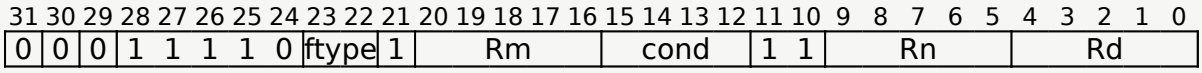
FCSEL

Floating-point Conditional Select (scalar). This instruction allows the SIMD&FP destination register to take the value from either one or the other of two SIMD&FP source registers. If the condition passes, the first SIMD&FP source register value is taken, otherwise the second SIMD&FP source register value is taken.

Depending on the settings in the *CPACR_EL1*, *CPTR_EL2*, and *CPTR_EL3* registers, and the current Security state and Exception level, an attempt to execute the instruction might be trapped.



Half-precision (ftype == 11)
(FEAT_FP16)

```
FCSEL <Hd>, <Hn>, <Hm>, <cond>
```

Single-precision (ftype == 00)

```
FCSEL <Sd>, <Sn>, <Sm>, <cond>
```

Double-precision (ftype == 01)

```
FCSEL <Dd>, <Dn>, <Dm>, <cond>
```

```
if ftype == '10' || (ftype == '11' && !IsFeatureImplemented(FEAT_FP16)) then

integer d = UInt(Rd);
integer n = UInt(Rn);
integer m = UInt(Rm);

constant integer datasize = 8 << UInt(ftype EOR '10');
```

Assembler Symbols

<Dd>	Is the 64-bit name of the SIMD&FP destination register, encoded in the "Rd" field.
<Dn>	Is the 64-bit name of the first SIMD&FP source register, encoded in the "Rn" field.
<Dm>	Is the 64-bit name of the second SIMD&FP source register, encoded in the "Rm" field.
<Hd>	Is the 16-bit name of the SIMD&FP destination register, encoded in the "Rd" field.

<Hn>	Is the 16-bit name of the first SIMD&FP source register, encoded in the "Rn" field.
<Hm>	Is the 16-bit name of the second SIMD&FP source register, encoded in the "Rm" field.
<Sd>	Is the 32-bit name of the SIMD&FP destination register, encoded in the "Rd" field.
<Sn>	Is the 32-bit name of the first SIMD&FP source register, encoded in the "Rn" field.
<Sm>	Is the 32-bit name of the second SIMD&FP source register, encoded in the "Rm" field.
<cond>	Is one of the standard conditions, encoded in the "cond" field in the standard way.

Operation

```
CheckFPEnabled64();
bits(datasize) result;

result = if ConditionHolds(cond) then V[n, datasize] else V[m, datasize

V[d, datasize] = result;
```

Operational information

If PSTATE.DIT is 1:

- The execution time of this instruction is independent of:
  - The values of the data supplied in any of its registers.
  - The values of the NZCV flags.
- The response of this instruction to asynchronous exceptions does not vary based on:
  - The values of the data supplied in any of its registers.
  - The values of the NZCV flags.

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