


```
detection_utils.utils.np  
_box_list_ops.change_coordinate_frame
```



A diagram consisting of two rectangular boxes connected by a blue arrow pointing from left to right. The left box is white with a black border and contains the text 'detection_utils.utils.np' followed by '_box_list_ops.change_coordinate_frame' on the next line. The right box is gray with a black border and contains the text 'detection_utils.utils.np' followed by '_box_list_ops.scale' on the next line.

```
detection_utils.utils.np  
_box_list_ops.scale
```