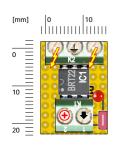
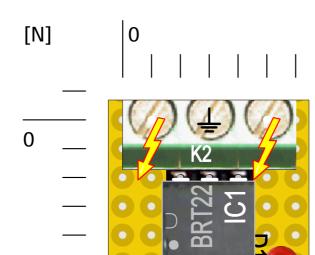
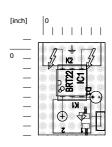


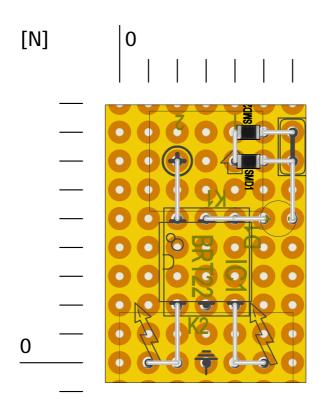
Projekt: maschinen_ssr_schütz [Schieber2xBee]

Abmessungen: 60,00 x 40,00 mm



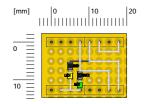


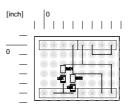


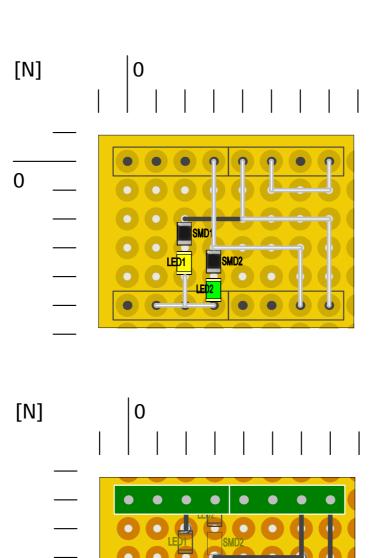


Projekt: maschinen_ssr_schütz [AC_SwitchNpktE1]

Abmessungen: 17,70 x 24,50 mm







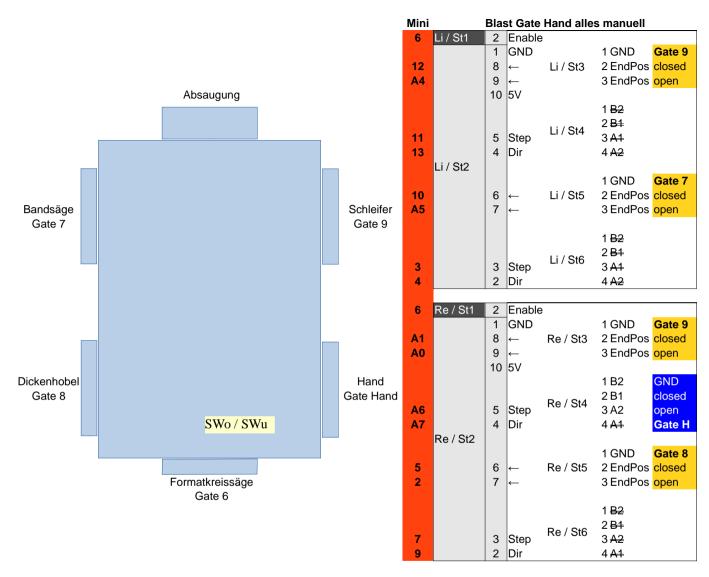
0

Benennung	K2 4polig	Strommessung		D-Sub	D-Sub I	Buchse Kabel
				1	bn	SW
5V	4	Buchse / Stecker	rot	2	rt	bn
				3	or	rt
A3	3		orange	4	ge	or
A2	2		braun	5	gn	ge
Strom +		rt		6	bl	gn
			rot	7	li	rs
GND	1	SW	schwarz	8	gr	li
			sw	9	SW	ws

Buchse / Stecker

Benennung	K1 5polig	K3 8polig	(Farbe)	D-Sub
5V	5		rot	1
SCL	4		orange	2
SDA	3		gelb	3
SCK		7	blau	4
MISO		5	gelb	5
MOSI		6	grün	6
SDA		8	violet	7
RST		2	braun	8
GND	1		schwarz	9

PinNr.	Netztei	Ί	Pin Out	Controller	Ardu Pin	Pin In	SM-Platine Li	Pin Out		Pin In	SM-Platine Re	Pin Out	PinNr.	EndPos
K1P1	L	~220V;12V												
K1P2	N	~220V;12V												
L/OD /	000/													
	SSR1	24V 4A												
K2P2	Vcc	5V - (24V)												
K3P1	SSR2	24V 4A												
K3P2	Vcc	5V - (24V)												
		(,												
			K1P1	Digital (INT)	2					St2P7	Gate 8 open	St5P3	St5P3	
			K1P2	Digital	5					St2P6	Gate 8 closed	St5P2	St5P2	
			K1P3 K1P4	Digital Digital	7 9					St2P3 St2P2	Step Dir	Gate 8 SM St6 Gate 8 SM St6	St6P1-4	B1;B2;A1;A2
K5P1	GND	GND	K2P1	GND	3				₽	OIZI Z	DII	Gale o Sivi Sto	St3&4&5P1	GND
K5P2		OND	K2P2	OptSSR (AD2)	A2				Ste				Olda-adi 1	GND
	SSR2		K2P3	Alarm (AD3)	А3				űe hr					
K5P4	Vcc	5V (DC/DC)	K2P4	Vcc					Schrittmotor Ansteuerung rechts					
			K4P1	GND					ng no	St2P1	GND			
			K4P2	Digital	6	St1P2	Enable SM		re to	St1P2	Enable SM			
			K4P3	Vcc					뀵	St2P10				
			K5P1	Analog	A0				S	St2P9	Gate 6 open	St3P3	St3P3	
			K5P2 K5P3	Analog Analog	A1 A6	Nur An Eingän	aloge			St2P8 St2P5	Gate 6 closed Step	St3P2 Gate 6 SM St4	St3P2 St4P2	Gate H closed
			K5P4	Analog Analog	A7	Lingan	gc			St2P4	Dir	Gate 6 SM St4	St4P3	Gate H open
			K7P1	GND	7	St2P1	GND			0.2		Cate Com Ct.	St3&5P1	GND
			K7P2	Digital (INT)	3	St2P3	Step	Gate 7 SM St6					St6P1-4	B1;B2;A1;A2
			K7P3	SDA (AD4)	A4	St2P9	Gate 9 open	St3P3	>				St3P3	
			K7P4	SCL (AD5)	A5	St2P7	Gate 7 open	St5P3	ns co				St5P3	
			K7P5	Vcc		St2P10	Vcc		te Sch					
			K9P1	Vcc		0:00=	5.	0 . = 01.45	Schrittmotor Ansteuerung links					D. D. A
				Digital	4 I	St2P2	Dir	Gate 7 SM St6					St6P1-4	B1;B2;A1;A2
			K9P3 <i>K9P4</i>	GND	_				g li					
			K9P5	- Digital	12	St2P8	Gate 9 closed	St3P2	Ž i				St3P2	
			K9P6	Digital Digital	11	St2P5	Step	Gate 9 SM St4	S					D4-D0-44-40
			K9P7	Digital	13	St2P4	Dir	Gate 9 SM St4					St4P1-4	B1;B2;A1;A2
			K9P8	Digital	10	St2P6	Gate 7 closed	St5P2					St5P2	



EndPos. = Endstellung unten oder oben (bei Schrittmotor mit Drehrichtung)

Mini	Blast	Gate S	Schrittmotor	automatisch	+ Hand
6	Li / St1	2 En	able		
		1 GI	ND	1 GND	Gate 9
12		8 ←	Li / St3	2 EndPos	closed open
A4		9		3	I2C SDA
		<mark>10</mark> 5∨	′		
				1 B2	M2
			Li / St4	2 B1	IVI∠
11		5 St	ep LI / St4	3 A1	
13		4 Dii	r	4 A2	M1
	Li / St2				
				1 GND	Gate 7
10		6←	Li / St5	2 EndPos	closed open
A5		7		3	I2C SLC
				1 B2	110
				2 B1	M2
3		3 St	ep Li/St6	3 A1	
4		2 Dii		4 A2	M1
6	Re / St1	2 En	able		
6	Re / St1	2En		1 GND	Gate 9
6 A1	Re / St1			3 2 EndPos	closed open
	Re / St1	1 GI	ND	3 2 EndPos	
A 1	Re / St1	1 GI 8 ←	ND Re / St	3 2 EndPos	closed open
A 1	Re / St1	1 GN 8 ← 9	ND Re / St	3 2 EndPos	closed open H closed
A 1	Re / St1	1 GN 8 ← 9 10 5 V	ND Re / St	3 2 EndPos 3 Gate 1 B2 2 B1	closed open
A 1	Re / St1	1 GN 8 ← 9	ND Re / St	3 2 EndPos 3 Gate 1 B2 2 B1	closed open H closed
A1 A6	Re / St1	1 GN 8 ← 9 10 5 V	Re / St.	3 2 EndPos 3 Gate 1 B2 2 B1	closed open H closed
A1 A6	Re / St1	1 GN 8 ← 9 10 5 ∨ 5 Sto	Re / St.	3 2 EndPos 3 Gate 1 B2 2 B1 4 3 A2	closed open H closed
A1 A6		1 GN 8 ← 9 10 5 ∨ 5 Sto	Re / St.	3 2 EndPos 3 Gate 1 B2 2 B1 3 A2 4 A1 1 GND	M2 M1 Gate 8
A1 A6		1 GN 8 ← 9 10 5 ∨ 5 Sto	Re / St.	3 2 EndPos 3 Gate 1 B2 2 B1 3 A2 4 A1 1 GND 5 2 EndPos	M2 M1 Gate 8 closed open
A1 A6 2 A0		1 Gf 8 ← 9 10 5 V 5 Std 4 Did	Re / St	3 2 EndPos 3 Gate 1 B2 2 B1 3 A2 4 A1 1 GND 5 2 EndPos	M2 M1 Gate 8
A1 A6 2 A0		1 Gf 8 ← 9 10 5 ∨ 5 Std 4 Did	Re / St	3 2 EndPos 3 Gate 1 B2 2 B1 3 A2 4 A1 1 GND 5 2 EndPos	M2 M1 Gate 8 closed open
A1 A6 2 A0		1 Gf 8 ← 9 10 5 ∨ 5 Std 4 Did	Re / St	3 2 EndPos 3 Gate 1 B2 2 B1 3 A2 4 A1 1 GND 5 2 EndPos	M2 M1 Gate 8 closed open H open
A1 A6 2 A0		1 Gf 8 ← 9 10 5 ∨ 5 Std 4 Did	Re / Sta	3 2 EndPos 3 Gate 1 B2 2 B1 3 A2 4 A1 1 GND 2 EndPos 3 Gate 1 B2 2 B1	M2 M1 Gate 8 closed open
A1 A6 2 A0		1 Gf 8 ← 9 10 5 ∨ 5 Std 4 Did	Re / Sta	3 2 EndPos 3 Gate 1 B2 2 B1 3 A2 4 A1 1 GND 2 EndPos 3 Gate 1 B2 2 B1	M2 M1 Gate 8 closed open H open