

SCLAMP

Multi-vector signed clamp to minimum/maximum vector

Clamp each signed element in the two or four destination vectors to between the signed minimum value in the corresponding element of the first source vector and the signed maximum value in the corresponding element of the second source vector and destructively place the clamped results in the corresponding elements of the two or four destination vectors.

This instruction is unpredicated.

It has encodings from 2 classes: [Two registers](#) and [Four registers](#)

Two registers (FEAT_SME2)

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
1	1	0	0	0	0	0	1	size	1		Zm					1	1	0	0	0	1					Zn			Zd		0

U

SCLAMP { **<Zd1>.<T>-<Zd2>.<T>** }, **<Zn>.<T>**, **<Zm>.<T>**

```
if !HaveSME2() then UNDEFINED;
constant integer esize = 8 << UInt(size);
integer n = UInt(Zn);
integer m = UInt(Zm);
integer d = UInt(Zd:'0');
constant integer nreg = 2;
```

Four registers (FEAT_SME2)

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
1	1	0	0	0	0	0	1	size	1		Zm					1	1	0	0	1	1					Zn			Zd	0	0

U

SCLAMP { **<Zd1>.<T>-<Zd4>.<T>** }, **<Zn>.<T>**, **<Zm>.<T>**

```
if !HaveSME2() then UNDEFINED;
constant integer esize = 8 << UInt(size);
integer n = UInt(Zn);
integer m = UInt(Zm);
integer d = UInt(Zd:'00');
constant integer nreg = 4;
```

Assembler Symbols

<Zd1>

For the two registers variant: is the name of the first destination scalable vector register of a multi-vector sequence, encoded as "Zd" times 2.

For the four registers variant: is the name of the first destination scalable vector register of a multi-vector sequence, encoded as "Zd" times 4.

<T>

Is the size specifier, encoded in "size":

size	<T>
00	B
01	H
10	S
11	D

<Zd4>

Is the name of the fourth destination scalable vector register of a multi-vector sequence, encoded as "Zd" times 4 plus 3.

<Zd2>

Is the name of the second destination scalable vector register of a multi-vector sequence, encoded as "Zd" times 2 plus 1.

<Zn>

Is the name of the first source scalable vector register, encoded in the "Zn" field.

<Zm>

Is the name of the second source scalable vector register, encoded in the "Zm" field.

Operation

```
CheckStreamingSVEEnabled();
constant integer VL = CurrentVL;
constant integer elements = VL DIV esize;
array [0..3] of bits(VL) results;

for r = 0 to nreg-1
    bits(VL) operand1 = Z[n, VL];
    bits(VL) operand2 = Z[m, VL];
    bits(VL) operand3 = Z[d+r, VL];
    for e = 0 to elements-1
        integer element1 = SInt(Elem[operand1, e, esize]);
        integer element2 = SInt(Elem[operand2, e, esize]);
        integer element3 = SInt(Elem[operand3, e, esize]);
        integer res = Min(Max(element1, element3), element2);
        Elem[results[r], e, esize] = res<esize-1:0>;

for r = 0 to nreg-1
    Z[d+r, VL] = results[r];
```

Operational information

If PSTATE.DIT is 1:

- The execution time of this instruction is independent of:
 - The values of the data supplied in any of its registers.
 - The values of the NZCV flags.

- The response of this instruction to asynchronous exceptions does not vary based on:
 - The values of the data supplied in any of its registers.
 - The values of the NZCV flags.

[Base
Instructions](#)

[SIMD&FP
Instructions](#)

[SVE
Instructions](#)

[SME
Instructions](#)

[Index by
Encoding](#)

[Sh
Pseud](#)

Internal version only: isa v33.64, AdvSIMD v29.12, pseudocode
no_diffs_2023_09_RC2, sve v2023-06_rel ; Build timestamp: 2023-09-18T17:56

Copyright Â© 2010-2023 Arm Limited or its affiliates. All rights reserved. This
document is Non-Confidential.