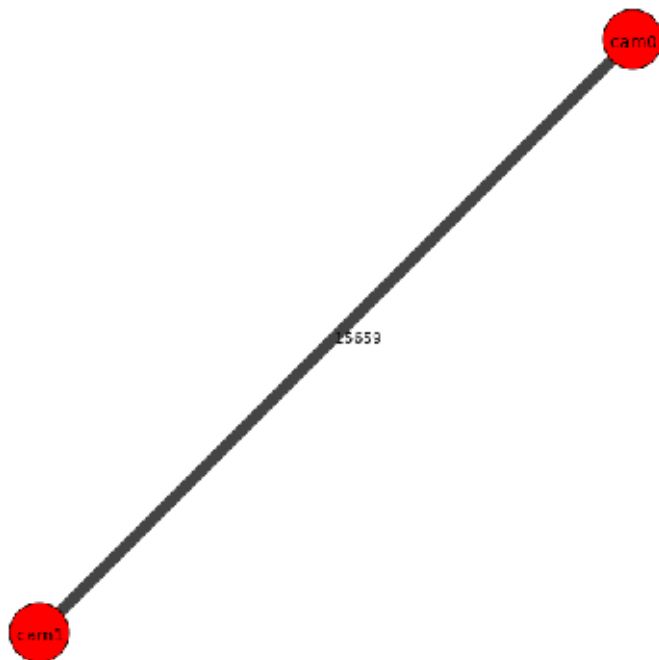
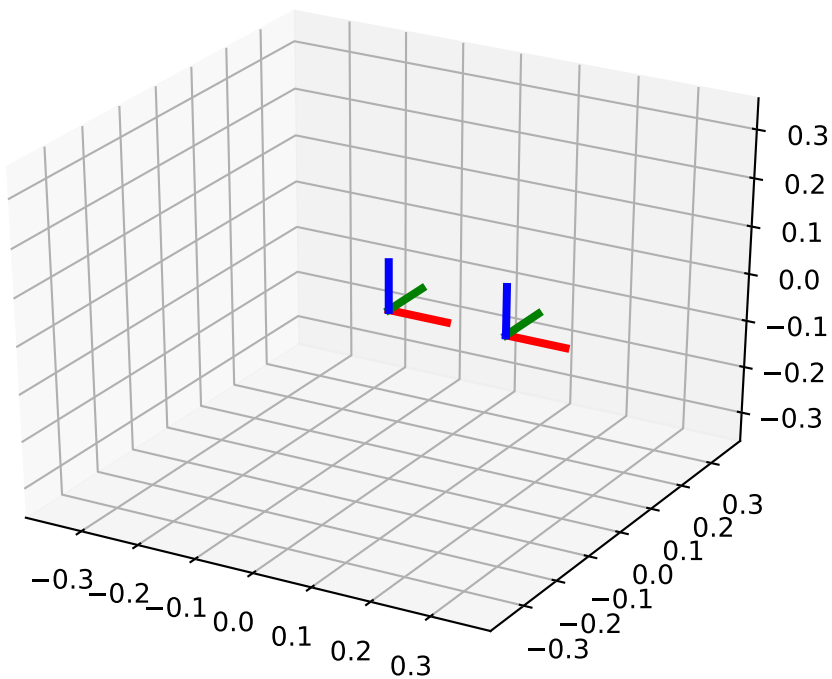


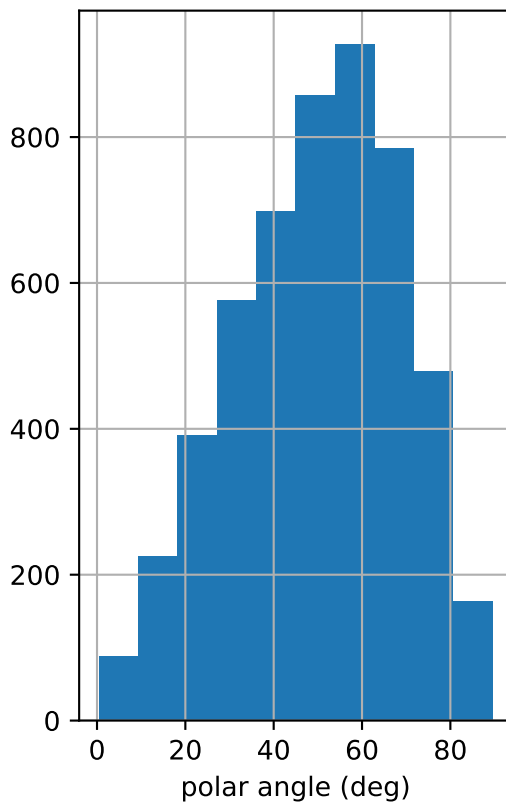
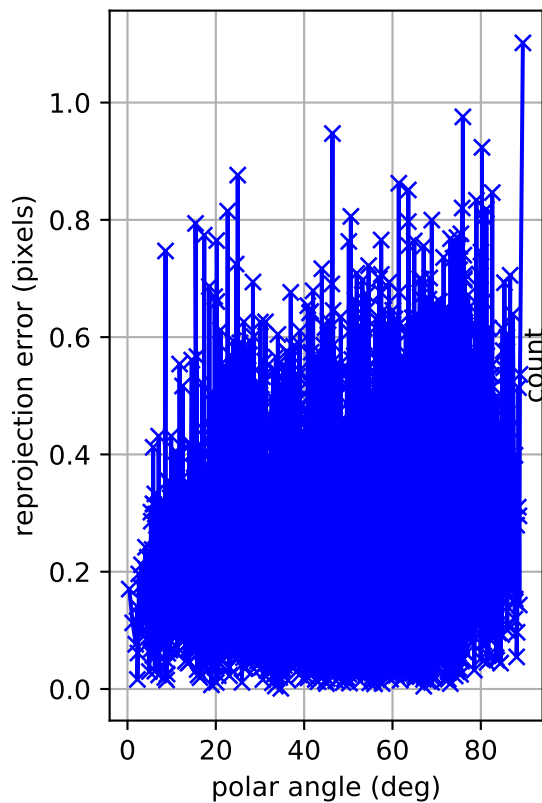
Inter-camera observations graph (edge weight=#mutual obs.)



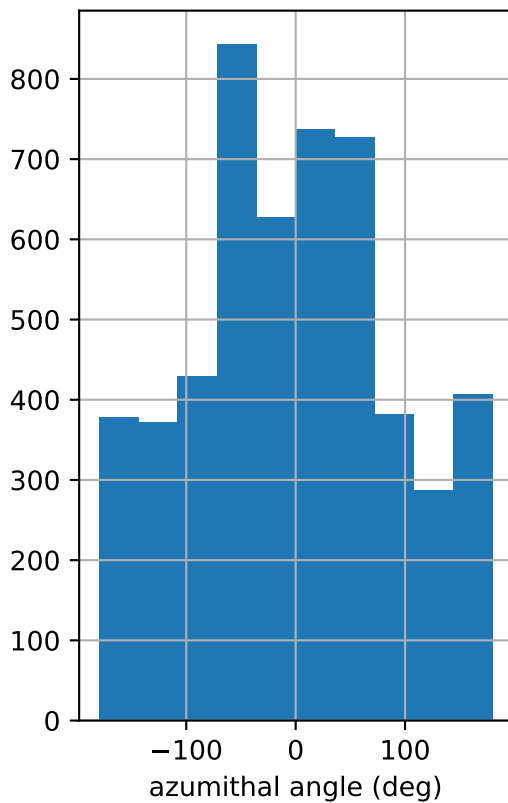
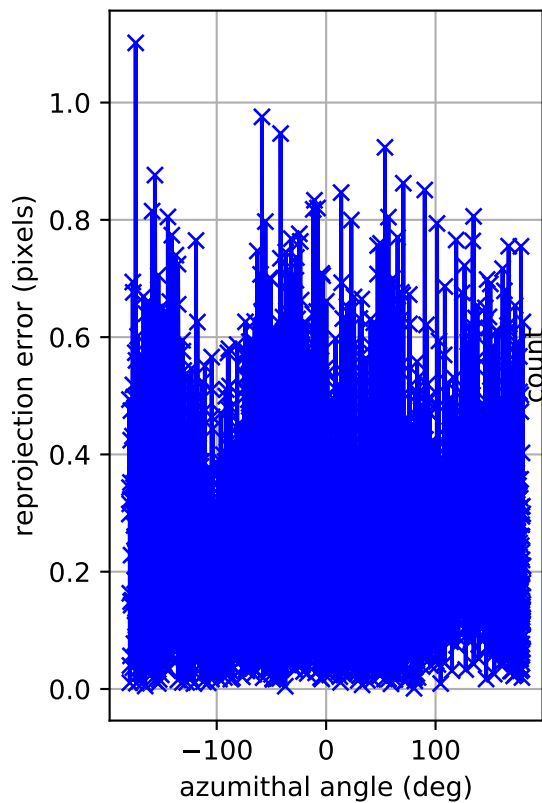
camera system



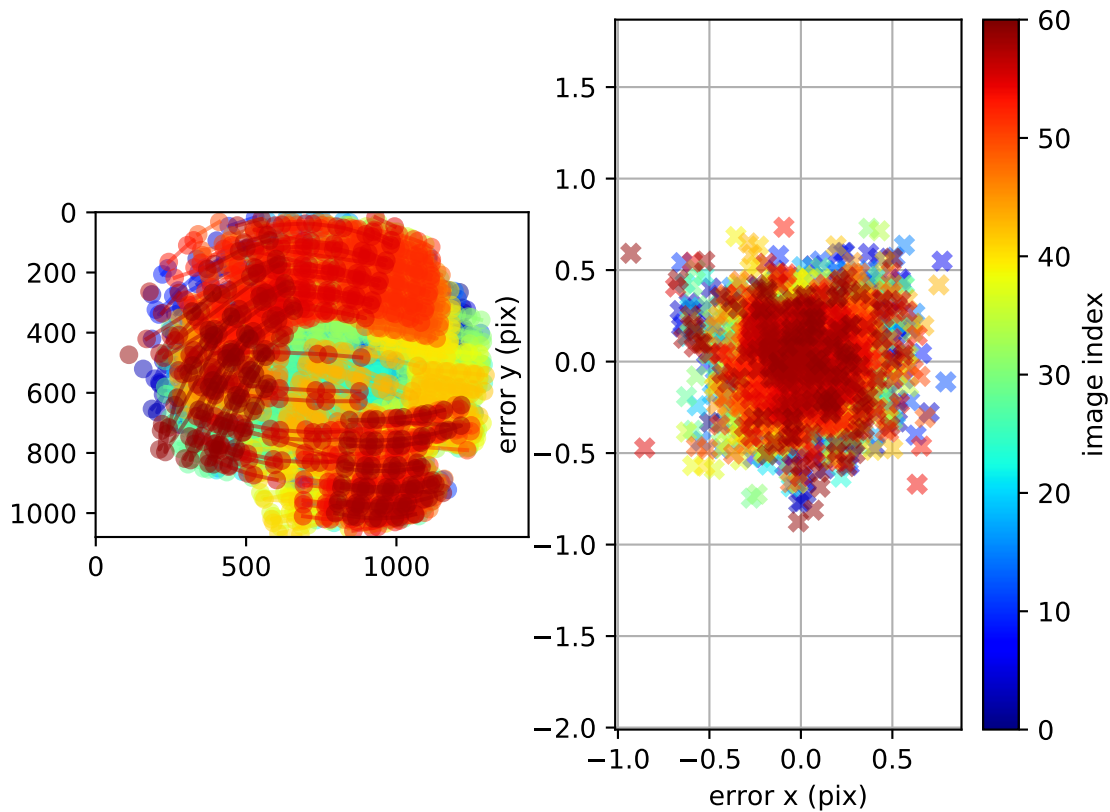
cam0: polar error



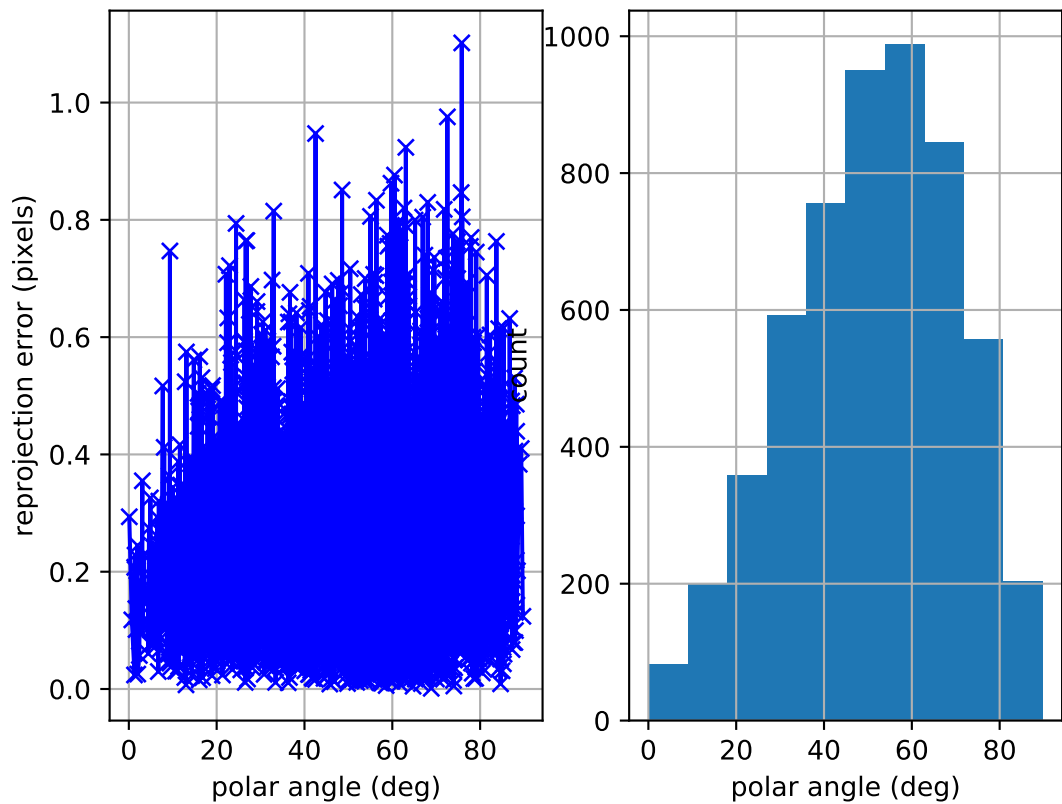
cam0: azimuthal error



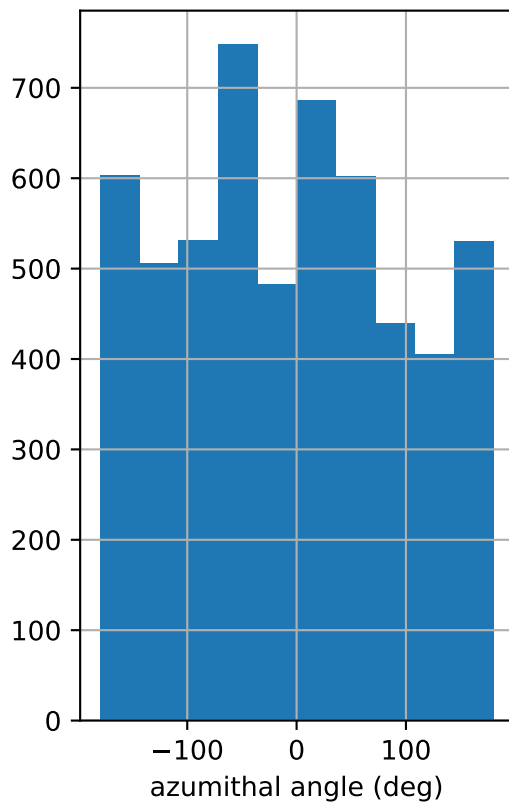
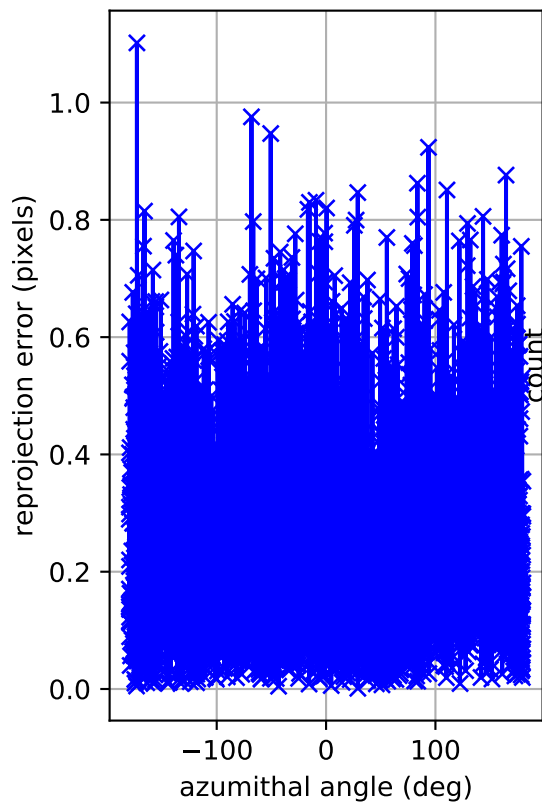
cam0: reprojection errors



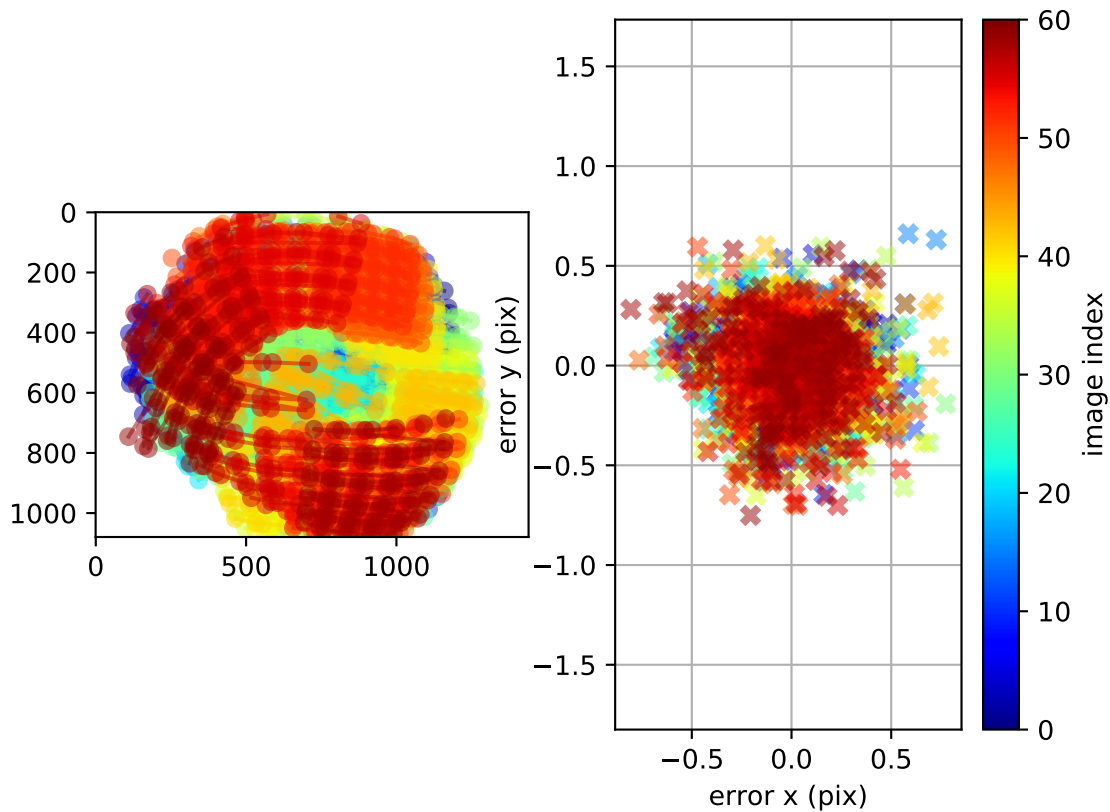
cam1: polar error



cam1: azimuthal error



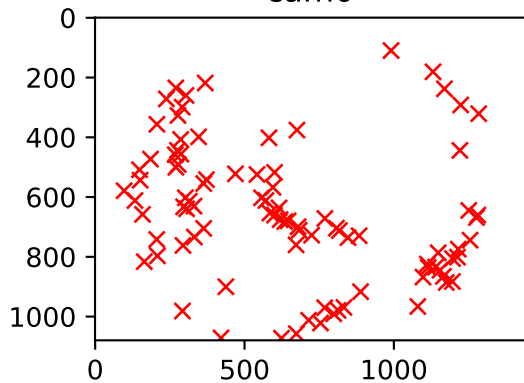
cam1: reprojection errors





# Location of removed outlier corners

cam0



cam1

