

ACTIVATION FUNCTIONS

why not just use identity?

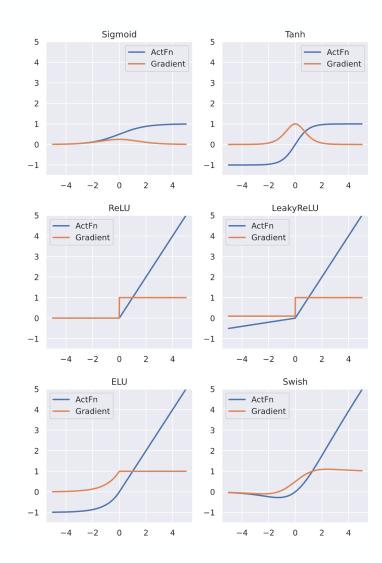
need a non-linear function

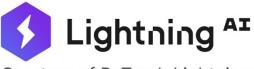
sigmoid might cause vanishing gradients

it's nice if the gradient is easy to calculate

sometimes we want some weights to $\rightarrow 0$

last three ones keep some negative values





Creators of PyTorch Lightning

https://lightning.ai/docs/pytorch/stable/notebooks/course UvA-DL/02-activation-functions.html

FEEDFORWARD NEURAL NETWORK

A feedforward neural network implements the perceptron algorithm this was intended to be a machine with 400 photocells!

stack layers of neurons, connect them all with activation functions → feedforward neural net

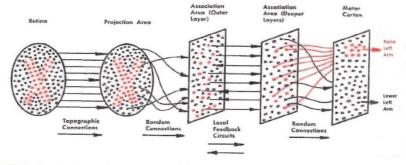


FIG. 1 — Organization of a biological brain. (Red areas indicate active cells, responding to the letter X.)

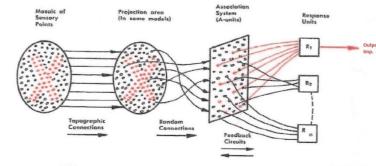
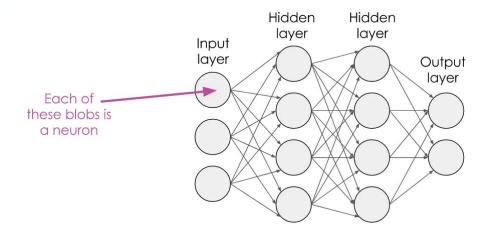


FIG. 2 - Organization of a perceptron.



https://medium.com/@RosieCampbellhttps://en.wikipedia.org/wiki/Perceptron#History

FEEDFORWARD NEURAL NETWORK

These all mean the same:

- fully connected layer
- (keras) dense layer
- (pytorch) inear layer

also:

FFN = Multi-Layer Perceptron



scikit-learn has probably the most accessible MLP model



Linear

Applies an affine linear transformation to the incoming data: $y = xA^T + b$.

This module supports TensorFloat32.

On certain ROCm devices, when using float16 inputs this module will use different precision for backward.

Parameters:

- in_features (int) size of each input sample
- out_features (int) size of each output sample

the layer will not learn an



Class $\underline{\text{MLPClassifier}}$ implements a multi-layer perceptron (MLP) algorithm that trains using $\underline{\text{Backpropagation}}$.

MLP trains on two arrays: array X of size (n_samples, n_features), which holds the training samples represented as floating point feature vectors; and array y of size (n_samples,), which holds the target values (class labels) for the training samples:

ns any number of $\mbox{nd $H_{\rm in}=$in_features.}$ but the last dimension are and $H_{\rm out}=\mbox{out_features.}$

```
► Keras 3 API documentation / Layers API / Core layers / Dense layer
Dense layer
Dense class
                                                            [source]
  keras.layers.Dense(
      units,
      activation=None,
      use_bias=True,
      kernel_initializer="glorot_uniform",
      bias_initializer="zeros",
      kernel_regularizer=None,
      bias_regularizer=None,
      activity_regularizer=None,
      kernel_constraint=None,
      bias_constraint=None,
      lora_rank=None,
```

Just your regular densely-connected NN layer.

lora_alpha=None,

**kwargs

 \equiv

https://scikitlearn.org/stable/modules/neural_net works supervised.html

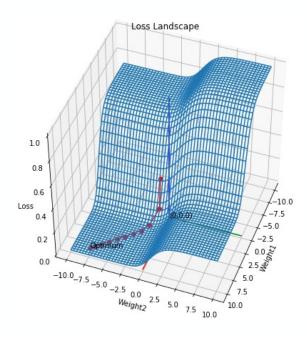
Q

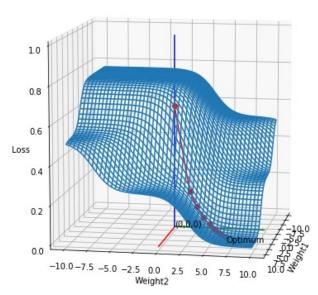
GRADIENT DESCENT

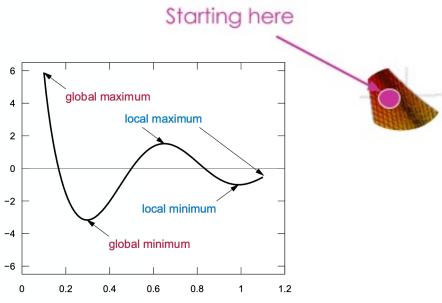
we formulate learning as minimizing an error function, usually called the loss.

Because the error functions of artificial neural networks are nonconvex, we will almost certainly only find a local minimum.

The loss value is a number, the "height" above ground in a multidim loss landscape.







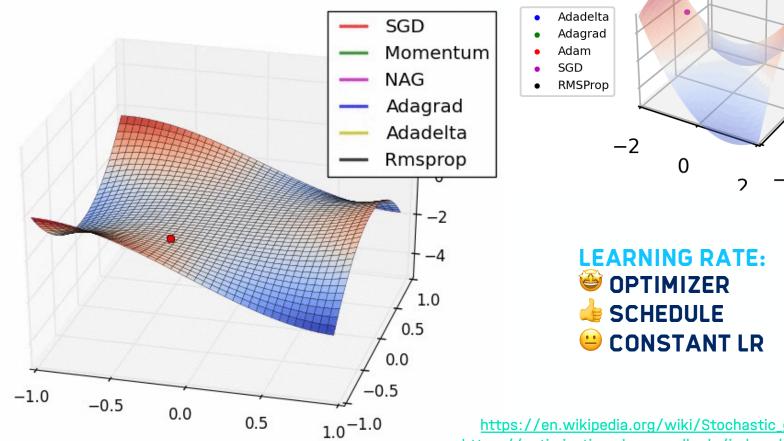
https://ai.stackexchange.com/users/2844/dan-d https://medium.com/@RosieCampbell https://en.wikipedia.org/wiki/Backpropagation

OPTIMIZERS

At the core, all common optimizers use variations of gradient descent.

Actually *stochastic* gradient descent: ∇ is calculated in many little batches instead of for the entire data set.

They all aim to speed up learning along stable directions by gathering momentum, while slowing oscillations.



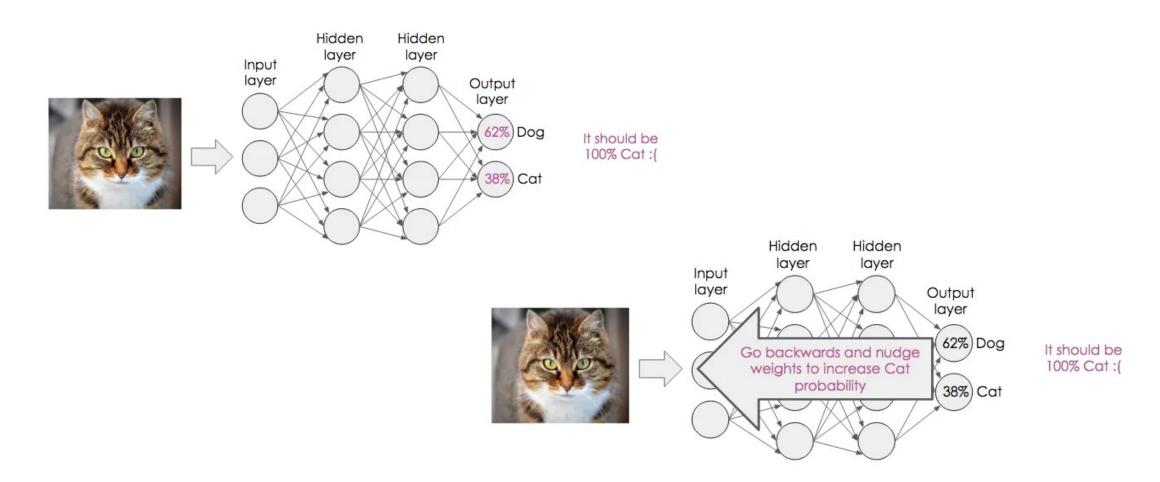
https://en.wikipedia.org/wiki/Stochastic_gradient_descent https://optimization.cbe.cornell.edu/index.php?title=RMSProp

2.5

0.0

-2.5

BACKPROPAGATION



https://medium.com/@RosieCampbell

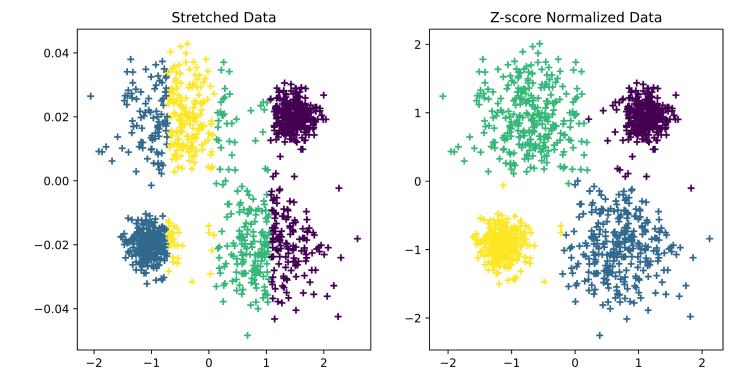


FEATURE SCALING

Feedforward neural networks can be susceptible to features "living" on different numerical scales → use feature scaling

min-max scaling, median scaling or z-scaling are common

the y-axes are different!



https://en.wikipedia.org/wiki/Feature_scaling

