

detection utils.utils.vrd evaluation. VRDDetectionEvaluation # per image eval

groundtruth box tuples # groundtruth class #

tuples

num qt instances # num gt imgs

_num_gt_instances_per # relationship

detection keys # _scores # _relation_field_values #

tp fp labels

average precisions precisions

#

#

#

#

#

+

+

+

_recalls # _mean_average precision

weighted average precision # recall 50

> median rank 50 _recall 100 _median_rank 100

init () clear detections() add single ground_truth image info()

add_single_detected image info()

evaluate() # update groundtruth

statistics()