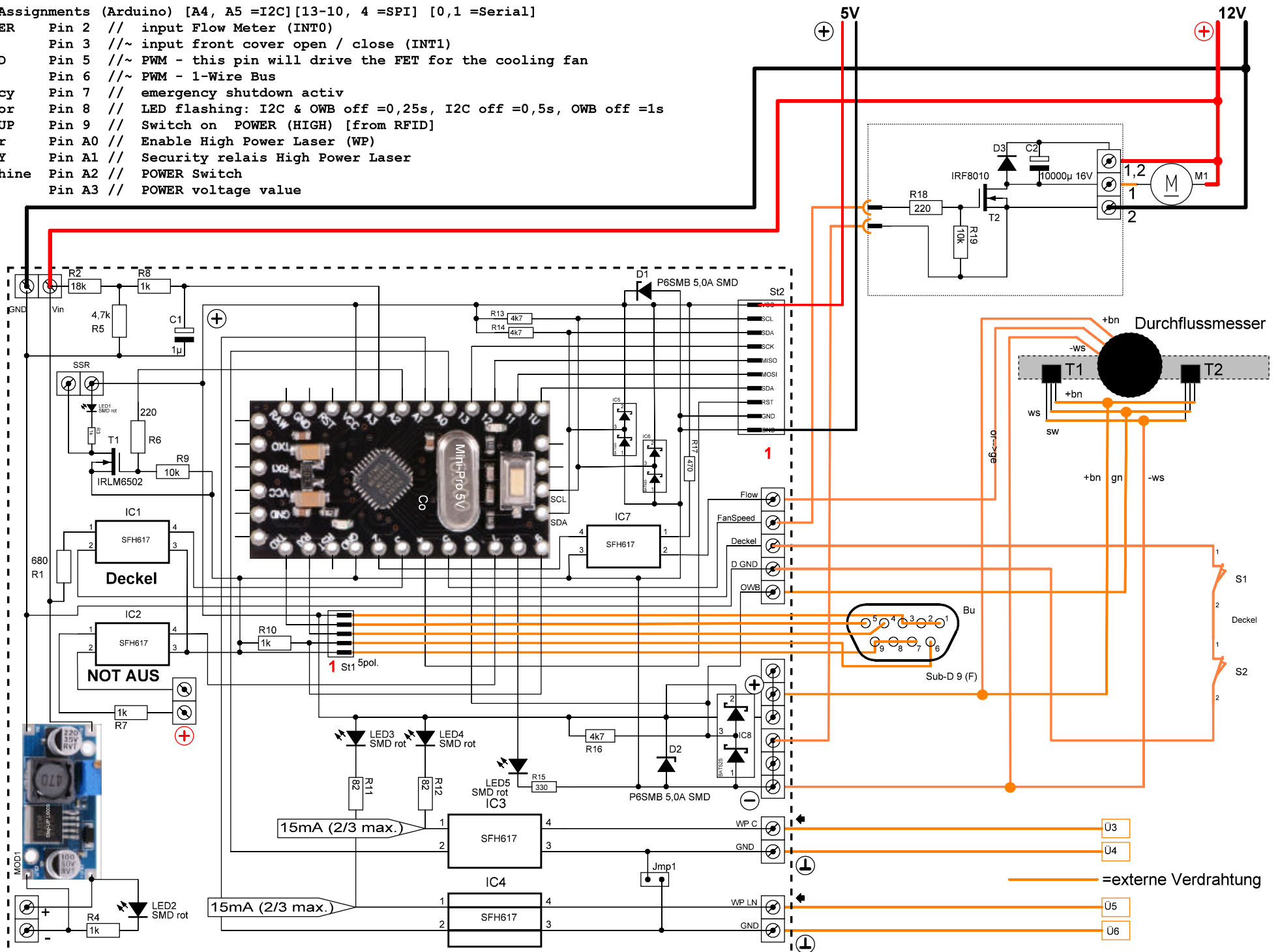
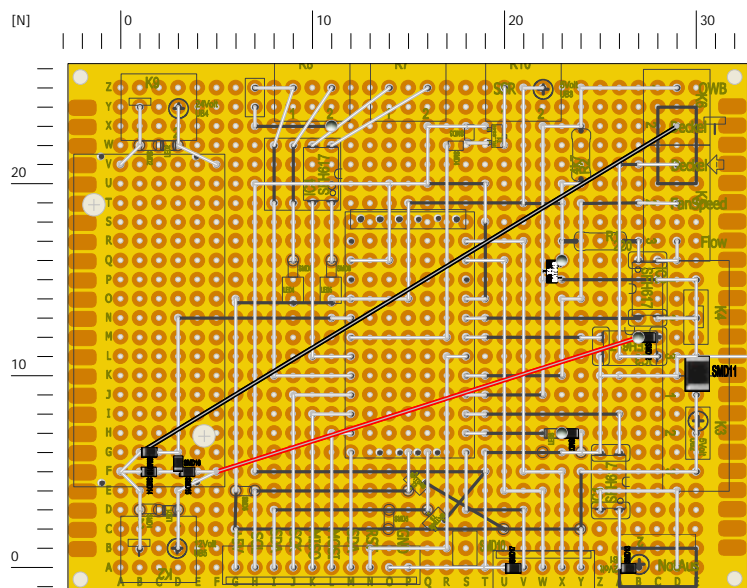
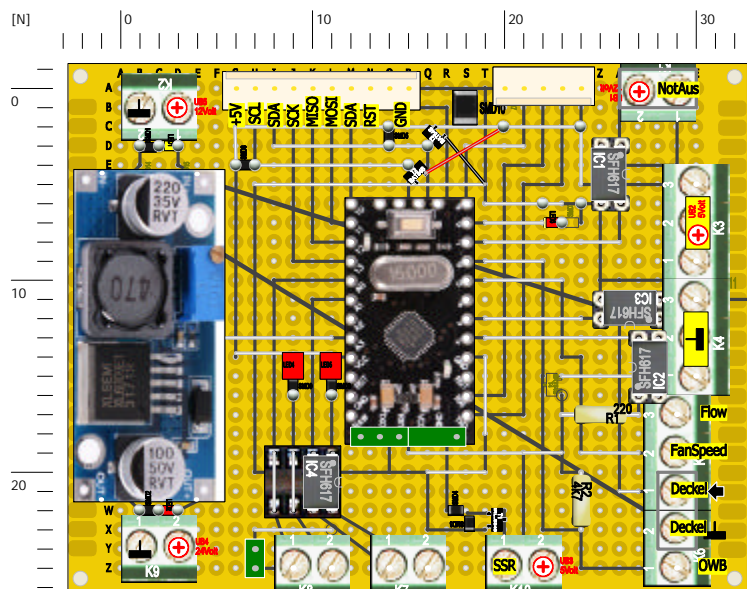
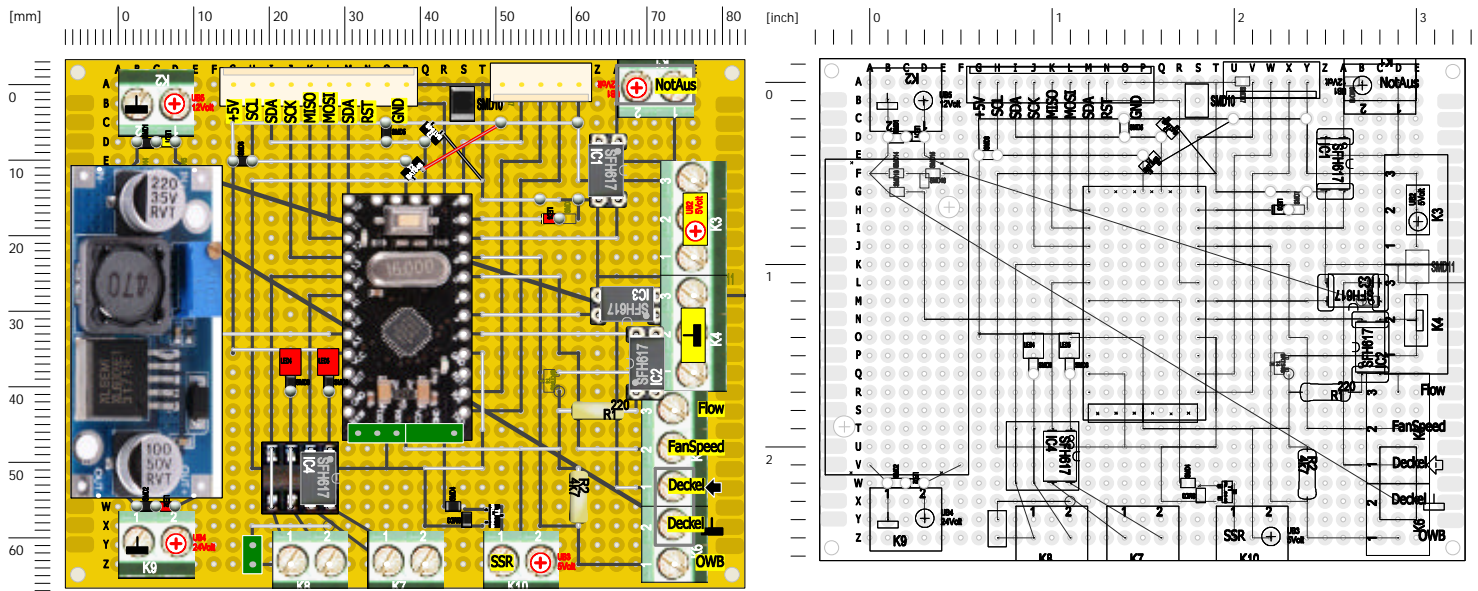
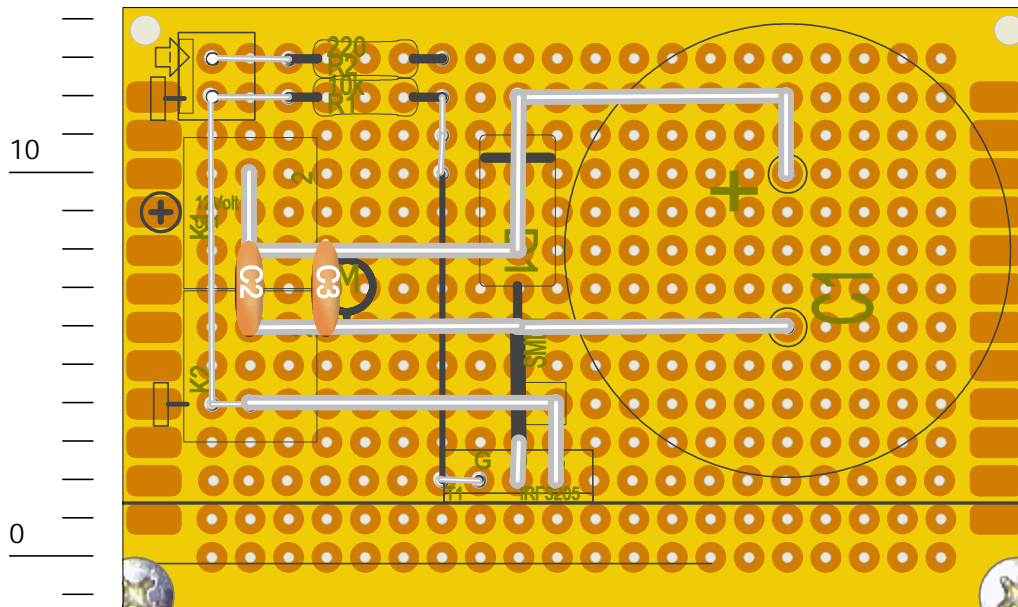
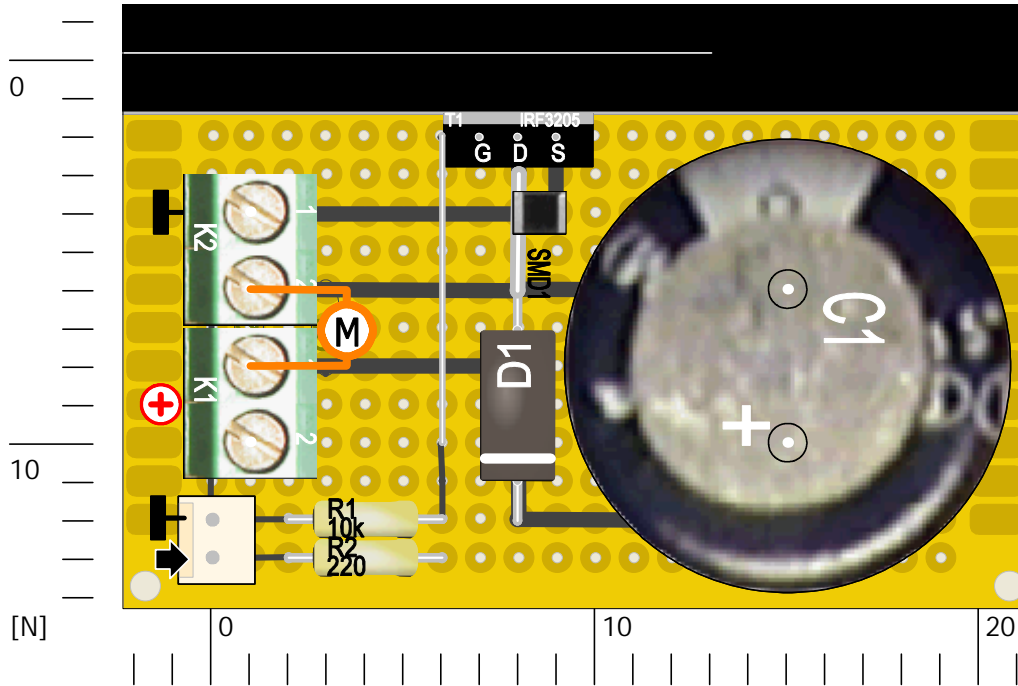
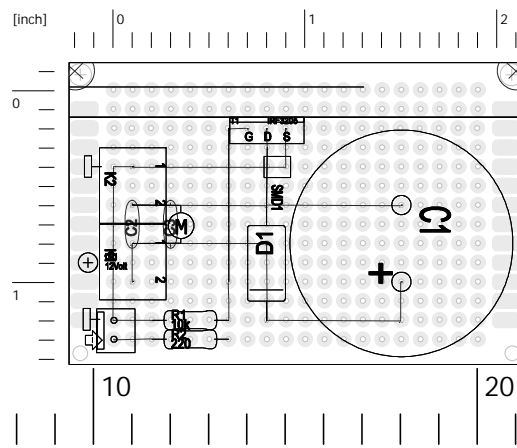
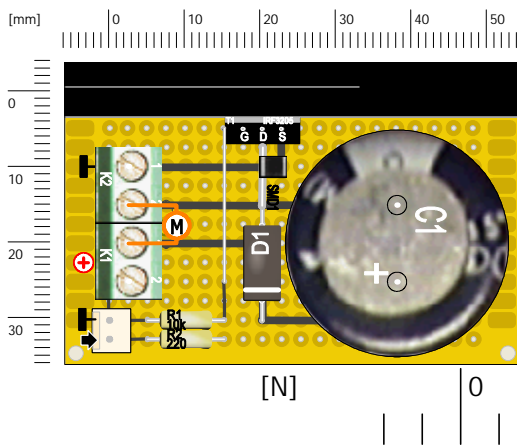
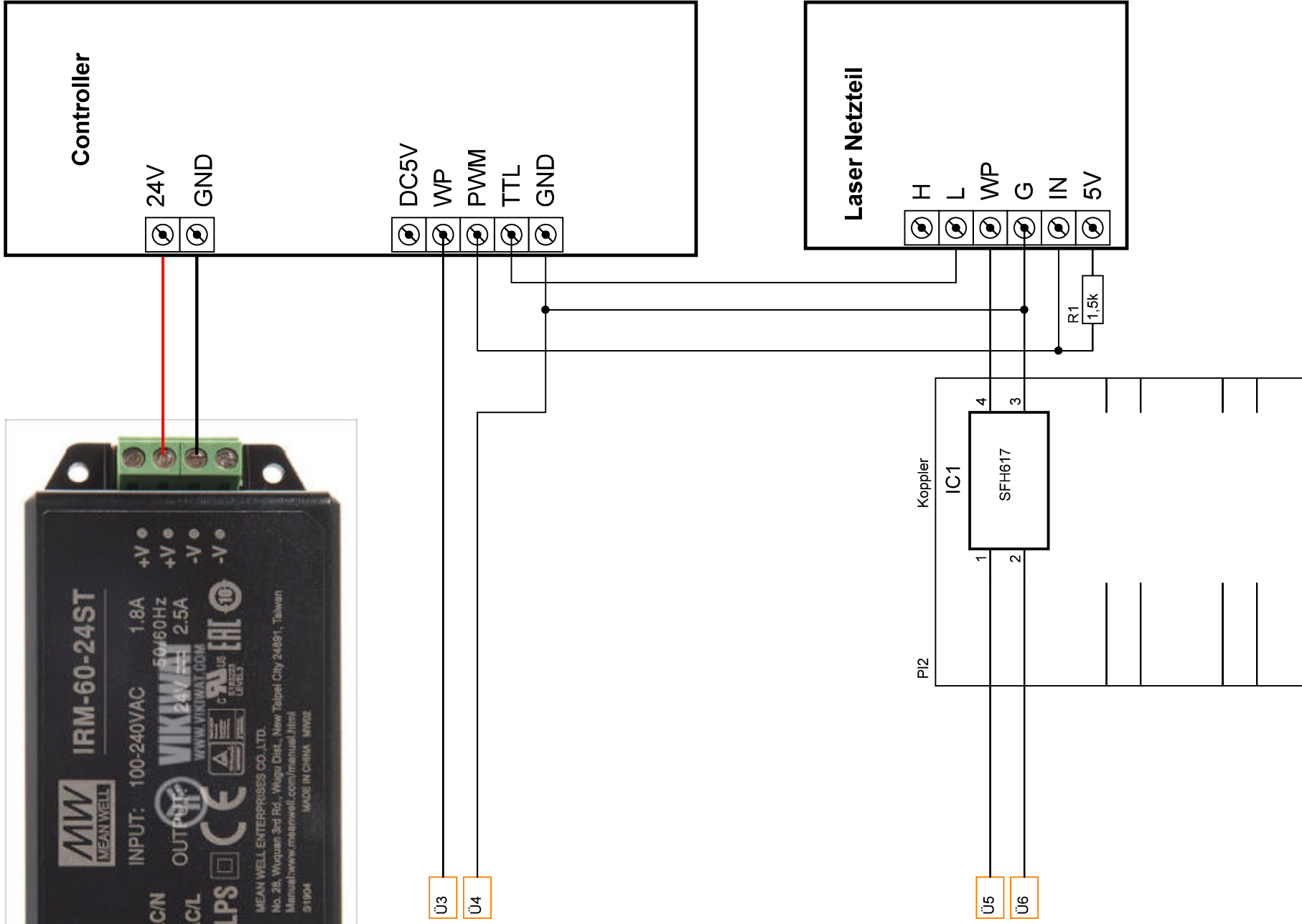


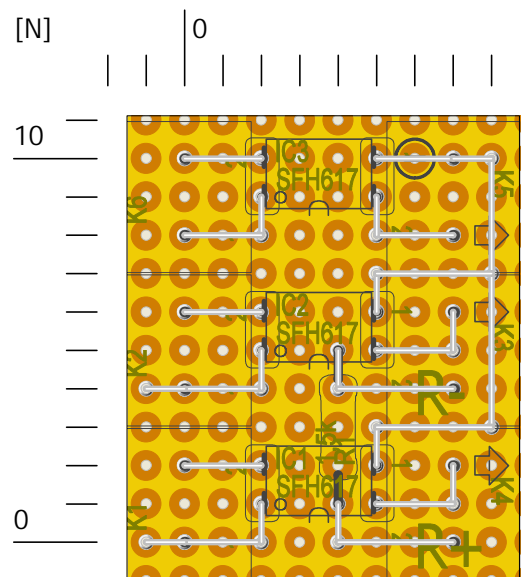
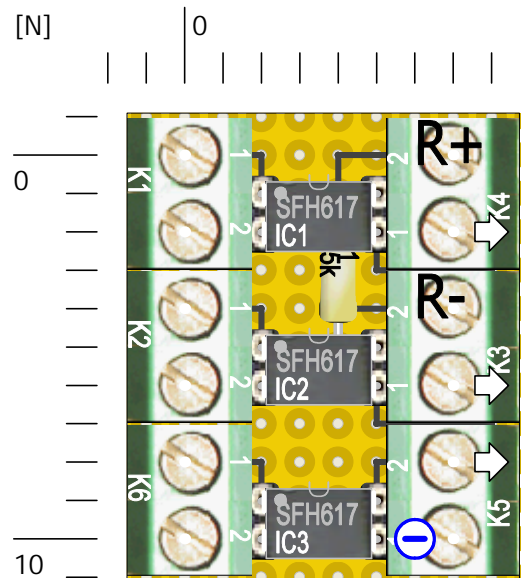
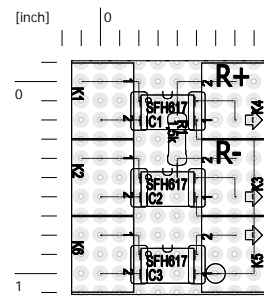
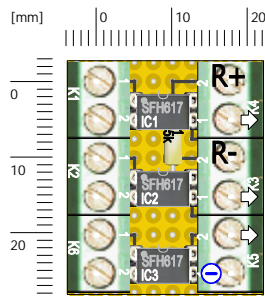
```
// Pin Assignments (Arduino) [A4, A5 =I2C][13-10, 4 =SPI] [0,1 =Serial]
FLOWMETER Pin 2 // input Flow Meter (INT0)
Cover Pin 3 //~ input front cover open / close (INT1)
FANSPEED Pin 5 //~ PWM - this pin will drive the FET for the cooling fan
OWB Pin 6 //~ PWM - 1-Wire Bus
Emergency Pin 7 // emergency shutdown aktiv
BUS-Error Pin 8 // LED flashing: I2C & OWB off =0,25s, I2C off =0,5s, OWB off =1s
LCPOWERUP Pin 9 // Switch on POWER (HIGH) [from RFID]
ENALaser Pin A0 // Enable High Power Laser (WP)
SECURITY Pin A1 // Security relais High Power Laser
SSR Machine Pin A2 // POWER Switch
POWERV Pin A3 // POWER voltage value
```

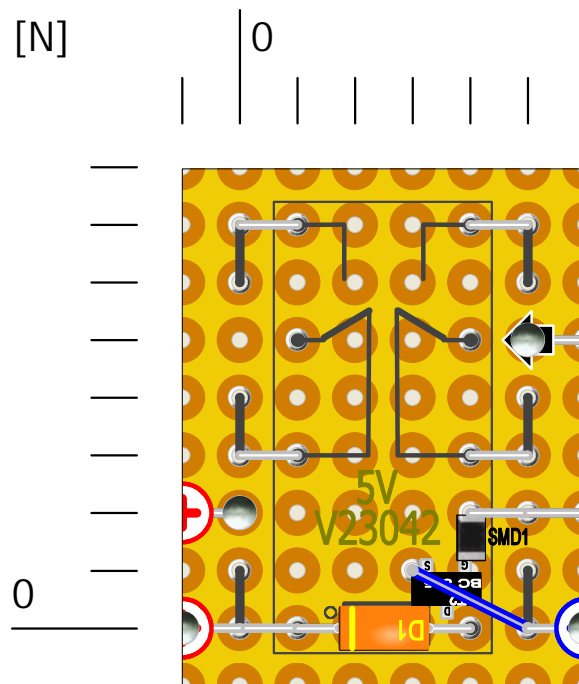
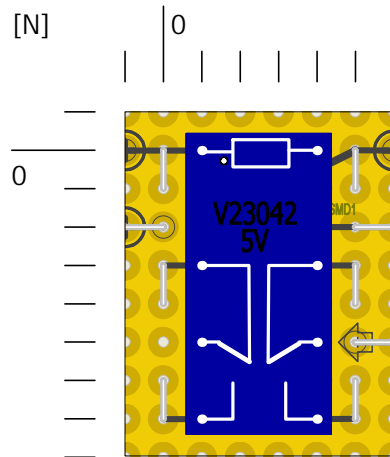
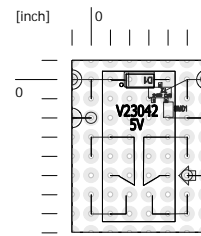
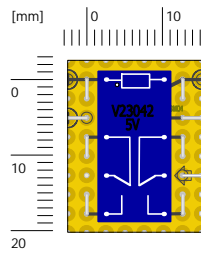


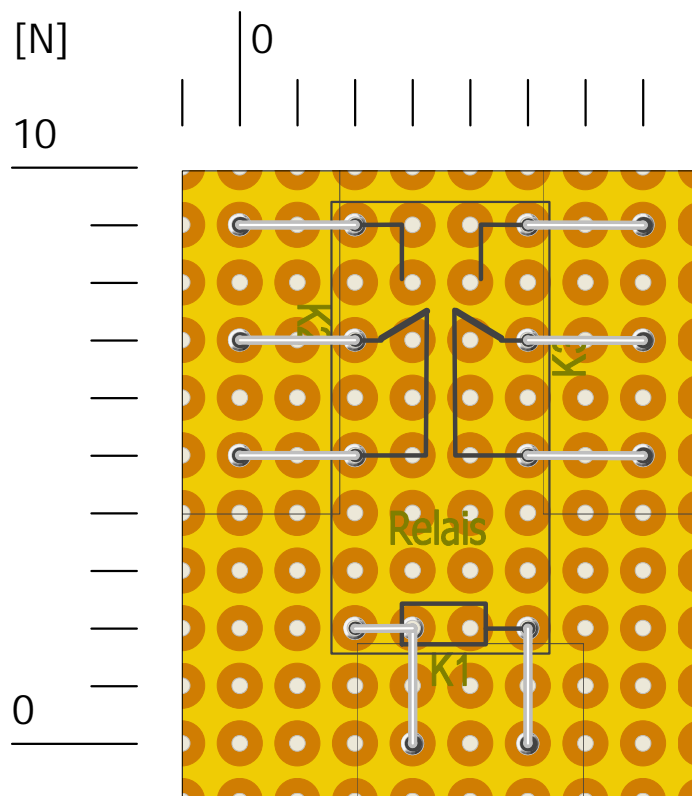
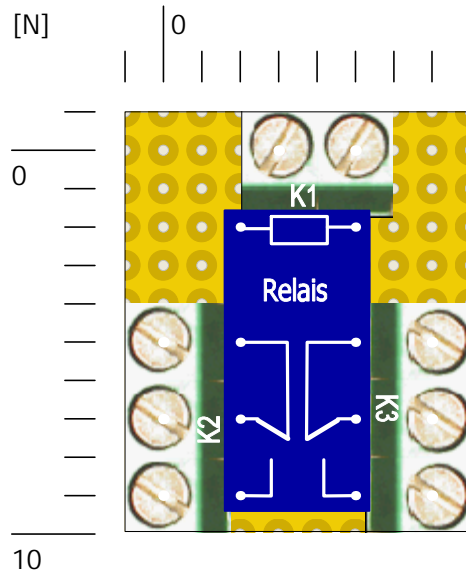
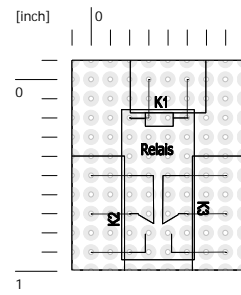
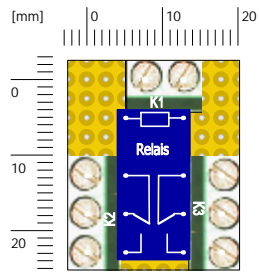


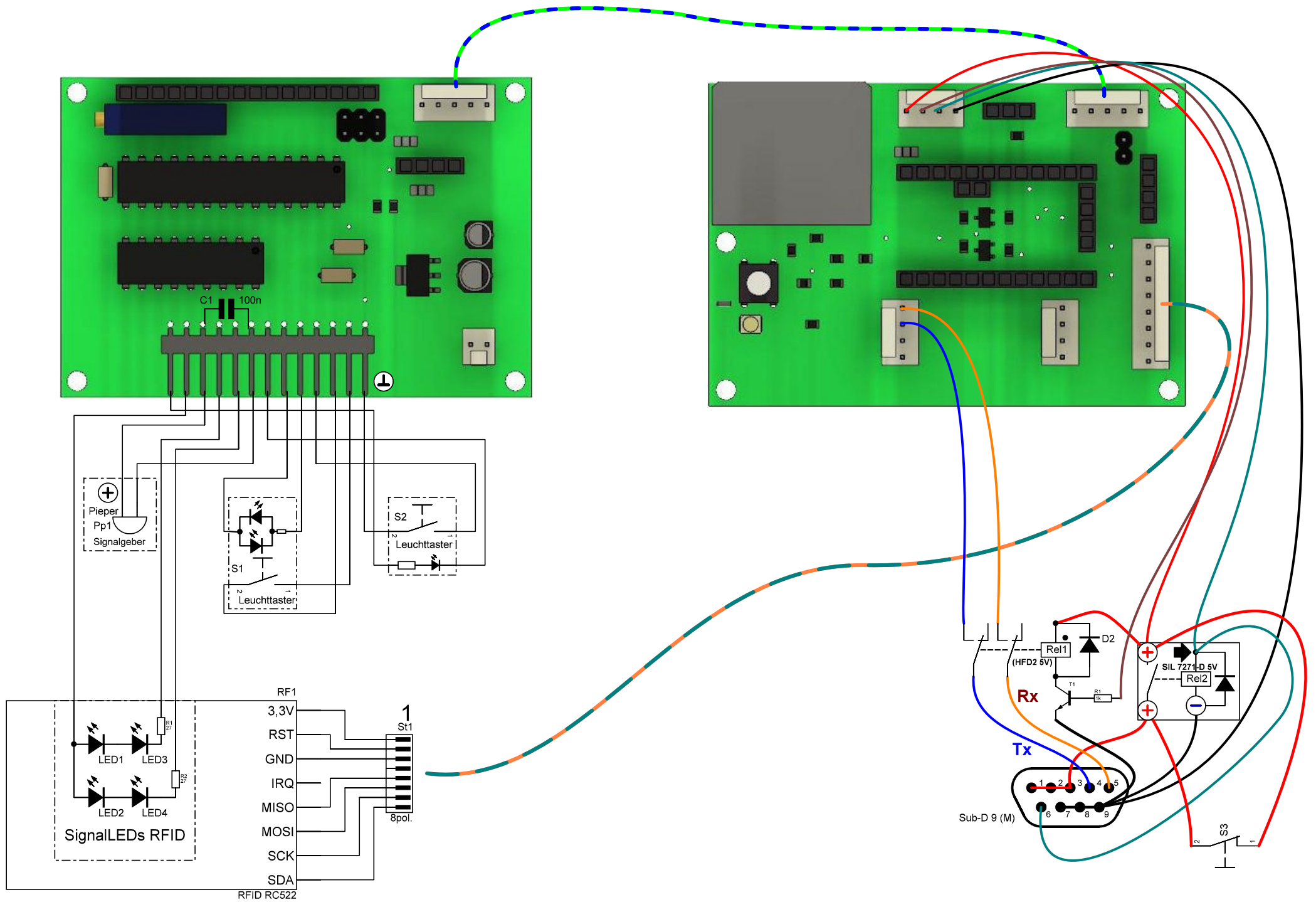


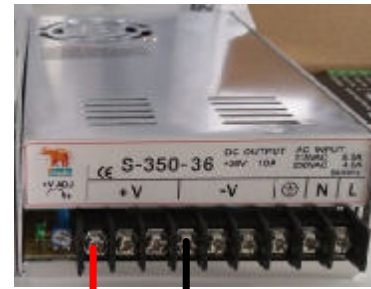






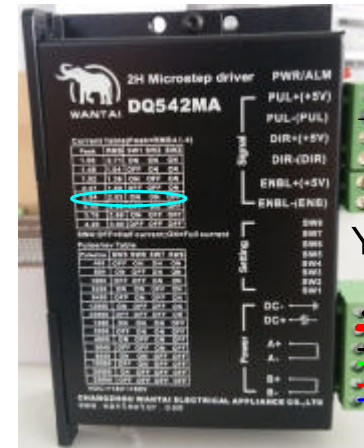




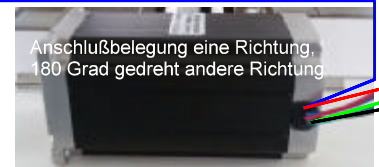


+ Z-Achse

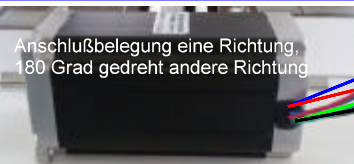
X-Achse



Y-Achse rechts



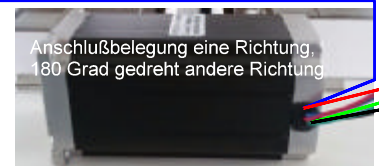
Anschlußbelegung eine Richtung,
180 Grad gedreht andere Richtung



Anschlußbelegung eine Richtung,
180 Grad gedreht andere Richtung



Y-Achse links



Anschlußbelegung eine Richtung,
180 Grad gedreht andere Richtung

