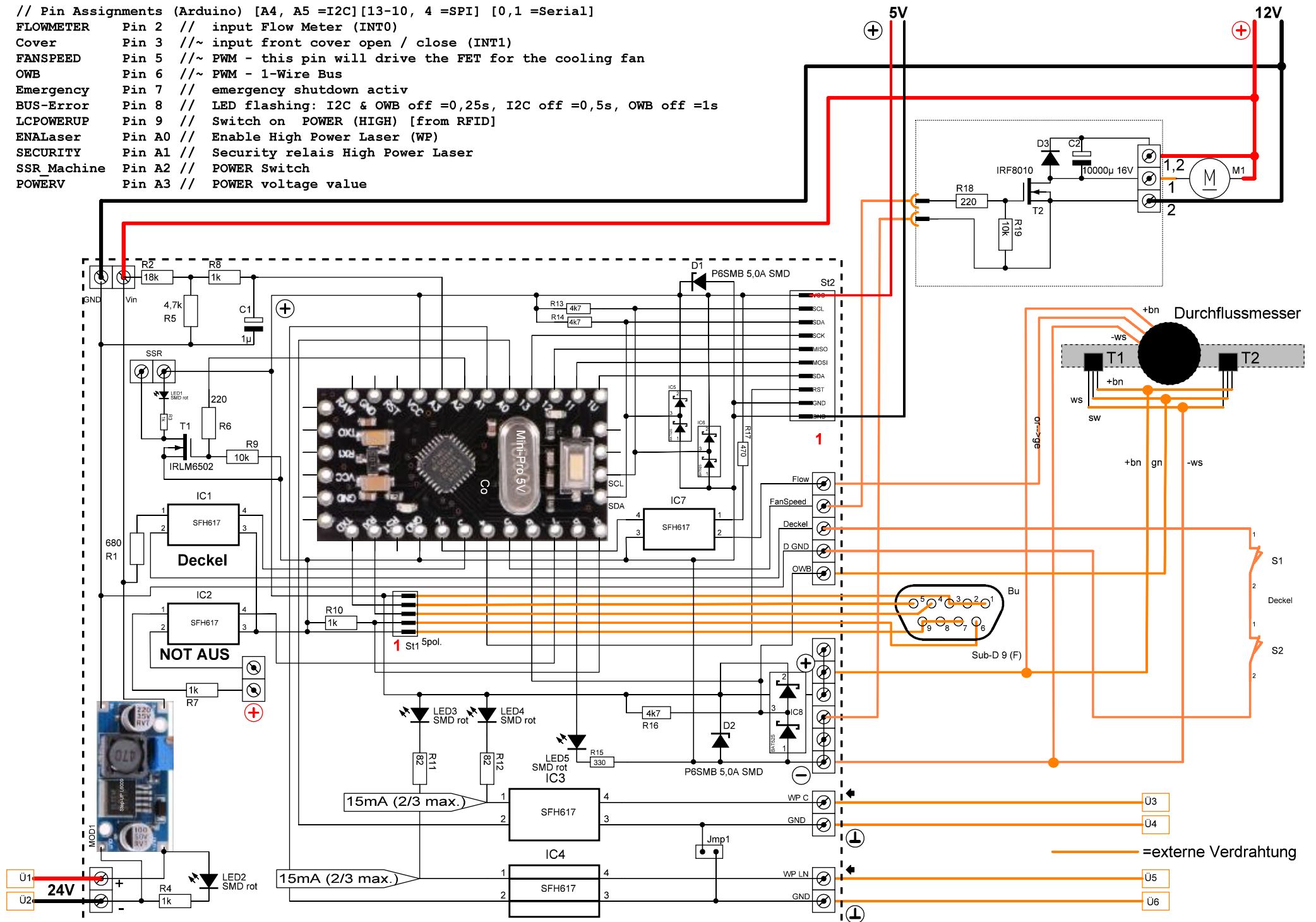
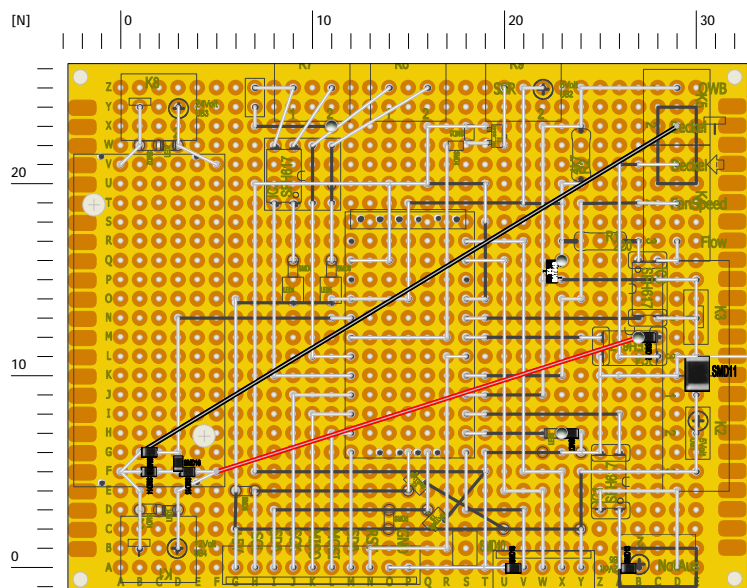
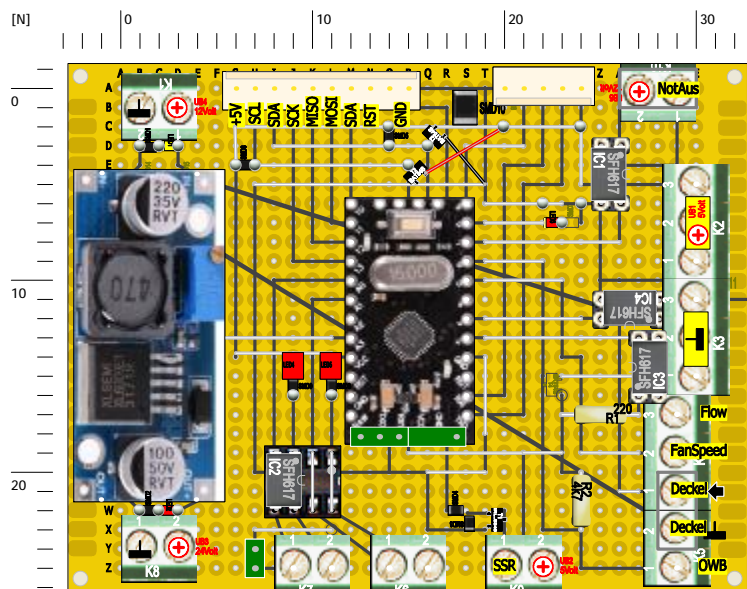
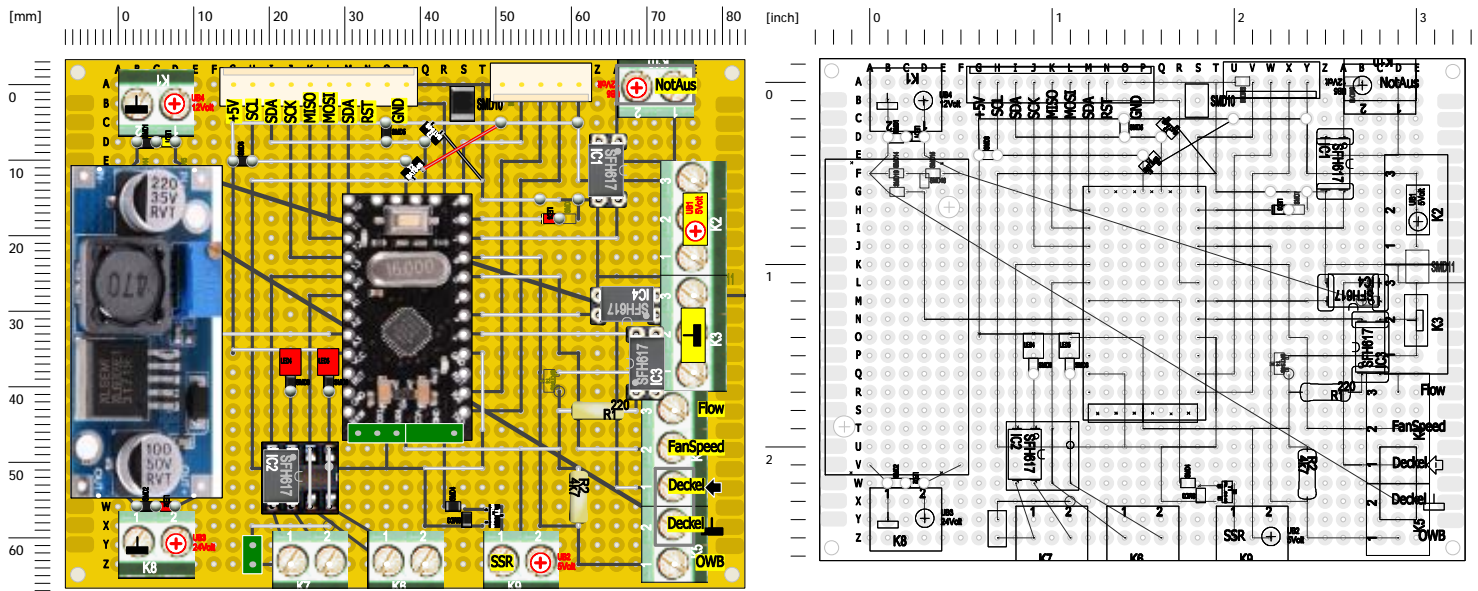
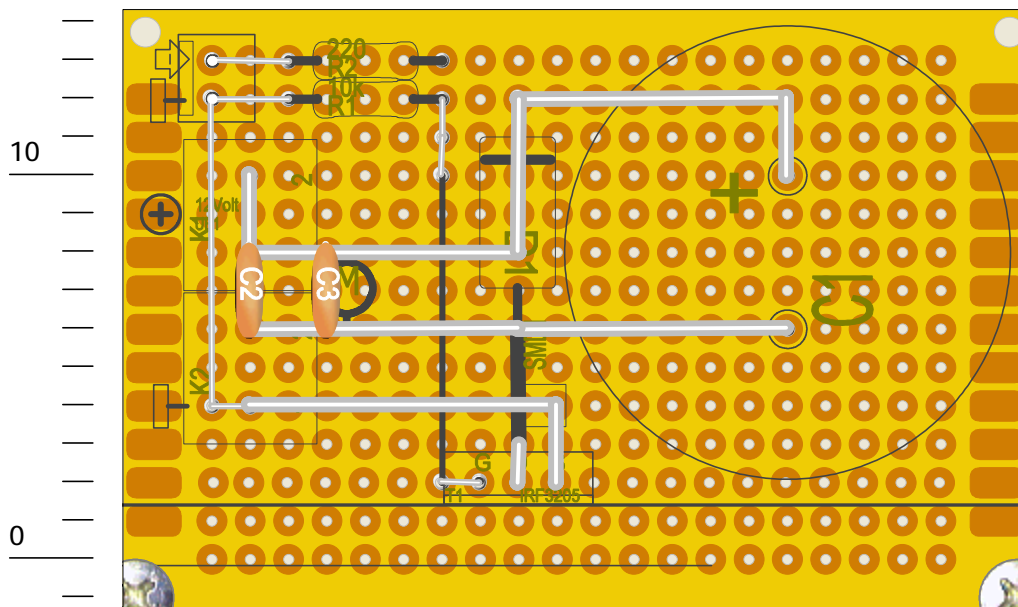
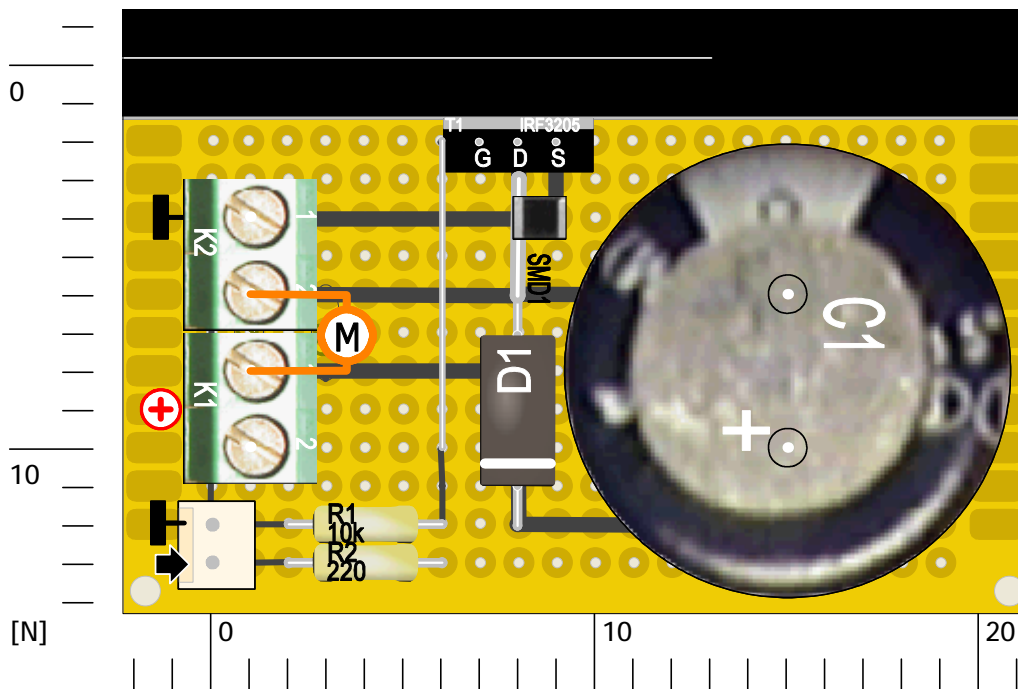
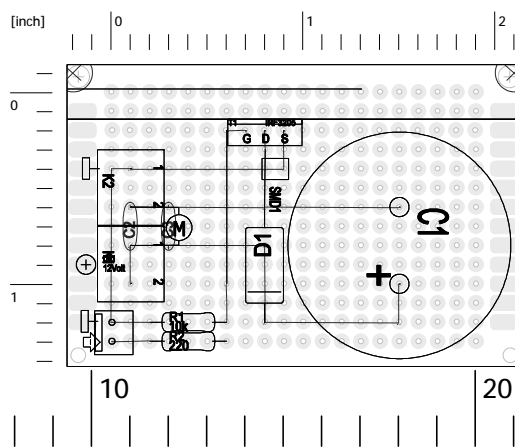
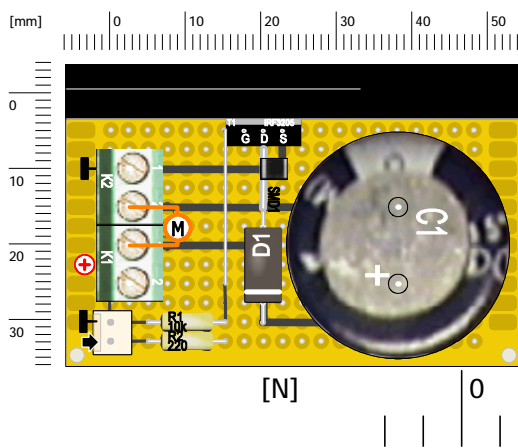
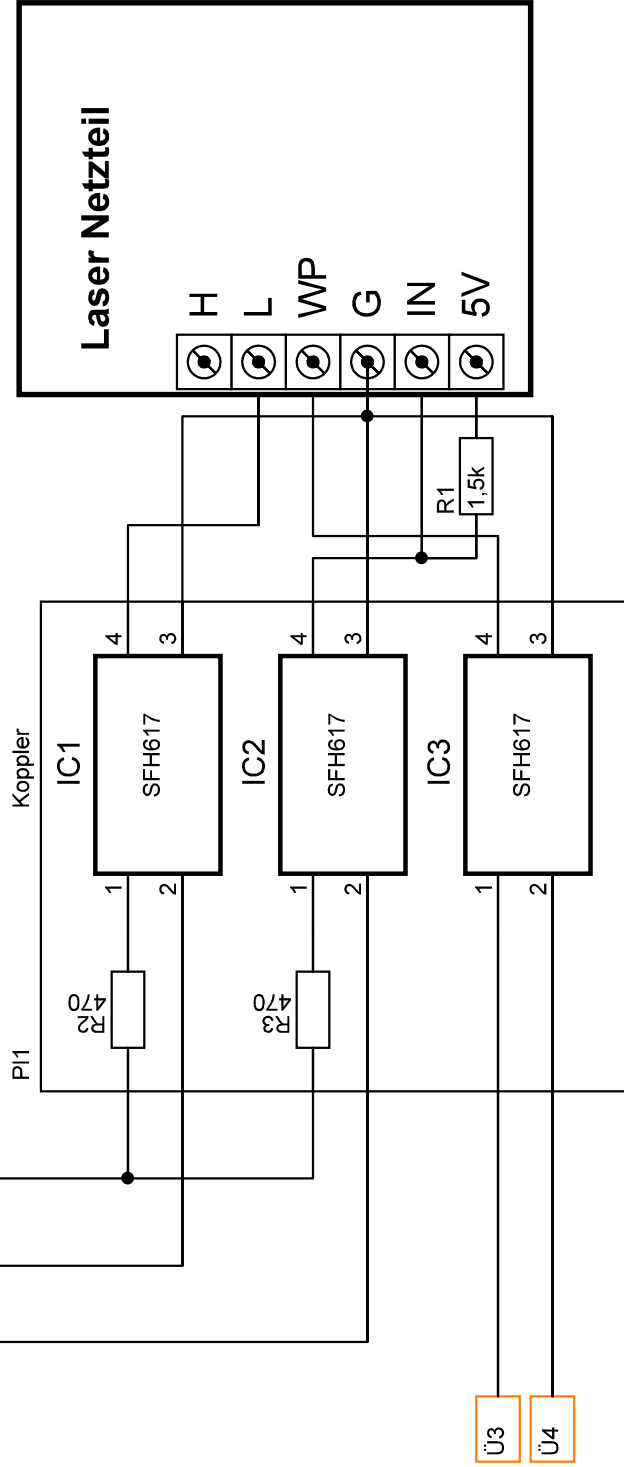
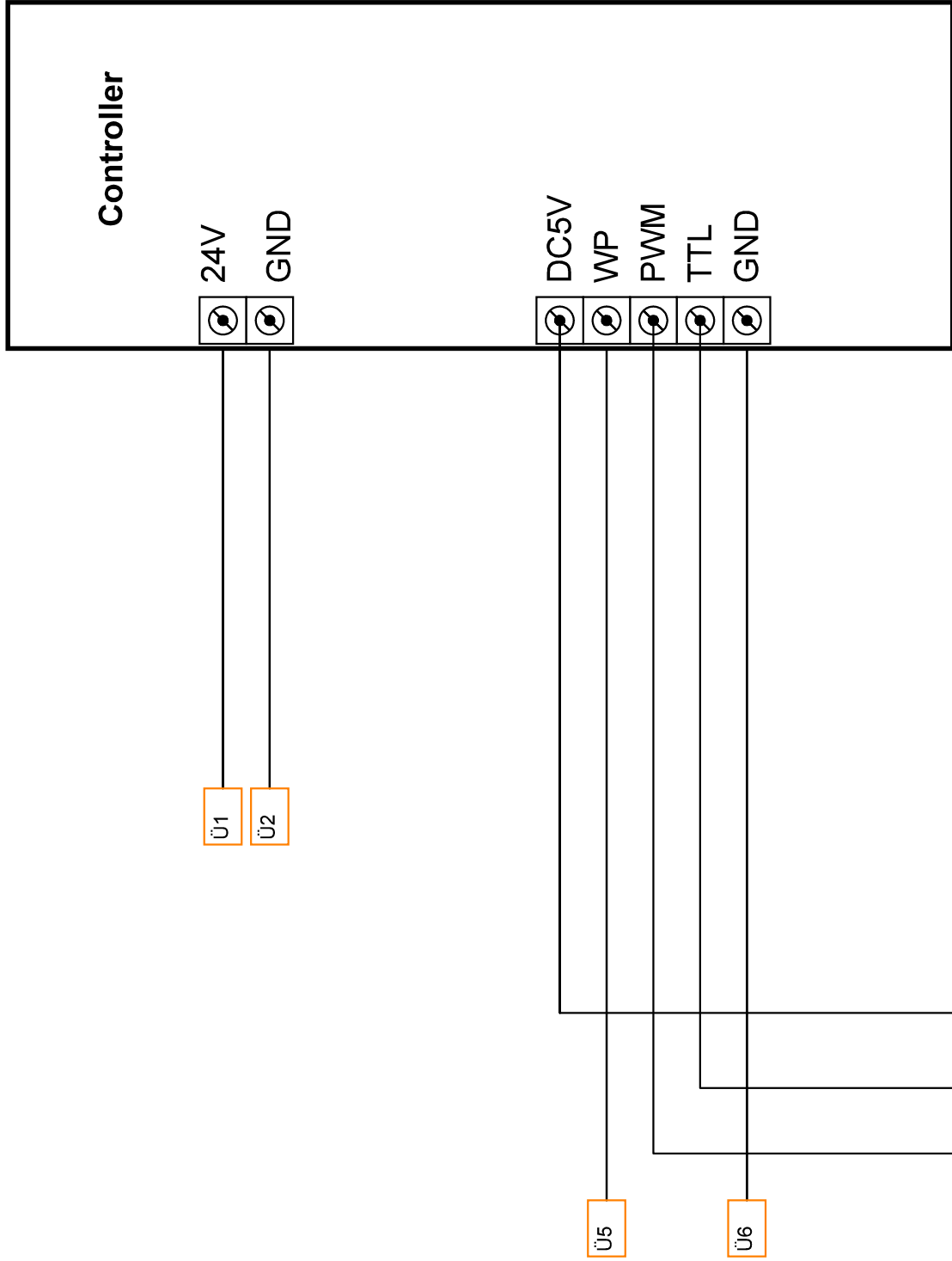


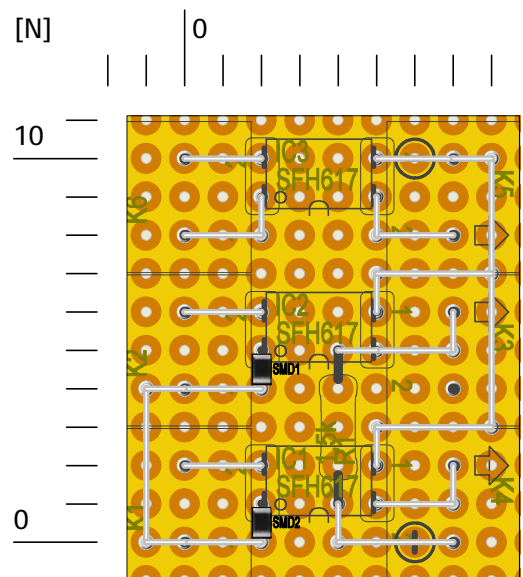
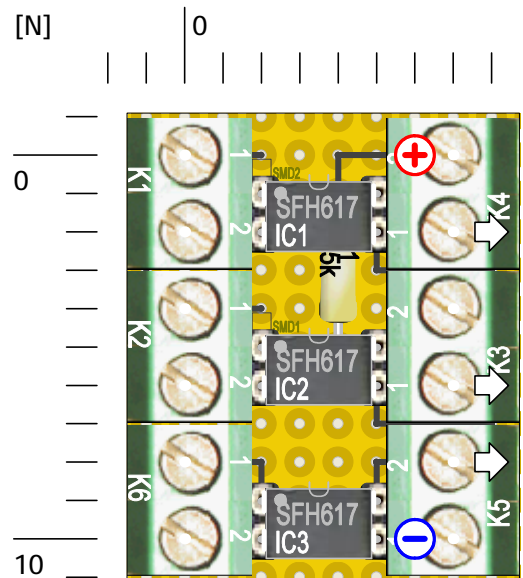
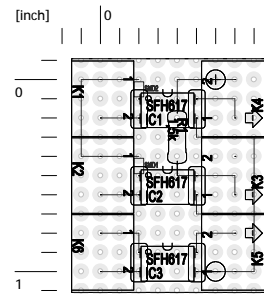
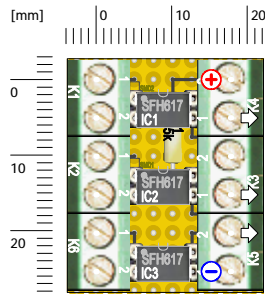
```
// Pin Assignments (Arduino) [A4, A5 =I2C] [13-10, 4 =SPI] [0,1 =Serial]
FLOWMETER      Pin 2  // input Flow Meter (INT0)
Cover          Pin 3  //~ input front cover open / close (INT1)
FANSPEED       Pin 5  //~ PWM - this pin will drive the FET for the cooling fan
OWB            Pin 6  //~ PWM - 1-Wire Bus
Emergency      Pin 7  // emergency shutdown activ
BUS-Error      Pin 8  // LED flashing: I2C & OWB off =0,25s, I2C off =0,5s, OWB off =1s
LCPowerUP      Pin 9  // Switch on POWER (HIGH) [from RFID]
ENALaser       Pin A0 // Enable High Power Laser (WP)
SECURITY       Pin A1 // Security relais High Power Laser
SSR_Machine    Pin A2 // POWER Switch
POWERV         Pin A3 // POWER voltage value
```

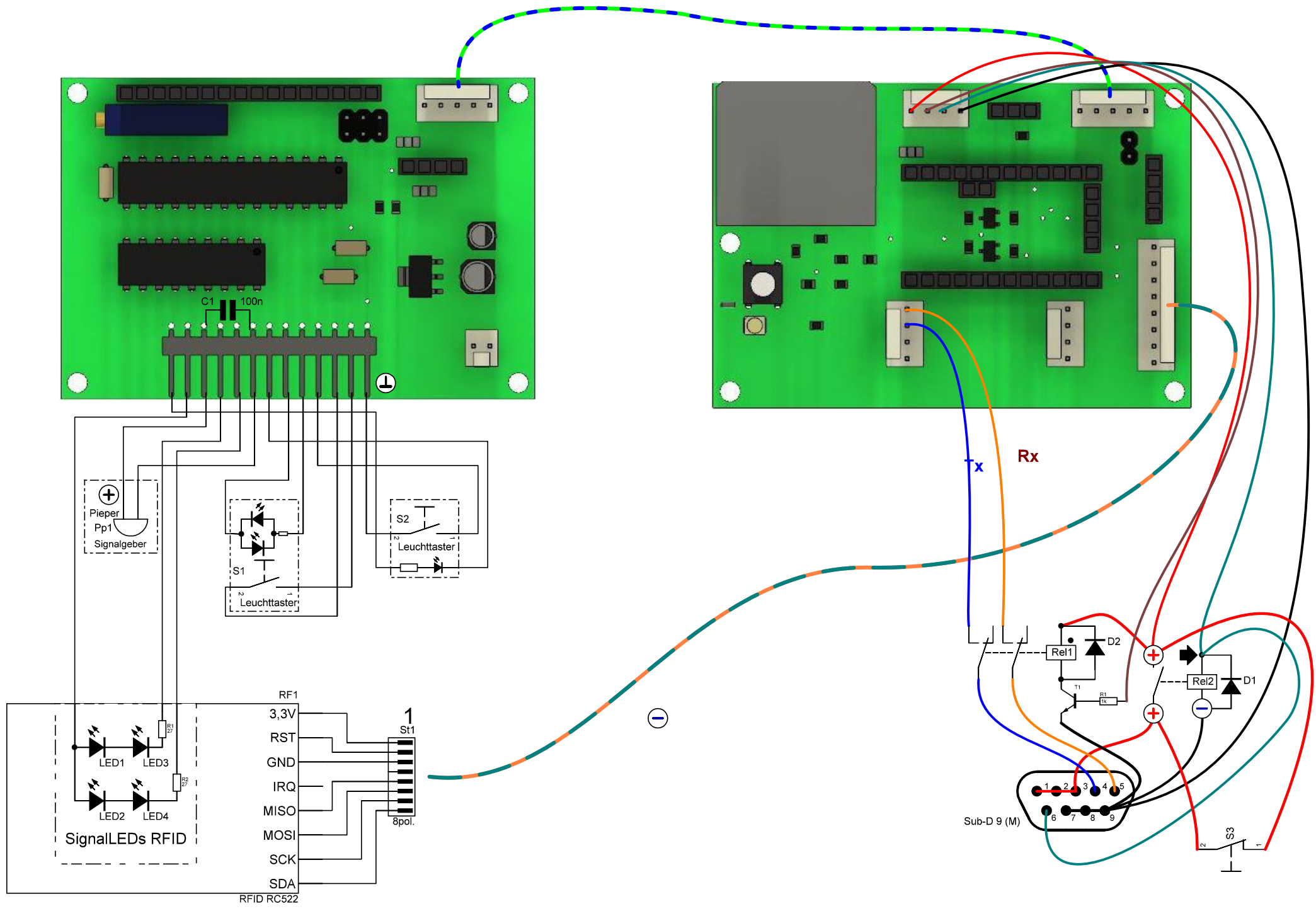


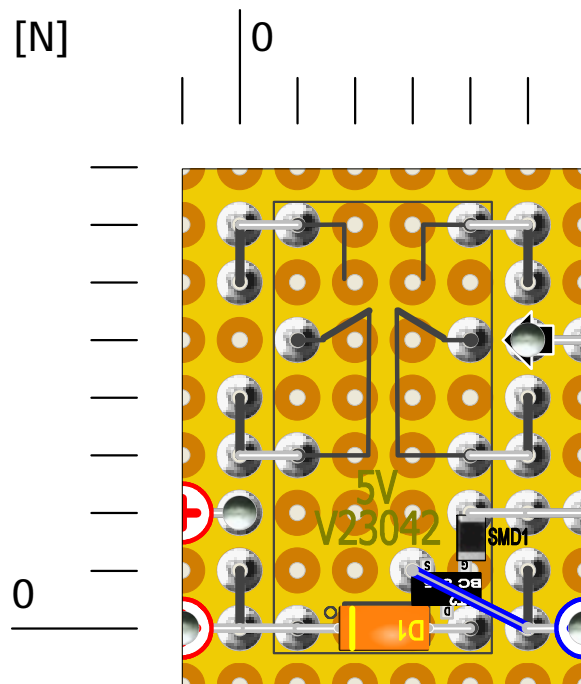
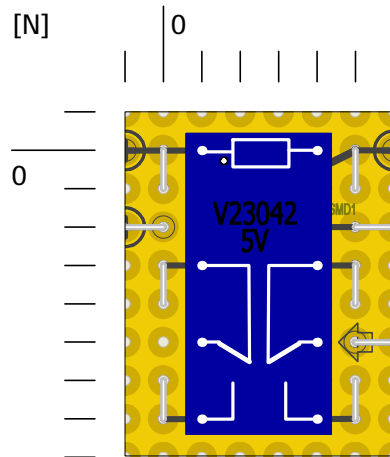
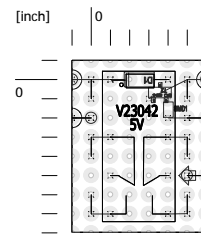
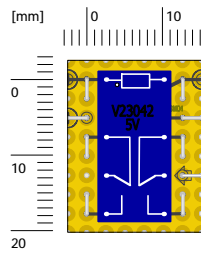


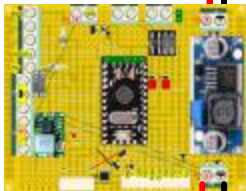










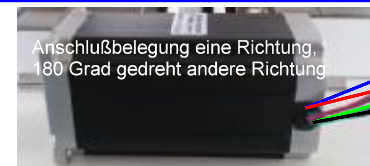


X-Achse

+ Z-Achse



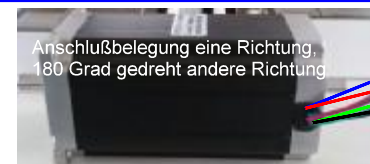
Y-Achse rechts



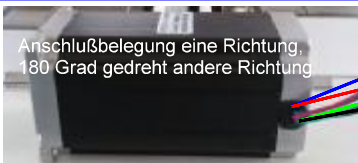
Anschlußbelegung eine Richtung, 180 Grad gedreht andere Richtung



Y-Achse links



Anschlußbelegung eine Richtung, 180 Grad gedreht andere Richtung



Anschlußbelegung eine Richtung, 180 Grad gedreht andere Richtung

