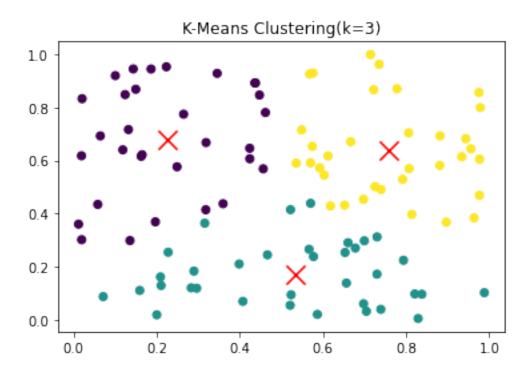
6-implement-k-means-algorithm

```
[1]: import numpy as np
      from sklearn.cluster import KMeans
      import matplotlib.pyplot as plt
 [2]: np.random.seed(0)
 [3]: X=np.random.rand(100,2)
 [4]: k=3
     kmeans=KMeans(n_clusters=k)
 [6]: kmeans.fit(X)
 [6]: KMeans(n_clusters=3)
 [7]: cluster_centers=kmeans.cluster_centers_
 [9]: labels=kmeans.labels_
[12]: plt.scatter(X[:,0],X[:,1],c=labels)
      plt.scatter(cluster_centers[:,0],cluster_centers[:
       ,1],marker='x',s=200,color='red')
      plt.title(f"K-Means Clustering(k={k})")
      plt.show()
```



[]:

ment-k-nearest-neighbour-algorithm

November 8, 2023

```
[19]: import numpy as np
      from sklearn.model_selection import train_test_split
      from sklearn.neighbors import KNeighborsClassifier
      from sklearn.metrics import accuracy_score
[20]: np.random.seed(0)
      X=np.random.rand(100,2)
      y=np.random.choice([0,1],size=100)
[21]: X_train, X_test, y_train, y_test=train_test_split(X,y,test_size=0.
       →2,random_state=42)
[22]: k=3
      knn_classifier=KNeighborsClassifier(n_neighbors=k)
      knn_classifier.fit(X_train,y_train)
[22]: KNeighborsClassifier(n_neighbors=3)
[23]:
     y_pred=knn_classifier.predict(X_test)
[24]: accuracy=accuracy_score(y_test,y_pred)
      print(f"Accuracy : {accuracy*100:.2f}%")
```

Accuracy : 30.00%

5-tsp-usiing-hueristic-approach

```
[1]: import math
[2]: def distance(point1,point2) :
         return math.sqrt((point1[0]-point2[0])**2 + (point1[1]-point2[1])**2)
[3]: def nearest_neighbours(points):
         n = len(points)
         unvisited = set(range(n))
         tour = [0]
         unvisited.remove(0)
         while unvisited:
             current_point = tour[-1]
            nearest_point = min(unvisited,key = lambda x:
      distance(points[current_point],points[x]))
            tour.append(nearest_point)
            unvisited.remove(nearest_point)
         tour.append(tour[0])
         return tour
[5]: if __name__ == "__main__" :
         points = [(0,0),(1,2),(2,3),(3,4),(4,2)]
         tour = nearest_neighbours(points)
         print("Optimal Tour:",tour)
    Optimal Tour: [0, 1, 2, 3, 4, 0]
[]:
```

1-best-first-search-algorithm

```
[1]: from queue import PriorityQueue
     v = 14
     graph = [[] for i in range(v)]
     # Function For Implementing Best First Search
     # Gives output path having lowest cost
     def best_first_search(actual_Src, target, n):
         visited = [False] * n
         pq = PriorityQueue()
         pq.put((0, actual_Src))
         visited[actual_Src] = True
         while pq.empty() == False:
             u = pq.get()[1]
             # Displaying the path having lowest cost
             print(u, end=" ")
             if u == target:
                 break
             for v, c in graph[u]:
                 if visited[v] == False:
                     visited[v] = True
                     pq.put((c, v))
         print()
     # Function for adding edges to graph
     def addedge(x, y, cost):
         graph[x].append((y, cost))
         graph[y].append((x, cost))
     # The nodes shown in above example(by alphabets) are
     # implemented using integers addedge(x,y,cost);
     addedge(0, 1, 3)
     addedge(0, 2, 6)
     addedge(0, 3, 5)
     addedge(1, 4, 9)
     addedge(1, 5, 8)
     addedge(2, 6, 12)
     addedge(2, 7, 14)
     addedge(3, 8, 7)
     addedge(8, 9, 5)
     addedge(8, 10, 6)
```

```
addedge(9, 11, 1)
addedge(9, 12, 10)
addedge(9, 13, 2)
source = 0
target = 9
best_first_search(source, target, v)
```

0 1 3 2 8 9

[]:[

3-water-jug-problem

```
[3]: def water_jug_dfs(jug1_capacity, jug2_capacity, target_capacity):
         def dfs(jug1, jug2, path):
             if jug1 == target_capacity or jug2 == target_capacity:
                 print("Solution found:", path)
                 return
     # Fill jug1
             if jug1 < jug1_capacity:</pre>
                 new_jug1 = jug1_capacity
                 new_jug2 = jug2
                 if (new_jug1, new_jug2) not in visited:
                     visited.add((new_jug1, new_jug2))
                     dfs(new_jug1, new_jug2, path + f"Fill Jug1\n")
     # Fill jug2
             if jug2 < jug2_capacity:</pre>
                 new_jug1 = jug1
                 new_jug2 = jug2_capacity
                 if (new_jug1, new_jug2) not in visited:
                     visited.add((new_jug1, new_jug2))
                     dfs(new_jug1, new_jug2, path + f"Fill Jug2\n")
     #pour water from jug1 to jug2
             if jug1>0 and jug2<jug2_capacity:</pre>
                 pour_amount=min(jug1,jug2_capacity-jug2)
                 new_jug1= jug1-pour_amount
                 new_jug2 = jug2 + pour_amount
                 if (new_jug1, new_jug2) not in visited:
                     visited.add((new_jug1, new_jug2))
                     dfs(new_jug1, new_jug2, path + f"Pour Jug1 into Jug2\n")
     # Pour water from jug2 to jug1
             if jug2 > 0 and jug1 < jug1_capacity:</pre>
                 pour_amount = min(jug2, jug1_capacity - jug1)
                 new_jug1 = jug1 + pour_amount
                 new_jug2 = jug2 - pour_amount
                 if (new_jug1, new_jug2) not in visited:
                     visited add((new_jug1, new_jug2))
```

```
dfs(new_jug1, new_jug2, path + f"Pour Jug2 into Jug1\n")
     # Empty jug1
             if jug1 > 0:
                 new_jug1 = 0
                 new_jug2 = jug2
                 if (new_jug1, new_jug2) not in visited:
                     visited.add((new_jug1, new_jug2))
                     dfs(new_jug1, new_jug2, path + f"Empty Jug1\n")
     # Empty jug2
             if jug2 > 0:
                 new_jug1 = jug1
                 new_jug2 = 0
                 if (new_jug1, new_jug2) not in visited:
                     visited.add((new_jug1, new_jug2))
                     dfs(new_jug1, new_jug2, path + f"Empty Jug2\n")
         visited= set()
         dfs(0, 0, "")
     # Example usage:
     jug1\_capacity = 4
     jug2\_capacity = 3
     target_capacity = 2
     water_jug_dfs(jug1_capacity, jug2_capacity, target_capacity)
    Solution found: Fill Jug1
    Fill Jug2
    Empty Jug1
    Pour Jug2 into Jug1
    Fill Jug2
    Pour Jug2 into Jug1
    Solution found: Fill Jug1
    Pour Jug1 into Jug2
    Empty Jug2
    Pour Jug1 into Jug2
    Fill Jug1
    Pour Jug1 into Jug2
[]:
```

4-8-queens

```
[1]: print("Taking the number of queens")
    N = int(input())
              [[0]*N for _ in range(N)]
     def attack(i,j) :
         for k in range(0,N) :
             if board[i][k] ==1 or board[k][j] ==1 :
                 return True
         for k in range(0,N) :
                 for 1 in range(0,N) :
                     if(k+l==i+j) or (k-l==i-j):
                         if board[k][l] == 1 :
                             return True
         return False
     def N_queens(n):
         if n==0:
             return True
         for i in range(0,N) :
             for j in range(0,N) :
                 if (not(attack(i,j))) and (board[i][j]!=1) :
                     board[i][j] = 1
                     if N_queens(n-1) == True :
                         return True
                     board[i][j] = 0
         return False
     N_queens(N)
```

```
for i in board :
    print (i)

Taking the number of queens
8

[1, 0, 0, 0, 0, 0, 0, 0, 0]
[0, 0, 0, 0, 1, 0, 0, 0]
[0, 0, 0, 0, 0, 0, 0, 1]
[0, 0, 0, 0, 0, 0, 1, 0, 0]
[0, 0, 1, 0, 0, 0, 0, 0, 0]
[0, 0, 0, 0, 0, 0, 0, 0, 0]
[0, 1, 0, 0, 0, 0, 0, 0]
[0, 1, 0, 0, 0, 0, 0, 0]
[0, 0, 0, 1, 0, 0, 0, 0]
```

ard-chaining-or-backward-chaining

November 8, 2023

1 Forawrd Chaining

```
[1]: class rule :
    def __init__(self,antecedents,consequent) :
        self.antecedents = antecedents
        self.consequent = consequent
```

```
[2]: class KnowledgeBase:
        def __init__(self) :
            self.facts = set()
            self.rules = []
        def add_facts(self,facts) :
             self.facts.add(facts)
        def add_rules(self,rule) :
             self.rules.append(rule)
        def apply_forward_chaining(self) :
            new_facts_derived = True
            while new_facts_derived :
                 new_facts_derived = False
                for rule in self.rules :
                     if all(antecedent in self.facts for antecedent in rule.
      →antecedents) and rule.consequent not in self.facts
                         self.facts.add(rule.consequent)
```

new_facts_derived = True

```
[3]: if __name__ == "__main__" :
    kb = KnowledgeBase()

#Define rules and facts

rule1 = rule(["A","C"],"E")
    rule2 = rule(["A","E"],"G")
    rule3 = rule(["B"],"E")
    rule4 = rule(["G"],"D")
    kb.add_rules(rule1)
    kb.add_rules(rule2)
    kb.add_rules(rule3)
    kb.add_rules(rule4)

kb.add_facts("A")
    kb.add_facts("C")

kb.apply_forward_chaining()

print("Derived Facts :",kb.facts)
```

Derived Facts : {'G', 'A', 'E', 'C', 'D'}

9-backward-chaining

```
[3]: knowledge_base = {
        "rule1" : {
            "if" : ["A", "B"] ,
            "then":"C"
        },
        "rule2" : {
            "if" : ["D"] ,
            "then" : "A"
        },
        "rule3" : {
            "if" : ["F"] ,
            "then" : "B"
        } ,
         "rule4" : {
            "if" : ["F"] ,
            "then" : "D"
        },
        "rule5" : {
             "if" : ["G"] ,
             "then" : "E"
        }
     }
     #Define a function to perform backward chaining
     def backward_chaining(goal,known_facts) :
        if goal in known_facts :
            return True
        for rule , value in knowledge_base.items() :
```

The goal $\ensuremath{^{\text{C'}}}$ cannot be reached .

10-implement-sym

```
[1]: import numpy as np
      from sklearn import datasets
      from sklearn.model_selection import train_test_split
      from sklearn.svm import SVC
      from sklearn.metrics import accuracy_score
 [3]: X,y=datasets.
       omake_classification(n_samples=500,n_features=3,n_informative=2,n_redundant=0,random_state=4
 [4]: X_train, X_test, y_train, y_test=train_test_split(X,y,test_size=0.
       →2,random_state=42)
 [5]: svm_classifier=SVC(kernel='linear',C=1.0)
 [6]: svm_classifier.fit(X_train,y_train)
 [6]: SVC(kernel='linear')
 [7]: y_pred=svm_classifier.predict(X_test)
 [9]: accuracy=accuracy_score(y_test,y_pred)
[10]: print("Accuracy : ",accuracy)
     Accuracy: 0.87
```