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CS20B1097 HIMANSHU
  1. Swap phase of the dog image and magnitude of the Lena image and display the output.
  2. Swap phase of the Lena image and magnitude of the dog image and display the output
  Solve 1 & 2 using built-in function (4 marks) and user defined function (6 marks).
import cv2
import numpy as np
def fft_1d(signal):
  n = len(signal)
  F = np.zeros(n, dtype=complex)
  for u in range(n):
      for x in range(n):
          F[u] = F[u] + (signal[x]*(round(np.cos(2*np.pi*u*x/n), 6) -
1j*round(np.sin(2*np.pi*u*x/n), 6)))
  return F
def fft_2d(signal):
  m = len(signal)
  n = len(signal[0])
  F = np.zeros((m, n), dtype=complex)
  temp = []
   for u in range(m):
      row_signal = signal[u, :]
      temp.append(fft_1d(row_signal))
  final = []
  for v in range(n):
      col_signal = [i[v] for i in temp]
       final.append(fft_1d(col_signal))
  F = np.transpose(final)
   return F
```

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def find_angle(complex_arr):
   phase = []
   for i in range(len(complex_arr)):
       temp = []
       for z in complex_arr[i]:
           if z.imag = 0:
               temp.append(0)
          elif z.real = 0:
               temp.append((abs(z.imag)/z.imag) * np.pi/2)
           else:
               temp.append(np.arctan(z.imag/z.real))
       phase.append(temp)
   return np.array(phase, dtype=np.float32)
dog = cv2.imread('dog.jpg', 0)
lena = cv2.imread('lena.png', 0)
dog_{fft} = fft_2d(dog)
lena_fft = fft_2d(lena)
dog_phase = np.angle(dog_fft)
lena_phase = np.angle(lena_fft)
dog_mag = np.abs(dog_fft)
lena_mag = np.abs(lena_fft)
dog_new = lena_mag * np.exp(1j * dog_phase)
lena_new = dog_mag * np.exp(1j * lena_phase)
dog_new = np.abs(np.fft.ifft2(dog_new))
lena_new = np.abs(np.fft.ifft2(lena_new))
```

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cv2.imshow('dog_new', dog_new.astype(np.uint8))
cv2.imshow('lena_new', lena_new.astype(np.uint8))
cv2.waitKey(0)
cv2.destroyAllWindows()
```

OUTPUT



