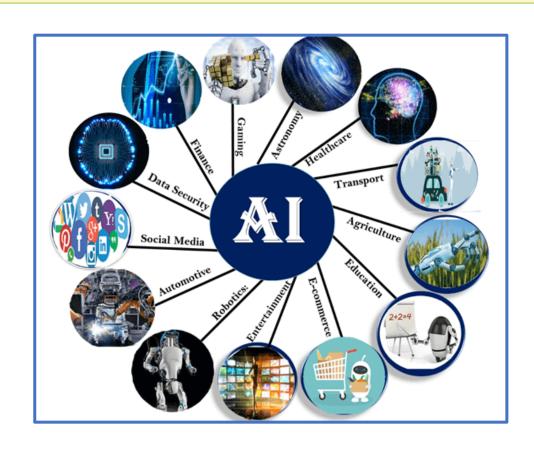
Introduction to Artificial Intelligence (20 Hours)

- Session 1-5:
- o Definition of Artificial Intelligence
- o Understanding Al
- o Different types of AI and main domains of AI technology
- Session 6-10:
- o History of Al
- o Al Uses
- o Various applications of Al
- Session 11-13:
- o Advantages and disadvantages associated with Artificial Intelligence
- Session 14-16:
- o Learn about the basics of Neural Networks, Fuzzy Logic and Genetic Algorithms
- Session 17-20:
- o Current trends and future directions in A

Definition of Artificial Intelligence

Artificial Intelligence is composed of two words Artificial and Intelligence, where Artificial defines "man-made," and intelligence defines "thinking power", hence AI means "a man-made thinking power."



Application of Al

Year 1956

first adopted by American Computer scientist John McCarthy at the Dartmouth Conference. For the first time, AI coined as an academic field.

Different domains of Artificial intelligence(AI)

There are certain domains of artificial intelligence on which we can create our expertise

- 1. Machine learning
- 2.Deep learning
- 3. Robotics
- 4.Expert systems
- 5. Fuzzy logic
- 6. Natural language processing
- 7. Computer vision

1. Machine learning

Machine learning is a subset of artificial intelligence. Machine learning enables computers or machines to make data-driven decisions rather than being explicitly programmed for a certain task.

These programs or algorithms are designed in a way that they learn and improve over time when are exposed to new data.

Different types of machine learning models

Supervised learning Unsupervised learning Reinforcement learning

Use cases

Product recommendation on a shopping website. spam filter on email.

Chatbots

2.Deep learning

Deep learning is artificial intelligence (AI) function that imitates the working of the human brain in processing data and creating patterns for use in decision making.

Deep learning is a subset of machine learning in artificial intelligence that has network capable of learning unsupervised from data that is unstructured or unlabeled also known as deep neural learning or deep neural network.

Different types of deep learning models

- 1.Autoencoders
- 2.Deep belief net
- 3.Convolutional neural network
- 4.Recurrent neural network
- 5. Reinforcement learning to neural network

Use cases

- Driverless vehicles
- Virtual assistants
- chatbots
- Medical research
- Facial recognition

3. Robotics

Robotics is a branch of engineering that involves the conception, design, manufacture, and operation of robots. This fields overlaps with electronics, computer science, artificial intelligence, mechatronics, nanotechnology and bioengineering.

Different types of robots

- 1.Pr-programmed robots
- 2. Humanoid robots
- 3. Autonomous robots
- 4.Teleoperated robots
- 5. Augmenting robots

Use cases

- Manufacturing
- Logistics
- •Healthcare
- •Home

4. Expert system

An expert system is a program that uses artificial intelligence technology to simulate the knowledge and judgement of humans. Expert systems usually include a subject-specific knowledge base and can have additional modules added to expand their capacities.

Different types of expert systems

Rule-based systems

Frame-based systems

Hybrid systems

Model-based systems

Off the shelf systems

Custom made systems

Use cases

In the medical field In the agriculture field In the education field

5. Fuzzy logic

Fuzzy logic is a method of reasoning that resembles human reasoning. The approach of fuzzy logic imitates the way of decision making in humans that involves all intermediate possibilities between digital values yes or no.

The conventional logic block that a computer can understand takes precise input and produces a definite output as true or false which is equivalent to human's yes or no.

Different types of fuzzifier

- 1. Singleton fuzzifier
- 2.Gaussian fuzzifier
- 3. Trapezoidal or triangular fuzzifier

Use cases

- Psychology
- Pattern recognition and classifications
- Securities
- Medical
- Marine
- Finance

6. Natural language processing

Natural language processing is a branch of artificial intelligence that helps the computers understand interpret and manipulate human language.

Natural language processing draws from many disciplines including computers science and computational linguistics in its pursuit to fill the gap between human communication and computer understanding.

Different types of Natural language processing (NLP)

- 1. Optical character recognition
- 2.Speech recognition
- 3. Machine translation
- 4. Natural language generation
- 5. Sentiment analysis
- 6.Semantic search
- 7. Machine learning

Use cases

- •Email filter
- •Smart assistants
- Search results
- Predictive text
- •Language translation
- Digital phone calls
- Text analytics

7. Computer vision

Today, computer vision is one of the hottest subfields of artificial intelligence and machine learning given its wide variety of applications and tremendous potential. It's a goal to replicate the powerful capacities of human vision.

Computer vision system must recognize the present objects and their characteristics such as shapes textures, colours, sizes, spatial arrangement, among other things to provide a description as complete as possible of the image.

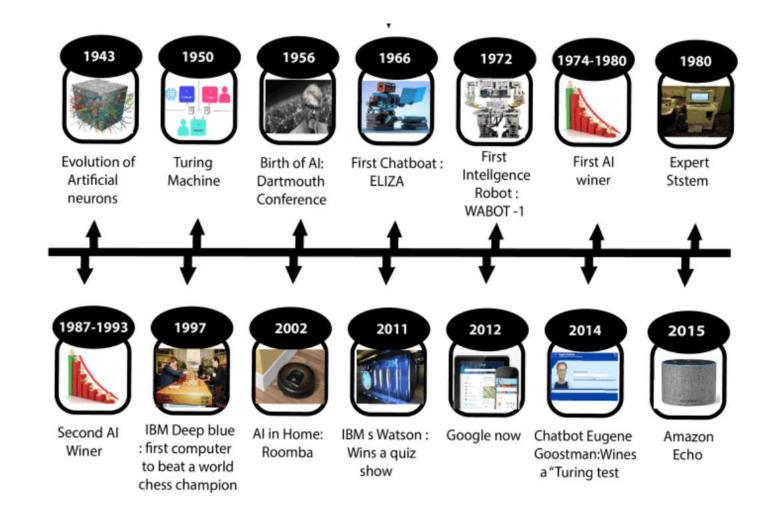
Different techniques of computer vision

Image classification
Object detection
Object tracking
Semantic segmentation
Instance segmentation

Use cases

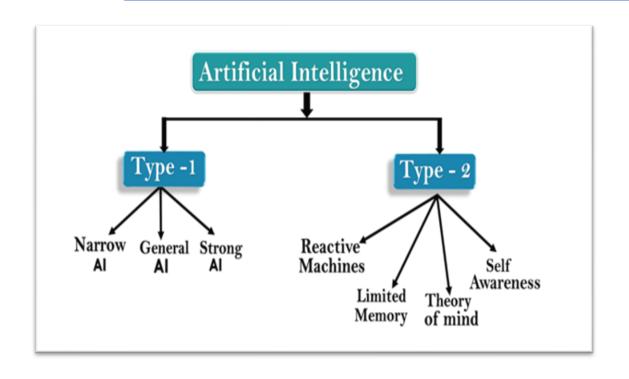
Defect detection Metrology Intruder detection Assembly verification Screen reader

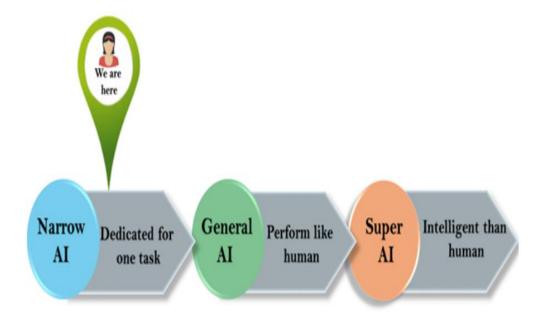
History of Artificial Intelligence



Types of Artificial Intelligence

Artificial Intelligence can be divided in various types, there are mainly two types of main categorization which are based on capabilities and based on functionally of AI. Following is flow diagram which explain the types of AI.





Narrow or Weak Al

Narrow AI cannot perform beyond its field or limitations, as it is only trained for one specific task. Hence it is also termed as weak AI. Narrow AI can fail in unpredictable ways if it goes beyond its limits.

Some Examples of Narrow AI are playing chess, purchasing suggestions on e-commerce site, self-driving cars, speech recognition, and image recognition.

Super Al

Super AI is a level of Intelligence of Systems at which machines could surpass human intelligence, and can perform any task better than human with cognitive properties. It is an outcome of general AI.

Some key characteristics of strong AI include capability include the ability to think, to reason, solve the puzzle, make judgments, plan, learn, and communicate by its own.

General AI

- •General AI is a type of intelligence which could perform any intellectual task with efficiency like a human.
- •Currently, there is no such system exist which could come under general AI and can perform any task as perfect as a human.

Advantages of Artificial Intelligence

Following are some main advantages of Artificial Intelligence:

High Accuracy with less errors: Al machines or systems are prone to less errors and high accuracy as it takes decisions as per pre-experience or information.

High-Speed: All systems can be of very high-speed and fast-decision making, because of that All systems can beat a chess champion in the Chess game.

High reliability: Al machines are highly reliable and can perform the same action multiple times with high accuracy.

Useful for risky areas: Al machines can be helpful in situations such as defusing a bomb, exploring the ocean floor, where to employ a human can be risky.

Digital Assistant: All can be very useful to provide digital assistant to the users such as All technology is currently used by various E-commerce websites to show the products as per customer requirement.

Useful as a public utility: Al can be very useful for public utilities such as a self-driving car which can make our journey safer and hassle-free, facial recognition for security purpose, Natural language processing to communicate with the human in human-language, etc.

Disadvantages of Artificial Intelligence

Every technology has some disadvantages, and the same goes for Artificial intelligence. Being so advantageous technology still, it has some disadvantages which we need to keep in our mind while creating an AI system. Following are the disadvantages of AI:

High Cost: The hardware and software requirement of AI is very costly as it requires lots of maintenance to meet current world requirements.

Can't think out of the box: Even we are making smarter machines with AI, but still they cannot work out of the box, as the robot will only do that work for which they are trained, or programmed.

No feelings and emotions: Al machines can be an outstanding performer, but still it does not have the feeling so it cannot make any kind of emotional attachment with human, and may sometime be harmful for users if the proper care is not taken.

- •Increase dependency on machines: With the increment of technology, people are getting more dependent on devices and hence they are losing their mental capabilities.
- •No Original Creativity: As humans are so creative and can imagine some new ideas but still AI machines cannot beat this power of human intelligence and cannot be creative and imaginative.

Goals of Artificial Intelligence

Following are the main goals of Artificial Intelligence:

Replicate human intelligence

Solve Knowledge-intensive tasks

An intelligent connection of perception and action

Building a machine which can perform tasks that requires human intelligence such as:

Proving a theorem

Playing chess

Plan some surgical operation

Driving a car in traffic

What is an Agent?

An agent can be anything that perceiveits environment through sensors and act upon that environment through actuators. An Agent runs in the cycle of perceiving, thinking, and acting. An agent can be:

Human-Agent: A human agent has eyes, ears, and other organs which work for sensors and hand, legs, vocal tract work for actuators.

Robotic Agent: A robotic agent can have cameras, infrared range finder, NLP for sensors and various motors for actuators.

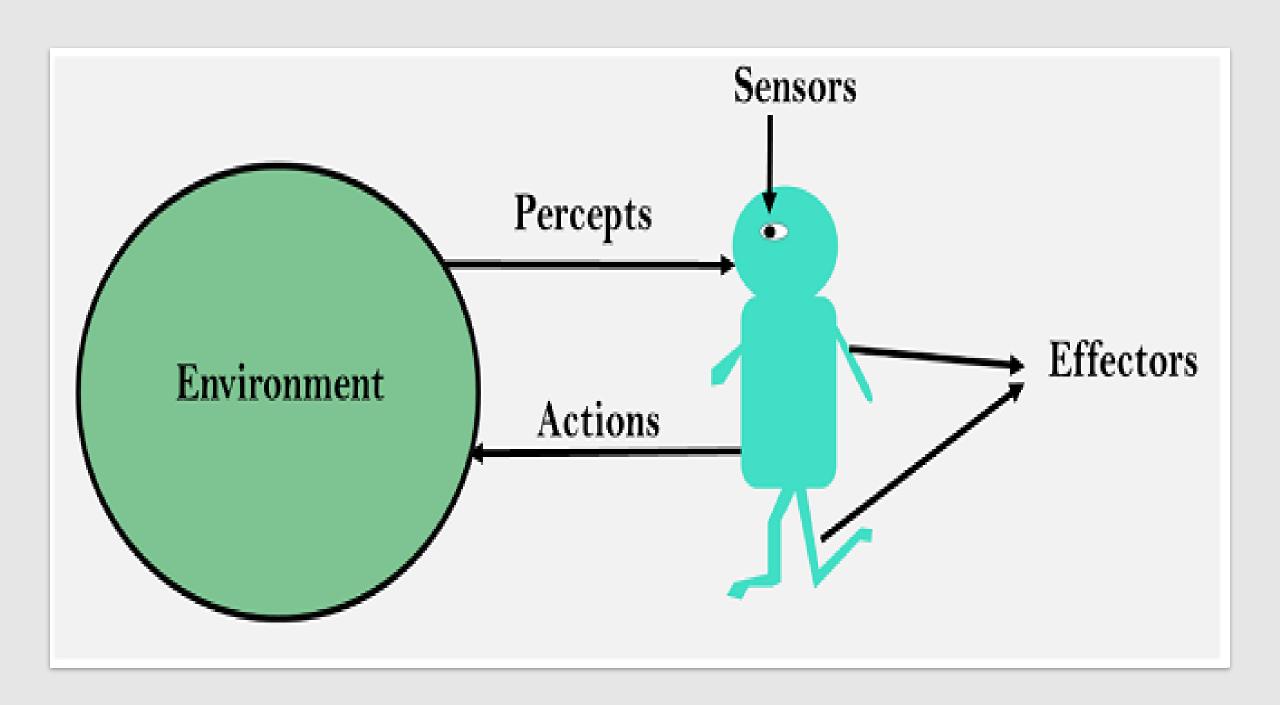
Software Agent: Software agent can have keystrokes, file contents as sensory input and act on those inputs and display output on the scree

Hence the world around us is full of agents such as thermostat, cellphone, camera, and even we are also agents. Before moving forward, we should first know about sensors, effectors, and actuators.

Sensor: Sensor is a device which detects the change in the environment and sends the information to other electronic devices. An agent observes its environment through sensors.

Actuators: Actuators are the component of machines that converts energy into motion. The actuators are only responsible for moving and controlling a system. An actuator can be an electric motor, gears, rails, etc.

Effectors: Effectors are the devices which affect the environment. Effectors can be legs, wheels, arms, fingers, wings, fins, and display screen.



Uninformed Searching

- 1) Seasch without Information
- 2) No knowledge
- Time Consuming
- More Complexity (Time, Space)
- DFS, BFS, etc.

Informed Searching

- 1) Seasich with information
- 2) Use knowledge to find steps to solution
- 3) Quick solution
- 4) Less Complexity (Time, Space)
- Hewistic DFS, Best finst Seasch

Hewristic

Agents / Intelligent Agents Coverent + History Porcept Change Actuator (Actions) Groals of Agent -> High Performance P: Performance E: Envisionment Optimized Result A: Actions Rational Action Right S : Sensons Agent -> Percept -> Decision -> Actions

Ty pes

- 1) Simple Reflex Agents
- 2) Model Based Reflex
- 3) Groal Based Agents
- 4) Utility-Based Agents
- 5) Learning Agents

Simple Reflex Agents ->/Act only on the basis of current perception Ignore the nest of porcept history -> Based on If - Then Rules -> Environment should be fully observable. Partially if +amp > 450 if Room is not empty

Envisionment Porcept Consent situation (What the wooded is like now) if they (Condition) Action

1. Simple Reflex agent:

The Simple reflex agents are the simplest agents. These agents take decisions on the basis of the current percepts and ignore the rest of the percept history.

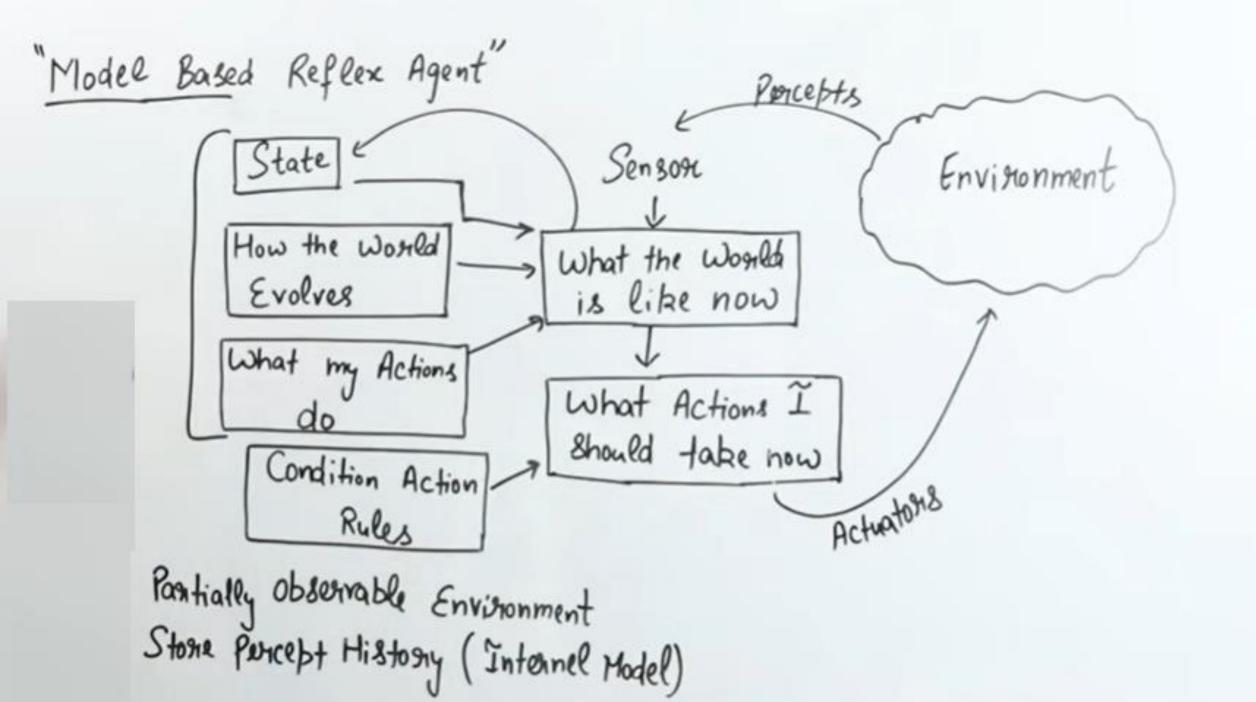
These agents only succeed in the fully observable environment.

The Simple reflex agent does not consider any part of percepts history during their decision and action process. The Simple reflex agent works on Condition-action rule, which means it maps the current state to action.

Such as a Room Cleaner agent, it works only if there is dirt in the room.

Problems for the simple reflex agent design approach:

They have very limited intelligence
They do not have knowledge of non-perceptual parts of the current state
Not adaptive to changes in the environment.



2. Model-based reflex agent

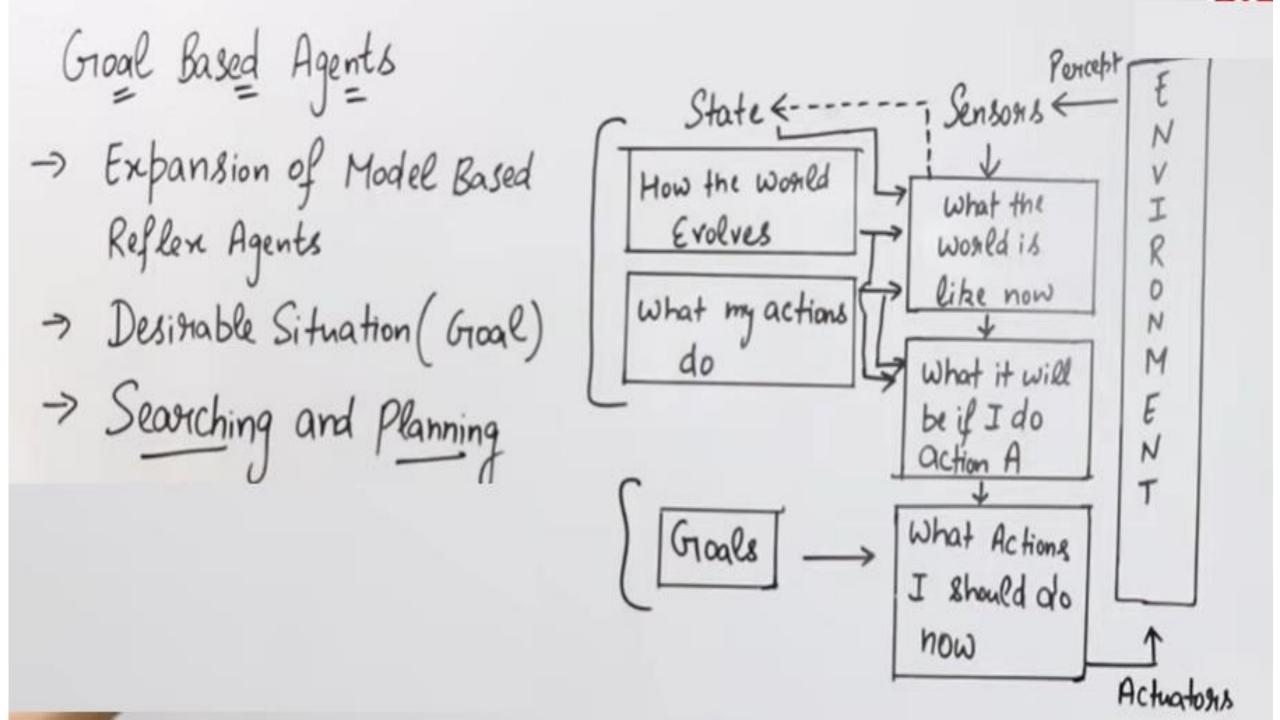
The Model-based agent can work in a partially observable environment and track the situation.

A model-based agent has two important factors:

based agent.

Model: It is knowledge about "how things happen in the world," so it is called a Model-

Internal State: It is a representation of the current state based on percept history.



3. Goal-based agents

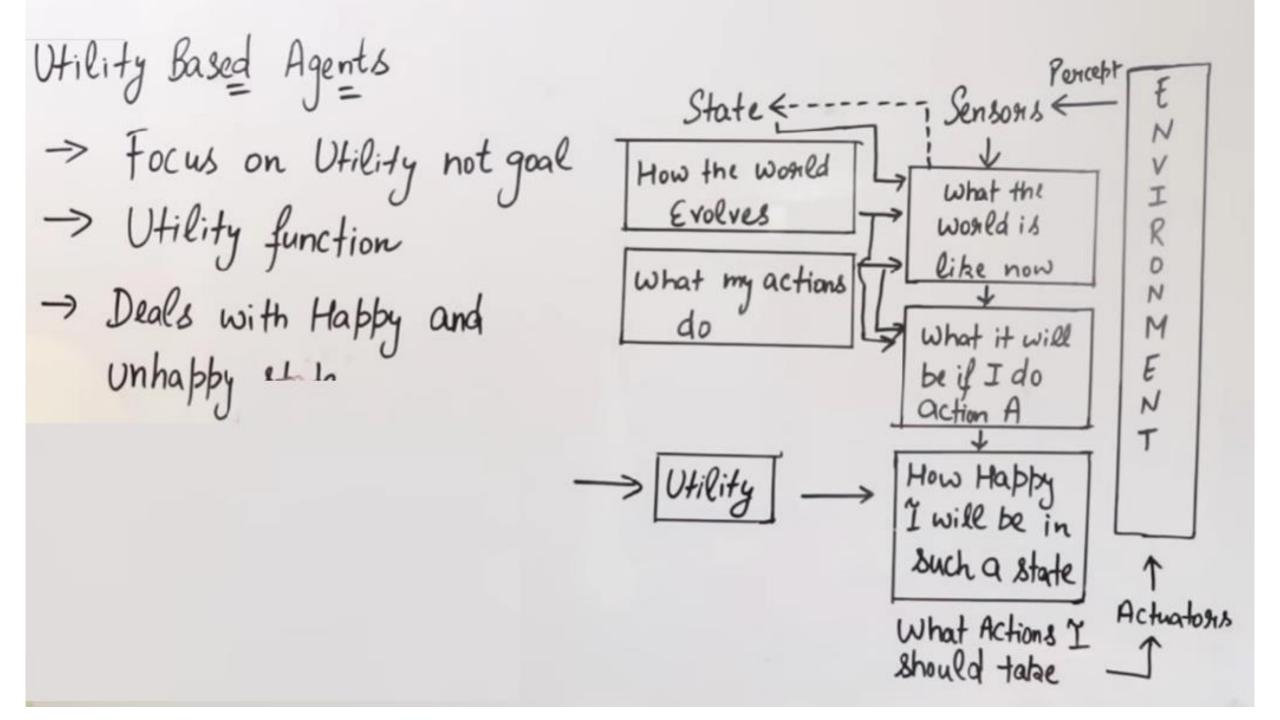
The knowledge of the current state environment is not always sufficient to decide for an agent to what to do.

The agent needs to know its goal which describes desirable situations.

Goal-based agents expand the capabilities of the model-based agent by having the "goal" information.

They choose an action, so that they can achieve the goal.

These agents may have to consider a long sequence of possible actions before deciding whether the goal is achieved or not. Such considerations of different scenario are called searching and planning, which makes an agent proactive.



Utility-based agents

- •These agents are similar to the goal-based agent but provide an extra component of utility measurement which makes them different by providing a measure of success at a given state.
- •Utility-based agent act based not only goals but also the best way to achieve the goal.
- •The Utility-based agent is useful when there are multiple possible alternatives, and an agent has to choose in order to perform the best action.
- •The utility function maps each state to a real number to check how efficiently each action achieves the goals.

Artificial Intelligence: - AI is the study of How to make computer do things which people do better. [machine + human Intelligence] - Al Can Cause a machine to work as -> AI Astificial [Man-Made] > Intelligence [Power of thinking] LioALS OF Al: i) Replication of Human Intelligence. ii) Solving problems - that require knowledge. iii) Building a machine that con do human Intelligence task. [CHESS, Priving theorem, automated car driving...]

Reasons of Boost in AI:

is I wor device an be made to solve Real-time Ymblems.

us Creation of Virtual assistant [SIRI, CORTANA]

in Robots development. [Helps in dangerous env. cond]

(v) New Job opportunities.

Applications of Al: (6) Enpert System: Integration of slu (i) Al in Ganing: Chess, roker, tic-toe. machine and special infor to provide reasoning & advise. -> machine Can think large no. of (7) Computer Vision: Understand 2) Al in NLP: Natural Dlong. Processing the visual automatically by Ly Machine Can understand human lang. machine. 3) Al in HealthCare: Fast diagonsis 8) Speech Recognition: Entract - the - Robotic Surgery. meaning of sentence by human talk. [Slong removal noise rem. (4) Al in Finance: Adaptive Intelligence Soutomatic chatboots, algorithm Talk and > Erica and sophia. (5) Al in Data Security: Helps in making behave like homans.

10 Al in e-Commerce: Automatic data opph more secure. -> AEG bot, AI2 recommendation of

Al is comprised of:	Advantages of Al	Disadvantages of Al
Sociology Computer	Accuracy 9 & Error &	COST 4
Artificial	Fast Decision Making.	Can't thing beyond-the limits.
Psycho - Intelligence Biolog	Reliability is more	No feeling 2 emotions
Math's Science	Usefulness in Risky	more dependency on machines 4.
La Reasoning	Area.	
Learning Problem solving	Digital Assistant	No original thinking
-> Language Undestand	ing.	

NEAK Al: Able to perform dedicated task with Intelligence. [Not concerned Lan't perform beyond its field or limitations. Enample: Flying machine
Using logics
Apple SIRI
Playing chess Evolutionary Al: It is the Study and design of machines that Simulate Simple Creatures and attempt to evolve. - Enample: Ants, Bees etc.

Strong Al: It is the Study and design of machines that Simulate human mind to perform intelligent tasks.

from psychology and neuroscience

in Forgetting things, andics,

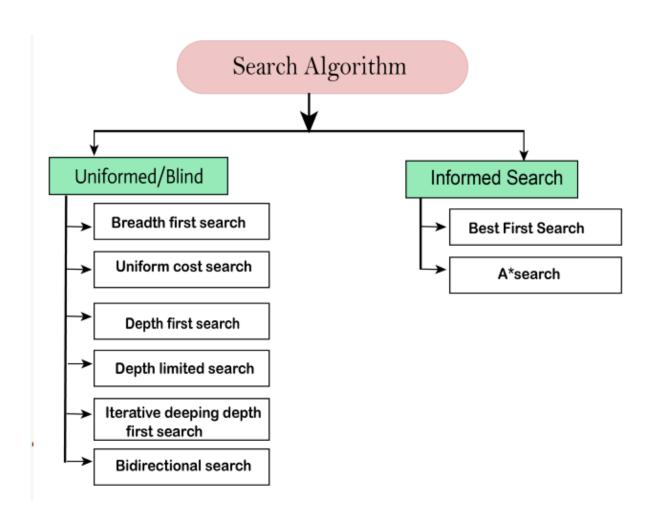
Language.

Super Al! - Hypothetical Concept.
machine > Human.

machine + machine]

Types of search algorithms

Based on the search problems we can classify the search algorithms into uninformed (Blind search) search and informed search (Heuristic search) algorithms.



Difference between Informed and Uninformed Search in AI

Informed

- •Use of Heuristics informed search algorithms use heuristics, or additional information, to guide the search process and prioritize which nodes to expand.
- •More efficient informed search algorithms are designed to be more efficient than uninformed search algorithms, such as breadth-first search or depth-first search, by avoiding the exploration of unlikely paths and focusing on more promising ones.
- •Goal-directed informed search algorithms are goal-directed, meaning that they are designed to find a solution to a specific problem.
- •Cost-based informed search algorithms often use cost-based estimates to evaluate nodes, such as the estimated cost to reach the goal or the cost of a particular path.
- •Prioritization informed search algorithms prioritize which nodes to expand based on the additional information available, often leading to more efficient problem-solving.
- •Optimality informed search algorithms may guarantee an optimal solution if the heuristics used are admissible (never overestimating the actual cost) and consistent (the estimated cost is a lower bound on the actual cost).

Examples of informed search algorithms include A* search, Best-First search, and Greedy search. Example: Greedy Search and Graph Search.

Uninformed Search in AI

Algorithms have no additional information on the goal node other than the one provided in the problem definition.

uninformed search algorithms in Al:

- •Systematic exploration uninformed search algorithms explore the search space systematically, either by expanding all children of a node (e.g. BFS) or by exploring as deep as possible in a single path before backtracking (e.g. DFS).
- •No heuristics uninformed search algorithms do not use additional information, such as heuristics or cost estimates, to guide the search process.
- •Blind search uninformed search algorithms do not consider the cost of reaching the goal or the likelihood of finding a solution, leading to a blind search process.
- •Simple to implement uninformed search algorithms are often simple to implement and understand, making them a good starting point for more complex algorithms.
- •Inefficient in complex problems uninformed search algorithms can be inefficient in complex problems with large search spaces, leading to an exponential increase in the number of states explored.

Ques! Differentiate blw blind and heuristic Search. Blind Search: It is also known as Heuristic Search: It is a method of Solving problems more easily and fast. They have unknown/uninformed Search. Knowledge of where god or finish of the graph. (Informed Search) Ly There is no info about the Searching.

Ly No Knowledge of where the GOAL.

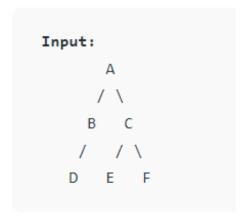
Ly Eg:- Depth dirst, Breadth first Search Eg:- Hill climbing, A", Ao* → Highly efficient (less time less cost > Efficiency is low L. Slower than Heuristic 4 finds sol Quickly.

Difference between BFS and DFS

Breadth-First Search

BFS, Breadth-First Search, is a vertex-based technique for finding the shortest path in the graph. It uses a Queue data structure that follows first in first out. In BFS, one vertex is selected at a time when it is visited and marked then its adjacent are visited and stored in the queue. It is slower than DFS.

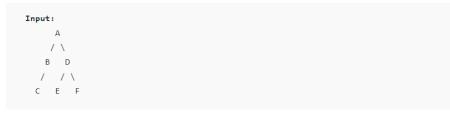
Example:



Output:

Depth First Search

DFS, Depth First Search, is an edge-based technique. It uses the Stack data structure and performs two stages, first visited vertices are pushed into the stack, and second if there are no vertices then visited vertices are popped. Example:



Dutput:

A, B, C, D, E, F

S. No.	Parameters	BFS	DFS	
1.	Stands for	BFS stands for Breadth First Search.	DFS stands for Depth First Search.	
2.	Data Structure	BFS(Breadth First Search) uses Queue data structure for finding the shortest path.	DFS(Depth First Search) uses Stack data structure.	
3.	Definition	BFS is a traversal approach in which we first walk through all nodes on the same level before moving on to the next level.	DFS is also a traversal approach in which the traverse begins at the root node and proceeds through the nodes as far as possible until we reach the node with no unvisited nearby nodes.	
4.	Technique	BFS can be used to find a single source shortest path in an unweighted graph because, in BFS, we reach a vertex with a minimum number of edges from a source vertex.	In DFS, we might traverse through more edges to reach a destination vertex from a source.	
5.	Conceptual Difference	BFS builds the tree level by level.	DFS builds the tree sub-tree by sub-tree.	
6.	Approach used	It works on the concept of FIFO (First In First Out).	It works on the concept of LIFO (Last In First Out).	

What is the other name of informed search strategy?

- a) Simple search
- b) Heuristic search
- c) Online search
- d) None of the mentioned

Uninformed search strategies are better than informed search strategies.

- (A). True
- (B). False
- (C). Partially true
- (E). None of these

Which of the following strategy is commonly known as a blind search?

- (A). Simple reflex search
- (B). Informed search
- (C). Uninformed search
- (D). All of these
- (E). None of these

Best-First search can be coded with the help of which of the following data structure.

- (A). Queue
- (B). Stack
- (C). Linked list
- (D). All
- (E). None of these

Which of the following is the search strategy the uses a not problem specific knowledge?

Which of the following is the search strategy the uses a problem specific knowledge?

- (A). Informed Search
- (B). A* algorithm
- (C). Uninformed search
- (D). All of these
- (E). None of these

which of the following uninformed search provides optimal solution?

- a) Breadth First search
- b) Depth First search
- c) A star
- d) None of the mentioned

Ques: Emplain Formal, Mundane and Expert tasks in Al. Ventication Humans Learns Mundane (Ordinary) tasks formal Task:- < -> Mathematics Theorem
-> Geometry. Proving.
-> logic , Go
-> Game-theor. Since - their birth Perception Easiest to Learn by Speaking lean.

Speaking languages lean. -> Game-theory + Chess tormal and Enpert task are learn later in the order. Entrest Task: Engineering, Mundane: - O Perception Speech Voice. Ly Manufacturing 2 NLP (Lang. generate Lang. Translation. -> Monitoring 1- Scientific, financial, Medical 3 Reasoning 4 Robotics (locomotive)

Ques: - what do you mean by Chinese Koom Test? BASIC CONFIGURATION: Enplain how it can be performed? -> A besson knowing english not chinese -> Also Known as Chinese Room Argument. sits in mom with huge volume of -> Proposed by Mr. John Searle in 01980. Chinese literature. -> Chinese Symbol B, return 4. [Kules - Argued that Turing Test Could not be By, return &. used to determine whether or not machine is Considered as Intelligent" Inbut (chi. According to John. Scarle a machine Could pass Chinese Turing Test Simply by manipulating Symbols, without any understanding of those symbols. T0/8 Ly A person/machine Can be Considered as Intelligent, Chinesa if and only if they Capital of India? [fdatabase > Knows only english have understanding of what they are doing!

Ques: what do you mean by uncertainity? why uncertainity anises? Uncertainity is defined as the Lack of enact infor or knowledge -that helps us to find correct Uncertainity may be caused by problems with data Such as: → 1 Missing (un available data 2 Unreliable lambiguous data 3 Imprecise/Inconsistent rep of data 4 Guess based

Sources of Uncertainity:

→ ① Uncertain Inputs

→ Missing Data

→ Noisy data

2 Uncertain Knowledge

-multiple Causes leads

-lo multiple effects.

- homplete knowledge of

Casuality in domain.

3 Uncertain outputs

Los Abduction, induction

are uncertain

Default reasoning

Incomplete deduction

inference.

Medical Diagnosis system is example of which task domain in artificial intelligence.

a) Mundane Task b) Expert task c) Formal Task d) Categorical Task

Which of the following is not a task domain in artificial intelligence?

- a) Mundane Task
- b) Expert task
- c) Formal Task
- d) Categorical Task

Artificial Intelligence is about 1.Playing a game on Computer	
2.Making a machine Intelligent	
3.Programming on Machine with your Own Intelligence	
4.Putting your intelligence in Machine	
Who is known as the -Father of AI"?	
1.Fisher Ada	
2.Alan Turing	
3.John McCarthy	
4.Allen Newell	
Select the most appropriate situation for that a blind	
search can be used.	
1.Real-life situation	
2.Small Search Space	
3.Complex game	
4.All of the above	
The application/applications of Artificial Intelligence	
is/are	
1.Expert Systems	
2.Gaming	
3. Vision Systems	
4.All of the above	
If a robot is able to change its own trajectory as per the	
external conditions, then the robot is considered as	
the	
1 Mahila	
1.Mobile 2.Non-Servo	
3.Open Loop	
4.Intelligent	
4.intengent	

Which of the given language is not commonly used for AI? 1.LISP 2.PROLOG 3.Python 4.Perl
A technique that was developed to determine whether a machine could or could not demonstrate the artificial intelligence known as the
1.Boolean Algebra2.Turing Test3.Logarithm4.Algorithm
The component of an Expert system is 1.Knowledge Base 2.Inference Engine 3.User Interface 4.All of the above
Which algorithm is used in the Game tree to make decisions of Win/Lose? 1.Heuristic Search Algorithm 2.DFS/BFS algorithm 3.Greedy Search Algorithm 4.Min/Max algorithm
An Al agent perceives and acts upon the environment using 1.Sensors 2.Perceiver 3.Actuators 4.Both a and c

Which rule is applied for the Simple reflex agent?

- 1.Simple-action rule
- 2.Simple &Condition-action rule
- 3. Condition-action rule
- 4. None of the above

Explanation: The simple reflex agent takes decisions only on the current condition and acts accordingly; it ignores the rest of history; hence it follows the Condition-action rule

Which agent deals with the happy and unhappy state?

- 1.Utility-based agent
- 2.Model-based agent
- 3.Goal-based Agent
- 4.Learning Agent

Utility-based agent uses an extra component of utility that provides a measure of success at a given state. It decides that how efficient that state to achieve the goal, which specifies the happiness of the agent.

Which term describes the common-sense of the judgmental part of problem-solving?

- 1.Values-based
- 2.Critical
- 3.Analytical
- 4.Heuristic

In problem-solving, the Heuristic describes the common sense or Judgemental part.

Which AI technique enables the computers to understand the associations and relationships between objects and events?

- 1.Heuristic Processing
- 2. Cognitive Science
- 3. Relative Symbolism
- 4. Pattern Matching

Pattern matching is a way to check a given sequence of tokens in order to determine the presence of a given character or data in the given sequence. It allows computers to understand the relationship between objects and events.

The search algorithm which is similar to the minimax search, but removes the branches that don't affect the final output is known as__.

- 1.Depth-first search
- 2.Breadth-first search
- 3.Alpha-beta pruning
- 4. None of the above

<u>Alpha-beta pruning</u> algorithm is the modified version of the Minimax algorithm and returns the same moves as the original algorithm, but it removes all those nodes/branches that do not affect the final decision.

Which algorithm takes two sentences as input and returns a Unifier?

- 1.Inference
- 2.Hill-Climbing
- 3. Unify algorithm
- 4.Depth-first search

The unify algorithm takes two atomic sentences and return a unifier. It is used for the unification process.

The PEAS in the task environment is about

- 1.Peer, Environment, Actuators, Sense
- 2.Performance, Environment, Actuators, Sensors
- 3. Perceiving, Environment, Actuators, Sensors
- 4. None of the above

Performance, Environment, Actuators, Sensors

In state-space, the set of actions for a given problem is expressed by the_____.

- 1.Intermediate States
- 2. Successor function that takes current action and returns next state
- 3.Initial States
- 4. None of the above

Explain:The successor function provides a description of all possible actions and their next states, which means their outcomes.

In which search problem, to find the shortest path, each city must be visited once only?

- 1.Map coloring Problem
- 2.Depth-first search traversal on a given map represented as a graph
- 3. Finding the shortest path between a source and a destination
- 4. Travelling Salesman problem

The TSP or Travelling Salesman problem is about finding the shortest possible route to visit each city only once and returning to the origin city when the list of all cities and distances between each pair of cities is given.

Web Crawler is an example of
Intelligent Agent Problem-solving agent Simple reflex agent Model-based agent
Explanation: The web crawler is an example of Intelligent agents, which is responsible for collecting resources from the Web, such as HTML documents, images, text files, etc.
Ways to achieve AI in real-life are 1.Machine Learning 2.Deep Learning 3.Both a & b 4.None of the above
The main tasks of an Al agent are 1.Input and Output 2.Moment and Humanly Actions 3.Perceiving, thinking, and acting on the environment 4.None of the above
The best Al agent is one which 1.Needs user inputs for solving any problem 2.Can solve a problem on its own without any human intervention 3.Need a similar exemplary problem in its knowledge base 4.All of the above
Can solve a problem on its own without any human intervention.

How many types of Machine Learning are there?
1.1
2.2
3.3
4.4
Platforms like Netflix, Amazon, Spotify, YouTube etc. show us
recommendations on the basis of what we like. This become possible because
of
a. Artificial Intelligence
b. Machine Intelligence
c. Platform Intelligence
d. Application Intelligence
What is the term used for describing the judgmental or commonsense part of
problem solving?
1.Heuristic
2.Critical
3. Value based
4.Analytical
In LISP, the addition 3 + 2 is entered as
A.3 + 2
B. 3 add 2
C. 3 + 2 =
D. (+ 3 2)

Weak AI is

A.the embodiment of human intellectual capabilities within a computer.

B.a set of computer programs that produce output that would be considered to reflect intelligence if it were generated by humans.

C.the study of mental faculties through the use of mental models implemented on a computer.

D.All of the above

E.None of the above

A robot can alter its own trajectory in response to external conditions, it is considered to be: A.intelligent B.mobile C.open loop D.non-servo E.None of the abovbove

Nils Nilsson headed a team at SRI that created a mobile robot named:

A.Robitics

B.Dedalus

C.Shakey

D.Vax

E.None of the above

What is the name of the computer program that simulates the thought processes of human beings?

A.Human logic

B.Expert reason

C.Expert system

D.Personal information

E.None of the above

A computer program that contains expertise in a particular domain is called an:

A.intelligent planner

B.automatic processor

C.expert system

D.operational symbolizer

E.None of the above