

GAP-Central Demo User's Guide

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1. Overview

This document explains how to setup an GAP-Central demo using SAML21 Xplained Pro, BM71-XPro. This document briefly talks about setting up hardware, building application, programming firmware and running a demo.

This demo application showcases a Proof-of-Concept example of using **ble_host_sdk** to setup BM71 as GAP-Central. This demo application scan for suitable GAP-Peripheral device and connects with it. Once connected it discovers device orientation service and characteristics in remote device and enable notifications to get accelerometer and gyroscope sensor data from remote device. Upon receiving data from remote GAP-Peripheral device, the Central demo prints them on serial console.

The following table provides the list of expected BLE services and Characteristics in this application.

Name	UUID	Properties	Size
			(bytes)
Device Orientation	0xF05ABAC1393611E587A60002A5D5C	-	-
Service (Custom)	51B		
Accelerometer	0x1BC5D5A50200A687E5113639D7BA5	Notify,	6
Position Characteristic	AF0	Read	
Gyroscope Position	0x1BC5D5A50200A687E5113639D4BA5	Notify,	6
Characteristic	AF0	Read	

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1.1. Hardware Setup

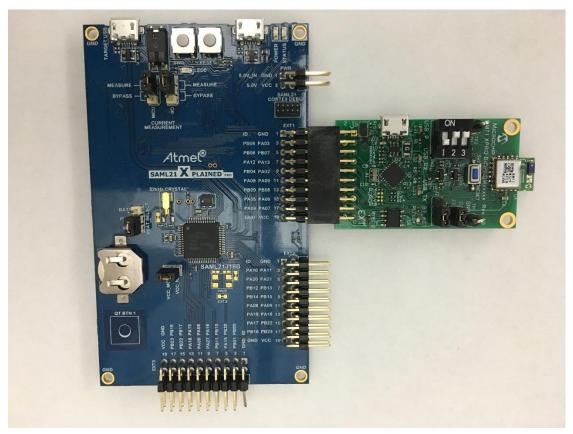


Figure 1: SAML21 Xplained Pro with BM71-XPro

- 1. Plugin the BM71-XPro board into EXT1 of SAML21 Xplained Pro board as shown in Figure 1.
- 2. Connect the SAML21 Xplained Pro board to the host PC using micro USB cable.

1.2. Console

The GAP-Central demo application uses the Universal Asynchronous Receiver/Transmitter (UART) interface on SAML21 Xplained Pro to send the status messages like Scanning, Connected, Disconnected and the sensor data from remote device. Any serial application (ex: TeraTerm) can be used to interact with SAML21 Xplained Pro.

Use the following serial port configuration to interact with BM70.

Baud rate	115200
Data	8 bits
Parity	none
Stop	1 bit
Flow control	none

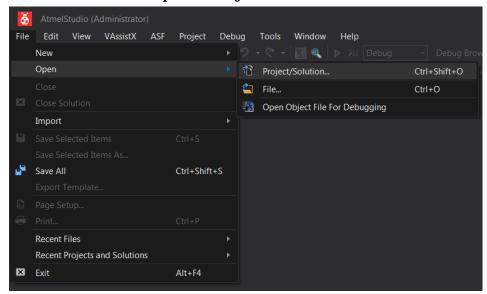
2. Build Procedure

This section describes the build procedure of GAP-Central demo application on Atmel Studio 7.

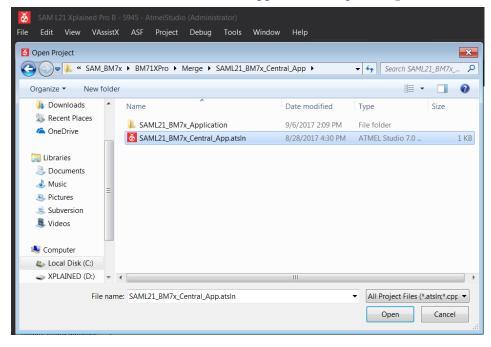
2.1. Open Atmel Studio 7

2.2. Open GAP-Central Demo Application

1. Go to menu File \rightarrow Open \rightarrow Project/Solution.



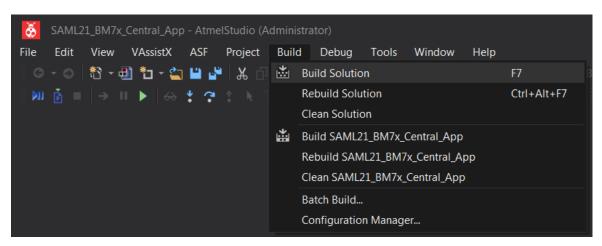
2. Select "SAML21_BM7x_Central_App.atsln" and press **Open**.



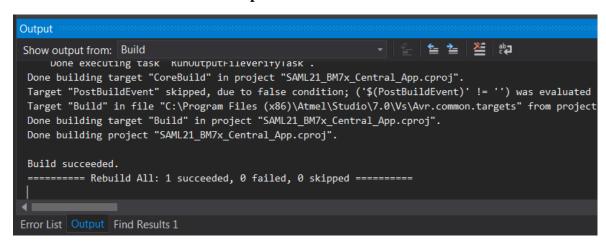
3. Once the project is opened, you can see the files attached to this project in Solution Explorer Window

2.3. Build GAP-Central Demo Application

1. Go to menu **Build** → **Build Solution** or Press **F7**



2. Build status can be checked in **Output** window

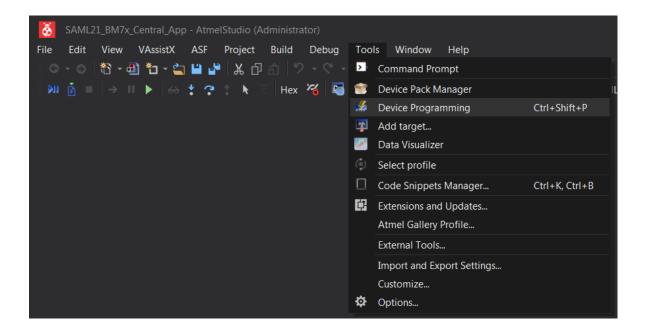


3. You can find the Hex images in "..\SAML21_BM7x_Application\Debug".

3. Programming Firmware

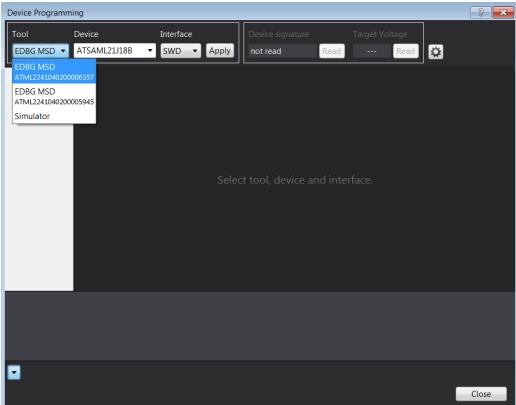
This section describes the procedure to program GAP-Central demo firmware on SAML21 Xplained Pro board.

- 1. Connect the SAML21 Xplained Pro board to the host PC using micro USB cable. Perform the following steps:
 - a. Verify that the virtual COM port is enumerated on the host PC.
 - b. Make sure that POWER LED (green) is solid ON.
- 2. To program the HEX files into the SAML21, go to menu **Tools** → **Device Programming** or Press **Ctrl** + **Shift** + **P**.

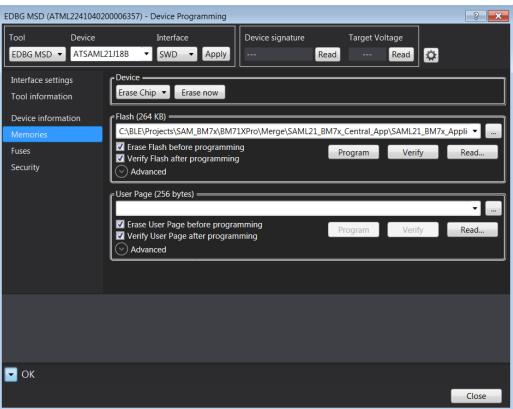


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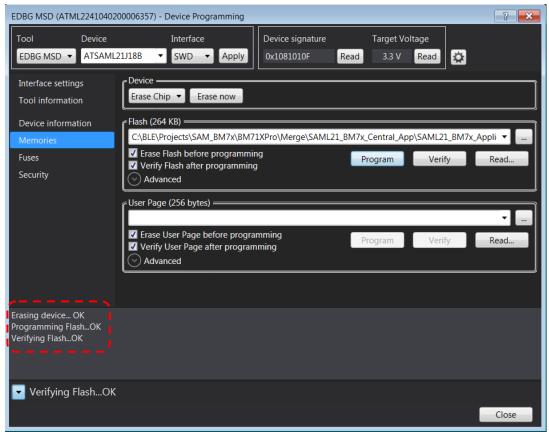
3. Select the corresponding **EDBG** and press **Apply**.



4. Go to **Memories** Tab and select Hex file.







6. Once programming is done, close the Device Programming window.

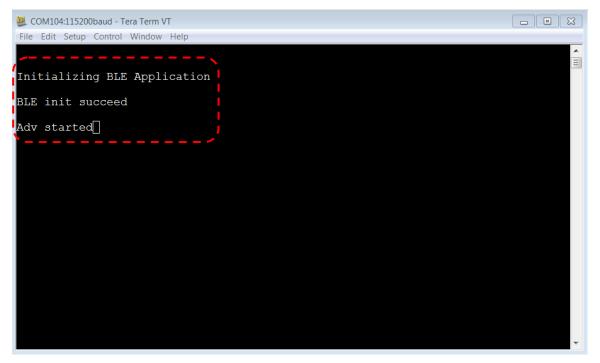
4. Running GAP-Central Demo with GAP-Peripheral Device

This section describes the GAP-Central Demo procedures to work with GAP-Peripheral device.

- 1. Connect BM71-XPro on EXT1 of SAML21 Xplained Pro board (GAP-Peripheral device).
- 2. Connect the GAP-Peripheral device to the host PC using micro USB cable. Perform the following steps:
 - a. Verify that the virtual COM port is enumerated on the host PC.
 - b. Open the enumerated COM port on a serial console application like TeraTerm with the following settings:

Baudrate	115200
Data	8 bits
Parity	none
Stop	1 bit
Flow control	none

- c. Make sure that POWER LED (green) on SAML21 Xplained Pro board is solid ON.
- d. Press Reset button on SAML21 Xplained Pro board and verify that LD4 (blue) on BM71-XPro is blinking at a regular interval.
- 3. Ensure that the GAP-Peripheral device is up and running and start advertising. Check status on a serial console application.

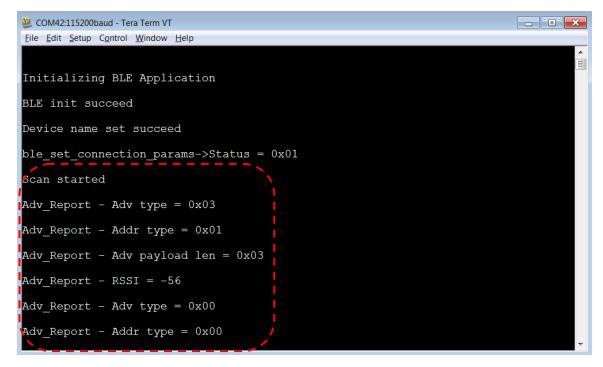


- 4. Connect BM71-XPro on EXT1 of SAML21 Xplained Pro board (GAP-Central device).
- 5. Connect the GAP-Central device to the host PC using micro USB cable. Perform the following steps:

- a. Verify that the virtual COM port is enumerated on the host PC.
- b. Open the enumerated COM port on a serial console application like TeraTerm with the following settings:

Baudrate	115200
Data	8 bits
Parity	none
Stop	1 bit
Flow control	none

- c. Make sure that POWER LED (green) on SAML21 Xplained Pro board is solid ON.
- d. Press Reset button on SAML21 Xplained Pro board and verify that LD4 (blue) on BM71-XPro is blinking at a regular interval.
- 6. Ensure GAP-Central device is up and running and start scanning. Check status on a serial console application.



- 7. As GAP-Central device receives advertisements from devices in vicinity, it prints the advertisement report in serial console.
- 8. GAP-Central device finds the suitable GAP-Peripheral device based on the advertisement payload and initiates a connection.
- 9. Once connected the GAP-Central device prints the GAP-Peripheral device address and connection parameters in serial console.

```
File Edit Setup Control Window Help

Adv_Report - RSSI = -50

Adv_Report - Adv type = 0x04

Adv_Report - Addr type = 0x00

Adv_Report - Adv payload len = 0x0D

Adv_Report - RSSI = -50

Device connected

Status = 0x00

Conn_handle = 0x81

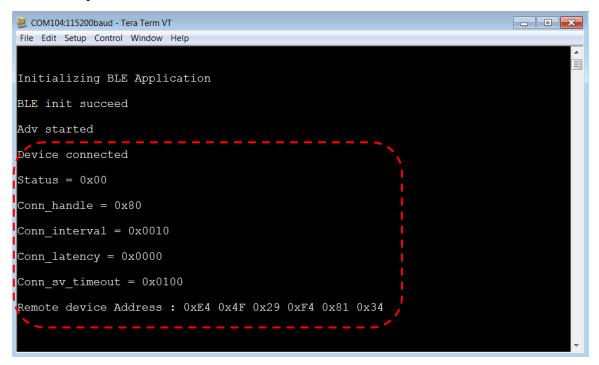
Conn_interval = 0x0010

Conn_latency = 0x0000

Conn_sv_timeout = 0x0100

Remote device Address : 0xE8 0x4F 0x29 0xF4 0x81 0x34
```

10. Similarly, once connected GAP-Peripheral device prints the GAP-Central device address and connection parameters in serial console.



11. Once connected, Multilink-Central discovers the device orientation service and characteristics in remote device based on the UUID.

```
GCOM42:115200baud - Tera Term VT

File Edit Setup Control Window Help

Adv_Report - Adv type = 0x04

Adv_Report - Adv type = 0x00

Adv_Report - Adv payload len = 0x0D

Adv_Report - RSSI = -60

Device connected

Status = 0x00

Conn_handle = 0x81

Conn_interval = 0x0010

Conn_latency = 0x0000

Conn_sv_timeout = 0x0100

Remote_device_Address : 0xE8_0x4F_0x29_0xF4_0x81_0x34_

***Discover_characteristics in sensor_service*** = 0x00
```

12. It also discovers the Client Characteristic Configuration Descriptors (CCCD) of accelerometer and gyroscope sensor characteristics and enabled them to receive notifications.

```
File Edit Setup Control Window Help

Status = 0x00

Conn_handle = 0x81

Conn_interval = 0x0010

Conn_sv_timeout = 0x0100

Remote device Address : 0xE8 0x4F 0x29 0xF4 0x81 0x34

***Discover characteristics in sensor service*** = 0x00

Conn handle = 0x81

Attrib length = 0x15

num_of_attrib = 0x02

***Acceleromoeter notification enabled status*** = 0x00
```

- 13. Upon notification enabled by GAP-Central device, GAP-Peripheral device start notifies the accelerometer and gyroscope sensor data to GAP-Central device.
- 14. GAP-Peripheral prints the accelerometer and gyroscope sensor data on serial console. It also prints notification status on serial console.

```
COM104:115200baud - Tera Term VT

File Edit Setup Control Window Help

Notification enabled!!!

Status of Accelerometer sensor data read = 0

Acce data x = -4097 || y = -27649 || z = 1796 |

Acce - value send status = 0x00

Notification enabled!!!

Status of Accelerometer sensor data read = 0

Acce data x = -3841 || y = -27649 || z = 4100

Acce - value send status = 0x00

Status of Gyroscope sensor data read = 0

Gyro data x = -1025 || y = -1793 || z = -257

Gyro - value send status = 0x00

Status of Accelerometer sensor data read = 0
```

15. GAP-Central devices receive sensor data notifications and print them on serial console.

```
COM42:115200baud - Tera Term VT

File Edit Setup Control Window Help

***Acceleromoeter notification enabled status*** = 0x00

***Gyroscope notification enabled status*** = 0x00

Acce Handle = 0x0070

Acce X = -3585

Acce Y = -27905

Acce Z = 2564

Gyro Handle = 0x0073

Gyro X = -2305

Gyro Y = -769

Gyro Z = -257

Acce Handle = 0x0070

Acce X = -3073
```

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