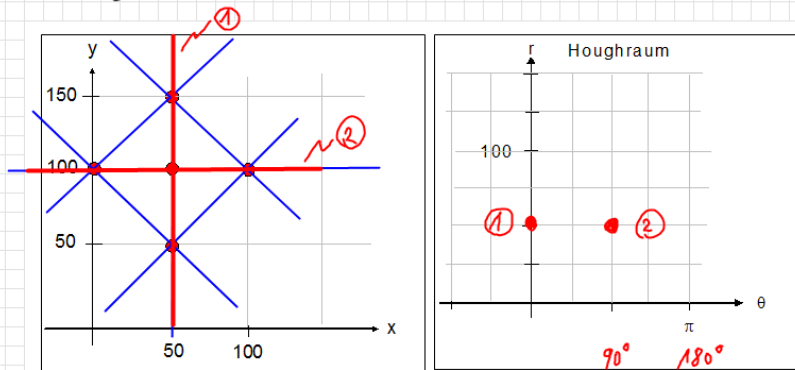


# Aufgabe 1



a) 6 Maxima

c)  $y = 3x + 2$

$$3x - y = -2 \quad /: (-2)$$

$$-1.5x + 0.5y = 1 \quad \Rightarrow \underline{A = -1.5} \quad \underline{B = 0.5}$$

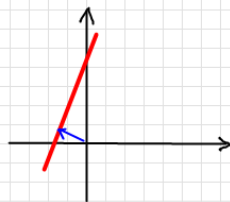
$$\frac{\cos \Theta}{r} x + \frac{\sin \Theta}{r} y = 1$$

$$x \cos \Theta + y \sin \Theta = r$$

$$\Rightarrow \frac{B}{A} = \frac{\sin \Theta}{\cos \Theta} = \tan \Theta$$

$$\Theta = \arctan \frac{B}{A} = \arctan \left( -\frac{2}{3} \right) = -18.43^\circ \quad (\text{Taschenrechner})$$

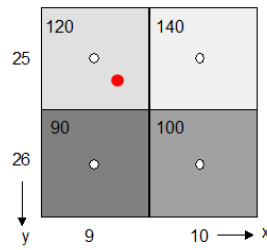
$$+ 180^\circ$$



$$\underline{\underline{\Theta = 161.6^\circ}} \quad r = \frac{\cos \Theta}{A} = \underline{\underline{0.632}}$$

$$\Rightarrow \underline{\underline{0.632 = x \cos 161.6^\circ + y \sin 161.6^\circ}}$$

## Aufgabe 2



$$f_{x_1} = 120 + (9.25 - 9) \cdot (140 - 120) = 125$$

$$f_{x_2} = 90 + (9.25 - 9) \cdot (100 - 90) = 92.5$$

$$\underline{\underline{f_y = 125 + (25.25 - 25) \cdot (92.5 - 125) = \underline{\underline{116.875}}}}$$

mit rad. Basisfunktionen:

$$h_1(x,y) = e^{-\frac{(x-9)^2 + (y-25)^2}{2\sigma^2}}$$

$$h_3(x,y) = e^{-\frac{(x-9)^2 + (y-26)^2}{2\sigma^2}}$$

$$h_2(x,y) = e^{-\frac{(x-10)^2 + (y-25)^2}{2\sigma^2}}$$

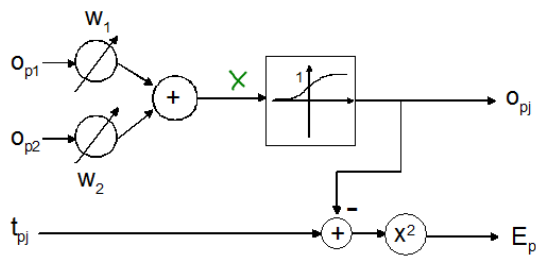
$$h_4(x,y) = e^{-\frac{(x-10)^2 + (y-26)^2}{2\sigma^2}}$$

$$f_{\text{int}}(x,y) = \frac{120 h_1(x,y) + 140 h_2(x,y) + 90 h_3(x,y) + 100 h_4(x,y)}{h_1(x,y) + h_2(x,y) + h_3(x,y) + h_4(x,y)}$$

$$\underline{\underline{f_{\text{int}}(9.25, 25.25) = \frac{120 \cdot 0.8825 + 140 \cdot 0.5353 + 90 \cdot 0.5353 + 100 \cdot 0.3247}{0.8825 + 0.5353 + 0.5353 + 0.3247}}}}$$

$$\underline{\underline{= 114.8}}}$$

### Aufgabe 3



$$\begin{pmatrix} w_1 \\ w_2 \\ \dots \\ w_m \end{pmatrix}_{n+1} = \begin{pmatrix} w_1 \\ w_2 \\ \dots \\ w_m \end{pmatrix}_n + \eta \cdot 2(t_{pj} - o_{pj}) \cdot f'(net_{pj}) \cdot \begin{pmatrix} o_{p1} \\ o_{p2} \\ \dots \\ o_{pm} \end{pmatrix}$$

$$t_{pj} = 1$$

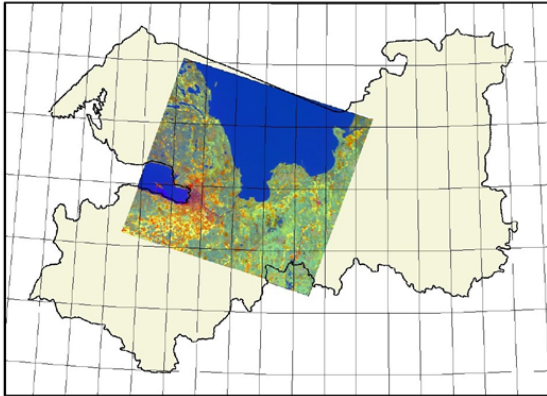
$$X = o_{p1} \cdot w_1 + o_{p2} \cdot w_2 = 0.2 \cdot 0.5 + 0.8 \cdot (-0.2) = \underline{-0.06}$$

$$\underline{o_{pj}} = \underline{f_{log}(X)} = \frac{1}{1 + e^{-(-0.06)}} = \underline{0.485}$$

$$\underline{f'_{log}(X)} = \frac{e^{-X}}{(1 + e^{-X})^2} = \underline{0.2498}$$

$$\begin{aligned} \underline{\underline{\begin{pmatrix} w_1 \\ w_2 \end{pmatrix}_{n+1}}} &= \begin{pmatrix} w_1 \\ w_2 \end{pmatrix}_n + \eta \cdot 2 \cdot (t_{pj} - o_{pj}) \cdot f'_{log}(X) \cdot \begin{pmatrix} o_{p1} \\ o_{p2} \end{pmatrix} \\ &= \begin{pmatrix} 0.5 \\ -0.2 \end{pmatrix} + \frac{1}{2} \cdot 2 \cdot (1 - 0.485) \cdot 0.2498 \cdot \begin{pmatrix} 0.2 \\ 0.8 \end{pmatrix} \\ &= \begin{pmatrix} 0.5 \\ -0.2 \end{pmatrix} + \begin{pmatrix} 0.0257 \\ 0.1029 \end{pmatrix} = \underline{\underline{\begin{pmatrix} 0.526 \\ -0.097 \end{pmatrix}}} \end{aligned}$$

# Aufgabe 4



Zielbild  $1800 \cdot 1200$

Quellbild  $600 \cdot 500$

| Q      | Z         |
|--------|-----------|
| 0, 0   | 600, 200  |
| 500, 0 | 1200, 400 |
| 0, 400 | 400, 600  |

$$X_q = a_1 X_z + a_2 y_z + a_0$$

$$\left. \begin{array}{l} 0 = a_1 \cdot 600 + a_2 \cdot 200 + a_0 \\ 500 = a_1 \cdot 1200 + a_2 \cdot 400 + a_0 \\ 0 = a_1 \cdot 400 + a_2 \cdot 600 + a_0 \end{array} \right\} \begin{pmatrix} 0 \\ 500 \\ 0 \end{pmatrix} = \begin{pmatrix} 600 & 200 & 1 \\ 1200 & 400 & 1 \\ 400 & 600 & 1 \end{pmatrix} \cdot \begin{pmatrix} a_1 \\ a_2 \\ a_0 \end{pmatrix}$$

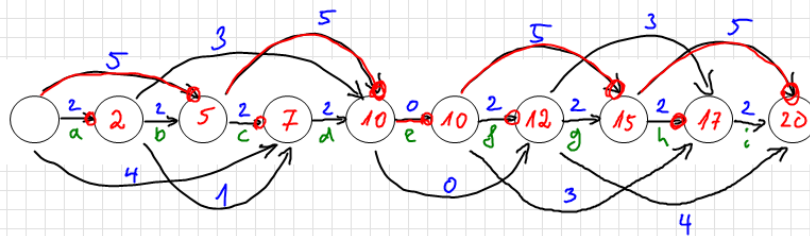
$$D_H = \begin{vmatrix} 600 & 200 & 1 \\ 1200 & 400 & 1 \\ 400 & 600 & 1 \end{vmatrix} = 240000 + 80000 + 720000 - 360000 - 240000 - 160000 = 280000$$

$$D_1 = \begin{vmatrix} 0 & 200 & 1 \\ 500 & 400 & 1 \\ 0 & 600 & 1 \end{vmatrix} = 300000 - 100000 = 200000$$

$$\underline{\underline{a_1 = \frac{D_1}{D_H} = \frac{20}{28} = \frac{5}{7} = 0.714}} \quad a_2, a_0 \text{ analog}$$

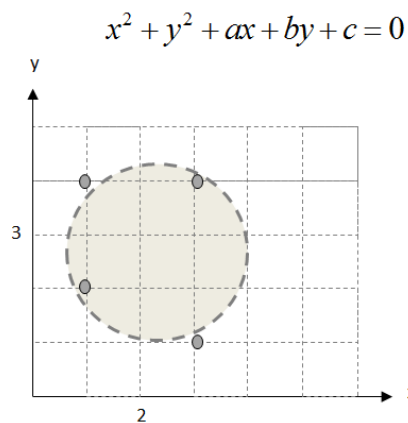
## Aufgabe 5

| Segment/<br>S.-gruppe | a | ab | abc | b | bc | bcd | c | cd | d | e | ef | f | fg | fgh | g | gh | ghi | h | hi | i |
|-----------------------|---|----|-----|---|----|-----|---|----|---|---|----|---|----|-----|---|----|-----|---|----|---|
| Bewer-<br>tung        | 2 | 5  | 4   | 2 | 1  | 3   | 2 | 5  | 2 | 0 | 0  | 2 | 5  | 3   | 2 | 3  | 4   | 2 | 5  | 2 |



Beste Sequenz: ab - cd - e - fg - hi

## Aufgabe 6



Auf der Kreiskontur werden folgende Koordinaten gemessen:

| Punkt | x | y |
|-------|---|---|
| P1    | 1 | 4 |
| P2    | 3 | 1 |
| P3    | 3 | 4 |
| P4    | 1 | 2 |

a)  $ax + by + c = -x^2 - y^2$

$$\begin{pmatrix} 1 & 4 & 1 \\ 3 & 1 & 1 \\ 3 & 4 & 1 \\ 1 & 2 & 1 \end{pmatrix} \cdot \begin{pmatrix} a \\ b \\ c \end{pmatrix} = - \begin{pmatrix} 17 \\ 10 \\ 25 \\ 5 \end{pmatrix} \quad \underline{A} \cdot \vec{f} = \vec{L}$$

b) Ausgleichung mit:  $\underline{A}^T \underline{A} \cdot \vec{f} = \underline{A}^T \cdot \vec{L}$

$$\underline{A}^T \cdot \underline{A} = \begin{pmatrix} 1 & 3 & 3 & 1 \\ 4 & 1 & 4 & 2 \\ 1 & 1 & 1 & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 4 & 1 \\ 3 & 1 & 1 \\ 3 & 4 & 1 \\ 1 & 2 & 1 \end{pmatrix} = \begin{pmatrix} 20 & 21 & 8 \\ 21 & 37 & 11 \\ 8 & 11 & 4 \end{pmatrix}$$

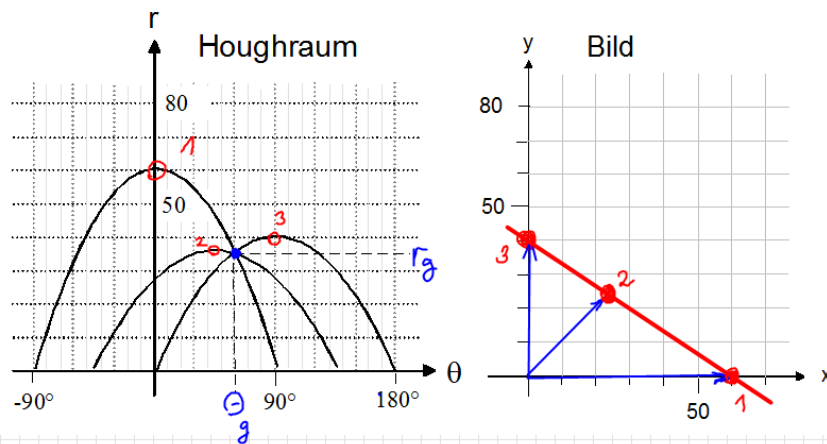
$$\underline{A}^T \cdot \vec{L} = \begin{pmatrix} 1 & 3 & 3 & 1 \\ 4 & 1 & 4 & 2 \\ 1 & 1 & 1 & 1 \end{pmatrix} \cdot \begin{pmatrix} -17 \\ -10 \\ -25 \\ -5 \end{pmatrix} = \begin{pmatrix} -127 \\ -188 \\ -57 \end{pmatrix}$$

$$c) \quad \underline{\underline{x_0 = -\frac{a}{2} = 2.2}}$$

$$\underline{\underline{y_0 = -\frac{b}{2} = 2.7}}$$

$$\underline{\underline{r = \sqrt{x_0^2 + y_0^2 - c} = 1.96}}$$

## Aufgabe 7:



$$\begin{aligned}
 1: & \quad r_1 = 60 \quad \Theta_1 = 0^\circ \\
 2: & \quad r_2 \approx 37 \quad \Theta_2 = 45^\circ \\
 3: & \quad r_3 = 40 \quad \Theta_3 = 90^\circ
 \end{aligned}$$

Gemeinsame Gerade:

$$\Theta_g = 60^\circ, \quad r_g \approx 35$$

$$\underline{\underline{35 = x \cos 60^\circ + y \sin 60^\circ}}$$

$$b) \quad 35 = x \frac{1}{2} + y \cdot 0.866$$

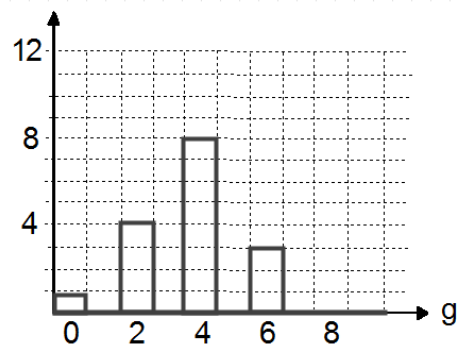
$$y \cdot 0.866 = -0.5x + 35$$

$$\underline{\underline{y = -0.577x + 40.42}}$$



# Aufgabe 8

|              |              |              |              |
|--------------|--------------|--------------|--------------|
| 2            | <del>2</del> | 4            | 4            |
| <del>2</del> | <del>2</del> | <del>4</del> | <del>4</del> |
| 4            | <del>4</del> | 6            | <del>6</del> |
| 4            | <del>4</del> | <del>6</del> | <del>0</del> |



$$254_{10} \hat{=} 11111110_3$$

| In | Out |
|----|-----|
| 0  | 0   |
| 1  | 0   |
| 2  | 2   |
| 3  | 2   |
| 4  | 4   |
| 5  | 4   |
| 6  | 6   |
| 7  | 6   |