URSHL (multiple vectors)

Multi-vector unsigned rounding shift left

Shift the unsigned elements of the two or four first source vectors by corresponding elements of the two or four second source vectors and destructively place the rounded results in the corresponding elements of the two or four first source vectors. A positive shift amount performs a left shift, otherwise a right shift by the negated shift amount is performed.

This instruction is unpredicated.

It has encodings from 2 classes: Two registers and Four registers

Two registers
(FEAT_SME2)

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
1	1	0	0	0	0	0	1	size		1	Zm				0	1	0	1	1	0	0	1	0	0	0	1	Zdn				1
																															U

URSHL { <Zdn1>.<T>-<Zdn2>.<T> }, { <Zdn1>.<T>-<Zdn2>.<T> }, { <Zm1>

```
if !HaveSME2() then UNDEFINED;
constant integer esize = 8 << UInt(size);
integer dn = UInt(Zdn:'0');
integer m = UInt(Zm:'0');
constant integer nreg = 2;
```

Four registers
(FEAT_SME2)

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
1	1	0	0	0	0	0	1	size		1	Zm				0	0	1	0	1	1	1	0	0	1	0	0	0	1	Zdn		0	1
																															U

URSHL { <Zdn1>.<T>-<Zdn4>.<T> }, { <Zdn1>.<T>-<Zdn4>.<T> }, { <Zm1>

```
if !HaveSME2() then UNDEFINED;
constant integer esize = 8 << UInt(size);
integer dn = UInt(Zdn:'00');
integer m = UInt(Zm:'00');
constant integer nreg = 4;
```

Assembler Symbols

<Zdn1>	For the two registers variant: is the name of the first scalable vector register of a multi-vector sequence, encoded as "Zdn" times 2.

For the four registers variant: is the name of the first scalable vector register of a multi-vector sequence, encoded as "Zdn" times 4.

<T>

Is the size specifier, encoded in “size”:

size	<T>
00	B
01	H
10	S
11	D

<Zdn4> Is the name of the fourth scalable vector register of a multi-vector sequence, encoded as "Zdn" times 4 plus 3.

<Zdn2> Is the name of the second scalable vector register of a multi-vector sequence, encoded as "Zdn" times 2 plus 1.

<Zm1> For the two registers variant: is the name of the first scalable vector register of a multi-vector sequence, encoded as "Zm" times 2.

For the four registers variant: is the name of the first scalable vector register of a multi-vector sequence, encoded as "Zm" times 4.

<Zm4> Is the name of the fourth scalable vector register of a multi-vector sequence, encoded as "Zm" times 4 plus 3.

<Zm2> Is the name of the second scalable vector register of a multi-vector sequence, encoded as "Zm" times 2 plus 1.

Operation

```
CheckStreamingSVEEnabled();
constant integer VL = CurrentVL;
constant integer elements = VL DIV esize;
array [0..3] of bits(VL) results;

for r = 0 to nreg-1
    bits(VL) operand1 = Z[dn+r, VL];
    bits(VL) operand2 = Z[m+r, VL];
    for e = 0 to elements-1
        integer element =  UInt(Elem[operand1, e, esize]);
        integer shift = ShiftSat(SInt(Elem[operand2, e, esize]), esize)
        integer res;
        if shift >= 0 then
            res = element << shift;
        else
            shift = -shift;
            res = (element + (1 << (shift - 1))) >> shift;
        Elem[results[r], e, esize] = res<esize-1:0>;

for r = 0 to nreg-1
    Z[dn+r, VL] = results[r];
```

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