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CS 5330: Week 5 Homework

Question #1

Give an intuitive definition of the meaning of eigenvectors in the context of image analysis (think about the faces example).

Solution-

- Eigenvectors represent the main ways faces in the dataset differ from each other.
- In the faces example, each eigenvector corresponds to a kind of “face pattern”:
 - One might capture hair style changes.
 - Another might capture face shape variation.
 - Another might reflect expression differences.
- We can think of eigenvectors as the basic building blocks of faces.
- Any face can be approximately reconstructed by combining these building blocks with different weights.
- Intuitively, they define the most important directions of variation in the dataset.

In General Image Analysis

- Eigenvectors capture the dominant patterns of variation across the image dataset
 - Each eigenvector represents a fundamental "feature template" - edges, textures, color gradients, or spatial patterns that frequently appear
 - Any image can be reconstructed as a weighted combination of these principal patterns
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Question #2

You have the set of eigenvalues 0.3, 0.25, 0.24, 0.12, 0.06, 0.02, 0.01

- A. What is the dimensionality of original data (the number of significant dimensions)?
- B. How many dimensions of the data would you need to keep to represent 75% of the variation?
- C. How many dimensions of the data would you need to keep to represent 90% of the variation?
- D. If you wanted to see best visualization of the data in 2-D, how would you do it?

Solution-

A. 7 dimensions (7 eigenvalues, one per original dimension)

B. Need 3 dimensions to capture at least 75% of variation [$0.3 + 0.25 + 0.24 = 0.79$ (79%)]

C. Need 4 dimensions to capture at least 90% of variation [$0.3 + 0.25 + 0.24 + 0.12 = 0.91$ (91%)]

D.

- Project data onto the first two eigenvectors (0.3, 0.25)
 - These capture the two directions of maximum variance ($0.3 + 0.25 = 55\%$ of total variation)
 - Each data point becomes a 2-D coordinate: (projection on eigenvector 1, projection on eigenvector 2)
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Question #3

How does aliasing affect building histograms? What is a solution to avoid aliasing when building a histogram?

Solution-

How Aliasing Affects Histograms

- Bin boundary artifacts: Values near bin edges get hard-assigned to one bin or another, creating artificial discontinuities
- Sensitivity to small changes: A pixel value of 127 vs 128 might fall into completely different bins, even though they're nearly identical
- Loss of smoothness: Similar colors/intensities that span bin boundaries don't contribute to neighboring bins, creating jagged histogram distributions
- Example: In a 16-bin color histogram, RGB values (63, 0, 0) and (64, 0, 0) fall into different bins despite being perceptually almost identical

Solution 1: Low-Pass Filtering Before Histogram

- Apply Gaussian blur or other smoothing filter to image first
- Reduces high-frequency noise and sharp transitions
- Creates smoother value distributions that span bin boundaries more naturally
- Example: Blur image slightly before computing color histogram - neighboring pixels influence each other, reducing abrupt intensity changes

Solution 2: Soft Binning (Interpolation)

- Instead of hard-assigning a value to one bin, distribute its contribution across multiple neighboring bins
 - Use weighted voting based on distance to bin centers
 - Example: A pixel value of 127.5 between bins [120-128] and [128-136] contributes 0.5 to each bin instead of 1.0 to just one
 - Common approaches:
 - Linear interpolation between adjacent bins
 - Trilinear interpolation for 3D color histograms (RGB)
 - Gaussian weighting for smoother distributions
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Question #4

What are the three types of aliasing we might encounter in computer vision? Give an example of each one.

Solution-

1. Spatial Aliasing

- Occurs when image resolution is too low to capture fine spatial details
- High-frequency spatial patterns appear as lower-frequency artifacts
- Example: Photographing a brick wall or chain-link fence - regular patterns create moiré effects or jagged edges because pixel spacing is too coarse to properly sample the fine details

2. Spectral (Color) Aliasing

- Happens when color/wavelength sampling is insufficient
- Incorrect color reconstruction or false colors appear
- Example: Demosaicing artifacts in Bayer-pattern cameras - a single red pixel trying to represent a region creates color fringing at edges. Or capturing a rainbow with too few color channels, losing subtle hue transitions

3. Temporal Aliasing

- Results from frame rate being too low to capture motion
 - Fast movements appear jerky, slowed, or reversed
 - Example: Wagon wheel effect in video - spinning wheels appear to rotate backward or freeze because the rotation frequency exceeds half the frame rate (violates temporal Nyquist limit)
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Question #5

Consider a training set of images of doors. Each image is $128 \times 128 = 2^{14}$ pixels. You decide to build an image eigenspace of reduced dimension using your data set. You find that 32 eigenvectors represents over 90% of the variation in the data set and decide to use those eigenvectors as your embedding space.

- A. What is the process for projecting a new image of a door into the door eigenspace?
- B. How many dimensions will the embedding of the new image have? What is the compression factor?
- C. How big is each eigenvector?
- D. What is the process for re-creating the original image from the embedding?
- E. If you project a picture of a frog into the door eigenspace and then try recreating the original image, what will the re-creation look like?

Solution-

1. Process for Projecting New Door Image

- Flatten the 128×128 image into a 16,384-dimensional vector
- Subtract the mean image (computed from training set) to center the data
- Compute dot product with each of the 32 eigenvectors
- Result is a 32-dimensional vector of coefficients (the embedding)

2. Embedding Dimensions & Compression Factor

- Embedding has 32 dimensions
- Compression factor: $16,384 / 32 = 512\times$ compression

3. Size of Each Eigenvector

- Each eigenvector is 16,384 dimensions (same as flattened image size: 128×128)

4. Recreating Original Image

- Multiply each of the 32 eigenvectors by its corresponding coefficient from the embedding
- Sum all 32 weighted eigenvectors together
- Add back the mean image
- Reshape from 16,384-D vector back to 128×128 image

5. Projecting a Frog Image

- The reconstruction will look door-like or ghostly/blurry
 - Since eigenvectors only capture door variations, the frog will be forced into "door space"
 - You'll lose frog-specific features and see a vague door-shaped blob
 - It's like trying to describe a frog using only vocabulary designed for doors
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