

detection\_utils.utils.object  
\_detection\_evaluation.ObjectDetection  
Evaluator.get\_estimator\_eval\_metric\_ops



detection\_utils.utils.vrd  
\_evaluation.\_VRDDetectionEvaluation.add  
\_single\_ground\_truth\_image\_info



detection\_utils.utils.vrd  
\_evaluation.\_VRDDetectionEvaluation.  
\_update\_groundtruth\_statistics