cv2: Library used for image processing

numpy: is the fundamental package for scientific computing with Python

argparse: Parser for command-line options, arguments and sub-commands

imutils: A series of convenience functions to make basic image processing functions such as translation, rotation, resizing, skeletonization, and displaying Matplotlib images easier with OpenCV.

neopixel and **board**: Used to control the blinking LED of the DIM bot.

time: provides functions for working with times, and for converting between representations

pyswip: is a Python - SWI-Prolog bridge enabling to query SWI-Prolog in your Python programs.

dialogflow: Dialogflow is an enterprise-grade NLU platform that makes it easy for developers to design and integrate conversational user interfaces int mobile apps, web applications, devices, and bots.

speech_recognition: Speech Recognition in Python using Google Speech API

os: provides a way of using operating system dependent functionality.

urllib3: urllib3 is a powerful, sanity-friendly HTTP client for Python.

rospy: is a pure Python client library for ROS. The rospy client API enables Python programmers to quickly interface with ROS Topics, Services, and Parameters.

std_msgs: Standard ROS Messages including common message types representing primitive data types and other basic message constructs, such as multiarrays.

Adafruit_PCA9685: This module allows you to easily write Python code that control servos and PWM with this breakout.

sys: System-specific parameters and functions. This module provides access to some variables used or maintained by the interpreter and to functions that interact strongly with the interpreter.