## Variational Inference

CS772A: Probabilistic Machine Learning
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# Variational Inference (VI)

lacktriangle Assume a latent variable model with data  $oldsymbol{\mathcal{D}}$  and latent variables  $oldsymbol{Z}$ 

lacktriangle A simple setting might look something like this  $egin{align*} \phi \\ \hline \phi \\ \hline \end{array}$ 

This setting is just one example. VI is applicable in more general and more complex probabilistic models with and without latent variables

- Assume the likelihood is  $p(\mathcal{D}|\mathbf{Z},\Theta)$  and prior is  $p(\mathbf{Z}|\Theta)$ . Want posterior over  $\mathbf{Z}$
- ullet  $\Theta = (\theta, \phi)$  denotes the other parameters that define the likelihood and the prior
- For now, assume  $\Theta$  is known and only Z is unknown (the  $\Theta$  unknown case later)
- Assume CP  $p(Z|D, \Theta)$  is intractable

## Variational Inference (VI)

lacktriangle Assuming  $p(Z|\mathcal{D},\Theta)$  is intractable, VI approximates it by a distr  $q(Z|\phi)$  or  $q_{\phi}(Z)$ 

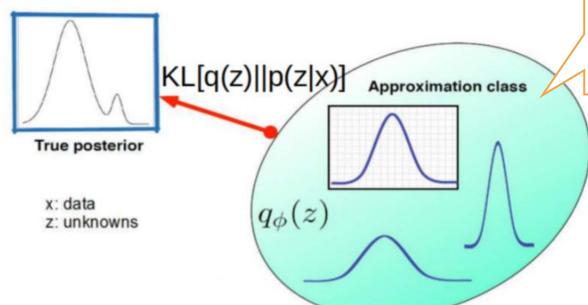
Find the optimal  $\phi$  which makes our approximation  $q(\mathbf{Z}|\phi)$  as closed to the true as possible to the true posterior  $p(\mathbf{Z}|\mathbf{D})$ 

Kullback Leibler divergence  $\mathrm{KL}[q||p]$  between q and p

Also possible to use KL[p||q] or divergences other than KL

$$\phi^* = \operatorname{argmin}_{\phi} \operatorname{KL}[q_{\phi}(\mathbf{Z})||p(\mathbf{Z}|\mathcal{D},\Theta)]$$

 $q_{m{\phi}}$  defines a class of distributions parametrized by  ${m{\phi}}$  sometimes called "variational parameters"



Name "variational" comes from
Physics and refers to problems
where we are optimizing functions
of distributions (here the function is
the KL divergence)



## Variational Inference (VI)

■ The optimization problem

$$\begin{split} \phi^* &= \operatorname{argmin}_{\phi} \operatorname{KL}[q_{\phi}(\boldsymbol{Z})||p(\boldsymbol{Z}|\boldsymbol{\mathcal{D}},\boldsymbol{\Theta})] \\ &= \operatorname{argmin}_{\phi} \mathbb{E}_{q_{\phi}(\boldsymbol{Z})} \left[ \log q_{\phi}(\boldsymbol{Z}) - \log \frac{p(\boldsymbol{\mathcal{D}}|\boldsymbol{Z},\boldsymbol{\Theta})p(\boldsymbol{Z}|\boldsymbol{\Theta})}{p(\boldsymbol{\mathcal{D}}|\boldsymbol{\Theta})} \right] \\ &= \operatorname{argmin}_{\phi} \mathbb{E}_{q_{\phi}(\boldsymbol{Z})} [\log q_{\phi}(\boldsymbol{Z}) - \log p(\boldsymbol{\mathcal{D}}|\boldsymbol{Z},\boldsymbol{\Theta}) - \log p(\boldsymbol{Z}|\boldsymbol{\Theta})] + \log p(\boldsymbol{\mathcal{D}}|\boldsymbol{\Theta}) \end{split}$$

■ Since  $\log p(\mathcal{D}|\Theta)$  is independent of  $\phi$ , the optimization problem becomes

$$\phi^* = \operatorname{argmin}_{\phi} \mathbb{E}_{q_{\phi}(\boldsymbol{Z})} \left[ \log q_{\phi}(\boldsymbol{Z}) - \log p(\boldsymbol{\mathcal{D}}|\boldsymbol{\mathcal{Z}}, \boldsymbol{\Theta}) - \log p(\boldsymbol{\mathcal{Z}}|\boldsymbol{\Theta}) \right]$$

$$\phi^* = \operatorname{argmin}_{\phi} \mathbb{E}_{q_{\phi}(\boldsymbol{Z})} \left[ \log q_{\phi}(\boldsymbol{Z}) - \log p(\boldsymbol{\mathcal{D}}, \boldsymbol{\mathcal{Z}}|\boldsymbol{\Theta}) \right]$$

$$\phi^* = \operatorname{argmax}_{\phi} \mathbb{E}_{q_{\phi}(\mathbf{Z})} [\log p(\mathbf{D}, \mathbf{Z} | \Theta) - \log q_{\phi}(\mathbf{Z})] = \operatorname{argmax} \mathcal{L}(\phi, \Theta)$$

■ Note that  $\mathcal{L}(\phi, \Theta) \leq \log p(\mathcal{D}|\Theta)$  and is called "Evidence Lower Bound" (ELBO)

#### The ELBO

■ The ELBO is defined as

$$\mathcal{L}(\phi, \Theta) = \mathbb{E}_{q_{\phi}(\mathbf{Z})} \left[ \log p(\mathbf{D}, \mathbf{Z}|\Theta) - \log q_{\phi}(\mathbf{Z}) \right]$$
$$= \mathbb{E}_{q_{\phi}(\mathbf{Z})} \left[ \log p(\mathbf{D}, \mathbf{Z}|\Theta) \right] + \mathbb{H}[q_{\phi}(\mathbf{Z})]$$

- Thus maximizing the ELBO w.r.t.  $\phi$  gives us a  $q_{\phi}(Z)$  which
  - Maximizes the expected joint probability of data and latent variables
  - Has a high entropy
- We can also write the ELBO as follows

$$\mathcal{L}(\phi, \Theta) = \mathbb{E}_{q_{\phi}(\mathbf{Z})}[\log p(\mathbf{D}|\mathbf{Z}, \Theta)] - \text{KL}[q_{\phi}(\mathbf{Z})||p(\mathbf{Z}|\Theta)]$$

- Thus maximizing the ELBO w.r.t.  $\phi$  will give us a  $q_{\phi}(Z)$  which
  - Explains the data  $\mathcal{D}$  well, i.e., gives it large expected probability  $\mathbb{E}_q[\log p(\mathcal{D}|\mathbf{Z},\Theta)]$
  - Is close to the prior  $p(\mathbf{Z})$ , i.e. is simple/regularized (small  $\mathrm{KL}[q_{\phi}(\mathbf{Z})||p(\mathbf{Z}|\Theta))$

## Maximizing the ELBO

Unknown  $\Theta$  case later

lacktriangle We need to maximize the ELBO w.r.t.  $oldsymbol{\phi}$  (for now, assuming  $oldsymbol{\Theta}$  is known)

$$\mathcal{L}(\phi, \Theta) = \mathbb{E}_{q_{\phi}(\mathbf{Z})}[\log p(\mathbf{D}|\mathbf{Z}, \Theta)] - \text{KL}[q_{\phi}(\mathbf{Z})||p(\mathbf{Z}|\Theta)]$$

- The general approach to maximize ELBO is based on gradient-based methods
  - Assume some suitable/convenient form for  $q_{\phi}(\mathbf{Z})$ , e.g.,  $\mathcal{N}(\mathbf{Z}|\mu,\Sigma)$  so  $\phi=(\mu,\Sigma)$
  - lacktriangle Maximize the ELBO w.r.t.  $oldsymbol{\phi}$  using gradient ascent

$$\phi_{t+1} = \phi_t + \eta_t \, \nabla_{\phi_t} \mathcal{L}(\phi, \Theta)$$

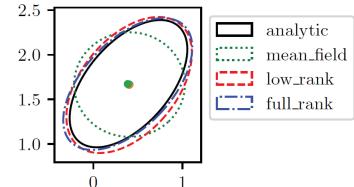
- lacktriangle Note: Expectations in ELBO and ELBO's gradients w.r.t.  $oldsymbol{\phi}$  may not be easy
  - Will see methods to handle such issues later
  - Assuming simple forms for  $q_{\phi}(\mathbf{Z})$  also helps (we can use random variable transformation methods to transform the simple form to more expressive ones will see later)

## A Simple Illustration for VI

Assume a simple likelihood model

$$p(\mathbf{D}|\mathbf{z}) = \prod_{n=1}^{N} \mathcal{N}(\mathbf{x}_{n}|\mathbf{z}, \mathbf{\Sigma}) \propto \mathcal{N}(\overline{\mathbf{x}}|\mathbf{z}, \frac{1}{N}\mathbf{\Sigma})$$

- lacktriangle Suppose we want to estimate the posterior of the mean z
- Assuming a Gaussian prior on z and assuming  $\Sigma$  is known, the posterior can be computed analytically (because of conjugacy)
- Let's still try VI to see how well it does
- Figure shows VI result for three Gaussian forms for q(z)
  - lacktriangle Low-rank:  $q(z) = \mathcal{N}(z|\mu_z, \Sigma_z)$  where  $\Sigma_z = LL^{\mathsf{T}}$
  - Full-rank:  $q(z) = \mathcal{N}(z|\mu_z, \Sigma_z)$  with no constraint on  $\Sigma_z$
  - lacktriangle Mean-field:  $q(z)=q(z_1)q(z_2)=\mathcal{N}ig(z_1ig|\mu_{z_1},\sigma_{z_1}^2ig)\,\mathcal{N}ig(z_2ig|\mu_{z_2},\sigma_{z_2}^2ig)$



#### Detour

Transformed random variable

A one-to-one transformation function

- Consider a scalar transformation of a scalar random variable u as  $\theta = T(u)$
- lacktriangle Probability distributions of random variables u and heta are related as

$$p(\theta) = p(u) \left| \frac{du}{d\theta} \right|$$

■ Similarly, for multivariate random variables (of same size) related as  $\theta = T(u)$ 

$$p(m{ heta}) = p(m{u}) \left| \det \left( \frac{\partial m{u}}{\partial m{ heta}} \right) \right|^{\text{Absolute value of the determinant of the Jacobian (note that } m{u} = T^{-1}(m{ heta})}$$

• We can use such transformations for VI by using a simple distribution for  $q(\mathbf{Z})$  and then transform it to a more expressive/appropriate distribution (more on this later)

#### Mean-Field VI

- A special way to maximize the ELBO is via the mean-field approximation
- Doesn't require specifying the form of  $q(\mathbf{Z}|\phi)$  or computing ELBO's gradients
- lacktriangle The idea: Assumes unknowns  $oldsymbol{Z}$  can be partitioned into  $oldsymbol{M}$  groups  $oldsymbol{Z_1, Z_2, \ldots, Z_M}$ , s.t.,

As a shorthand, often written as 
$$q = \prod_{i=1}^{M} q_i$$
 where  $q_i = q(Z_i|\phi_i)$   $q(Z|\phi) = \prod_{i=1}^{M} q(Z_i|\phi_i)$  For models with local conjugacy, it becomes super easy!

- lacktriangle Learning the optimal  $q(\pmb{Z}|\pmb{\phi})$  reduces to learning the optimal  $q_1,q_2,\ldots,q_M$
- Can select groupsbased on model's structure, e.g., in Bayesian neural net for regression

$$p(\pmb{w}|\pmb{X},\pmb{y},\lambda,eta)pprox q(\pmb{w}|\pmb{\phi})=\prod_{\ell=1}^Lq(\pmb{w}^{(\ell)}|\pmb{\phi}_\ell)$$
 Assuming a network with  $L$  layers, mean-field across layers

- Mean-field has limitations. Factorized form ignores the correlations among unknowns
  - Variants such as "structured mean-field" exist where some correlations can be modeled

# Deriving Mean-Field VI Updates

Writing this is the same as  $\operatorname{argmax}_{\phi} \mathcal{L}(\phi, \Theta)$ . We are just writing optimization w.r.t. q directly

- With  $q = \prod_{i=1}^{M} q_i$ , what's the optimal  $q_i$  when we do  $\underset{q}{\operatorname{argmax}} \mathcal{L}(q)$ ?
- Note that under this mean-field assumption, the ELBO simplifies to

$$\mathcal{L}(q) = \int q(\mathbf{Z}) \log \left[ \frac{p(\mathbf{D}, \mathbf{Z}|\Theta)}{q(\mathbf{Z})} \right] d\mathbf{Z} = \int \prod_{i} q_{i} \left[ \log p(\mathbf{D}, \mathbf{Z}|\Theta) - \sum_{i} \log q_{i} \right] d\mathbf{Z}$$

■ Suppose we wish to find the optimal  $q_i$  given all other  $q_i$ 's  $(i \neq j)$  as fixed, then

$$\mathcal{L}(q) = \int q_{j} \left[ \int \log p(\mathbf{D}, \mathbf{Z}|\Theta) \prod_{i \neq j} q_{i} dZ_{i} \right] dZ_{j} - \int q_{j} \log q_{j} dZ_{j} + \text{const w.r.t. } q_{j}$$

$$= \int q_{j} \log \hat{p}(\mathbf{D}, Z_{j}|\Theta) dZ_{j} - \int q_{j} \log q_{j} Z_{j}$$

$$= -\text{KL}(q_{j}||\hat{p}) \log \hat{p}(\mathbf{D}, Z_{j}|\Theta) = \mathbb{E}_{i \neq j} [\log p(\mathbf{D}, \mathbf{Z}|\Theta)] + \text{const}$$

$$q_{j}^{*} = \frac{\exp(\mathbb{E}_{i \neq j} [\log p(\mathbf{D}, \mathbf{Z}|\Theta)])}{\int \exp(\mathbb{E}_{i \neq j} [\log p(\mathbf{D}, \mathbf{Z}|\Theta)] dZ_{j}}$$

■ Thus  $q_j^* = \operatorname{argmax}_{q_j} \mathcal{L}(q) = \operatorname{argmin}_{q_i} \operatorname{KL}(q_j || \hat{p}) = \hat{p}(\mathcal{D}, Z_j | \Theta)$ 



## Deriving Mean-Field VI Updates

lacktriangle So we saw that the optimal  $q_i$  when doing mean-field VI is

$$q_j^*(\mathbf{Z}_j) = \frac{\exp(\mathbb{E}_{i \neq j}[\log p(\mathbf{D}, \mathbf{Z}|\Theta)])}{\int \exp(\mathbb{E}_{i \neq j}[\log p(\mathbf{D}, \mathbf{Z}|\Theta)] d\mathbf{Z}_j}$$

- Note: Can often just compute the numerator and recognize denominator by inspection
- Important: For locally conj models,  $q_j^*(\mathbf{Z}_j)$  will have the same form as prior  $p(\mathbf{Z}_j|\Theta)$ 
  - Only the distribution parameters will be different
- Important: For estimating  $q_j$  the required expectation depends on other  $\{q_i\}_{i\neq j}$ 
  - Thus we use an alternating update scheme for these
- Guaranteed to converge (to a local optima)
  - We are basically solving a sequence of concave maximization problems
  - Reason:  $\mathcal{L}(q) = \int q_j \log \hat{p}(\mathbf{D}, Z_j | \Theta) Z_j \int q_j \log q_j Z_j$  is concave in  $q_j$



## The Mean-Field VI Algorithm

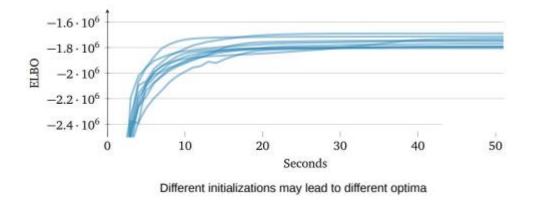
- Also known as Co-ordinate Ascent Variational Inference (CAVI) Algorithm
- Input: Model in form of priors and likelihood, or joint  $p(\mathcal{D}, Z|\Theta)$ , Data  $\mathcal{D}$
- lacksquare Output: A variational distribution  $q(\pmb{Z}) = \prod_{j=1}^M q_j(\pmb{Z}_j)$
- Initialize: Variational distributions  $q_j(\mathbf{Z}_j)$ , j=1,2,...M
- While the ELBO has not converged
  - For each j = 1,2, ...M, set

$$q_j(\mathbf{Z}_j) \propto \exp(\mathbb{E}_{i \neq j}[\log p(\mathbf{D}, \mathbf{Z}|\mathbf{\Theta})])$$

- lacktriangle Compute ELBO  $\mathcal{L}(q) = \mathbb{E}_q[\log p(\mathcal{D}, \mathbf{Z}|\Theta)] \mathbb{E}_q[\log q(\mathbf{Z})]$
- ullet NOTE: We can also use mean-field assumption for q(Z) and optimize the ELBO using gradient based methods if we don't have local conjugacy

### VI and Convergence

- VI is guaranteed to converge to a local optima (just like EM)
- Therefore proper initialization is important (just like EM)
  - Can sometimes run multiple times with different initializations and choose the best run

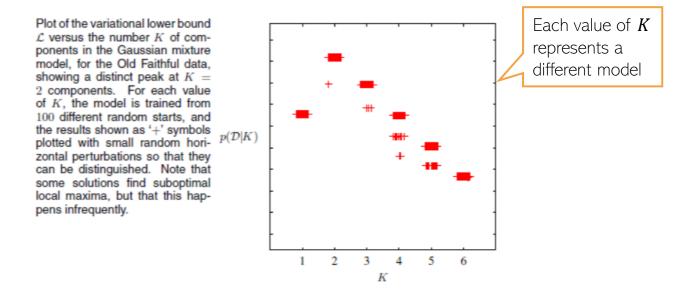


- ELBO increases monotonically with iterations
  - Can thus monitor the ELBO to assess convergence



#### **ELBO** for Model Selection

- Recall that ELBO is a <u>lower bound</u> on log of model evidence  $\log p(X|m)$
- lacktriangle Can compute ELBO for each model m and choose the one with largest ELBO



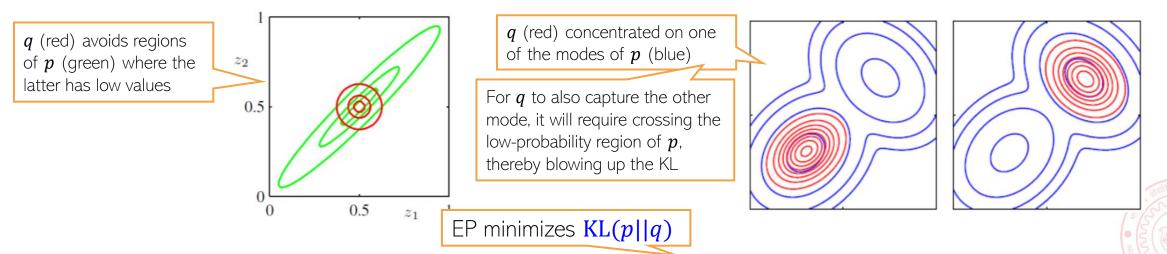
Some criticism since we are using a lower-bound but often works well in practice

## VI might <u>under-estimate</u> posterior's variance

■ Recall that VI approximates a posterior p by finding q that minimizes  $\mathrm{KL}(q||p)$ 

$$KL(q||p) = -\int q(\mathbf{Z})\log\left\{\frac{p(\mathbf{Z}|\mathcal{D})}{q(\mathbf{Z})}\right\}d\mathbf{Z}$$

- $lackbox{\bf q}({m Z})$  will be small where  $p({m Z}|{m \mathcal D})$  is small otherwise KL will blow up
- Thus  $q(\mathbf{Z})$  avoids low-probability regions of the true posterior



■ Some methods, e.g., Expectation Propagation (EP), can avoid this behavior

#### Variational EM

- If the parameters  $\Theta$  are also unknown then we can use variational EM (VEM)
- VEM is the same as EM except the E step uses VI to approximate the CP of Z
- VEM alternates between the following two steps
  - lacktriangle Maximize the ELBO w.r.t.  $oldsymbol{\phi}$  (gives the variational approximation  $q(oldsymbol{Z})$  of CP of  $oldsymbol{Z}$ )

$$\phi^{(t)} = \operatorname{argmax}_{\phi} \mathbb{E}_{q_{\phi}(\mathbf{Z})} \left[ \log p(\mathbf{D}, \mathbf{Z} | \Theta^{(t-1)}) - \log q_{\phi}(\mathbf{Z}) \right]$$

■ Maximize the ELBO w.r.t.  $\Theta$  (gives us point estimate of  $\Theta$ )

$$\begin{split} \Theta^{(t)} &= \operatorname{argmax}_{\Theta} \mathbb{E}_{q_{\phi^{(t)}}(\boldsymbol{Z})} \left[ \log p(\boldsymbol{\mathcal{D}}, \boldsymbol{Z} | \boldsymbol{\Theta}) - \log q_{\phi^{(t)}}(\boldsymbol{Z}) \right] \\ &= \operatorname{argmax}_{\Theta} \mathbb{E}_{q_{\phi^{(t)}}(\boldsymbol{Z})} \left[ \log p(\boldsymbol{\mathcal{D}}, \boldsymbol{Z} | \boldsymbol{\Theta}) \right] & \overset{\text{This looks very similar to the expected CLL with the CP replaced by its variational approximation} \end{split}$$

■ Note: If we want posterior for  $\Theta$  as well, treat it similar to Z and apply variational approximation (instead of using VEM) if the posterior isn't tractable

## Extra Slides - Mean-Field VI: A Simple Example

- Consider data  $\mathbf{X} = \{x_1, x_2, ..., x_N\}$  from a one-dim Gaussian  $\mathcal{N}(\mu, \tau^{-1})$
- lacktriangle Assume the following normal-gamma prior on  $\mu$  and au

$$p(\mu|\tau) = \mathcal{N}(\mu|\mu_0, (\lambda_0\tau)^{-1})$$
  $p(\tau) = \mathsf{Gamma}(\tau|a_0, b_0)$ 

- Posterior is also normal-gamma due to the jointly conjugate prior
- Let's anyway verify this by trying mean-field VI for this model
- With mean-field assumption on the variational posterior  $q(\mu,\tau)=q_{\mu}(\mu)q_{\tau}(\tau)$

$$\log q_{\mu}^{*}(\mu) = \mathbb{E}_{q_{\tau}}[\log p(\mathbf{X}, \mu, \tau)] + \text{const}$$
$$\log q_{\tau}^{*}(\tau) = \mathbb{E}_{q_{\mu}}[\log p(\mathbf{X}, \mu, \tau)] + \text{const}$$

■ In this example, the log-joint  $\log p(\mathbf{X}, \mu, \tau) = \log p(\mathbf{X}|\mu, \tau) + \log p(\mu|\tau) + \log p(\tau)$ . Thus

$$\log q_{\mu}^*(\mu) = \mathbb{E}_{q_{\tau}}[\log p(\mathbf{X}|\mu,\tau) + \log p(\mu|\tau)] + \text{const} \qquad \text{(only keeping terms that involve } \mu\text{)}$$

$$\log q_{\tau}^*(\tau) = \mathbb{E}_{q_{\mu}}[\log p(\mathbf{X}|\mu,\tau) + \log p(\mu|\tau) + \log p(\tau)] + \text{const}$$

# Extra Slides - Mean-Field VI: A Simple Example

■ Substituting  $p(\mathbf{X}|\mu,\tau) = \prod_{n=1}^{N} p(x_n|\mu,\tau)$  and  $p(\mu|\tau)$ , we get

$$\log q_{\mu}^{*}(\mu) = \mathbb{E}_{q_{\tau}}[\log p(\mathbf{X}|\mu,\tau) + \log p(\mu|\tau)] + \text{const}$$

$$= -\frac{\mathbb{E}_{q_{\tau}}[\tau]}{2} \left\{ \sum_{n=1}^{N} (x_{n} - \mu)^{2} + \lambda_{0}(\mu - \mu_{0})^{2} \right\} + \text{const}$$

• (Verify) The above is log of a Gaussian. This  $q_{\mu}^* = \mathcal{N}(\mu | \mu_N, \lambda_N)$  with

$$\mu_{N}=rac{\lambda_{0}\mu_{0}+Nar{x}}{\lambda_{0}+N}$$
 and  $\lambda_{N}=(\lambda_{0}+N)\mathbb{E}_{q_{ au}}[ au]$  This update depends on  $q_{ au}$ 

■ Proceeding in a similar way (verify), we can show that  $q_{\tau}^* = \operatorname{Gamma}(\tau | a_N, b_N)$ 

$$a_N=a_0+rac{N+1}{2}$$
 and  $b_N=b_0+rac{1}{2}\mathbb{E}_{q_\mu}\left[\sum_{n=1}^N(x_n-\mu)^2+\lambda_0(\mu-\mu_0)^2
ight]$  This update depends on  $q_\mu$ 

■ Note: Updates of  $q_{\mu}^*$  and  $q_{\tau}^*$  depend on each other (hence alternating updates needed)