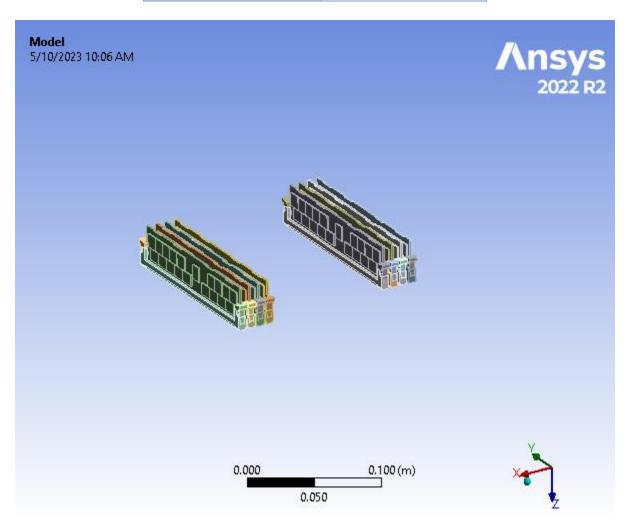


Project*

First Saved	Wednesday, May 10, 2023
Last Saved	Wednesday, May 10, 2023
Product Version	2022 R2
Save Project Before Solution	No
Save Project After Solution	No



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- Units
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- Material Data
 - o AISI 1020 Steel, cold rolled
 - o <u>Aluminum 6061-T6; 6061-T651</u>
 - o Nylon
 - o Glass Epoxy Composite
 - o <u>LCF</u>
 - o Oxygen-free Electronic Copper (OFE), UNS C10100, H00 Temper, flat prod
 - o <u>ABS</u>

Units

Angle	Degrees
Rotational Velocity	rad/s
Temperature	Celsius

Model (A4, B4)

TABLE 2 Model (A4, B4) > Geometry Imports

Object Name | Geometry Imports State Solved

TABLE 3 Model (A4, B4) > Geometry Imports > Geometry Import (A3, B3)

Object	Geometry Import (A3, B3)								
Name	Geometry Import (A5, B5)								
State	Solved								
Definition									
Source	$\verb lem:lem:lem:lem:lem:lem:lem:lem:lem:lem:$								
Type	SpaceClaim								
	Basic Geometry Options								
ameters	Independent								
rameter									
Key									
	Advanced Geometry Options								
compare									
Parts On	No								
Update									
Analysis	3-D								
Type									

Geometry

Object

ength Y

Length Z

TABLE 4 Model (A4, B4) > Geometry

Object Name									
State	Fully Defined								
	Definition								
Source	\\iowa.uiowa.edu\shared\Engineering\Home\makaufman\windowsdata\Desktop\ASSEMBLIES_FINAL\assembly_simplified_10.sq								
Туре	SpaceClaim								
ngth Unit	Meters								
Element Control	Program Controlled								
Display Style									
	Bounding Box								
ength X	0.48082 m								

0.55504 m

4.3696e-002 m

	Properties
Volume	2.1006e-003 m³
Mass	8.377 kg
Scale	4
Factor Value	1.
value	Statistics
Bodies	119
Active	
Bodies	119
Nodes	386311
Elements	193691
sh Metric	None
	Update Options
Assign	
Default	No
Material	
0 " (Basic Geometry Options
Solid Bodies	Yes
Surface	
Bodies	Yes
e Bodies	Yes
rameters	Independent
arameter	
Key	
Attributes	Yes
Attribute	
Key	
Named	Yes
elections	
Named Selection	
Key	
Material	V
roperties	Yes
	Advanced Geometry Options
Use	Yes
ociativity	100
ordinate	Yes
Systems ordinate	
tem Key	
Reader	
Mode	
Saves	No
Updated	
File	
Use	Yes
nstances	

nart CAD Update	
Compare Parts On Update	No
Analysis Type	
Mixed Import esolution	None
Import Facet Quality	Source
Clean odies On Import	No
Stitch Surfaces In Import	None
compose Disjoint eometry	Yes
nclosure and ymmetry ocessing	Yes
i	

Smallest

TABLE 5
Model (A4, B4) > Geometry > Smallest > Parts

	woder (A4, B4) > Geometry > Smallest > Farts										
Object Name	Screw- 1\Screw- 1	Screw- 2\Screw- 2	Screw- 3\Screw- 3	Screw- 4\Screw- 4	Left-Nut- 1\Left- Nut-1	Left- Nut- 2\Left- Nut-2	Left-Nut- 3\Left- Nut-3	Left-Nut- 4\Left- Nut-4	Left- Nut- 5\Left- Nut-5	Left-Nut- 6\Left- Nut-6	Left-Nut- 7\Left- Nut-7
State						Hidden					
				Graph	ics Prope	rties					
Visible						No					
Transparency						1					
	Definition										
Suppressed						No					
Stiffness Behavior						Flexible					
Coordinate System					Default C	oordinate	System				
Reference Temperature					Ву Е	Environme	ent				
Treatment						None					
					Material						
Assignment					AISI 1020	Steel, co	old rolled				
Nonlinear Effects						Yes					

Thermal Strain Effects		Yes										
		Bounding Box										
Length X		1.5875€	e-002 m				3.2	2512e-003	m			
Length Y		6.65486	e-003 m				7.	874e-003	m			
Length Z		6.65486	e-003 m				7.	874e-003	m			
				P	roperties							
Volume		1.6217e	-007 m³				1.0	658e-007	m³			
Mass		1.2763e	-003 kg		8.3878e- 004 kg			8.3877e	e-004 kg			
Centroid X	0.148	94 m	-0.27	984 m			(0.16035 m)			
Centroid Y	0.245	0.24544 m 0.24545 m		-0.18287 m	- 0.12731 m	- 7.1745e- 002 m	- 1.6183e- 002 m	3.938e- 002 m	9.4942e- 002 m	0.1505 m		
Centroid Z	- 1.2777e- 002 m				-7.7017e-005 m -7.7016e-005 m 7.7017e 005 m						7.7017e-	
Moment of Inertia		2.622e-0	09 kg⋅m²	•	7.1033e-009 kg⋅m²							
Moment of Inertia		3.0131e-008 kg·m² 4.1369e-009 kg·m²										
Moment of Inertia		3.0131e-0)08 kg⋅m²				4.13	69e-009 k	g·m²			
				9	Statistics							
Nodes	704	690	6	81	1112	1056	1110	1043	987	1044	1073	
Elements	344	336	3:	29	572	535	573	527	491	523	552	
Mesh Metric						None						
				CAI	D Attribut	es						
PartTolerance:					0.	0000000	1					
Color:98.98.98												
Color:175.168.143												

TABLE 6
Model (A4, B4) > Geometry > Smallest > Parts

model (71) = 1) = oranically = challenger alto											
Object Name	Left-Nut- 8\Left- Nut-8	Left-Nut- 9\Left- Nut-9	Right- Nut- 1\Right- Nut-1	Right- Nut- 2\Right- Nut-2	Right- Nut- 3\Right- Nut-3	Right- Nut- 4\Right- Nut-4	Right- Nut- 5\Right- Nut-5	Right- Nut- 6\Right- Nut-6	Right- Nut- 7\Right- Nut-7	Right- Nut- 8\Right- Nut-8	Right- Nut- 9\Right- Nut-9
State			TVGC 1	rvat 2		Hidden	rvat o	True o	rvat r	rvat o	7441.0
				Graphi	ics Prope	rties					
Visible		No									
Transparency		1									
				D	efinition						
Suppressed						No					
Stiffness Behavior						Flexible					
Coordinate System		Default Coordinate System									
Reference Temperature		By Environment									
Treatment						None					

Material Material											
Assignment		AISI 1020 Steel, cold rolled									
Nonlinear Effects		Yes									
Thermal Strain Effects		Yes									
				Вог	unding Bo	X					
Length X					3.25	512e-003 r	n				
Length Y					7.8	74e-003 m	า				
Length Z					7.8	74e-003 m	1				
				P	roperties						
Volume					1.06	58e-007 n	N ³				
Mass	8.3877€	-004 kg	8.3878e- 004 kg				8.3877e	-004 kg			
Centroid X	0.160)35 m				-0	.29122 m	1			
Centroid Y	0.20607 m	0.26163 m	-0.18287 m	- 0.12731 m	- 7.1745e- 002 m	- 1.6183e- 002 m	3.938e- 002 m	9.4942e- 002 m	0.1505 m	0.20607 m	0.26163 m
Centroid Z	- 7.7016e- 005 m	- 7.7017e- 005 m	- 8.4578e- 005 m				-8.45796	e-005 m			
Moment of Inertia					7.103	3e-009 kg	·m²				
Moment of Inertia					4.136	9e-009 kg	·m²				
Moment of Inertia					4.136	9e-009 kg	·m²				
				5	Statistics						
Nodes	1038	1045	1091	1039	1065	1062	1019	1096	1062	1023	1051
Elements	528	524	556	526	540	544	517	561	542	514	531
Mesh Metric						None					
				CAI	O Attribute						
PartTolerance:					0.0	00000001					
Color:175.168.143											

TABLE 7 Model (A4, B4) > Geometry > Smallest > Parts

Screw2\Screw2	Screw3\Screw3	Screw4\Screw4	Screw5\Screw5	Screw6\Screw6	Screw7\Screw7	Screw8\Screw8	Screw9\Screw9	Sc			
Hidden											
			Graphics	Properties							
No .											
				1							
			Defi	nition							
				No							
				Flexible							
			De	fault Coordinate	System						
				By Environme	nt						

None

Material

			AIS	SI 1020 Steel, co	ld rolled				
				Yes					
				Yes					
			Bound	ling Box					
	1.1379€				9.525e-003				
e-002 m	1.13796	2.20476			7.9248e-003 7.9248e-003				
	1.13796	9-002 III	Pror	perties			7.92466-003	111	
4.934e-007 m ³	5.8374e-007 m³	5.8373e-007 m³	5.8374e-007 m ³			1.5136e-007	m³		
3.8831e-003 kg	4.594e-003 kg	4.5939e-003 kg	4.594e-	-003 kg			1.1912e-003	kg	
-0.298 m	0.167	'13 m	-0.29	98 m		T	0.15538 m	1	
.697 m		-0.233	358 m		-0.18287 m	-0.12731 m	-7.1745e-002 m		
-8.4578e-005 m	-1.5952e-002 m	1.5798e-002 m	-1.596e-002 m	1.579e-002 m	-7.7016	e-005 m	-7.7015e-005 m		
007 kg·m²		2.2852e-(007 kg⋅m²		4.0912e-009 kg·m²	4.0911e-009 kg·m²		4.	
008 kg⋅m²		3.4996e-0	008 kg⋅m²				1.2206e-008 k	g∙m	
007 kg⋅m²		2.2852e-(007 kg⋅m²		1.2206e-008 kg⋅m				
	1000	1011		istics	540	400	540		
143 71	1336 656	1314 644	1326 650	1311 642	518 252	493 234	518 252		
7 1	030	044	630	None	252	234	202		
			CAD A	ttributes					
				0.00000001					
3\Screw13 Screw	v14\Screw14 Scr		(A4, B4) > Geor	6 Screw17\Screv		rew18 Screw19\	Screw19 Screw	2015	
			Cranhias	Hidden Properties					
			Grapines	No					
				1					
			Defi	nition					
				No					
				Flexible					
			De	fault Coordinate	System				
				By Environme	ent				
			N/a	None terial					
				SI 1020 Steel, co	ld rolled				
			7110	Yes					

					Yes					
				Bounding	ј Вох					
					9.525e-00	3 m				
					7.9248e-00)3 m				
					7.9248e-00	03 m				
				Propert	ies					
					1.5136e-00	7 m³				
					1.1912e-00)3 kg				
5538 m		-0.28628 m	0.1553	38 m					-0.2	8628 m
505 m	0.20607 m	-0.18287 m	0.2616	33 m	-0.12731	m -7.	1745e-002	m -1.61	83e-002 m	3.938
6e-005 m		-8.4578e-005 m	-7.7016e	-005 m				-8.45	78e-005 m	1
	4.0912e-009 kg⋅m²					4.09	11e-009 kg	·m²		
				1.	2206e-008	kg·m²				
				1.	2206e-008	kg·m²				
				Statisti	ics					
	510	511	503		514		499		510	5
	24		24		250		237		246	2
					None			<u> </u>		
				CAD Attri						
					0.000000	01				
				TABLE	: a					
		Mode	el (A4, B4)			est > Parts	3			
			PEM-							
							Fastener-			
oject Name	Screw23\Screw23	Screw24\Screw24		2\PEM-	3\PEM-	4\PEM-	5\PEM-	6\PEM-	7\PEM-	8\PEM-
			Fastener- 1	Fastener- 2	Fastener- 3	Fastener- 4	Fastener- 5	Fastener- 6	Fastener- 7	Fastener- 8
State			I		Hidden	1	J	U	/	U
State			Gı	raphics Pr		ı				
Visible			- 01	apinos i II	No					
ansparency					1					
				Definiti						
uppressed				20.11116	No					
s Behavior					Flexible					
Coordinate				D-(
System				Defau	It Coordina	ite System				
Reference				ı	By Environi	mant				
emperature						IIICIII				
Treatment					None					
				Materi	al					
Assignment	AISI 1020 Ste	eel, cold rolled			Alum	ninum 6061	-T6; 6061-7	Γ651		
	1									

ear Effects					Yes						,
rmal Strain Effects					Yes						
				Bounding	Вох						
Length X	9.525e-	-003 m	7.3324e- 003 m		7	.3323e-003	m		7.3324e- 003 m	7.3323e- 003 m	7
Length Y	7.9248e	e-003 m				6.35e-	003 m				7
Length Z	7.9248e	e-003 m				4.74986	e-003 m				9
				Propert	ies						
Volume	1.5136e	-007 m³				8.8258e	-008 m³				1
Mass	1.1912e	-003 kg				2.383e-	-004 kg				1
Centroid X	-0.286	628 m	-0.15686 m	6.1601e- 004 m		0.12508 m		6.1601e- 004 m	-0.15686 m	6.6656e- 002 m	C
Centroid Y	0.20607 m	0.26163 m	4.6568e- 002 m	0.228	318 m	8.4788e- 004 m	7.3238e- 002 m	8.47886	e-004 m	7.3238e- 002 m	8
Centroid Z	-8.45786	e-005 m				1.9415	e-002 m				1
nt of Inertia Ip1	4.0912e-0	009 kg·m²				1.0709e-0	009 kg⋅m²				9
nt of Inertia lp2	1.2206e-0	008 kg⋅m²				1.0709e-0)09 kg⋅m²				9
nt of Inertia Ip3	1.2206e-0	008 kg⋅m²				1.1596e-0)09 kg⋅m²				5
				Statisti							
Nodes	490	510	491	466	529	503	479	451	483	478	
Elements	233	246	227	208	250	229	212	199	2	15	
lesh Metric				CAD Attail	None						
Tolerance:				CAD Attri	0.000000	201					
14.214.214					0.000000	JU I					
43.143.175											
43.164.175											

TABLE 10 Model (A4, B4) > Geometry > Smallest > Parts

Object Name	Screw- 2\Screw- 2	Screw- 3\Screw- 3	Screw- 4\Screw- 4	Screw- 5\Screw- 5	Screw- 6\Screw- 6	Screw- 7\Screw- 7	Screw- 8\Screw- 8	Screw- 9\Screw- 9	Nut- 1\Nut-1	Standoff- 1\Standoff- 1		
State		Hidden										
				Graphics	Propertie	es						
Visible						No						
Transparency						1						

		Definition												
Suppressed						No								
Stiffness Behavior					Fle	exible								
Coordinate				ъ.	. f = It O =		-1							
System				De	etault Cool	dinate Sy	stem							
Reference					ъ г.									
Temperature					By Env	rironment								
Treatment					N	one								
				Ma	terial									
Assignment				AISI 102	0 Steel, co	old rolled				Aluminum 6061-T6; 6061-T651				
Nonlinear Effects					`	es es								
Thermal Strain					,	/								
Effects		Yes												
		Bounding Box												
Length X		7.9756e-003 m 7.0866e- 6.8162e- 6.3498e-												
Longuix		003 m 003 m 003 m												
Length Y		7.9756e-003 m 7.0866e- 7.2982e- 7.3321e-												
		003 m 003 m 003 m												
Length Z		9.2456e-003 m 9.4742e- 3.0226e- 003 m 003 m												
<u> </u>		003 m 003 m 003 m												
				Proj	perties			0.0500	0.500	7.0050				
Volume			1.4	187e-007	m³			9.9522e- 008 m ³	6.596e- 008 m ³	7.9856e-				
										008 m ³				
Mass			1.1	165e-003	kg			7.8324e- 004 kg	5.191e- 004 kg	2.1561e- 004 kg				
	6.1601e-	-0.15686	6 66560	-0.15686			6.1601e-	004 Kg	004 kg	004 Kg				
Centroid X	004 m	m	0.0050e-	m	0.125	508 m	004 m		-0.15686	m				
_	8.4788e-	4.6568e-	7.3238e-	8.4788e-	7.3238e-		1							
Centroid Y	004 m	002 m	002 m	004 m	002 m	0.228	318 m		0.20532	m				
0	1.5731e-	1.5831e-	1.5731e-	1.5831e-				1.7521e-	1.8458e-	1.3605e-				
Centroid Z	002 m	002 m	002 m	002 m	1.5	5731e-002	m	002 m	002 m	002 m				
Moment of Inertia								7.2928e-	2.2327e-	0.50075				
			9.53	67e-009 k	g·m²			009	009	9.5297e-				
lp1								kg·m²	kg·m²	010 kg·m²				
Moment of Inertia								7.2928e-	2.2328e-	9.5296e-				
lp2			9.53	67e-009 k	g·m²			009	009	010 kg·m²				
.,-2								kg·m²	kg·m²	o rong m				
Moment of Inertia			- 40					1.8303e-	3.8088e-	1.5463e-				
lp3			5.19	06e-009 k	g·m²			009	009	009 kg·m²				
·				04-	4:-4:			kg∙m²	kg∙m²					
Nodes	953	964	950	915	tistics 943	971	987	432	2206	397				
Elements Mach Matria	477	481	469	451	469	490	498	203	1160	187				
Mesh Metric		None												
DowtTalassa	CAD Attributes 0.00000001													
PartTolerance:					0.000	JUUUU1								
Color:143.164.175														
Color:175.168.143														
Color:168.175.143														

Small

TABLE 11
Model (A4, B4) > Geometry > Small > Parts

	Model (A4, B4) > Geometry > Small > Parts										
Object Name	DIMM- Slot- 1\Clip- 1a	DIMM- Slot- 1\Clip- 1b	DIMM- Slot- 1\Slot-1	DIMM- Slot- 2\Clip- 2a	DIMM- Slot- 2\Clip- 2b	DIMM- Slot- 2\Slot-2	DIMM- Slot- 3\Clip- 3a	DIMM- Slot- 3\Clip- 3b	DIMM- Slot- 3\Slot-3	DIMM- Slot- 4\Clip- 4a	DIMM- Slot- 4\Clip- 4b
State						Meshed					
				Graph	nics Prop	erties					
Visible				•	•	Yes					
Transparency						1					
				I	Definition	1					
Suppressed						No					
Stiffness Behavior						Flexible					
Coordinate System					Default (Coordinate	System				
Reference Temperature					Ву	Environm	ent				
Treatment						None					
					Material						
Assignment		LCP Vas									
Nonlinear Effects		Yes									
Thermal Strain Effects		Yes									
	1			Во	unding E						
Length X					(6.3e-003 n	<u>n</u>		I		
Length Y	7.525e	-003 m	0.14096 m	7.525e	-003 m	0.14096 m	7.525e-	-003 m	0.14096 m	7.525e-	-003 m
Length Z	2.005e	-002 m	1.53e- 002 m	1.53e- 002 m 2.005e-002 m 1.53e 002 r			2.005e	-002 m	1.53e- 002 m	2.005e	-002 m
				F	Properties	s					
Volume	4.2684e	-007 m³	4.761e- 006 m³	4.2684e	-007 m³	4.761e- 006 m ³	4.2684e	-007 m³	4.761e- 006 m ³		
Mass	7.5124e	-004 kg	8.3794e- 003 kg	7.5124e	-004 kg	8.3794e- 003 kg	7.5124e	-004 kg	8.3794e- 003 kg	7.5124e	-004 kg
Centroid X	-1.00236	e-002 m	- 1.0022e- 002 m	-1.78976	e-002 m	- 1.7896e- 002 m	-2.57716	e-002 m	-2.577e- 002 m	-3.36456	e-002 m
Centroid Y	5.0028e- 002 m	0.18667 m	0.11834 m	5.0028e- 002 m	0.18667 m	0.11834 m	5.0028e- 002 m	0.18667 m	0.11834 m	5.0028e- 002 m	0.18667 m
Centroid Z	2.1936	e-003 m	1.1534e- 002 m	2.1936e	e-003 m	1.1534e- 002 m	2.1936e	-003 m	1.1534e- 002 m	2.1936e	-003 m
Moment of Inertia	2.3543 kg-		1.6709e- 005 kg·m²	2.3543e-008 kg·m²		1.6709e- 005 kg·m²	2.3543 kg·		1.6709e- 005 kg·m²	2.3543 kg·	
Moment of Inertia lp2	2.3293 kg-		9.6647e- 008 kg·m²	2.3293e-008 9.			2.3293 kg·		9.6647e- 008 kg·m²	2.3293e-008 kg·m²	

Moment of Inertia	3.6451 kg·		1.6672e- 005 kg·m²	3.6451 kg·		1.6672e- 005 kg·m²	3.6451 kg·		1.6672e- 005 kg·m²	3.6451e-009 kg·m²		
	Statistics											
Nodes	2200	2256	3328	2221	2263	3328	2190	2187	3328	2178	2173	
Elements	1144											
Mesh Metric						None						
				CAI	D Attribu	ites						
PartTolerance:					(0.0000000	1					
Color:143.143.175												
Color:143.145.175												

TABLE 12 Model (A4, B4) > Geometry > Small > Parts

Object Name	DIMM- Slot- 4\Slot-4	DIMM- Slot- 5\Clip- 5a	DIMM- Slot- 5\Clip- 5b	DIMM- Slot- 5\Slot-5	DIMM- Slot- 6\Clip- 6a	DIMM- Slot- 6\Clip- 6b	DIMM- Slot- 6\Slot-6	DIMM- Slot- 7\Clip- 7a	DIMM- Slot- 7\Clip- 7b	DIMM- Slot- 7\Slot-7	DIMM- Slot- 8\Clip- 8a		
State						Meshed							
				Graph	ics Prop								
Visible						Yes							
Transparency		1 Definition											
		Definition											
Suppressed		No											
Stiffness Behavior		Flexible											
Coordinate System		Default Coordinate System											
Reference Temperature		By Environment											
Treatment						None							
					Material								
Assignment						LCP							
Nonlinear Effects						Yes							
Thermal Strain Effects						Yes							
				Во	unding E	ox							
Length X					(6.3e-003	m						
Length Y	0.14096 m	7.525e	-003 m	0.14096 m	7.525e	-003 m	0.14096 m	7.525e	-003 m	0.14096 m	7.525e- 003 m		
Length Z	1.53e- 002 m	2.005e	-002 m	1.53e- 002 m	2.005e	-002 m	1.53e- 002 m	2.005e	-002 m	1.53e- 002 m	2.005e- 002 m		
				Р	ropertie	S							
Volume	4.761e- 006 m ³	.761e- 4.2684e 007 m ³ 4.761e- 4.2684e 007 m ³ 4.761e- 4.2684e 007 m ³ 4.761e- 4.2684e											
Mass	8.3794e- 003 kg	/ 61:246 OO/4 kg											
Centroid X	- 3.3644e- 002 m	-0.16148 3644e0.13786 m -0.14573 m -0.15361 m											

Centroid Y	0.11834	5.638e-	0.19302	0.12469	5.638e-	0.19302	0.12469	5.638e-	0.19302	0.12469	0.19302
Centrola	m	002 m	m	m	002 m	m	m	002 m	m	m	m
Centroid Z	1.1534e- 002 m	2.1936	e-003 m	1.1534e- 002 m	2.1936	e-003 m	1.1534e- 002 m	2.1936	e-003 m	1.1534e- 002 m	2.1936e- 003 m
Moment of Inertia	1.6709e- 005 kg·m²		3e-008 ·m²	1.6709e- 005 kg·m²		3e-008 ·m²	1.6709e- 005 kg·m²		3e-008 ·m²	1.6709e- 005 kg·m²	2.3543e- 008 kg·m²
Moment of Inertia	9.6647e- 008 kg·m²		3e-008 ·m²	9.6647e- 008 kg·m²		3e-008 ·m²	9.6647e- 008 kg·m²		3e-008 ·m²	9.6647e- 008 kg·m²	2.3293e- 008 kg·m²
Moment of Inertia	1.6672e- 005 kg·m²		1e-009 ·m²	1.6672e- 005 kg·m²		1e-009 ·m²	1.6672e- 005 kg·m²		1e-009 ·m²	1.6672e- 005 kg·m²	3.6451e- 009 kg·m²
				,	Statistics	3					
Nodes	3328	2197	2202	3333	2237	2226	3332	2209	2243	3332	2213
Elements	1618	1122	1131	1620	1156	1149	1619	1140	1160	1619	1150
Mesh Metric						None					
		CAD Attributes									
PartTolerance:		0.0000001									
Color:143.145.175											
Color:143.143.175											

TABLE 13 Model (A4, B4) > Geometry > Small > Parts

Object Name DIMM- Slot- Slot-	DIMM- Stick- 8\Stick- 8									
Graphics Properties Visible Yes Transparency 1 Definition										
Visible Yes Transparency 1 Definition										
Transparency 1 Definition										
Definition										
Suppressed	Definition									
• •										
Stiffness Behavior Flexible	Flexible									
Coordinate System Default Coordinate System										
Reference By Environment										
Treatment										
Material Material										
Assignment LCP Glass Epoxy Composite										
Nonlinear Effects Yes										
Thermal Strain Effects Yes										
Bounding Box										
Length X 6.3e-003 m 3.3782e-003 m	6.3e-003 m 3.3782e-003 m									
Length Y 7.525e- 003 m m 0.13322 m										
Length Z 2.005e- 002 m 002 m 3.1179e-002 m										

Properties											
Volume	4.2684e- 007 m ³	4.761e- 006 m³				9.4439e-	006 m³				
Mass	7.5124e- 004 kg	8.3794e- 003 kg				6.894e-0)02 kg				
Centroid X	-0.16	148 m	- 1.0162e- 002 m	- 1.8036e- 002 m	- 2.591e- 002 m	- 3.3784e- 002 m	- 0.13818 m	- 0.14605 m	- 0.15392 m	- 0.1618 m	
Centroid Y	5.638e- 002 m	0.12469 m		0.117	59 m			0.123	94 m		
Centroid Z	2.1936e- 003 m	1.1534e- 002 m				-2.7043e	-003 m				
Moment of Inertia	2.3543e- 008 kg·m²	1.6709e- 005 kg·m²	1.0662e-004 kg⋅m²								
Moment of Inertia	2.3293e- 008 kg·m²	9.6647e- 008 kg·m²			4	4.1638e-00	06 kg⋅m²				
Moment of Inertia	3.6451e- 009 kg·m²	1.6672e- 005 kg·m²				1.0255e-00	04 kg⋅m²				
				Statist	ics						
Nodes	2272	3332	24427	24486	24220	24251	24247	24423	24274	24354	
Elements	1181	1619	12610	12684	12455	12473	12476	12624	12492	12554	
Mesh Metric					Nor	ne					
			CAD Attributes								
PartTolerance:					0.0000	0001					
Color:143.143.175											
Color:143.145.175											
Color:161.161.161											

Medium

Left-

TABLE 14 Model (A4, B4) > Geometry > Medium > Parts Left-

Right-

ıme	Front- Plate\Front- Plate	Left- Plate- Inner\Left- Plate- Inner	Right- Plate- Inner\Right- Plate-Inner	Back- Plate\Back- Plate		Ear\Left-	Ear_Rear\Right-		Left- Guidebar\Left- Guidebar	Right- Guidebar∖Ri Guidebal			
tate						Hidde	n						
					Graphics P	roperties							
ible	No												
ncy	1												
					Defini	ition							
sed						No							
vior						Flexib	le						
ate					Defa	ult Coordin	ata Svetam						
tem		Default Coordinate System											
nce	By Environment												
ure	by Environment												

ent	None Material											
			. To ooo: T	-								
ent	Alur	mınum 6061	1-T6; 6061-T6	651	A		eel, cold rolled		Ny	/lon		
ects						Yes						
rain ects						Yes						
					Boundir	ng Box						
h X	0.4252 m	9.144€	e-003 m	0.48082 m	1.7882e-002 m	1.651e- 002 m	1.7882e-002 m	1.651e- 002 m	6.35e	-003 m		
hΥ	1.27e-002 m	0.48	326 m	9.525e-003 m	0.4916 m	0.49721 m	0.4916 m	0.49721 m	0.46	699 m		
th Z	4.3307e- 002 m	4.3688	e-002 m	4.3307e- 002 m		4.3688	e-002 m		1.1684	e-002 m		
					Prope	rties						
ıme	005 m ³ 004 m ³ 005 m ³ m ³ 005 m ³ 005 m ³											
ass	0.13438 kg 0.40199 kg 0.4018 kg 0.22381 kg 0.50963 kg 0.4126 kg 0.50963 kg 0.4126 kg 3.2089e											
d X	-4.775e- 002 m	0.15149 m	-0.28239 m	-6.5449e- 002 m	0.16474 m	0.15954 m	-0.29561 m	-0.29042 m	0.15427 m	-0.28517 ו		
d Y	0.2476 m	1.2658e- 002 m	1.2625e- 002 m	-0.23384 m	7.3426e-002 m	2.1425e- 002 m	7.3426e-002 m	2.1425e- 002 m	3.938	e-002 m		
id Z	1.1534e- 003 m	-7.4915e- 005 m	-7.0092e- 005 m	4.7337e- 005 m	-7.6983e-005 m	-7.7017e- 005 m	-8.4613e-005 m	-8.4579e- 005 m	-7.7016e-005 m	-8.4579e-0 m		
ertia Ip1	3.4683e- 005 kg·m²	7.7884e- 003 kg·m²	7.7855e- 003 kg·m²	4.8203e- 005 kg·m²	1.0799e-002 kg·m²	8.4792e- 003 kg·m²	1.0799e-002 kg·m²	8.4792e- 003 kg·m²	5.8192e-	004 kg⋅m²		
ertia Ip2	2.4242e- 003 kg·m²	7.7224e- 003 kg·m²	7.7196e- 003 kg·m²	5.2268e- 003 kg·m²	8.5857e-005 kg·m²	9.2028e- 005 kg·m²	8.5857e-005 kg·m²	9.2028e- 005 kg·m²	3.8703e-007 kg·m²	3.8704e-00 kg·m²		
ertia Ip3	2.3933e- 003 kg·m²	7.1982e- 005 kg·m²	7.1958e- 005 kg·m²	5.2717e- 003 kg·m²	1.072e-002 kg⋅m²	8.3912e- 003 kg·m²	1.072e-002 kg⋅m²	8.3912e- 003 kg·m²	5.8175e-	004 kg⋅m²		
					Statis							
des	4944	13423	14018	6096	4191	5282	4128	5258	3944	3923		
ents	2297	7471	7857	2828	1891	2274	1858	2257	1804	1790		
etric						None	9					
					CAD Att		201					
nce:						0.00000	001					
175												
199 143												
143												

TABLE 15 Model (A4, B4) > Geometry > Medium > Parts

mousi (71), 21) > Comon y > mountain > 1 and									
	PCI-	PCI-	PCI-	PCI-	PCI-	PCI-			
Object Name	Slots\PCI-	Slots\PCI-	Slots\PCI-	Slots\PCI-	Slots\PCI-	Slots\PCI-	Base\Base		
	2	3	4	5	6	7			
State		Hidden							
Graphics Properties									

Visible										
Transparency		1								
Transparoney		Definition								
Suppressed		No								
Stiffness Behavior		Flexible								
Coordinate			Defe	ult Coordinat	o Cuatam					
System			Delac	ılt Coordinat	e System					
Reference				By Environn	nent					
Temperature										
Treatment			Materi	None						
Assignment		LCP								
Nonlinear Effects				Yes						
Thermal Strain Effects		Yes								
	Bounding Box									
Length X	7.5e-0	003 m		7.4e-003 m			7.9e-002 m			
Length Y	5.59996	e-002 m	8.9e-002 m	5.5999e- 002 m	8.9e-002 m	5.5999e- 002 m	0.10214 m			
Length Z	1.108e-002 m					9.185e-003 m				
	Properties									
Volume	4.6535e	-006 m³	7.2973e- 006 m ³	4.5915e- 006 m ³	7.2973e- 006 m ³	4.5915e- 006 m ³	7.4113e-005 m ³			
Mass	8.1902	e-003 kg	1.2843e- 002 kg	8.081e- 003 kg	1.2843e- 002 kg	8.081e- 003 kg	0.12255 kg			
Centroid X	0.10065 m	8.0327e- 002 m	6.0006e- 002 m	3.9681e- 002 m	1.9366e- 002 m	-9.5399e- 004 m	-8.5753e-002 m			
Centroid Y		'89 m	0.15139 m	0.16789 m	0.15139 m	0.16789 m	0.10549 m			
Centroid Z			ı	e-003 m			1.0693e-002 m			
Moment of Inertia	2 22446 (006 kg·m²	8.609e-	2.1945e-	8.609e-	2.1945e-	1.074e-004			
lp1	Z.ZZ41 0 -0	Juo ky·III-	006 kg⋅m²	_	006 kg⋅m²	006 kg⋅m²	kg∙m²			
Moment of Inertia	1.2218e-0	007 kg·m²	1.9e-007	1.1955e-	1.9e-007	1.1955e-	6.4595e-005			
Ip2 Moment of Inertia			kg·m² 8.5362e-	007 kg·m² 2.1487e-	kg·m² 8.5362e-	007 kg·m² 2.1487e-	kg·m² 1.7027e-004			
Ip3	2.1787e-0	006 kg⋅m²	0.5502e- 006 kg·m²		0.5502e-	006 kg·m²	kg·m²			
			Statist				<u> </u>			
Nodes	12	27	184	127	184	127	714			
Elements	1	2	18	12	18	12	88			
Mesh Metric				None						
			CAD Attri							
PartTolerance:				0.0000000	01					
Color:143.175.143										

TABLE 16 Model (A4, B4) > Geometry > Big > Parts

Model (A4, B4) > Geometry > Big > Parts								
Object Name	Board\Board	Sink\Sink	PSK\Solid1					
State		Hidden						
		Graphics Properties						
Visible		No						
Transparency		1						
		Definition						
Suppressed		No						
Stiffness Behavior		Flexible						
Coordinate System		Default Coordinate System						
Reference		·						
Temperature		By Environment						
Treatment		None						
		Material						
Assignment	Glass Epoxy Composite	Oxygen-free Electronic Copper (OFE), UNS C10100, H00 Temper, flat prod	ABS					
Nonlinear Effects	•	Yes						
Thermal Strain Effects Yes								
		Bounding Box						
Length X	0.30734 m	7.9e-002 m	0.10096 m					
Length Y		0.254 m 0.10214 m						
Length Z	1.6e-003 m 2.4698e-002 m		0.2222 m 3.847e-002 m					
	1100 000 111	Properties	0.0110 002 111					
Volume	1.2466e-004 m³	1.678e-004 m³	5.2225e-004 m³					
Mass	0.91003 kg	0.27745 kg	0.67892 kg					
Centroid X	-1.201e-002 m	-8.5753e-002 m	-0.23166 m					
Centroid Y	0.11111 m	0.10549 m	0.10571 m					
Centroid Z	1.6085e-002 m	-6.2487e-003 m	1.2126e-004 m					
Moment of Inertia Ip1	4.8752e-003 kg·m²	2.0414e-004 kg·m²	2.4675e-003 kg·m²					
Moment of Inertia Ip2	7.1721e-003 kg·m²	1.3733e-004 kg⋅m²	4.7089e-004 kg·m²					
Moment of Inertia Ip3	1.2047e-002 kg·m²	3.1326e-004 kg·m²	2.8016e-003 kg·m²					
	Ţ.	Statistics	Ü					
Nodes	2807	379	3149					
Elements	1307							
Mesh Metric		None	1550					
		CAD Attributes						
PartTolerance:		0.0000001						
Color:143.143.175								
Color:143.175.143								
20.0 10111 017 10								

TABLE 17
Model (A4, B4) > Geometry > Biggest > Parts

Model (A4, B4) > Geometry > Biggest > Parts							
Object Name	Plate\Plate						
State	Hidden						
Graphics	s Properties						
Visible	No						
Transparency	1						
Def	inition						
Suppressed	No						
Stiffness Behavior	Flexible						
Coordinate System	Default Coordinate System						
Reference Temperature	By Environment						
Treatment	None						
Ma	aterial						
Assignment	AISI 1020 Steel, cold rolled						
Nonlinear Effects	Yes						
Thermal Strain Effects	Yes						
Boun	ding Box						
Length X	0.43713 m						
Length Y	0.48971 m						
Length Z	1.5189e-003 m						
Pro	perties						
Volume	3.2278e-004 m³						
Mass	2.5403 kg						
Centroid X	-6.5508e-002 m						
Centroid Y	6.888e-003 m						
Centroid Z	2.0875e-002 m						
Moment of Inertia lp1	5.0134e-002 kg·m²						
Moment of Inertia Ip2	4.0459e-002 kg·m²						
Moment of Inertia lp3	9.0592e-002 kg·m²						
Sta	tistics						
Nodes	3285						
Elements	432						
Mesh Metric	None						
CAD A	Attributes						
PartTolerance:	0.0000001						
Color:175.159.143							

TABLE 18 Model (A4, B4) > Materials

Wodel (A4, B4) > Waterials						
Object Name	Materials					
State	Fully Defined					
Statistics						
Materials	8					
Material Assignments	0					

TABLE 19
Model (A4, B4) > Coordinate Systems > Coordinate System

Object Name	Global Coordinate System					
State	Fully Defined					
Definition						
Туре	Cartesian					
Coordinate System ID	0.					
Origin						
Origin X	0. m					
Origin Y	0. m					
Origin Z	0. m					
Directio	nal Vectors					
X Axis Data	[1. 0. 0.]					
Y Axis Data	[0. 1. 0.]					
Z Axis Data	[0. 0. 1.]					

Connections

TABLE 20 Model (A4, B4) > Connections

1110401 (714) 24/ 2 00111100110110						
Object Name	Connections					
State	Fully Defined					
Auto Detection						
Generate Automatic Connection On Refresh	Yes					
Transparency						
Enabled	Yes					

TABLE 21
Model (A4, B4) > Connections > Contacts

, lions > Contacts
Contacts
Fully Defined
n
Contact
Geometry Selection
All Bodies
tion
Slider
0.
1.8391e-003 m
No
Yes
75. °
Off
Include
No
No
Include All
Bodies

Search Across	Bodies
Statistics	S
Connections	289
Active Connections	289

TABLE 22

Object

Contact

 Model (A4, B4) > Connections > Contacts > Contact Regions

 Contact
 Contact

Conta

Name	Region	Region 2	Region 3	Region 4	Region 5	Region 6	Region 7	Region 8	Region 9	Region 10	Region
State						Fully Defin	ied				
					Sc	оре					
Scoping Method					Ge	eometry Sel	ection				
Contact	ct 2 Faces 1 Face 2 Faces 1 Face 2 Faces 1							1 Face	2 Fa	aces	
Target	2 Fa	ces	1 Face	2 Fa	ces	1 Face	2 Fa	aces	1 Face	2 Fa	aces
Contact Bodies	Scr	ew-1\Screw	-1	Scr	ew-2\Screw	1-2	Sc	rew-3\Screw-	-3	Screw-4\	\Screw-4
Target Bodies	Front- Plate\Front- Plate	Left- Plate- Inner\Left- Plate- Inner	Left- Mounting- Ear\Left- Mounting- Ear	Front- Plate\Front- Plate	Left- Plate- Inner\Left- Plate- Inner	Mounting- Ear	Front- Plate\Front- Plate	Right- Plate- Inner\Right- Plate-Inner	Right- Mounting- Ear\Right- Mounting- Ear	Front- Plate\Front- Plate	Righ Plate Inner\Ri Plate-Ir
rotected						No					
					Defi	nition					
Туре						Bonded					
Scope Mode						Automati	С				
Behavior					Pr	ogram Cont	trolled				
Trim Contact					Pro	ogram Cont	trolled				
Trim olerance						1.8391e-00	3 m				
pressed						No					
					Dis	splay					
Element Normals						No					
					Adv	anced					
mulation					Pro	ogram Cont	trolled				
Small Sliding					Pr	ogram Cont	trolled				
etection Method					Pr	ogram Cont	trolled				
netration plerance					Pr	ogram Cont	trolled				
stic Slip blerance					Pr	ogram Cont	trolled				
Normal Stiffness					Pr	ogram Cont	trolled				
Update Stiffness					Pr	ogram Cont	trolled				

Pinball Region					Pro	ogram Controlle	d			
rtogion				(Geometric	Modification				
Contact eometry prrection						None				
Target eometry prrection	None									
			Model (A4, B4) > Cc		LE 23 s > Contacts > C	Contact Regions	S		
Contact Region 12	Contact Region 13	Contact Region 14	Contact Region 15	Contact	Contact Region 17	Contact Region 18			Contact Region 21	С
						Fully Defined				
					Sco	ope				
					Ge	eometry Selectio	n			
	1 Face		4 Faces	1 Face	2 Faces	7 Faces			Face	
	1 Face		4 Faces	1 Face	5 Faces	7 Faces		1	Face	
Screw- Screw-4	Fron	t-Plate\Front-	-Plate			l	Left-Plate-Inner\Left-Plate-Inner			
Right- ounting- ar\Right- ounting- Ear	Left- Plate- Inner\Left- Plate- Inner	Right- Plate- Inner\Right- Plate-Inner	Plate\Plate	Back- Plate\Back- Plate	Left- Mounting- Ear\Left- Mounting- Ear	Guidebar	Screw7\Screw7	Screw8\Screw8	Screw9\Screw9	Sc
					Defi	No				
					Detir	nition Bonded				
						Automatic				
					Pro	ogram Controlle				
						ogram Controlle				
						1.8391e-003 m				
						No				
					Dis	splay				
						No				
						anced	_1			
						ogram Controlle ogram Controlle				
						ogram Controlle				
						ogram Controlle				
						79.0111 001111 0110				

	Program Controlled									
	Program Controlled									
			Prog	ram Controlle	ed					
			Prog	ram Controlle	ed					
		G	eometric Mo	odification						
				None						
				None						
TABLE 24 Model (A4, B4) > Connections > Contact Regions										
Contact Region 24	Contact Region 25	Contact Region 26	Contact Region 27	Contact Region 28	Contact Region 29	Contact Region 30	Contact Region 31	Cont		
			F	ully Defined						
			Scop	e						
			Geor	netry Selecti	on					
1 Fa	ace		2 Faces	1 Face	2 Faces	7 Faces		1		
1 Fa	ace		2 Faces	1 Face	5 Faces	7 Faces		1		
Left-Plate	-Inner\Left-Plate-Inr	ner				Right-Pla	ate-Inner\Right-Plate	e-Inner		
Screw12\Screw12	Screw13\Screw13	Screw14\Screw14	Plate\Plate	Back- Plate\Back- Plate	Right- Mounting- Ear\Right- Mounting- Ear	Right- Guidebar\Right- Guidebar	Screw15\Screw15	Screw		
				No						
			Definit							
				Bonded						
				Automatic						
			Prog	ram Controlle	ed					
			Prog	ram Controlle	ed					
			1.8	3391e-003 m						
				No						
			Displ	_						
				No						
			Advan	ced						
			Prog	ram Controll	ed					

				Program Controlle	ed						
				Program Controlle	ed						
				Program Controlle	ed						
				Program Controlle	ed						
				Program Controlle	ed						
				Program Controlle	ed						
				Program Controlle	ed						
			Geome	tric Modification							
				None							
				None							
		Model (TABLE 25	Contact Red	aions					
gion	Model (A4, B4) > Connections > Contacts > Contact Regions gion Contact Region Contact Region 35 Contact Region 37 Contact Region 38 Contact Region 39 Region 40 Region 40 Region 40 Contact Region 40 Region										
		I	I	Fully Defined	I	I		- -			
				Scope							
				Geometry Selection	on						
		1 Face	!			2 Faces	1 F	ace			
		1 Face			4 Faces	2 Faces	5 Fa	aces			
		Right-Plate-Inr	ner\Right-Plate-Inne	r				Back	-Plate∖B		
rew19	Screw20\Screw20	Screw21\Screw21	Screw22\Screw22	Screw23\Screw23	PSK\Solid1	Plate\Plate	Left- Mounting- Ear\Left- Mounting- Ear	Right- Mounting- Ear\Right- Mounting- Ear	Screw1		
				No	•						
				Definition Bonded							
				Automatic							
				Program Controlle	<u>-</u>						
				Program Controlle							
				1.8391e-003 m							
				No							
									_		

				Display	y						
					No						
				Advance							
				Progra	am Controlled	d					
				Progra	am Controlled	.d					
				Progra	am Controlle	:d					
	Program Controlled										
	Program Controlled										
	Program Controlled										
 				Progra	am Controlled	,d					
					am Controlled	.d					
				Geometric Mod	dification						
					None						
					None						
		N	lodel (A4, B4) > (TABLE 2		Contact Re	rgione				
	<u> </u>					Contact Re		Contact	Contact	Contact	
oject ame	Contact Region 45	Contact Region 46	Contact Region 47	Contact Region 48	Contact Region 49	Region 50	Contact Region 51	Region 52			
state	1			Ful	lly Defined					<u> </u>	
				Scope	•						
ping thod				Geom	etry Selection	n n					
ntact		3 Fa	aces		6 Fac	ices	1 Face		2 Fa	aces	
ırget		2 Fa			6 Fac		1 Face		6 Fa		
ntact dies		Back	x-Plate\Back-Plate	<u>;</u>		Ear_Rear\l	Mounting- Left-Mounting- Ear	Left-Mo		ar\Left-Mo ar	
ırget dies	rget Scrow3\Scrow3\Scrow4\Scrow4\Scrow5\Scrow5\Scrow6\Scro										
cted					No						
				Definition							
Type					Bonded						
cope lode				A ^r	utomatic	_				_	

avior							Program Contr	rolled					
Trim							Program Contr	rolled					
ntact													
Trim ance							1.8391e-003	3 m					
ssed							No						
							Display						
nent							No						
nals							Advanced						
ation							Program Contr	rolled					
mall													
ding							Program Contr	rollea					
ction							Program Contr	rolled					
thod ation													
ance							Program Conti	rolled					
Slip							Program Contr	rolled					
ance							- rogiam com						
rmal ness		Program Controlled											
date													
ness							Program Contr	rollea					
nball	Program Controlled												
gion	Geometric Modification												
ntact	:												
netry	,						None						
ction													
irget netry							None						
ction													
				Ma	adal (A4		TABLE 27 tions > Contacts	. Contact Bogi	ions				
	Contact	Contact	Contact	Contact									
\sim	Region			Region		Contact Region 61	Contact Region 62	Contact Region 63	Contact Region 64	Contact Region 65	Contac		
	56	57	58	59	60	Region on			04	00			
ate							Fully Define Scope	ed					
ing							•						
nod							Geometry Sele	ection					
act			2 Faces			1 Face	3 Faces	2 Fa	aces		ace		
get			6 Faces			1 Face	2 Faces		1 F	ace			
act ies						Left-M	lounting-Ear\Left-	Mounting-Ear					
	Left-	Left-	Left-	Left-	Left-	l oft							
get	Nut-	Nut-	Nut-	Nut-	Nut-	Left- Guidebar\Left-	Screw1\Screw1	Screw3\Screw3	Screw4\Screw4	Screw7\Screw7	Screw		
ies	5\Left- Nut-5	6\Left- Nut-6	7\Left- Nut-7	8\Left- Nut-8	9\Left- Nut-9	Guidebar					3.5		
ted	างนเร	INUI-0	INUL-1	INUI-O	INUI-9	<u> </u>	No	<u> </u>	<u> </u>	<u> </u>			
-04							110						

			Definiti							
/pe				Bonded						
ppe ode			1	Automatic						
/ior			Progr	ram Controlled						
rim act			Prog [,]	ram Controlled						
act rim										
ice			1.8 	3391e-003 m						
ed	<u></u>		Displa	No						
ent			וואפוע							
als				No						
			Advano							
ion				ram Controlled						
nall ing			Progr	ram Controlled						
ion iod	Program Controlled									
ion ice			Progr	ram Controlled						
Slip nce			Prog	ram Controlled						
mal ess			Prog	ram Controlled						
ate ess			Prog	ram Controlled						
pall			Prog	ram Controlled						
ion			Geometric Mo							
act etry ion				None						
get etry ion				None						
		Model (A4, B4	TABLE) > Connections >	E 28 Contacts > Contac	ct Regions					
tact Region 68	Contact Region 69	Contact Region 70	Contact Region 71	Contact Region 72	Contact Region 73	Contact Region 74	Contact Reg 75			
				ully Defined						
			Scop	е						
			Geor	metry Selection						

Geometry Selection		
1 Face	2 Faces	1 Face
1 Face		
Left-Mounting-Ear\Left-Mounting-Ear	Left-Nut-1\	Left-Nut-1

/10∖Screw10	Screw11\Screw11	Screw12\Screw12	Screw13\Screw13	Screw14\Screw1	4 Screw16\Screw16	Left- Guidebar\Left- Guidebar	Screw7\Scre
				No			
			Definit	ti on Bonded			
				Automatic			
				ram Controlled			
			Prog	ram Controlled			
			1.8	3391e-003 m			
				No			
			Displ				
				No			
			Advan				
				ram Controlled			
			Prog	ram Controlled			
			Prog	ram Controlled			
			Prog	ram Controlled			
			Prog	ram Controlled			
			Prog	ram Controlled			
			Prog	ram Controlled			
			Prog	ram Controlled			
			Geometric M	odification			
				None			
				None			
		Model (A4 R4	TABLE) > Connections >		act Pagions		
ontact Regior	n Contact	Contact Region				t Region C	ontact C
79	Region 80	81	Region 82	83 R			gion 86
			F Scor	ully Defined			
		1		metry Selection			1
1 Face	2 Faces	1 Face	2 Faces	1 Face 2	Faces 1 F	ace 2	Faces

1 Face

eft-Nut-3	Left-Nu	ut-4\Left-Nut-4	Left-Nut	t-5\Left-Nut	t-5	Left-Nut	:-6\Left-Nut-6		Left-Nut-	·7\L
crew9\Scre	Left- w9 Guidebar\Left Guidebar	Screw10\Screw10	Left- Guidebar\Left- Guidebar	Screw11\	\Screw11	Left- Guidebar\Left- Guidebar	Screw12\Screw12	2 Guidel	.eft- bar\Left- debar	Sci
					No					
				Definition						
					onded					_
					omatic					
				Program	Controlled	d				
				Program	Controlled	d				
				1.8391	1e-003 m					
					No					
				Display						
					No					
			ı	Advanced						
				Program	Controlled	<u>d</u>				
				Program	Controlled	d				
				Program	Controlled	d				
				Program	Controlled	d				
				Program	Controlled	d				
				Program	Controlled	d				
				Program	Controlled	d				
				Program	Controlled	d				
			Geome	tric Modifi	ication					
				N	lone					
				N	lone					
		Model (A4.	T B4) > Connecti	TABLE 30		Contact Region	ns			
Object Co	ontact Region 89		tact Region	Contact Region	Contact Re	egion Contact Region	Contact Contact Region Region	Region	Region	
_				92		94	95 96	97	98	

Fully Defined Scope

State

coping //ethod				Geome	etry Selection						
Contact	1 Face	2 Faces	1 Face	6 Faces	1 Face			2 Fa	aces		
Target		1 Face		6 Faces	1 Face			6 Fa	aces		
Contact Bodies	Left-Nut-8\Left- Nut-8	Left-Nut	-9\Left-Nut-9		t-Mounting- Right-Mounting- Ear	Right-Mounting-Ear\Right-Mounting			ounting-E	ar	
Target Bodies	Screw14\Screw14	Left- Guidebar\Left- Guidebar	Screw16\Screw16	Right- Mounting- Ear\Right- Mounting- Ear	Right- Guidebar\Right- Guidebar	Nut- Nut- Nut- Nut- Nut- Nut- 1\Right- 2\Right- 3\Right- 4\Right- 5\Right				Right- Nut- 5\Right- Nut-5	R 1 6\F N
tected					No						
				Definition	n						
Type				E	Bonded						
Scope Mode	Automatic										
ehavior	Program Controlled										
Trim Contact		Program Controlled									
Trim erance	1.8391e-003 m										
ressed	No										
				Display	1						
lement ormals	No										
				Advance							
ulation				Progra	m Controlled						
Small Sliding				Progra	m Controlled						
tection /lethod				Progra	m Controlled						
etration erance				Progra	m Controlled						
tic Slip erance				Progra	m Controlled						
Normal iffness				Progra	m Controlled						
Jpdate				Progra	m Controlled						
iffness Pinball	·										
Region			_		m Controlled						
			Geo	metric Mod	lification						
contact ometry rection	None										
Target ometry rection	None										

TABLE 31
Model (A4, B4) > Connections > Contacts > Contact Regions

_	_		iviouei (A4, B	(4) > Connection	s > Contacts > C	Jontact Regions		
Contact Region 101	Contact Region 102	Contact Region 103	Contact Region 104	Contact Region 105	Contact Region 106	Contact Region 107	Contact Region 108	Contact Regi 109
					Fully Defined			
				S	cope			
				G	Seometry Selectio	'n		
2 Faces		1 Face	3 Faces	2 Fa	aces		1 F	ace
Faces		1 Face	2 Faces				1 Face	
				Right-Moun	nting-Ear\Right-Mo	ounting-Ear		
Right- Nut- 3\Right- Nut-8	Right- Nut- 9\Right- Nut-9	Right- Guidebar\Right- Guidebar	Screw2\Screw2	Screw5\Screw5	Screw6\Screw6	Screw15\Screw15	Screw17\Screw17	Screw18\Screv
					No			
				Def	finition			
					Bonded			
					Automatic			
				P	Program Controlle	d		
				P	Program Controlle	d		
					1.8391e-003 m			
					No			
				Di	isplay			
					No			
					vanced			
				P	Program Controlle	d		
				P	rogram Controlle	d		
				P	rogram Controlle	d		
				Р	rogram Controlle	d		
				P	Program Controlle	d		
				P	rogram Controlle	d		
				P	Program Controlle	d		
				P	Program Controlle	d		
				Geometric	Modification			
					None			
1								Į.

None

		Model (A4, E	TABL 34) > Connections :		ntact Regions		
ct Region 112	Contact Region 113	Contact Region 114	Contact Region 115	Contact Region 116		Contact Region 118	Contact Region 119
			!	Fully Defined			
			Sco	pe			
			Geo	ometry Selection			
	1 Face			2 Faces	1 Face	2 Faces	1 Face
				1 Face			
Right-Mou	ınting-Ear\Right-Mo	unting-Ear		Right-Nut-1	1\Right-Nut-1	Right-Nut-2	2\Right-Nut-2
1\Screw21	Screw22\Screw22	Screw23\Screw23	Screw24\Screw24	Right- Guidebar\Right- Guidebar	Screw15\Screw15	Right- Guidebar\Right- Guidebar	Screw17\Screv
				No			
			Defin				
				Bonded			
				Automatic			
			Pro	gram Controlled			
			Pro	gram Controlled			
			1	.8391e-003 m			
				No			
			Disp	olay			
				No			
			Adva				
			Pro	gram Controlled			
			Pro	gram Controlled			
			Pro	gram Controlled			
			Pro	gram Controlled			
			Pro	gram Controlled			
			Pro	gram Controlled			
			Pro	gram Controlled			
			Pro	gram Controlled			
			Geometric N	Modification			

				None			
				None			
		Model (A4		ABLE 33 ns > Contacts > C	ontact Regions		
act Region	Contact Region	-	Contact Region	1	Contact Region	Contact Region	Contact Region
123	124	125	126	127	128	129	130
				Fully Defined			
				Scope			
				Geometry Selection	1		
1 Face	2 Faces	1 Face	2 Faces	1 Face	2 Faces	1 Face	2 Faces
				1 Face			
-Nut-4	Right-Nut-	5\Right-Nut-5	Right-Nut-	6\Right-Nut-6	Right-Nut-	7\Right-Nut-7	Right-Nut-
19\Screw19	Right- Guidebar\Right- Guidebar	Screw20\Screw20	Right- Guidebar\Right- Guidebar	Screw21\Screw21	Right- Guidebar\Right- Guidebar	Screw22\Screw22	Right- Guidebar\Right- Guidebar
				No			
			Do	efinition			
				Bonded			
				Automatic			
				Program Controlled	l		
				Program Controlled	I		
				1.8391e-003 m			
				No			
				Display			
				No			
				dvanced			
				Program Controlled	l		
				Program Controlled	I		
				Program Controlled	I		
				Program Controlled	I		
				Program Controlled	I		
				Program Controlled	I		
				Program Controlled	I		
i							

				Program Contro	olled		
			Geon	netric Modification			
				None			
				None			
		Model	I (A4. B4) > Conne	TABLE 34 ctions > Contacts :	> Contact Regions	•	
t Region 134	Contact Region 135	Contact Region 136		Contact Region 138	Contact Region 139	Contact Region 140	Contact Region 141
				Fully Defined	t		
				Scope			
				Geometry Selec	ction		
	8 F	aces		2 Faces			8 Faces
					2 Faces		
			l	Left-Guidebar\Left-G	Guidebar		
r\Screw7	Screw8\Screw8	Screw9\Screw9	Screw10\Screw10	Screw11\Screw11	Screw12\Screw12	Screw13\Screw13	Screw14\Screw14
				No			
				Definition			
				Bonded			
				Automatic			
				Program Contro	olled		
				Program Contro	olled		
				1.8391e-003 i	m		
				No			
				Display			
				No			
				Advanced			
				Program Contro	olled		
				Program Contro	olled		
				Program Contro	olled		
				Program Contro	olled		
				Program Contro	olled		
				Program Contro	olled		
i e							

Program Controlled										
Program Controlled										
Geometric Modification										
None										
None										
TABLE 35 Model (A4, B4) > Connections > Contact Regions										
Contact Region 145	Contact Region Contact									
Fully Defined										
Scope										
0.5	Geometry Selection									
8 Faces		2 Faces	aces	8 Fa	aces					
2 Faces Right-Guidebar\Right-Guidebar										
Screw18\Screw18	Screw19\Screw19	Screw20\Screw20	Screw21\Screw21	Screw22\Screw22	Screw23\Screw23	Screw24\Screw24 S				
			No							
			Definition Bonde	ed						
			Automa	atic						
Program Controlled										
			Program Co	ntrolled						
			1.8391e-0	03 m						
			No							
			Display							
			No							
			Advanced Program Co	ntrolled						
Program Controlled Program Controlled										
Program Controlled										
Program Controlled										

Program Controlled				
Program Controlled				
Program Controlled				
Program Controlled				
Geometric Modification				

None

None

TABLE 36
Model (A4, B4) > Connections > Contacts > Contact Regions

		WIOGE	i (A4, D4 <i>) ></i>	Commectic	ons > Conta	CIS > CO	maci Ne	gions			
Object Name	Contact Region 155	Contact Region 156	Contact Region 157	Contact Region 158	Contact Region 159	Contact Region 160				Contact Region 164	Contact Region 165
State		Fully Defined									
Scope											
Scoping Method		Geometry Selection									
Contact	1 Face										
Target		1 Face					2 Faces		2 Faces		5 Faces
Contact Bodies		Board\Board									
Target Bodies	PCI- Slots\PCI- 4	PCI- Slots\PCI- 5	PCI- Slots\PCI- 6	PCI- Slots\PCI- 7	Base\Base	DIMM- Slot- 1\Clip- 1a	DIMM- Slot- 1\Clip- 1b	DIMM- Slot- 1\Slot-1	DIMM- Slot- 2\Clip- 2a	DIMM- Slot- 2\Clip- 2b	DIMM- Slot- 2\Slot-2
Protected		No									
Definition											
Type		Bonded									
Scope Mode		Automatic									
Behavior	Program Controlled										
Trim Contact		Program Controlled									
Trim Tolerance	1.8391e-003 m										
Suppressed	No										
					Display						
Element Normals	No										
Advanced											
Formulation	Program Controlled										

Small Sliding	Program Controlled
Detection Method	Program Controlled
Penetration Tolerance	Program Controlled
Elastic Slip Tolerance	Program Controlled
Normal Stiffness	Program Controlled
Update Stiffness	Program Controlled
Pinball Region	Program Controlled
	Geometric Modification
Contact Geometry Correction	None
Target Geometry Correction	None

TABLE 37
Model (A4, B4) > Connections > Contacts > Contact Regions

Object Name	Contact Region 166	Contact Region 167	Contact Region 168	Contact Region 169	Contact Region 170		Contact Region 172		Contact Region 174	Contact Region 175	Contact Region 176	
State					Fu	ılly Define	ed					
					Scop	е						
Scoping Method					Geon	netry Sele	ection					
Contact						1 Face						
Target	2 Fa	2 Faces 5 2 Faces 5 2 Faces 5 Faces 5 2 Faces										
Contact Bodies		Board\Board										
Target Bodies	DIMM- Slot- 3\Clip- 3a	DIMM- Slot- 3\Clip- 3b	DIMM- Slot- 3\Slot-3	DIMM- Slot- 4\Clip- 4a	DIMM- Slot- 4\Clip- 4b	DIMM- Slot- 4\Slot-4	DIMM- Slot- 5\Clip- 5a	DIMM- Slot- 5\Clip- 5b	DIMM- Slot- 5\Slot-5	DIMM- Slot- 6\Clip- 6a	DIMM- Slot- 6\Clip- 6b	
Protected						No						
					Definit	ion						
Type						Bonded						
Scope Mode					,	Automatio	:					
Behavior					Progr	am Cont	rolled					
Trim Contact		Program Controlled										
Trim Tolerance					1.8	391e-003	3 m					
Suppressed						No						

	Display
Element Normals	No
	Advanced
Formulation	Program Controlled
Small Sliding	Program Controlled
Detection Method	Program Controlled
Penetration Tolerance	Program Controlled
Elastic Slip Tolerance	Program Controlled
Normal Stiffness	Program Controlled
Update Stiffness	Program Controlled
Pinball Region	Program Controlled
	Geometric Modification
Contact Geometry Correction	None
Target Geometry Correction	None

TABLE 38
Model (A4, B4) > Connections > Contacts > Contact Regions

	Model (A4, B4) > Connections > Contacts > Contact Regions											
Object Name	Contact Region 177	Contact Region 178		Contact Region 180		Contact Region 182		Contact Region 184	Contact Region 185	Contact Region 186	Contact Region 187	
State						Fully De	efined					
					S	соре						
Scoping Method					G	eometry	Selection	l				
Contact		1 Face										
Target	5 Faces	7 F2000										
Contact Bodies						Board\l	Board					
Target Bodies	DIMM- Slot- 6\Slot-6	DIMM- Slot- 7\Clip- 7a	DIMM- Slot- 7\Clip- 7b	DIMM- Slot- 7\Slot-7	DIMM- Slot- 8\Clip- 8a	DIMM- Slot- 8\Clip- 8b	DIMM- Slot- 8\Slot-8	PEM- Fastener- 1\PEM- Fastener- 1	2\PEM-	PEM- Fastener- 3\PEM- Fastener- 3	PEM- Fastener- 4\PEM- Fastener- 4	
Protected						No)					
					Def	inition						
Туре		Bonded										
Scope Mode						Auton	natic					

Behavior	Program Controlled
Trim Contact	Program Controlled
Trim Tolerance	1.8391e-003 m
Suppressed	No
	Display
Element Normals	No
	Advanced
Formulation	Program Controlled
Small Sliding	Program Controlled
Detection Method	Program Controlled
Penetration Tolerance	Program Controlled
Elastic Slip Tolerance	Program Controlled
Normal Stiffness	Program Controlled
Update Stiffness	Program Controlled
Pinball Region	Program Controlled
	Geometric Modification
Contact Geometry Correction	None
Target Geometry Correction	None

TABLE 39
Model (A4, B4) > Connections > Contacts > Contact Regions

Object Name	Contact Region 188	Contact Region 189	Contact Region 190	Contact Region 191	Contact Region 192	Contact Region 193	Contact Region 194	Contact Region 195	Contact Region 196	Contact Region 197	Contact Region 198
State		Fully Defined									
	Scope										
Scoping Method					Geom	etry Selec	tion				
Contact		1 Face									
Target						1 Face					
Contact Bodies					Во	ard\Board					
Target Bodies		PEM- Fastener- 6\PEM- Fastener- 6	PEM- Fastener- 7\PEM- Fastener- 7	8\PEM-	Screw- 1\Screw- 1	Screw- 2\Screw- 2	Screw- 3\Screw- 3	Screw- 4\Screw- 4	Screw- 5\Screw- 5	Screw- 6\Screw- 6	Screw- 7\Screw- 7

Protected	No
	Definition
Type	Bonded
Scope Mode	Automatic
Behavior	Program Controlled
Trim Contact	Program Controlled
Trim Tolerance	1.8391e-003 m
Suppressed	No
	Display
Element Normals	No
	Advanced
Formulation	Program Controlled
Small Sliding	Program Controlled
Detection Method	Program Controlled
Penetration Tolerance	Program Controlled
Elastic Slip Tolerance	Program Controlled
Normal Stiffness	Program Controlled
Update Stiffness	Program Controlled
Pinball Region	Program Controlled
	Geometric Modification
Contact Geometry Correction	None
Target Geometry Correction	None

TABLE 40
Model (A4, B4) > Connections > Contacts > Contact Regions

, , ,											
Object	Contact	Contact	Contact	Contact	Contact	Contact	Contact	Contact	Contact	Contact	Contact
Name	Region	Region	Region	Region	Region	Region	Region	Region	Region	Region	Region
Name	199	200	201	202	203	204	205	206	207	208	209
State					Fully I	Defined					
		Scope									
Scoping Method		Geometry Selection									
Contact		1	Face		16 Faces	1 Face	24 Faces	16 Faces	1 Face	14 Faces	1 Face
Target	1 Face	2 Faces	1 Fa	ace	5 Faces	1 Face	14 Faces	5 Faces	1 Face	10 Faces	1 Face

Contact Bodies	E	3oard∖Bo	ard	Sink\Sink	DIMM	l-Slot-1\C	lip-1a	DIMM	I-Slot-1\C	lip-1b	DIMM- Slot- 1\Slot-1
Target Bodies	Screw- 8\Screw- 8	Nut- 1\Nut-1	Standoff- 1\Standoff- 1	Base\Base	DIMM- Slot- 1\Slot-1	DIMM- Slot- 2\Clip- 2a	DIMM- Stick- 1\Stick- 1	DIMM- Slot- 1\Slot-1	DIMM- Slot- 2\Clip- 2b	DIMM- Stick- 1\Stick- 1	DIMM- Slot- 2\Slot-2
Protected						٧o					
				De	efinition						
Туре					Bor	nded					
Scope Mode					Auto	matic					
Behavior					Program	Controlle	hd				
Trim											
Contact					Program	Controlle	ed				
Trim					1 8391	e-003 m					
Tolerance											
Suppressed				_		٧o					
Element				L	Display						
Normals					1	٧o					
				Ac	dvanced						
Formulation					Program	Controlle	ed				
Small Sliding					Program	Controlle	ed				
Detection Method					Program	Controlle	ed				
Penetration Tolerance					Program	Controlle	ed				
Elastic Slip Tolerance					Program	Controlle	ed				
Normal Stiffness					Program	Controlle	ed				
Update Stiffness					Program	Controlle	ed				
Pinball Region					Program		ed				
				Geometr	ic Modifi	cation					
Contact Geometry Correction	None										
Target Geometry Correction					No	one					

TABLE 41
Model (A4, B4) > Connections > Contacts > Contact Regions

Object Name	Contact Region 210	Contact Region 211	Contact Region 212	Contact Region 213	Contact Region 214	-		Contact Region 217	Contact Region 219	Contact Region 220
State					Fι	ılly Define	ed			

					Scop	е						
Scoping Method					Geon	netry Sele	ection					
Contact	16 F	aces	1 Face	24 Faces	16 Faces	1 Face	14 Faces	1 Face	16 F	aces	1 Face	
Target	342 Faces	5 Faces	1 Face	14 Faces	5 Faces	1 Face	10 Faces	1 Face	342 Faces	5 Faces	1 Face	
Contact Bodies	DIMM- Slot- 1\Slot-1	Slot- \Slot-1 DIMM-Slot-2\Clip-2a DIMM-Slot-2\Clip-2b DIMM-Slot- 2\Slot-2 DIMM-Slot- 3\Clip-3a										
Target Bodies	DIMM- Stick- 1\Stick- 1	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$										
Protected						No						
					Definit							
Туре						Bonded						
Scope Mode						Automatio						
Behavior					Progr	am Cont	rolled					
Trim Contact					Progr	am Cont	rolled					
Trim												
Tolerance					1.8	391e-003	3 m					
Suppressed						No						
	Display											
Element Normals						No						
					Advand							
Formulation					Progr	am Cont	rolled					
Small Sliding					Progr	am Cont	rolled					
Detection Method					Progr	am Cont	rolled					
Penetration					Progr	am Cont	rolled					
Tolerance Elastic Slip						am Cont						
Tolerance Normal												
Stiffness					Progr	am Cont	rolled					
Update Stiffness					Progr	am Cont	rolled					
Pinball Region					Progr	am Cont	rolled					
				Geon	netric Mo	dificatio	n					
Contact Geometry Correction						None						
Target Geometry Correction						None						

TABLE 42
Model (A4, B4) > Connections > Contacts > Contact Regions

Contact Contac												
Object	Contact											
Name	Region	Region	Region	Region	Region	Region	Region	Region	Region	Region	Region	
Otata	221	222	223	224	225	226	227	228	229	230	231	
State						ılly Defin	ea					
Caanina					Scop	е						
Scoping Method					Geon	netry Sele	ection					
Contact	24	16	1 Face	14	1 Face	16 F	aces	24	16	14	16	
Contact	Faces	Faces	11 400	Faces	11 400			Faces	Faces	Faces	Faces	
Target	14	1 F2CA 1 F2CA								342		
0	Faces	Faces		Faces		Faces	Faces	Faces	Faces	Faces	Faces	
Contact Bodies	DIMM- Slot- 3\Clip- 3a	DIMM	l-Slot-3\C	lip-3b	DIMM 3\SI		DIMM 4\Cli			l-Slot- p-4b	DIMM- Slot- 4\Slot-4	
Target Bodies	DIMM- Stick- 3\Stick- 3	tick- Slot- Slot- Stick- Slot- Stick- Slot- Slot										
Protected						No						
					Definit	ion						
Туре						Bonded						
Scope					,	Automatio	2					
Mode												
Behavior	Program Controlled											
Trim Contact					Progr	am Cont	rolled					
Trim Tolerance					1.8	391e-003	3 m					
Suppressed						No						
					Displa	ay						
Element Normals						No						
					Advand	ed						
Formulation						am Cont	rolled					
Small Sliding					Progr	am Cont	rolled					
Detection Method					Progr	am Cont	rolled					
Penetration Tolerance					Progr	am Cont	rolled					
Elastic Slip Tolerance					Progr	am Cont	rolled					
Normal					Progr	am Cont	rolled					
Stiffness Update						am Cont						
Stiffness Pinball						am Cont						
Region				Coor								
				Geon	netric Mo	ouricatio	11					

Contact	
Geometry	None
Correction	
Target	
Geometry	None
Correction	

TABLE 43
Model (A4, B4) > Connections > Contacts > Contact Regions

Object Contact	act Contact									
UDICCI _ , _ , _ , _ , - ,	iot Comact									
Name Region Regio	on Region									
Name 232 233 234 235 236 237 238 239 240 24										
State Fully Defined										
	·									
Scope										
Scoping Geometry Selection										
Contact 16 Faces 1 Face 24 16 Faces 1 Face 17 Faces 1 Faces 1 Face 17 Faces 1	e 24 Faces									
5 14 5 11 245 5	14									
Target Faces 1 Face Faces 1 Face 1 Face	e Faces									
	races									
Contact Bodies DIMM-Slot-5\Clip-5a DIMM-Slot-5\Clip-5b DIMM-Slot-5\Slot-5	6\Clip-6a									
DIMM- DIMM- DIMM- DIMM- DIMM- DIMM- DIMM- DIMM-	л- DIMM-									
Target Slot-	- Stick-									
Podice 5101- 6/Clip 5/Stick 5101- 6/Clip 5/Stick 5101- 5/Stick 5101- 7/C										
5\Slot-5 6a 5\Slot-5 6b 5\Slot-6 5\Slot-6 5\Slot-6 6\Slot-6	6									
Protected No										
Definition										
Type Bonded										
Scope										
Mode Automatic										
Behavior Program Controlled										
Trim Program Controlled										
Contact										
Trim 1.8391e-003 m										
Tolerance 1.6591e-0051ff										
Suppressed										
Display										
Element No										
Normals										
Advanced										
Formulation Program Controlled										
Small Dragger Controlled										
Sliding Program Controlled										
Detection	December 2011 1									
Method Program Controlled	Program Controlled									
Penetration Program Controlled	Program Controlled									
Tolerance										
Elastic Slip Taleranea Program Controlled										
Tolerance										

Normal Stiffness	Program Controlled								
Update Stiffness	Program Controlled								
Pinball Region	Program Controlled								
	Geometric Modification								
Contact Geometry Correction	None								
Target Geometry Correction	None								

TABLE 44
Model (A4, B4) > Connections > Contacts > Contact Regions

	Model (A4, B4) > Connections > Contacts > Contact Regions										
Object Name	Contact Region 243	Contact Region 244	Contact Region 245	Contact Region 246	Contact Region 247	Contact Region 248	Contact Region 249	Contact Region 250	Contact Region 251	Contact Region 252	Contact Region 253
State					Fι	ılly Define	ed				
					Scop						
Scoping Method					Geon	netry Sele	ection				
Contact	16 Faces	1 Face	17 Faces	1 Face	17 Faces	16 Faces	1 Face	24 Faces	16 Faces	1 Face	17 Faces
Target	5 Faces	1 Face	11 Faces	1 Face	345 Faces	5 Faces	1 Face	14 Faces	5 Faces	1 Face	11 Faces
Contact Bodies	DIMM	-Slot-6\C	lip-6b	DIMM 6\SI		DIMM	l-Slot-7\C	lip-7a	DIMM	l-Slot-7\C	lip-7b
Target Bodies	DIMM- Slot- 6\Slot-6	DIMM- Slot- 7\Clip- 7b	DIMM- Stick- 6\Stick- 6	DIMM- Slot- 7\Slot-7	DIMM- Stick- 6\Stick- 6	DIMM- Slot- 7\Slot-7	DIMM- Slot- 8\Clip- 8b	DIMM- Stick- 7\Stick- 7	DIMM- Slot- 7\Slot-7	DIMM- Slot- 8\Clip- 8a	DIMM- Stick- 7\Stick- 7
Protected						No					
					Definit	ion					
Type						Bonded					
Scope Mode					,	Automatio					
Behavior					Progr	am Cont	rolled				
Trim Contact					Progr	am Cont	rolled				
Trim Tolerance					1.8	391e-003	3 m				
Suppressed						No					
					Displa	ay					
Element Normals	No										
					Advand	ed					
Formulation					Progr	am Cont	rolled				
Small Sliding					Progr	am Cont	rolled				

Detection Method	Program Controlled
Penetration Tolerance	Program Controlled
Elastic Slip Tolerance	Program Controlled
Normal Stiffness	Program Controlled
Update Stiffness	Program Controlled
Pinball Region	Program Controlled
	Geometric Modification
Contact Geometry Correction	None
Target Geometry Correction	None

TABLE 45

Model (A4, B4) > Connections > Contacts > Contact Regions

tact Contact Cont

Object Name	Contact Region 254	Contact Region 255	Contact Region 256	Contact Region 257			Contact Region 260	Contact Region 261	Contact Region 262	Contact Region 263	Contact Region 264
State							efined				
	Scope										
Scoping Method		Geometry Selection									
Contact	1 Face	17 Faces	16 Faces	17 Faces	16 Faces	24 Faces	17 Faces	1 Face		2 Faces	
Target	1 Face	345 Faces	5 Faces	11 Faces	5 Faces	14 Faces	345 Faces	1 Face		9 Faces	
Contact Bodies	DIMM 7\SI		DIMM 8\Cli		DIMM 8\Cli		DIMM- Slot- 8\Slot-8	PSK\Solid1		Plate\Plate	
Target Bodies	DIMM- Slot- 8\Slot-8	DIMM- Stick- 7\Stick- 7	DIMM- Slot- 8\Slot-8	DIMM- Stick- 8\Stick- 8	DIMM- Slot- 8\Slot-8		DIMM-Stick- 8\Stick-8		PEM- Fastener- 1\PEM- Fastener- 1	PEM- Fastener- 2\PEM- Fastener- 2	PEM- Fastener- 3\PEM- Fastener- 3
Protected						Ν	lo				
					De	finition					
Туре						Bon	ded				
Scope Mode						Auto	matic				
Behavior					F	Program (Controlle	d			
Trim Contact		Program Controlled									
Trim Tolerance						1.8391	e-003 m				
Suppressed						Ν	lo				

	Display									
Element Normals	No									
	Advanced									
Formulation	Program Controlled									
Small Sliding	Program Controlled									
Detection Method	Program Controlled									
Penetration Tolerance	Program Controlled									
Elastic Slip Tolerance	Program Controlled									
Normal Stiffness	Program Controlled									
Update Stiffness	Program Controlled									
Pinball Region	Program Controlled									
	Geometric Modification									
Contact Geometry Correction	None									
Target Geometry Correction	None									

TABLE 46
Model (A4, B4) > Connections > Contacts > Contact Regions

Object Name	Contact Region 265	Contact Region 266	Contact Region 267	Contact Region 268	Contact Region 269	Contact Region 270	Contact Region 271	Contact Region 272	Contact Region 273	Contact Region 274	Contact Region 275
State					Full	y Defined					
	Scope										
Scoping Method		Geometry Selection									
Contact			2 Faces					1 F	ace		
Target			9 Faces					1 F	ace		
Contact Bodies		Plate\Plate									
Target Bodies	PEM- Fastener- 4\PEM- Fastener- 4	PEM- Fastener- 5\PEM- Fastener- 5	PEM- Fastener- 6\PEM- Fastener- 6	PEM- Fastener- 7\PEM- Fastener- 7	PEM- Fastener- 8\PEM- Fastener- 8	Screw- 1\Screw- 1	Screw- 2\Screw- 2	Screw- 3\Screw- 3	Screw- 4\Screw- 4	Screw- 5\Screw- 5	Screw- 6\Screw- 6
Protected						No					
					Definition	n					
Туре					E	Bonded					
Scope Mode		Automatic									
Behavior		Program Controlled									

Trim	
Contact	Program Controlled
Trim	1.8391e-003 m
Tolerance	
Suppressed	No
	Display
Element Normals	No
	Advanced
Formulation	Program Controlled
Small Sliding	Program Controlled
Detection Method	Program Controlled
Penetration Tolerance	Program Controlled
Elastic Slip Tolerance	Program Controlled
Normal Stiffness	Program Controlled
Update Stiffness	Program Controlled
Pinball Region	Program Controlled
	Geometric Modification
Contact	
Geometry Correction	None
Target Geometry	None
Correction	

TABLE 47
Model (A4, B4) > Connections > Contacts > Contact Regions

Object Name	Contact Region 276	Contact Region 277	Contact Region 278	Contact Region 279	Contact Region 280	Contact Region 281	Contact Region 282	Contact Region 283	Contact Region 284	Contact Region 285	Contact Region 286
State						Fully Defin	ned				
Scope											
Scoping Method		Geometry Selection									
Contact	1 F	ace	2 Faces	1 Face				2 Faces			
Target	1 F	ace	2 Faces	8 Faces	2 Faces						
Contact Bodies	Plate\Plate				PEM- Fastener- 1\PEM- Fastener- 1	2\PEM-	PEM- Fastener- 3\PEM- Fastener- 3	PEM- Fastener- 4\PEM- Fastener- 4	PEM- Fastener- 5\PEM- Fastener- 5	6\PEM-	7∖PEM-
Target Bodies	Screw- 7\Screw- 7	Screw- 8\Screw- 8	Screw- 9\Screw- 9	Nut- 1\Nut-1	Screw- 3\Screw- 3	Screw- 8\Screw- 8	Screw- 7\Screw- 7	Screw- 1\Screw- 1	Screw- 6\Screw- 6	Screw- 2\Screw- 2	Screw- 5\Screw- 5

Protected	No
	Definition
Type	Bonded
Scope Mode	Automatic
Behavior	Program Controlled
Trim Contact	Program Controlled
Trim Tolerance	1.8391e-003 m
Suppressed	No
	Display
Element Normals	No
	Advanced
Formulation	Program Controlled
Small Sliding	Program Controlled
Detection Method	Program Controlled
Penetration Tolerance	Program Controlled
Elastic Slip Tolerance	Program Controlled
Normal Stiffness	Program Controlled
Update Stiffness	Program Controlled
Pinball Region	Program Controlled
	Geometric Modification
Contact Geometry Correction	None
Target Geometry Correction	None

TABLE 48
Model (A4, B4) > Connections > Contacts > Contact Regions

mount (11, 21) / commoditions / commoditions									
Object Name	Object Name Contact Region 287		Contact Region 289						
State									
Scope									
Scoping Method	Geometry Selection								
Contact	2 Faces	2 Faces							
Target	2 Faces	4 Faces	1 Face						
Contact Bodies	PEM-Fastener-8\PEM- Fastener-8	Screw-9\Screw-9							
Target Bodies	Screw-4\Screw-4	Nut-1\Nut-1	Standoff-1\Standoff-						

Protected	No	
Definition		
Туре	Bonded	
Scope Mode	Automatic	
Behavior	Program Controlled	
Trim Contact	Program Controlled	
Trim Tolerance	1.8391e-003 m	
Suppressed	No	
	Display	
Element Normals	No	
Advanced		
Formulation	Program Controlled	
Small Sliding	Program Controlled	
Detection Method	Program Controlled	
Penetration Tolerance	Program Controlled	
Elastic Slip Tolerance	Program Controlled	
Normal Stiffness	Program Controlled	
Update Stiffness	Program Controlled	
Pinball Region	Program Controlled	
	Geometric Modification	
Contact Geometry	None	
Correction		
Target Geometry Correction	None	

Mesh

TABLE 49 Model (A4. B4) > Mesh

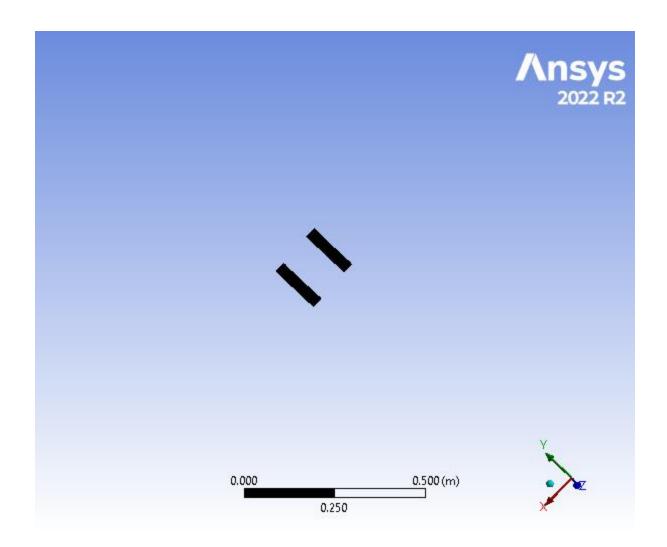
Model (A4, B4) > Mesh				
Object Name	Mesh			
State	Solved			
Display				
Display Style	Use Geometry Setting			
Defaults				
Physics Preference	Mechanical			
Element Order	Program Controlled			
Element Size	Default			
Sizing				
Use Adaptive Sizing	Yes			
Resolution	Default (2)			
Mesh Defeaturing	Yes			
Defeature Size	Default			
Transition	Fast			
Span Angle Center	Coarse			
Initial Size Seed	Assembly			
Bounding Box Diagonal	0.73564 m			
Average Surface Area	1.6021e-004 m ²			
Minimum Edge Length	1.2136e-005 m			
Quality				

Check Mesh Quality	Yes, Errors
Error Limits	Aggressive Mechanical
Target Element Quality	Default (5.e-002)
Smoothing	Medium
Mesh Metric	None
Inflation	
Use Automatic Inflation	None
Inflation Option	Smooth Transition
Transition Ratio	0.272
Maximum Layers	5
Growth Rate	1.2
Inflation Algorithm	Pre
View Advanced Options	No
Advanced	
Number of CPUs for Parallel Part Meshing	Program Controlled
Straight Sided Elements	No
Rigid Body Behavior	Dimensionally Reduced
Triangle Surface Mesher	Program Controlled
Topology Checking	Yes
Pinch Tolerance	Please Define
Generate Pinch on Refresh	No
Statistics	
Nodes	386311
Elements	193691

TABLE 50 Model (A4, B4) > Mesh > Mesh Controls

Model (A4, B4) > Mesn > Mesn Controls					
Object Name	Smallest	Small	Medium	Big	Biggest
State	Fully Defined				
		Scope			
Scoping Method		Geom	etry Selecti	on	
Geometry	1387 Faces	6256 Faces	634 Faces	66 Faces	21 Faces
Definition					
Suppressed	No				
Type	Element Size				
Element Size	2.5e-003 m 5.e-003 m 1.e-002 m 2.e-002 m 3.e-002 r				3.e-002 m
Advanced					
Defeature Size	Default				
Influence Volume	No				
Behavior	Soft				

FIGURE 1 Model (A4, B4) > Mesh > Mesh



Named Selections

TABLE 51
Model (A4. B4) > Named Selections > Named Selections

Middel (A4, B4) > Named delections > Named delections							
Object Name	DIMM1 DIMM2	DIMM3	DIMM4	DIMM5	DIMM6	DIMM7	DIMM8
State	Fully Defined						
	S	cope					
Scoping Method	Scoping Method Geometry Selection						
Geometry		1 Body					
	Definition						
Send to Solver			Υe	es			
Protected	Program Controlled						
Visible	Yes						
Program Controlled Inflation	Exclude						
	Statistics						
Туре			Mar	nual			
Total Selection	1 Body						
Suppressed			()			
Used by Mesh Worksheet	No						

Modal (A5)

TABLE 52 Model (A4, B4) > Analysis

Widdel (A4, D4) > Allalysis				
Modal (A5)				
Solved				
1				
Structural				
Modal				
Mechanical APDL				
22. °C				
No				

TABLE 53 Model (A4, B4) > Modal (A5) > Initial Condition

Object Name	Pre-Stress (None)	
State	Fully Defined	
Definition		
Pre-Stress Environment	None Available	

TABLE 54

Model (A4, B4) > Modal (A5) > Analysis Settings Analysis Settings

٧.	Thay or Stange
e	Fully Defined
	Options
c b	15
d h e	No
d n	
	Solver Controls
b e	No
е	Program Controlled
	Rotordynamics Controls
t II	Off
II n	OII
	Advanced
it)	Off
	Output Controls
s	Yes
e s n a	No
s	No
h	Yes
а	No

s	Constrained Nodes
d y	No
y s	No
e s	Yes
s al s	Program Controlled
al S	No
e n	Program Controlled
	Analysis Data Management
s y	\\iowa.uiowa.edu\shared\Engineering\Home\makaufman\windowsdata\Desktop\ASSEMBLIES_FINAL\assembly_simplified_10_project_f 1\MECH\
e	MSUP Analyses
h s y	
L b	Yes
t	Program Controlled
y e d s	Yes
s	Active System
it n	mks

TABLE 55 Model (A4, B4) > Modal (A5) > Loads

Object Name	Fixed Support	
State	Fully Defined	
S	cope	
Scoping Method	Geometry Selection	
Geometry	2 Faces	
Definition		
Туре	Fixed Support	
Suppressed	No	

Solution (A6)

TABLE 56 Model (A4, B4) > Modal (A5) > Solution

ylodei (A4, B4) > iviodai (Ab) > Solution
Object Name	Solution (A6)
State	Solved
Adaptive Mesh Ref	inement
Max Refinement Loops	1.

Refinement Depth	2.	
Information	1	
Status	Done	
MAPDL Elapsed Time	6 m 51 s	
MAPDL Memory Used	5.7803 GB	
MAPDL Result File Size	1017.1 MB	
Post Processing		
Beam Section Results	No	

The following bar chart indicates the frequency at each calculated mode.

FIGURE 2 Model (A4, B4) > Modal (A5) > Solution (A6)

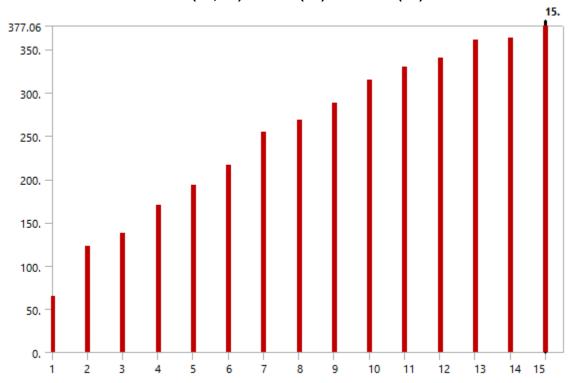


TABLE 57
Model (A4, B4) > Modal (A5) > Solution (A6)

Mode	Frequency [Hz]
1.	65.062
2.	122.1
3.	137.37
4.	170.56
5.	192.99
6.	215.95
7.	254.77
8.	267.84
9.	287.61

10.	314.53
11.	329.52
12.	340.6
13.	361.12
14.	363.44
15.	377.06

TABLE 58
Model (A4, B4) > Modal (A5) > Solution (A6) > Solution Information

Solution Information
Solved
ation
Solver Output
0
0
2.5 s
All
isibility
Yes
All FE Connectors
All Nodes
Connection Type
No
Single

Harmonic Response (B5)

TABLE 59 Model (A4, B4) > Analysis

Model (A4, D4) > Allalysis			
Object Name Harmonic Response			
State	Solved		
Definition			
Physics Type Structural			
Analysis Type	Harmonic Response		
Solver Target Mechanical AP			
Options			
Generate Input Only	No		

TABLE 60
Model (A4, B4) > Harmonic Response (B5) > Initial Condition

. ,			
Object Name	Modal (Modal)		
State	Fully Defined		
Definition			
Modal Environment	Modal		
Pre-Stress Environment	None		

TABLE 61 Model (A4, B4) > Harmonic Response (B5) > Analysis Settings

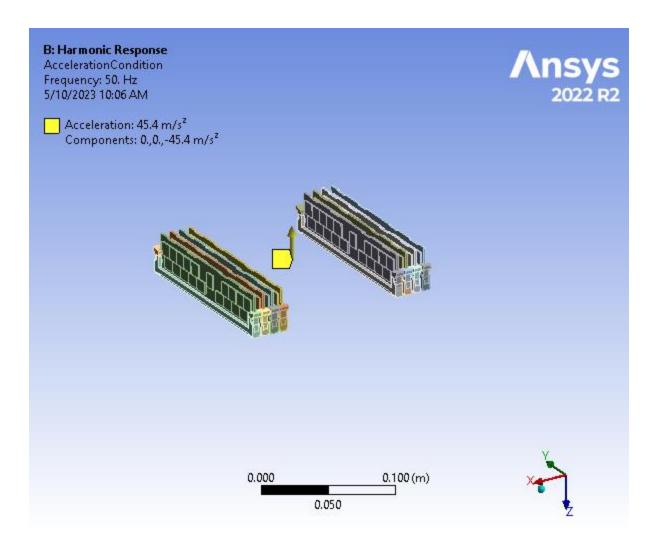
	model (A4, B4) / Harmonia Response (B9) / Analysis Settings					
e e	Analysis Settings					
е	Fully Defined					
	Step Controls					
s	No					
	Options					
y	1					
g	Linear					
е	E0.11					
n	50. Hz					
е	400 11-					
n	100. Hz					
n	F0					
s	50					
d	Off					
s	Oil					
y g e n e n n s d s n d e d r r s d n s II s	Mode Superposition					
d	wide Superposition					
е						
al	No					
r						
r	No					
S	···•					
d	No					
n	1.0					
S	· ·					
II	Yes					
S	Detection and the Controls					
	Rotordynamics Controls					
t	Off					
	Output Controls					
S	Yes					
s e s s n a s d y s	No					
S						
S	No					
n	Yes					
а	Yes					
S	No					
d	Yes					
y	100					
S	Yes					
е	Yes					
S	100					
al	No					
S	110					
d	Program Controlled					
e s al s d n e n	r regram controlled					
n	Modal Solution					
е	Program Controlled					
n	. rogram controlled					

	Damping Controls				
_	Damping Condois				
g n al	No				
g y	Damping Ratio				
g o	2.e-002				
s it y	Direct Input				
s	0.				
s it	0.				
	Analysis Data Management \tiowa.uiowa.edu\shared\Engineering\Home\makaufman\windowsdata\Desktop\ASSEMBLIES_FINAL\assembly_simplified_10_project_fi				
s y	\\liowa.ulowa.edu\shared\Engineening\nome\makauman\windowsdata\Desktop\ASSEMBLIES_FINAL\assembiy_simpililed_10_project_n 2\MECH\				
e s	None				
h s					
У					
b	No				
:t y	Program Controlled				
e d s	Yes				
s	Active System				
it n	mks				

TABLE 62
Model (A4, B4) > Harmonic Response (B5) > Accelerations

(A4, D4) > Harrion	(A+, B+) > Harmonio Response (Bo) > Accelei			
Object Name	Acceleration			
State	Fully Defined			
Scope				
Geometry	All Bodies			
Definition				
Base Excitation	No			
Define By	Components			
Coordinate System	Global Coordinate System			
X Component	0. m/s²			
Y Component	0. m/s²			
Z Component	-45.4 m/s²			
Suppressed	No			

FIGURE 3
Model (A4, B4) > Harmonic Response (B5) > Acceleration > AccelerationCondition



Solution (B6)

TABLE 63 Model (A4, B4) > Harmonic Response (B5) > Solution

Object Name	Solution (B6)			
State	Solved			
Information				
Status	Done			
MAPDL Elapsed Time	11 m 24 s			
MAPDL Memory Used	4.0957 GB			
MAPDL Result File Size	10.588 GB			
Post Processing				
Beam Section Results	No			

FIGURE 4
Model (A4, B4) > Harmonic Response (B5) > Solution (B6)

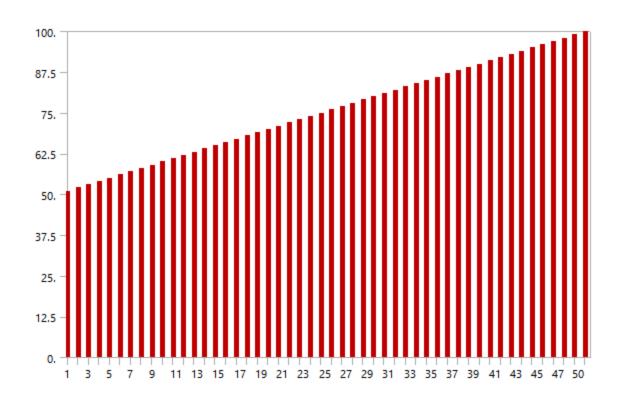


TABLE 64
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > Solution Information

Object Name	Solution Information				
State	Solved				
Solution Inform	ation				
Solution Output	Solver Output				
Newton-Raphson Residuals	0				
Identify Element Violations	0				
Update Interval	2.5 s				
Display Points	All				
FE Connection Visibility					
Activate Visibility	Yes				
Display	All FE Connectors				
Draw Connections Attached To	All Nodes				
Line Color	Connection Type				
Visible on Results	No				
Line Thickness	Single				
Display Type	Lines				

TABLE 65
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > Result Charts

ionFrequencyRespons	AccelerationFrequencyRespons	AccelerationFrequencyRespons	DeformationFrequencyRespons	DeformationFre
eDIMM1x	eDIMM1y	eDIMM1z	eDIMM1x	eDII
		Solved		

		Geometry Selection		
		1 Body		
		Use Average		
		Definition		
	Directional Acceleration			Directional
X Axis	Y Axis	Z Axis	X Axis	Y
		Global Coordinate System		
		No		
		Options		
		Use Parent		
		50. Hz		
		100. Hz		
		Bode		
		Log Y		,
		Results		
48.533 m/s²	66.873 m/s²	1238.6 m/s²	2.9097e-004 m	4.0092
		65. Hz		
-87.481 °	-87.777 °	92.769 °	92.519 °	92.2
2.1331 m/s ²	2.5936 m/s ²	-59.838 m/s ²	-1.2789e-005 m	-1.555
-48.487 m/s²	-66.822 m/s²	1237.1 m/s ²	2.9069e-004 m	4.0062

FIGURE 5
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > VelocityFrequencyResponseDIMM1x

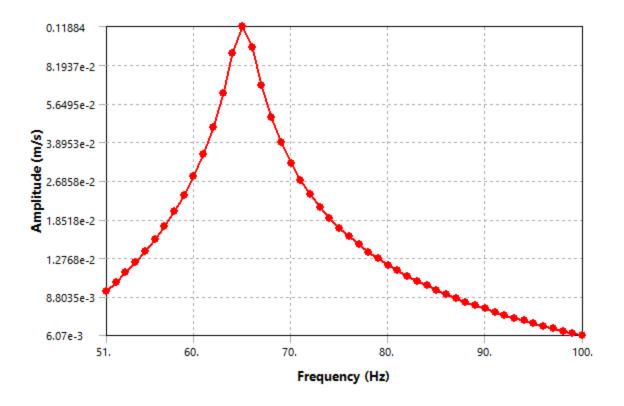


FIGURE 6
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > VelocityFrequencyResponseDIMM1y

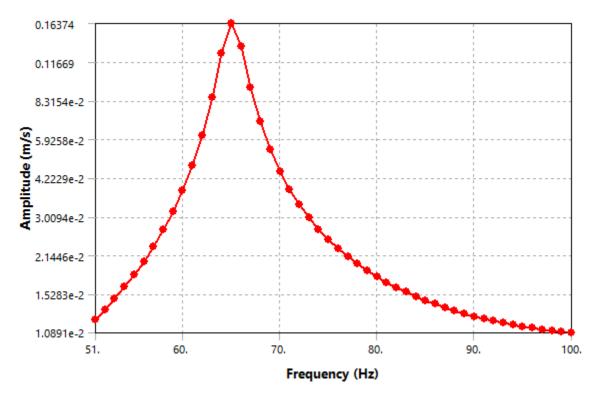


FIGURE 7
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > VelocityFrequencyResponseDIMM1z

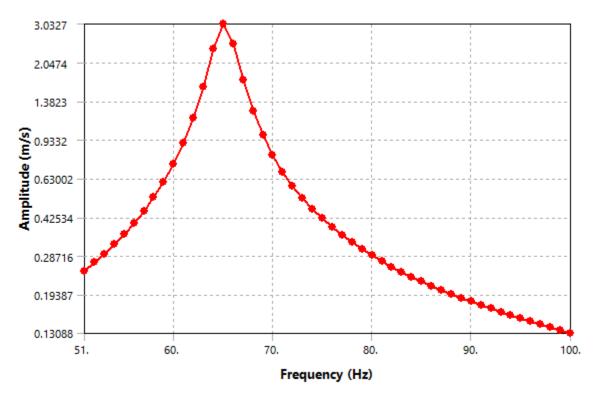


FIGURE 8
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) >
AccelerationFrequencyResponseDIMM1x

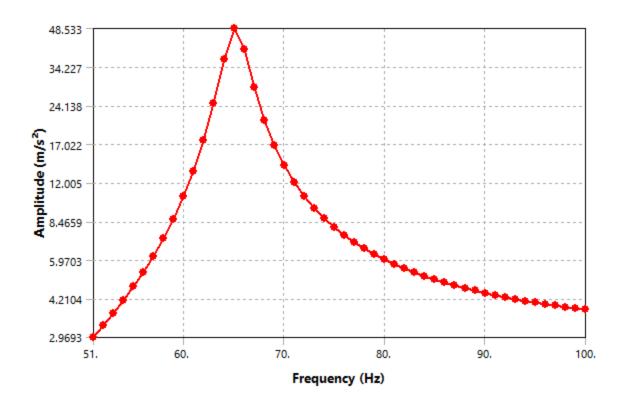


FIGURE 9
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) >
AccelerationFrequencyResponseDIMM1y

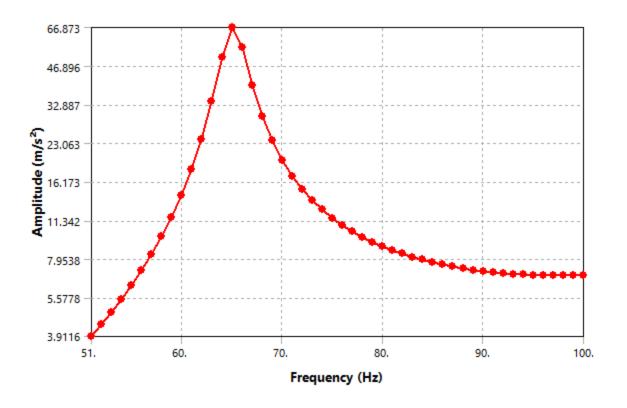


FIGURE 10 Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > AccelerationFrequencyResponseDIMM1z

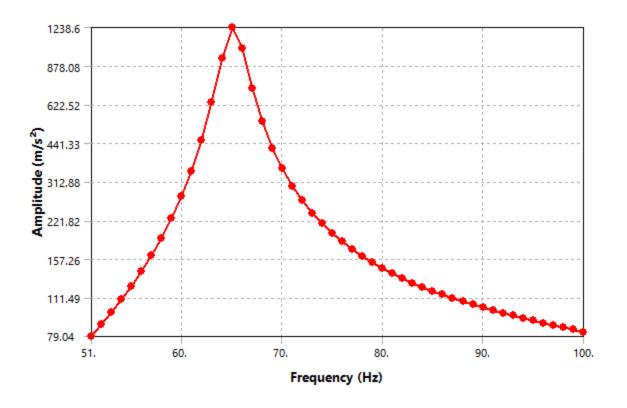


FIGURE 11
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > DeformationFrequencyResponseDIMM1x

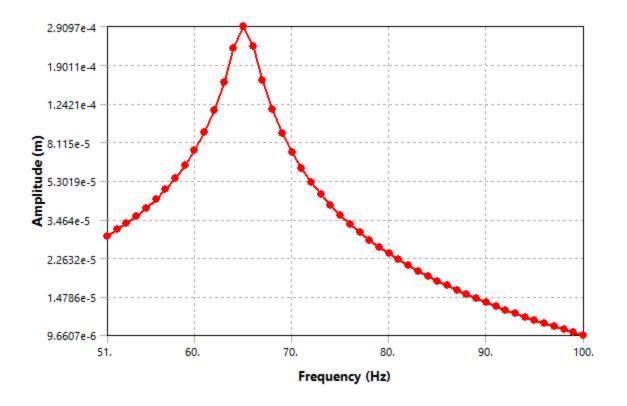


FIGURE 12 Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > DeformationFrequencyResponseDIMM1y

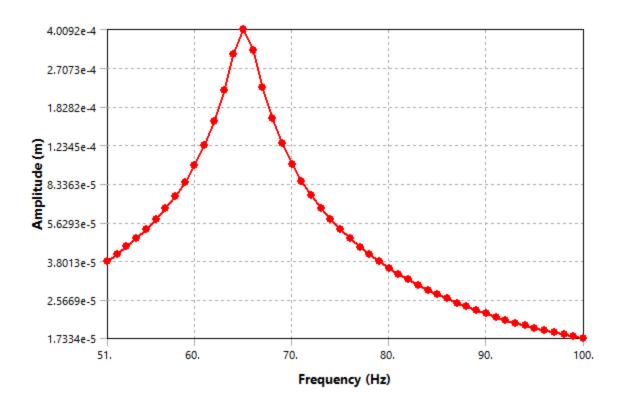


FIGURE 13 Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > DeformationFrequencyResponseDIMM1z

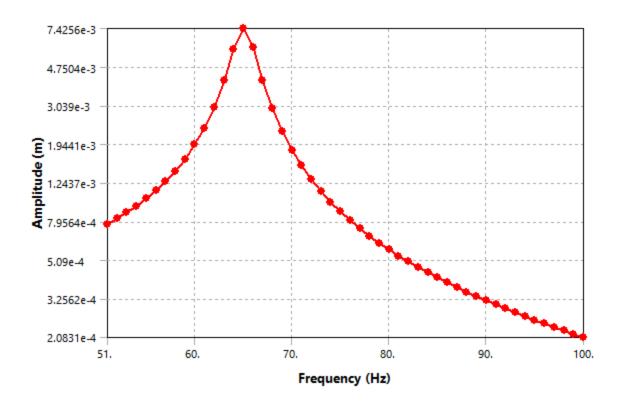


FIGURE 14
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > VelocityFrequencyResponseDIMM2x

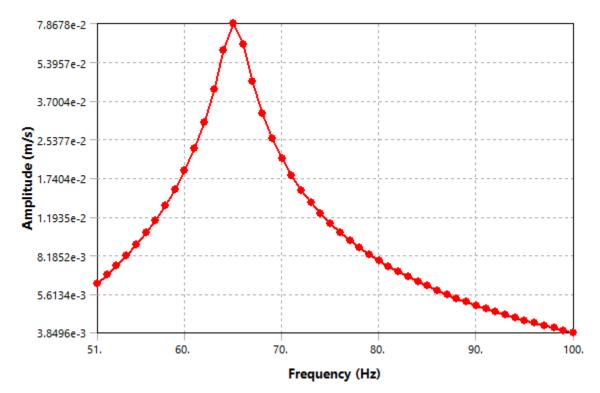


FIGURE 15
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > VelocityFrequencyResponseDIMM2y

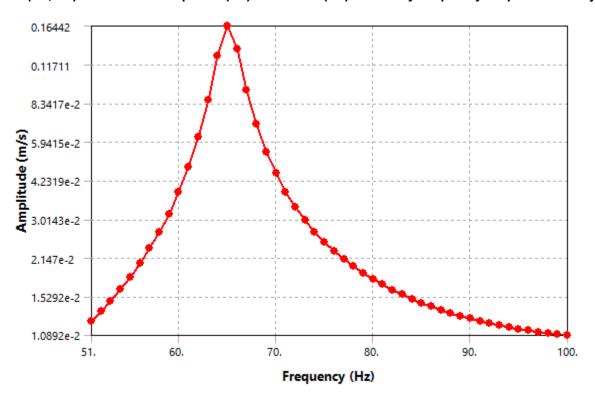


TABLE 66
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > Result Charts

celerationFrequencyRespon seDIMM2z	DeformationFrequencyRespon seDIMM2x	DeformationFrequencyRespon seDIMM2y	DeformationFrequencyRespon seDIMM2z	VelocityFre			
		Solved					
Scope							
Geometry Selection							
1 Body							

Use Average

Definition							
	Directional Deformation						
Z Axis	X Axis	Y Axis	Z Axis				

Global Coordinate System

No

Options

Use Parent				
50. Hz				
100. Hz				
Bode				
Log Y				
Dogulto				

Results							
1260.6 m/s²	1.9265e-004 m	4.026e-004 m	7.5576e-003 m	4.171			
		65. Hz					
92.763 °	92.591 °	92.229 °	-87.237 °				
-60.766 m/s ²	-8.7095e-006 m	-1.5659e-005 m	3.6431e-004 m	-4.16			
1259.1 m/s ²	1.9245e-004 m	4.023e-004 m	-7.5488e-003 m	-2.049			

FIGURE 16
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > VelocityFrequencyResponseDIMM2z

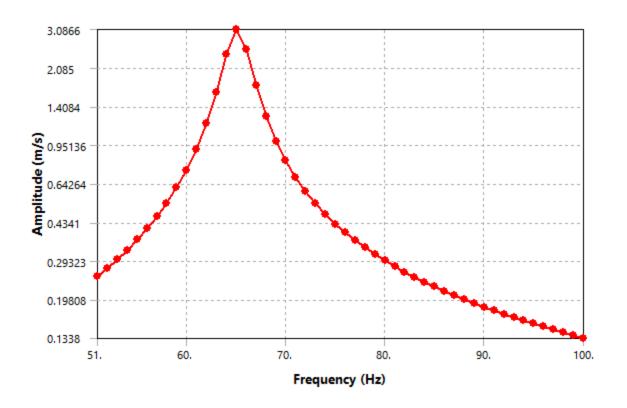


FIGURE 17
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > AccelerationFrequencyResponseDIMM2x

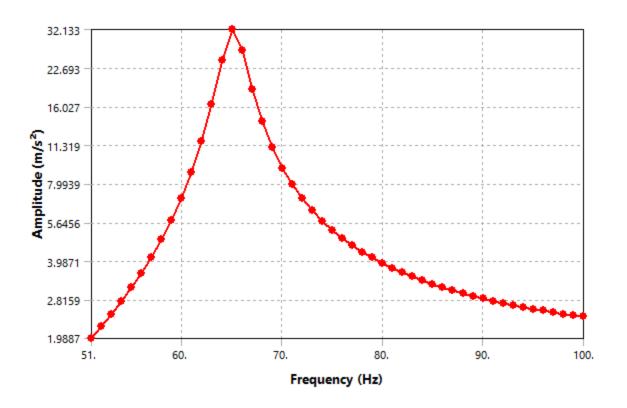


FIGURE 18
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > AccelerationFrequencyResponseDIMM2y

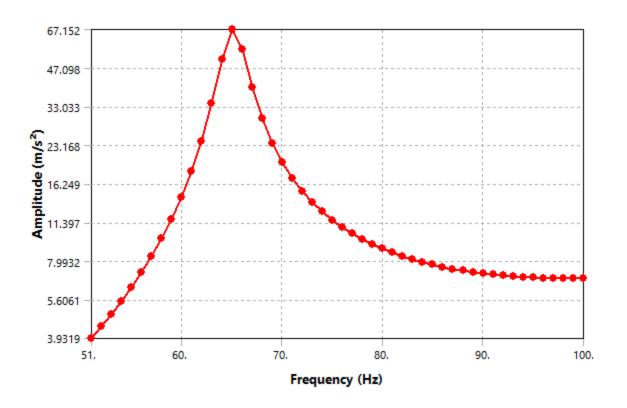


FIGURE 19
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > AccelerationFrequencyResponseDIMM2z

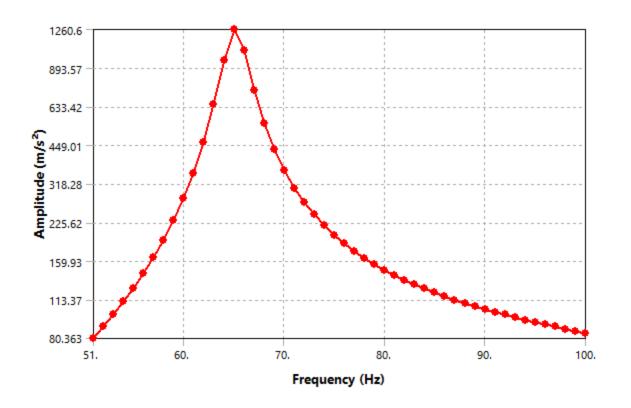


FIGURE 20 Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > DeformationFrequencyResponseDIMM2x

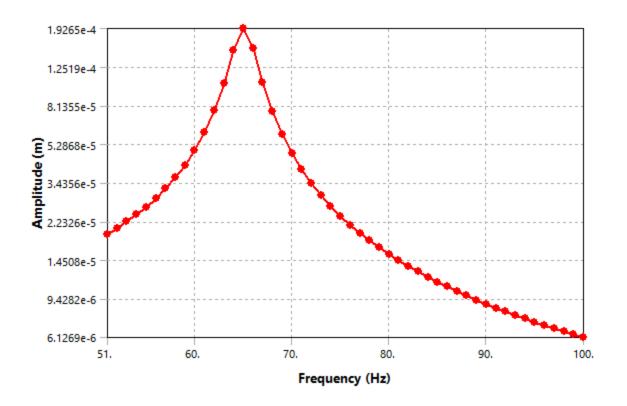


FIGURE 21 Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > DeformationFrequencyResponseDIMM2y

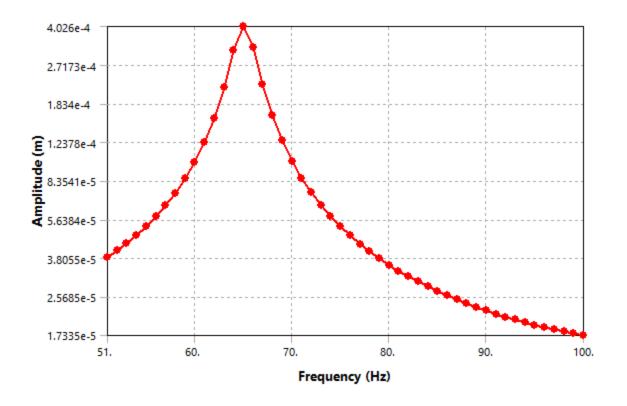


FIGURE 22 Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > DeformationFrequencyResponseDIMM2z

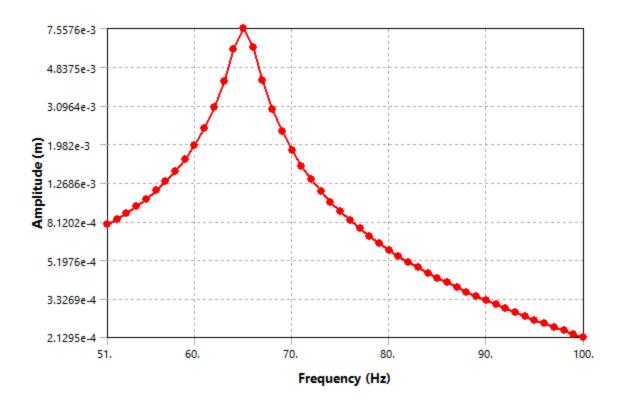


FIGURE 23
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > VelocityFrequencyResponseDIMM3x

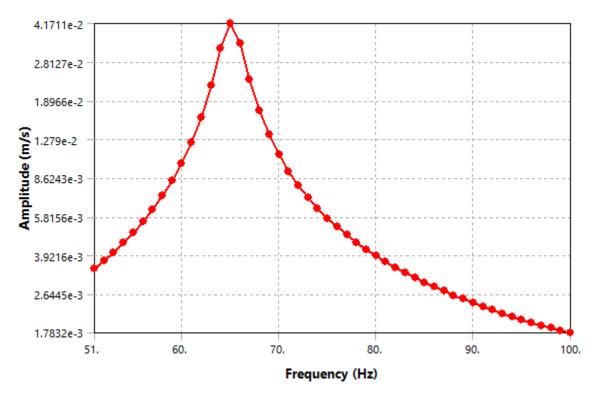


FIGURE 24
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > VelocityFrequencyResponseDIMM3y

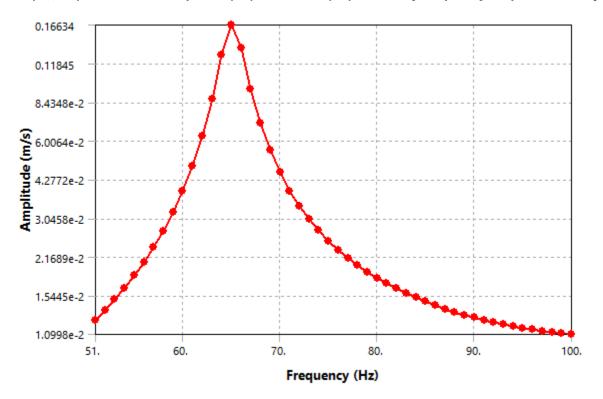


FIGURE 25 Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > VelocityFrequencyResponseDIMM3z

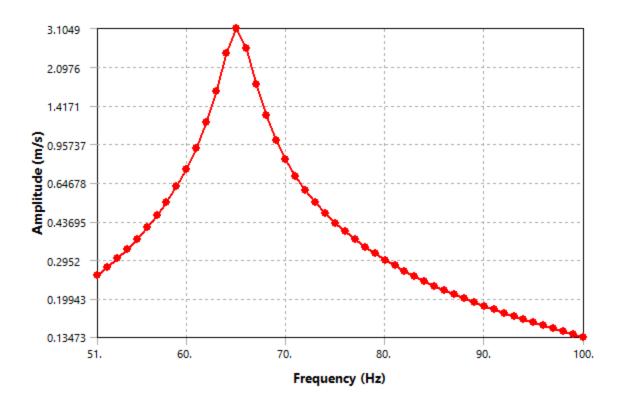


FIGURE 26
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > AccelerationFrequencyResponseDIMM3x

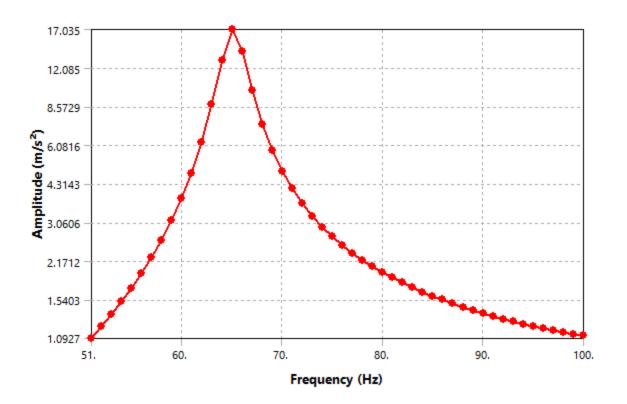


TABLE 67
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > Result Charts

eformationFrequencyRespon	DeformationFrequencyRespon	VelocityFrequencyRespons	VelocityFrequencyRespons	VelocityFrequen	
seDIMM3y	seDIMM3z	eDIMM4x	eDIMM4y	eDIMM	
	Solved				
	Scope				
Geometry Selection					
1 Body					

Use Average

Definition				
Directional Deformation Directional Velocity				
Y Axis	Z Axis	X Axis	Y Axis	Z Axis

Global Coordinate System

No

Options

Use Parent

100. Hz

Bode

Log Y

Results						
4.0729e-004 m	7.6025e-003 m	5.8281e-003 m/s	0.16607 m/s	3.1045 r		
	65. Hz					
92.232 °	-87.239 °	-174.13 °	-177.77 °	2.7614		
-1.5859e-005 m	3.6625e-004 m	-5.7975e-003 m/s	-0.16594 m/s	3.1009 r		
4.0698e-004 m	-7.5936e-003 m	-5.9561e-004 m/s	-6.4691e-003 m/s	0.14957		

FIGURE 27
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > AccelerationFrequencyResponseDIMM3y

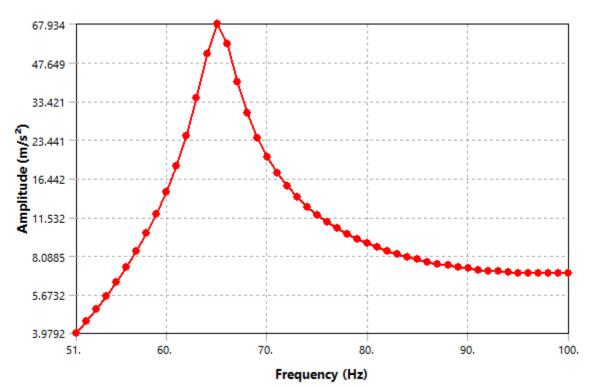


FIGURE 28
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > AccelerationFrequencyResponseDIMM3z

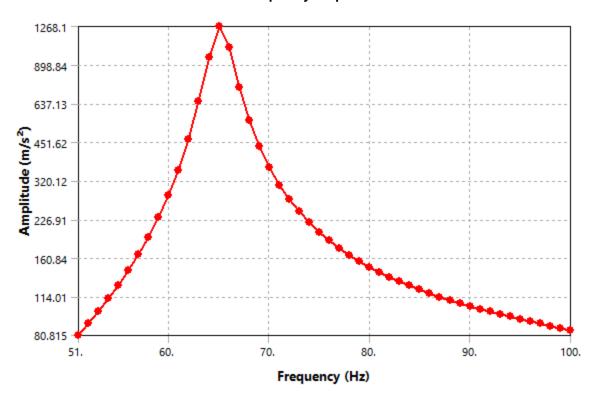


FIGURE 29
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > DeformationFrequencyResponseDIMM3x

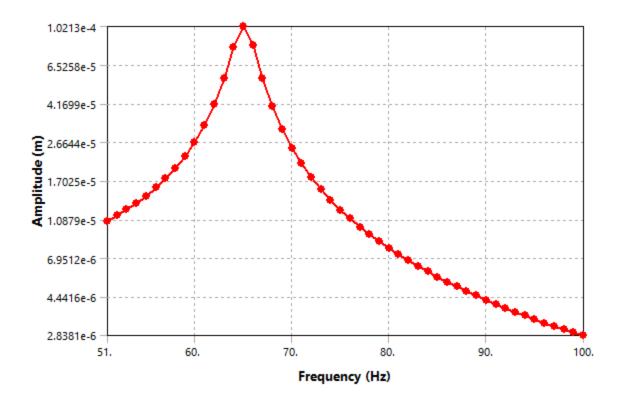


FIGURE 30 Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > DeformationFrequencyResponseDIMM3y

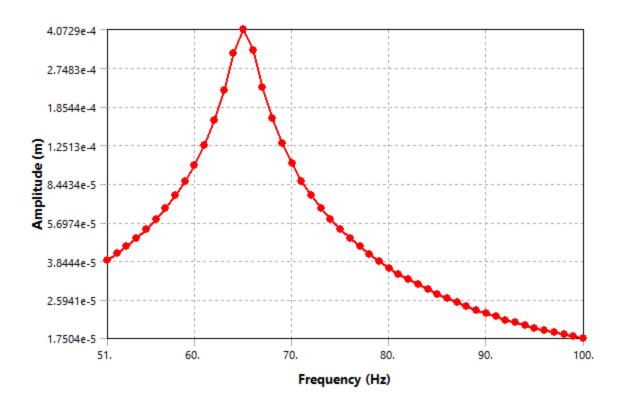


FIGURE 31 Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > DeformationFrequencyResponseDIMM3z

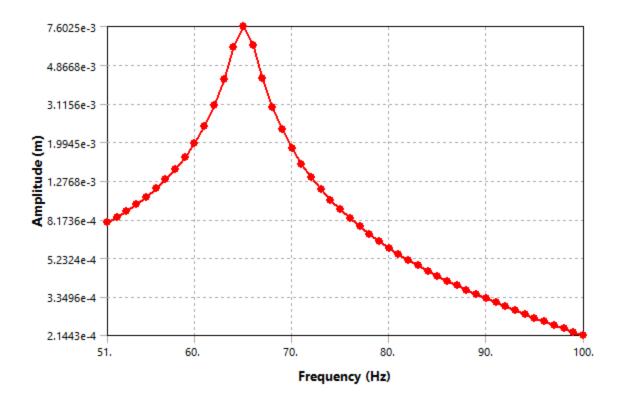


FIGURE 32
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > VelocityFrequencyResponseDIMM4x

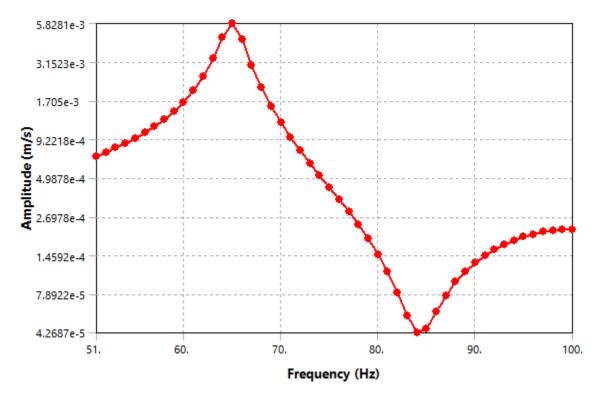


FIGURE 33
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > VelocityFrequencyResponseDIMM4y

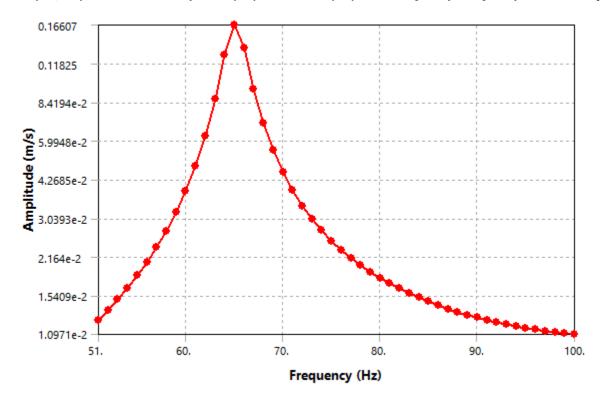


FIGURE 34
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > VelocityFrequencyResponseDIMM4z

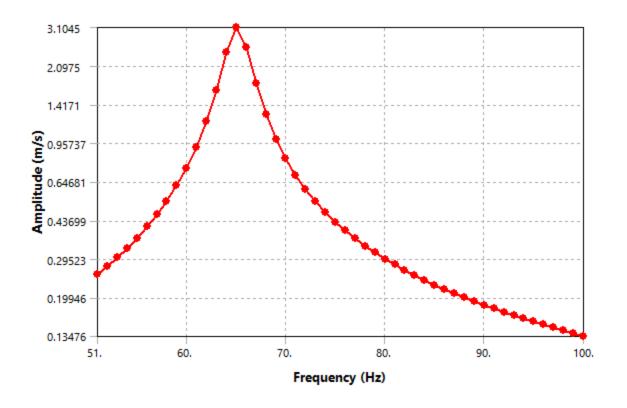


FIGURE 35
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > AccelerationFrequencyResponseDIMM4x

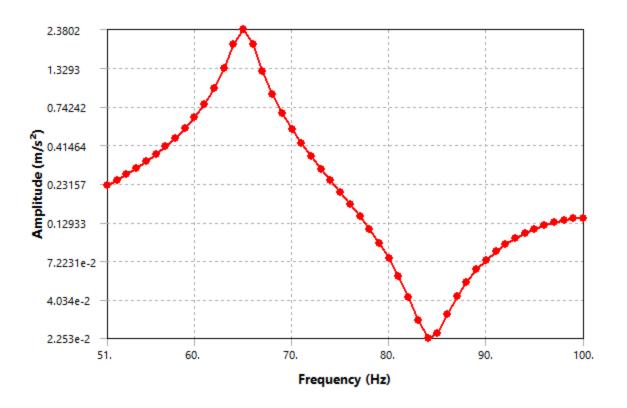


FIGURE 36
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > AccelerationFrequencyResponseDIMM4y

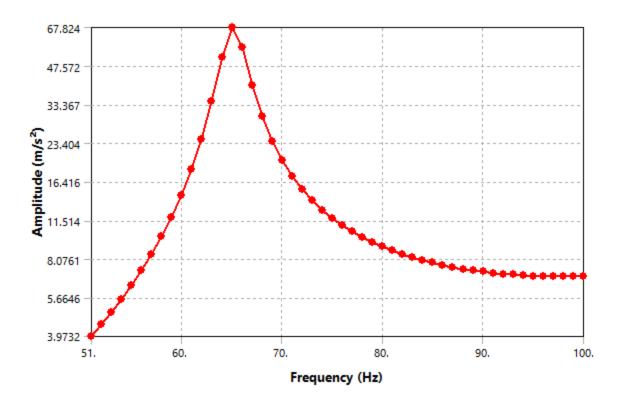


FIGURE 37
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > AccelerationFrequencyResponseDIMM4z

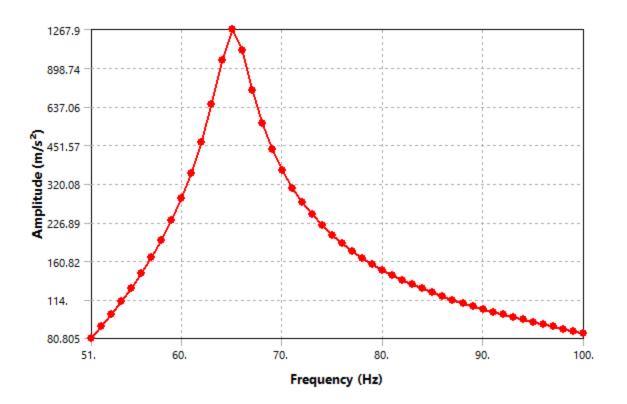


TABLE 68

Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > Result Charts

Velocity/Frequency/Response | Acceleration/Frequency/Response | Acceleration/Frequency/Respon

(elocityFrequencyRespons ∣	VelocityFrequencyRespons	VelocityFrequencyRespons	AccelerationFrequencyRespon	AccelerationFreque		
eDIMM5x	eDIMM5y	eDIMM5z	seDIMM5x	seDIMM5		
	Solved					
	Scope					
Geometry Selection						
1 Body						

Use Average

Definition				
Directional Velocity				Directional Acce
X Axis	Y Axis	Z Axis	X Axis	Y Axis

Global Coordinate System

No

Options

Use Parent

100. Hz

Bode

Log Y

Results					
5.6757e-002 m/s	0.1765 m/s	2.0965 m/s	23.18 m/s²	72.085 m/	
	65. Hz				
2.2814°	-177.74 °	2.9411 °	92.281 °	-87.737 °	
5.6712e-002 m/s	-0.17636 m/s	2.0937 m/s	-0.92273 m/s²	2.8458 m/	
2.2593e-003 m/s	-6.9681e-003 m/s	0.10757 m/s	23.161 m/s ²	-72.029 m/	

FIGURE 38 Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > DeformationFrequencyResponseDIMM4x

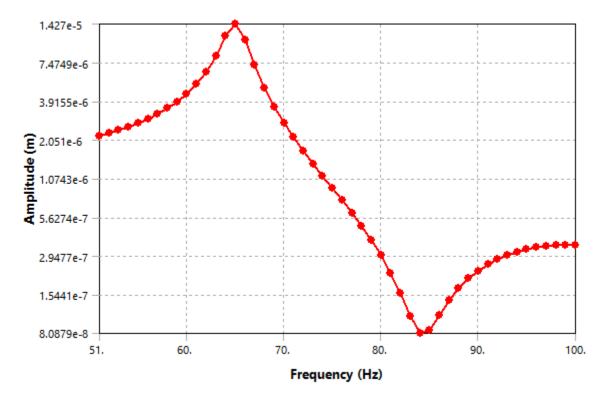


FIGURE 39
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > DeformationFrequencyResponseDIMM4y

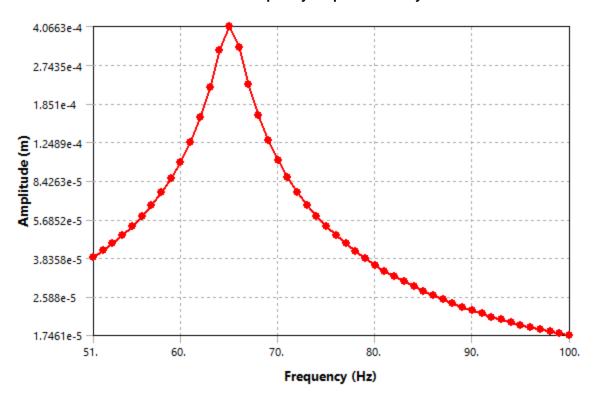


FIGURE 40 Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > DeformationFrequencyResponseDIMM4z

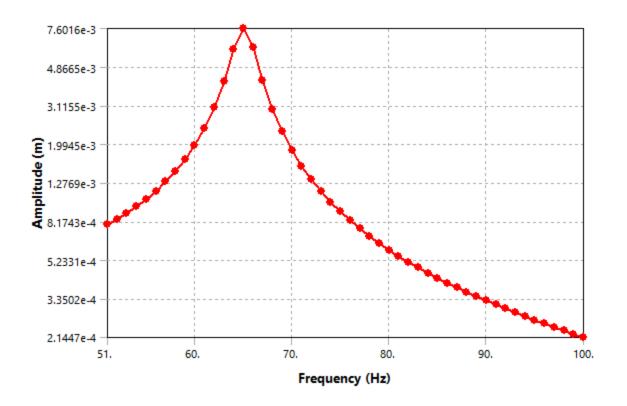


FIGURE 41
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > VelocityFrequencyResponseDIMM5x

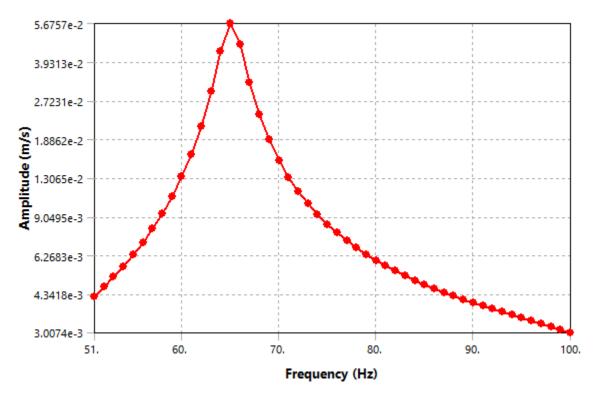


FIGURE 42
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > VelocityFrequencyResponseDIMM5y

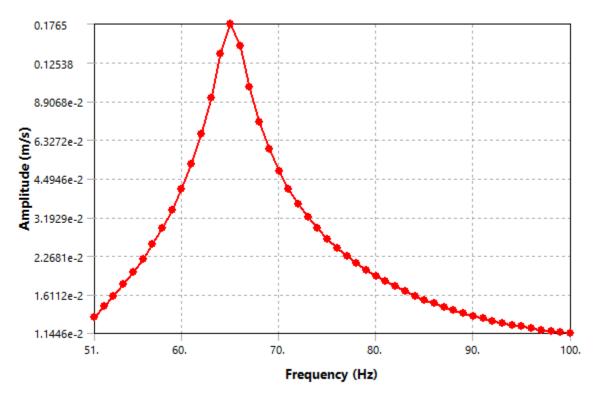


FIGURE 43
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > VelocityFrequencyResponseDIMM5z

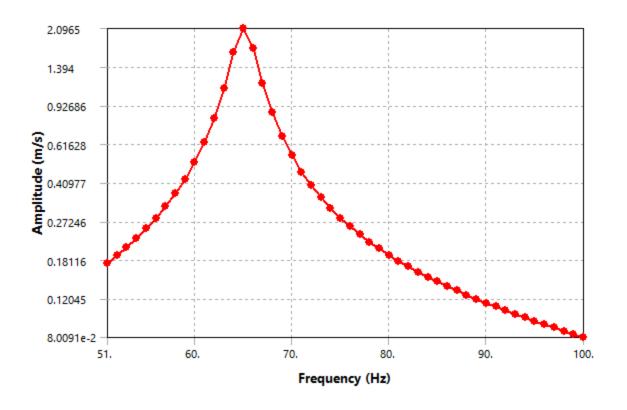


FIGURE 44
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > AccelerationFrequencyResponseDIMM5x

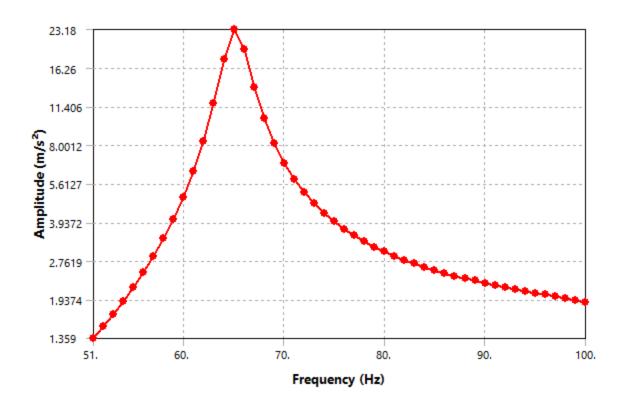


FIGURE 45
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > AccelerationFrequencyResponseDIMM5y

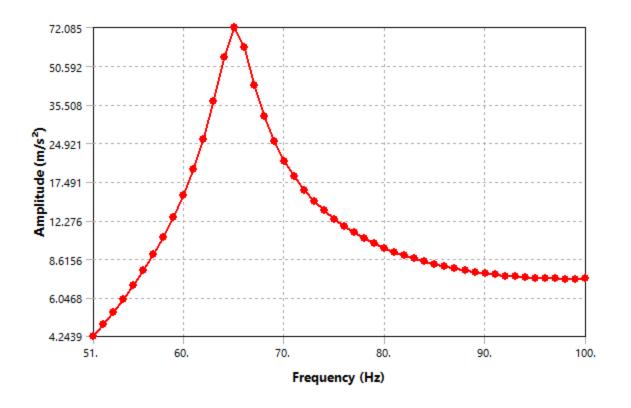


FIGURE 46
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > AccelerationFrequencyResponseDIMM5z

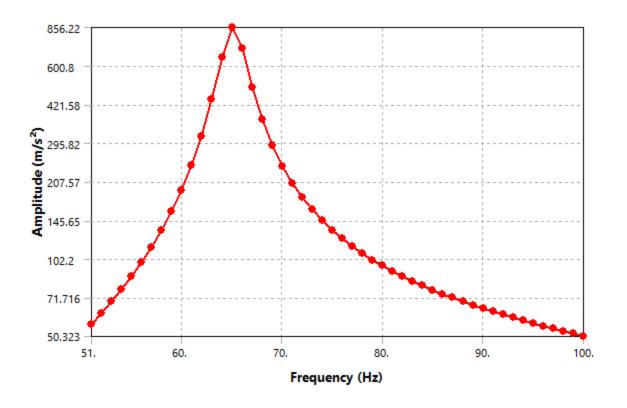


FIGURE 47
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > DeformationFrequencyResponseDIMM5x

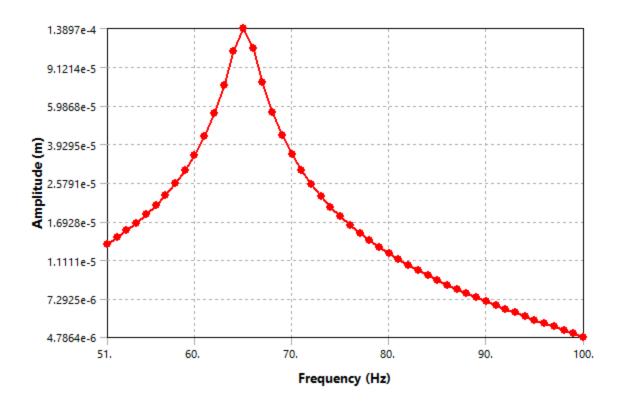


FIGURE 48
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) >
DeformationFrequencyResponseDIMM5y

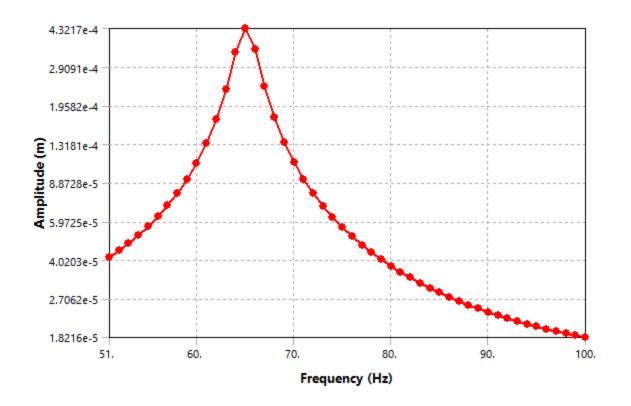


TABLE 69
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > Result Charts

y⊦requencyRespons	AccelerationFrequencyRespon	AccelerationFrequencyRespon	AccelerationFrequencyRespon	∣ DetormationFreq	
eDIMM6z	seDIMM6x	seDIMM6y	seDIMM6z	seDIMi	
Solved					
	Scope				
Geometry Selection					
1 Body					

Use Average

Definition				
Directional Acceleration				
Z Axis	X Axis	Y Axis	Z Axis	X Ax

Global Coordinate System

No

Options

Use Parent

<u>Ε</u> Λ	⊔→
OU.	ПΖ

100. Hz

Bode

Log Y

Results					
2.0345 m/s	20.404 m/s²	72.358 m/s²	830.9 m/s²	1.2233e-0	
	65. Hz				
2.9507°	92.405 °	-87.714 °	92.951 °	-87.59	
2.0318 m/s	-0.85615 m/s²	2.8867 m/s²	-42.772 m/s ²	5.1329e-0	
0.10473 m/s	20.386 m/s ²	-72.3 m/s²	829.8 m/s ²	-1.2222e-	

FIGURE 49 Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > DeformationFrequencyResponseDIMM5z

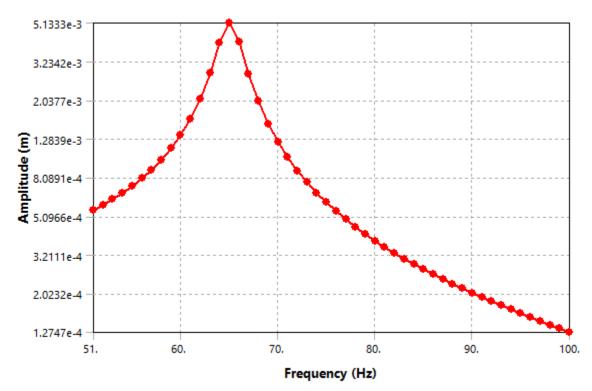


FIGURE 50
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > VelocityFrequencyResponseDIMM6x

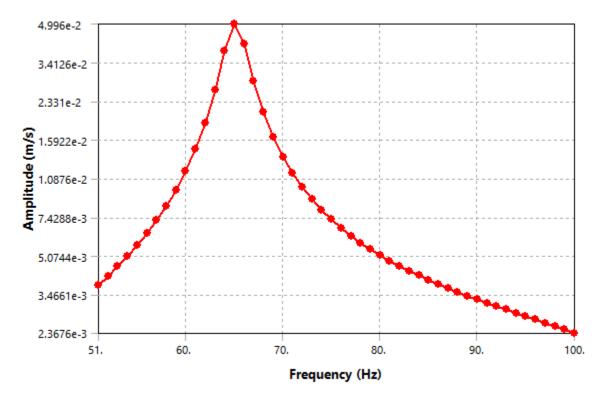


FIGURE 51
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > VelocityFrequencyResponseDIMM6y

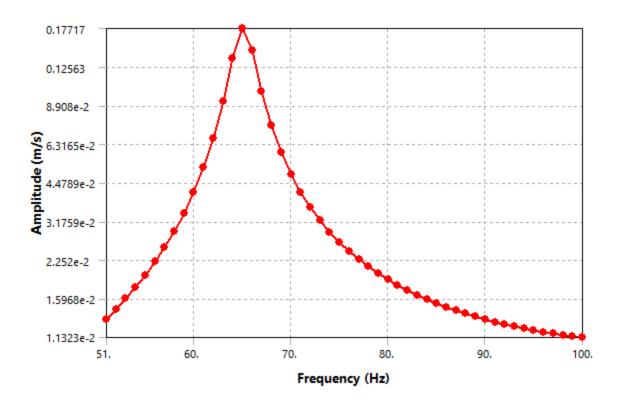


FIGURE 52
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > VelocityFrequencyResponseDIMM6z

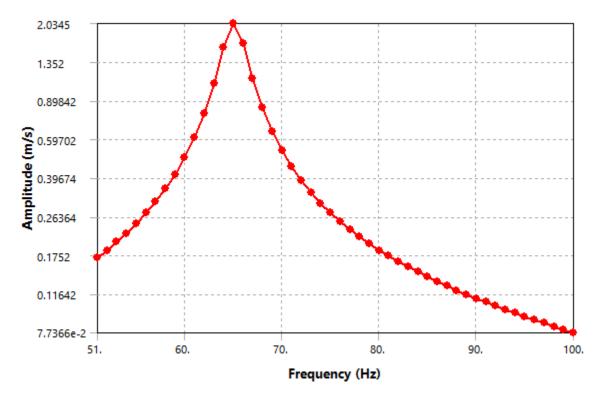


FIGURE 53
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > AccelerationFrequencyResponseDIMM6x

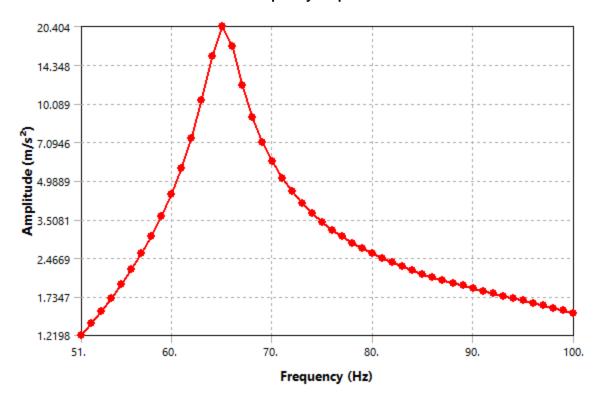


FIGURE 54
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > AccelerationFrequencyResponseDIMM6y

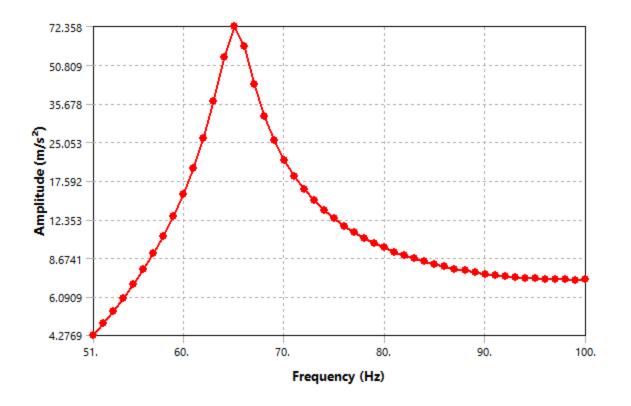


FIGURE 55
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > AccelerationFrequencyResponseDIMM6z

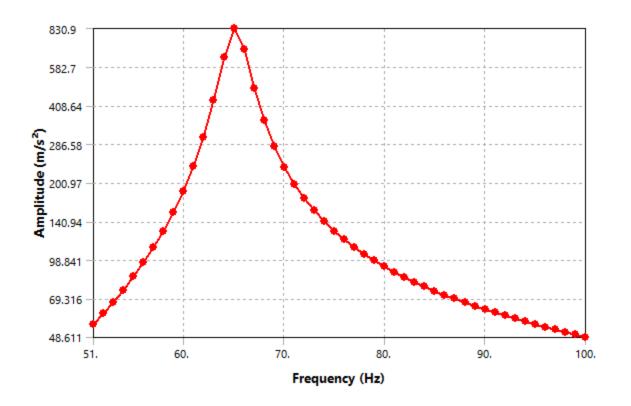


FIGURE 56
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > DeformationFrequencyResponseDIMM6x

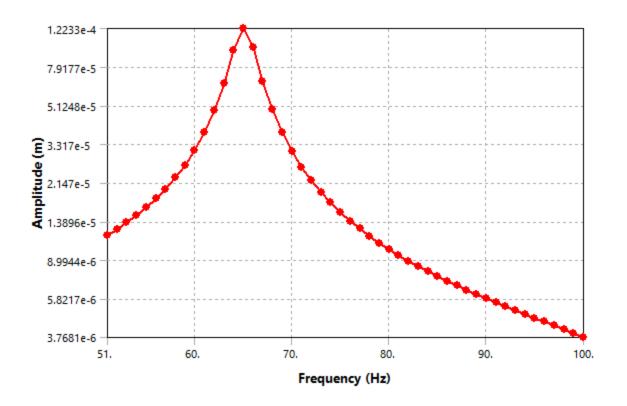


FIGURE 57
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > DeformationFrequencyResponseDIMM6y

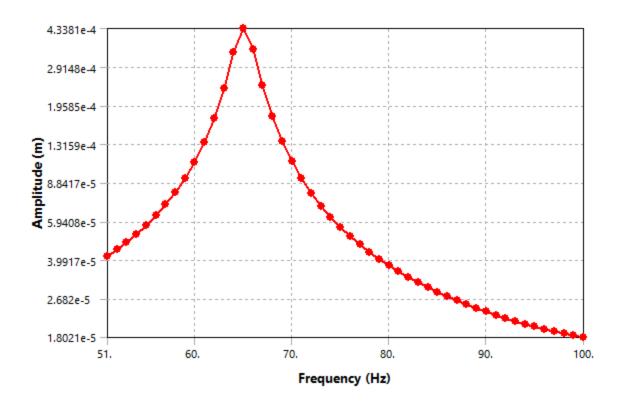


FIGURE 58
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > DeformationFrequencyResponseDIMM6z

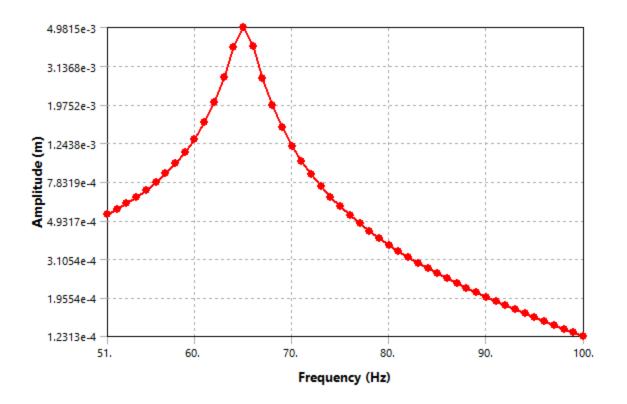


FIGURE 59
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > VelocityFrequencyResponseDIMM7x

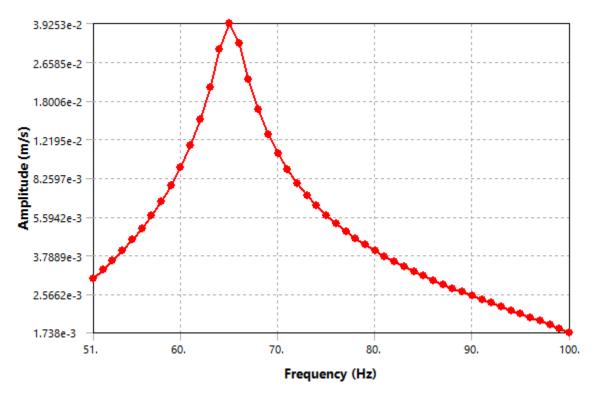


TABLE 70 Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > Result Charts erationFrequencyRespons | AccelerationFrequencyRespons | DeformationFrequencyRespons | DeformationFrequ

eDIMM7y	eDIMM7z	eDIMM7x	eDIMM7y	Deformation
		Solved		
		Scope		
		Geometry Selection		
		1 Body		
		Use Average		
		Definition		
rectional Acceleration			Directional Deformation	
Y Axis	Z Axis	X Axis	Y Axis	
		Global Coordinate System		
		No		
		Options		
		Use Parent		
		50. Hz		
		100. Hz		
		Bode		
		Log Y		
		Results		
72.826 m/s²	805.95 m/s²	9.6112e-005 m	4.3662e-004 m	4.8
	1	65. Hz	1	ı
-87.69 °	92.959 °	-87.559 °	92.31 °	
2.936 m/s ²	-41.603 m/s²	4.093e-006 m	-1.7602e-005 m	2.4

FIGURE 60
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > VelocityFrequencyResponseDIMM7y

-9.6025e-005 m

4.3626e-004 m

-4.8

804.87 m/s²

-72.767 m/s²

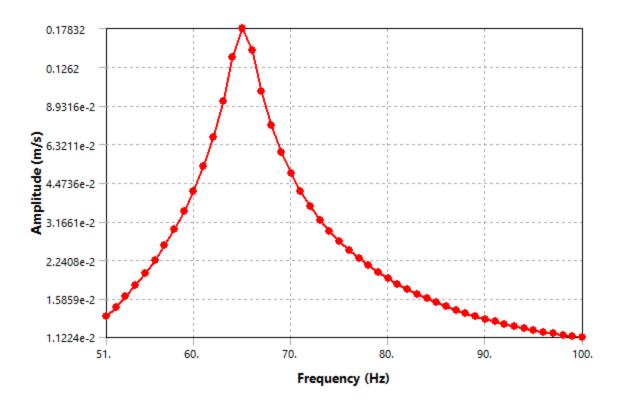


FIGURE 61
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > VelocityFrequencyResponseDIMM7z

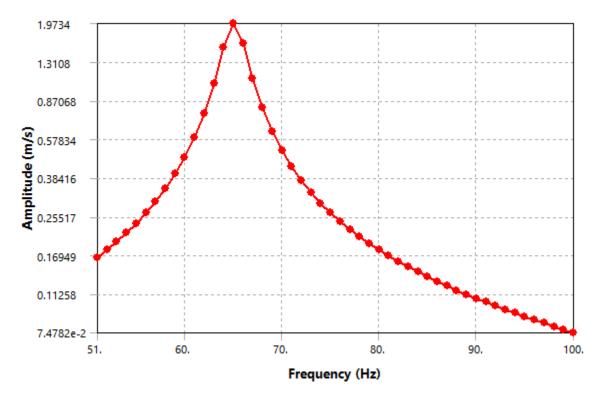


FIGURE 62
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > AccelerationFrequencyResponseDIMM7x

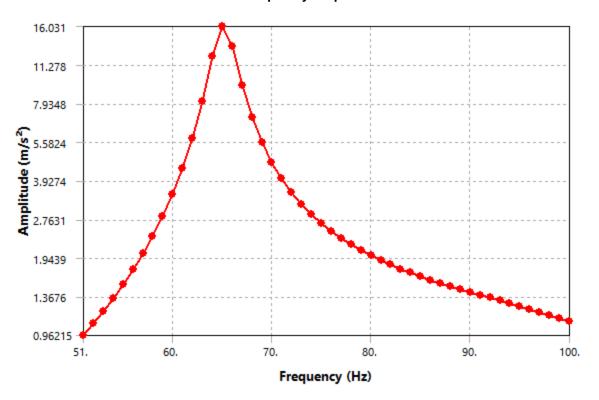


FIGURE 63
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > AccelerationFrequencyResponseDIMM7y

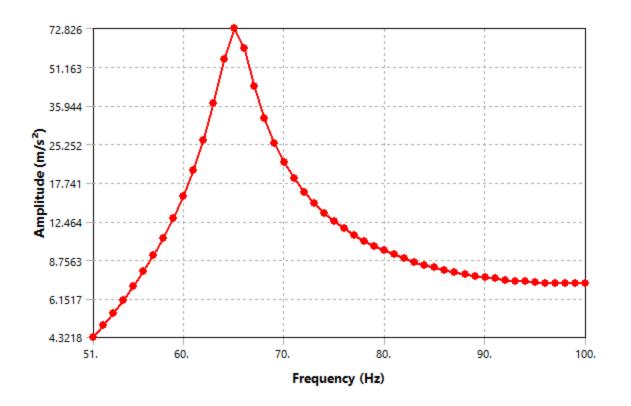


FIGURE 64
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > AccelerationFrequencyResponseDIMM7z

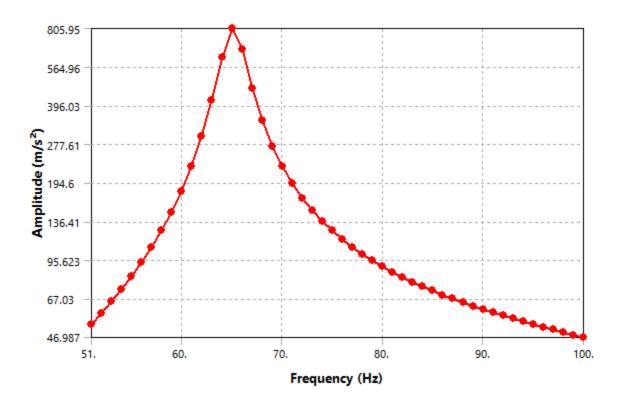


FIGURE 65
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > DeformationFrequencyResponseDIMM7x

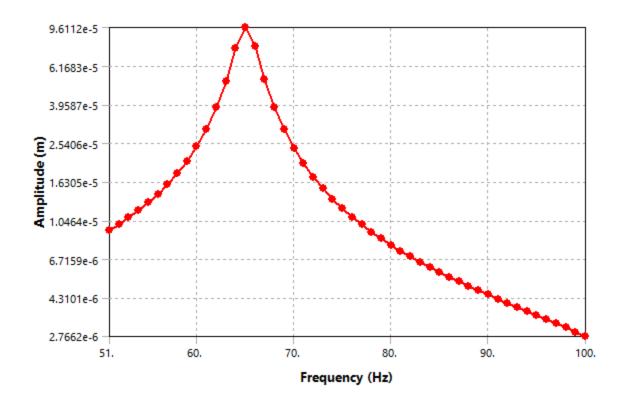


FIGURE 66
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > DeformationFrequencyResponseDIMM7y

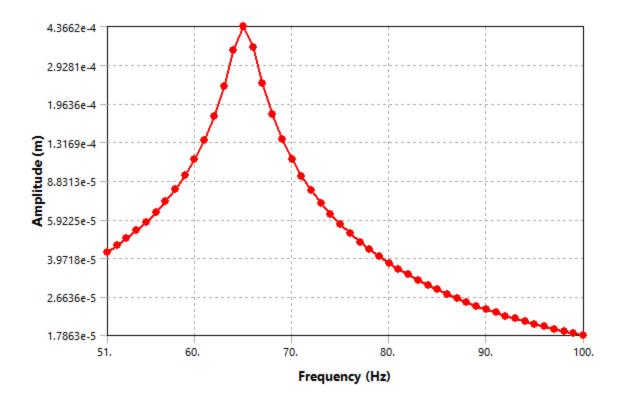


FIGURE 67
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > DeformationFrequencyResponseDIMM7z

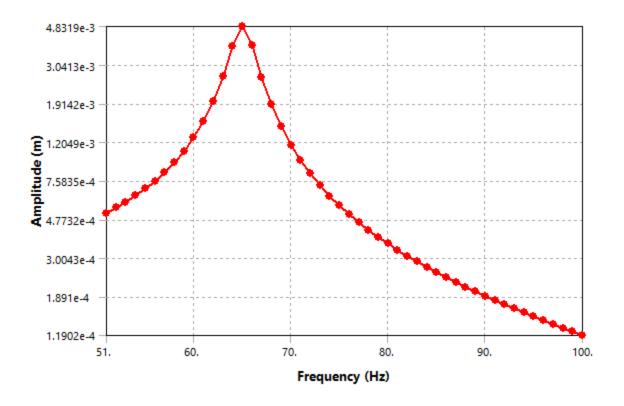


FIGURE 68
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > VelocityFrequencyResponseDIMM8x

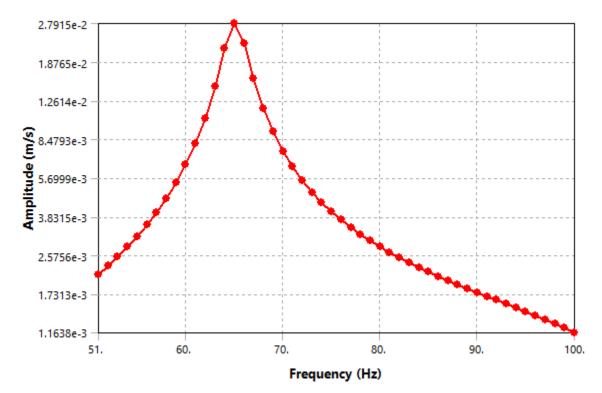


FIGURE 69
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > VelocityFrequencyResponseDIMM8y

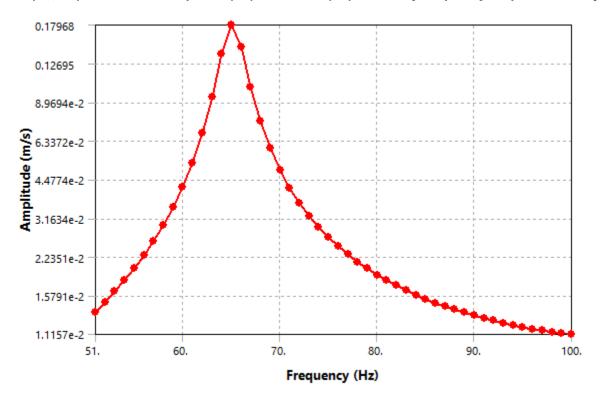


FIGURE 70
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > VelocityFrequencyResponseDIMM8z

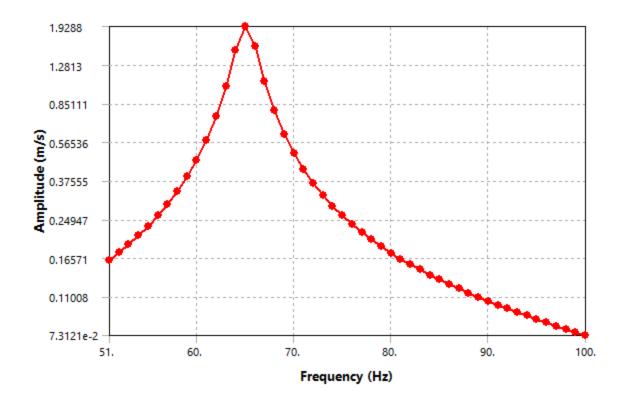


TABLE 71
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > Result Charts

tionFrequencyResponseDIMM8y | AccelerationFrequencyResponseDIMM8z | DeformationFrequencyResponseDIMM8x | DeformationFrequencyResponseDIMM8x |

. , , ,	, , ,	, , ,	•
	Sol	ved	1
	Scope		
	Geometry	Selection	
	1 B	ody	
	Use A	verage	
	Definition		
Directional Acceleration			Directiona
Y Axis	Z Axis	X Axis	Y
	Global Coord	linate System	
	N	lo	
	Options		
	Use F	Parent	
	50.	Hz	

100. Hz Bode

Log Y

Results				
73.383 m/s²	787.75 m/s²	6.8351e-005 m	4.399	
	65.	. Hz		
-87.669 °	92.963 °	-87.576 °	92	
2.9852 m/s²	-40.717 m/s²	2.891e-006 m	-1.789	
-73.322 m/s ²	786.7 m/s²	-6.829e-005 m	4.395	

FIGURE 71

Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > AccelerationFrequencyResponseDIMM8x

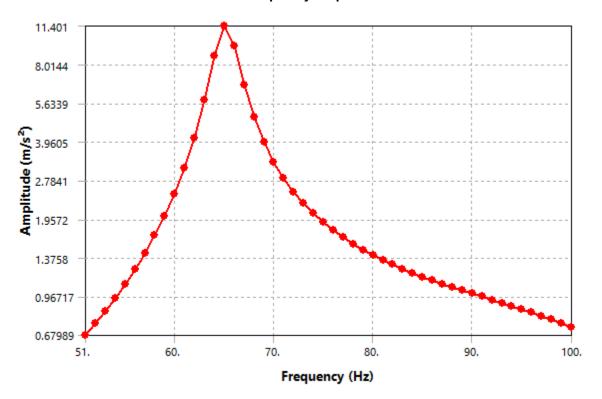


FIGURE 72 Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > AccelerationFrequencyResponseDIMM8y

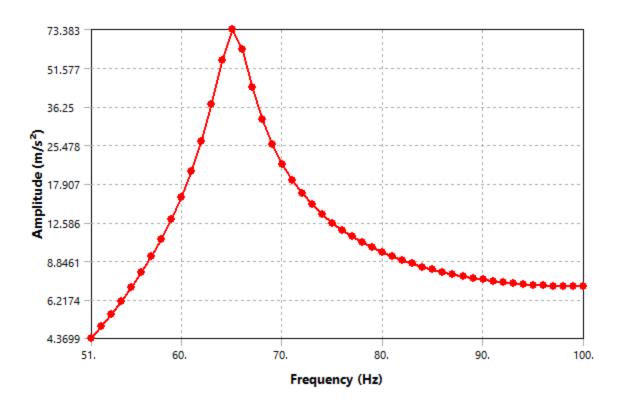


FIGURE 73
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > AccelerationFrequencyResponseDIMM8z

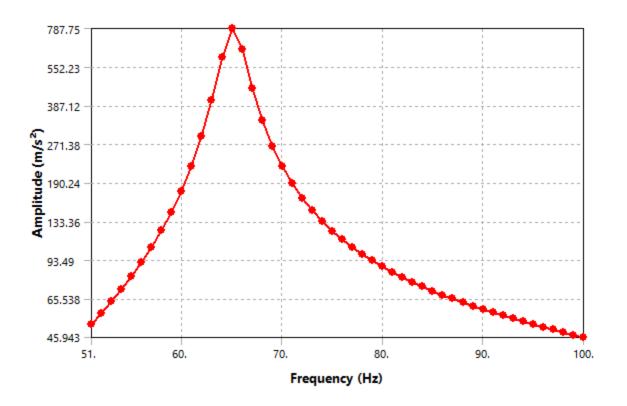


FIGURE 74
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > DeformationFrequencyResponseDIMM8x

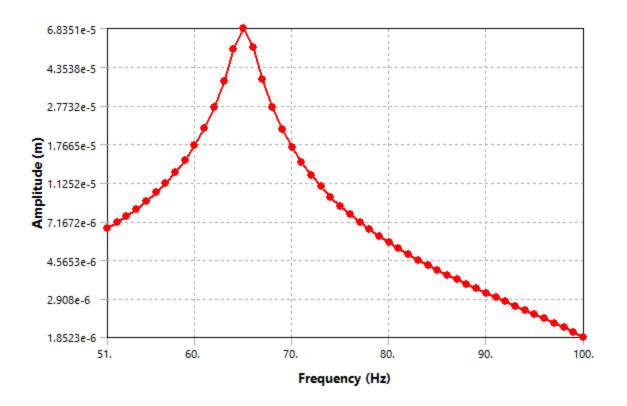


FIGURE 75
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > DeformationFrequencyResponseDIMM8y

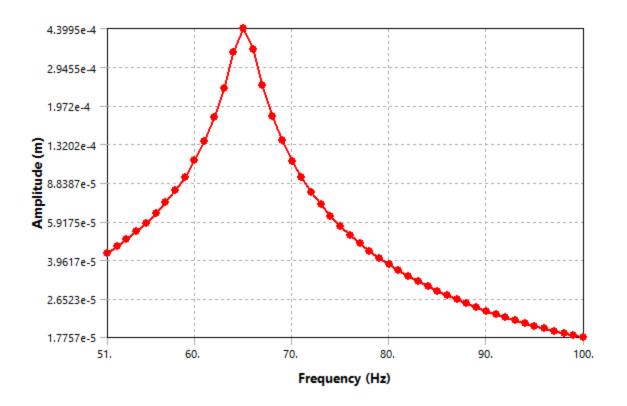
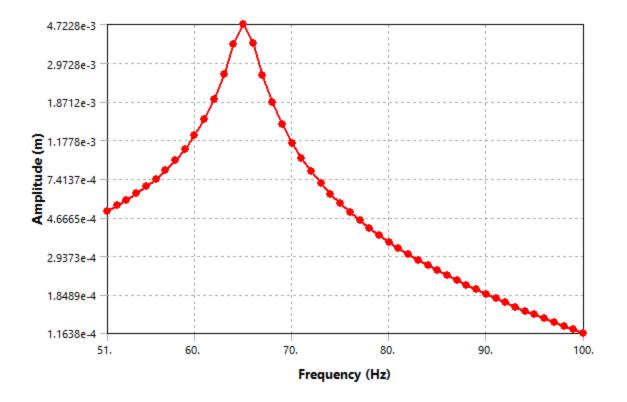


FIGURE 76
Model (A4, B4) > Harmonic Response (B5) > Solution (B6) > DeformationFrequencyResponseDIMM8z



Material Data

AISI 1020 Steel, cold rolled

TABLE 72
AISI 1020 Steel, cold rolled > Isotropic Elasticity

Young's Modulus Pa	Poisson's Ratio	Bulk Modulus Pa	Shear Modulus Pa
2.05e+011	0.29	1.627e+011	7.9457e+010

TABLE 73
AISI 1020 Steel, cold rolled > Density

Density kg m^-3 7870

TABLE 74

AISI 1020 Steel, cold rolled > Isotropic Secant Coefficient of Thermal Expansion

Coefficient of Thermal Expansion C^-1
Zero-Thermal-Strain Reference Temperature C
22

TABLE 75
AISI 1020 Steel, cold rolled > Tensile Yield Strength
Tensile Yield Strength Pa

TABLE 76

AISI 1020 Steel, cold rolled > Tensile Ultimate Strength

Tensile Ultimate Strength Pa 4.2e+008

TABLE 77

AISI 1020 Steel, cold rolled > Specific Heat Constant Pressure

Specific Heat J kg^-1 C^-1 486

TABLE 78

AISI 1020 Steel, cold rolled > Isotropic Thermal Conductivity

Thermal Conductivity W m^-1 C^-1 51.9

Aluminum 6061-T6; 6061-T651

TABLE 79

Aluminum 6061-T6; 6061-T651 > Isotropic Elasticity

Young's Modulus Pa	Poisson's Ratio	Bulk Modulus Pa	Shear Modulus Pa
6.895e+010	0.33	6.7598e+010	2.5921e+010

TABLE 80

Aluminum 6061-T6; 6061-T651 > Density

Density kg m^-3 2700

TABLE 81

Aluminum 6061-T6; 6061-T651 > Isotropic Secant Coefficient of Thermal Expansion

Coefficient of Thermal Expansion C^-1			
Zero-Thermal-Strain Reference Temperature C			
22			

TABLE 82

Aluminum 6061-T6; 6061-T651 > Tensile Yield Strength

Tensile Yield Strength Pa

TABLE 83

Aluminum 6061-T6; 6061-T651 > Tensile Ultimate Strength

Tensile Ultimate Strength Pa 3.103e+008

TABLE 84

Aluminum 6061-T6; 6061-T651 > Specific Heat Constant Pressure

Specific Heat J kg^-1 C^-1 896

TABLE 85

Aluminum 6061-T6; 6061-T651 > Isotropic Thermal Conductivity

Thermal Conductivity W m^-1 C^-1
167.2

Nylon

TABLE 86 Nylon > Isotropic Elasticity

Young's Modulus Pa	Poisson's Ratio	Bulk Modulus Pa	Shear Modulus Pa
3.e+009	0.42	6.25e+009	1.0563e+009

TABLE 87 Nylon > Density Density kg m^-3 1160

TABLE 88

Nylon > Isotropic Secant Coefficient of Thermal Expansion

Coefficient of Thermal Expansion C^-1
Zero-Thermal-Strain Reference Temperature C
22

TABLE 89 Nylon > Tensile Yield Strength

Tensile Yield Strength Pa

TABLE 90 Nylon > Tensile Ultimate Strength Tensile Ultimate Strength Pa

7.e+007

TABLE 91 Nylon > Specific Heat Constant Pressure Specific Heat J kg^-1 C^-1

950

TABLE 92 Nylon > Isotropic Thermal Conductivity

Thermal Conductivity W m^-1 C^-1 0.285

Glass Epoxy Composite

TABLE 93 Glass Epoxy Composite > Isotropic Elasticity

Young's Modulus Pa	Poisson's Ratio	Bulk Modulus Pa	Shear Modulus Pa
2.14e+010	0.3	1.7833e+010	8.2308e+009

TABLE 94 **Glass Epoxy Composite > Density** Density kg m^-3 7300

TABLE 95

Glass Epoxy Composite > Isotropic Secant Coefficient of Thermal Expansion

Coefficient of Thermal Expansion C^-1
Zero-Thermal-Strain Reference Temperature C
22

TABLE 96

Glass Epoxy Composite > Tensile Yield Strength

Tensile Yield Strength Pa

TABLE 97

Glass Epoxy Composite > Tensile Ultimate Strength

Tensile Ultimate Strength Pa 3.19e+008

TABLE 98

Glass Epoxy Composite > Specific Heat Constant Pressure

Specific Heat J kg^-1 C^-1 1620

TABLE 99

Glass Epoxy Composite > Isotropic Thermal Conductivity

Thermal Conductivity W m^-1 C^-1 1.19

LCP

TABLE 100

LCP > Isotropic Elasticity

Young's Modulus Pa	Poisson's Ratio	Bulk Modulus Pa	Shear Modulus Pa
2.e+009	0.36	2.381e+009	7.3529e+008

TABLE 101 LCP > Density

Density kg m^-3

TABLE 102

LCP > Isotropic Secant Coefficient of Thermal Expansion

Coefficient of Thermal Expansion C^-1
Zero-Thermal-Strain Reference Temperature C
22

TABLE 103

LCP > Tensile Yield Strength

Tensile Yield Strength Pa

TABLE 104

LCP > Tensile Ultimate Strength

Tensile Ultimate Strength Pa 1.17e+008

TABLE 105

LCP > Specific Heat Constant Pressure

Specific Heat J kg^-1 C^-1 1850

TABLE 106

LCP > Isotropic Thermal Conductivity

Thermal Conductivity W m^-1 C^-1
0.18

Oxygen-free Electronic Copper (OFE), UNS C10100, H00 Temper, flat prod

TABLE 107

Oxygen-free Electronic Copper (OFE), UNS C10100, H00 Temper, flat prod > Isotropic Elasticity

Young's Modulus Pa	Poisson's Ratio	Bulk Modulus Pa	Shear Modulus Pa
1.15e+011	0.31	1.0088e+011	4.3893e+010

TABLE 108

Oxygen-free Electronic Copper (OFE), UNS C10100, H00 Temper, flat prod > Density

Density kg m^-3 1653.5

TABLE 109

Oxygen-free Electronic Copper (OFE), UNS C10100, H00 Temper, flat prod > Isotropic Secant Coefficient of Thermal Expansion

Coefficient of Thermal Expansion C^-1
Zero-Thermal-Strain Reference Temperature C
22

TABLE 110

Oxygen-free Electronic Copper (OFE), UNS C10100, H00 Temper, flat prod > Tensile Yield Strength
Tensile Yield Strength Pa

TABLE 111

Oxygen-free Electronic Copper (OFE), UNS C10100, H00 Temper, flat prod > Tensile Ultimate Strength

Tensile Ultimate Strength Pa 2.5e+008

TABLE 112

Oxygen-free Electronic Copper (OFE), UNS C10100, H00 Temper, flat prod > Specific Heat Constant Pressure

Specific Heat J kg^-1 C^-1 385

TABLE 113

Oxygen-free Electronic Copper (OFE), UNS C10100, H00 Temper, flat prod > Isotropic Thermal Conductivity

Thermal Conductivity W m^-1 C^-1
391

ABS

TABLE 114 ABS > Isotropic Elasticity

Young's Modulus Pa	Poisson's Ratio	Bulk Modulus Pa	Shear Modulus Pa
2.e+009	0.36	2.381e+009	7.3529e+008

TABLE 115 ABS > Density

Density kg m^-3

TABLE 116

ABS > Isotropic Secant Coefficient of Thermal Expansion

Coefficient of Thermal Expansion C^-1
Zero-Thermal-Strain Reference Temperature C
22

TABLE 117 ABS > Tensile Yield Strength Tensile Yield Strength Pa

TABLE 118 ABS > Tensile Ultimate Strength

Tensile Ultimate Strength Pa 4.e+007

TABLE 119

ABS > Specific Heat Constant Pressure

Specific Heat J kg^-1 C^-1 1850

TABLE 120

ABS > Isotropic Thermal Conductivity

Thermal Conductivity W m^-1 C^-1 0.18