## Home work 3 - SDS

An SDS **S** is defined as a tuple (G, F,  $\pi$ ), where: (a) G=(V, E) is the underlying graph on a set V of nodes, |V| = n and |E| = m, (b)  $F = (f_v)$  denotes a set of local functions for each node v in V, on some fixed domain. Each node v computes its state by applying the function  $f_v$  on the states of its neighbors. (c)  $\pi$  denotes a permutation on V, and specifies the order in which the node states are to be updated by applying the appropriate function in *F*. One update of the SDS involves applying the local functions in the order specified by  $\pi$ . An SyDS is a variant of SDS in which nodes are updated simultaneously (synchronously). Here we will use **D** to denote the domain of the local functions in *F* and we will assume that all functions are over a Boolean domain  $\{0, 1\}$ . Thus each function  $f_v$  takes as input the value of v and its neighbors (all from the set  $\{0, 1\}$ ) and returns either a 0 or a 1. A configuration **C** of an SDS (SyDS) **S** is an *n*-vector ( $s_1$ ,  $s_2$ , ...,  $s_n$ ), where each  $s_i$  is from **D** and denotes the state of node i. A single update of an SyDS (SDS) can be thought of as a function  $\mathbf{H}: \{0,1\}^n \rightarrow$  $\{0,1\}^n$  that takes a configuration  $C_1$  and returns a new configuration  $C_2$  by applying each of the node functions synchronously (or in the order given by the specified permutation). A phase space PS of an SDS (SyDS) S is a directed graph  $G_1 = (V_1, E_1)$ , in which each node is a configuration X of S and there is a directed edge from a configuration X to a configuration Y if  $\mathbf{H}(X)$  yields Y, i.e., the dynamical system starting at *X* reaches *Y* in one step.

A predecessor of a configuration X is a configuration Y such that  $\mathbf{H}(Y)$  returns X. A fixed point is a configuration X such that  $\mathbf{H}(X)$  returns X. A Garden of Eden configuration is one that has no predecessors.

A threshold-SDS (SyDS) is one in which all of the local functions are simple Boolean threshold functions (recall that a *t*-threshold function is a Boolean function that returns a 0 when less than *t* of its inputs are 1 and returns 1 otherwise).

**Question 1:** Given an SDS (SyDS) S with n nodes, how many nodes does the phase space graph  $G_1$  have?

**Question 2:** Consider a simple SDS (SyDS) with 5 nodes arranged in a simple cycle, i.e., the nodes of the SDS (SyDS) are  $\{v_1, v_2, v_3, v_4, v_5\}$ , and the edges are  $\{(v_1, v_2), (v_2, v_3), (v_3, v_4), (v_4, v_5), (v_5, v_1)\}$ . When viewing this as an SDS let  $\pi$  be  $[v_1, v_2, v_3, v_4, v_5]$ . Let each node compute a 2-threshold function.

- 1. Draw the phase space of the SDS and SvDS.
- 2. Count the number of fixed points and Garden of Eden configurations for SDS and the SyDS.
- 3. What is the length of the longest path in the phase space of the SDS and SyDS.
- 4. What is the predecessor of the configuration (0,0,0,0,0) and (1,1,1,1,1)?
- 5. Suppose I change my permutation from  $[v_1, v_2, v_3, v_4, v_5]$  to  $[v_2, v_1, v_4, v_3, v_5]$ . Draw the phase space of this new SDS.

6. Repeat the above computations with modified SDS (SyDS) in which we add additional edges  $(v_1, v_3)$  and  $(v_2, v_4)$ .

**Question 3:** Design an SyDS with four nodes or less that has the property that has a cycle of length 2 in its phase space. Do you think you can design a SDS with a similar property?

**Question 4:** Write a program that takes as input a number n (the number of nodes) and constructs a small world network on them: you arrange the nodes in a simple cycle and then add an edge between two nodes with probability p that is proportional to  $d(u, v)^{-r}$ , i.e., for say r = 1 edges are added between vertices inversely proportional to their distance in the graph. We will consider just 3 values or r: 1, 2, and 4. Define p such that in expectation each node should have approximately n/4 edges incident on it in addition to the 2 edges that make up its neighbors. Think how would you do this (hint: you have 2 vertices at distance 2, 2 at distance 3, etc.). Each edge between vertices at distance i has the same probability of being present 1/i (in case r = 1). Then appropriate sum of these probabilities should be n/4. Each node then has an n/8 threshold function, i.e., roughly it becomes 1 when  $\frac{1}{2}$  or more of its neighbors are 1.

- 1. Device an elementary algorithm to count the number of fixed points and Garden of Eden configuration. What is the largest *n* for which you can count the number of fixed points and Garden of Eden configurations?
- 2. Do you notice a sharp increase in the running time as a function of n (plot it for n = 6, 7, 8, 9, 10, ...) Can you think why?