# COLLATE

# Software Engineering

## Notes

## Unit 3

# Syllabus

## UNIT – III

Software Design:
Cohesion & Coupling, Classification of Cohesiveness & Coupling,
Function Oriented Design, Object Oriented
Design, User Interface Design.
Software Reliability:
Failure and Faults, Reliability Models: Basic Model, Logarithmic
Poisson Model, Calendar time Component,
Reliability Allocation.

*LECTURE NOTE 26*

# SOFTWARE RELIABILITY AND QUALITY MANAGEMENT

**Repeatable vs. non-repeatable software development organization**

A repeatable software development organization is one in which the software development process is person-independent. In a non-repeatable software development organization, a software development project becomes successful primarily due to the initiative, effort, brilliance, or enthusiasm displayed by certain individuals. Thus, in a non-repeatable software development organization, the chances of successful completion of a software project is to a great extent depends on the team members.

**Software Reliability**

Reliability of a software product essentially denotes its trustworthiness or dependability. Alternatively, reliability of a software product can also be defined as the probability of the product working "correctly" over a given period of time.

It is obvious that a software product having a large number of defects is unreliable. It is also clear that the reliability of a system improves, if the number of defects in it is reduced. However, there is no simple relationship between the observed system reliability and the number of latent defects in the system. For example, removing errors from parts of a software which are rarely executed makes little difference to the perceived reliability of the product. It has been experimentally observed by analyzing the behavior of a large number of programs that 90% of the execution time of a typical program is spent in executing only 10% of the instructions in the program. These most used 10% instructions are often called the core of the program. The rest 90% of the program statements are called non-core and are executed only for 10% of the total execution time. It therefore may not be very surprising to note that removing 60% product defects from the least used parts of a system would typically lead to only 3% improvement to the product reliability. It is clear that the quantity by which the overall reliability of a program improves due to the correction of a single error depends on how frequently the corresponding instruction is executed.

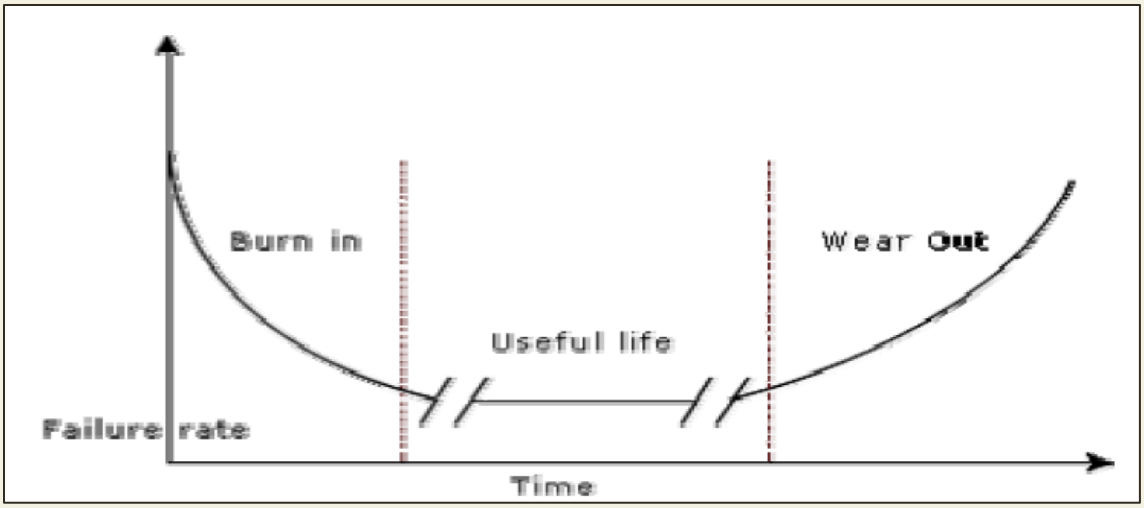
Thus, reliability of a product depends not only on the number of latent errors but also on the exact location of the errors. Apart from this, reliability also depends upon how the product is used, i.e. on its execution profile. If it is selected input data to the system such that only the "correctly" implemented functions are executed, none of the errors will be exposed and the perceived reliability of the product will be high. On the other hand, if the input data is selected such that only those functions which contain errors are invoked, the perceived reliability of the system will be very low.

**Reasons for software reliability being difficult to measure**

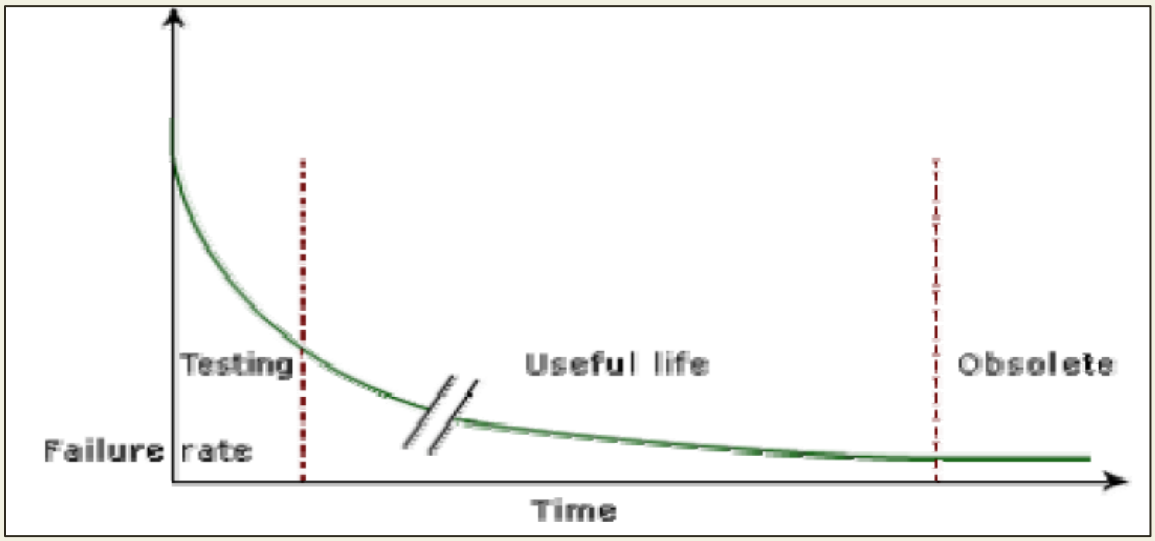
The reasons why software reliability is difficult to measure can be summarized as follows:

- The reliability improvement due to fixing a single bug depends on where the bug is located in the code.
- The perceived reliability of a software product is highly observer-dependent.
- The reliability of a product keeps changing as errors are detected and fixed.
- Hardware reliability vs. software reliability differs.

Reliability behavior for hardware and software are very different. For example, hardware failures are inherently different from software failures. Most hardware failures are due to component wear and tear. A logic gate may be stuck at 1 or 0, or a resistor might short circuit. To fix hardware faults, one has to either replace or repair the failed part. On the other hand, a software product would continue to fail until the error is tracked down and either the design or the code is changed. For this reason, when a hardware is repaired its reliability is maintained at the level that existed before the failure occurred; whereas when a software failure is repaired, the reliability may either increase or decrease (reliability may decrease if a bug introduces new errors). To put this fact in a different perspective, hardware reliability study is concerned with stability (for example, inter-failure times remain constant). On the other hand, software reliability study aims at reliability growth (i.e. inter-failure times increase). The change of failure rate over the product lifetime for a typical hardware and a software product are sketched in fig. 26.1. For hardware products, it can be observed that failure rate is high initially but decreases as the faulty components are identified and removed. The system then enters its useful life. After some time (called product life time) the components wear out, and the failure rate increases. This gives the plot of hardware reliability over time its characteristics “bath tub” shape. On the other hand, for software the failure rate is at it’s highest during integration and test. As the system is tested, more and more errors are identified and removed resulting in reduced failure rate. This error removal continues at a slower pace during the useful life of the product. As the software becomes obsolete no error corrections occurs and the failure rate remains unchanged.




**(a)** Hardware product




**(b)** Software product

Fig. 26.1: Change in failure rate of a product

**Reliability Metrics**

The reliability requirements for different categories of software products may be different. For this reason, it is necessary that the level of reliability required for a software product should be specified in the SRS (software requirements specification) document. In order to be able to do this, some metrics are needed to quantitatively express the reliability of a software product. A good reliability measure should be observer-dependent, so that different people can agree on the degree of reliability a system has. For example, there are precise techniques for measuring performance, which would result in obtaining the same performance value irrespective of who is carrying out the performance measurement. However, in practice, it is very difficult to formulate a precise reliability measurement technique. The next base case is to have measures that correlate

with reliability. There are six reliability metrics which can be used to quantify the reliability of software products.

- **Rate of occurrence of failure (ROCOF)-** ROCOF measures the frequency of occurrence of unexpected behavior (i.e. failures). ROCOF measure of a software product can be obtained by observing the behavior of a software product in operation over a specified time interval and then recording the total number of failures occurring during the interval.
- **Mean Time To Failure (MTTF) -** MTTF is the average time between two successive failures, observed over a large number of failures. To measure MTTF, we can record the failure data for n failures. Let the failures occur at the time instants $t_1$, $t_2$, …, $t_n$. Then, MTTF can be calculated as

$$\sum_{i=1}^{n} \frac{t_{i+1} - t_i}{(n-1)}$$

  It is important to note that only run time is considered in the time measurements, i.e. the time for which the system is down to fix the error, the boot time, etc are not taken into account in the time measurements and the clock is stopped at these times.
- **Mean Time To Repair (MTTR) -** Once failure occurs, sometime is required to fix the error. MTTR measures the average time it takes to track the errors causing the failure and to fix them.
- **Mean Time Between Failure (MTBR) -** MTTF and MTTR can be combined to get the MTBR metric: MTBF = MTTF + MTTR. Thus, MTBF of 300 hours indicates that once a failure occurs, the next failure is expected after 300 hours. In this case, time measurements are real time and not the execution time as in MTTF.
- **Probability of Failure on Demand (POFOD) -** Unlike the other metrics discussed, this metric does not explicitly involve time measurements. POFOD measures the likelihood of the system failing when a service request is made. For example, a POFOD of 0.001 would mean that 1 out of every 1000 service requests would result in a failure.
- **Availability-** Availability of a system is a measure of how likely shall the system be available for use over a given period of time. This metric not only considers the number of failures occurring during a time interval, but also takes into account the repair time (down time) of a system when a failure occurs. This metric is important for systems such as telecommunication systems, and operating systems, which are supposed to be never down and where repair and restart time are significant and loss of service during that time is important.

Classification of software failures

A possible classification of failures of software products into five different types is as follows:

- **Transient-** Transient failures occur only for certain input values while invoking a function of the system.
- **Permanent-** Permanent failures occur for all input values while invoking a function of the system.
- **Recoverable-** When recoverable failures occur, the system recovers with or without operator intervention.
- **Unrecoverable-** In unrecoverable failures, the system may need to be restarted.
- **Cosmetic-** These classes of failures cause only minor irritations, and do not lead to incorrect results. An example of a cosmetic failure is the case where the mouse button has to be clicked twice instead of once to invoke a given function through the graphical user interface.

*LECTURE NOTE 27*

# RELIABILITY GROWTH MODELS

A reliability growth model is a mathematical model of how software reliability improves as errors are detected and repaired. A reliability growth model can be used to predict when (or if at all) a particular level of reliability is likely to be attained. Thus, reliability growth modeling can be used to determine when to stop testing to attain a given reliability level. Although several different reliability growth models have been proposed, in this text we will discuss only two very simple reliability growth models.

**Jelinski and Moranda Model** -The simplest reliability growth model is a step function model where it is assumed that the reliability increases by a constant increment each time an error is detected and repaired. Such a model is shown in fig. 27.1. However, this simple model of reliability which implicitly assumes that all errors contribute equally to reliability growth, is highly unrealistic since it is already known that correction of different types of errors contribute differently to reliability growth.

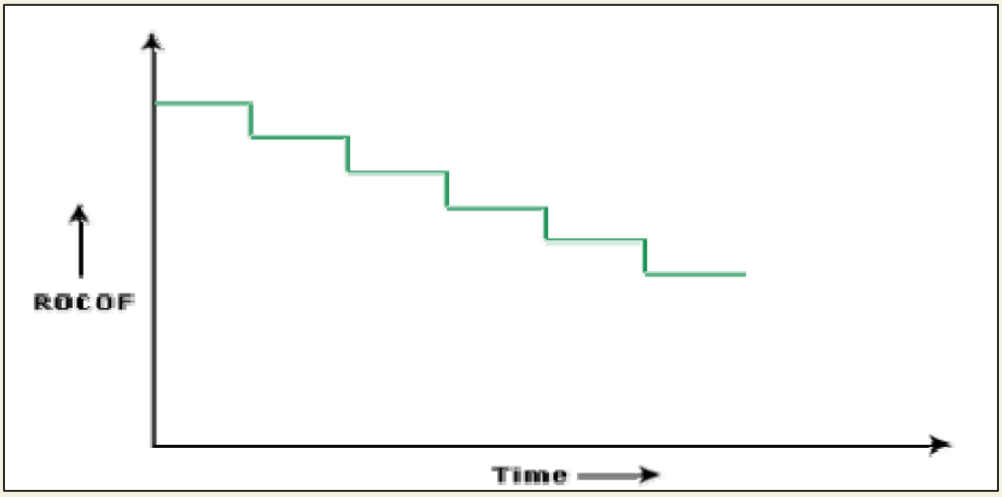



Fig. 27.1: Step function model of reliability growth

**Littlewood and Verall's Model** -This model allows for negative reliability growth to reflect the fact that when a repair is carried out, it may introduce additional errors. It also models the fact that as errors are repaired, the average improvement in reliability per repair decreases (Fig. 27.2). It treat's an error's contribution to reliability improvement to be an independent random variable having Gamma distribution. This distribution models the fact that error corrections with large contributions to reliability growth are removed first. This represents diminishing return as test continues.

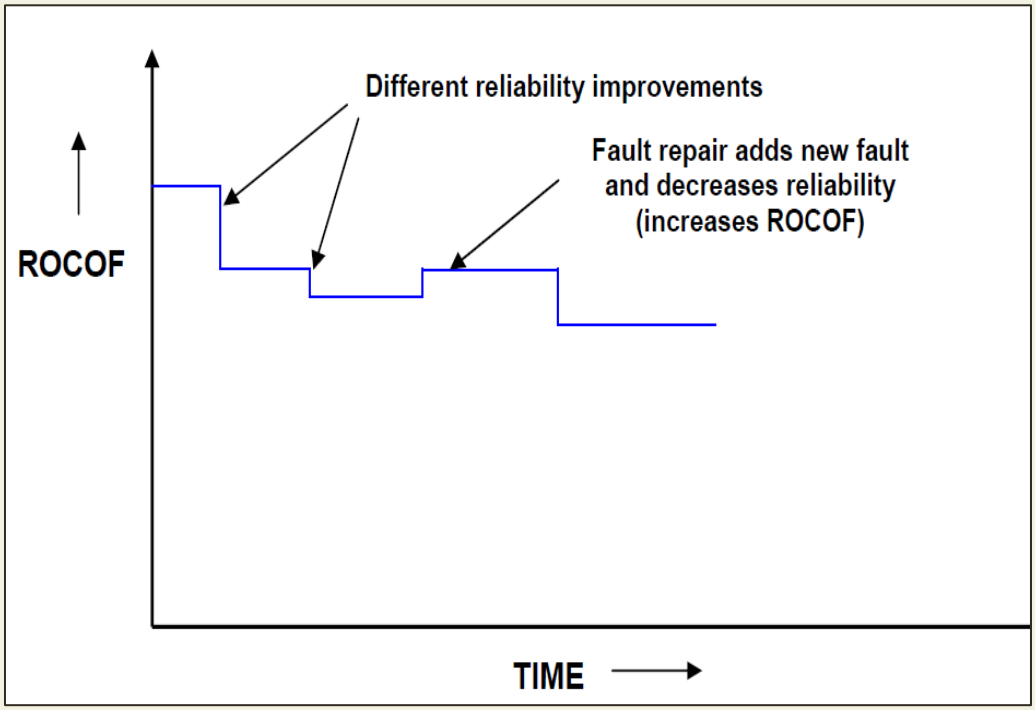



Fig. 27.2: Random-step function model of reliability growth

**Statistical Testing**

Statistical testing is a testing process whose objective is to determine the reliability of software products rather than discovering errors. Test cases are designed for statistical testing with an entirely different objective than those of conventional testing.

**Operation profile**

Different categories of users may use a software for different purposes. For example, a Librarian might use the library automation software to create member records, add books to the library, etc. whereas a library member might use to software to query about the availability of the book, or to issue and return books. Formally, the operation profile of a software can be defined as the probability distribution of the input of an average user. If the input to a number of classes $\{C_i\}$ is divided, the probability value of a class represent the probability of an average user selecting his next input from this class. Thus, the operation profile assigns a probability value $P_i$ to each input class $C_i$.

**Steps in statistical testing**

Statistical testing allows one to concentrate on testing those parts of the system that are most likely to be used. The first step of statistical testing is to determine the operation profile of the software. The next step is to generate a set of test data corresponding to the determined operation profile. The third step is to apply the test cases to the software and record the time between each

failure. After a statistically significant number of failures have been observed, the reliability can be computed.

**Advantages and disadvantages of statistical testing**

Statistical testing allows one to concentrate on testing parts of the system that are most likely to be used. Therefore, it results in a system that the users to be more reliable (than actually it is!). Reliability estimation using statistical testing is more accurate compared to those of other methods such as ROCOF, POFOD etc. But it is not easy to perform statistical testing properly. There is no simple and repeatable way of defining operation profiles. Also it is very much cumbersome to generate test cases for statistical testing because the number of test cases with which the system is to be tested should be statistically significant.

*LECTURE NOTE 8*

# SOFTWARE DESIGN

Software design is a process to transform user requirements into some suitable form, which helps the programmer in software coding and implementation.

For assessing user requirements, an SRS (Software Requirement Specification) document is created whereas for coding and implementation, there is a need of more specific and detailed requirements in software terms. The output of this process can directly be used into implementation in programming languages.

Software design is the first step in SDLC (Software Design Life Cycle), which moves the concentration from problem domain to solution domain. It tries to specify how to fulfill the requirements mentioned in SRS.

## Software Design Levels

Software design yields three levels of results:

- **Architectural Design -** The architectural design is the highest abstract version of the system. It identifies the software as a system with many components interacting with each other. At this level, the designers get the idea of proposed solution domain.
- **High-level Design-** The high-level design breaks the 'single entity-multiple component' concept of architectural design into less-abstracted view of sub-systems and modules and depicts their interaction with each other. High-level design focuses on how the system along with all of its components can be implemented in forms of modules. It recognizes modular structure of each sub-system and their relation and interaction among each other.
- **Detailed Design-** Detailed design deals with the implementation part of what is seen as a system and its sub-systems in the previous two designs. It is more detailed towards modules and their implementations. It defines logical structure of each module and their interfaces to communicate with other modules.

## Modularization

Modularization is a technique to divide a software system into multiple discrete and independent modules, which are expected to be capable of carrying out task(s) independently. These modules may work as basic constructs for the entire software. Designers tend to design modules such that they can be executed and/or compiled separately and independently.

Modular design unintentionally follows the rules of 'divide and conquer' problem-solving strategy this is because there are many other benefits attached with the modular design of a software.

Advantage of modularization:

- Smaller components are easier to maintain
- Program can be divided based on functional aspects
- Desired level of abstraction ca n be brought in the program
- Components with high cohesion can be re-used again.
- Concurrent execution can be made possible
- Desired from security aspect

**Concurrency**

Back in time, all softwares were meant to be executed sequentially. By sequential execution we mean that the coded instruction will be executed one after another implying only one portion of program being activated at any given time. Say, a software has multiple modules, then only one of all the modules can be found active at any time of execution.

In software design, concurrency is implemented by splitting the software into multiple independent units of execution, like modules and executing them in parallel. In other words, concurrency provides capability to the software to execute more than one part of code in parallel to each other.

It is necessary for the programmers and designers to recognize those modules, which can be made parallel execution.

Example

The spell check feature in word processor is a module of software, which runs alongside the word processor itself.

**Coupling and Cohesion**

When a software program is modularized, its tasks are divided into several modules based on some characteristics. As we know, modules are set of instructions put together in order to achieve some tasks. They are though, considered as single entity but may refer to each other to work together. There are measures by which the quality of a design of modules and their interaction among them can be measured. These measures are called coupling and cohesion.

**Cohesion**

Cohesion is a measure that defines the degree of intra-dependability within elements of a module. The greater the cohesion, the better is the program design.

There are seven types of cohesion, namely –

- **Co-incidental cohesion -** It is unplanned and random cohesion, which might be the result of breaking the program into smaller modules for the sake of modularization. Because it is unplanned, it may serve confusion to the programmers and is generally not-accepted.
- **Logical cohesion -** When logically categorized elements are put together into a module, it is called logical cohesion.
- **Temporal Cohesion -** When elements of module are organized such that they are processed at a similar point in time, it is called temporal cohesion.
- **Procedural cohesion -** When elements of module are grouped together, which are executed sequentially in order to perform a task, it is called procedural cohesion.
- **Communicational cohesion -** When elements of module are grouped together, which are executed sequentially and work on same data (information), it is called communicational cohesion.
- **Sequential cohesion -** When elements of module are grouped because the output of one element serves as input to another and so on, it is called sequential cohesion.
- **Functional cohesion -** It is considered to be the highest degree of cohesion, and it is highly expected. Elements of module in functional cohesion are grouped because they all contribute to a single well-defined function. It can also be reused.

**Coupling**

Coupling is a measure that defines the level of inter-dependability among modules of a program. It tells at what level the modules interfere and interact with each other. The lower the coupling, the better the program.

There are five levels of coupling, namely -

- **Content coupling -** When a module can directly access or modify or refer to the content of another module, it is called content level coupling.
- **Common coupling-** When multiple modules have read and write access to some global data, it is called common or global coupling.
- **Control coupling-** Two modules are called control-coupled if one of them decides the function of the other module or changes its flow of execution.
- **Stamp coupling-** When multiple modules share common data structure and work on different part of it, it is called stamp coupling.
- **Data coupling-** Data coupling is when two modules interact with each other by means of passing data (as parameter). If a module passes data structure as parameter, then the receiving module should use all its components.

Ideally, no coupling is considered to be the best.

**Design Verification**

The output of software design process is design documentation, pseudo codes, detailed logic diagrams, process diagrams, and detailed description of all functional or non-functional requirements.

The next phase, which is the implementation of software, depends on all outputs mentioned above.

It is then becomes necessary to verify the output before proceeding to the next phase. The early any mistake is detected, the better it is or it might not be detected until testing of the product. If the outputs of design phase are in formal notation form, then their associated tools for verification should be used otherwise a thorough design review can be used for verification and validation.

By structured verification approach, reviewers can detect defects that might be caused by overlooking some conditions. A good design review is important for good software design, accuracy and quality.

*LECTURE NOTE 9*

# SOFTWARE DESIGN STRATEGIES

Software design is a process to conceptualize the software requirements into software implementation. Software design takes the user requirements as challenges and tries to find optimum solution. While the software is being conceptualized, a plan is chalked out to find the best possible design for implementing the intended solution.

There are multiple variants of software design. Let us study them briefly:

Software design is a process to conceptualize the software requirements into software implementation. Software design takes the user requirements as challenges and tries to find optimum solution. While the software is being conceptualized, a plan is chalked out to find the best possible design for implementing the intended solution.

There are multiple variants of software design. Let us study them briefly:

**Structured Design**

Structured design is a conceptualization of problem into several well-organized elements of solution. It is basically concerned with the solution design. Benefit of structured design is, it gives better understanding of how the problem is being solved. Structured design also makes it simpler for designer to concentrate on the problem more accurately.

Structured design is mostly based on 'divide and conquer' strategy where a problem is broken into several small problems and each small problem is individually solved until the whole problem is solved.

The small pieces of problem are solved by means of solution modules. Structured design emphasis that these modules be well organized in order to achieve precise solution.

These modules are arranged in hierarchy. They communicate with each other. A good structured design always follows some rules for communication among multiple modules, namely -

**Cohesion** - grouping of all functionally related elements.

**Coupling** - communication between different modules.

A good structured design has ***high*** cohesion and ***low*** coupling arrangements.

### Function Oriented Design

In function-oriented design, the system is comprised of many smaller sub-systems known as functions. These functions are capable of performing significant task in the system. The system is considered as top view of all functions.

Function oriented design inherits some properties of structured design where divide and conquer methodology is used.

This design mechanism divides the whole system into smaller functions, which provides means of abstraction by concealing the information and their operation. These functional modules can share information among themselves by means of information passing and using information available globally.

Another characteristic of functions is that when a program calls a function, the function changes the state of the program, which sometimes is not acceptable by other modules. Function oriented design works well where the system state does not matter and program/functions work on input rather than on a state.

### Design Process

- The whole system is seen as how data flows in the system by means of data flow diagram.
- DFD depicts how functions change the data and state of entire system.
- The entire system is logically broken down into smaller units known as functions on the basis of their operation in the system.
- Each function is then described at large.

### Object Oriented Design

Object oriented design works around the entities and their characteristics instead of functions involved in the software system. This design strategy focuses on entities and its characteristics. The whole concept of software solution revolves around the engaged entities.

Let us see the important concepts of Object Oriented Design:

- **Objects -** All entities involved in the solution design are known as objects. For example, person, banks, company and customers are treated as objects. Every entity has some attributes associated to it and has some methods to perform on the attributes.
- **Classes -** A class is a generalized description of an object. An object is an instance of a class. Class defines all the attributes, which an object can have and methods, which defines the functionality of the object.

In the solution design, attributes are stored as variables and functionalities are defined by means of methods or procedures.

- **Encapsulation -** In OOD, the attributes (data variables) and methods (operation on the data) are bundled together is called encapsulation. Encapsulation not only bundles important information of an object together, but also restricts access of the data and methods from the outside world. This is called information hiding.
- **Inheritance -** OOD allows similar classes to stack up in hierarchical manner where the lower or sub-classes can import, implement and re-use allowed variables and methods from their immediate super classes. This property of OOD is known as inheritance. This makes it easier to define specific class and to create generalized classes from specific ones.
- **Polymorphism -** OOD languages provide a mechanism where methods performing similar tasks but vary in arguments, can be assigned same name. This is called polymorphism, which allows a single interface performing tasks for different types. Depending upon how the function is invoked, respective portion of the code gets executed.

**Design Process**

Software design process can be perceived as series of well-defined steps. Though it varies according to design approach (function oriented or object oriented, yet It may have the following steps involved:

- A solution design is created from requirement or previous used system and/or system sequence diagram.
- Objects are identified and grouped into classes on behalf of similarity in attribute characteristics.
- Class hierarchy and relation among them are defined.
- Application framework is defined.

**Software Design Approaches**

There are two generic approaches for software designing:

**Top down Design**

We know that a system is composed of more than one sub-systems and it contains a number of components. Further, these sub-systems and components may have their one set of sub-system and components and creates hierarchical structure in the system.

Top-down design takes the whole software system as one entity and then decomposes it to achieve more than one sub-system or component based on some characteristics. Each sub-

system or component is then treated as a system and decomposed further. This process keeps on running until the lowest level of system in the top-down hierarchy is achieved.

Top-down design starts with a generalized model of system and keeps on defining the more specific part of it. When all components are composed the whole system comes into existence.

Top-down design is more suitable when the software solution needs to be designed from scratch and specific details are unknown.

**Bottom-up Design**

The bottom up design model starts with most specific and basic components. It proceeds with composing higher level of components by using basic or lower level components. It keeps creating higher level components until the desired system is not evolved as one single component. With each higher level, the amount of abstraction is increased.

Bottom-up strategy is more suitable when a system needs to be created from some existing system, where the basic primitives can be used in the newer system.

Both, top-down and bottom-up approaches are not practical individually. Instead, a good combination of both is used.

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