.

A closer look at the spatial dimensions



- $7 \times 7 \times D$ input (just display one plane).
- Have $3 \times 3 \times D$ filter.
- Apply with **stride 3**.
- **Doesn't fit nicely!** Don't include last column and row.

Output volume dimension

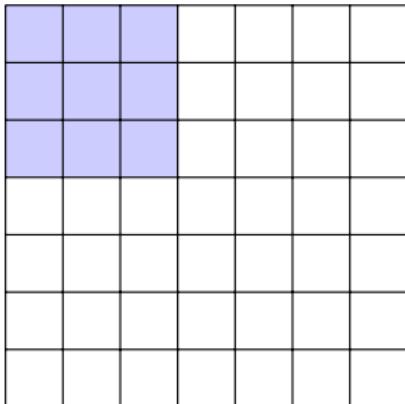


- $w \times h \times D$ input.
- Have $f \times f \times D$ filter.
- Apply with **stride** s .
- **Output dimension:** $w' \times h'$

$$w' = (w - f) / s + 1$$

$$h' = (h - f) / s + 1$$

Output volume dimension



- $w \times h \times D$ input.
- Have $f \times f \times D$ filter.
- Apply with **stride** s .
- **Output dimension:** $w' \times h'$

$$w' = (w - f) / s + 1$$
$$h' = (h - f) / s + 1$$

- **Our example:**
 $w = h = 7, f = 3$

$$s=1 \implies w' = (7 - 3) / 1 + 1 = 5$$

$$s=2 \implies w' = (7 - 3) / 2 + 1 = 3$$

$$s=3 \implies w' = (7 - 3) / 3 + 1 = 2.33$$

In practice: Common to zero pad the border

0	0	0	0	0	0	0	0	0
0								0
0								0
0								0
0								0
0								0
0								0
0								0
0	0	0	0	0	0	0	0	0

- $7 \times 7 \times D$ input.
- Have $3 \times 3 \times D$ filter.
- Apply with **stride** s .
- Pad input with 1 pixel border.
- **Output dimension:** ?
- Remember

$$w' = (w - f) / s + 1$$

$$h' = (h - f) / s + 1$$

In practice: Common to zero pad the border

0	0	0	0	0	0	0	0	0
0								0
0								0
0								0
0								0
0								0
0								0
0								0
0	0	0	0	0	0	0	0	0

- $7 \times 7 \times D$ input.
- Have $3 \times 3 \times D$ filter.
- Apply with **stride** s .
- Pad input with 1 pixel border.
- **Output dimension:** ?
- Remember

$$w' = (w - f) / s + 1$$

$$h' = (h - f) / s + 1$$

In practice: Common to zero pad the border

0	0	0	0	0	0	0	0	0
0								0
0								0
0								0
0								0
0								0
0								0
0								0
0	0	0	0	0	0	0	0	0

- $7 \times 7 \times D$ input.
- Have $3 \times 3 \times D$ filter.
- Apply with **stride** s .
- Pad input with 1 pixel border.
- **Output dimension:** 7×7

In practice: Common to zero pad the border

0	0	0	0	0	0	0	0	0
0								0
0								0
0								0
0								0
0								0
0								0
0								0
0	0	0	0	0	0	0	0	0

- $7 \times 7 \times D$ input.
- Have $3 \times 3 \times D$ filter.
- Apply with **stride** s .
- Pad input with 1 pixel border. ($P = 1$)
- **Output dimension:** 7×7
- In general

$$w' = (w + 2P - f) / s + 1$$

$$h' = (h + 2P - f) / s + 1$$

In practice: Common to zero pad the border

0	0	0	0	0	0	0	0	0
0								0
0								0
0								0
0								0
0								0
0								0
0								0
0	0	0	0	0	0	0	0	0

- $7 \times 7 \times D$ input.
 - Have $3 \times 3 \times D$ filter.
 - Apply with **stride** s .
 - Pad input with 1 pixel border. ($P = 1$)
 - **Output dimension:** 7×7
 - In general, common to have convolutional layers with
 - stride $s = 1$,
 - filters of size $f \times f \times D$,
 - zero-padding $P = (f - 1)/2$
- $\implies w' = w, h' = h$

- **Input volume dimension:** $32 \times 32 \times 3$
- Hyper-parameters of Conv layer:
 - 10 filters of size $5 \times 5 \times 3$
 - Stride: $s = 1$
 - Pad: $P = 2$
- **Output volume dimension:** ?

Example of Dimension Counting

- **Input volume dimension:** $32 \times 32 \times 3$
- Hyper-parameters of Conv layer:
 - 10 filters of size $5 \times 5 \times 3$
 - Stride: $s = 1$
 - Pad: $P = 2$
- **Output volume dimension:** $w' \times h' \times 10$
where

$$w' = (w + 2P - f)/s + 1 = (32 + 2 * 2 - 5)/1 + 1 = 32$$

$$h' = (h + 2P - f)/s + 1 = (32 + 2 * 2 - 5)/1 + 1 = 32$$

Example of Dimension Counting

- **Input volume dimension:** $32 \times 32 \times 3$
- Hyper-parameters of Conv layer:
 - 10 filters of size $5 \times 5 \times 3$
 - Stride $s = 1$
 - Pad $P = 2$
- **# of parameters in this layer:** ?

Example of Dimension Counting

- **Input volume dimension:** $32 \times 32 \times 3$
- Hyper-parameters of Conv layer:
 - 10 filters of size $5 \times 5 \times 3$
 - Stride: $s = 1$
 - Pad: $P = 2$
- **# of parameters in this layer:** 760
 - Each filter has $5 \times 5 \times 3 + 1 = 76$ parameters.
 - There are 10 filters $\implies 76 \times 10$ total parameters.

Summary of dimensions in Convolutional Layer

- **Input:**

Volume, $\mathbf{X}^{(i)} = \{X_1^{(i)}, \dots, X_D^{(i)}\}$, of size $w \times h \times D$

- Requires 4 hyper-parameters:

- Number of filters: n_F
- Spatial size of filters: f
- Stride: s
- Amount of zero padding: P

- **Output:**

Volume $\mathbf{S}^{(i+1)} = \{S_1^{(i+1)}, \dots, S_{n_F}^{(i+1)}\}$ size $w' \times h' \times n_F$ where

- $w' = (w - f + 2P)/s + 1$
- $h' = (h - f + 2P)/s + 1$

where

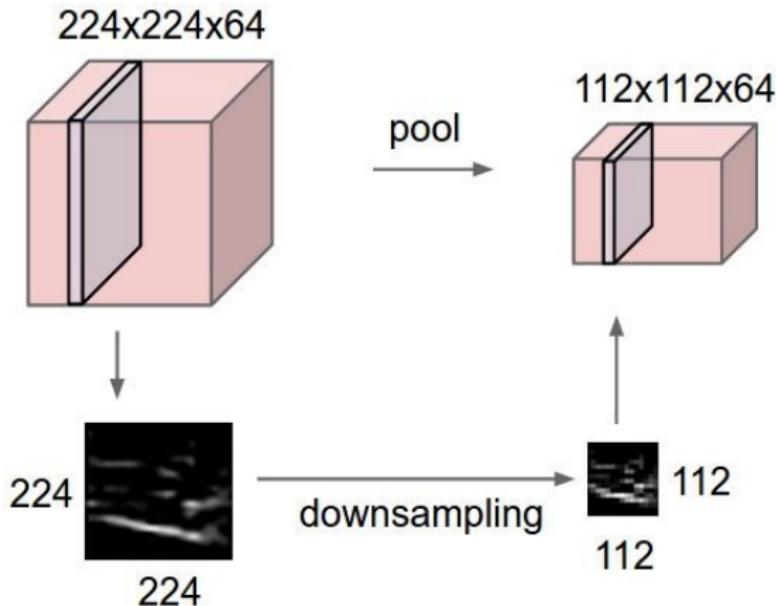
$$S_j^{(i+1)} = \mathbf{X}^{(i)} * \mathbf{F}_j + b_j$$

- $n_F = \text{powers of 2}$ (e.g. 32, 64, 128, 512)
 - $f = 3, s = 1, P = 1$
 - $f = 5, s = 1, P = 2$
 - $f = 5, s = 2, P = ?$ (whatever fits)
 - $f = 1, s = 1, P = 1$

Common Operator in Convolutional Networks: **Pooling Operators**

Pooling layer

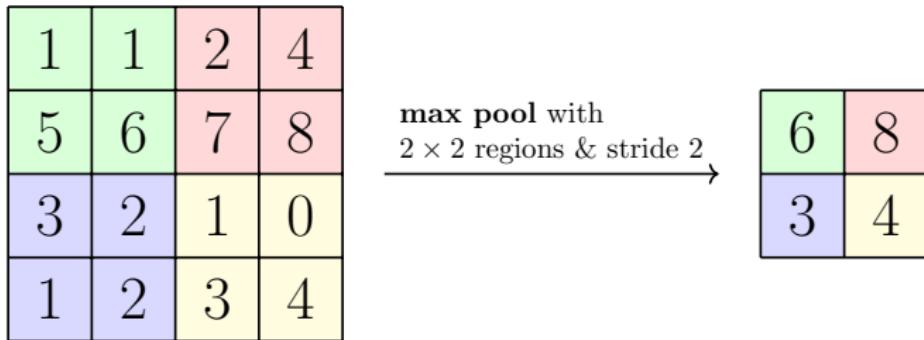
- Make the representation smaller and more manageable
- Operates over each response/activation map independently



Simple Example: Max Pooling one response map

1	1	2	4
5	6	7	8
3	2	1	0
1	2	3	4

max pool with
 2×2 regions & stride 2



6	8
3	4

- Denote the max pooling operation with regions of size $r \times r$ and stride s with

$$\tilde{\mathbf{H}} = \text{MaxPool}(\mathbf{H}, r, s)$$

- If \mathbf{H} has size $w \times h \times D$
 $\implies \tilde{\mathbf{H}}$ has size $(w - r)/s + 1 \times (h - r)/s + 1 \times D$
- Mathematical expression for each entry in $\tilde{\mathbf{H}}$:

$$\tilde{\mathbf{H}}_{ijk} = \max_{\substack{i' \leq l \leq i'+r-1 \\ j' \leq m \leq j'+r-1}} \mathbf{H}_{lmk} \quad \text{where } i' = (i-1)s+1, j' = (j-1)s+1$$

- Common settings $r = 2, s = 2$ or $r = 3, s = 2$.

- Denote the max pooling operation with regions of size $r \times r$ and stride s with

$$\tilde{\mathbf{H}} = \text{MaxPool}(\mathbf{H}, r, s)$$

- If \mathbf{H} has size $w \times h \times D$
 $\implies \tilde{\mathbf{H}}$ has size $(w - r)/s + 1 \times (h - r)/s + 1 \times D$
- Mathematical expression for each entry in $\tilde{\mathbf{H}}$:

$$\tilde{\mathbf{H}}_{ijk} = \max_{\substack{i' \leq l \leq i'+r-1 \\ j' \leq m \leq j'+r-1}} \mathbf{H}_{lmk} \quad \text{where } i' = (i-1)s+1, j' = (j-1)s+1$$

- Common settings $r = 2, s = 2$ or $r = 3, s = 2$.

Jacobian Computations for a Max Pooling layer

- Let

$$\tilde{\mathbf{H}} = \text{MaxPool}(\mathbf{H}, r, r)$$

- For backprop need to calculate:

$$\frac{\partial \text{vec}(\tilde{\mathbf{H}})}{\partial \text{vec}(\mathbf{H})} = ?$$

- Can write MaxPool operation as a matrix operation

$$\text{vec}(\tilde{\mathbf{H}}) = A_{\text{MaxPool}} \text{vec}(\mathbf{H})$$

\implies

$$\frac{\partial \text{vec}(\tilde{\mathbf{H}})}{\partial \text{vec}(\mathbf{H})} = A_{\text{MaxPool}}$$

- What are the entries of A_{MaxPool} ?

Jacobian Computations for a Max Pooling layer

- Let

$$\tilde{\mathbf{H}} = \text{MaxPool}(\mathbf{H}, r, r)$$

- For backprop need to calculate:

$$\frac{\partial \text{vec}(\tilde{\mathbf{H}})}{\partial \text{vec}(\mathbf{H})} = ?$$

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$$\text{vec}(\tilde{\mathbf{H}}) = A_{\text{MaxPool}} \text{vec}(\mathbf{H})$$

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$$\frac{\partial \text{vec}(\tilde{\mathbf{H}})}{\partial \text{vec}(\mathbf{H})} = A_{\text{MaxPool}}$$

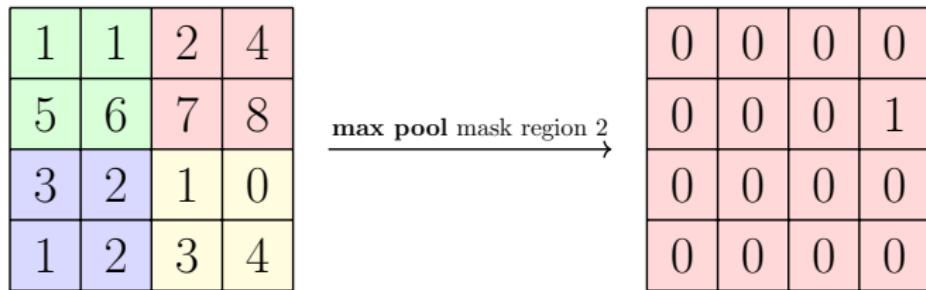
- What are the entries of A_{MaxPool} ?

Simple Example: Max Pooling as a matrix multiplication



$$(\tilde{H}_{11}) = (0 \quad 0 \quad 0 \quad 0 \quad 0 \quad 1 \quad 0 \quad 0) \text{vec}(H)$$

Simple Example: Max Pooling as a matrix multiplication

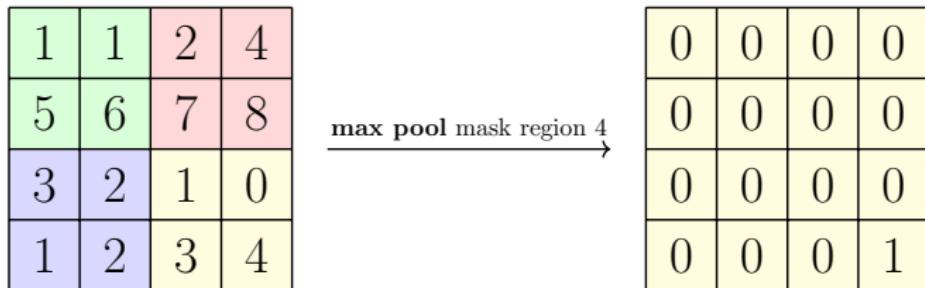


Simple Example: Max Pooling as a matrix multiplication



$$\begin{pmatrix} \tilde{H}_{11} \\ \tilde{H}_{12} \\ \tilde{H}_{21} \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix} \text{vec}(H)$$

Simple Example: Max Pooling as a matrix multiplication



Simple Example: Max Pooling as a matrix multiplication



$$\begin{pmatrix} \tilde{H}_{11} \\ \tilde{H}_{12} \\ \tilde{H}_{21} \\ \tilde{H}_{22} \end{pmatrix} = \underbrace{\begin{pmatrix} 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}}_{A_{\text{MaxPool}} \text{ and has size } 4 \times 16} \text{vec}(H)$$

What is A_{AvgPool} ?

- Say in each region we pool by **averaging** the responses instead of choosing the max.
- What is A_{AvgPool} for our simple example?