

Summary

Embedded Software Engineer specializing in robotics and real-time embedded systems, with hands-on experience in drones, industrial manipulators, and neuromorphic AI research. Graduated with an MSc in Computer and Embedded Systems Engineering from TU Delft, Proficient in C, C++, Rust, and Python for microcontroller-based embedded systems, with strong experience in system integration and hardware-software interfacing (SPI, I<sup>2</sup>C, UART) for reliable real-time control. Collaborate effectively in cross-functional environments using Git and Linux workflows to ensure robust, maintainable, and well-tested code delivery.

Education

<b>MSc in Computer and Embedded Systems Engineering</b> <i>Delft University of Technology</i> CGPA (2-year program): 7.5/10	Sept 2023 – June 2025 Delft, Netherlands
<b>B.E. in Electronics and Communication Engineering</b> <i>Sir M Visvesvaraya Institute of Technology</i> CGPA (4-year program): 9.3/10	Aug 2018 – Aug 2022 Bangalore, India

Skills and Certifications

<b>Programming Languages</b>	C, C++, Python, Rust
<b>Microcontrollers</b>	ATmega328P, ESP32, nRF51822 (ARM Cortex-M0)
<b>Communication Protocols</b>	SPI, I <sup>2</sup> C, UART
<b>Operating Systems</b>	Linux
<b>Tools &amp; Frameworks</b>	Git and Docker

**Certifications:** Industrial IoT on Google Cloud — Google; Programming for Everybody (Python) — University of Michigan

Experience

<b>IMEC</b>	Eindhoven, Netherlands
<b>Graduate Research Student</b>	Sep 2024 – July 2025
<ul style="list-style-type: none"><li>Analyzed state-of-the-art mapping tools (Timeloop, ZigZag) and identified their limitations in modeling event-driven accelerator architectures.</li><li>Designed and developed AeDAM, a framework for design space and mapping exploration of AI workloads on event-driven architectures.</li><li>Built analytical models to estimate energy, latency, and area for dense neural networks, and validated them through a case study on the SENECA neuromorphic architecture.</li><li>Achieved up to 2.5× faster exploration and up to 52% latency improvement over ZigZag, establishing AeDAM as an effective framework for event-driven accelerator optimization.</li></ul>	
<b>UVASKA</b>	Bangalore, India
<b>Robotics Software Engineer</b>	Aug 2022 – Aug 2023
<ul style="list-style-type: none"><li>Led the development of the software stack for a custom 7-axis and 6-axis gantry-style articulated robot, including motion control, hardware interface integration, and system testing.</li><li>Implemented kinematics and motion planning algorithms in C++ and Python, improving control precision.</li><li>Evaluated and integrated modular software packages for system-level control and testing.</li><li>Established structured version control workflows using Git, and collaborated within a 4-member team to iteratively test and debug software modules for a 6-axis industrial manipulator.</li></ul>	
<b>Epson</b>	Bangalore, India
<b>Robotics Software Intern</b>	Mar 2021 – Sept 2021
<ul style="list-style-type: none"><li>Developed a Python-based interface on Raspberry Pi to control EPSON SCARA robots, bypassing proprietary SPEL-based software to simplify programming for new developers.</li><li>Tested and validated the interface on physical robot hardware, improving accessibility and speeding up programming workflows within the R&amp;D team.</li><li>Assisted in a client project to build an automation system using the robot’s vision module to detect specific shapes and perform sorting operations.</li></ul>	

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## Projects

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### Embedded Quadcopter Control System

- Implemented a flight-control stack in Rust featuring a safety-first FSM, PID loops (roll/pitch/yaw), and Mahony sensor fusion at 200 Hz.
- Designed a fault-tolerant UART protocol with checksums and recovery logic; integrated joystick input (girs) and GUI telemetry (egui).
- Validated closed-loop stability and communication reliability through hardware-in-the-loop testing on a Cortex-M0 platform.

### NES Emulator

- Built a cycle-accurate 6502 CPU emulator with memory-mapped I/O, interrupts, and cartridge mappers (NROM, MMC1).
- Integrated the PPU using the tudelft-nes-ppu crate and verified correctness against automated test ROMs.
- Ensured reliable execution of classic games such as Super Mario Bros and The Legend of Zelda through testing and system-level debugging.

### TrackIn: Real-Time Indoor Tracking and Activity Recognition

- Built a smartphone-based tracking system integrating Bayesian localization, particle filtering, and an on-device TensorFlow Lite MLP classifier for real-time activity recognition.
- Processed multi-sensor data (Wi-Fi RSSI, accelerometer, gyroscope, magnetometer) using a 5th-order Butterworth filter and custom motion model, achieving 98% activity-classification accuracy.
- Deployed a compact Tiny-AI pipeline on Android with sub-second inference latency and validated localization consistency across 14 test cells.

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## Achievements

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### Best Idea Award

2018

- Led the design of a smart agriculture automation system, APEX, which won 1st prize for its innovative approach to optimizing farming resources, securing €1,000 in funding to develop the solution.

### Gov-Tec-Thon

2020

- Achieved 15th place out of 100 teams in a national-level competition, demonstrating the project's scalability and potential societal impact.

### Eyantra Competition

2020

- Advanced to the second round in a prestigious robotics competition by IIT Bombay, ranking in the top 250 out of 500 international teams.

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## Publication

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### Artificial intelligence enabled plant emotion xpresser in the development hydroponics system

2021

Materials Today: Proceedings

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## Extracurricular activities

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### IEEE

Bangalore, India

### Student Branch Chair

Aug 2021 – Aug 2022

- Spearheaded the hosting and management of online events on diverse topics, including Entrepreneurship, Mobile App Development, and the integration of robotics in the Food Industry.
- Orchestrated the IEEE Day celebration, significantly enhancing club engagement and membership, with a successful addition of 10 new members to the IEEE club.

### ROS Tutorials Channel

Online

### Content Creator

2021 – Present

- Created and maintain a YouTube channel with tutorials on the Robot Operating System (ROS), demonstrating the hardware implementation and communication frameworks.
- Produced practical, project-based videos to support learners and showcase applied knowledge in robotics development.

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## Languages & Interests

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**Languages:** English, Hindi, Telugu

**Interests:** Reading non-fiction books, writing blogs, and playing badminton