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BSCS-12C

1. Code Documentation

- Step-by-step implementation.
- Discussion of results
- challenges faced
-

2. Simulation of real-world distributed application

BSS Implementation

1. Code Analysis

The code defines two primary classes: Process and CausalOrderingSystem.

- **Process Class:**

- Represents a single process in the distributed system.
- Maintains a vector clock, event history, and a queue of delayed messages.
- Implements send_message and receive_message methods to simulate message passing.
- Uses helper methods _is_deliverable, _update_vector_clock, and _check_delayed_messages to handle causal ordering.

- **CausalOrderingSystem Class:**

- Manages a collection of Process objects.
- Provides a send_message method to simulate message sending between processes.
- Implements a _deliver_message method to deliver messages to processes.
- Includes plot_process_timelines for visualizing the causal ordering.

- Implements `run_simulation` which simulates several different scenarios.

2. Step-by-Step Documentation

1. Process Class:

- **`__init__(self, process_id, num_processes):`**
 - Initializes the process with its ID, the total number of processes, a vector clock (initialized to zeros), event history lists, and a delayed messages queue.
- **`send_message(self, target_id, content):`**
 - Increments the process's own vector clock entry.
 - Records the send event and current vector clock.
 - Returns a tuple containing the target ID, message content, and a copy of the vector clock.
- **`receive_message(self, sender_id, content, sender_vector):`**
 - Calls `_is_deliverable` to check if the message can be delivered.
 - If deliverable:
 - Updates the vector clock using `_update_vector_clock`.
 - Records the receive event and current vector clock.
 - Calls `_check_delayed_messages` to check for deliverable delayed messages.
 - Returns True.
 - Else:
 - Adds the message to `delayed_messages`.
 - Records the delay event and current vector clock.
 - Returns False.
- **`_is_deliverable(self, sender_vector):`**
 - Determines if the message is causally ready for delivery based on the BSS algorithm's rules.
 - Returns True if deliverable, False otherwise.
- **`_update_vector_clock(self, sender_vector):`**

- Updates the process's vector clock by taking the element-wise maximum of its current clock and the sender's clock.
- **_check_delayed_messages(self):**
 - Iterates through delayed_messages and delivers any messages that are now deliverable.

2. CausalOrderingSystem Class:

- **__init__(self, num_processes):**
 - Creates a list of Process objects.
 - Creates a system event log.
 - Creates a list of colors for plotting.
- **send_message(self, sender_id, receiver_id, content, delay=False):**
 - Retrieves the sender Process object.
 - Calls the sender's send_message method.
 - Adds the send event to the system event log.
 - Calls _deliver_message to deliver the message (or adds a delayed message event).
- **_deliver_message(self, message):**
 - Retrieves the receiver Process object.
 - Calls the receiver's receive_message method.
 - Adds a receive or delay event to the system event log.
 - Returns the result of the receive message function.
- **plot_process_timelines(self):**
 - Generates a plot visualizing the causal ordering of events using Matplotlib.
 - Displays the process timelines, events, and vector clock values.
- **run_simulation(self, scenario='basic'):**
 - Simulates different scenarios (basic causal chain, out-of-order delivery, causal violation).
 - Prints the event log and final vector clock states.

3. Discussion of Results and Challenges Faced

- **Results:**

- The code successfully implements the BSS algorithm, ensuring causal message delivery.
- The `plot_process_timelines` method provides a clear visualization of the causal ordering.
- The different test cases show the correct behavior of the implemented BSS algorithm.

- **Challenges Faced:**

- **Complexity of Vector Clocks:** Understanding and implementing vector clock logic can be challenging, especially for larger systems.
- **Delayed Message Handling:** Managing delayed messages and correctly checking for deliverability requires careful attention to detail.
- **Visualization:** Creating a clear visualization of causal ordering can be complex, especially with many processes and events.
- **Simulation Design:** Designing realistic scenarios that effectively demonstrate causal ordering can be tricky.
- **Performance:** For very large systems, the overhead of vector clocks and delayed message checks could become significant.

- **Improvements:**

- **Error Handling:** Add more robust error handling, such as input validation and exception handling.
- **Optimization:** For very large systems, consider optimizing the `_check_delayed_messages` method.
- **Testing:** Implement more comprehensive test cases to cover various scenarios and edge cases.
- **User Interface:** Add a command-line interface or GUI to allow users to interact with the system and define their own scenarios.
- **Logging:** Implement more detailed logging to track system behavior and debug issues.

- **Abstraction:** The simulation relies on manual delivery of delayed messages, a more robust system would automate this based on network simulations.

Outputs-BSS:



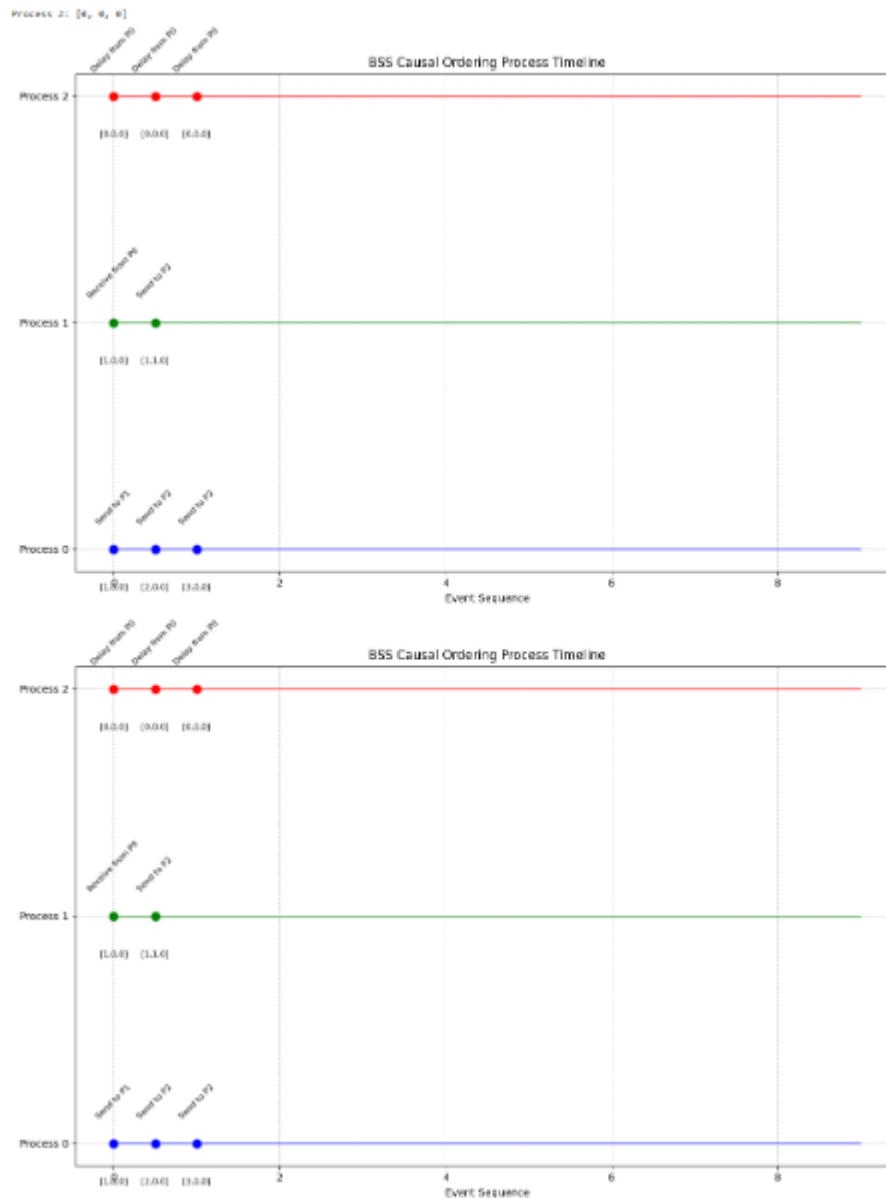
Running out-of-order delivery scenario...

Event Log:

```
0: P0 -> P1: Message A
1: P1 received: Message A
2: P1 -> P2: Message B
3: P2 delayed: Message B
4: P0 -> P2: Message C
5: (Delayed) P0 -> P2: Message C
6: P0 -> P2: Message D
7: P2 delayed: Message D
8: P2 delayed: Message C
```

Final Vector Clocks:

```
Process 0: [3, 0, 0]
Process 1: [1, 1, 0]
Process 2: [0, 0, 0]
```



Schwarz & Mattern (SES) Implementation

- **ProcessSES Class:**
 - **__init__(self, process_id, num_processes):**
 - Initializes the process with its ID, the total number of processes, a sequence number (starting at 0), a list to track the last received

sequence number from each process, an event log, and a list of delayed messages.

- **send_message(self, target_id, content):**
 - Increments the process's sequence number.
 - Records the send event in the event log.
 - Returns a tuple containing the target ID, message content, the sequence number, and the original senders ID.
- **receive_message(self, sender_id, content, sequence_number, original_sender):**
 - Checks if the received sequence number is the next expected sequence number from the original sender.
 - If it is, updates the received sequence number, records the receive event, calls `_check_delayed_messages`, and returns `True`.
 - If not, stores the message in `delayed_messages`, records the delay event, and returns `False`.
- **_check_delayed_messages(self):**
 - Iterates through `delayed_messages` and delivers any messages that are now deliverable.
 - Continues until no more delayed messages can be delivered.
- **CausalOrderingSystemSES Class:**
 - **__init__(self, num_processes):**
 - Creates a list of `ProcessSES` objects, a system event log, and a list of colors for plotting.
 - **send_message(self, sender_id, receiver_id, content, delay=False):**
 - Retrieves the sender process, calls its `send_message` method, and adds the send event to the system event log.
 - If `delay` is `False`, calls `_deliver_message`; otherwise, adds a delayed message event and returns the message.
 - **_deliver_message(self, message):**
 - Retrieves the receiver process, calls its `receive_message` method, and adds a receive or delay event to the system event log.

- returns the result of the receive message function.
- **plot_process_timelines(self):**
 - Generates a plot visualizing the causal ordering of events.
- **run_simulation(self, scenario):**
 - Simulates different scenarios (basic, out-of-order, potential violation).
 - prints the event log, and the final received sequence number arrays.

Results and Challenges Faced

- **SES Implementation:**
 - **Results:**
 - The SES implementation successfully ensures potential causal ordering.
 - It is more efficient than the BSS and Matrix Clock implementations due to its use of simple sequence number comparisons.
 - Test cases show that messages are delivered in a mostly causally correct manner.
 - **Challenges:**
 - SES only ensures potential causality, which can lead to unnecessary delays.
 - It does not provide a complete view of causal relationships.
 - Debugging potential causal violations can be difficult.

Output SS – SES

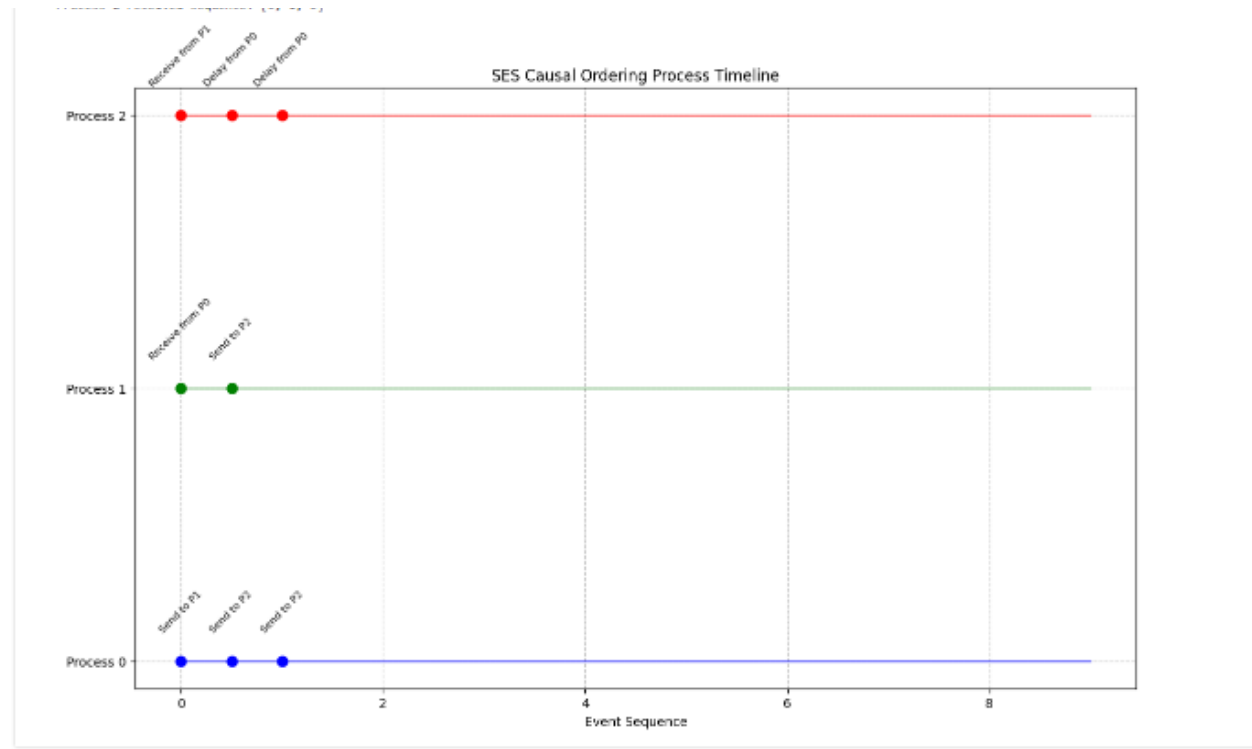
Event Log:

- 0: P0 -> P1: Message A
- 1: P1 received: Message A
- 2: P1 -> P2: Message B
- 3: P2 received: Message B
- 4: P0 -> P2: Message C
- 5: (Delayed) P0 -> P2: Message C
- 6: P0 -> P2: Message D
- 7: P2 delayed: Message D
- 8: P2 delayed: Message C

Process 0 received sequence: [0, 0, 0]

Process 1 received sequence: [1, 0, 0]

Process 2 received sequence: [0, 1, 0]



Matrix Clock Implementation

- **ProcessMatrix Class:**

- **__init__(self, process_id, num_processes):**
 - Initializes the process with its ID, the total number of processes, a matrix clock (initialized to zeros), an event log, and a list of delayed messages.
- **send_message(self, target_id, content):**
 - Increments the process's own entry in the matrix clock.
 - Records the send event.
 - Returns a tuple containing the target ID, message content, and a copy of the matrix clock.
- **receive_message(self, sender_id, content, sender_matrix):**
 - Calls `_is_deliverable` to check if the message can be delivered.
 - If deliverable, updates the matrix clock, records the receive event, calls `_check_delayed_messages`, and returns True.
 - If not, stores the message in `delayed_messages`, records the delay event, and returns False.
- **_is_deliverable(self, sender_matrix):**
 - Checks if the senders event on the receiving processes column is one more than the receivers current event on the receivers column.
 - Checks that the senders matrix is less than or equal to the receivers matrix, insuring no causal violations.
 - Returns True if deliverable, False otherwise.
- **_update_matrix_clock(self, sender_matrix):**
 - Updates the matrix clock by taking the element-wise maximum and then updating the current processes row to the senders row.
- **_check_delayed_messages(self):**
 - Iterates through `delayed_messages` and delivers any messages that are now deliverable.

- Continues until no more delayed messages can be delivered.
- **CausalOrderingSystemMatrix Class:**
 - **__init__(self, num_processes):**
 - Creates a list of ProcessMatrix objects, a system event log, and a list of colors for plotting.
 - **send_message(self, sender_id, receiver_id, content, delay=False):**
 - Retrieves the sender process, calls its send_message method, and adds the send event to the system event log.
 - If delay is False, calls _deliver_message; otherwise, adds a delayed message event and returns the message.
 - **_deliver_message(self, message):**
 - Retrieves the receiver process, calls its receive_message method, and adds a receive or delay event to the system event log.
 - returns the result of the receive message function.
 - **plot_process_timelines(self):**
 - Generates a plot visualizing the causal ordering of events.
 - **run_simulation(self, scenario):**
 - Simulates different scenarios (basic, out-of-order, causal violation).
 - prints the event log, and the final matrix clock states.

Results and Challenges Faced

Results:

- The Matrix Clock implementation provides a complete view of causal relationships.
- It ensures strict causal ordering, guaranteeing that messages are delivered in the correct order.
- Test cases show that messages are always delivered in the correct causal order.

Challenges:

- Matrix clocks have high overhead in terms of storage and computation, especially for large systems.
- The matrix operations can be complex and computationally expensive.
- Visualizing matrix clocks can be difficult, the visualization provided only shows the event order, not the matrix data itself.

Output SS -Matrix Clock Algo



Event Log:

```
0: P0 -> P1: Message A
1: P1 delayed: Message A
2: P1 -> P2: Message B
3: P2 delayed: Message B
4: P0 -> P2: Message C
5: (Delayed) P0 -> P2: Message C
6: P0 -> P2: Message D
7: P2 delayed: Message D
8: P2 delayed: Message C
```

Process 0 Matrix Clock:

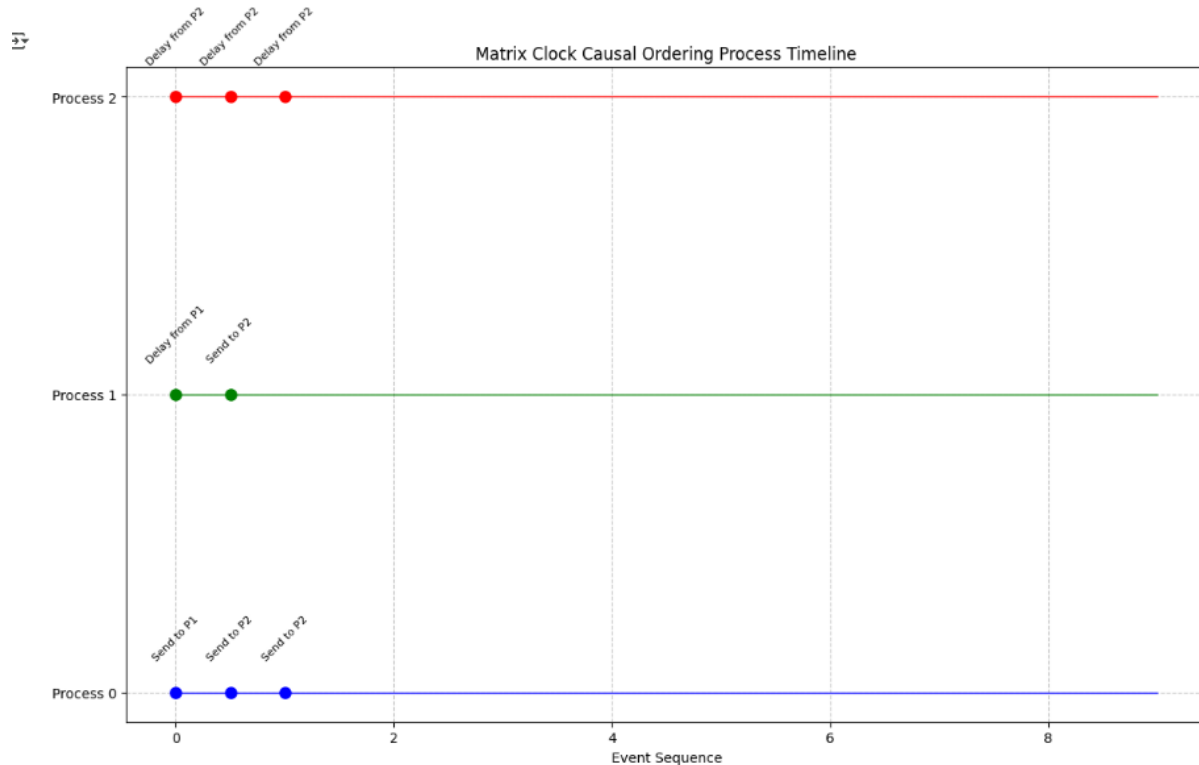
```
[[3 0 0]
 [0 0 0]
 [0 0 0]]
```

Process 1 Matrix Clock:

```
[[0 0 0]
 [0 1 0]
 [0 0 0]]
```

Process 2 Matrix Clock:

```
[[0 0 0]
 [0 0 0]]
```



Simulation of real-world distributed application

1. Problem Importance: Concurrent Editing and Causal Consistency

- **The Challenge of Concurrent Editing:**

- *In real-world collaborative editing scenarios (like Google Docs), multiple users can edit the same document simultaneously.*
- *This concurrency can lead to conflicts if changes are not applied in a consistent order across all users' views.*
- *Without proper synchronization, users might see different versions of the document, leading to confusion and data loss.*

- **The Importance of Causal Consistency:**

- *Causal consistency ensures that if one operation (e.g., inserting text) happens before another operation (e.g., deleting text), then all users will see those operations applied in the same order.*

- *This is crucial for maintaining document integrity and preventing conflicts.*
- *It ensures that users see a logically consistent view of the document, even though changes are being made concurrently.*

2. How We Solved the Problem: Matrix Clocks and Causal Ordering

- **Matrix Clocks:**

- *We used Matrix Clocks to track the causal dependencies between operations.*
- *Each process (user) maintains a Matrix Clock, which is a matrix of timestamps.*
- *When a process performs an operation, it increments its own entry in the Matrix Clock and propagates the updated clock along with the operation.*
- *When a process receives an operation, it updates its Matrix Clock by taking the element-wise maximum of its current clock and the sender's clock.*

- **Causal Delivery:**

- *Before applying an operation, a process checks if it is causally ready.*
- *This is done by comparing the sender's Matrix Clock with the receiver's Matrix Clock.*
- *An operation is causally ready if:*
 - *The sender's event on the receiving processes column is one more than the receiver's current event on the receiver's column.*
 - *The sender's matrix is less than or equal to the receiver's matrix.*
- *If an operation is not causally ready, it is delayed until its dependencies are met.*

- **Operation Application:**

- *Once an operation is causally ready, it is applied to the document.*
- *We support two basic operations: INSERT and DELETE.*
- *The `_apply_operation` method updates the document string accordingly.*

- **Simulation and Visualization:**

- We created a simulation to demonstrate concurrent editing and causal ordering.
- We visualized the sequence of operations and the final document states to show how Matrix Clocks ensure consistency.

3. Step-by-Step Documentation of the Implementation

- **CollaborativeEditProcess Class:**

- **`__init__(self, process_id, num_processes, document="")`:**
 - Initializes the process with its ID, the number of processes, the document string, the Matrix Clock, an event log, and a list of delayed operations.
- **`perform_operation(self, operation, position, content)`:**
 - Increments the process's Matrix Clock.
 - Applies the operation to the document.
 - Returns the operation data (sender ID, operation, position, content, Matrix Clock).
- **`receive_operation(self, sender_id, operation, position, content, sender_matrix)`:**
 - Checks if the operation is causally ready.
 - If ready, applies the operation, updates the Matrix Clock, and checks for delayed operations.
 - If not ready, delays the operation.
- **`_apply_operation(self, operation, position, content)`:**
 - Applies the INSERT or DELETE operation to the document string.
- **`_is_deliverable(self, sender_matrix)`:**
 - Checks if the operation is causally ready based on the Matrix Clock.
- **`_update_matrix_clock(self, sender_matrix)`:**
 - Updates the Matrix Clock.
- **`_check_delayed_operations(self)`:**
 - Checks for and applies delayed operations.

- **CollaborativeEditorSystem Class:**
 - **`__init__(self, num_processes, initial_document=""):`**
 - *Initializes the system with a list of processes, an event log, and colors for visualization.*
 - **`perform_and_send_operation(self, sender_id, operation, position, content, delay=False):`**
 - *Simulates a user performing an operation and sending it to other users.*
 - **`_deliver_operation(self, receiver_id, operation_data):`**
 - *Delivers an operation to a receiver process.*
 - **`plot_process_timelines(self):`**
 - *Visualizes the sequence of operations.*
 - **`run_simulation(self):`**
 - *Runs a simulation of concurrent editing.*

Final Document States:
Process 0: 'Helloinitial'
Process 1: 'Initi, worldal'
Process 2: 'Initial!'

Event Log:

0: P0 -> P1: INSERT at 0 'Hello'
1: P1 delayed operation: INSERT at 0 'Hello'
2: P0 -> P2: INSERT at 0 'Hello'
3: P2 delayed operation: INSERT at 0 'Hello'
4: P1 -> P0: INSERT at 5 ', world'
5: P0 delayed operation: INSERT at 5 ', world'
6: P1 -> P2: INSERT at 5 ', world'
7: P2 delayed operation: INSERT at 5 ', world'
8: P0 -> P1: DELETE at 5 'o'
9: (Delayed) P0 -> P1: DELETE at 5 'o'
10: P2 -> P0: INSERT at 11 '!'!
11: P0 delayed operation: INSERT at 11 '!'!
12: P2 -> P1: INSERT at 11 '!'!
13: P1 delayed operation: INSERT at 11 '!'!
14: P0 delayed operation: DELETE at 5 'o'

Operation
Operation

By using Matrix Clocks and causal delivery, we ensure that all users see a consistent view of the document, even when changes are made concurrently. This approach effectively addresses the challenges of collaborative editing and maintains document integrity