<u>Base</u>	SIMD&FP	<u>SVE</u>	<u>SME</u>	<u>Index by</u>
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Pseu

MLS (vector)

Multiply-Subtract from accumulator (vector). This instruction multiplies corresponding elements in the vectors of the two source SIMD&FP registers, and subtracts the results from the vector elements of the destination SIMD&FP register.

Depending on the settings in the *CPACR_EL1*, *CPTR_EL2*, and *CPTR_EL3* registers, and the current Security state and Exception level, an attempt to execute the instruction might be trapped.

31 30 29 28 27	26 25 24 23 22	21 20 19 18 17 16	15 14 13 12 11 10	9 8 7 6 5	4 3 2 1 0
0 Q 1 0 1	1 1 0 size	1 Rm	1 0 0 1 0 1	Rn	Rd
U		•	•		

```
MLS <Vd>.<T>, <Vn>.<T>, <Vm>.<T>
```

```
integer d = UInt(Rd);
integer n = UInt(Rn);
integer m = UInt(Rm);
if size == '11' then UNDEFINED;
constant integer esize = 8 << UInt(size);
constant integer datasize = 64 << UInt(Q);
integer elements = datasize DIV esize;

boolean sub_op = (U == '1');</pre>
```

Assembler Symbols

<Vd>

Is the name of the SIMD&FP destination register, encoded in the "Rd" field.

<T>

Is an arrangement specifier, encoded in "size:Q":

size	Q	<t></t>
0.0	0	8B
00	1	16B
01	0	4H
01	1	8H
10	0	2S
10	1	4S
11	Х	RESERVED

<Vn>

Is the name of the first SIMD&FP source register, encoded in the "Rn" field.

<Vm>

Is the name of the second SIMD&FP source register, encoded in the "Rm" field.

Operation

```
CheckFPAdvSIMDEnabled64();
bits(datasize) operand1 = V[n, datasize];
bits(datasize) operand2 = \underline{\underline{V}}[m, datasize];
bits(datasize) operand3 = V[d, datasize];
bits(datasize) result;
bits(esize) element1;
bits(esize) element2;
bits(esize) product;
for e = 0 to elements-1
    element1 = Elem[operand1, e, esize];
    element2 = <u>Elem</u>[operand2, e, esize];
    product = (UInt (element1) *UInt (element2)) <esize-1:0>;
    if sub op then
        Elem[result, e, esize] = Elem[operand3, e, esize] - product;
    else
        Elem[result, e, esize] = Elem[operand3, e, esize] + product;
V[d, datasize] = result;
```

Operational information

If PSTATE.DIT is 1:

- The execution time of this instruction is independent of:
 - The values of the data supplied in any of its registers.
 - The values of the NZCV flags.
- The response of this instruction to asynchronous exceptions does not vary based on:
 - The values of the data supplied in any of its registers.
 - The values of the NZCV flags.

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