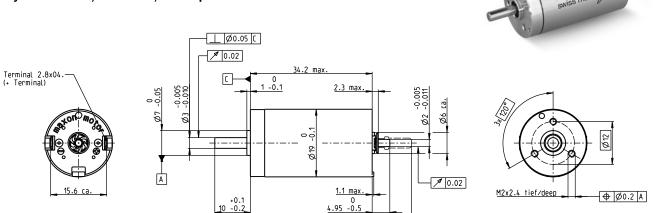
M 1:1

## DCX 19 S Precious Metal Brushes DC motor Ø19 mm

## Key Data: 5/8 W, 11.0 mNm, 7500 rpm



\_10 max

- 1	Motor Data								
1_	Nominal voltage	V	4.5	6	9	12	18	24	
2_	No load speed	rpm	6440	6350	6260	6360	6360	6350	
3_	No load current	mA	72	53	34.6	26.5	17.7	13.2	
4_	Nominal speed	rpm	5080	4540	4350	4490	4490	4480	
5_	Nominal torque (max. continuous torq	jue) mNm	7.46	10.3	10.8	11.0	11.0	10.9	
6_	Nominal current (max. continuous cur	rent) A	1.20	1.20	0.829	0.643	0.428	0.319	
7_	Stall torque	mNm	35.7	36.3	35.8	38.0	37.8	37.5	
8_	Stall current	Α	5.42	4.07	2.64	2.13	1.41	1.05	
9_	Max. efficiency	%	78	79	79	79	79	79	
10_	Terminal resistance	Ω	0.831	1.47	3.40	5.63	12.7	22.8	
11_	Terminal inductance	mH	0.045	0.082	0.191	0.329	0.740	1.320	
12_	Torque constant	mNm/A	6.58	8.90	13.5	17.8	26.7	35.6	
13_	Speed constant	rpm/V	1450	1070	705	536	358	268	
14_	Speed/torque gradient	rpm/mNm	183	177	177	170	170	172	
15_	Mechanical time constant	ms	5.12	4.99	4.92	4.89	4.89	4.90	
16_	Rotor inertia	gcm²	2.67	2.68	2.65	2.75	2.74	2.72	
	Thermal data		С	perating Rang	je				

1/_ Thermal resistance housing-ambient K/W 1/.6 n [rpm] W 18 Thermal resistance winding-housing K/W 6.5	/inding 9 V
io_ mermanesistance winding-nousing forw 0.5	
19_ Thermal time constant winding s 11,6	
20_ Thermal time constant motor s 312 20000	
21_ Ambient temperature ball bearings °C -40+85	
Ambient temperature sleeve bearings °C -30+85	
22_ Max. winding temperature °C 100 15000	
Mechanical data ball bearings	
23_ Max. speed rpm 7500 10000	
24_ Axial play mm 00.1	
Preload N 2.5 5000	
25_ Radial play mm 0,02	
26_ Max. axial load (dynamic) N 2.5	
27_ Max. force for press fits (static) N 30	5
(static, shaft supported) N 440	
28_ Max. radial load [mm from flange] N 16 [5]	
Mechanical data sleeve bearings maxon Mo	dular System

	(static, shaft supported)	N	440	
28_	Max. radial load [mm from flange]	N	16 [5]	
	Mechanical data sleeve bearings			max
23_	Max. speed	rpm	7500	max
24_	Axial play	mm	00.2	335
	Preload	N	0	336
25_	Radial play	mm	0.02	337
26_	Max. axial load (dynamic)	N	0.1	339
27_	Max. force for press fits (static)	N	80	340
	(static, shaft supported)	N	440	341
28_	Max. radial load [mm from flange]	N	3 [5]	
	Other specifications			

28_	Max. radial load [mm from flange]	N	3 [5]
	Other specifications		
29_	Number of pole pairs		1
30_	Number of commutator segments		9
31_	Weight of motor	g	50
32_	Typical noise level	dBA	48

## n [rpm] Winding 9 V

10000 5000 M [mNm]

Continuous operation Continuous operation with reduced thermal resistance R<sub>th2</sub> 50% Intermittent operation

axon gear	Stages [opt.]	maxon sensor
35_GPX 19 A/C	1-2 [3-4]	433_ENX 10 EASY
36_GPX 19 LN/LZ	1-2 [3-4]	433_ENX 10 QUAD
37_GPX 19 HP	2-3 [4]	434_ENX 10 EASY XT
39_GPX 22 A/C	3-4	436_ENX 16 EASY
10_GPX 22 LN/LZ	3-4	437_ENX 16 EASY XT
11_GPX 22 HP	4	438_ENX 16 EASY Abs.
		439_ENX 16 EASY Abs. XT
		443_ENX 16 RIO

maxon motor control 486\_ESCON Module 24/2 486\_ESCON 36/2 DC 496\_EPOS4 Mod./Comp. 24/1.5 504\_EPOS2 P 24/5

Details on catalog page 32

Bearing: Ball bearings preloaded/sleeve bearings Commutation: Precious metal brushes with CLL/graphite brushes Flange front/back: Standard flange/configurable flange/no flange Shaft front/back: Length/diameter/flat face Electric connection: Terminals or cable/alignment of connection/cable length/connector type

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