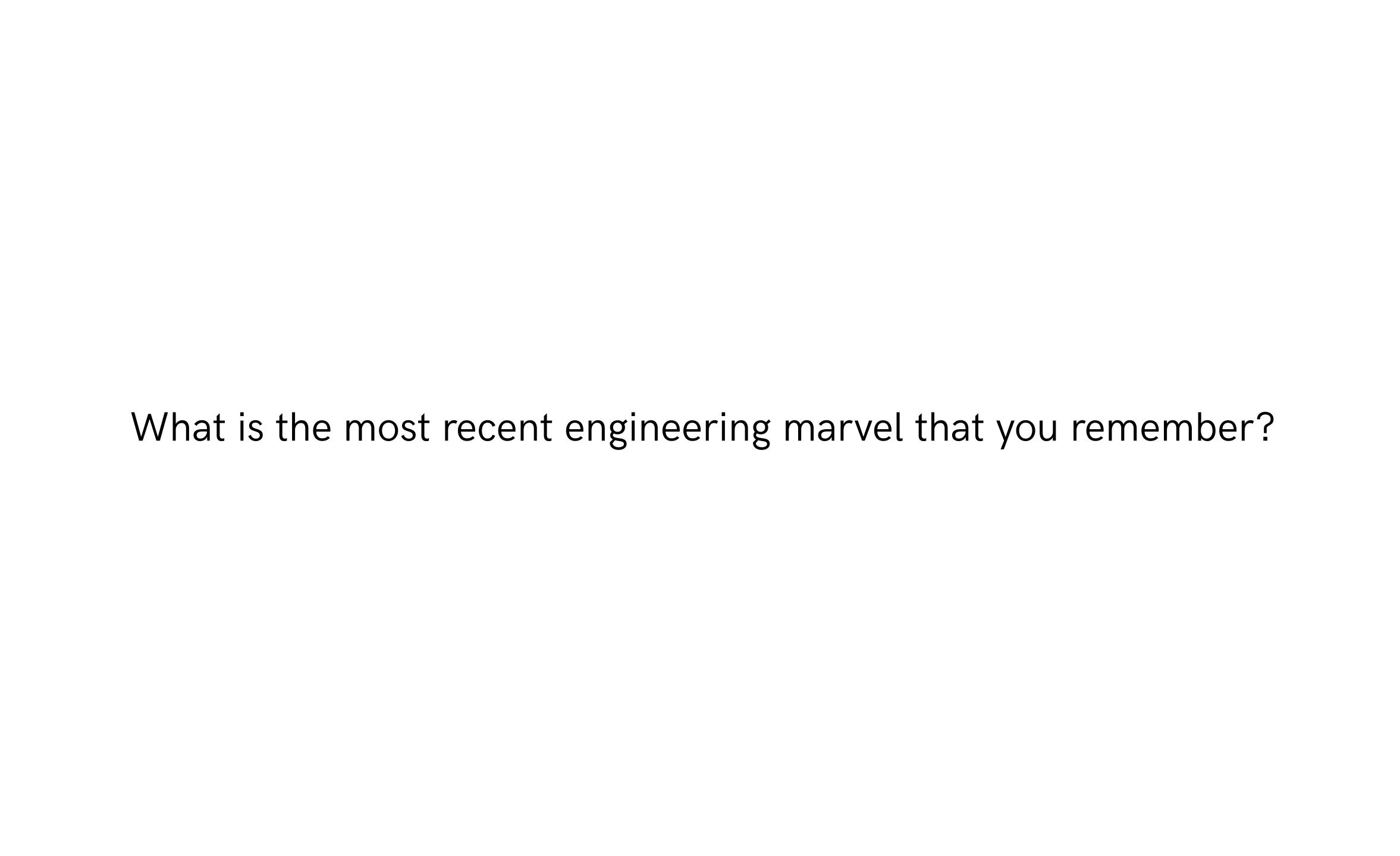
Engineering, Robotics

Introduction, Tasks

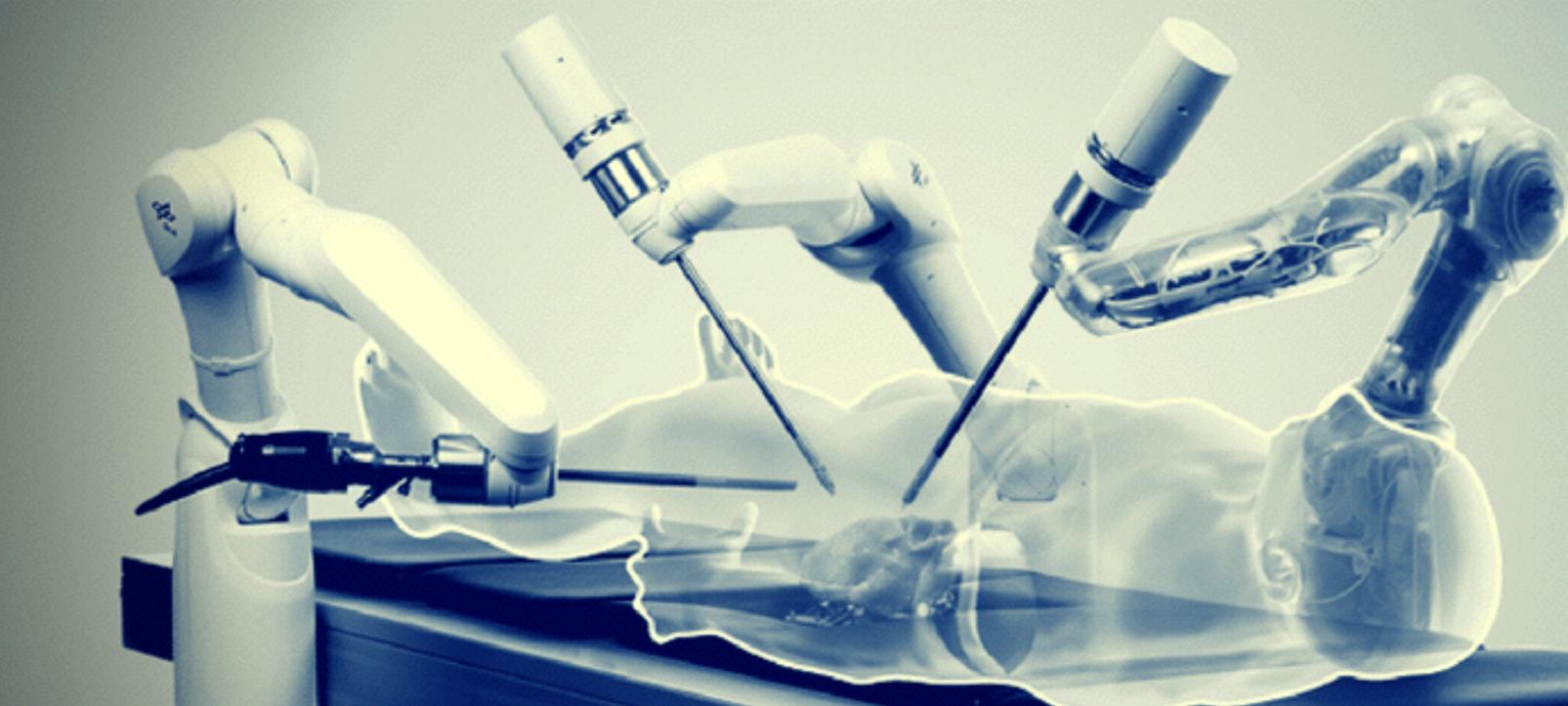


What do engineers do?

Robots and Engineering

- What is a robot?
- How do they 'fit in' engineering problem solving?

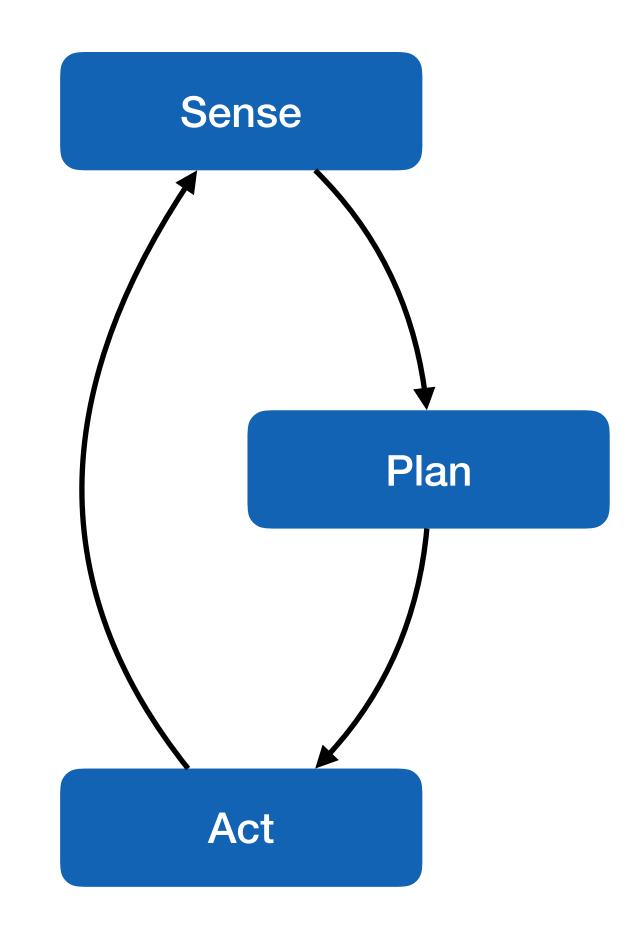






Robotics - Science

- To develop engineering solutions involving robots, a number of core robotics problems need to be solved (approximately)
 - Perception/Sensing Observe and interpret the environment
 - Plan Think and decide about what to do next.
 - Act Perform the chosen action



Robotics - Engineering

- Robotics tasks
 - Manipulation techniques for 'modifying' the environment
 - Navigation techniques for 'moving' around in an environment
- The engineer's view of robotics
 - Automate, automate, automate
 - Examples:
 - Agriculture, transportation, software, manufacturing

MISE Robotics Project

Project 1: Navigational Aid

- Develop:
 - Navigational aid system for the visually impaired, using only cameras, laptop and microphones.
 - Step 1: via Stereo
 - Step 2: via Optical flow
 - In both steps, develop an automatic way 'communicating' occupancy information to the subject.

Tools for MISE Tasks

- Solution design
 - Engineering design process
- Math fundamentals
 - Frames, transformations, linear algebra
- Multi-view geometry in computer vision
- Audio synthesis
- Integration software and hardware, communicating result.

Final Results

- Solution demo
 - Live demo of the navigational aid.
- Report
 - Details of the design
 - Components, methods

Reading/Reference Material

- Math fundamentals
 - https://www.khanacademy.org/math/linear-algebra
- Engineering design
 - https://en.wikipedia.org/wiki/Engineering_design_process
- Computer vision
 - https://en.wikipedia.org/wiki/Visual_perception
 - https://en.wikipedia.org/wiki/Depth_perception
- https://docs.scipy.org/doc/numpy/user/quickstart.html