

# Computer Animation

## Lab 4 - A1 Forward Kinematics

COMP 477

# Background

What is forward kinematics?

How is it useful?

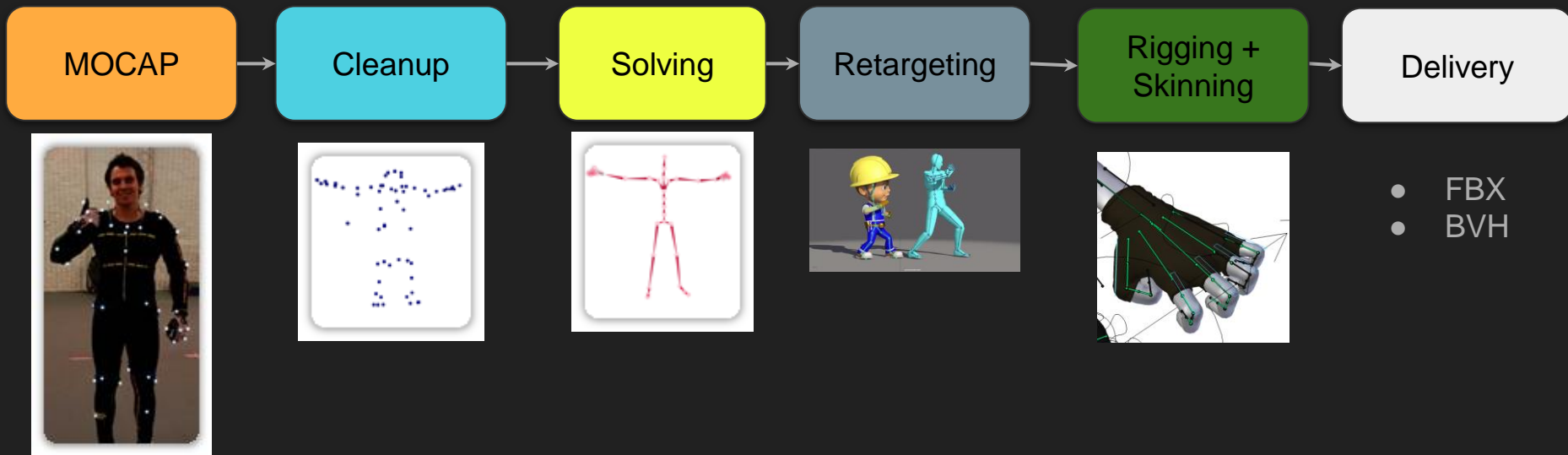
How is it used in games?

*Let's take a look at where it fits in a game pipeline...*

# Game Animation Pipeline

Computer Animation pipelines vary drastically by studio. Typically for a AAA game, the pipeline will resemble the following:

## Preprocessing



# Game Animation Pipeline

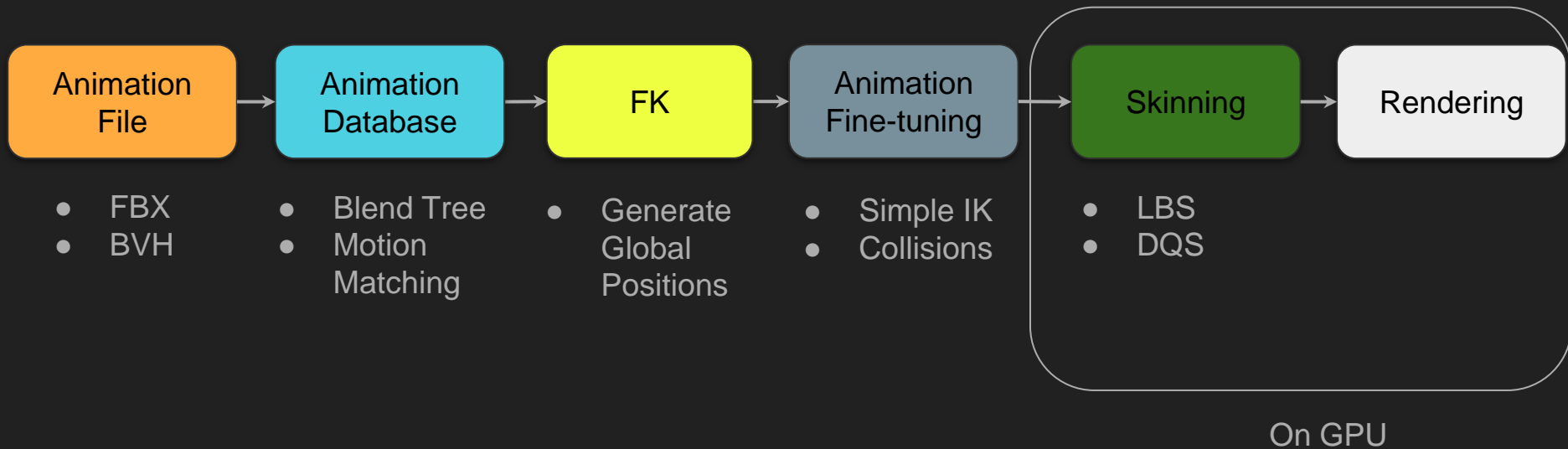
## Delivery

The result of the pipeline is a character animation file stored a standardized format (**FBX**, **BVH**, etc.) Formats vary, but typically we store need the following information:

- **Skeletal Structure:**
  - “At-rest” joint lengths
  - “Pre-rotations”
  - Hierarchical Information (parent indices)
- **Animation Information**
  - Per-frame joint rotations
  - Per-frame joint translations
    - Usually only the root
- **Skinning Information:**
  - Vertex-joint correspondances (*typically max 4 joints per vertex*)
  - Skinning weights

# Game Animation Pipeline

## In-Engine



# Assignment 1: Intro

## Goal:

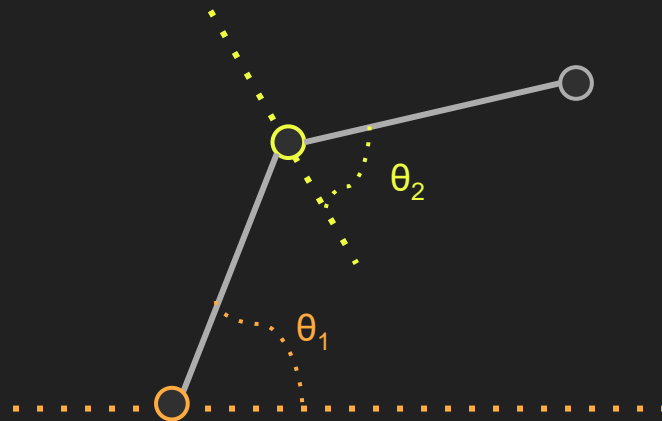
Implement Forward Kinematics

## Instructions:

[https://moodle.concordia.ca/moodle/pluginfile.php/5155229/mod\\_resource/content/0/A1.pdf](https://moodle.concordia.ca/moodle/pluginfile.php/5155229/mod_resource/content/0/A1.pdf)

## Github:

[https://github.com/tiperiu/COMP477\\_A1](https://github.com/tiperiu/COMP477_A1)



# Assignment 1: Implementation

Essentially, you'll need to write an “FK” function, which:

## **Takes in:**

- Local Joint Rotations, Joint Lengths

## **Spits out:**

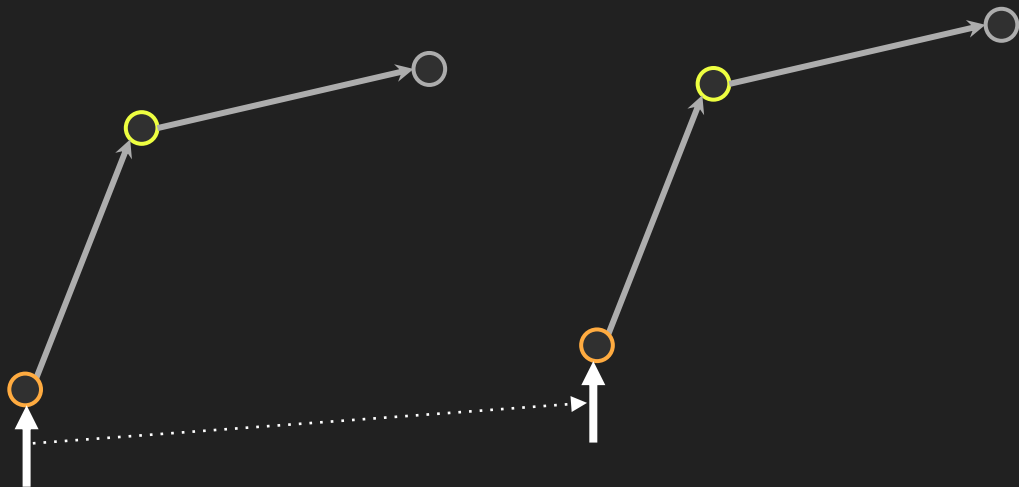
- Global Joint Positions

The course “Forward Kinematics” slides will be useful for this assignment

# Assignment 1: Expected Behavior

Once in “*Showtime*” mode, the user can drag individual joints. Two different behaviors are expected:

If the **root** joint (*joint with no parents*) is dragged, the whole structure moves rigidly as follows:

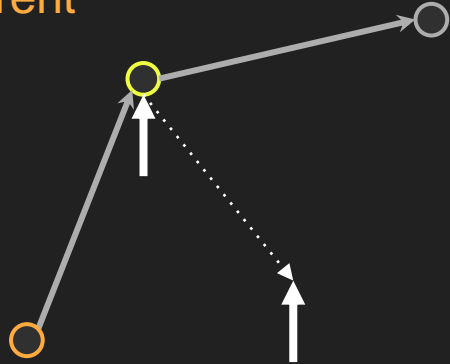




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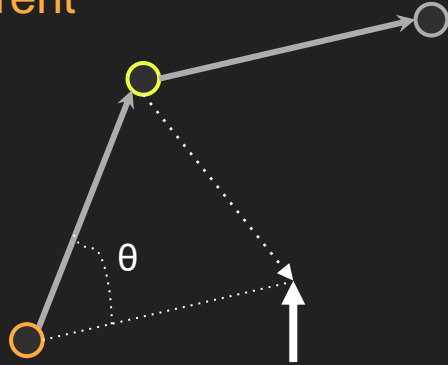
If the any other **joint** is dragged, it, along with all the joints “under” it, rotate around the **joint**’s **parent**



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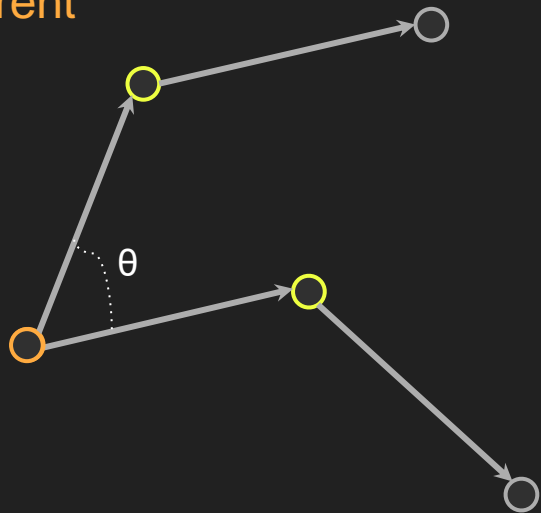
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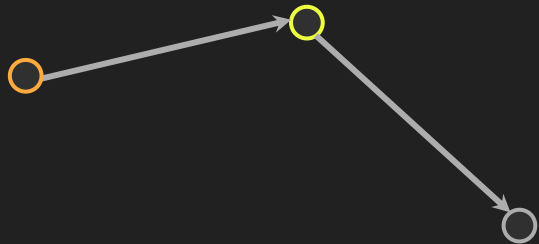
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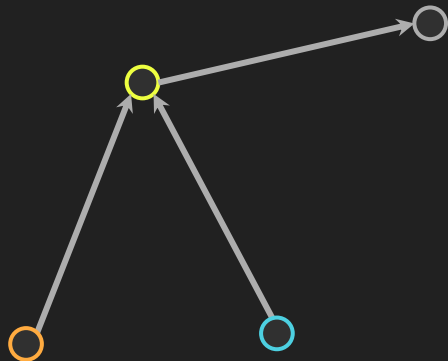
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# Assignment 1: Expected Behavior

Note that you **don't** need to worry about the case where a joint has multiple parents (and subsequently, the case where a hierarchy has multiple roots)



# Further Reading

Useful blog post covering FK in Unity:

<https://www.alanzucconi.com/2017/04/06/implementing-forward-kinematics/>