

#### **CHAPTER 5.3.4: Static Step Simulation Test Considering Constant Angle Position Using LSTM and Feedforward NN**

Main code to run the LSTM and FNN is gyroscope.mlx. This produces results in Figure 5.20. Simulated data had 60 steps with 24000 points running from -1 to 1 rad/s.

To test with different scenarios, pre-saved networks of LSTM and FNN are used to run.

1. +1 to -1 with halved steps (120 in total) with 48000 points (opp\_stepdata.mat)
2. -1 to 2 with same number of steps as the original simulated data (minus1\_TO\_2\_stepdata.mat)
3. Dynamic data from Chapter 5.3.2 (simulated\_data.mat)

To try with LSTM, the code is Trial\_for\_testdatas\_LSTM.mlx. Change lines 10 - 12 in order to test different scenarios.

To try with FNN, the code is Trial\_for\_testdatas\_FNN.mlx. Change lines 10 - 12 in order to test different scenarios.

Another attempt was to average the steps from the original dataset from -1 to 1 rad/s and train in LSTM and also FNN. With this, use the original data to test the network to see how it behaves. This is with the code average.m