MVFR1_EL1, AArch32 Media and VFP Feature Register 1

The MVFR1_EL1 characteristics are:

Purpose

Describes the features provided by the AArch32 Advanced SIMD and Floating-point implementation.

Must be interpreted with MVFR0_EL1 and MVFR2_EL1.

For general information about the interpretation of the ID registers see 'Principles of the ID scheme for fields in ID registers'.

Configuration

AArch64 System register MVFR1_EL1 bits [31:0] are architecturally mapped to AArch32 System register MVFR1[31:0].

In an implementation where at least one Exception level supports execution in AArch32 state, but there is no support for Advanced SIMD and floating-point operation, this register is RAZ.

Attributes

MVFR1_EL1 is a 64-bit register.

Field descriptions

When AArch32 is supported:

63	62	61	60	59	58	57	56	55	54	53	52	51	50	49	48	47	46	45	44	43	42	41	40	39	38	37	36	35	34	33	32
RES0																															

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
SIMDFMAC				FPHP				SIMDHP				SIMDSP				SIMDInt				SIMDLS				FPDNaN				FPFtZ			

Bits [63:32]

Reserved, res0.

SIMDFMAC, bits [31:28]

Advanced SIMD Fused Multiply-Accumulate. Indicates whether the Advanced SIMD implementation provides fused multiply accumulate instructions. Defined values are:

SIMDFMAC	Meaning
0b0000	Not implemented.
0b0001	Implemented.

All other values are reserved.

In Armv8-A, the permitted values are 0b0000 and 0b0001.

The Advanced SIMD and floating-point implementations must provide the same level of support for these instructions.

FPHP, bits [27:24]

Floating Point Half Precision. Indicates the level of half-precision floating-point support. Defined values are:

FPHP	Meaning
0b0000	Not supported.
0b0001	Floating-point half-precision conversion instructions are supported for conversion between single-precision and half-precision.
0b0010	As for 0b0001, and adds instructions for conversion between double-precision and half-precision.
0b0011	As for 0b0010, and adds support for half-precision floating-point arithmetic.

All other values are reserved.

In Armv8-A, the permitted values are:

- 0b0000 in an implementation without floating-point support.
- 0b0010 in an implementation with floating-point support that does not include the FEAT_FP16 extension.
- 0b0011 in an implementation with floating-point support that includes the FEAT_FP16 extension.

The level of support indicated by this field must be equivalent to the level of support indicated by the SIMDHP field, meaning the permitted values are:

Half Precision instructions supported	FPHP	SIMDHP
No support	0b0000	0b0000
Conversions only	0b0010	0b0001

Half Precision instructions supported	FPHP	SIMDHP
Conversions and arithmetic	0b0011	0b0010

SIMDHP, bits [23:20]

Advanced SIMD Half Precision. Indicates the level of half-precision floating-point support. Defined values are:

SIMDHP	Meaning
0b0000	Not supported.
0b0001	SIMD half-precision conversion instructions are supported for conversion between single-precision and half-precision.
0b0010	As for 0b0001, and adds support for half-precision floating-point arithmetic.

All other values are reserved.

In Armv8-A, the permitted values are:

- 0b0000 in an implementation without SIMD floating-point support.
- 0b0001 in an implementation with SIMD floating-point support that does not include the FEAT_FP16 extension.
- 0b0010 in an implementation with SIMD floating-point support that includes the FEAT_FP16 extension.

The level of support indicated by this field must be equivalent to the level of support indicated by the FPHP field, meaning the permitted values are:

Half Precision instructions supported	FPHP	SIMDHP
No support	0b0000	0b0000
Conversions only	0b0010	0b0001
Conversions and arithmetic	0b0011	0b0010

SIMDSP, bits [19:16]

Advanced SIMD Single Precision. Indicates whether the Advanced SIMD and floating-point implementation provides single-precision floating-point instructions. Defined values are:

SIMDSP	Meaning
0b0000	Not implemented.
0b0001	Implemented. This value is permitted only if the SIMDInt field is 0b0001.

All other values are reserved.

In Armv8-A, the permitted values are 0b0000 and 0b0001.

SIMDInt, bits [15:12]

Advanced SIMD Integer. Indicates whether the Advanced SIMD and floating-point implementation provides integer instructions. Defined values are:

SIMDInt	Meaning
0b0000	Not implemented.
0b0001	Implemented.

All other values are reserved.

In Armv8-A, the permitted values are 0b0000 and 0b0001.

SIMDLS, bits [11:8]

Advanced SIMD Load/Store. Indicates whether the Advanced SIMD and floating-point implementation provides load/store instructions. Defined values are:

SIMDLS	Meaning
0b0000	Not implemented.
0b0001	Implemented.

All other values are reserved.

In Armv8-A, the permitted values are 0b0000 and 0b0001.

FPDNaN, bits [7:4]

Default NaN mode. Indicates whether the floating-point implementation provides support only for the Default NaN mode. Defined values are:

FPDNaN	Meaning
0b0000	Not implemented, or hardware supports only the Default NaN mode.
0b0001	Hardware supports propagation of NaN values.

All other values are reserved.

In Armv8-A, the permitted values are `0b0000` and `0b0001`.

FPFtZ, bits [3:0]

Flush to Zero mode. Indicates whether the floating-point implementation provides support only for the Flush-to-Zero mode of operation. Defined values are:

FPFtZ	Meaning
`0b0000`	Not implemented, or hardware supports only the Flush-to-Zero mode of operation.
`0b0001`	Hardware supports full denormalized number arithmetic.

All other values are reserved.

In Armv8-A, the permitted values are `0b0000` and `0b0001`.

Otherwise:

63 62 61 60 59 58 57 56 55 54 53 52 51 50 49 48 47 46 45 44 43 42 41 40 39 38 37 36 35 34 33 32
UNKNOWN
UNKNOWN
31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

Bits [63:0]

Reserved, unknown.

Accessing MVFR1_EL1

Accesses to this register use the following encodings in the System register encoding space:

MRS <Xt>, MVFR1_EL1

op0	op1	CRn	CRm	op2
0b11	0b000	0b0000	0b0011	0b001

```
if PSTATE.EL == EL0 then
    if IsFeatureImplemented(FEAT_IDST) then
        if EL2Enabled() && HCR_EL2.TGE == '1' then
            AArch64.SystemAccessTrap(EL2, 0x18);
        else
```

```
            AArch64.SystemAccessTrap(EL1, 0x18);
    else
        UNDEFINED;
elsif PSTATE.EL == EL1 then
    if EL2Enabled() && HCR_EL2.TID3 == '1' then
        AArch64.SystemAccessTrap(EL2, 0x18);
    else
        X[t, 64] = MVFR1_EL1;
elsif PSTATE.EL == EL2 then
    X[t, 64] = MVFR1_EL1;
elsif PSTATE.EL == EL3 then
    X[t, 64] = MVFR1_EL1;
```

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