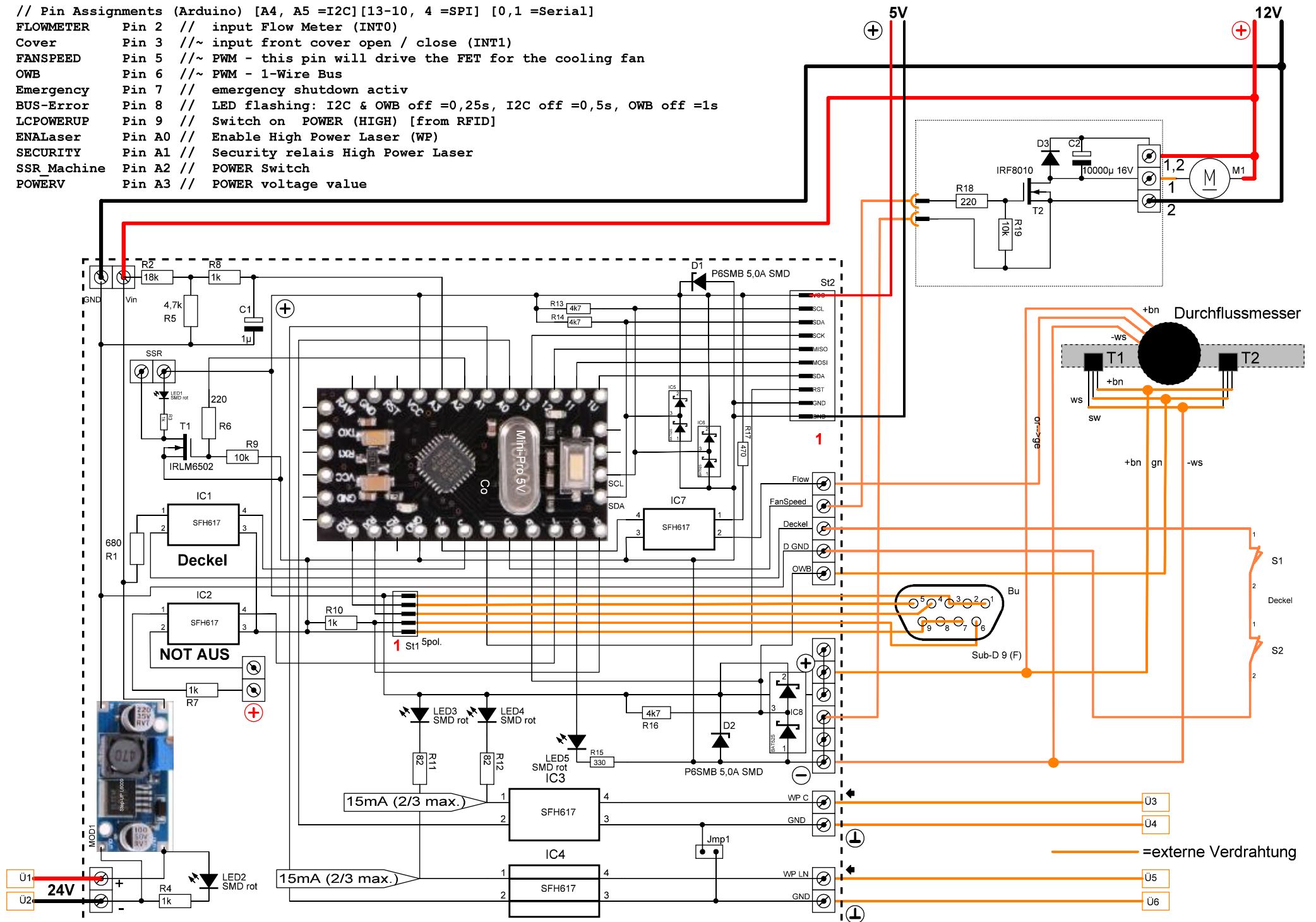
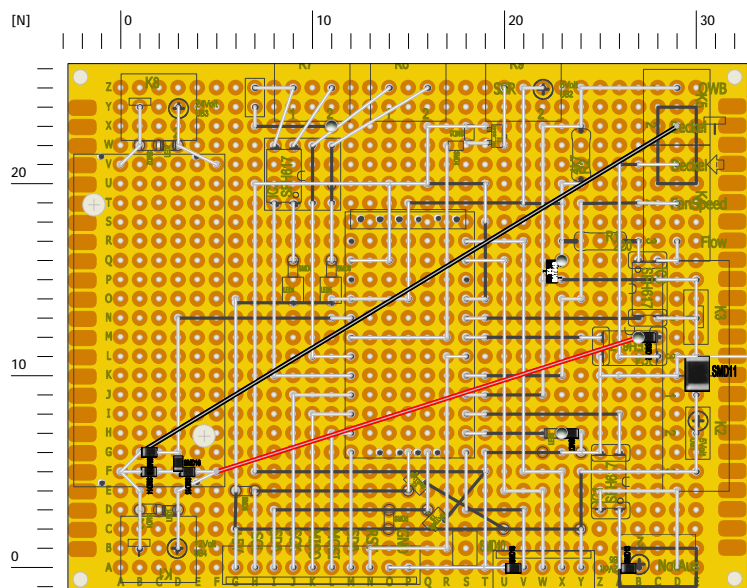
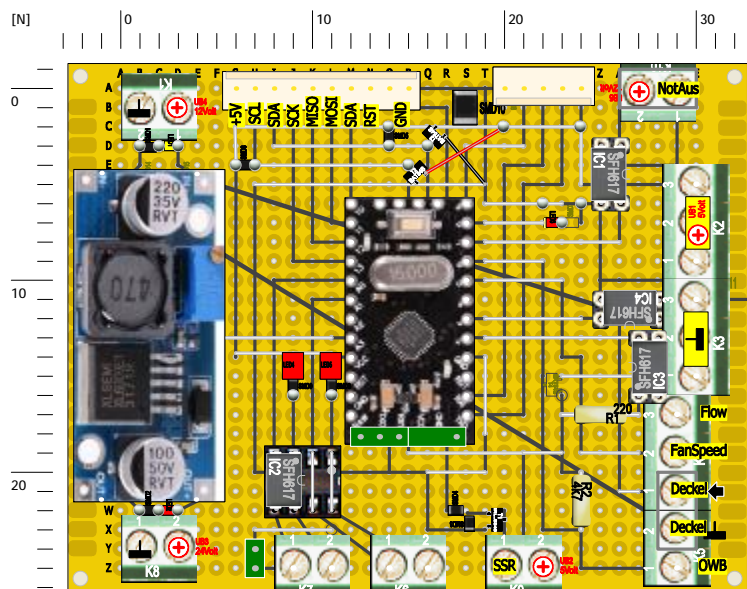
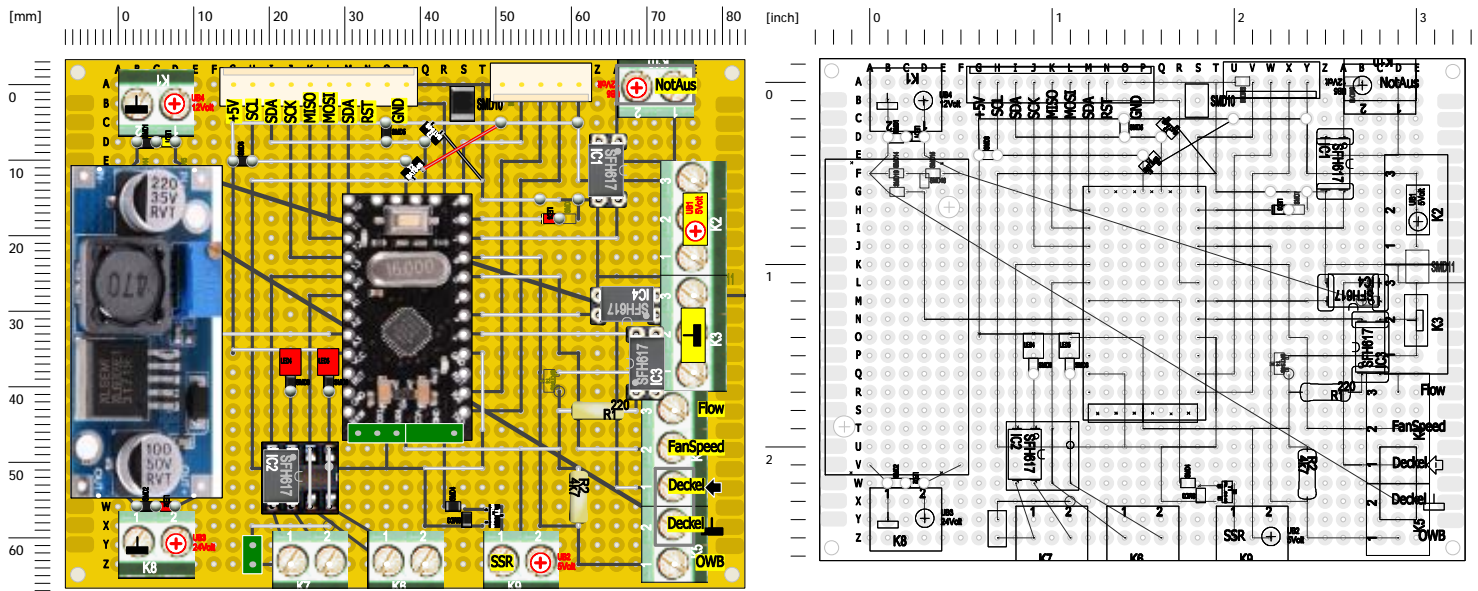
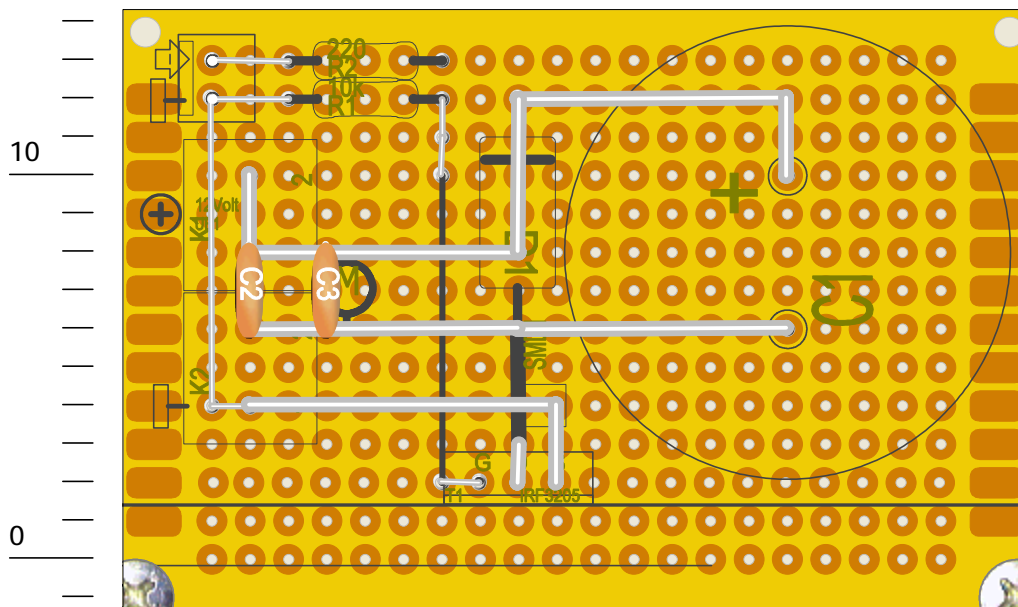
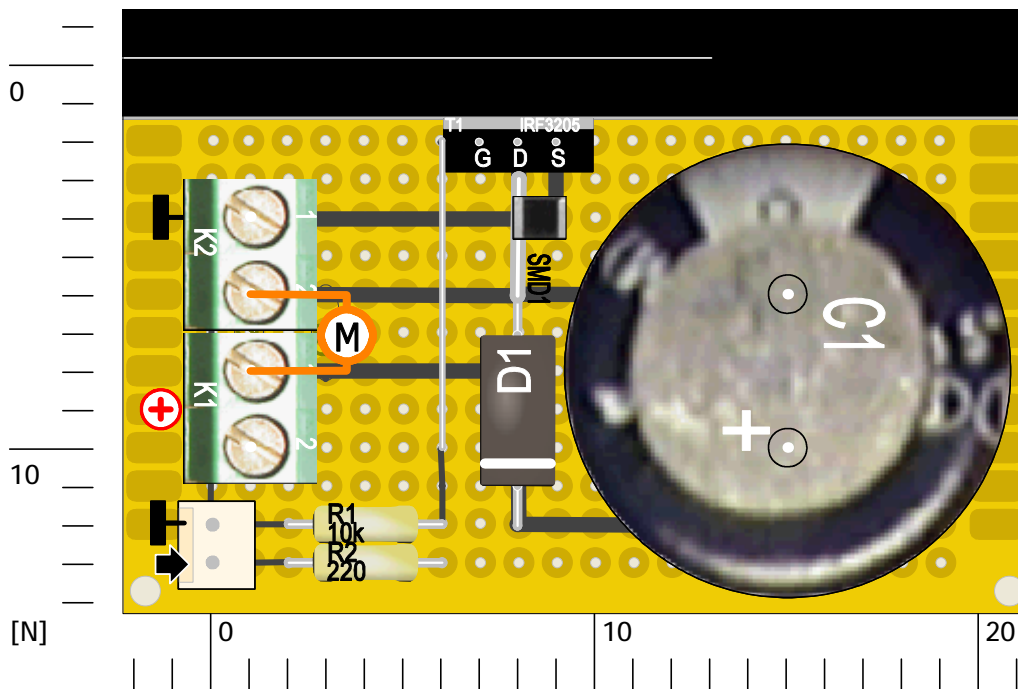
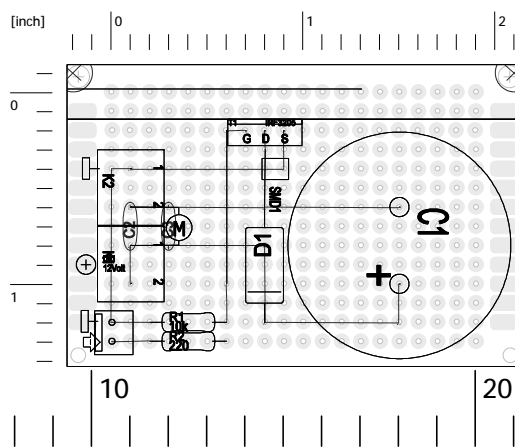
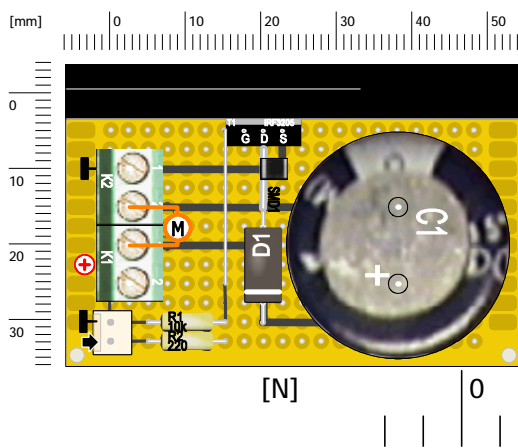
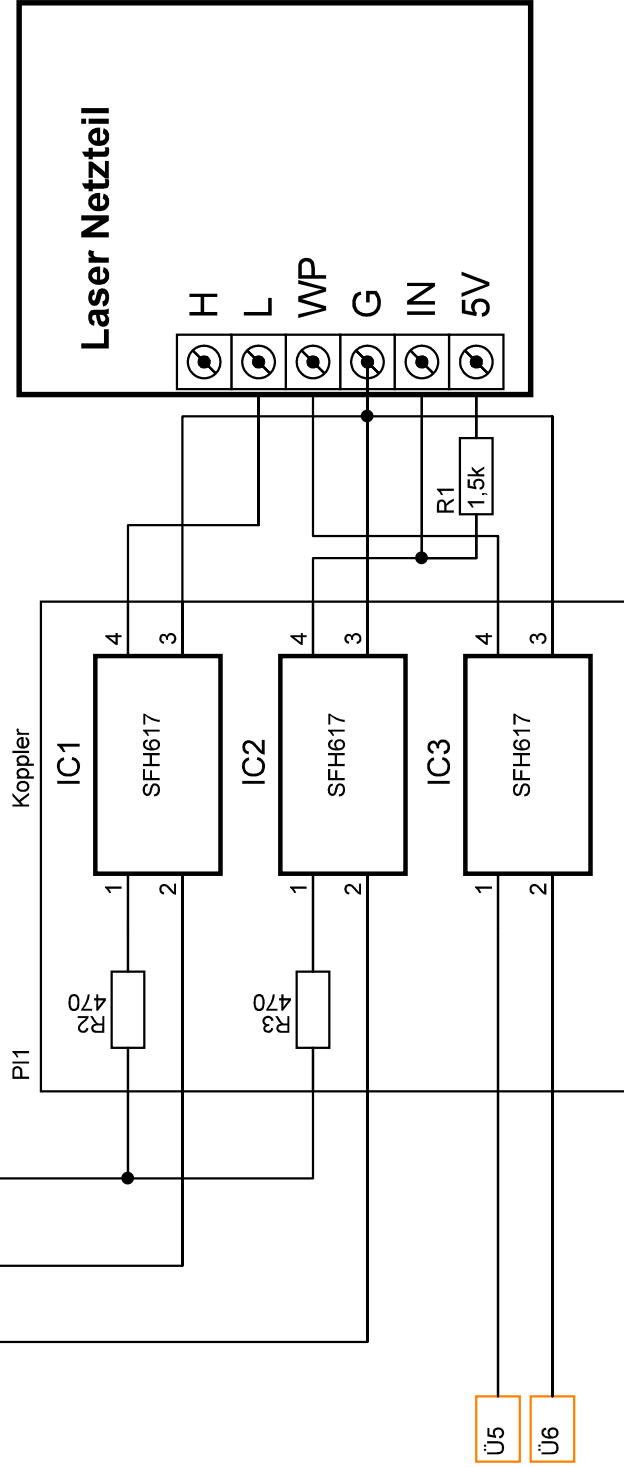
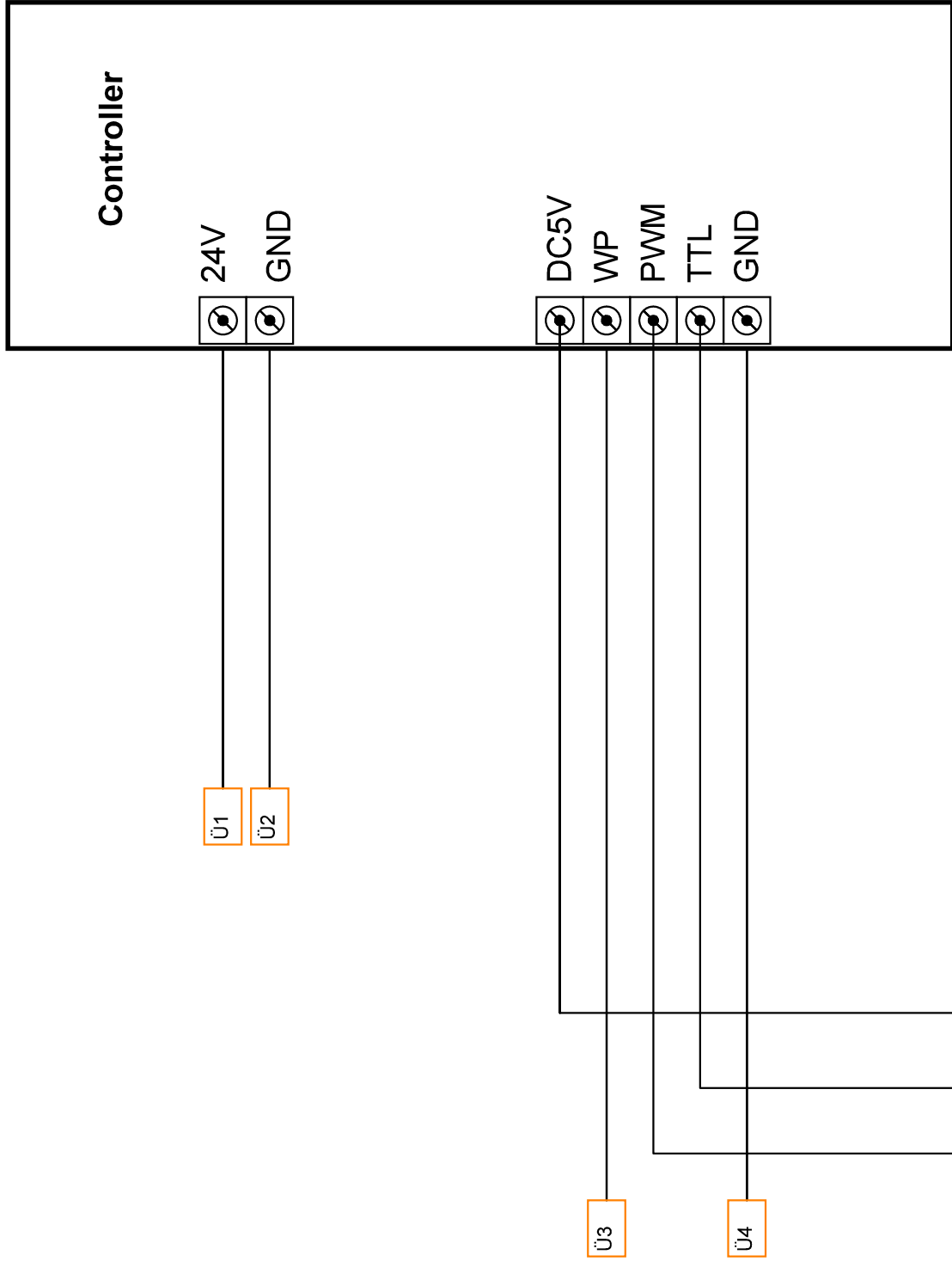


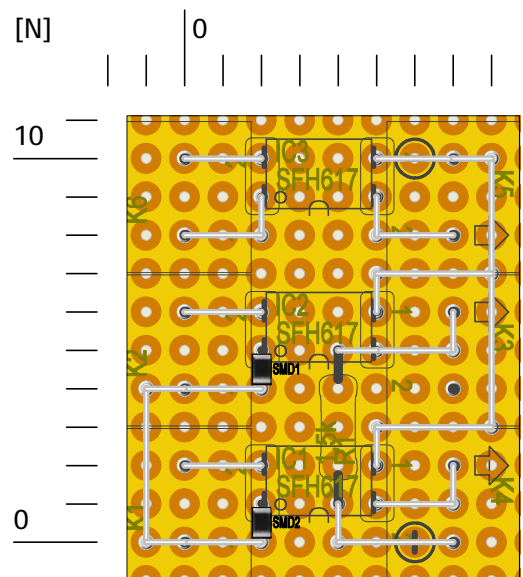
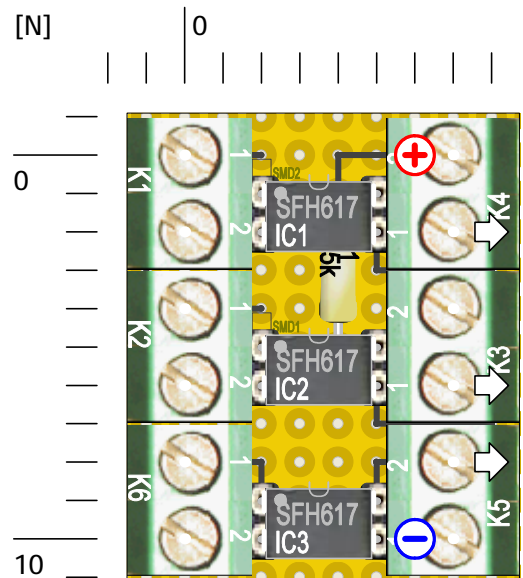
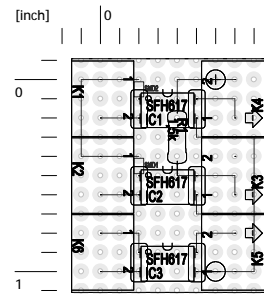
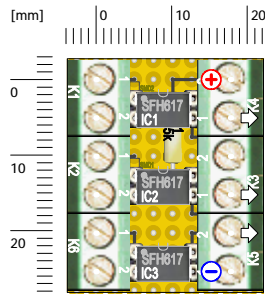
```
// Pin Assignments (Arduino) [A4, A5 =I2C][13-10, 4 =SPI] [0,1 =Serial]
FLOWMETER   Pin 2  // input Flow Meter (INT0)
Cover       Pin 3  //~ input front cover open / close (INT1)
FANSPEED    Pin 5  //~ PWM - this pin will drive the FET for the cooling fan
OWB         Pin 6  //~ PWM - 1-Wire Bus
Emergency   Pin 7  // emergency shutdown aktiv
BUS-Error   Pin 8  // LED flashing: I2C & OWB off =0,25s, I2C off =0,5s, OWB off =1s
LCPOWERUP   Pin 9  // Switch on POWER (HIGH) [from RFID]
ENALaser    Pin A0 // Enable High Power Laser (WP)
SECURITY    Pin A1 // Security relais High Power Laser
SSR Machine Pin A2 // POWER Switch
POWERV      Pin A3 // POWER voltage value
```



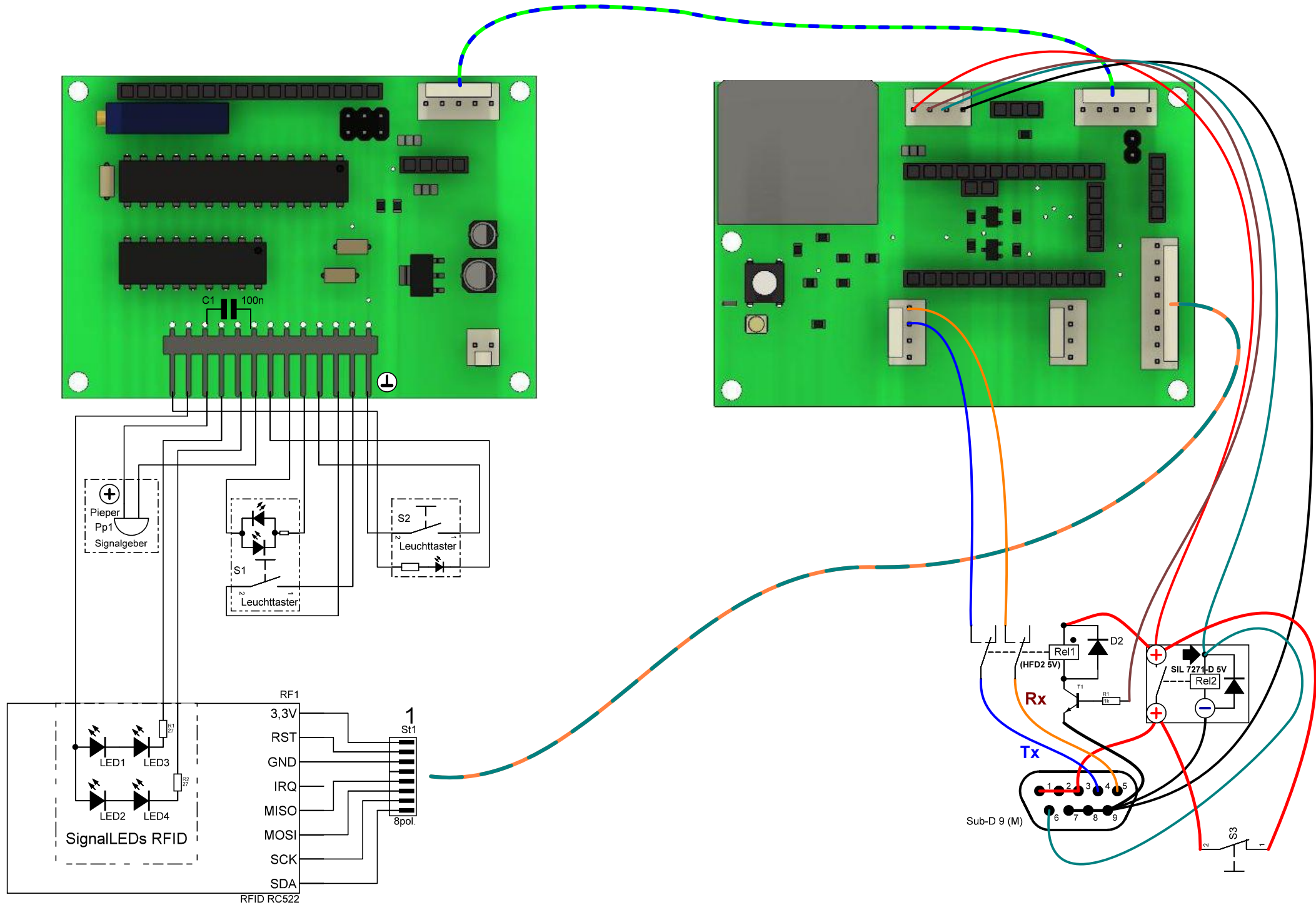


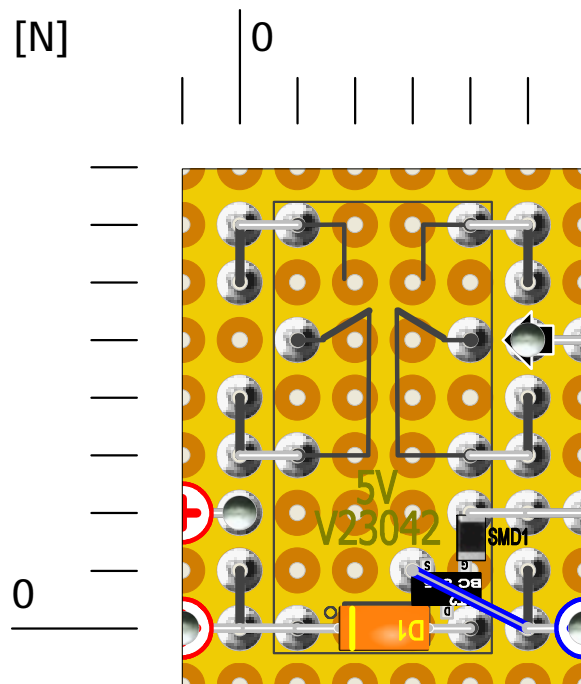
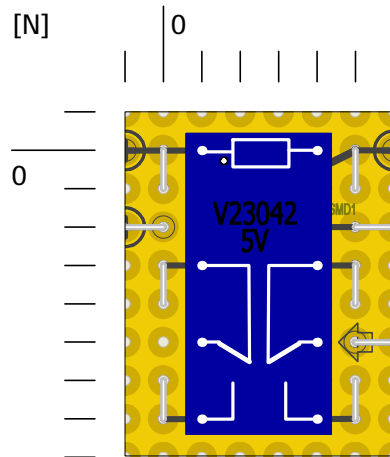
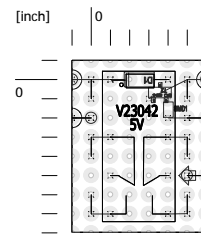
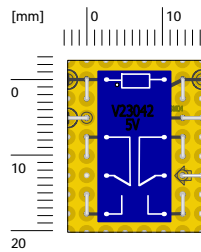


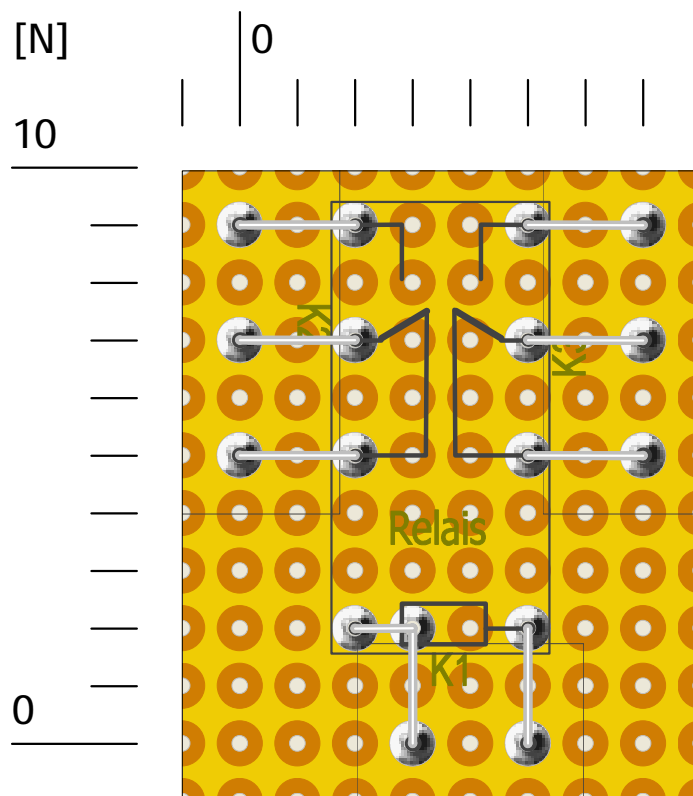
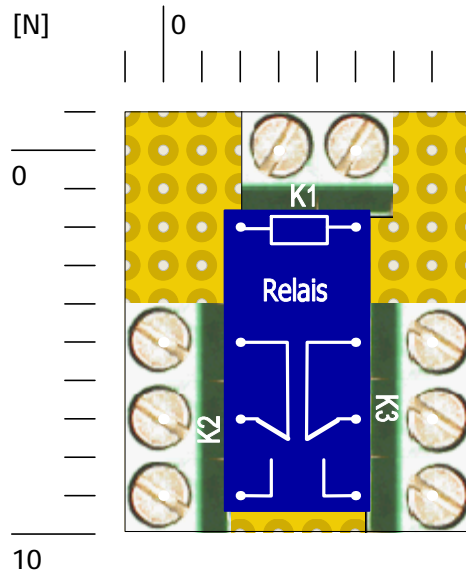
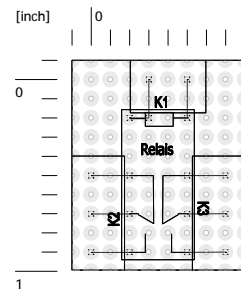
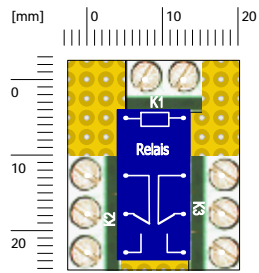




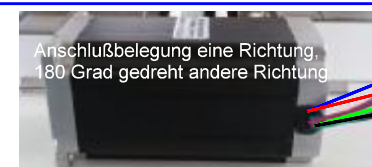
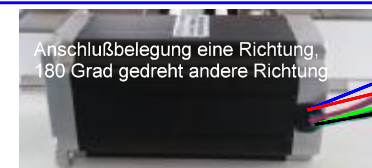
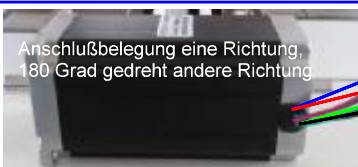
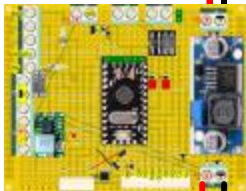












X-Achse

Y-Achse rechts

Y-Achse links

+ Z-Achse

Anschlußbelegung eine Richtung,  
180 Grad gedreht andere Richtung

Anschlußbelegung eine Richtung,  
180 Grad gedreht andere Richtung

