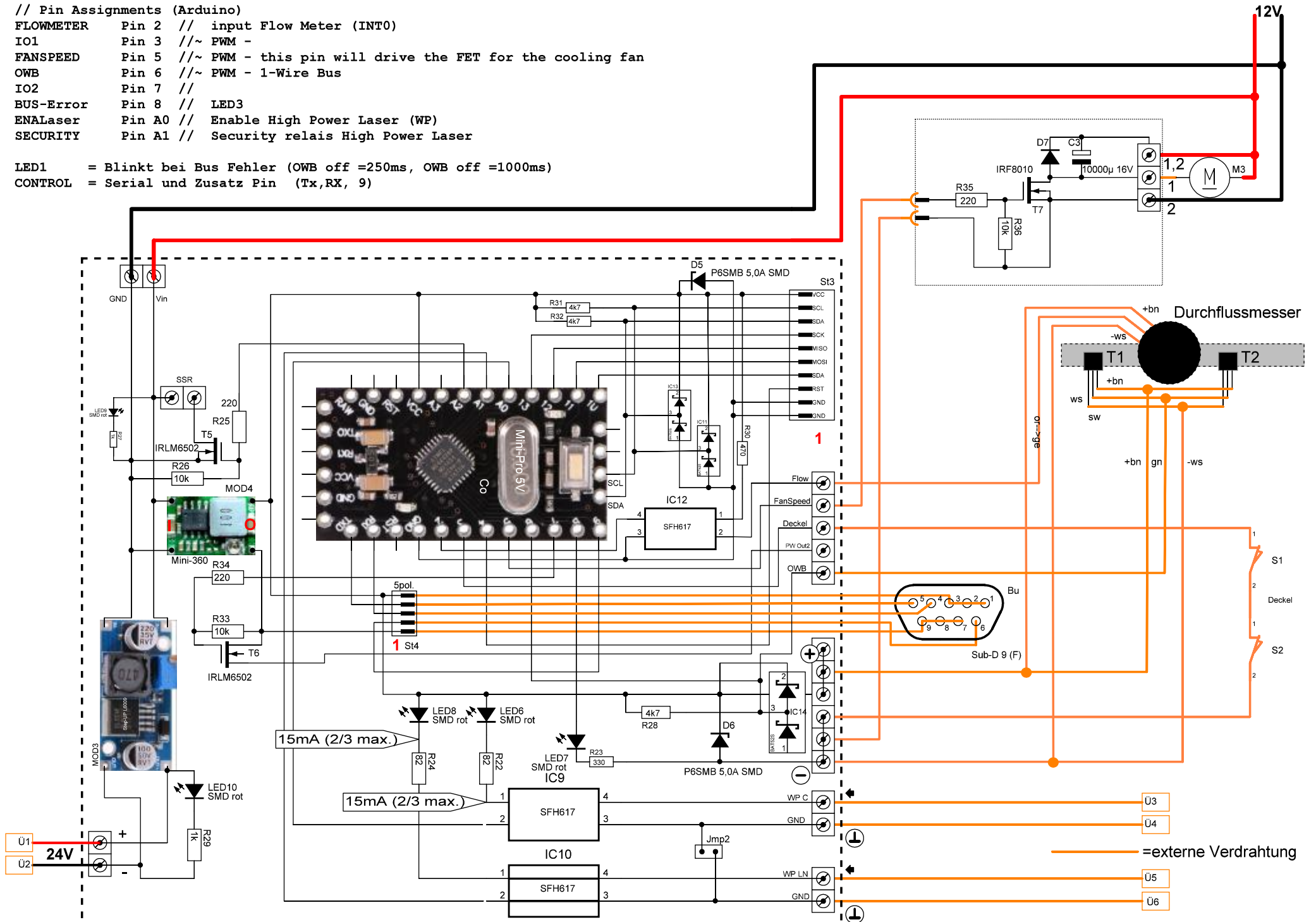
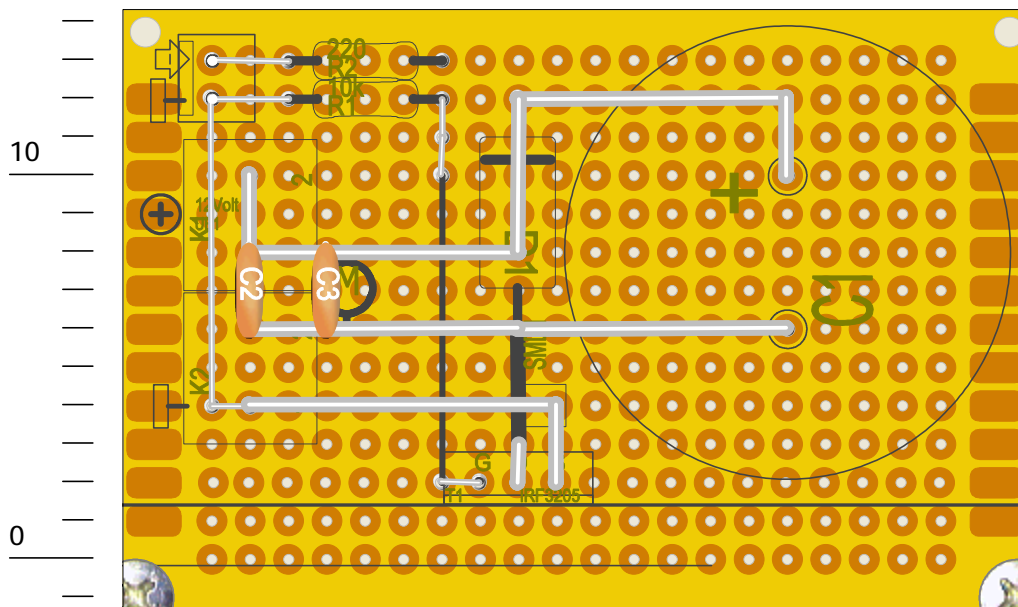
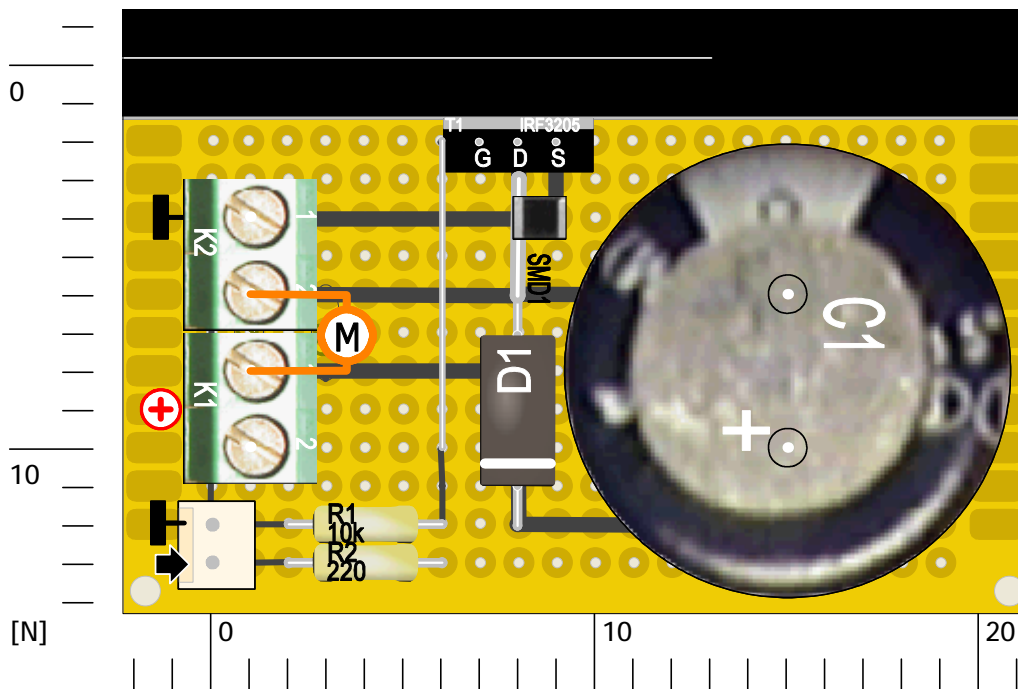
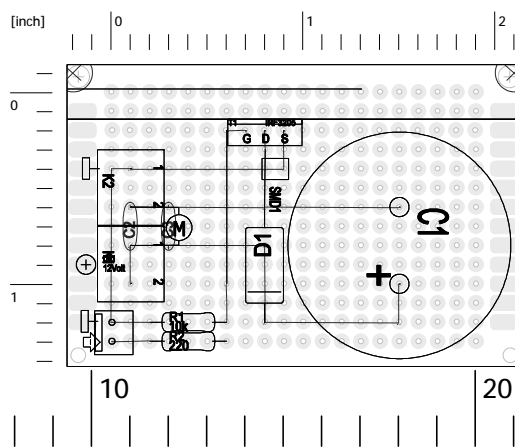
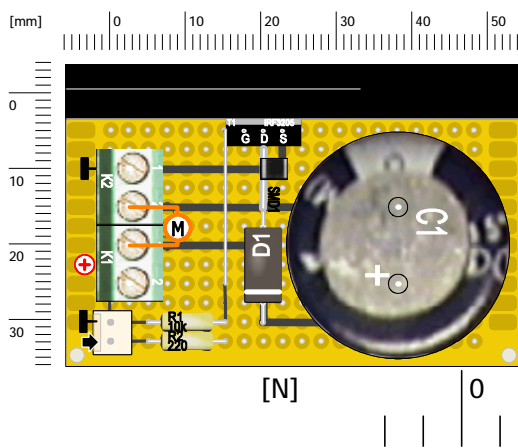


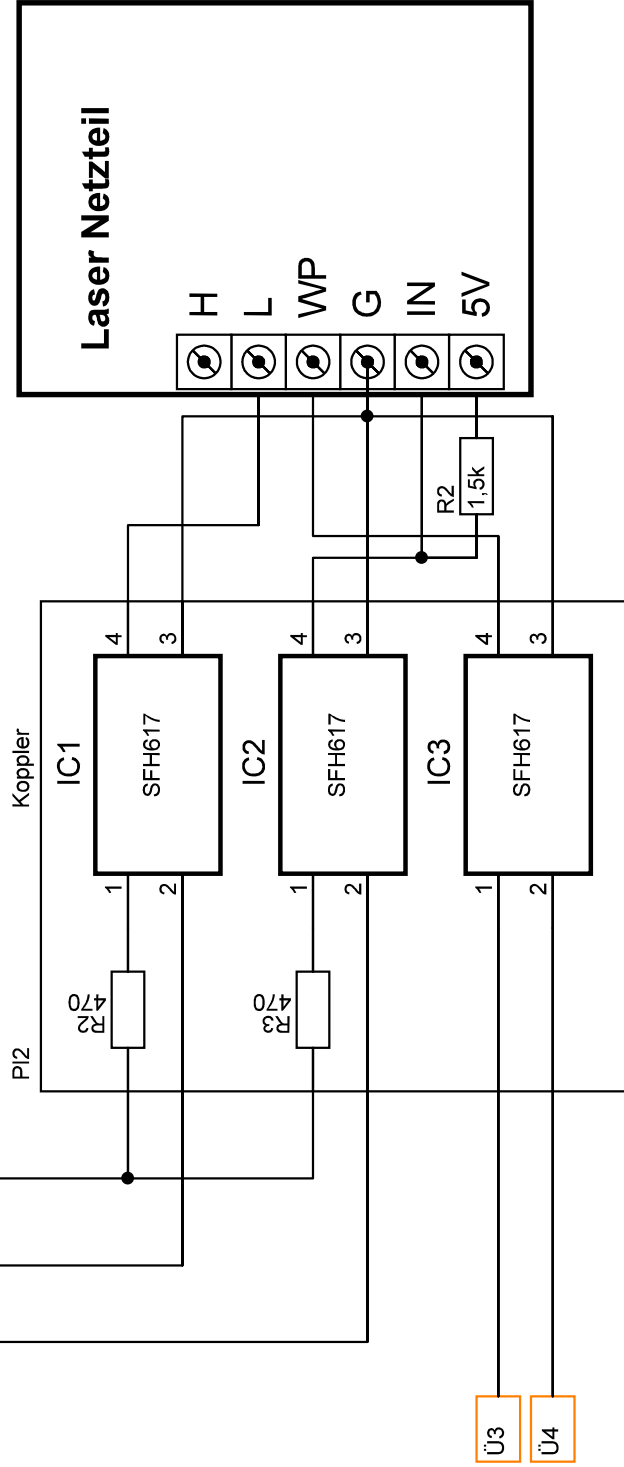
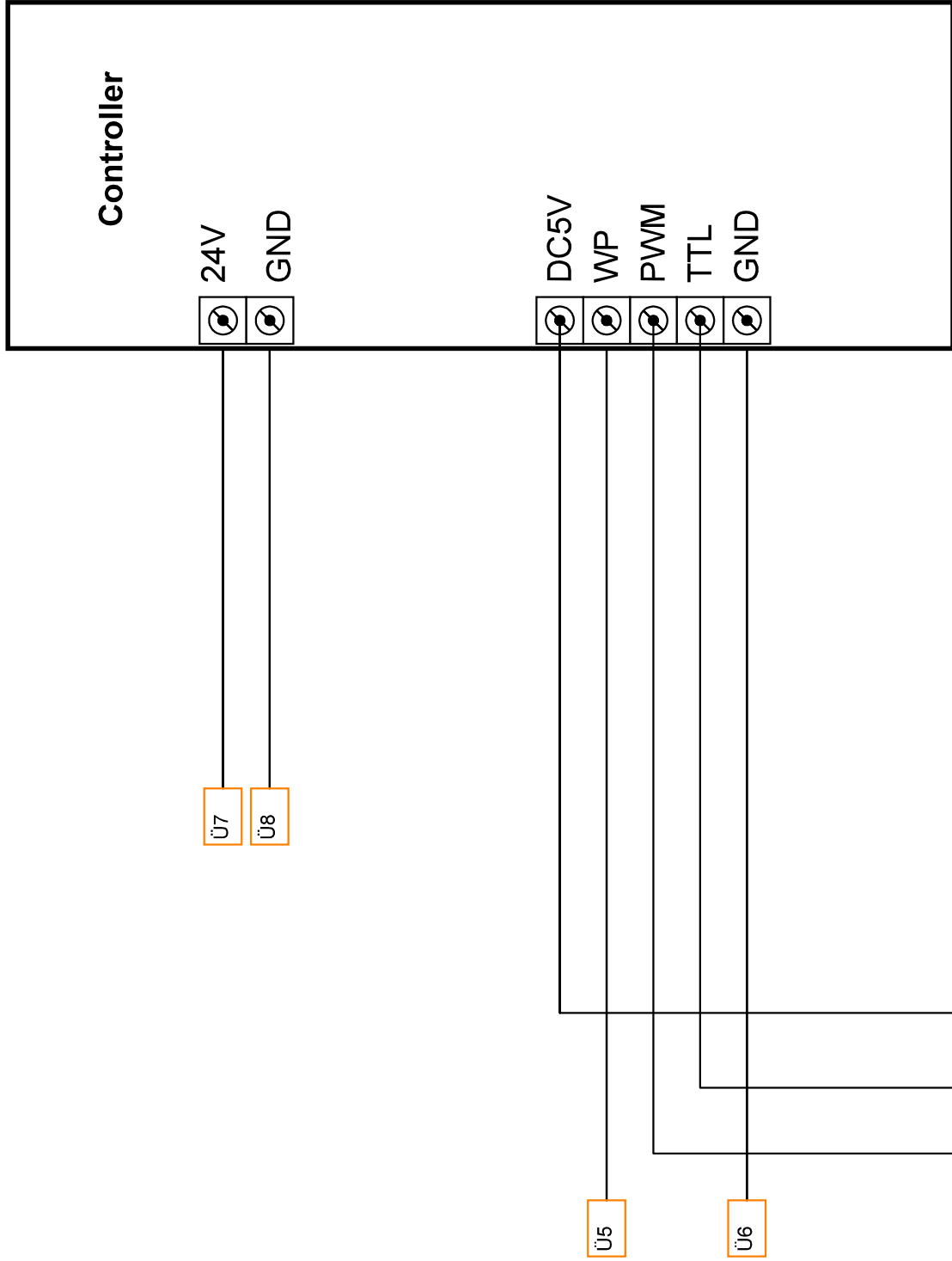
```
// Pin Assignments (Arduino)
FLOWMETER   Pin 2  // input Flow Meter (INT0)
IO1          Pin 3  //~ PWM -
FANSPEED     Pin 5  //~ PWM - this pin will drive the FET for the cooling fan
OWB          Pin 6  //~ PWM - 1-Wire Bus
IO2          Pin 7  //
BUS-Error    Pin 8  // LED3
ENALaser     Pin A0 // Enable High Power Laser (WP)
SECURITY     Pin A1 // Security relais High Power Laser
```

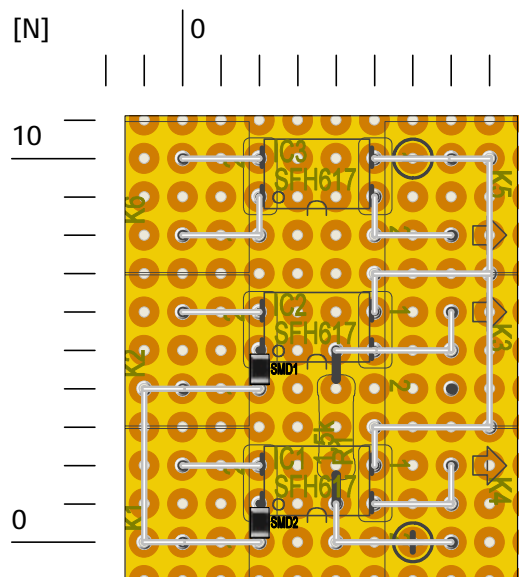
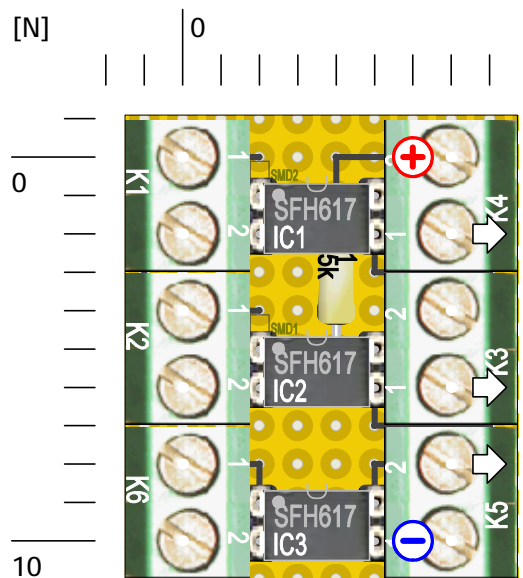
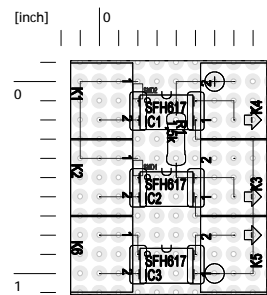
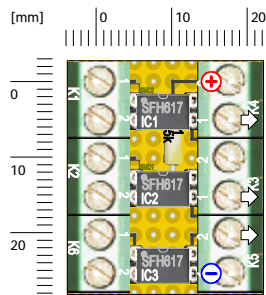
LED1 = Blinkt bei Bus Fehler (OWB off =250ms, OWB off =1000ms)

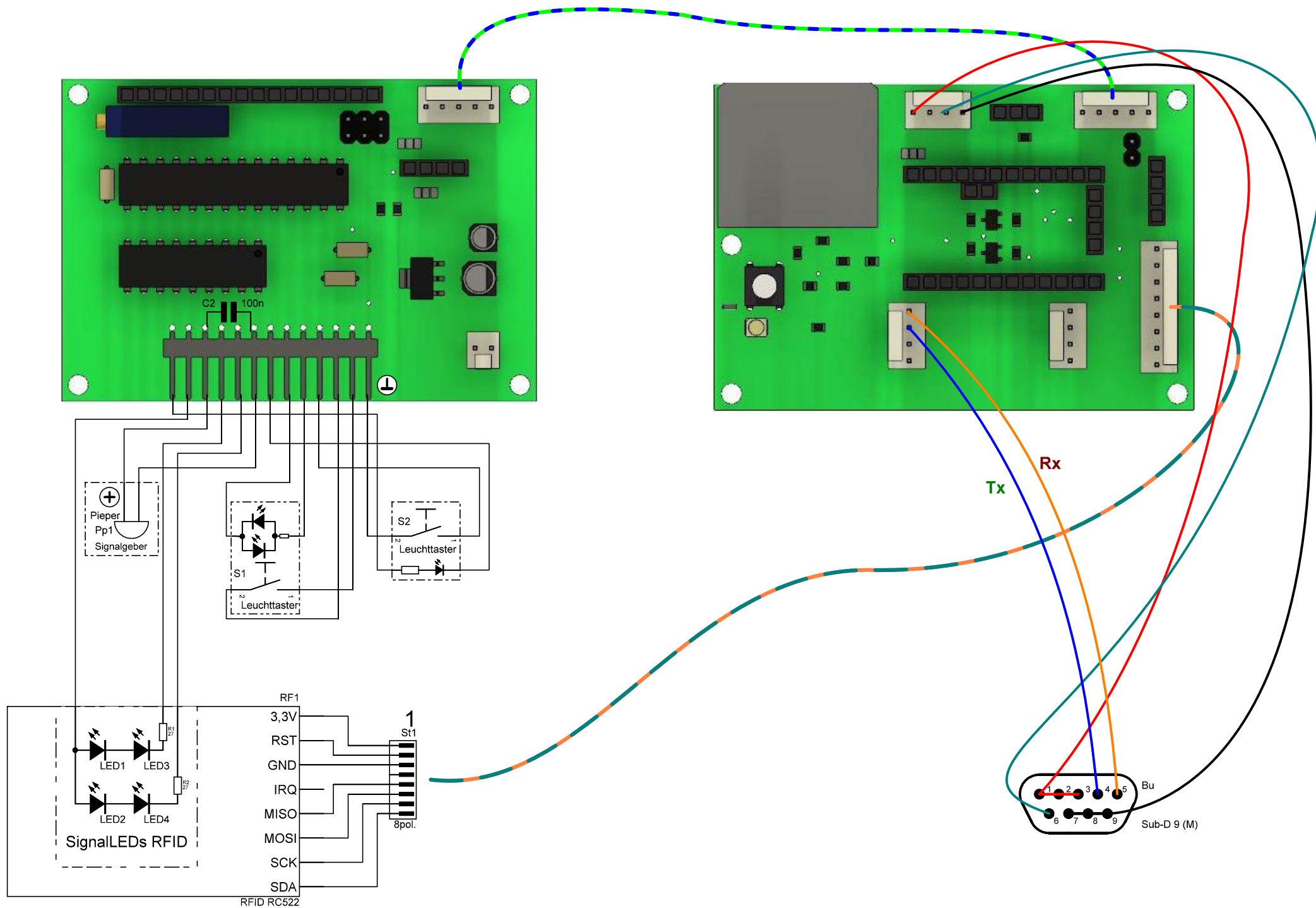
CONTROL = Serial und Zusatz Pin (Tx,RX, 9)





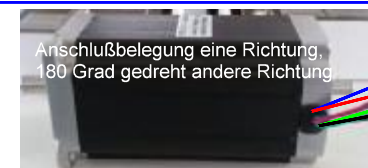








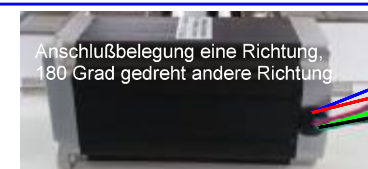
Y-Achse rechts



Anschlußbelegung eine Richtung, 180 Grad gedreht andere Richtung



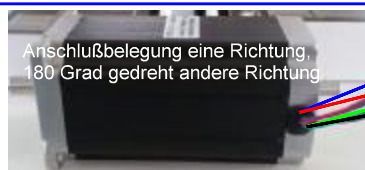
Y-Achse links



Anschlußbelegung eine Richtung, 180 Grad gedreht andere Richtung



X-Achse



Anschlußbelegung eine Richtung, 180 Grad gedreht andere Richtung

+ Z-Achse



36V

Motoren



12V



36V

Motoren

