

# Elec 391 – 2022-W2

Mini-Project Description

Jan –Apr 2023

## **Software**

- Design Pendulum
- Draw Motor
- Simscape Model

## **Hardware**

- Program PLD
- Demo PLD on Breadboard
- Draw PCB

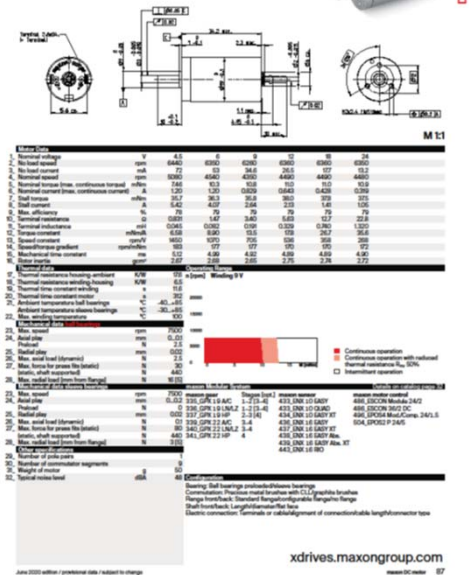
# Software System

Identify motor using maxmot.p

- Physical Dimensions
- Winding R & L
- Rotor Inertia
- Robot Friction
  - Dynamic only
  - Model as linear damper

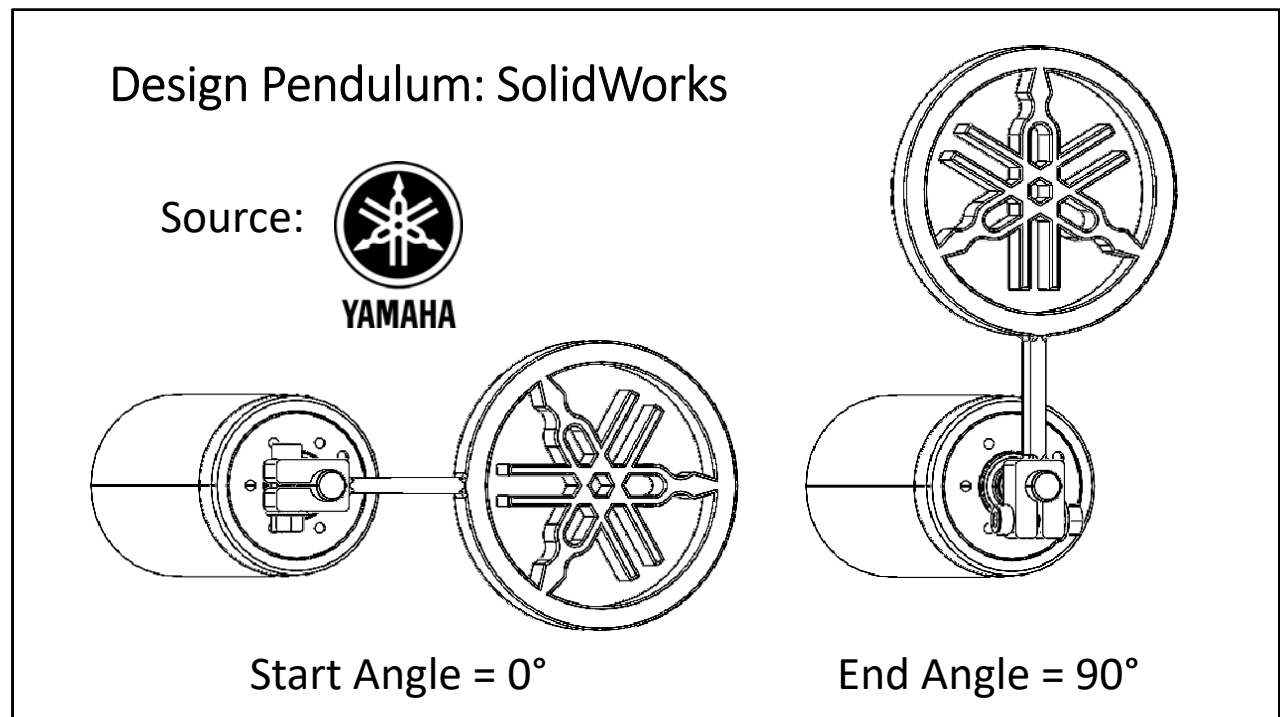
DCX 19 S Precious Metal Brushes  
DC motor  $\varnothing 19$  mm

Key Data: 5/8 W, 11.0 mNm, 7500 rpm



## maxmot.p

- Download from Canvas
- Enter Student Number
- Look up Page & Voltage from DCX catalog



### **Download motor model**

- maxongroup .com
- Brushed DC motor
- STEP file
- Create simplified model

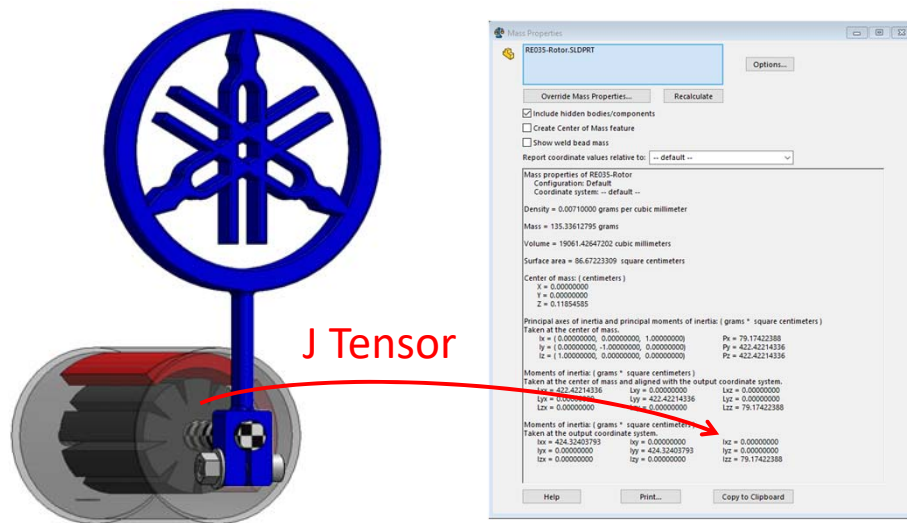
### **Custom Pendulum**

- Pendulum contains logo of your choice
- Show source where you copied Logo
- Fits motor shaft
- Reasonable length
- 3003 Aluminum
- Compute Mass, Mass Centre, Inertia

### **SolidWorks Assembly File**

- Motor (from Maxon)
- Pendulum
- Fasteners (from McMaster Carr)

## Generate Motor & Simscape Model: SW



### Download motor model

- maxongroup .com
- Brushed DC motor
- STEP file
- Create simplified model

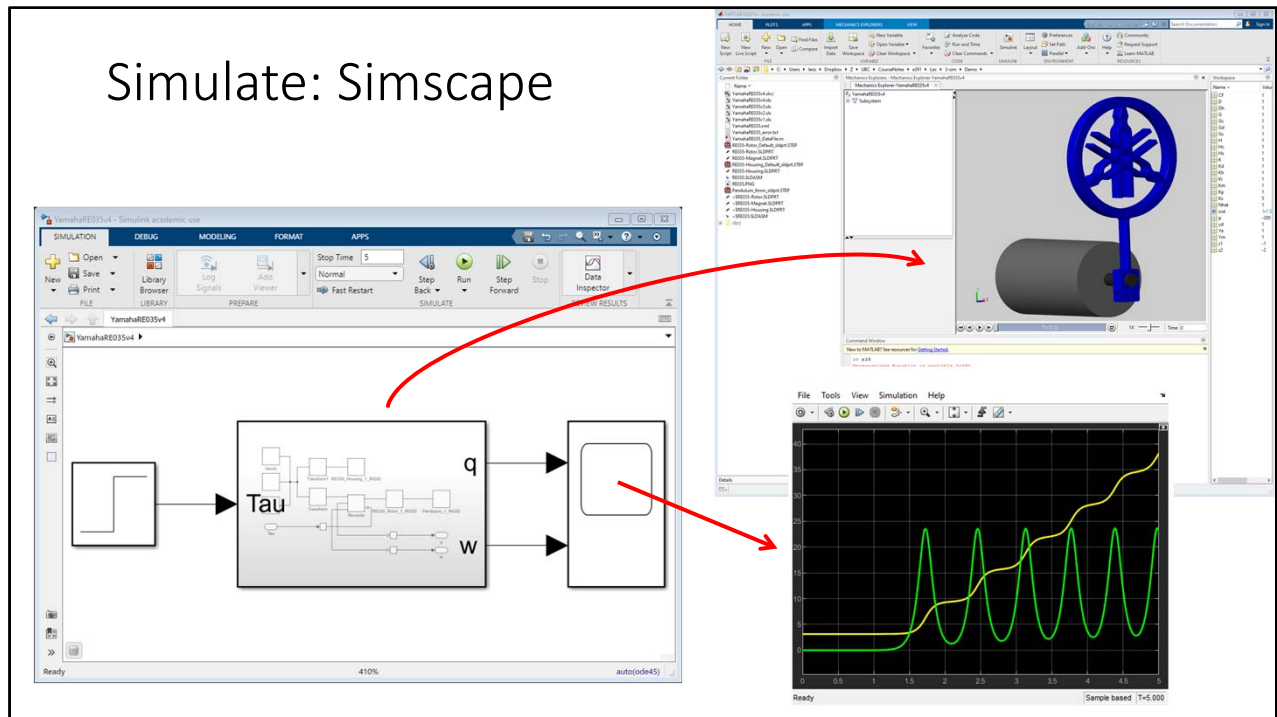
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### SolidWorks Assembly File

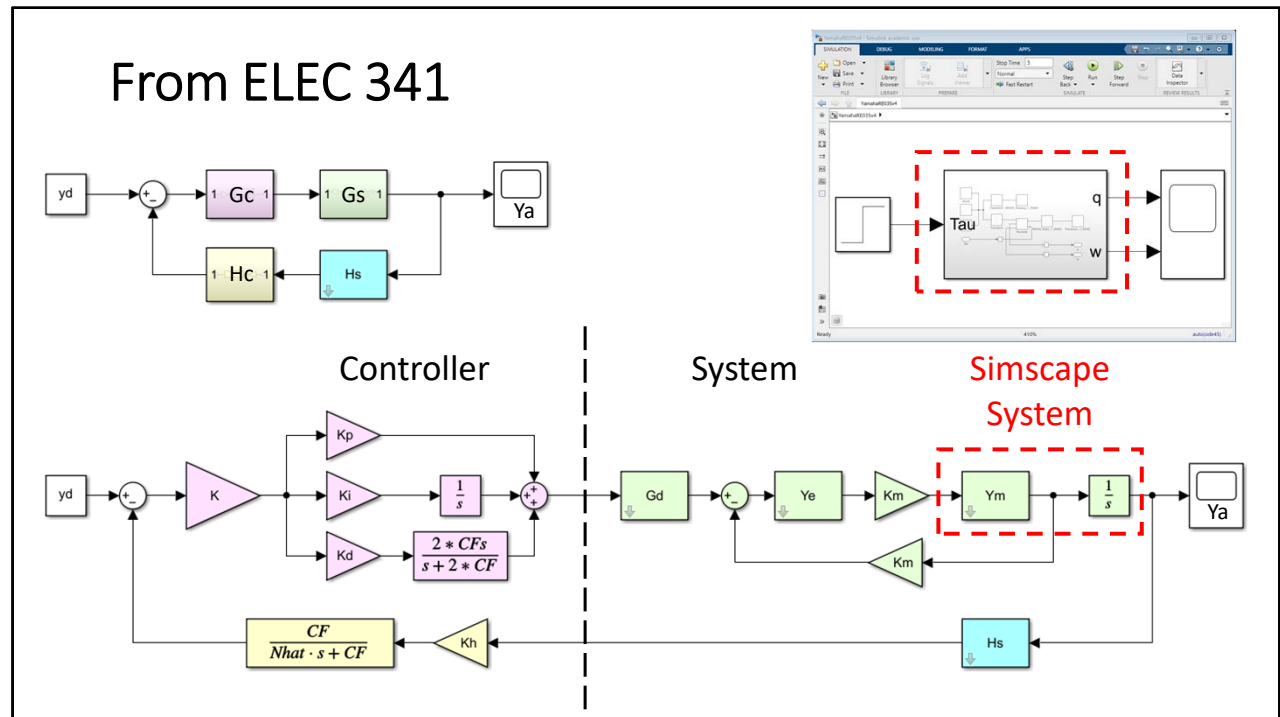
- Motor (from Maxon)
- Pendulum
- Fasteners (from McMaster Carr)

## Simulate: Simscape



### Configure Simscape model

- Mechanical parameters
- Inputs & Outputs
- Simulate
  - Animation
  - Plot Results

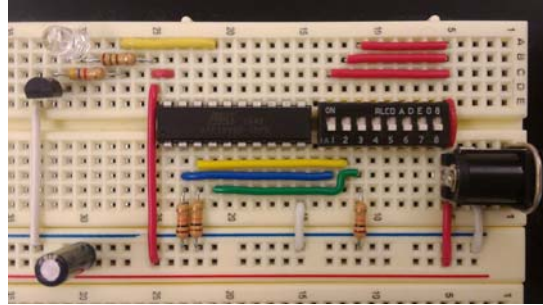
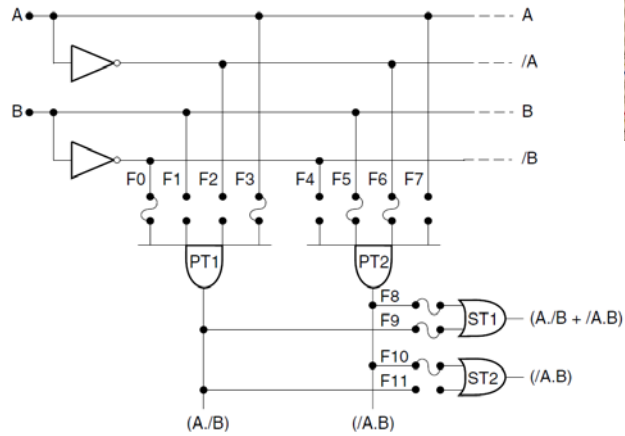


### How is this used?

- Identify System
  - Develop  $Y_m$  transfer function
- Compare to Simscape Model
- Use  $Y_m$  to design controller
- Replace  $Y_m$  and  $1/s$  blocks in “rubber-stamp” control system model with Simscape Model
- Add non-linearities to Simscape Model
- Re-tune controller (Heuristic)
- Animate (Demonstrate)
- Compare to REAL system

## Hardware System

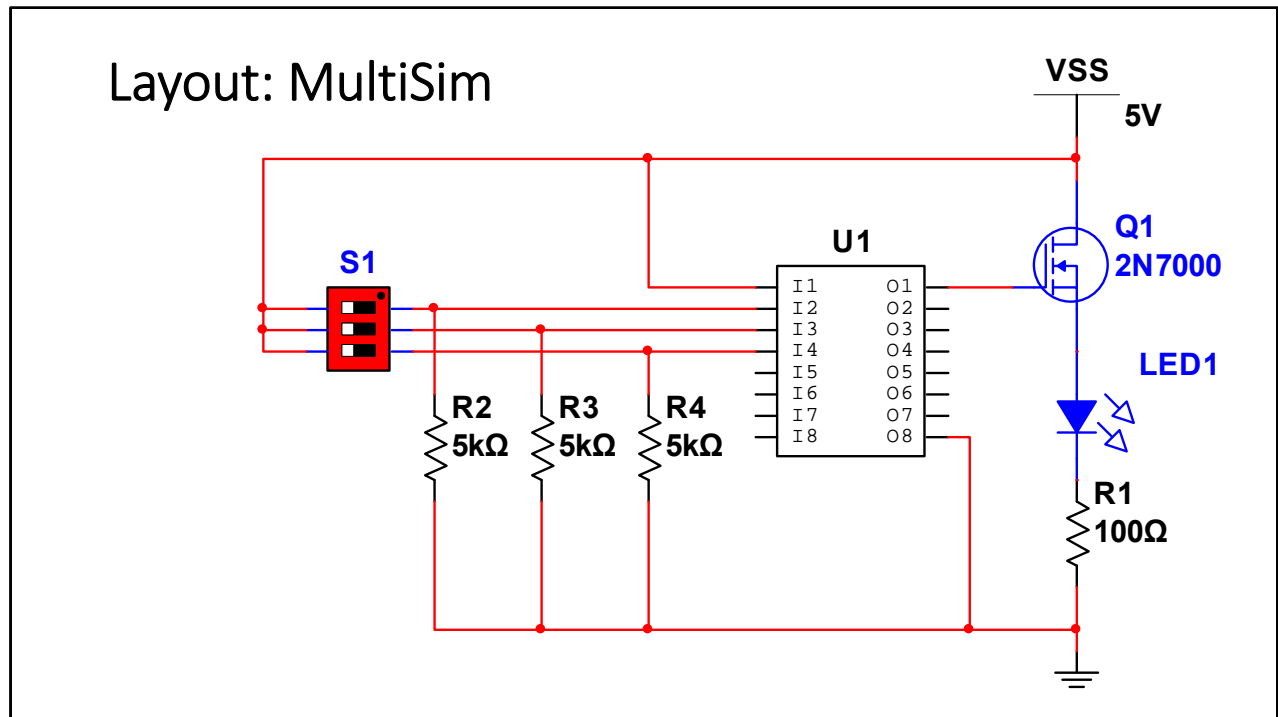
Figure 1-3. Elementary PLA architecture



DIP/SOIC	
I/CLK <input type="checkbox"/> 1	20 <input type="checkbox"/> VCC
I1 <input type="checkbox"/> 2	19 <input type="checkbox"/> I/O
I2 <input type="checkbox"/> 3	18 <input type="checkbox"/> I/O
I3 <input type="checkbox"/> 4	17 <input type="checkbox"/> I/O
I4 <input type="checkbox"/> 5	16 <input type="checkbox"/> I/O
I5 <input type="checkbox"/> 6	15 <input type="checkbox"/> I/O
I6 <input type="checkbox"/> 7	14 <input type="checkbox"/> I/O
I7 <input type="checkbox"/> 8	13 <input type="checkbox"/> I/O
I8 <input type="checkbox"/> 9	12 <input type="checkbox"/> I/O
GND <input type="checkbox"/> 10	11 <input type="checkbox"/> I9/OE

### Programmable Logic Device

- Download from Canvas
- Enter Student Number
- Look up Page & Voltage from DCX catalog

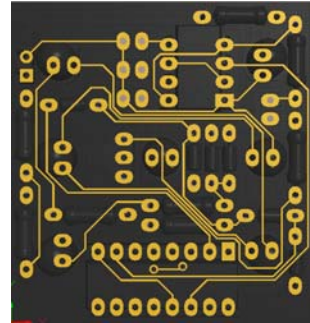
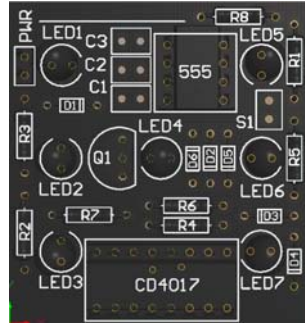
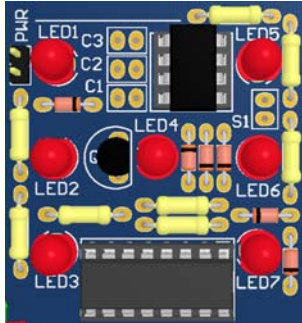


### MultiSim Circuit

- Logic 1 = ON
- Logic 0 = OFF
- External power source



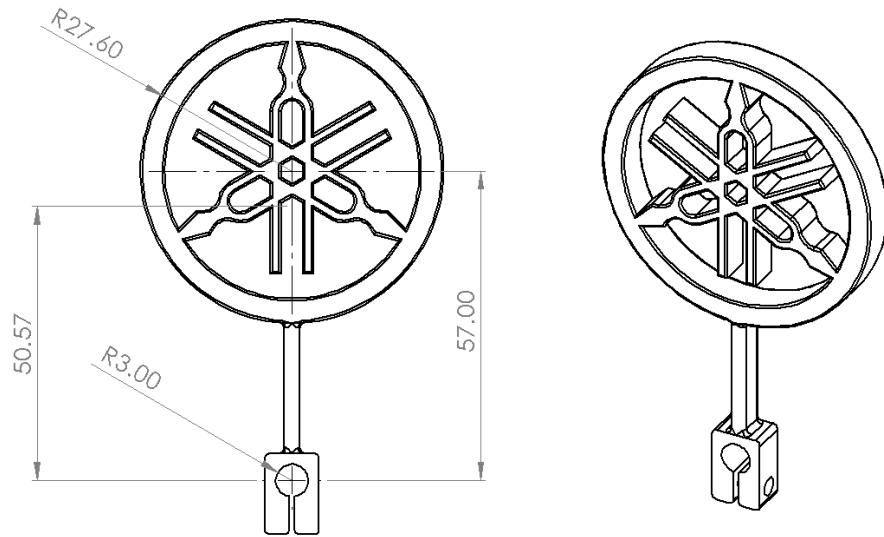
## Design PCB: UltiBoard



### UltiBoard

- Layout PCB
- 2-Sided
- No wasted space
- Labels (silk screen layer)
- Connectors
- Mounting holes

## Documentation



### PPT Slides

- Evidence of work done
- At least 1 slide / task
- Slide-Deck Format
  - See e391ReportFormat.pdf