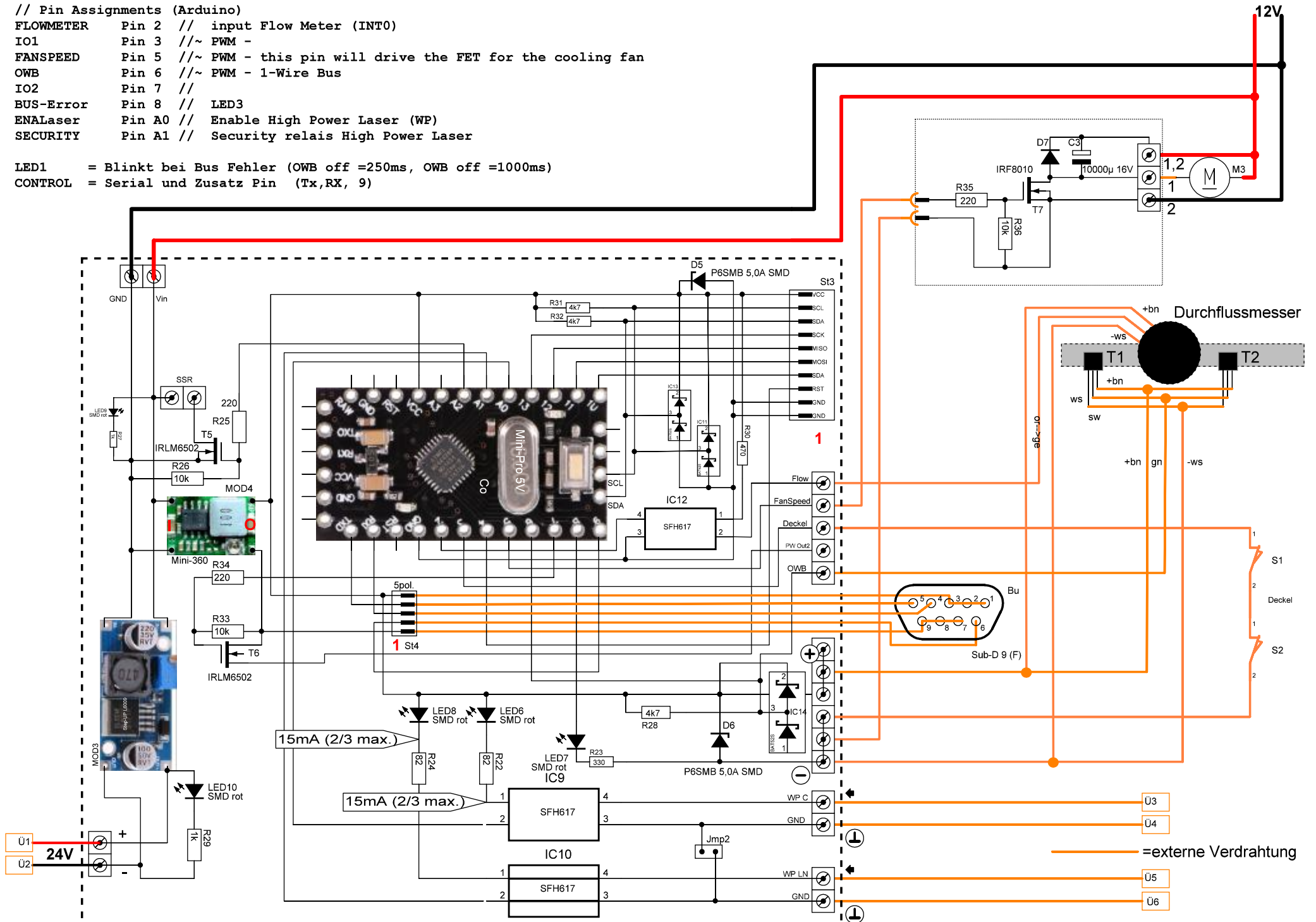


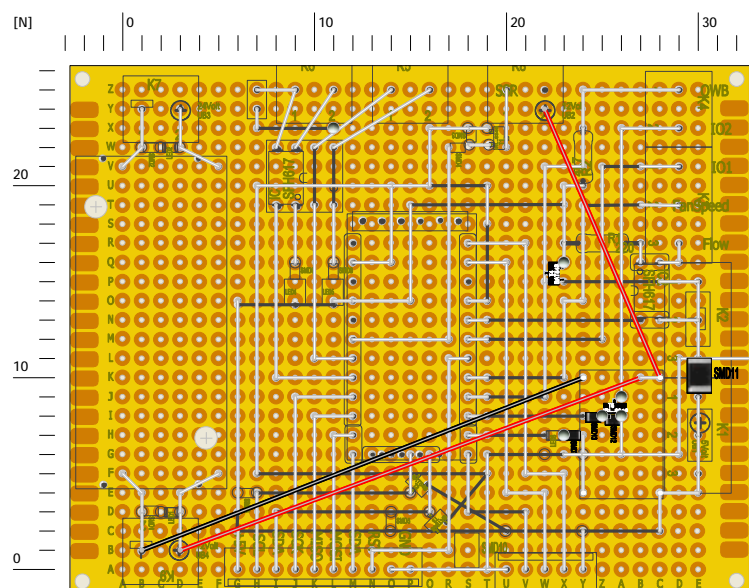
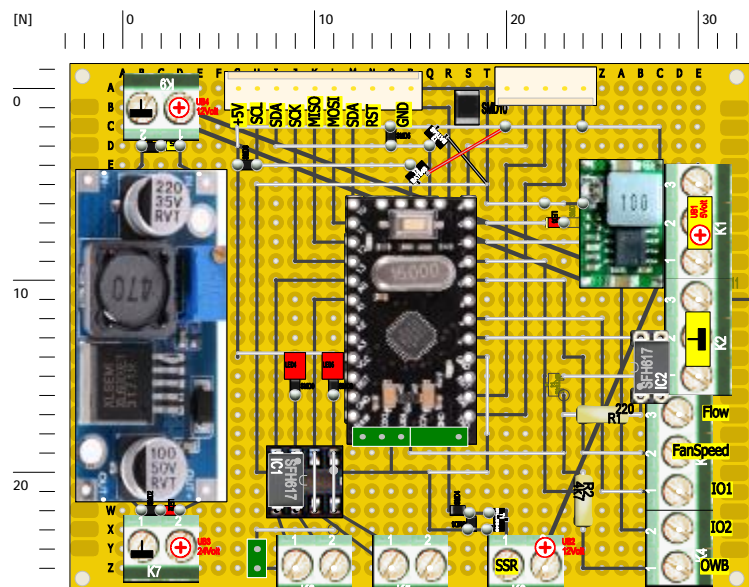
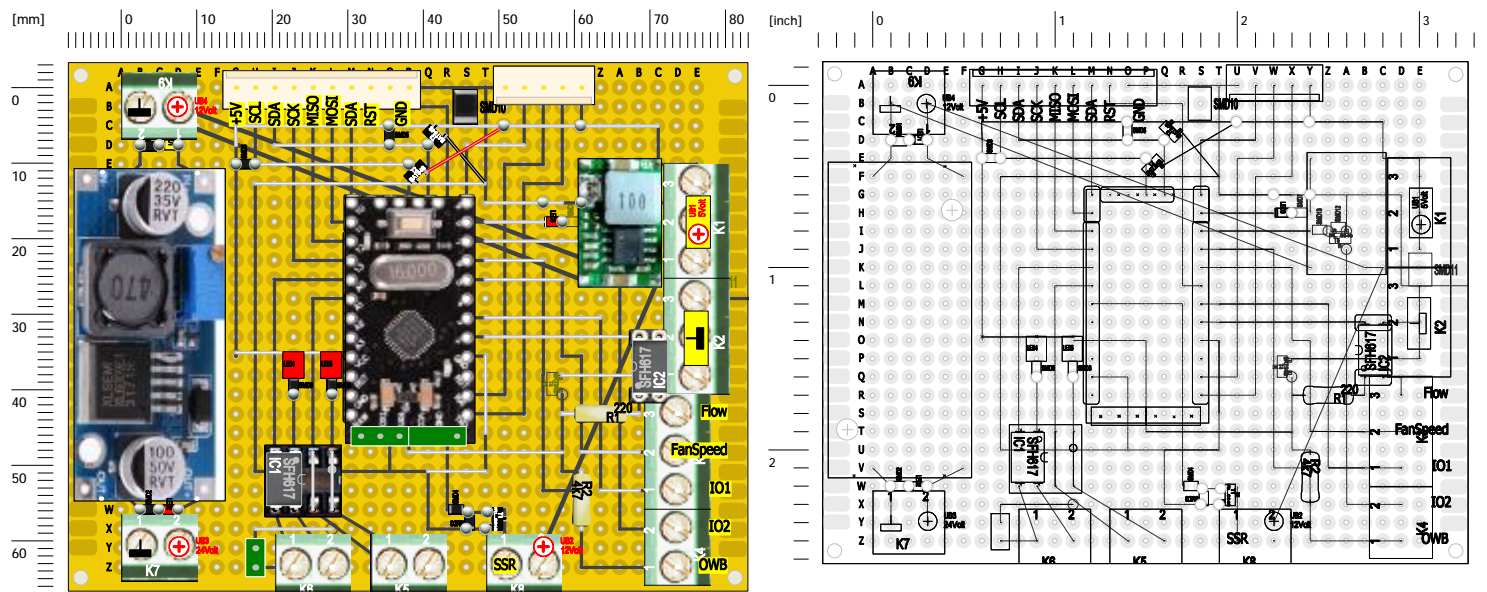
// Pin Assignments (Arduino)

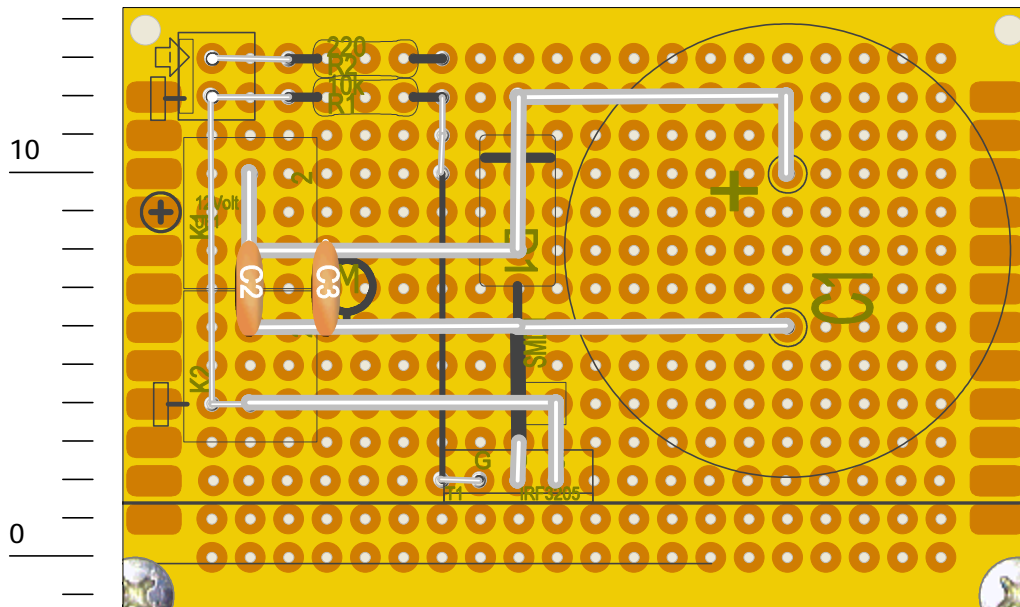
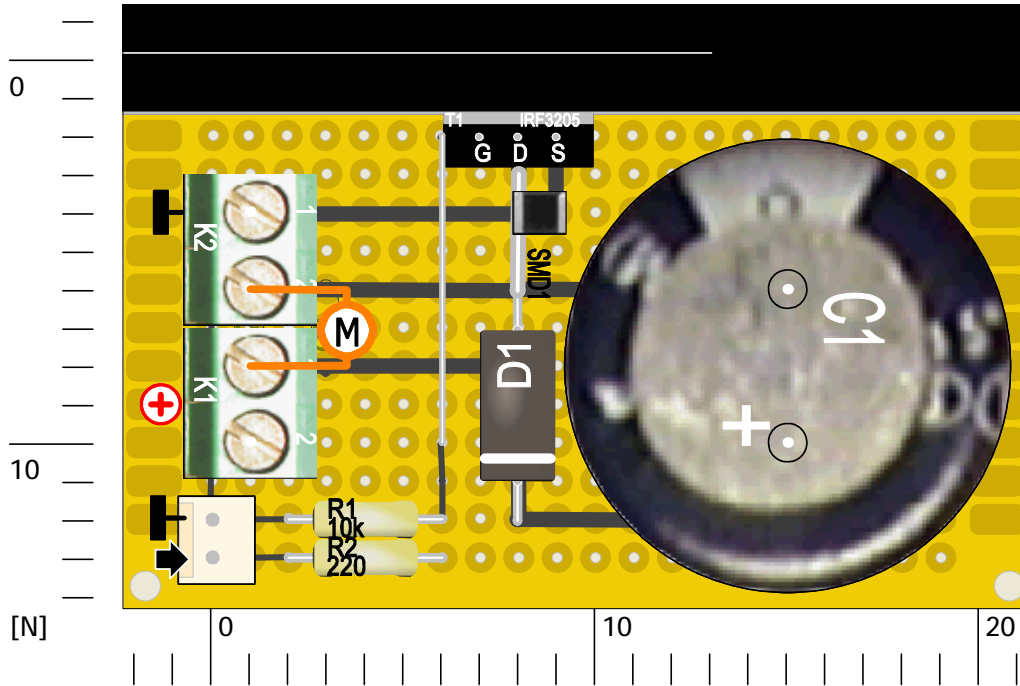
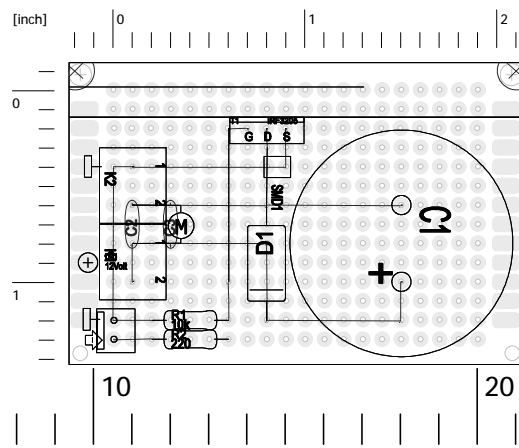
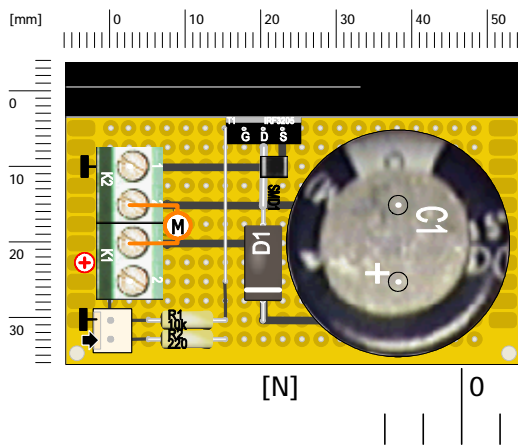
FLOWMETER Pin 2 // input Flow Meter (INT0)
 IO1 Pin 3 //~ PWM -
 FANSPEED Pin 5 //~ PWM - this pin will drive the FET for the cooling fan
 OWB Pin 6 //~ PWM - 1-Wire Bus
 IO2 Pin 7 //
 BUS-Error Pin 8 // LED3
 ENALaser Pin A0 // Enable High Power Laser (WP)
 SECURITY Pin A1 // Security relais High Power Laser

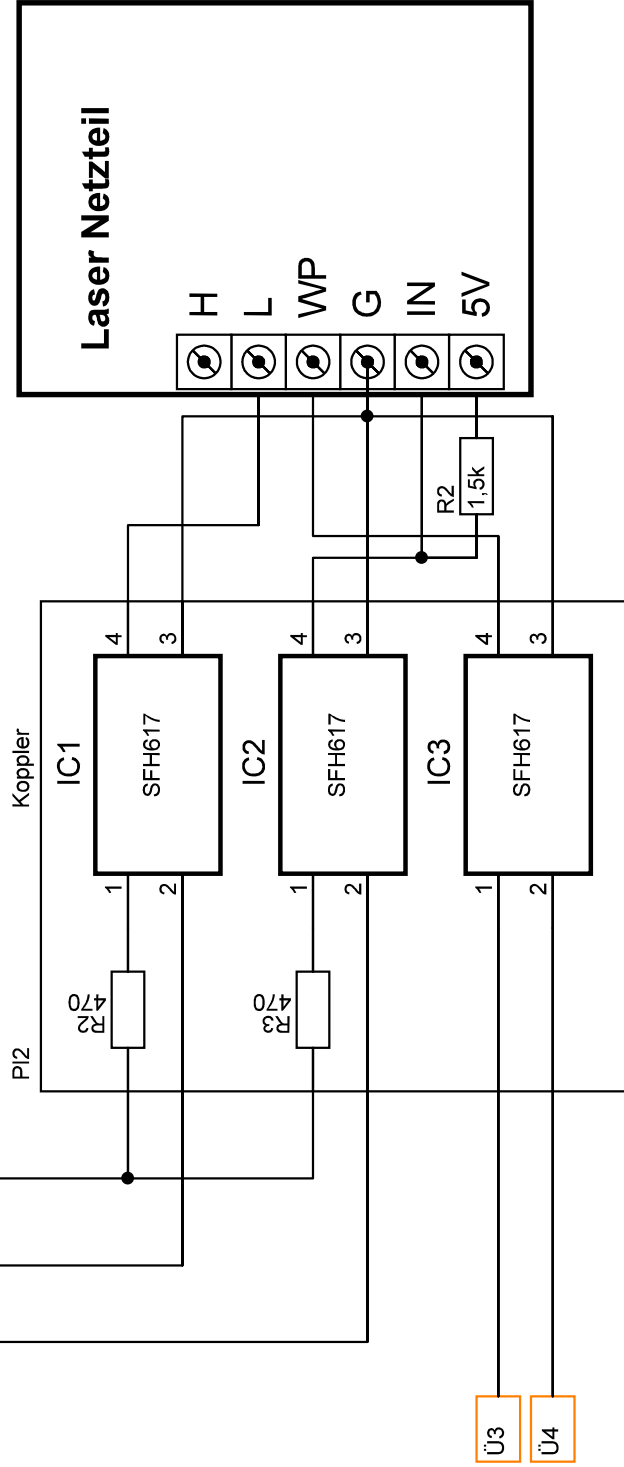
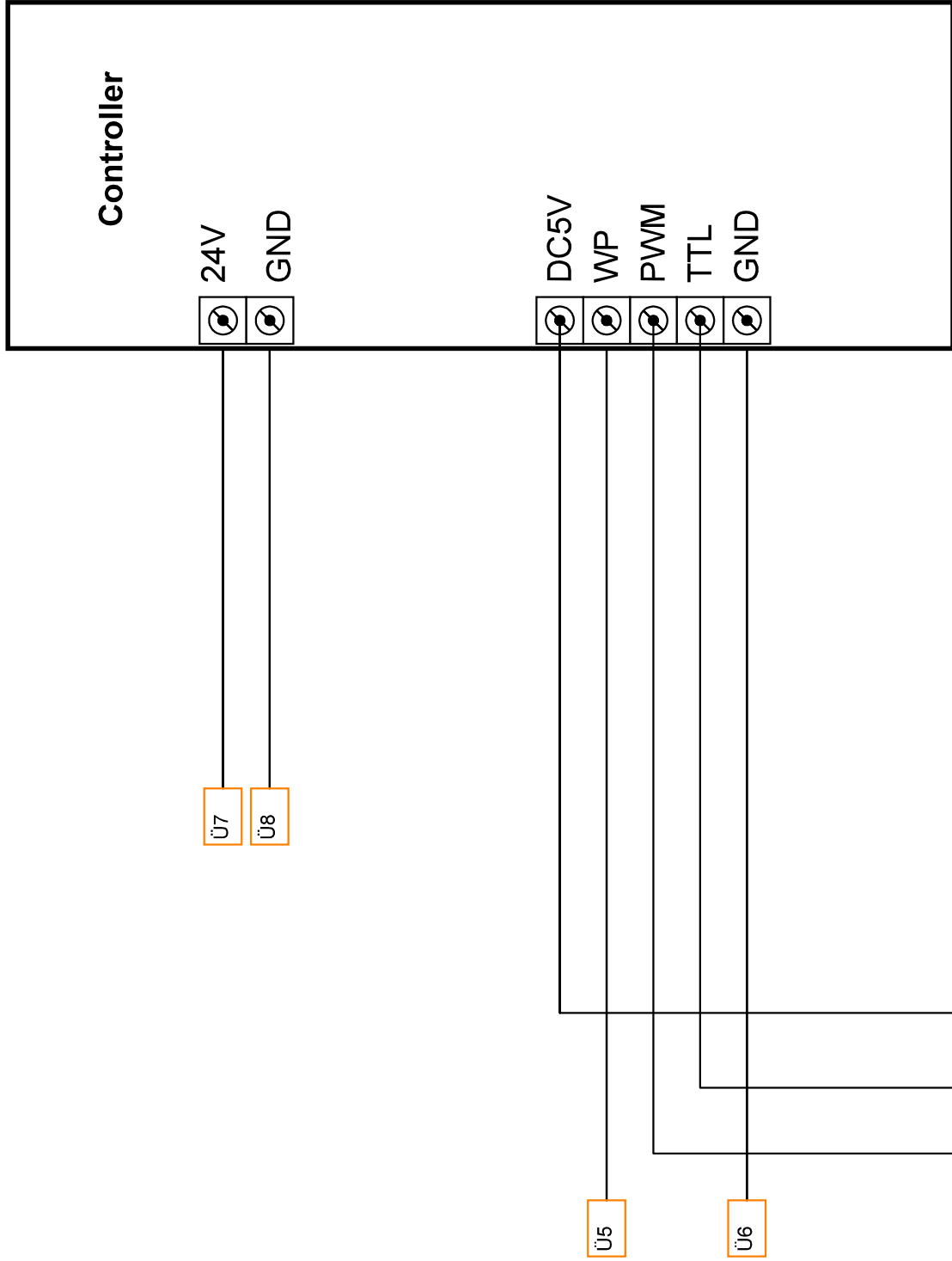
LED1 = Blinkt bei Bus Fehler (OWB off =250ms, OWB off =1000ms)

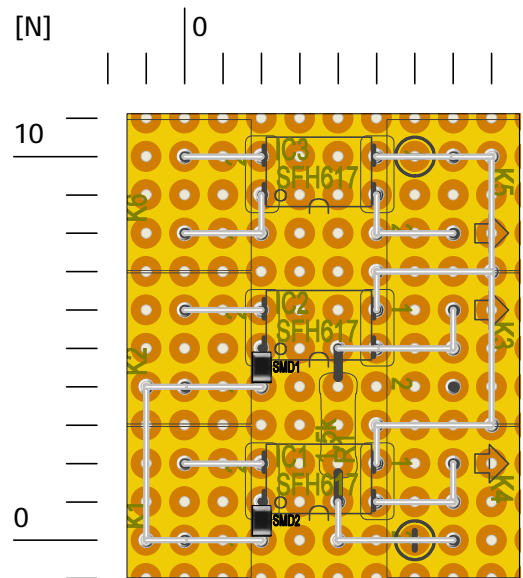
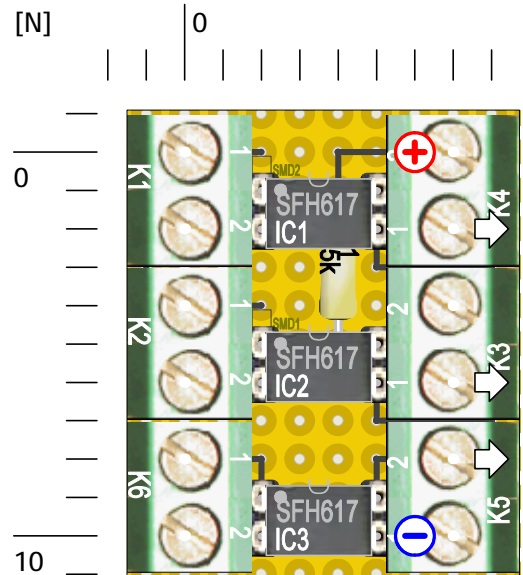
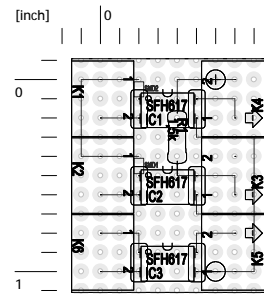
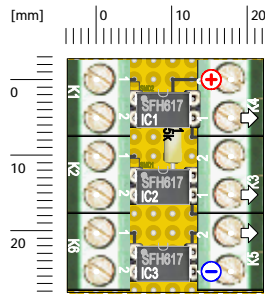
CONTROL = Serial und Zusatz Pin (Tx,RX, 9)

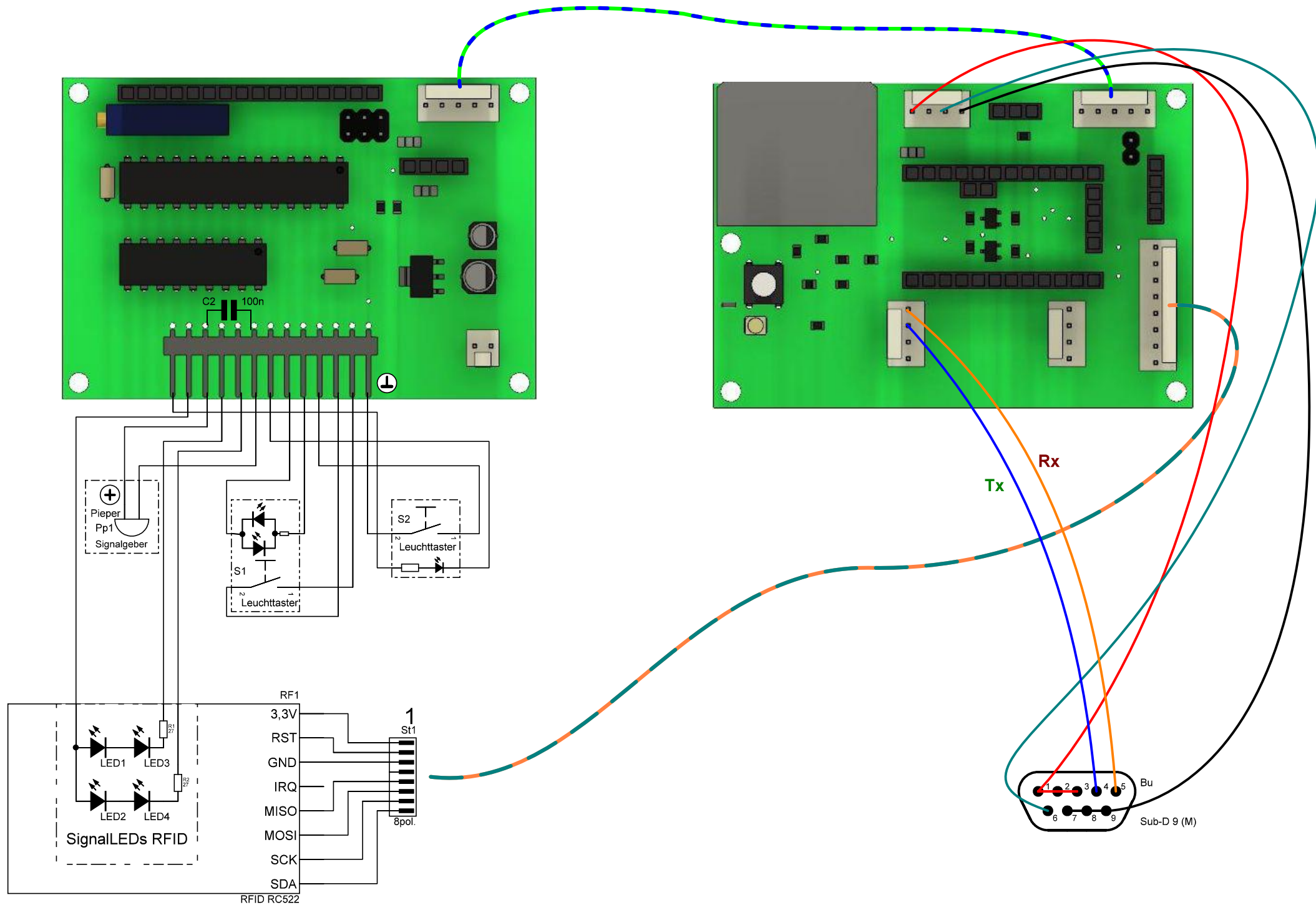






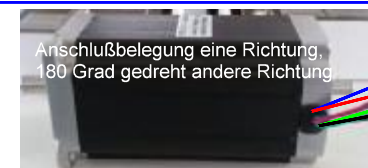








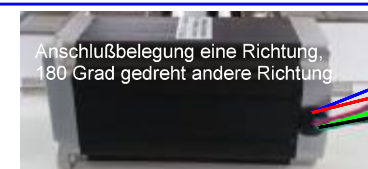
Y-Achse rechts



Anschlußbelegung eine Richtung, 180 Grad gedreht andere Richtung



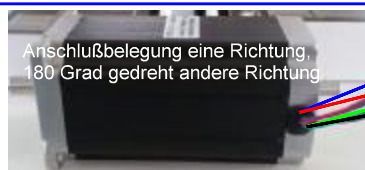
Y-Achse links



Anschlußbelegung eine Richtung, 180 Grad gedreht andere Richtung



X-Achse



Anschlußbelegung eine Richtung, 180 Grad gedreht andere Richtung

+ Z-Achse



36V

Motoren



12V



36V

Motoren

