## Project 2

Least squares regression and nearest neighbor classifiers

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### Least squares regression for missing value prediction

Height and weight data:

$$\mathbf{x} = [x_1, ..., x_n]^T$$
 and  $\mathbf{y} = [y_1, ..., y_n]^T$ 

Fit polynomials:

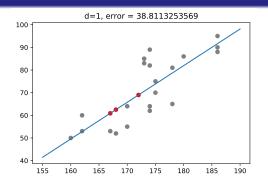
$$y(x) = \sum_{i=0}^{d} w_j x^j$$

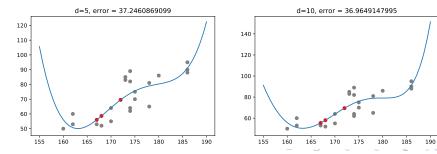
Use least squares method with Vandermonde matrix:

$$\begin{pmatrix} 1 & x_1 & x_1^2 & \cdots & x_1^d \\ 1 & x_2 & x_2^2 & \cdots & x_2^d \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_n & x_n^2 & \cdots & x_n^d \end{pmatrix}$$

Used pseudo-inverse for numerical stability







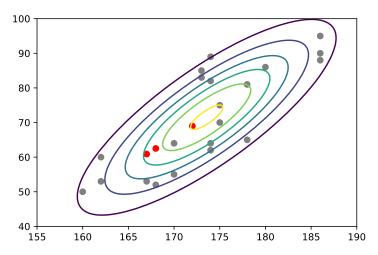
### Conditional expectation for missing value prediction

Fit bi-variate Gaussian and use conditional expectation for missing value prediction:

$$\mathbb{E}[w|h_0] = \int wp(w|h_0)dw$$
$$= \mu_w + \rho \frac{\sigma_w}{\sigma_h}(h_0 - \mu_h)$$

### Numeric Results

The red points have the predicted weight.



### Bayesian regression for missing value prediction

Compare fifth degree polynomial

$$y(x) = \sum_{j=0}^{5} w_j x^j$$

to a Bayesian regression assuming a Gaussian prior

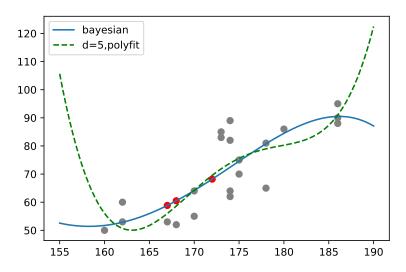
$$p(\mathbf{w}) \sim \mathcal{N}(\mathbf{w}|\mu_0, \sigma_0^2 \mathbf{I})$$

with  $\mu_0 = \mathbf{0}$  and  $\sigma_0^2 = 3$ 

Use:

$$w = (\mathbf{X}^T \mathbf{X} + \frac{\sigma^2}{\sigma_o^2})^{-1} \mathbf{X}^T \mathbf{y}$$

### Results



### Boolean functions and the Boolean Fourier transform

#### Subtask 1.

Rule 110 and 126 are given by

$$y_{110} = (-1, 1, 1, 1, -1, 1, 1 - 1)^T$$
  
 $y_{126} = (-1, 1, 1, 1, 1, 1, 1, 1 - 1)^T$ 

$$w^* = \operatorname{argmin} ||\mathbf{X}w - y||^2$$

yields for  $\hat{y} = \mathbf{X} w^*$ :

$$\hat{y}_{110} = (-0.25, 0.25, 0.25, 0.75, -0.75, -0.25, -0.25, 0.25)^T$$

$$\hat{y}_{126} = (0, 0, 0, 0, 0, 0, 0, 0)^T$$

**Subtask 2**. There are  $2^m$  different basis functions  $\phi_{S_i}: \{-1,1\}^m \to \{-1,1\}, i \in \{1,...,2^m\}$ , and we have  $2^m$  different input vectors  $x_1,x_2,...,x_{2^m} \in \{-1,1\}^m$ . Thus:

$$\begin{pmatrix} f(x_1) \\ \vdots \\ f(x_{2^m}) \end{pmatrix} = \begin{pmatrix} \phi_{S_1}(x_1) \dots \phi_{S_{2^m}}(x_1) \\ \vdots & \ddots & \vdots \\ \phi_{S_1}(x_{2^m}) \dots \phi_{S_{2^m}}(x_{2^m}) \end{pmatrix} \cdot \begin{pmatrix} w_{S_1} \\ \vdots \\ w_{S_{2^m}} \end{pmatrix}$$
$$= \begin{pmatrix} \phi(x_1)^T \\ \vdots \\ \phi(x_{2^m})^T \end{pmatrix} \cdot \begin{pmatrix} w_{S_1} \\ \vdots \\ w_{S_{2^m}} \end{pmatrix} = \mathbf{\Phi} w$$

### Subtask 3. Minimizing

$$w^* = \operatorname{argmin} ||\mathbf{\Phi} w - y||^2$$

yields for  $\Phi w^*$ :

$$\hat{y}_{110} = (-1, 1, 1, 1, -1, 1, 1 - 1)^{T}$$

$$\hat{y}_{126} = (-1, 1, 1, 1, 1, 1, 1, 1 - 1)^{T}$$

The reconstructed rules match the original ones.

# (Naive) k nearest neighbor

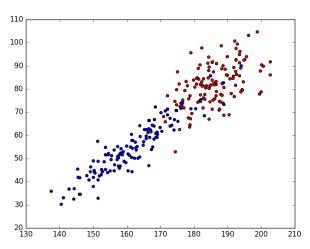
Use the train data set as a prediction for the test data set

Compute the k nearest neighbors for each data point in the data set

And use the majorant of those k labels as a prediction

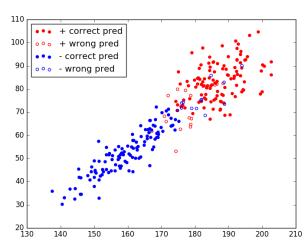
Experiment on data2.dat with  $k \in \{1,3,5\}$ 

#### Correct labels of test data:

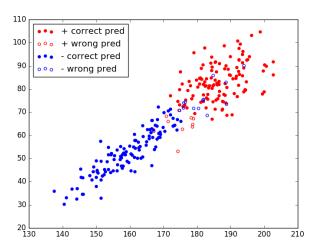




#### Prediction of 1NN:

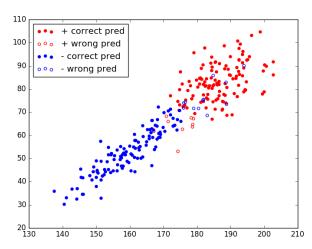


#### Prediction of 3NN:





#### Prediction of 5NN:





## Accuracy and running time

Accuracies of kNN predictions:

- 0.77 for k = 1
- 0.82 for k = 3
- 0.83 for k = 5

Running times of our distance calculation vs sklearn.metrics.pairwise:

k	our implementation	sklearn
1	0.02s	0.003s
3	0.02s	0.003s
5	0.02s	0.003s

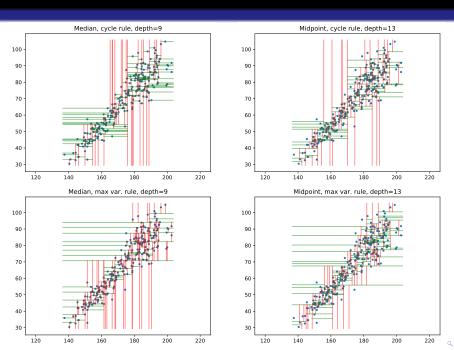
### **KDTrees**

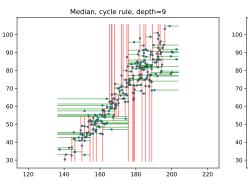
Plot four different KDTrees for combinations of axis-cycling rules:

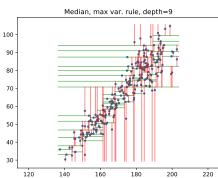
- cycle through axes
- select axis with highest variance

and the split point rules w.r.t. the splitting axis:

- select the median point
- select the midpoint







## Timings for 1-NN per combination

	Median	Midpoint
Cycle	0.01425s	0.00994s
Max. Var	0.01360s	0.01053s

Table: Mean running time in seconds, 100 runs

Thank you for your attention!