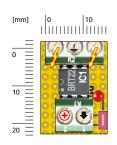
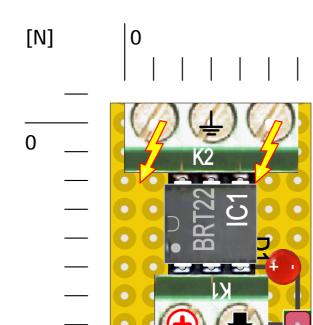
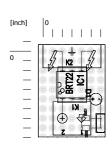


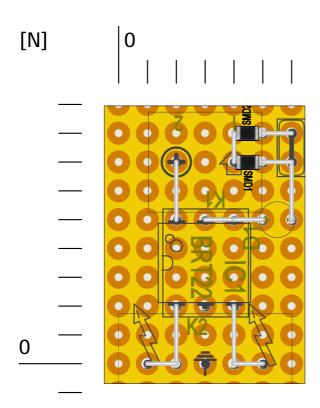
Projekt: maschinen_ssr_schütz [Schieber2xBee]

Abmessungen: 60,00 x 40,00 mm



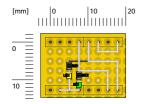


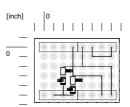


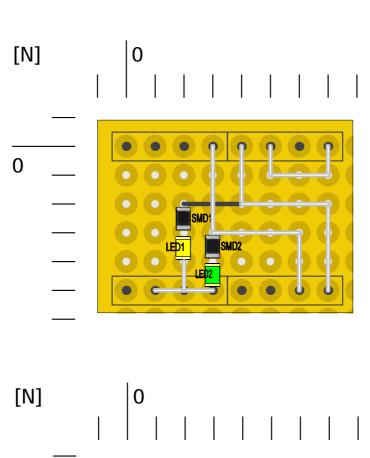


 $Projekt: maschinen_ssr_sch\"{u}tz \ [AC_SwitchNpktE1]$

Abmessungen: 17,70 x 24,50 mm







GeräteVerdrahtung

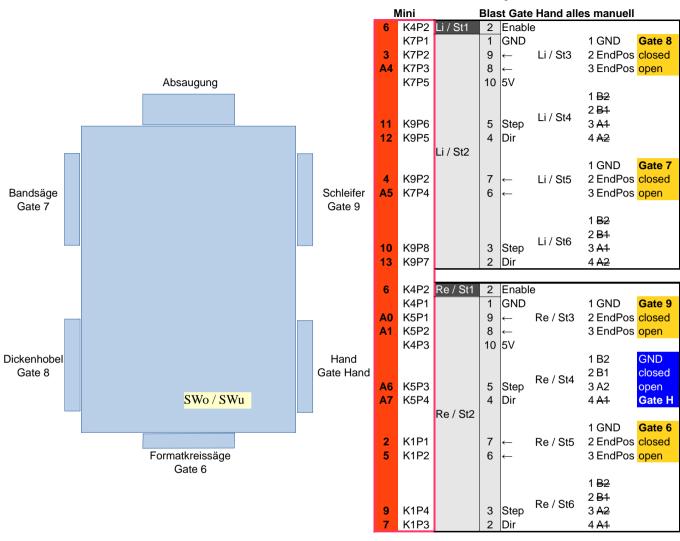
Benennung	K2 4polig	Strommessung		D-Sub	D-Sub E	Buchse Kabel
				/1	bn	sw
5V	4	Buchse / Stecker	rot	2	rt	bn
				3	or	rt
A3	3		orange	4	ge	or
A2	2		braun	5	gn	ge
Strom +		rt		6	bl	gn
			rot	7	li	rs
GND	1	sw	schwarz	8	gr	li
			sw	9	SW	WS

Buchse / Stecker

Benennung	K1 5polig	K3 8polig	(Farbe)	D-Sub
5V	5		rot	1
SCL	4		orange	2
SDA	3		gelb	3
SCK		7	blau	4
MISO		5	gelb	5
MOSI		6	grün	6
SDA		8	violet	7
RST		2	braun	8
GND	1		schwarz	9

PinNr.	Netztei	1	Pin Out	Controller	Ardu Pin	Pin In	SM-Platine Li	Pin Out		Pin In	SM-Platine Re	Pin Out	PinNr.	EndPos
K1P1	L	~220V;12V												
K1P2	N	~220V;12V												
1/05/		- 0.7.44												
K2P1		24V 4A												
K2P2	Vcc	5V - (24V)												
K3P1	SSR2	24V 4A												
K3P2	Vcc	5V - (24V)												
		,												
			K1P1	Digital (INT)	2					St2P7	Gate 6 closed	St5P2	St5P2	
			K1P2 K1P3	Digital (PWM)	5					St2P6 St2P2	Gate 6 open	St5P3	St5P3	
			K1P3 K1P4	Digital Digital (PWM)	7 9					St2P2 St2P3	Dir Sten	Gate 6 SM St6	St6P1-4	B1;B2;A1;A2
K5P1	GND	GND	K2P1	GND	J				ă	OLZI O	Otop		St3&4&5P1	GND
K5P2			K2P2	OptSSR (AD2)	A2				Ste				Olou ruor r	U
K5P3	SSR2		K2P3	Alarm (AD3)	А3				hri					
K5P4	Vcc	5V (DC/DC)	K2P4	Vcc					Schrittmotor Ansteuerung rechts					
			K4P1	GND					not g	St2P1	GND			
			K4P2	Digital (PWM)	6	St1P2	Enable SM		ec ec		Enable SM	Ì		
			K4P3	Vcc	10				hts	St2P10		0,000	Overno	
			K5P1 K5P2	Analog Analog	A0 A1	Nur An	nalogo		0,	St2P9 St2P8	Gate 9 closed Gate 9 open	St3P2 St3P3	St3P2 St3P3	
			K5P3	Analog	A6	Eingän				St2P5	(Step)		St4P3	Gate H open
			K5P4	Analog	A7					St2P4	(Dir)	Gate 9 SM St4	St4P2	Gate H closed
			K7P1	GND		St2P1	GND						St3&5P1	GND
			K7P2	Digital (INT, PWM)	3	St2P9	Gate 8 closed	St3P2					St3P2	
			K7P3	SDA (AD4)	A4	St2P8	Gate 8 open	St3P3	≥				St3P3	
			K7P4 K7P5	SCL (AD5)	A5	St2P6 St2P10	Gate 7 open	St5P3	St				St5P3	
			K9P1	Vcc		OLZI IV	VCC		Schrittmotor steuerung lin					
			K9P2	Digital	4	St2P7	Gate 7 closed	St5P2	er itt				St5P2	
			K9P3	GND					no					•
			K9P4	-	-				Schrittmotor Ansteuerung links					
			K9P5	Digital	12	St2P4	Dir	Gate 8 SM St4	ıks				St4P1-4	B1;B2;A1;A2
			K9P6	Digital (PWM)	11	St2P5	Step	Cato o om ota	•				3(4) 1 4	2,72,711, 712
			K9P7 K9P8	Digital Digital (PWM)	13 10	St2P2 St2P3	Dir Step	Gate 7 SM St6					St4P1-4	B1;B2;A1;A2
			NJFO	Digital (F VVIVI)	10	SIZES	σισμ		I				l	

BlasgatePosition



	Vlini	Blast	Gat	e Sch	rittmotor a	automatiscl	h + Hand
6	K4P2	Li / St1	2	Enabl	е		
	K7P1		1	GND		1 GND	Gate 8
3	K7P2		9	<==	Li / St3	2 EndPos	closed open
A4	K7P3		8	\leftrightarrow		3	I2C SDA
	K7P5		10	5V			
						1 B2	140
					6	2 B1	M2
11	K9P6		5	Step	Li / St4	3 A1	
12	K9P5			Dir		4 A2	M1
		Li / St2					
		,				1 GND	Gate 7
4	K9P2		7	<==	Li / St5		closed open
A5	K7P4			>	217 010	3	I2C SLC
70	1071 -					Ü	120 020
						1 B2	
						2 B1	M2
10	K9P8		3	Step	Li / St6	3 A1	
13	K9P7			Dir		4 A2	M1
13	NOF I			ווט		4 //2	
6	KAD2	Po / St1	2	Enabl	٥		
6		Re / St1		Enabl	е	1 GND	Cato 0
	K4P1	Re / St1	1	GND		1 GND	Gate 9
Α0	K4P1 K5P1	Re / St1	1 9	GND <==	e Re / St3	2 EndPos	closed open
	K4P1 K5P1 K5P3	Re / St1	1 9 8	GND <== ←		2 EndPos	
Α0	K4P1 K5P1	Re / St1	1 9	GND <== ←		2 EndPos 3 Gate	closed open
Α0	K4P1 K5P1 K5P3	Re / St1	1 9 8	GND <== ←		2 EndPos 3 Gate 1 B2	closed open
A0 A6	K4P1 K5P1 K5P3 K4P3	Re / St1	1 9 8 10	GND <== ← 5V		2 EndPos 3 Gate 1 B2 2 B1	closed open H closed
A0 A6	K4P1 K5P1 K5P3 K4P3	Re / St1	1 9 8 10	GND <== ← 5V	Re / St3	2 EndPos 3 Gate 1 B2 2 B1 3 A2	closed open H closed
A0 A6	K4P1 K5P1 K5P3 K4P3		1 9 8 10	GND <== ← 5V	Re / St3	2 EndPos 3 Gate 1 B2 2 B1	closed open H closed
A0 A6	K4P1 K5P1 K5P3 K4P3	Re / St1	1 9 8 10	GND <== ← 5V	Re / St3	2 EndPos 3 Gate 1 B2 2 B1 3 A2 4 A1	closed open H closed M2 M1
A0 A6 5 2	K4P1 K5P1 K5P3 K4P3 K1P2 K1P1		1 9 8 10 5 4	GND <== ← 5V Step Dir	Re / St3	2 EndPos 3 Gate 1 B2 2 B1 3 A2 4 A1 1 GND	closed open H closed M2 M1 Gate 6
A0 A6 5 2	K4P1 K5P1 K5P3 K4P3 K1P2 K1P1		1 9 8 10 5 4	GND <== ← 5V Step Dir <==	Re / St3	2 EndPos 3 Gate 1 B2 2 B1 3 A2 4 A1 1 GND 2 EndPos	M2 M1 Gate 6 closed open
A0 A6 5 2	K4P1 K5P1 K5P3 K4P3 K1P2 K1P1		1 9 8 10 5 4	GND <== ← 5V Step Dir	Re / St3	2 EndPos 3 Gate 1 B2 2 B1 3 A2 4 A1 1 GND 2 EndPos	closed open H closed M2 M1 Gate 6
A0 A6 5 2	K4P1 K5P1 K5P3 K4P3 K1P2 K1P1		1 9 8 10 5 4	GND <== ← 5V Step Dir <==	Re / St3	2 EndPos 3 Gate 1 B2 2 B1 3 A2 4 A1 1 GND 2 EndPos 3 Gate	M2 M1 Gate 6 closed open
A0 A6 5 2	K4P1 K5P1 K5P3 K4P3 K1P2 K1P1		1 9 8 10 5 4	GND <== ← 5V Step Dir <==	Re / St3	2 EndPos 3 Gate 1 B2 2 B1 3 A2 4 A1 1 GND 2 EndPos 3 Gate 1 B2	M2 M1 Gate 6 closed open
A0 A6 5 2 A1 A7	K4P1 K5P1 K5P3 K4P3 K1P2 K1P1 K5P2 K5P4		1 9 8 10 5 4	GND <== ← 5V Step Dir <== ←	Re / St3	2 EndPos 3 Gate 1 B2 2 B1 3 A2 4 A1 1 GND 2 EndPos 3 Gate 1 B2 2 B1	M2 M1 Gate 6 closed open H open
A0 A6 5 2	K4P1 K5P1 K5P3 K4P3 K1P2 K1P1		1 9 8 10 5 4	GND <== ← 5V Step Dir <==	Re / St4 Re / St5	2 EndPos 3 Gate 1 B2 2 B1 3 A2 4 A1 1 GND 2 EndPos 3 Gate 1 B2	M2 M1 Gate 6 closed open H open

EndPos. = Endstellung unten oder oben (bei Schrittmotor mit Drehrichtung)