Homework 4 Marlen Akimaliev BIL622-Numerical Analysis II

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Problem 1

Solve the following Boundary Value Problem:

$$x^2 \times y'' - x \times y = 3 \times x^3$$

$$y(1) = 2$$

$$y(2) = 9$$

Use shooting method for solution.

$\mathbf{2}$ Solution

In order to solve second order BVP problem it has to be converted into a first order system of two equations:

Higher order differential equations can be written as a system with a very simple change of variable. We'll start by defining the following two new functions.

$$x_1(t) = y(t)$$

$$x_2(t) = y'(t)$$

If we differentiate both sides of these we get;

$$x_1' = y' = x_2$$

$$x_2' = y'' = (3 \times x^3 + x \times y')/x^2 = (3 \times x^3 + x \times x_1)/x^2$$

Putting all of this together gives the following system of differential equations.

$$x_1' = x_2, x_1(1) = 2$$

$$x'_1 = x_2, x_1(1) = 2$$

 $x'_2 = (3 \times x^3 + x \times x_1)/x^2, x_1(2) = 9$

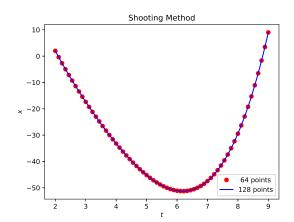
Following is the table after getting results at the range [2,9].

t	x
2.0	2.00000000000000000
2.8	-13.4076702532885363
3.6	-26.5513372930734732
4.3	-37.6932727986715363
5.1	-46.1898472357814711
5.9	-50.8412316172525038
6.7	-49.9920471001467845
7.4	-41.5416864109323285
8.2	-22.9134425699207362
9.0	9.00000000000004121

Following Python code [1] is used to evaluate values and plot the graph.

```
import numpy
def shoot( f, a, b, z1, z2, t, tol ):
    from diffeq import rk4
                      # Maximum number of shooting iterations
    max\_iter = 25
                      # Determine the size of the arrays we will generate
    n = len(t)
    y = rk4(f, [a, z1], t)
    w1 = y[n-1,0]
    for i in xrange( max_iter ):
         y = rk4(f, [a, z2], t)
         w2 = y[n-1,0]
         if abs(b-w2) < tol:
             break
         z1, z2 = (z2, z2 + (z2 - z1)) / (w2 - w1) * (b - w2))
         w1 = w2
    if abs(b - w2) >= tol:
         print "\a****_ERROR_****"
         print "Maximum_number_of_iterations_(%d)_exceeded" % max_iter
         print "Returned_values_may_not_have_desired_accuracy"
         print "Error_estimate_of_returned_solution_is_%e" % ( b - w2 )
    return y[:,0]
if _-name_- = "_-main_-":
    import math
    from pylab import *
    a = 2
    b = 9
    n1 = 10
    t1 = linspace(a, b, n1)
    # Compute shooting method solutions
    \mathbf{def} \ \mathbf{f}(\mathbf{x},\mathbf{t}):
         \textbf{return} \ \ \text{array} \left( \ \ \left[ \, x \, [\, 1 \, \right] \, , \ \ \left( \, 3 * \, t \, * * 3 + t \, * x \, [\, 0 \, \right] \, \right) / \, t \, * * 2 \, \right] \ \ )
    xs1 = shoot(f, 2, 9, 1.0, 10.0, t1, 1e-5)
    # Prepare for display; set interactive mode to true so each plot
    # is shown as it is generated
    interactive (True)
    for p1, p2 in list (zip(t1, xs1))[::1]:
         print ("%4.1f_%10.16f" % (p1, p2))
    # Plot solutions
    plot( t1, xs1, 'ro')
    title ('Shooting_Method')
    xlabel ("t")
    ylabel ("x")
    #legend(('%3d points' % n1, '%3d points' % n2), loc='lower right')
    savefig( '1_2.eps', fmt='EPS', dpi=100 )
    z = raw_input( "Press_ENTER_to_quit..." )
```

If we try to plot these values as a graph result is as follows:



References

[1] MAT342/CPS342 Python Demos, gordon.edu, http://www.math-cs.gordon.edu/courses/ma342/python/bvp.py