The Z specification language

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February 1, 2022

Introduction

- ➤ Z (pronounced "zed") is a *specification language* based on predicate logic and set theory.
- ► A formal specification in Z describes *what* the system does, without saying *how* it does it.
- ▶ The formal specification is implementation independent.

Example: Birthday book

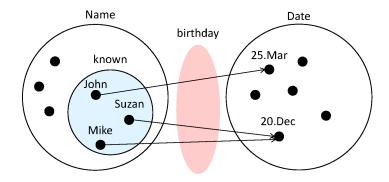
- ▶ In this example we are defining the specification of a birthday book.
- ▶ We introduce the set of all names, and the set of all dates, as basic types in the specification:

```
[Name, Date]
```

One possible state of the system has three people in the set known, with their birthdays recorded by the function birthday:

```
known = \{John, Mike, Suzan\}
birthday = \{ \\ John \mapsto 25.Mar, \\ Mike \mapsto 20.Dec, \\ Suzan \mapsto 20.Dec \}
```

Birthday book /cont. - Function birthday



Birthday book: State schema

- A specification is decomposed into *schemata* (plural for *schema*).
- A Z schema can provide a high-level description of a model.

- ► Variable <u>known</u> is the <u>set of names</u> with birthdates recorded and <u>birthday</u> is a function which, when applied to certain names, gives the birthdays associated with them.
- Note that *birthday* is a <u>partial function</u>: It does not relate every element of *Name* to *Date*.

Schemata /cont.

We define a schema for both the data of the model as well as for each of the system's operations.

```
Name ______
Declaration part (state)

Predicate part
```

- ► A schema consists of
- Name
- ▶ **Declaration part (state)**: specifies a set of variable assignments and their types (called the *state* of the system).
- Predicate part
 - Properties of the model expressed in terms of the variables defined in the declaration part.
 - These properties constitute state invariants (must be true at all times).

Schemata /cont.

Alternatively a schema can be expressed in a linear notation as

name = [declaration part | predicate part]

Decorations: Before and after state

- Decorations give identifiers conventional meanings.
- A variable decorated with the symbol 'denotes its value after having being manipulated by an operation.
- Thus, *known* and *birthday* denote the states of their corresponding sets before an operation is invoked, whereas *known'* and *birthday'* denote the states of their corresponding sets after an operation has been successfully terminated.

A birthday book /cont.

- The predicate *known* = dom *birthday* states that the set *known* is the same as the domain of the function *birthday*, i.e. the set of names that the function can apply.
- ▶ This relationship is an *invariant* of the system.

```
___BirthdayBook
known: P Name
birthday: Name → Date
known = dom birthday
```

A birthday book: State schema

- ▶ In our schema we have managed to capture the information that
- 1 Each person can have only one birthday (because birthday is a function), and
- 2 Two (or more) people can share the same birthday (as in the example).
- ► The invariant *known* = dom *birthday* is satisfied, because *birthday* records a date for exactly the three names in set *known*.

- Once the state space is defined, we must provide a schema for each of the operations of the system.
- Operation AddBirthday adds a new birthday into the system:

```
AddBirthday \_
\Delta Birthday Book
name?: Name
date?: Date
name? \notin known
known' = known \cup \{name?\}
birthday' = birthday \cup \{name? \mapsto date?\}
```

- The declaration $\triangle BirthdayBook$ captures the fact that the schema describes a *state change*: it introduces variables *known*, *birthday*, and *known'*, *birthday'*.
- ► The first is an observation of the state before the change, and the last two are observations of the state after the change.

Next come the declarations of the two inputs to the operation and by convention, the names of inputs end in a question mark.

name? : Name date? : Date

The first line under the dividing line defines the precondition to the operation:

name? ∉ known

- The name to be added must not already be one of those known to the system, as each person can have only one birthday.
- ► The specification can be extended to include error conditions in the case of a precondition failure.

If the precondition is satisfied, the next two lines specify the postcondition to the operation:

```
known' = known \cup \{name?\}
birthday' = birthday \cup \{name? \mapsto date?\}
```

- 1 name? is now a member of the set known.
- 2 The birthday function is extended to map the new name to the given date.

► Operation *FindBirthday* finds the birthday of a person known to the system:

- The declaration $\Xi Birthday Book$ indicates that this is an operation in which the state of the system does not change.
- It makes the following statements redundant:

```
known' = known
birthday' = birthday
```

Operation FindBirthday: Declaring an output

The use of a name ending in an exclamation mark defines an output:

date! : Date

Operation FindBirthday: Precondition and output

The precondition of the operation is that *name*? is one of the names known to the system:

If this is so, then the output date! is the value of the birthday function given argument name?.

```
date! = birthday(name?)
```

A birthday book: Operation Remind

Operation Remind finds which people have a birthday on a given date:

```
Remind Remind EBirthdayBook today?: Date Cards!: \mathbb{P} Name Cards! = \{n: known | birthday(n) = today?\}
```

- This time there is no precondition.
- ► The output *cards*! is defined as the set of all values drawn from the set *known* such that the value of the birthday function at *n* is *today*?.

Initializing the system

➤ To complete the specification, we must state the initial state of the system:

InitBirthdayBook	
BirthdayBook	
$known = \emptyset$	

Handling errors

- ▶ What will happen if the user tries to add a birthday for someone already known to the system? Or if they try to find the birthday of someone not known?
- Our current specification makes no claim about what should happen: The system may ignore incorrect input, or it may break down (among other things).
- In addition to the basic specification, we can describe, separately the errors which might be detected and the desired responses to them.
- We can then use operations to combine the two descriptions into a stronger (robust) specification.

Handling errors /cont.

► We define Report as an enumerated set of values that an output variable *result*! may assume:

```
Report ::= ok | already_known | not_known.
```

► We can now define a schema that specifies that the result should be *ok*.

```
Success

EBirthdayBook
result!: Report

result! = ok
```

▶ We can now combine this description with AddBirthday as

 $AddBirthday \land Success$

Handling errors /cont.

- For each precondition error we must define a schema which describes the conditions under which the error occurs and specifies the appropriate report to be produced.
- ► Schema *AlreadyKnown* specifies that the report *already_known* should be produced when the input *name*? is already a member of *known*:

__AlreadyKnown EBirthdayBook name?: Name result!: Report name? ∈ known result! = already_known

Strengthening the specification: *RAddBirthday*

▶ We can now provide a robust version of AddBirthday:

 $RAddBirthday \triangleq (AddBirthday \land Success) \oplus AlreadyKnown$

- ► This definition introduces a new schema obtained by combining the schemas on the right-hand side.
- ▶ Alternatively, operation *RAddBirthday* could be specified directly by writing a single schema which combines the predicate parts of the three schemas *AddBirthday*, *Success* and *AlreadyKnown*.

Strengthening the specification: RFindBirthday

A robust version of operation *FindBirthday* must be able to report if the input name is not known:

```
NotKnown

≡BirthdayBook

name? : Name

result! : Report

name? ∉ known

result! = not_known
```

► The robust operation either behaves as described by FindBirthday and reports success, or reports that the name was not known:

 $RFindBirthday = (FindBirthday \land Success) \oplus NotKnown$

Strengthening the specification: RRemind

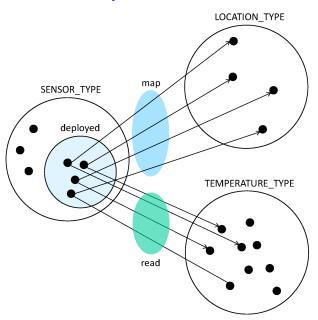
▶ Operation *Remind* never results in an error, so its robust version need only add the reporting of success:

Example: Temperature monitoring

- A system maintains a number of sensors, where each is deployed in a separate location in order to read the location's temperature.
- Before the system is deployed, all locations are marked on a map, and each location will be addressed by a sensor.
- The formal specification of the system introduces the following three types:

SENSOR_TYPE, LOCATION_TYPE, TEMPERATURE_TYPE

Visualization of the system



State schema

TempMonitor ______ deployed : $\mathbb{P} SENSOR_TYPE$

 $map: SENSOR_TYPE \rightarrow LOCATION_TYPE$

read : SENSOR_TYPE → TEMPERATURE_TYPE

deployed = dom mapdeployed = dom read

Operation DeploySensorOK

- Operation DeploySensorOK places a new sensor to a unique location.
- We may assume that some (default) temperature is also passed as an argument.

```
DeploySensorOK _
\Delta TempMonitor
sensor?: SENSOR TYPE
location?: LOCATION TYPE
temperature?: TEMPERATURE_TYPE
sensor? ∉ deployed
location? \notin \operatorname{ran} \mathsf{map}
deployed' = deployed \cup \{sensor?\}
map' = map \cup \{sensor? \mapsto location?\}
read' = read \cup \{sensor? \mapsto temperature?\}
```

Operation ReadTemperatureOK

► Operation ReadTemperatureOK obtains the temperature reading from a sensor, given the sensor's location.

```
ReadTemperatureOK ETempMonitor Iocation?: LOCATION_TYPE temperature!: TEMPERATURE_TYPE Iocation? \in ran map temperature! = read(map^{-1}(location?))
```

Success and error schemata

▶ We introduce an enumerated type *MESSAGE* which will assume values that correspond to success and error messages.

```
Success ______

E TempMonitor

response! : MESSAGE

response! = 'ok'
```

Error schema SensorAlreadyDeployed for DeploySensorOK

- Operation DeploySensorOK places the following precondition: sensor? ∉ deployed
- We provide an error schema for the case where this precondition fails:

```
SensorAlreadyDeployed ______

ETempMonitor

sensor? : SENSOR_TYPE

response! : MESSAGE

sensor? ∈ deployed

response! = 'Sensor deployed'
```

Error schema LocationAlreadyCovered for DeploySensorOK

- Operation DeploySensorOK places the following precondition: location? ∉ ran map
- We provide an error schema for the case where this precondition fails:

```
LocationAlreadyCovered

∃TempMonitor
location?: LOCATION_TYPE
response!: MESSAGE

location? ∈ ran map
response! = 'Location already covered'
```

Error schema LocationUnknown for ReadTemperatureOK

- Operation ReadTemperatureOK places the following precondition: location? ∈ ran map
- We provide an error schema for the case where this precondition fails:

```
__LocationUnknown

ETempMonitor

location?: LOCATION_TYPE

response!: MESSAGE

location? ∉ ran map

response! = 'Location not covered'
```

Defining reliable operations

```
\begin{array}{l} \textit{DeploySensor} \, \hat{=} \\ (\textit{DeploySensorOK} \, \land \, \textit{Success}) \, \oplus \\ (\textit{SensorAlreadyDeployed} \, \lor \, \textit{LocationAlreadyCovered}) \\ \\ \textit{ReadTemperature} \, \hat{=} \\ (\textit{ReadTemperatureOK} \, \land \, \textit{Success}) \, \oplus \, \textit{LocationUnknown} \end{array}
```

Bibliography

- 1. V. S. Alagar and K. Periyasamy, *Specification of Software Systems*, 2nd. ed., Springer, 2011.
- 2. J. Jacky *The Way of Z: Practical Programming with Formal Methods*, Cambridge University Press, 1997.
- 3. J. M. Spivey, *The Z Notation: A Reference Manual*, 2nd. ed., Prentice Hall International (UK) Ltd, 1992.

Appendix A: Operations on sets

Operator	Synopsis	Meaning
€	$x \in S$	set membership
U	$S_1 \cup S_2$	set union
Π	$S_1\cap S_2$	set intersection
\	$S_1 \setminus S_2$	set difference
#	#S	cardinality of a set
⊆	$S_1 \subseteq S_2$	subset
C	$S_1 \subset S_2$	proper subset
=	$S_1 = S_2$	set equality
U	Uss	generalized union of sets SS
\cap	∩ss	generalized intersection of sets SS
\mathbb{P}	\mathbb{P} S	power set of the set S
F	F S	finite subsets of the set S

Appendix B: Notations for functions

Symbol	Meaning
\rightarrow	Total function
-+>	Partial function
\rightarrowtail	Total injective function
>+→	Partial injective function
\longrightarrow	Total surjective function
-+>>	Partial surjective function
> + >>	Partial bijective function
>─	Total bijective function
-11>	Finite partial function
> ->	Finite partial injective function

Appendix C: Operations on relations and functions

Operator	Synopsis	Meaning
\leftrightarrow	$X \leftrightarrow Y$	declaration of a binary relation between X and Y
\mapsto	$x \mapsto y$	maplet
dom	$\mathrm{dom}\;R$	domain of the relation R
ran	ran R	range of the relation R
id	$\operatorname{id} X$	identity relation
9	$R_1 \S R_2$	relational composition
0	$R_1 \circ R_2$	backward relational composition
⊲	$S \lhd R$	domain restriction
\triangleright	$R \rhd S$	range restriction
⊲	$S \triangleleft R$	domain subtraction (domain anti-restriction)
⊳	$R \triangleright S$	range subtraction (range anti-restriction)
~	R∼	relational inverse
_(_)	R (S)	relational image
⊕	$R_1 \oplus R_2$	relational overriding
	\mathbb{R}^k	relational iteration
	R ⁺	transitive closure of the relation R
	R*	reflexive transitive closure of the relation R

Appendix D: Operations on sequences

Operator	Synopsis	Meaning
#	# S	length of the sequence S
$\hat{}$	$S_1 \cap S_2$	concatenation of sequence S_1 with S_2
rev	rev S	reverse of the sequence S
head	head S	first element of the sequence S
last	last S	last element of the sequence S
tail	tail S	sequence S with its first element removed
front	front S	sequence S with its last element removed
^/	^/ SS	distributed concatenation of the sequence of sequences SS
⊆	$S\subseteq T$	S is a sequence forming the prefix of the sequence T
suffix	S suffix T	S is a sequence forming the suffix of the sequence T
in	S in T	S is a segment inside the sequence T
1	U1S	extract the elements from the sequence S corresponding to the index set U; the result is also a sequence, maintaining the same order as in S
1	$S \upharpoonright V$	extract the elements of the set V from the sequence S; the result is also a sequence, maintaining the same order as in S
disjoint	disjoint SeqSet	SeqSet is an indexed family of mutually distinct sets
partitions	SeqSet partitions T	the indexed family of mutually disjoint sets whose distributed union is T