



# THE UNIVERSITY OF BRITISH COLUMBIA

Martin Alejo #7529665

October 7<sup>th</sup>, 2022

Mini Project 1

University of British Columbia

Electrical and Computer Engineering

ELEC 301

Instructor: Nicholas Jaeger

A handwritten signature in black ink, appearing to read 'Martin', is positioned below the instructor's name.

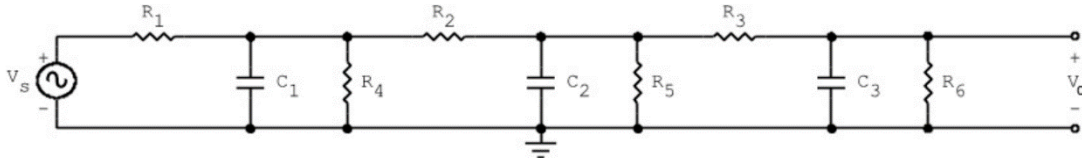
## Contents

<b>Part 1</b> .....	<b>3</b>
<b>Part A:</b> .....	<b>3</b>
<b>Calculation of Capacitances</b> .....	<b>3</b>
<b>Part B</b> .....	<b>5</b>
<b>Finding the Bode plots of Transfer function</b> .....	<b>5</b>
<b>Part II</b> .....	<b>6</b>
<b>Part A</b> .....	<b>6</b>
<b>Approximation of Pole values</b> .....	<b>6</b>
<b>Approximation of <math>\omega_{3dB}</math></b> .....	<b>8</b>
<b>Part B</b> .....	<b>8</b>
<b>Calculation for <math>\omega_{LF1}</math>, <math>\omega_{LF2}</math></b> .....	<b>8</b>
<b>Calculations for <math>C_3 = 1\mu F, 2\mu F, 5\mu F, 10\mu F</math>:</b> .....	<b>9</b>
<b>Part 3</b> .....	<b>10</b>
<b>Part A</b> .....	<b>10</b>
<b>Miller's Theorem Analysis:</b> .....	<b>10</b>
<b>Mid-band Gain Calculation:</b> .....	<b>11</b>
<b>Part B</b> .....	<b>12</b>
<b>Approximation of Lower 3dB Frequency:</b> .....	<b>13</b>
<b>Pole Frequency Approximation:</b> .....	<b>14</b>
<b>Calculating Percent Error:</b> .....	<b>15</b>
<b>References</b> .....	<b>16</b>

## Part 1

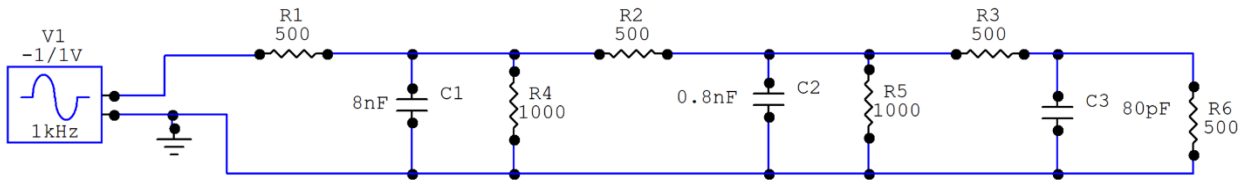
Our circuit and related transfer function in question is shown below:

$$T(s) = \frac{V_o(s)}{V_s(s)} = 0.125 \times \frac{5 \times 10^5 / \text{sec}}{s + 5 \times 10^5 / \text{sec}} \times \frac{5 \times 10^6 / \text{sec}}{s + 5 \times 10^6 / \text{sec}} \times \frac{5 \times 10^7 / \text{sec}}{s + 5 \times 10^7 / \text{sec}}$$



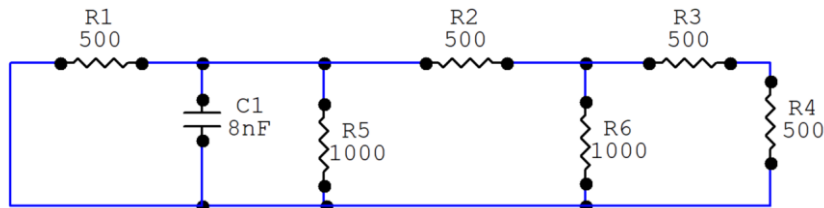
## Part A:

Using four  $500\Omega$  and two  $1000\Omega$  resistors, a low pass circuit shown below was designed from the transfer function above.



In this circuit, we know that  $C_1 > C_2 > C_3$ , and  $\omega_{h1} = 5 \times 10^5 / \text{sec}$ ,  $\omega_{h2} = 5 \times 10^6 / \text{sec}$ ,  $\omega_{h3} = 5 \times 10^7 / \text{sec}$  from the transfer function shown above. From the mid-band gain, we know the values of each of the resistors, by inspection. From those values, we can calculate the values of the capacitors above from setting up Short Circuit and Open Circuit time constant equations.

For Capacitor  $C_1$ , we can create the circuit to solve for the value by opening the other capacitors. As shown below:



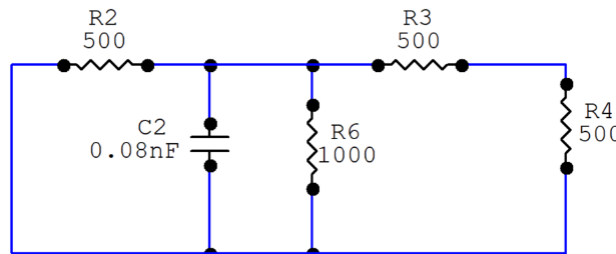
## Calculation of Capacitances

$$(((R_3 + R_6) \parallel R_5) + R_2) \parallel R_4 \parallel R_1 = 250\Omega$$

From this, we can calculate  $C_1$ :

$$\frac{1}{RC} = \omega \text{ to } \frac{1}{\omega R} = C = 8nF$$

The calculation for  $C_2$  is a similar calculation, however we short  $C_1$  and open  $C_3$ , and the equivalent circuit is shown as:

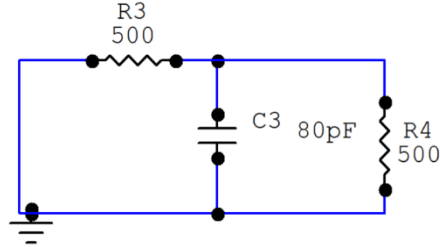


The calculation for the resistance seen by  $C_1$ :

$$R_2 || ((R_3 + R_4) || R_6) = 250\Omega$$

From the same calculation for  $C_1$ , we would evaluate  $C_2=0.08\text{nF}$ .

For  $C_3$ , we would calculate the resistance seen by shorting  $C_1$  and  $C_2$ . Similarly, the circuit would be:



The equivalent resistance seen by  $C_3$  would be  $R_3 || R_4 = 250\Omega$ . The capacitance calculation follows the previous calculations and evaluates to  $C_3=80\text{pF}$ .

The Bode Magnitude plot and Phase plot of the above circuit is shown below:

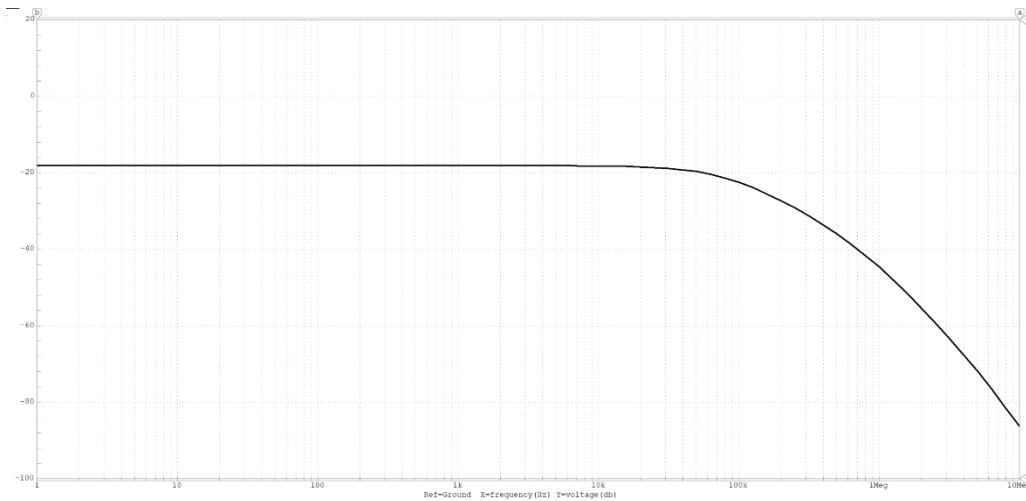


Figure 1.1 (Magnitude Plot)

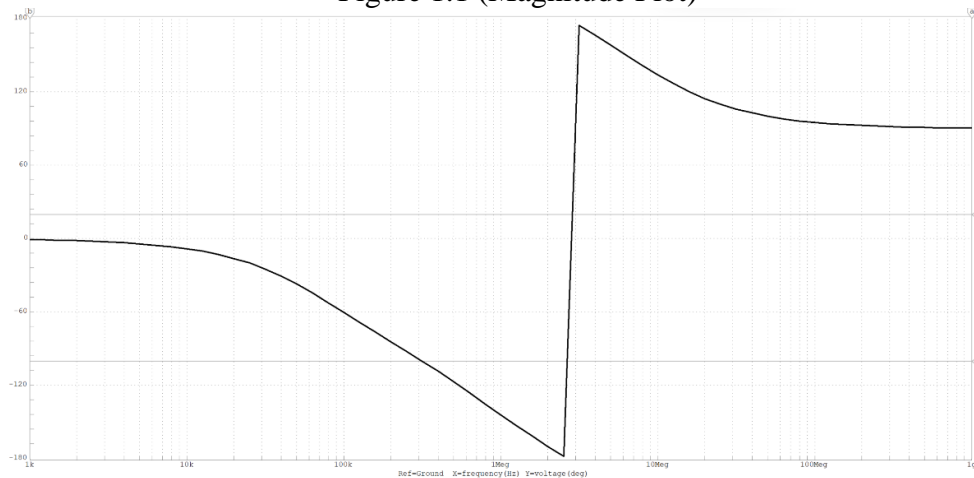
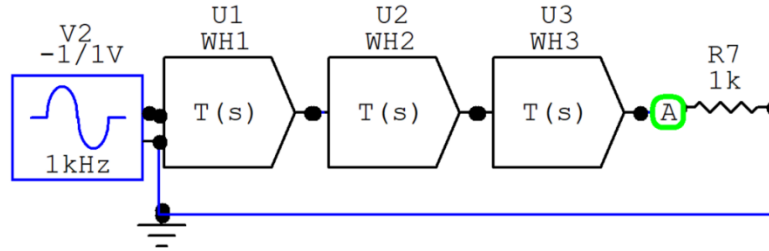


Figure 1.2 (Phase Plot)

## Part B

### Finding the Bode plots of Transfer function



The bode plot was found from the test point A, as marked in the circuit. Each of the transfer blocks was each of the high frequency pole transfer function cascading onto each other to form the general transfer function for the circuit. The mid-band gain was added to the first transfer block. The plots are as shown below:

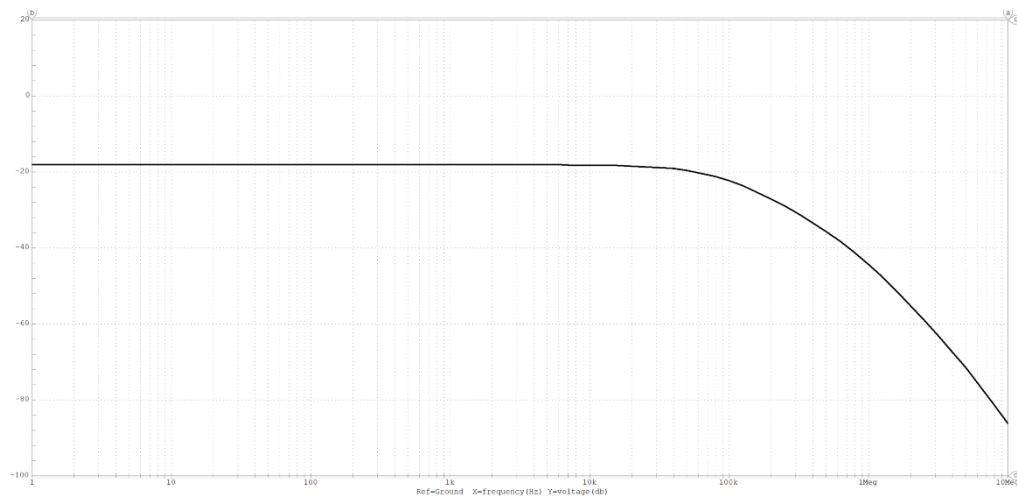


Figure 1.3 (Magnitude Plot)

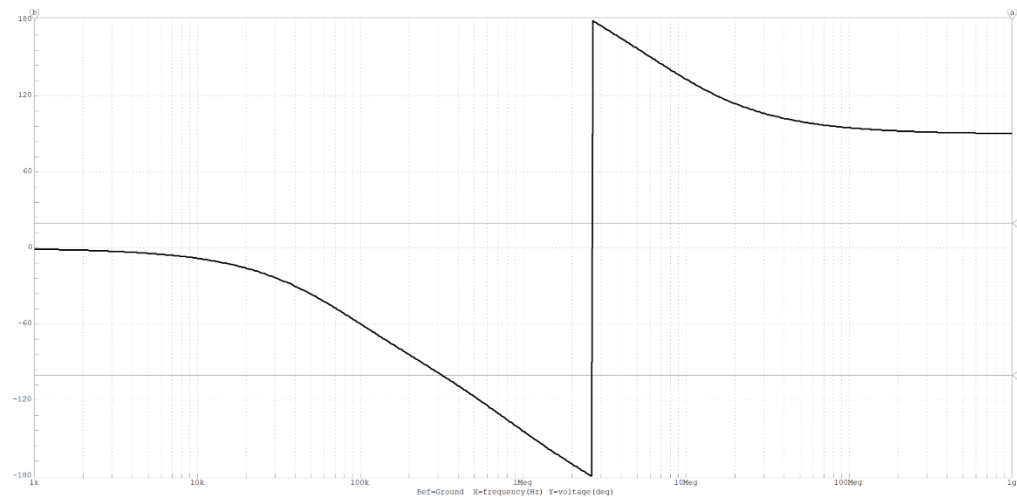


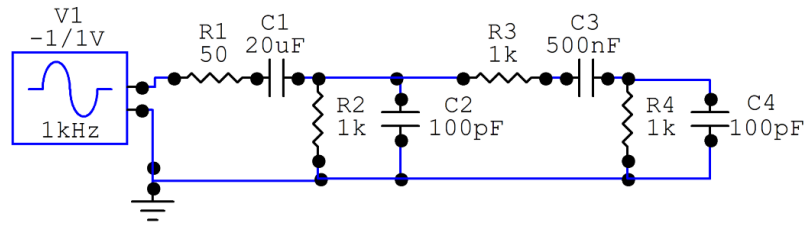
Figure 1.4 (Phase Plot)

From inspecting the ideal plot and the simulated plot, we can state that both are very similar to each other and are almost the same.

## Part II

### Part A

The circuit shown below was created with values given, and simulated by CircuitMaker:



### Approximation of Pole values

To find the approximations for the pole values, we sketch on the graph and estimate where they are located. We do this by estimating where the slope changes.

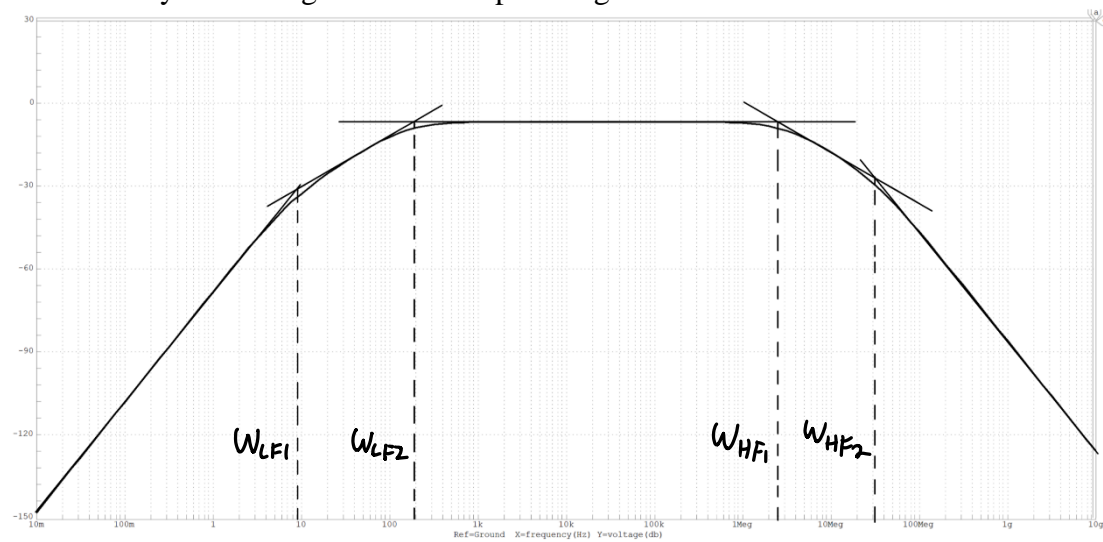


Figure 2.1 (Magnitude Plot)

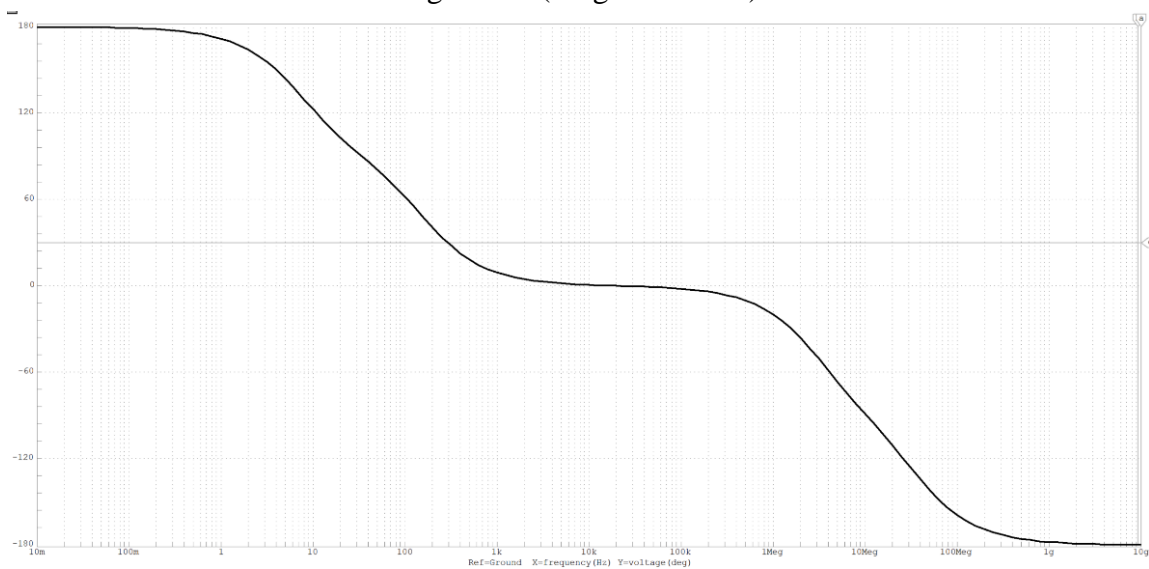


Figure 2.2 (Phase Plot)

The values are found with CircuitMaker cursor tools to find the approximate values of each pole frequency. An example of which is shown below:

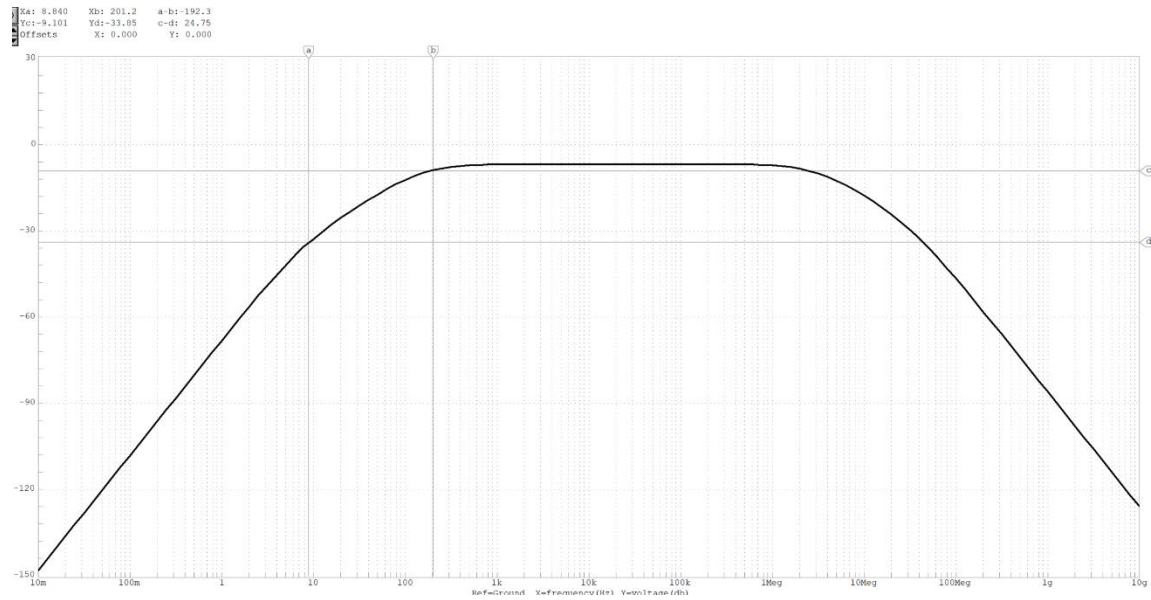


Figure 2.3 ( $\omega$  Approximations)

According to the approximation,  $\omega_{LF1} = 8.840 \cdot 2\pi$  rad/s, and  $\omega_{LF2} = 201.2 \cdot 2\pi$  rad/s. Where the cursor 'a' and 'b' were  $\omega_{LF1}$  and  $\omega_{LF2}$  respectively. The approximations for  $\omega_{HF1}$  and  $\omega_{HF2}$  is shown below:

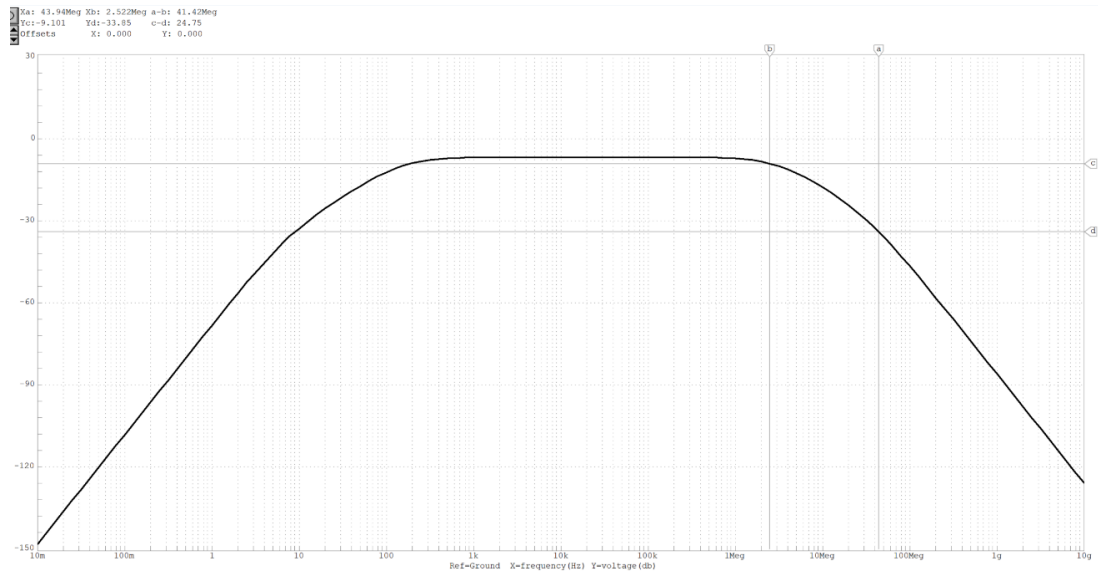


Figure 2.4 ( $\omega$  Approximations)

As shown, the values approximate to  $\omega_{HF1} = 2.522 \cdot (2\pi) \cdot 10^6$  rad/s, and  $\omega_{HF2} = 43.94 \cdot (2\pi) \cdot 10^6$  rad/s. Where the cursor 'b' and 'a' were  $\omega_{HF1}$  and  $\omega_{HF2}$  respectively.

### Approximation of $\omega_{3dB}$

To find the values of  $\omega_{L3dB}$ , we find the value of the frequency at a point where it is 3 decibels lower than the mid-band gain. The graphical approximation is shown below:

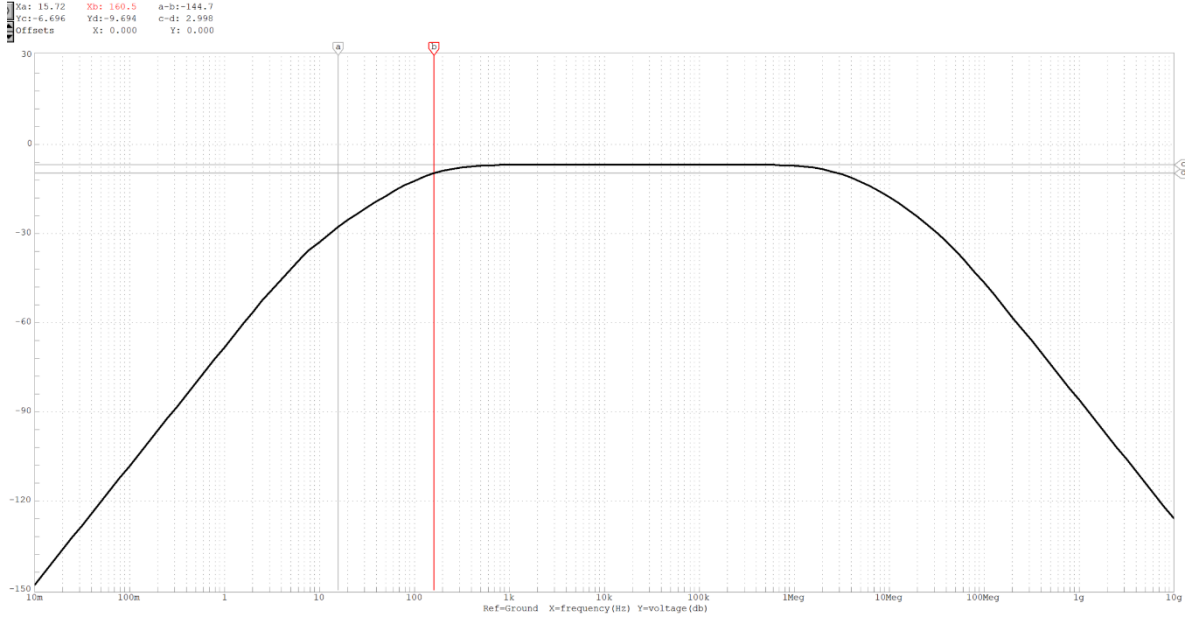


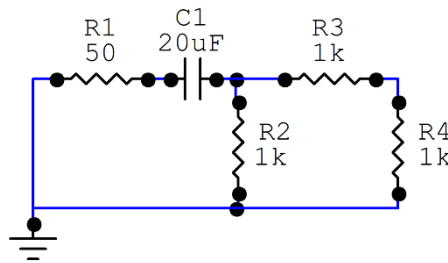
Figure 2.6

From the cursors, we can find that the value of  $\omega_{L3dB}$  is  $160.5 \cdot 2\pi$  rad/s.

### Part B

#### Calculation for $\omega_{LF1}$ , $\omega_{LF2}$

These calculations are for  $C_1 = 500\text{nF}$ . To find the values of  $\omega_{LF1}$ ,  $\omega_{LF2}$ , analytically, we can set up SCT and OCT equations. To find  $\omega_{HF1}$ , we find the resistance seen by  $C_1$ , and from knowing that  $\frac{1}{RC} = \omega$ , we can find the value. The calculation for the first low frequency pole would follow similarly to the calculations in the previous part. The circuit needed for such calculation can be seen below:



The resistance seen by  $C_1$  evaluates to  $(R_3 + R_4 || R_2) + R_1 = 716.67\Omega$ , and  $\omega_{LF1} = 69.77 \text{ rad/s}$

The second low frequency pole would follow the same calculation, and eventually evaluates to

$$\omega_{LF2} = 976.74 \text{ rad/s}$$

After finding the low frequency poles, we can find the calculated  $\omega_{L3dB}$  using this formula:

$$\sum_{i=1}^N \frac{1}{R_i C_{is}} = \omega_{LF1} + \omega_{LF2} = 1046.51 \text{ rad/s.}$$



To find the percentage error we use:

$$\%error = \left| \frac{\omega_{L3dB(calculated)} - \omega_{L3dB(measured)}}{\omega_{L3dB(measured)}} \right| * 100$$

Which evaluates to:

$$\left| \frac{1046.512 - 1008.451}{1008.451} \right| * 100 = 3.77\%$$

### Calculations for $C_3 = 1\mu F, 2\mu F, 5\mu F, 10\mu F$

Here are the Magnitude plots of all the different capacitance values (Plots from left to right are  $10\mu F, 5\mu F, 2\mu F, 1\mu F$ ):

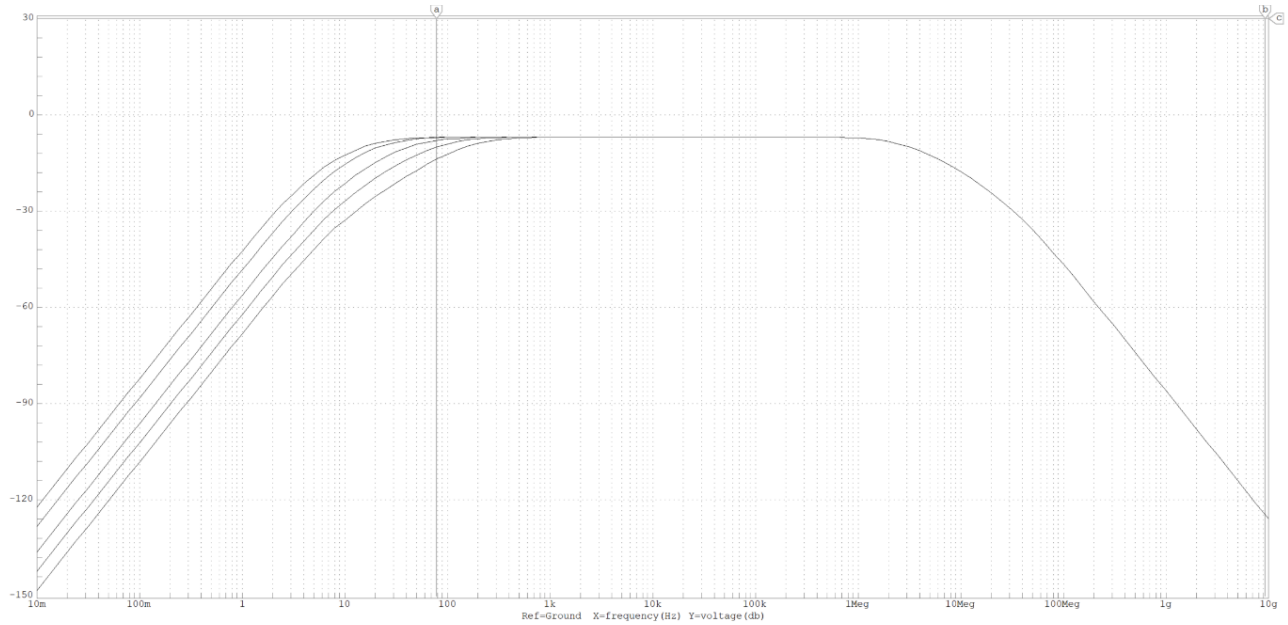


Figure 2.7 (Magnitude Plot)

The calculations for each  $\omega_{L3dB}$  follows the same calculation as shown previously. The values are evaluated as follows:

	$\omega_{L3dB(calculated)} \left[ \frac{rad}{s} \right]$	$\omega_{L3dB(measured)} \left[ \frac{rad}{s} \right]$	% Error
1uF	558.139	522.196	6.883
2uF	313.953	276.083	13.717
5uF	167.442	140.115	19.503
10uF	118.605	98.772	20.079

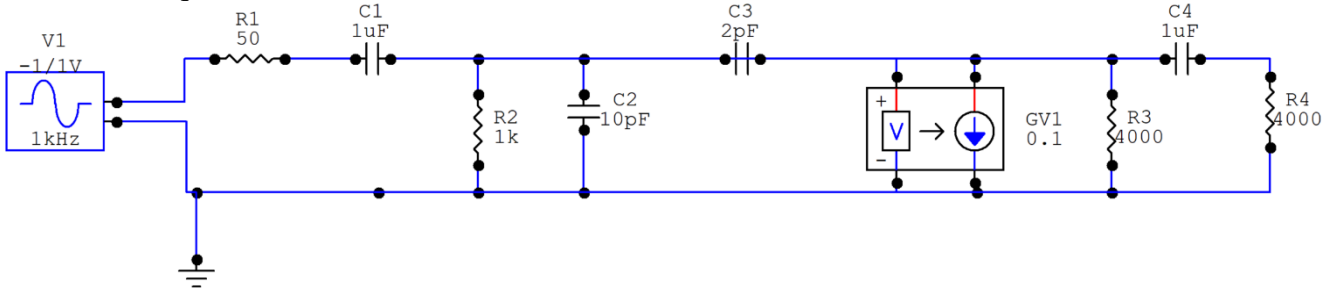
Figure 2.8 (Table of Measured and Calculated Frequencies with percent error)

As the capacitances increase, we can find a correlating increase in error. This is because as we increase the capacitances, they would affect the  $\omega_{3dB}$  values. This is because when we increase the value of the capacitance, it would change the impedance of that capacitor. Doing this will affect where the capacitor filters the signal.

## Part 3

### Part A

Our circuit in question is shown below:

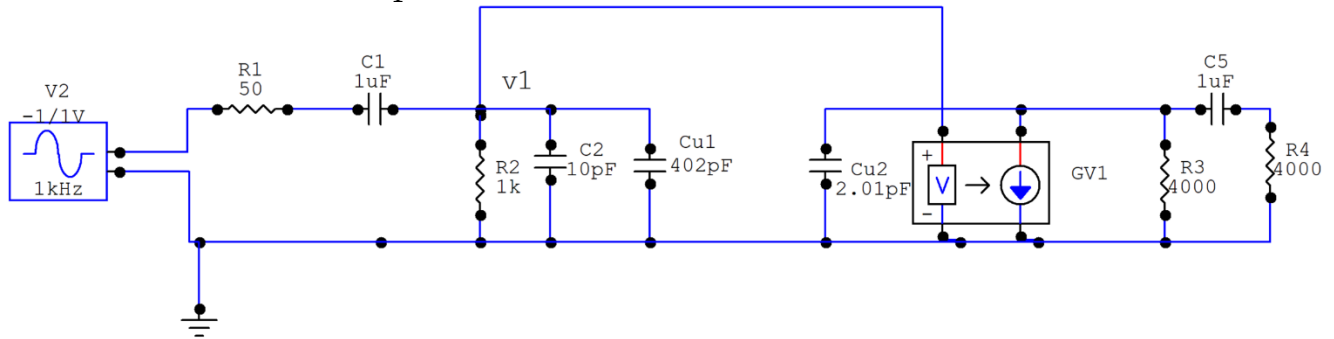


### Miller's Theorem Analysis:

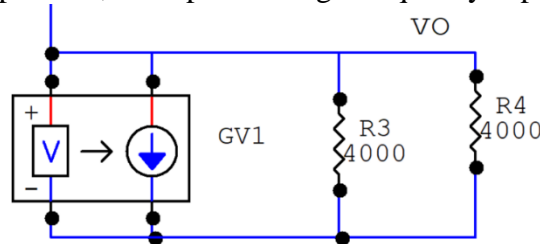
In the case of this analysis, we perform miller's theorem on capacitor  $c_3$

To perform Miller's theorem, we first find the miller gain  $k$ , and the equivalent miller capacitances with these formulas and the following circuit:

$$k = \frac{v_o}{v_1} \quad c_{\mu 1} = c(1 - k) \quad c_{\mu 2} = c(1 - \frac{1}{k})$$



To find  $k$  we first find the expression for  $v_o$  in terms of  $v_1$ . To do this, we look only at the output stage and short our low frequency capacitors, and open our high frequency capacitors:



With this circuit, we first find the current across  $R_4$  ( $I_o$ ). We can do this using a current divider:

$$I_o = -Gv_1 \frac{R_3}{R_4 + R_3}$$

Then, we can find the voltage across the resistor using:

$$R_4(I_o) = (-0.1)(v_1)\left(\frac{4000}{4000+4000}\right) = -200v_1$$

Therefore:

$$k = \frac{200v_1}{v_1} = -200$$

With this information, we can find  $c_{\mu1}$  and  $c_{\mu2}$  with the formulas stated previously. They evaluate to:

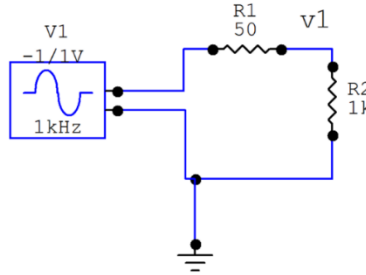
$$c_{\mu1} = c_3(1 - k) = 402pF \quad c_{\mu2} = c_3(1 - \frac{1}{k}) = 2.01pF$$

### Mid-band Gain Calculation:

With all our components found, we can now calculate our mid-band gain. We can use this equation for the mid-band gain:

$$A_m = \frac{v_1 v_o}{v_s v_1}$$

We need to find an equation for  $v_1$  in to find our mid-band gain. However, to find it, we also need use SCT and OCT equations. In this case, we open the capacitors in parallel and short the capacitors in series:



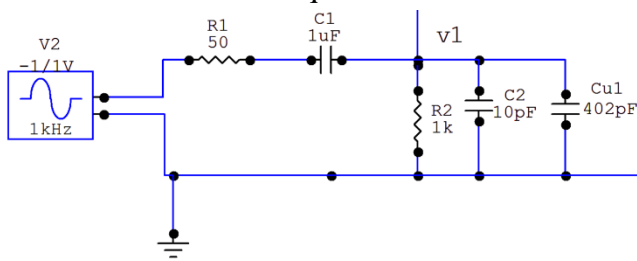
We can use a voltage divider to get the equation for  $v_1$  in terms of  $v_s$ :

$$v_1 = v_s \left( \frac{R_2}{R_2 + R_1} \right)$$

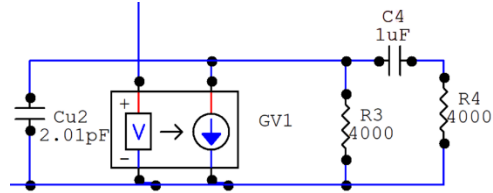
Therefore, mid-band gain is:

$$A_m = \frac{v_1 v_o}{v_s v_1} = \frac{v_s \left( \frac{R_2}{R_2 + R_1} \right) - 200v_1}{v_s v_1} = -190.476$$

To calculate the poles, we can use similar calculations as shown in the previous parts to find them (SC time constant and OC time constant equations). We split the input output stage as follows, and from there we use the equations:



Input Stage



Output Stage

Using the SC time constant and OC time constant calculations, similar to Part 1, the equations are:

$$\omega_{lf1} = \frac{1}{c_1(R_1 + R_2)} \quad \omega_{lf2} = \frac{1}{c_4(R_4 + R_3)} \quad \omega_{hf1} = \frac{1}{(c_2 + c_{\mu1})(R_1 || R_2)} \quad \omega_{hf2} = \frac{1}{c_{\mu2}(R_3 || R_4)}$$

Evaluates to:

	$\omega_{lf1}$	$\omega_{lf2}$	$\omega_{hf1}$	$\omega_{hf2}$
$\omega$ [rad/s]	952.381	125	$50.971 \cdot 10^6$	$248.756 \cdot 10^6$

Figure 3.1 (Table of calculated Frequencies)

With these values, the transfer function of this circuit results to:

$$T(s) = (-190.476) \frac{s}{s + 952.381} * \frac{s}{s + 125} * \frac{50.971 * 10^6}{s + 50.971 * 10^6} * \frac{248.756 * 10^6}{s + 248.756 * 10^6}$$

## Part B

Below are the magnitude and phase plots for the simulated circuit:

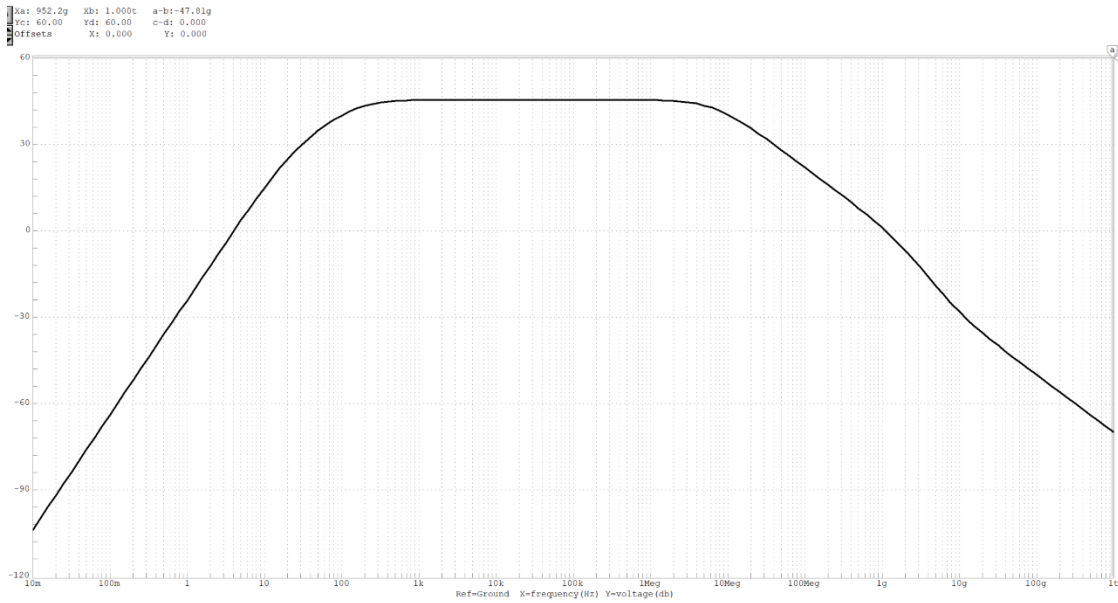


Figure 3.2 (Magnitude Plot)

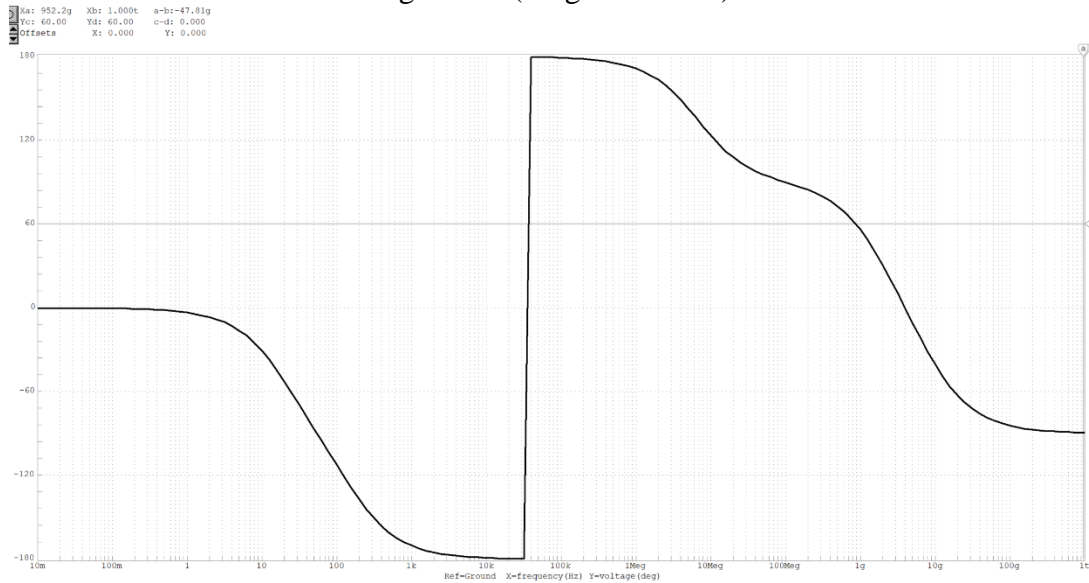


Figure 3.3 (Phase Plot)

### Approximation of Lower 3dB Frequency:

To approximate the lower 3dB frequency  $\omega_{L3dB}$ , we follow the same process as previously shown, where we measure a point in the plot where it is 3 decibels lower than the mid-band gain:

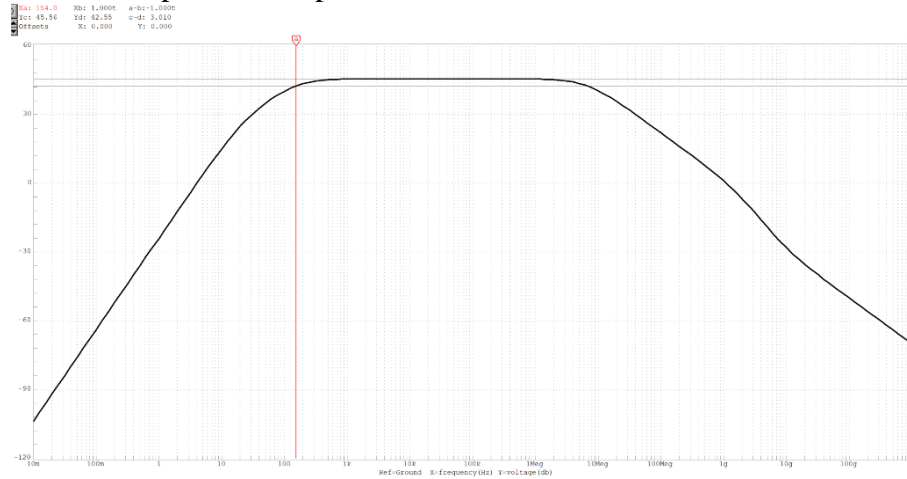


Figure 3.4( $\omega_{L3dB}$  Approximation)

Above, the cursor was used to approximate the point in the graph, leading to  $\omega_{L3dB} = 154 * 2\pi$  rad/s.

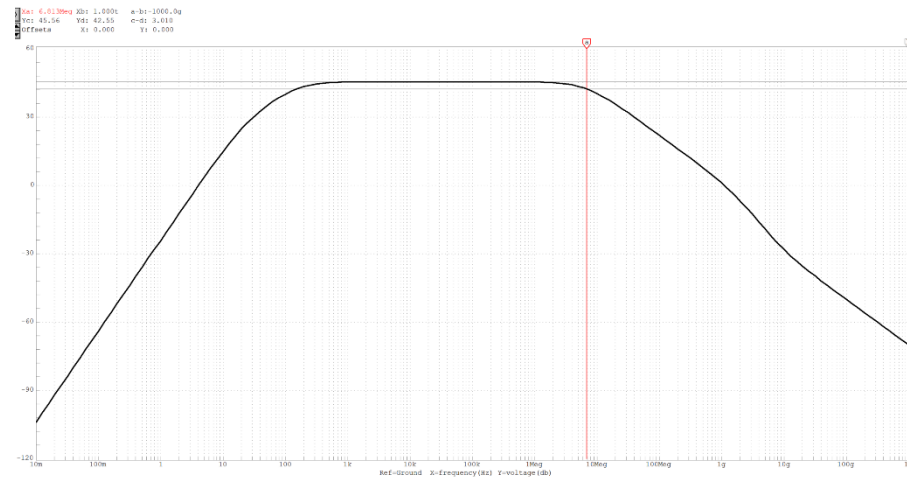


Figure 3.5 ( $\omega_{H3dB}$  Approximation)

Similarly, for the plot shown above, we can approximate  $\omega_{H3dB} = 6.813 * 10^6 * 2\pi$  rad/s.

### Pole Frequency Approximation:

To estimate the poles and zeros on the plot, we can sketch slopes on the plot, and finding where the slopes change can estimate approximately where the poles and zeros are, as shown below:

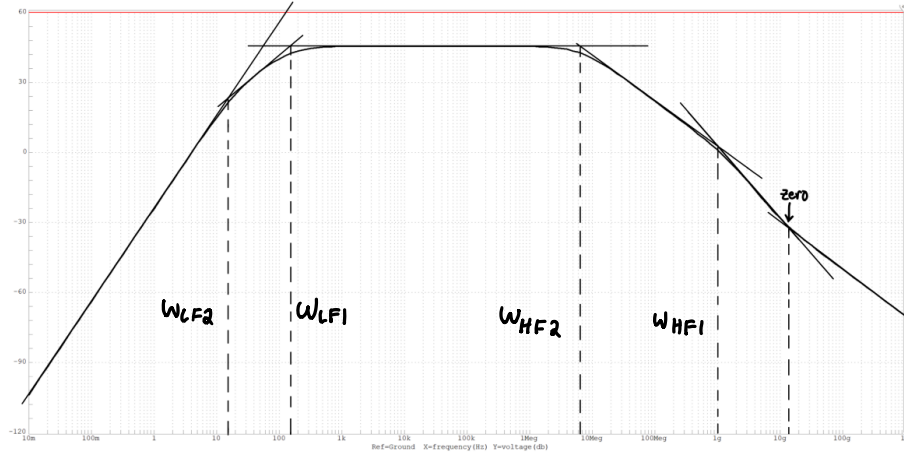


Figure 3.6 (Pole Frequency Estimation)

The approximated poles and zeros are as follows:

	$\omega_{lf1}$	$\omega_{lf2}$	$\omega_{hf1}$	$\omega_{hf2}$	zero
$\omega[\frac{rad}{s}]$	1000.028	100.28	$40.351 \times 10^6$	$6.87 \times 10^9$	$50.35 \times 10^9$

Figure 3.7 (Table of Frequencies)

Comparing each of the poles with the calculated values, we find that the estimated low frequency poles are quite close to the calculation, as the difference between each of the estimated and calculated poles are within about 100 rad/s of each other. As with the estimated and calculated high frequency poles, they are extremely far from each other to the point where they are not reasonable estimates of each other. The difference between the calculated  $\omega_{hf1}$  and the measured value is about 10MHz. Doing the same calculation on  $\omega_{hf2}$  leads to about a 6600MHz difference. The reason why the low frequency poles have a good estimation on the plot is because of the logarithmic scale. In the area of the plot around where the low frequency poles are, the plot is in the 1-100Hz range, making graphical estimates to be reasonable. In the area where the high frequency poles are, the scale of the x-axis is in the 10MHz-1GHz range, making the estimates graphically extremely inaccurate. This is because each small increment of the x-axis in that range can jump in the MHz range. This would make measurements be very difficult to perform accurately.

### Calculating Percent Error:

For calculating the percent error in the  $\omega_{3dB}$ , we can use similar calculations as we did in Part 2. First, we need calculated  $\omega_{L3dB}$ :

$$\sum_{i=1}^N \frac{1}{R_i C_{is}} = \omega_{lf1} + \omega_{lf2} = 1077.381 \text{ rad/s}$$

This formula is for calculated  $\omega_{H3dB}$ :

$$\frac{1}{\sum_{i=1}^M C_i R_{is}} = \frac{1}{\tau_{hf1} + \tau_{hf2}} = \frac{1}{c_{\mu2}(R_3 || R_4) + (c_2 + c_{\mu1})(R_1 || R_2)} = 42.302 * 10^6 \text{ rad/s}$$

For percent error:

$$\%error = \left| \frac{\omega_{3dB(calculated)} - \omega_{3dB(measured)}}{\omega_{3dB(measured)}} \right| * 100$$

For  $\omega_{L3dB}$ :

$$\left| \frac{1077.38095238 - 967.610537306}{967.610537306} \right| * 100 = 11.344\% \text{ error}$$

For  $\omega_{H3dB}$ :

$$\left| \frac{42.302 * 10^6 - 42.807 * 10^6}{42.807 * 10^6} \right| * 100 = 1.178\% \text{ error}$$

The reason why the 3dB calculations were relatively accurate was because the measurement was reliant on the y-axis. Once we find the decibel level on where the 3dB point should be, it was relatively easy to line up the cursors on CircuitMaker to find the exact point on where the 3dB point was on the x-axis.

## References

1. CircuitMaker™ Manual
2. ELEC 301 Class Notes
3. Mini Project 1 Document