

**Question 1. (10 points)**

The spatial average (excluding the center term) is

$$g(x, y) = \frac{1}{4} [f(x, y+1) + f(x+1, y) + f(x-1, y) + f(x, y-1)]$$

From property 3 in Table 4.3,

$$\begin{aligned} G(u, v) &= \frac{1}{4} \left[ e^{\frac{j2\pi v}{N}} + e^{\frac{j2\pi u}{M}} + e^{-\frac{j2\pi u}{M}} + e^{-\frac{j2\pi v}{N}} \right] F(u, v) \\ &= H(u, v) F(u, v) \end{aligned}$$

where

$$H(u, v) = \frac{1}{2} \left[ \cos\left(\frac{2\pi u}{M}\right) + \cos\left(\frac{2\pi v}{N}\right) \right]$$

is the filter transfer function in the frequency domain.

**Question 2. (16 points = 8 points for Part a and 8 points for Part b)**

(a) From Section 2.6, we know that an operator,  $O$ , is linear if  $O(af_1 + bf_2) = aO(f_1) + bO(f_2)$ . From the definition of the Radon transform in Eq. (5.11-3),

$$\begin{aligned} O(af_1 + bf_2) &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (af_1 + bf_2) \delta(x \cos \theta + y \sin \theta - \rho) dx dy \\ &= a \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f_1 \delta(x \cos \theta + y \sin \theta - \rho) dx dy \\ &\quad + b \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f_2 \delta(x \cos \theta + y \sin \theta - \rho) dx dy \\ &= aO(f_1) + bO(f_2) \end{aligned}$$

thus showing that the Radon transform is a linear operation.

(b) Let  $p = x - x_0$  and  $q = y - y_0$ . Then  $dp = dx$  and  $dq = dy$ . From Eq. (5.11-3), the Radon transform of  $f(x - x_0, y - y_0)$  is

$$\begin{aligned} g(\rho, \theta) &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x - x_0, y - y_0) \delta(x \cos \theta + y \sin \theta - \rho) dx dy \\ &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(p, q) \delta[(p + x_0) \cos \theta + (q + y_0) \sin \theta - \rho] dp dq \\ &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(p, q) \delta[p \cos \theta + q \sin \theta - (\rho - x_0 \cos \theta - y_0 \sin \theta)] dp dq \\ &= g(\rho - x_0 \cos \theta - y_0 \sin \theta, \theta). \end{aligned}$$

## Part II: Programming

### Q1 (6 points)

$I_1$  : reconstructed image obtained by inverse Fourier Transform using magnitude  $|F_A|$  of image A and phase  $\Omega(F_B)$  image B.

$I_2$  reconstructed image obtained by inverse Fourier transform using the magnitude  $|F_B|$  of image B and phase  $\Omega(F_A)$  of image A. Among these two images,  $I_2$  is the better reconstruction of the original image  $I_A$ .

If we compare the image  $I_2$  reconstructed by using phase  $\Omega(F_A)$  and magnitude  $|F_B|$  with the image  $I_1$  reconstructed by using phase  $\Omega(F_B)$  and magnitude  $|F_A|$ , we can easily recognize that  $I_2$  will have the structure of original image A while  $I_1$  keeps the structure of image B.

Moreover, for the reconstructed image  $I_2$ , all frequencies with their configurations of image A are still there except the magnitude is bigger or smaller. Of course, there will be some cases that the frequencies are absent since their magnitudes are 0 (corresponding to magnitudes of image B). However, the “locations” of all frequencies are still the same so all objects in image are kept. On the other hand, in case of  $I_1$ , the structure will be changed corresponding to what we have in image B. Therefore, even we keep the magnitude  $|F_A|$ , the change of structural information results in making reconstructed image more different from original image A. As a result,  $I_2$  is the better reconstruction of the original image  $I_A$ .

### Q2 (18 points)

- 1) 4 points
- 2) 4 points
- 3) 4 points
- 4) 6 points: result comparison 4 points, appropriate comments 2 points