**cv2**: Library used for image processing

**numpy**: is the fundamental package for scientific computing with Python

**argparse**: Parser for command-line options, arguments and sub-commands

**imutils**: A series of convenience functions to make basic image processing functions such as translation, rotation, resizing, skeletonization, and displaying Matplotlib images easier with OpenCV.

**neopixel** and **board**: Used to control the blinking LED of the DIM bot.

**time**: provides functions for working with times, and for converting between representations

**pyswip**: is a Python - SWI-Prolog bridge enabling to query SWI-Prolog in your Python programs.

**dialogflow**: Dialogflow is an enterprise-grade NLU platform that makes it easy for developers to design and integrate conversational user interfaces int mobile apps, web applications, devices, and bots.

**speech\_recognition**: Speech Recognition in Python using Google Speech API

**os**: provides a way of using operating system dependent functionality.

**urllib3**: urllib3 is a powerful, sanity-friendly HTTP client for Python.

**rospy**: is a pure Python client library for ROS. The rospy client API enables Python programmers to quickly interface with ROS Topics, Services, and Parameters.

**std\_msgs**: Standard ROS Messages including common message types representing primitive data types and other basic message constructs, such as multiarrays.

**Adafruit\_PCA9685**: This module allows you to easily write Python code that control servos and PWM with this breakout.

**sys**: System-specific parameters and functions. This module provides access to some variables used or maintained by the interpreter and to functions that interact strongly with the interpreter.