

Rotational averaging in  
the third order Couette pathways

ad b)

$$\vec{d}_m = d_m \vec{n}_m$$

$$\langle (\vec{d}_1 \cdot \vec{e}_1) (\vec{d}_2 \cdot \vec{e}_2) (\vec{d}_3 \cdot \vec{e}_3) (\vec{d}_4 \cdot \vec{e}_4) \rangle_S = ?$$

$$= d_1 d_2 d_3 d_4 \sum_{\substack{i j \in e \\ \alpha \beta \gamma}} \ell_i^{(1)} \ell_j^{(2)} \ell_\varepsilon^{(3)} \ell_e^{(4)} \langle I_{ij\epsilon\alpha\beta\gamma} \rangle_S m_i^{(1)} m_j^{(2)} m_\varepsilon^{(3)} m_e^{(4)}$$

$(m_i^{(1)} m_j^{(2)} m_\varepsilon^{(3)} m_e^{(4)})$

$$= d_1 d_2 d_3 d_4 \sum_{ij\epsilon e} \ell_i^{(1)} \ell_j^{(2)} \ell_\varepsilon^{(3)} \ell_e^{(4)} \langle m_i^{(1)} m_j^{(2)} m_\varepsilon^{(3)} m_e^{(4)} \rangle_S$$

$$\langle m_i^{(1)} m_j^{(2)} m_\varepsilon^{(3)} m_e^{(4)} \rangle_S = A^{(1)} \delta_{ij} \delta_{\epsilon e} + A^{(2)} \delta_{ie} \delta_{j\epsilon} + A^{(3)} \delta_{je} \delta_{i\epsilon}$$

$$\langle \dots \rangle_S = d_1 d_2 d_3 d_4 \left[ (\vec{e}_1 \cdot \vec{e}_2) (\vec{e}_3 \cdot \vec{e}_4) A^{(1)} \right.$$

$$\left. + (\vec{e}_1 \cdot \vec{e}_3) (\vec{e}_2 \cdot \vec{e}_4) A^{(2)} + (\vec{e}_1 \cdot \vec{e}_4) (\vec{e}_2 \cdot \vec{e}_3) A^{(3)} \right]$$

Invariance

$$\sum_{ij} \langle m_i^{(1)} m_i^{(2)} m_j^{(3)} m_j^{(4)} \rangle_S = \langle (\vec{m}_1 \cdot \vec{m}_2) (\vec{m}_3 \cdot \vec{m}_4) \rangle_S = \underline{(\vec{m}_1 \cdot \vec{m}_2) (\vec{m}_3 \cdot \vec{m}_4)}$$

$$\begin{aligned} \sum_{ij} \langle m_i^{(1)} m_i^{(2)} m_\theta^{(3)} m_\theta^{(4)} \rangle_S &= \sum_{ij} (A^{(1)} \delta_{ii} \delta_{jj} + A^{(2)} \delta_{ij} \delta_{ij} + A^{(3)} \delta_{ij} \delta_{ij}) \\ &= \underline{A^{(1)} g + A^{(2)} 3 + A^{(3)} 3} \end{aligned}$$

$$\sum_{ij} \langle u_i^{(1)} u_j^{(2)} u_i^{(3)} u_j^{(4)} \rangle = \underline{(\vec{u}_1 \cdot \vec{u}_3)(\vec{u}_2 \cdot \vec{u}_4)}$$

$$\begin{aligned} \sum_{ij} \langle u_i^{(1)} u_j^{(2)} u_i^{(3)} u_j^{(4)} \rangle &= \sum_{ij} A^{(1)} \delta_{ij} \delta_{ij} + A^{(2)} \delta_{ii} \delta_{jj} + A^{(3)} \delta_{ij} \delta_{ij} \\ &= \underline{A^{(1)} 3 + A^{(2)} 9 + A^{(3)} 3} \end{aligned}$$

$$\begin{aligned} \sum_{ij} \langle u_i^{(1)} u_j^{(2)} u_j^{(3)} u_i^{(4)} \rangle &= \underline{(\vec{u}_1 \cdot \vec{u}_4)(\vec{u}_2 \cdot \vec{u}_3)} \\ &= \underline{A^{(1)} 3 + A^{(2)} 3 + A^{(3)} 9} \end{aligned}$$

$$\begin{pmatrix} 9 & 3 & 3 \\ 3 & 9 & 3 \\ 3 & 3 & 9 \end{pmatrix} \begin{pmatrix} A^{(1)} \\ A^{(2)} \\ A^{(3)} \end{pmatrix} = \begin{pmatrix} (\vec{u}_1 \cdot \vec{u}_2)(\vec{u}_3 \cdot \vec{u}_4) \\ (\vec{u}_1 \cdot \vec{u}_3)(\vec{u}_2 \cdot \vec{u}_4) \\ (\vec{u}_1 \cdot \vec{u}_4)(\vec{u}_2 \cdot \vec{u}_3) \end{pmatrix}$$

$$\begin{pmatrix} A^{(1)} \\ A^{(2)} \\ A^{(3)} \end{pmatrix} = \begin{pmatrix} 9 & 3 & 3 \\ 3 & 9 & 3 \\ 3 & 3 & 9 \end{pmatrix}^{-1} \begin{pmatrix} (\vec{u}_1 \cdot \vec{u}_2)(\vec{u}_3 \cdot \vec{u}_4) \\ (\vec{u}_1 \cdot \vec{u}_3)(\vec{u}_2 \cdot \vec{u}_4) \\ (\vec{u}_1 \cdot \vec{u}_4)(\vec{u}_2 \cdot \vec{u}_3) \end{pmatrix}$$

$$\begin{pmatrix} 9 & 3 & 3 \\ 3 & 9 & 3 \\ 3 & 3 & 9 \end{pmatrix}^{-1} = \frac{1}{30} \begin{pmatrix} 4 & -1 & -1 \\ -1 & 4 & -1 \\ -1 & -1 & 4 \end{pmatrix}$$

$$\langle (\vec{d}_1 \cdot \vec{l}_1) (\vec{d}_2 \cdot \vec{l}_2) (\vec{d}_3 \cdot \vec{l}_3) (\vec{d}_4 \cdot \vec{l}_4) \rangle_{S^2} =$$

$$= d_1 d_2 d_3 d_4 \begin{pmatrix} (\vec{d}_1 \cdot \vec{l}_1) (\vec{d}_2 \cdot \vec{l}_2) \\ (\vec{d}_1 \cdot \vec{l}_2) (\vec{d}_2 \cdot \vec{l}_1) \\ (\vec{d}_1 \cdot \vec{l}_3) (\vec{d}_3 \cdot \vec{l}_1) \\ (\vec{d}_1 \cdot \vec{l}_4) (\vec{d}_4 \cdot \vec{l}_1) \end{pmatrix}^T \frac{1}{30} \begin{pmatrix} 4 & -1 & -1 \\ -1 & 4 & -1 \\ -1 & -1 & 4 \end{pmatrix} \begin{pmatrix} (\vec{d}_1 \cdot \vec{l}_1) (\vec{d}_2 \cdot \vec{l}_2) \\ (\vec{d}_1 \cdot \vec{l}_2) (\vec{d}_3 \cdot \vec{l}_2) \\ (\vec{d}_1 \cdot \vec{l}_3) (\vec{d}_4 \cdot \vec{l}_3) \\ (\vec{d}_1 \cdot \vec{l}_4) (\vec{d}_2 \cdot \vec{l}_4) \end{pmatrix}$$

### Examples

$$\vec{d} = \vec{d}_1 = \vec{d}_2 = \vec{d}_3 = \vec{d}_4$$

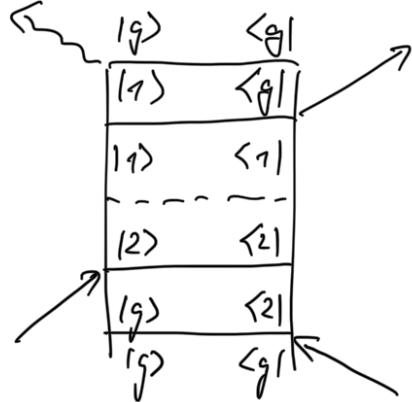
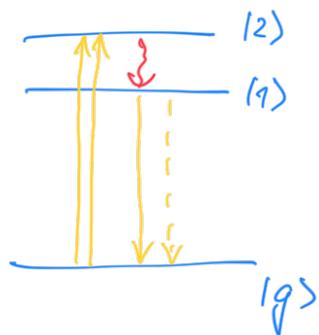
$$\langle (\vec{d}_1 \cdot \vec{d}) (\vec{d}_2 \cdot \vec{d}) (\vec{d}_3 \cdot \vec{d}) (\vec{d}_4 \cdot \vec{d}) \rangle_{S^2} = \frac{d_1 d_2 d_3 d_4}{30} \begin{pmatrix} 2 & 2 & 2 \\ \vdots & & \end{pmatrix} \begin{pmatrix} (\vec{d}_1 \cdot \vec{d}_1) (\vec{d}_2 \cdot \vec{d}_1) \\ (\vec{d}_1 \cdot \vec{d}_2) (\vec{d}_2 \cdot \vec{d}_1) \\ \vdots \end{pmatrix}$$

$$= \frac{d_1 d_2 d_3 d_4}{15} \left[ (\vec{m}_1 \cdot \vec{m}_2) (\vec{m}_3 \cdot \vec{m}_4) + (\vec{m}_1 \cdot \vec{m}_3) (\vec{m}_2 \cdot \vec{m}_4) + (\vec{m}_1 \cdot \vec{m}_4) (\vec{m}_2 \cdot \vec{m}_3) \right]$$

if  $\vec{d} = \vec{d}_1 = \vec{d}_2 = \vec{d}_3 = \vec{d}_4$

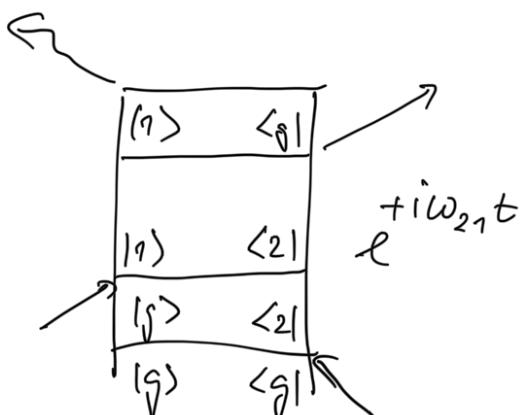
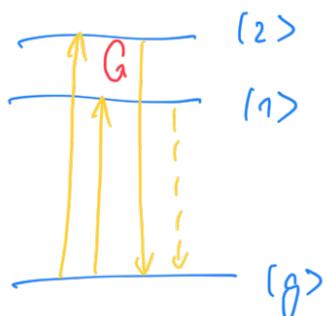
$$\boxed{\langle (\vec{d} \cdot \vec{d})^4 \rangle_{S^2} = \frac{d^4}{5}}$$

## Energy transfer



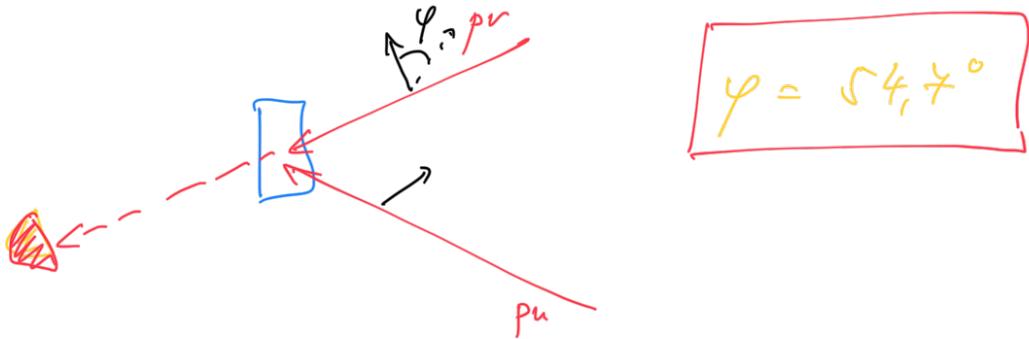
$$\begin{aligned} & \left\langle \underbrace{(\vec{d}_2 \cdot \vec{\ell})}_{\text{red}} \underbrace{(\vec{d}_2 \cdot \vec{\ell})}_{\text{green}} \underbrace{(\vec{d}_1 \cdot \vec{\ell})}_{\text{green}} \underbrace{(\vec{d}_1 \cdot \vec{\ell})}_{\text{red}} \right\rangle_S = \\ &= \frac{d_1^2 d_2^2}{15} \left[ 1 + 2 (\vec{m}_2 \cdot \vec{m}_1) (\vec{m}_2 \cdot \vec{m}_1) \right] \end{aligned}$$

## Cohherence



$$\left\langle (\vec{d}_2 \cdot \vec{\ell}) (\vec{d}_2 \cdot \vec{\ell}) (\vec{d}_1 \cdot \vec{\ell}) (\vec{d}_1 \cdot \vec{\ell}) \right\rangle_S = \frac{d_1^2 d_2^2}{15} \left[ 1 + 2 (\vec{m}_1 \cdot \vec{m}_2)^2 \right]$$

## Magic angle

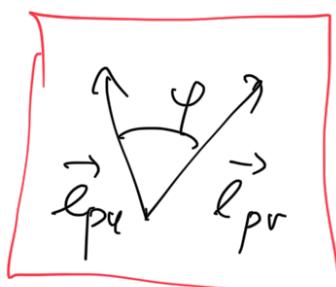


$$\vec{d}_T \nearrow \dots \nearrow \nearrow \vec{d}_0$$

$$\swarrow \vec{d}_T \dots \nearrow \nearrow \nearrow \vec{d}_0$$

Pump  $\vec{d}_1 = \vec{d}_2 = \vec{e}_{pu}$

Probe  $\vec{d}_3 = \vec{d}_4 = \vec{e}_{pr}$



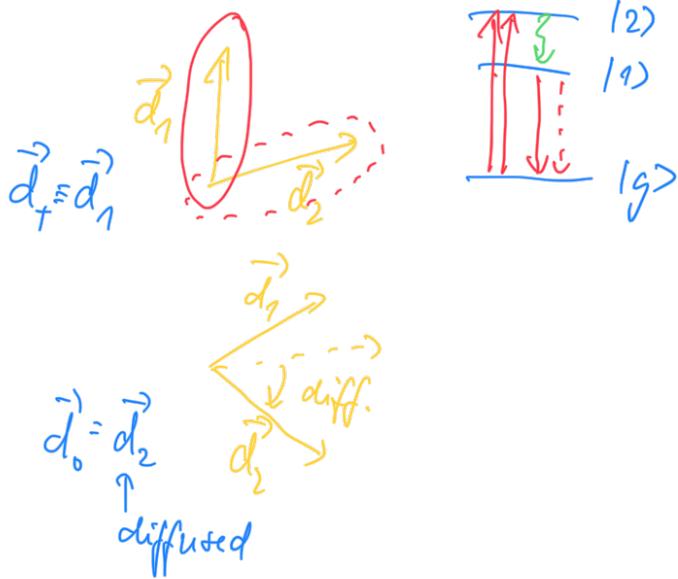
$$\langle (\vec{d}_T \cdot \vec{e}_{pu}) (\vec{d}_T \cdot \vec{e}_{pu}) (\vec{d}_0 \cdot \vec{e}_{pr}) (\vec{d}_0 \cdot \vec{e}_{pr}) \rangle =$$

$$= \frac{\vec{d}_T^2 \vec{d}_0^2}{30} \begin{pmatrix} 1 & 1 & 1 \\ (\vec{e}_{pu} \cdot \vec{e}_{pr})^2 & (\vec{e}_{pu} \cdot \vec{e}_{pr})^2 & (\vec{e}_{pu} \cdot \vec{e}_{pr})^2 \end{pmatrix}^T \begin{pmatrix} 4 & 1 & 1 \\ -1 & 4 & -1 \\ -1 & -1 & 4 \end{pmatrix} \begin{pmatrix} 1 \\ (\vec{e}_T \cdot \vec{e}_0)^2 \\ (\vec{e}_T \cdot \vec{e}_0)^2 \end{pmatrix}$$

$$\begin{aligned}
&= \frac{d_T^2 d_0^2}{30} \begin{pmatrix} 1 \\ \cos^2 \varphi \\ \cos^2 \varphi \end{pmatrix}^T \begin{pmatrix} 4 - (\vec{u}_T^\perp \cdot \vec{u}_0) \cdot (\vec{u}_T^\perp \cdot \vec{u}_0) \\ -1 + 4(\vec{u}_T^\perp \cdot \vec{u}_0) \cdot (\vec{u}_T^\perp \cdot \vec{u}_0) \\ -1 - (\vec{u}_T^\perp \cdot \vec{u}_0) \cdot (\vec{u}_T^\perp \cdot \vec{u}_0) + 4(\vec{u}_T^\perp \cdot \vec{u}_0)^2 \end{pmatrix} \\
&\Delta_{T0} = \vec{u}_T^\perp \cdot \vec{u}_0 \\
&= \frac{d_T^2 d_0^2}{30} \left( 4 - 2 \Delta_{T0}^2 + \cos^2 \varphi (3 \Delta_{T0}^2 - 1) + \cos^2 \varphi (3 \Delta_{T0}^2 - 1) \right) \\
&= \frac{d_T^2 d_0^2}{15} \left( 2 - \Delta_{T0}^2 + \cos^2 \varphi (3 \Delta_{T0}^2 - 1) \right) = \\
&= \frac{d_T^2 d_0^2}{15} \left( \underbrace{[3 \cos^2 \varphi - 1] \Delta_{T0}^2}_{= 0^2} + 2 - \cos^2 \varphi \right)
\end{aligned}$$

$$\begin{aligned}
3 \cos^2 \varphi &= 1 \\
\cos^2 \varphi &= \frac{1}{3} \Rightarrow \boxed{\varphi = \arccos\left(\frac{1}{\sqrt{3}}\right) = 54.7^\circ}
\end{aligned}$$

Magic angle



## Cohherence

$$\langle \underbrace{(\vec{d}_1 \cdot \vec{\ell}_{pu})}_{\text{1D}} (\vec{d}_2 \cdot \vec{\ell}_{pa}) (\vec{d}_3 \cdot \vec{\ell}_{pr}) (\vec{d}_4 \cdot \vec{\ell}_{pr}) \rangle_{S2}$$

$$= \frac{d_1 d_2 d_3 d_4}{30} \begin{pmatrix} 1 \\ (\vec{\ell}_{pu} \cdot \vec{\ell}_{pr})^2 \\ (\vec{\ell}_{pa} \cdot \vec{\ell}_{pr})^2 \end{pmatrix}^T \begin{pmatrix} 4 & -1 & -1 \\ -1 & 4 & -1 \\ -1 & -1 & 4 \end{pmatrix} \begin{pmatrix} (\vec{u}_1 \cdot \vec{u}_2)(\vec{u}_3 \cdot \vec{u}_4) \\ (\vec{u}_1 \cdot \vec{u}_3)(\vec{u}_2 \cdot \vec{u}_4) \\ (\vec{u}_1 \cdot \vec{u}_4)(\vec{u}_2 \cdot \vec{u}_3) \end{pmatrix}$$

$$\Delta_1 = (\vec{u}_1 \cdot \vec{u}_3)(\vec{u}_2 \cdot \vec{u}_4)$$

$$\Delta_2 = (\vec{u}_1 \cdot \vec{u}_4)(\vec{u}_2 \cdot \vec{u}_3)$$

$$\Delta = (\vec{u}_1 \cdot \vec{u}_2)(\vec{u}_3 \cdot \vec{u}_4)$$

subject to  
diffusion

— have to be eliminated

not influenced  
by rotational  
diffusion

$$\langle \dots \rangle_{S2} = \Delta \frac{d_1 d_2 d_3 d_4}{30} \begin{pmatrix} 1 \\ \cos^2 \varphi \\ \cos^2 \varphi \end{pmatrix}^T \begin{pmatrix} 4 & -1 & -1 \\ -1 & 4 & -1 \\ -1 & -1 & 4 \end{pmatrix} \begin{pmatrix} 1 \\ \frac{\Delta_1}{\Delta} \\ \frac{\Delta_2}{\Delta} \end{pmatrix}$$

$$= \frac{\Delta d_1 d_2 d_3 d_4}{30} \begin{pmatrix} 1 \\ \cos^2 \varphi \\ \cos^2 \varphi \end{pmatrix}^T \begin{pmatrix} 4 - \frac{\Delta_1 + \Delta_2}{\Delta} \\ -1 + 4 \frac{\Delta_1}{\Delta} - \frac{\Delta_2}{\Delta} \\ -1 - \frac{\Delta_1}{\Delta} + 4 \frac{\Delta_2}{\Delta} \end{pmatrix}$$

$$= \Delta \frac{d_1 d_2 d_3 d_4}{30} \left( 4 - \frac{\Delta_1 + \Delta_2}{\Delta} + \left( \frac{4 \Delta_1 - \Delta_2}{\Delta} - 1 \right) \cos^2 \varphi + \left( \frac{4 \Delta_2 - \Delta_1}{\Delta} - 1 \right) \cos^2 \varphi \right)$$

$$= \Delta \frac{d_1 d_2 d_3 d_4}{30} \left( 4 - 2 \cos^2 \varphi + \frac{\Delta_1 + \Delta_2}{\Delta} (2 \cos^2 \varphi - 1) \right)$$

Magic angle work generally!

## Special case of even-order spectroscopies

$$\langle (\vec{d}_1 \cdot \vec{\ell}_1) (\vec{d}_2 \cdot \vec{\ell}_2) \rangle_n \neq 0$$

$$\langle (\vec{d}_1 \cdot \vec{\ell}_1) (\vec{d}_2 \cdot \vec{\ell}_2) (\vec{d}_3 \cdot \vec{\ell}_3) (\vec{d}_4 \cdot \vec{\ell}_4) \rangle_n \neq 0$$

$$\langle (\vec{d}_1 \cdot \vec{\ell}) \rangle_S = 0$$

$$\langle (\vec{d}_1 \cdot \vec{\ell}) (\vec{d}_2 \cdot \vec{\ell}) (\vec{d}_j \cdot \vec{\ell}) \rangle_S \approx 0 !$$

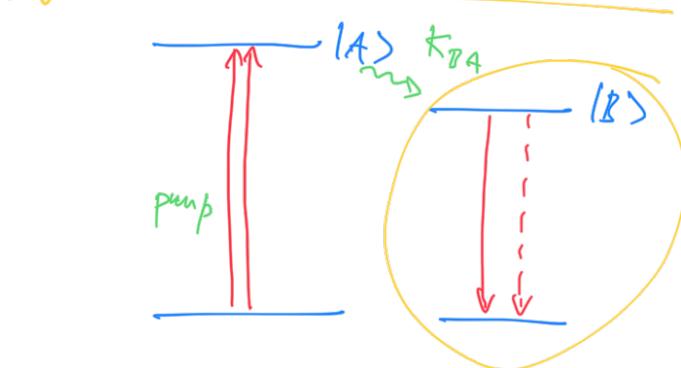
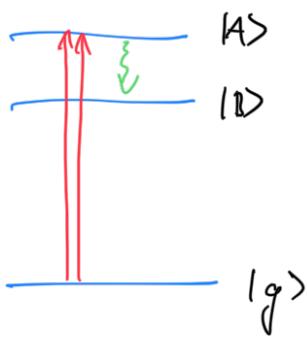
$$\vec{k}_S = \vec{k}_1 + \vec{k}_2 \rightarrow \omega_S = \omega_1 + \omega_2$$

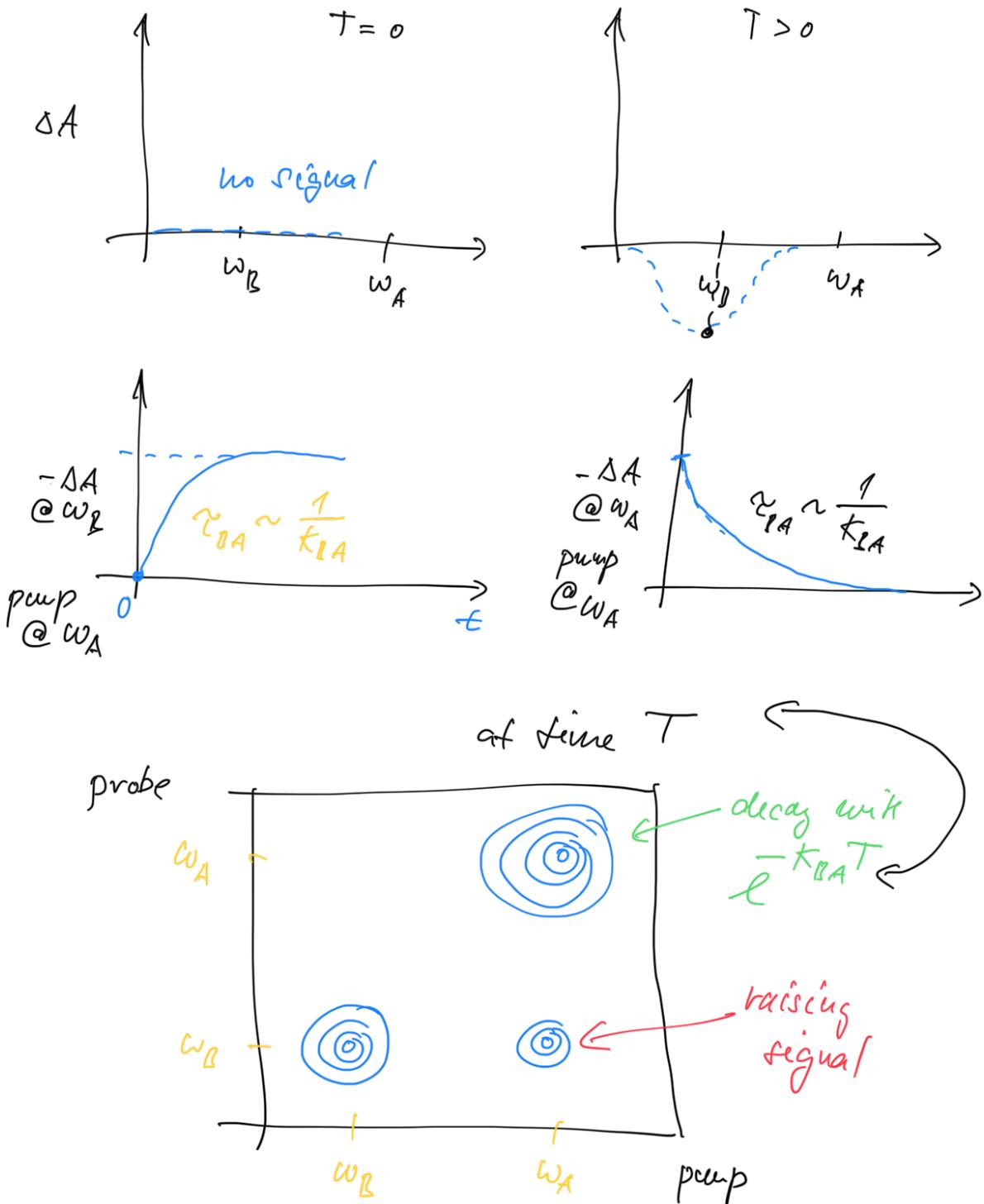
$$\vec{\ell} \cdot i(\vec{k}_1 + \vec{k}_2) \cdot \vec{\ell} - i(\omega_1 + \omega_2) \in$$

We cannot produce second harmonic (sum frequency) in an isotropic sample.

## Monitoring energy transfer processes

by pump-probe spectroscopy





Probing and pumping write frequency resolution -  $\Delta\omega$

→ length of the pulse = time resolution  
scales with  $\frac{1}{\Delta\omega}$