

The Impact of the Open Set Recognition Problem on Deep Learning

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Benchmarks in computer vision

Assume we have examples from all classes:

Airfield



Campsite



Gas Station



Mountain



Water Park



Places2 Data Set (part of ILSVRC 2016)

Out in the real world...

Detect the cars in this image



while rejecting the trees, signs, telephone poles...

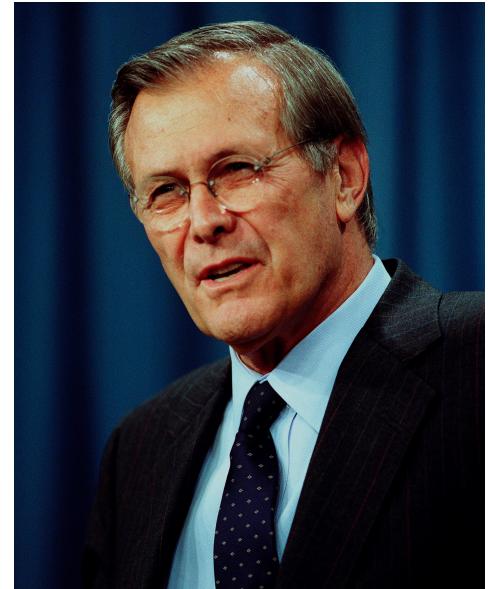
Open Set Recognition: incomplete knowledge of the world is present at training time, and unknown classes can be submitted to an algorithm during its operation.

“There are known knowns...”

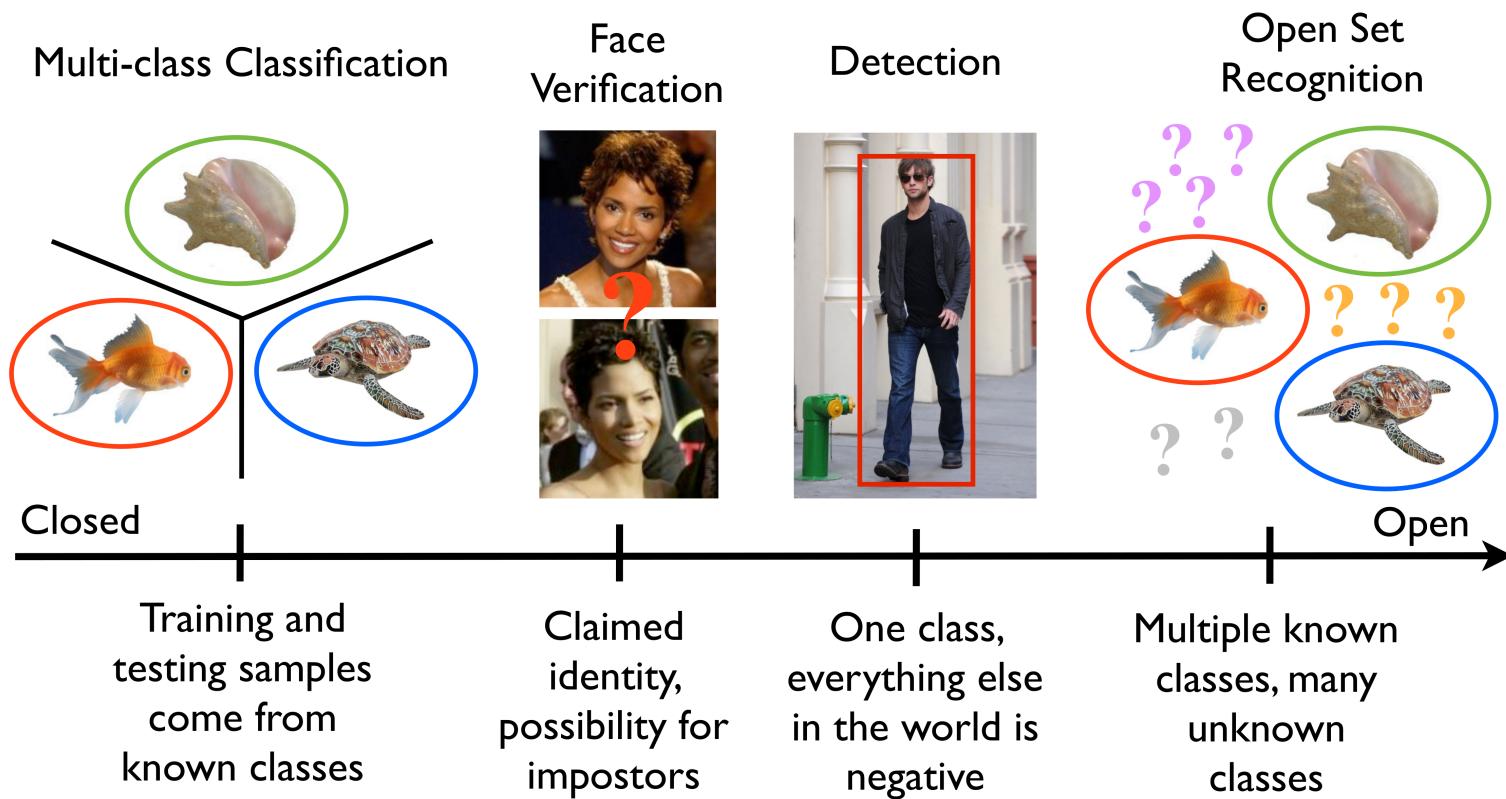
known classes: the classes with distinctly labeled positive training examples (also serving as negative examples for other known classes)

known unknown classes: labeled negative examples, not necessarily grouped into meaningful categories

unknown unknown classes: classes unseen in training



Vision problems in order of “openness”



Fundamental multi-class recognition problem

$$\operatorname{argmin}_f \left\{ R_{\mathcal{I}}(f) := \int_{\mathbb{R}^d \times \mathbb{N}} L(x, y, f(x)) P(x, y) \right\}$$

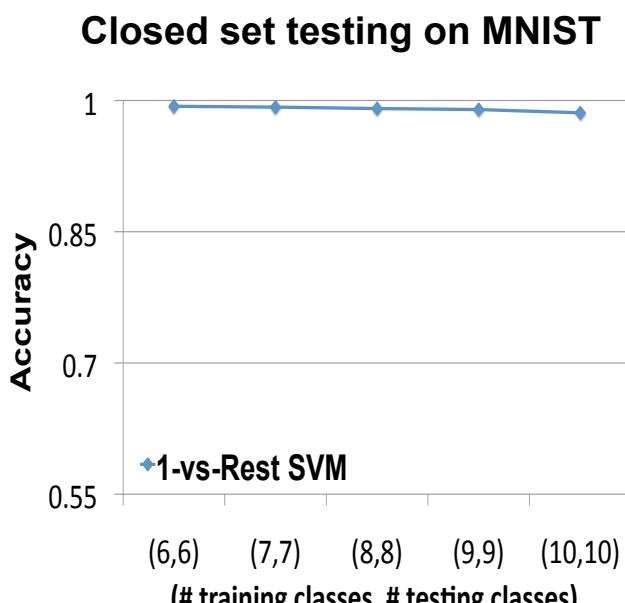
↑ ↑ ↑
Ideal Risk Loss Function Joint Distribution

**Undefined for
open set recognition!**

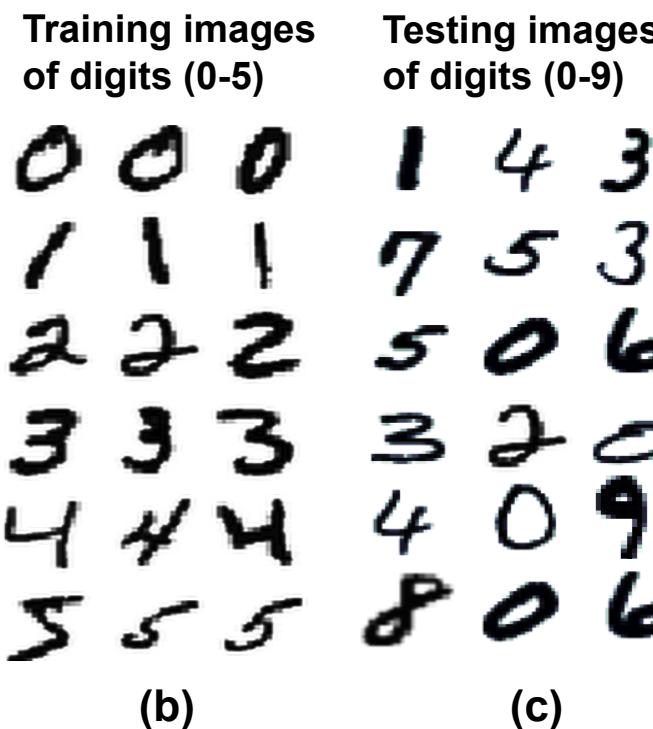
Open Space



Open Set MNIST Benchmark

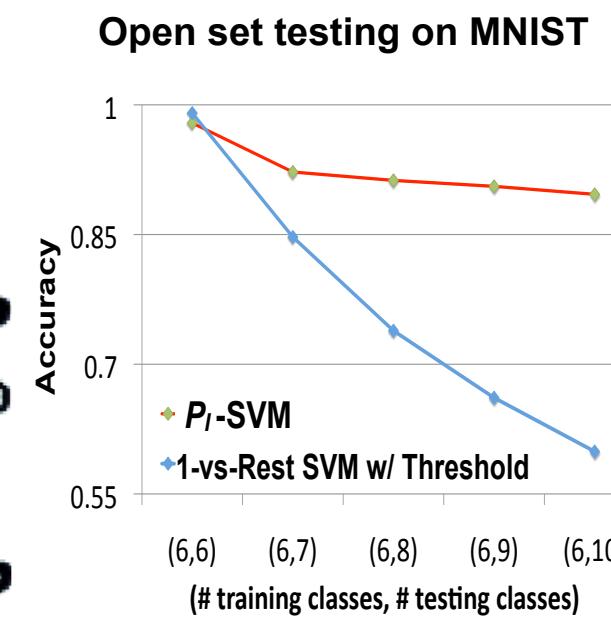


(a)



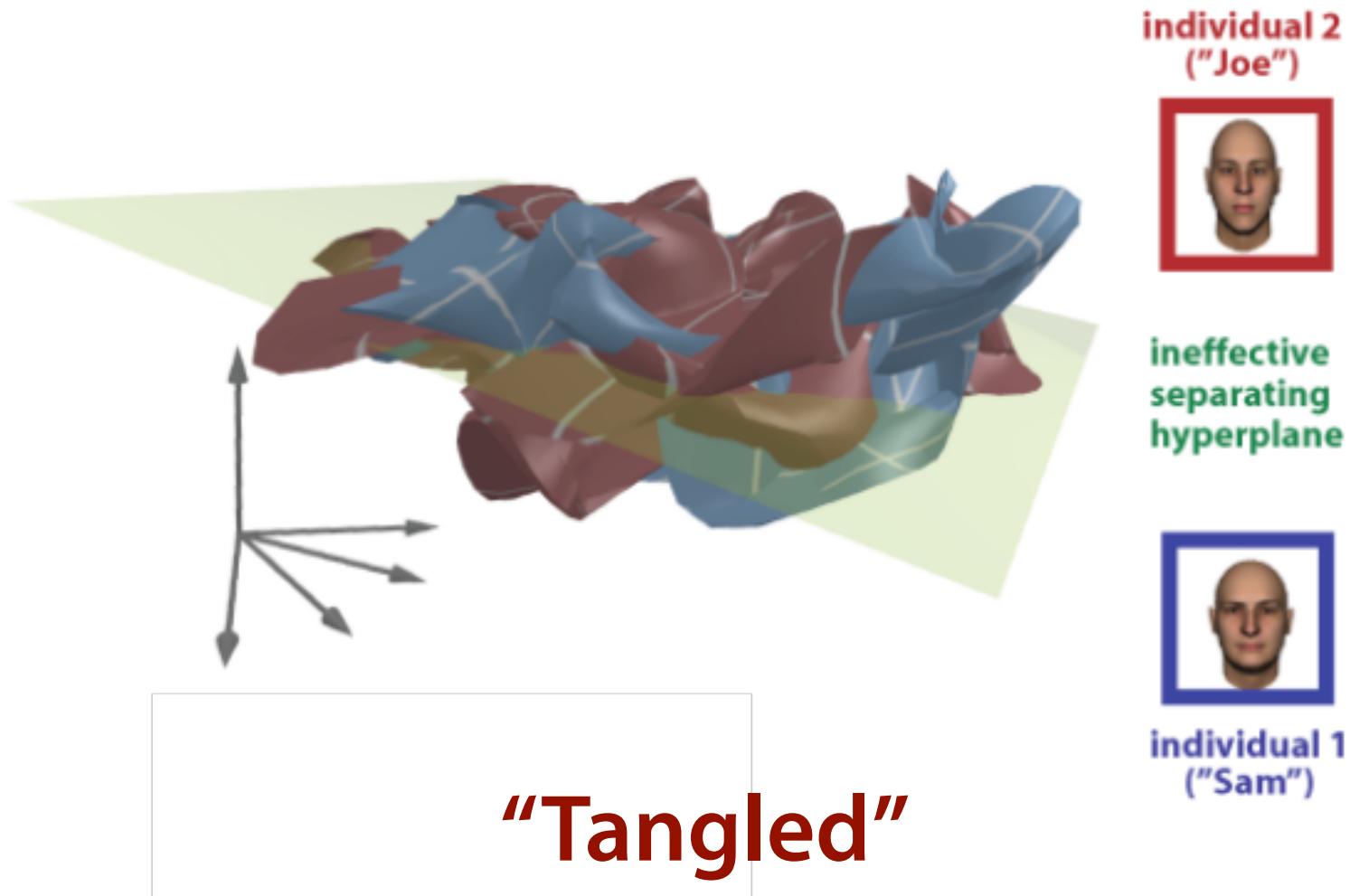
(b)

(c)

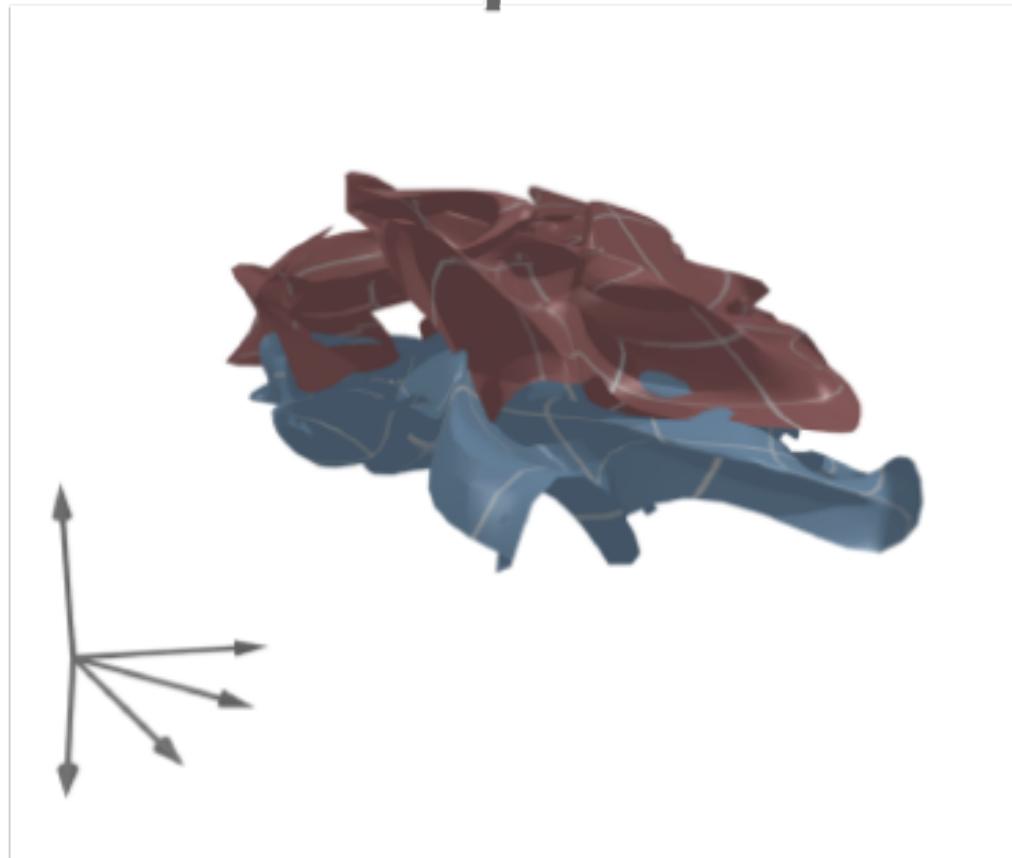


(d)

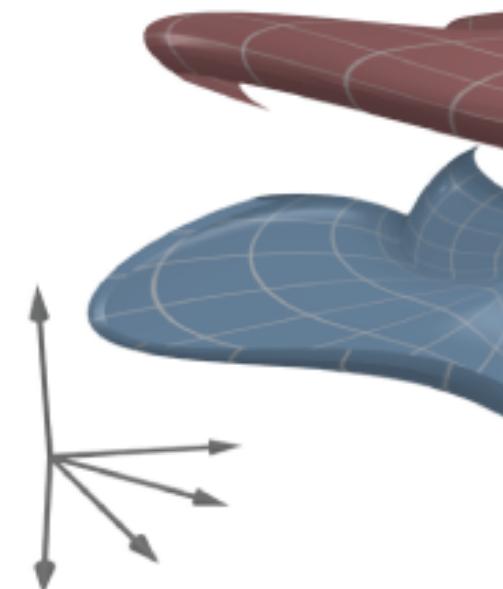
pixel space



V1 space

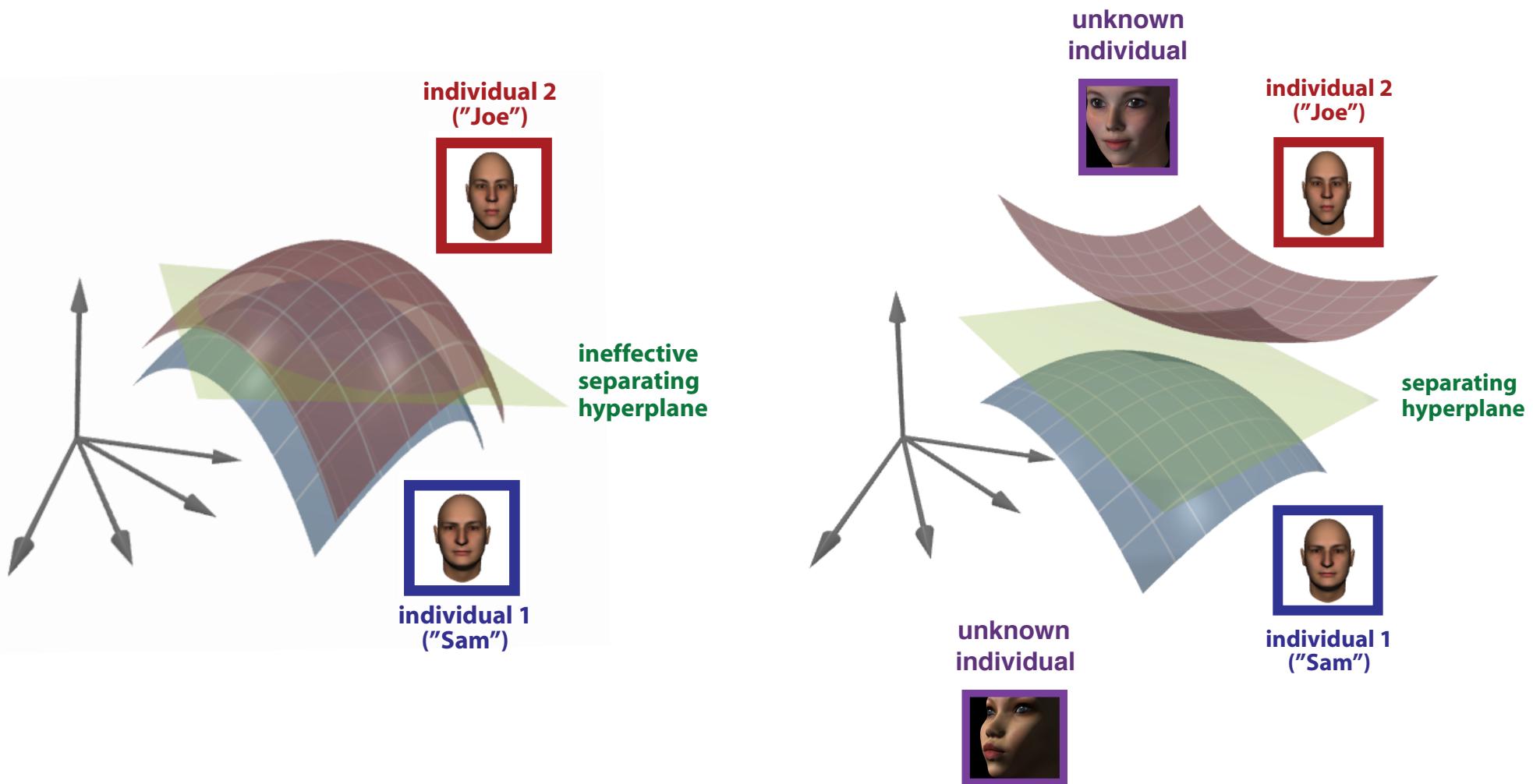


IT space

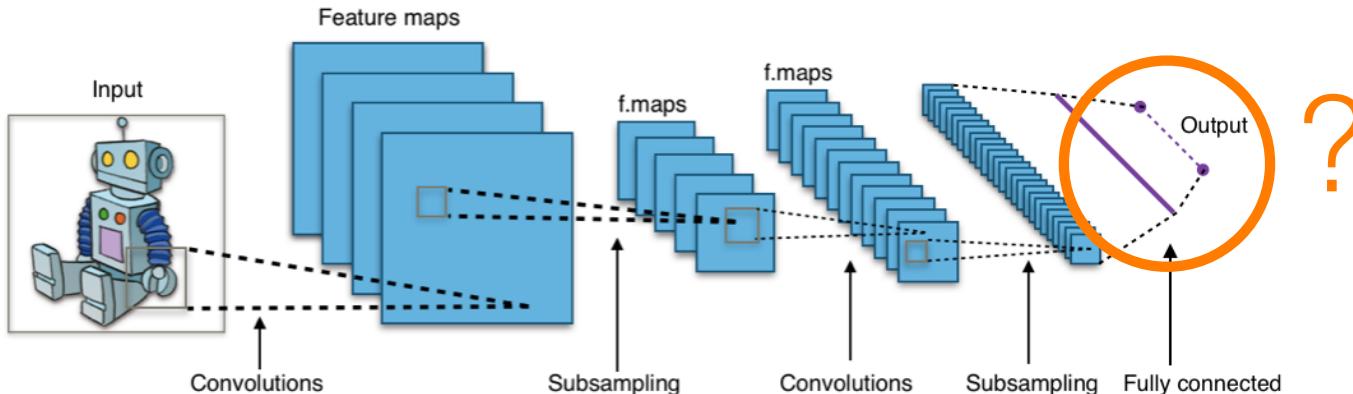


"Untangled"

Linear separation of CNN feature representations



Read-out layer



Typical CNN architecture CC BY 4.0 Aphex34

Softmax

$$P(y = j|\mathbf{x}) = \frac{e^{\mathbf{v}_j(\mathbf{x})}}{\sum_{i=1}^N e^{\mathbf{v}_i(\mathbf{x})}}$$



Sum over all of the classes

Linear SVM

$$\min \frac{1}{2} \|\mathbf{w}\|^2$$

subject to

$$y_i(\mathbf{w} * \mathbf{x}_i + b) \geq 1, \forall i$$

Known positive or negative sample

Cosine Similarity

$$\frac{\mathbf{A} \cdot \mathbf{B}}{\|\mathbf{A}\| \|\mathbf{B}\|} < \delta$$

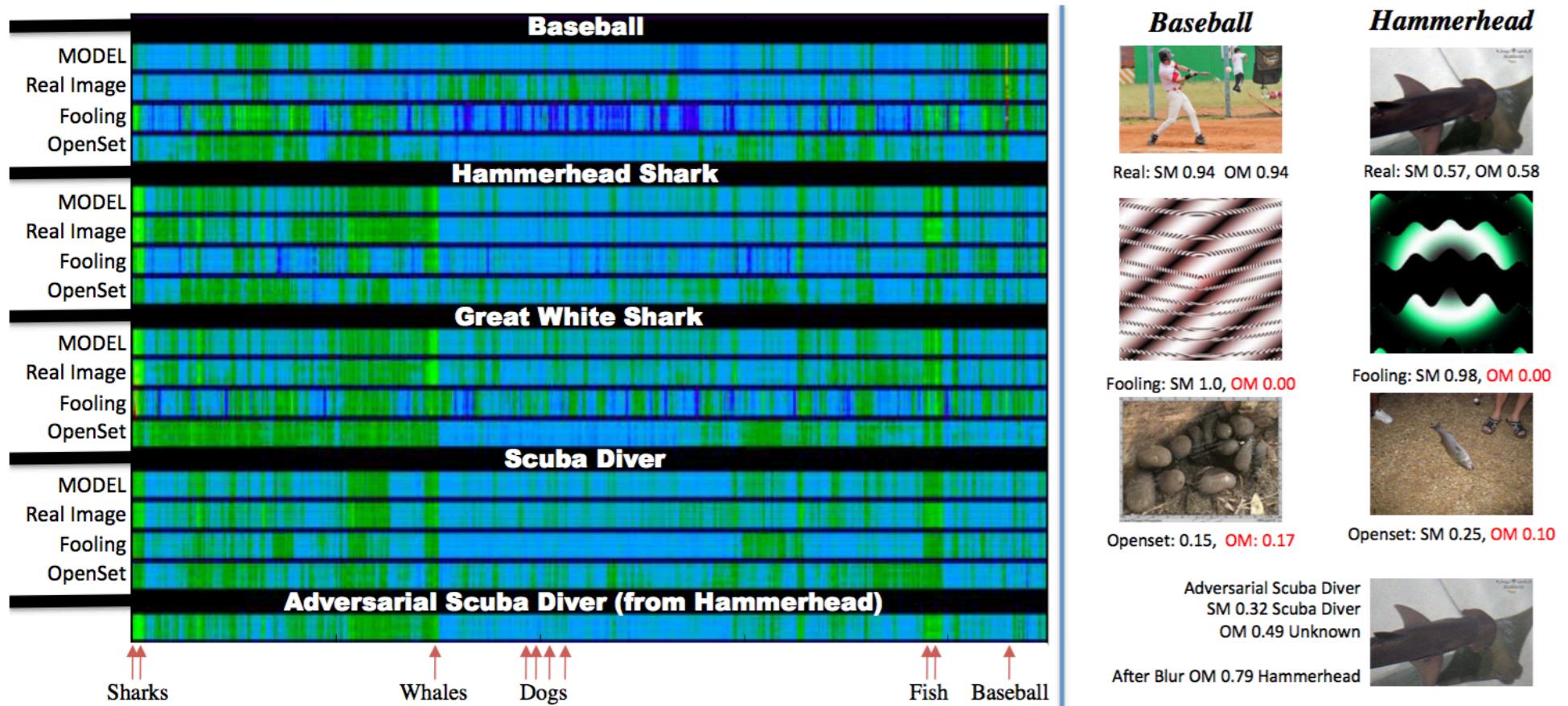


Threshold determined empirically via known pairs

Evolving images to match CNN classes



A step towards a fix: OpenMax



How does OpenMax work?

Require: Activation vector for $\mathbf{v}(\mathbf{x}) = v_1(x), \dots, v_N(x)$

Require: means μ_j and libMR models $\rho_j = (\tau_i, \lambda_i, \kappa_i)$

Require: α , the number of “top” classes to revise

1: Let $s(i) = \text{argsort}(v_j(x))$; Let $\omega_j = 1$

2: **for** $i = 1, \dots, \alpha$ **do**

3: $\omega_{s(i)}(x) = 1 - \frac{\alpha-i}{\alpha} e^{-\left(\frac{\|x-\tau_{s(i)}\|}{\lambda_{s(i)}}\right)^{\kappa_{s(i)}}}$

4: **end for**

5: Revise activation vector $\hat{v}(x) = \mathbf{v}(\mathbf{x}) \circ \omega(\mathbf{x})$

6: Define $\hat{v}_0(x) = \sum_i v_i(x)(1 - \omega_i(x)).$

7:

$$\hat{P}(y = j | \mathbf{x}) = \frac{e^{\hat{\mathbf{v}}_j(\mathbf{x})}}{\sum_{i=0}^N e^{\hat{\mathbf{v}}_i(\mathbf{x})}}$$

Apply probability models derived from statistical extreme value theory to calculate class weights

Use weights to adjust activation

8: Let $y^* = \text{argmax}_j P(y = j | \mathbf{x})$

9: Reject input if $y^* == 0$ or $P(y = y^* | \mathbf{x}) < \epsilon$

← Apply rejection threshold

But you don't have to use tricky manipulations

GoogleNet Output

Label: Hammerhead
Shark



Label: Blow Dryer



Label: Mosque



Label: Syringe



Label: Trimaran

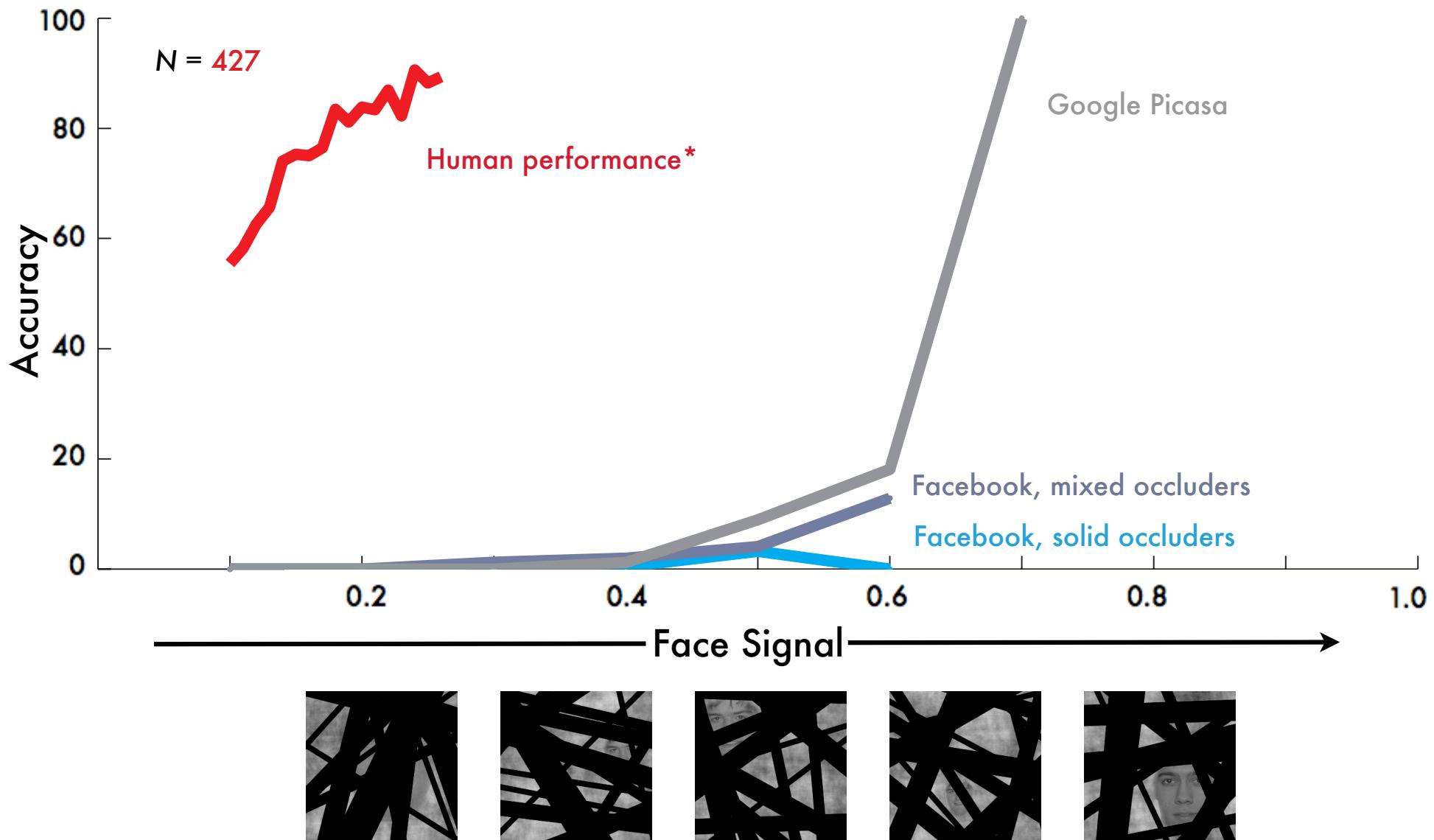


Label: Missile



Are performance measures
misleading us?

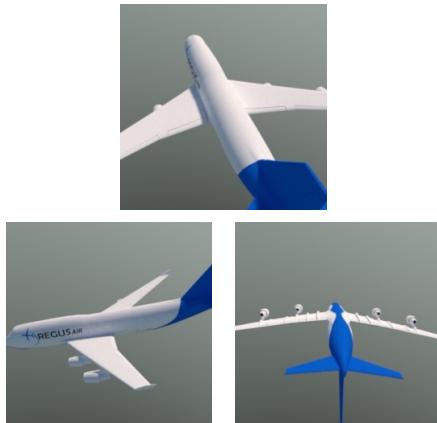
Psychophysics on the Model



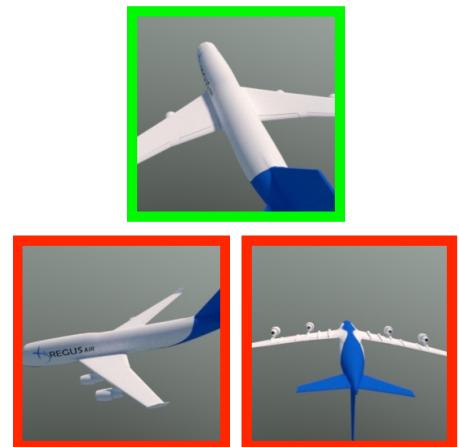
W.J. Scheirer, S. Anthony, K. Nakayama, and D. D. Cox, "Perceptual Annotation: Measuring Human Vision to Improve Computer Vision," IEEE T-PAMI, 36(8) August 2014.

Psychophysics pipeline

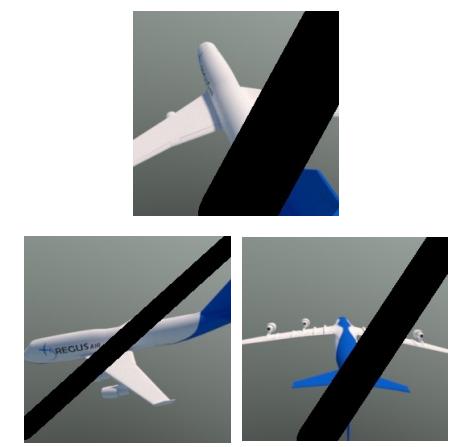
1. Render Class
Canonical View (CCV)
Candidates



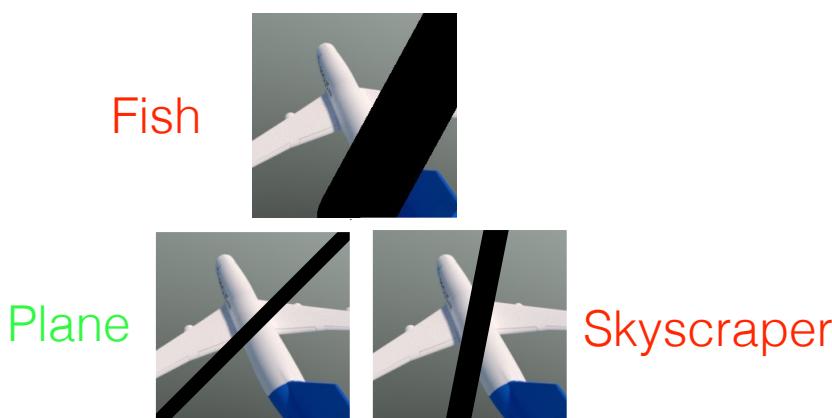
2. CCV Classifier



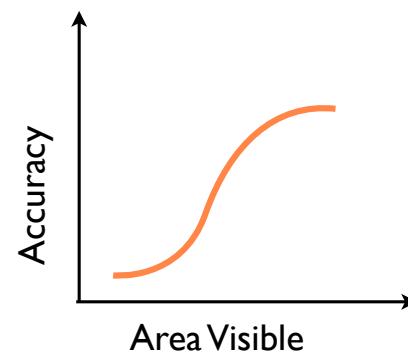
3. Manipulate Chosen
Variable



4. Classify Images

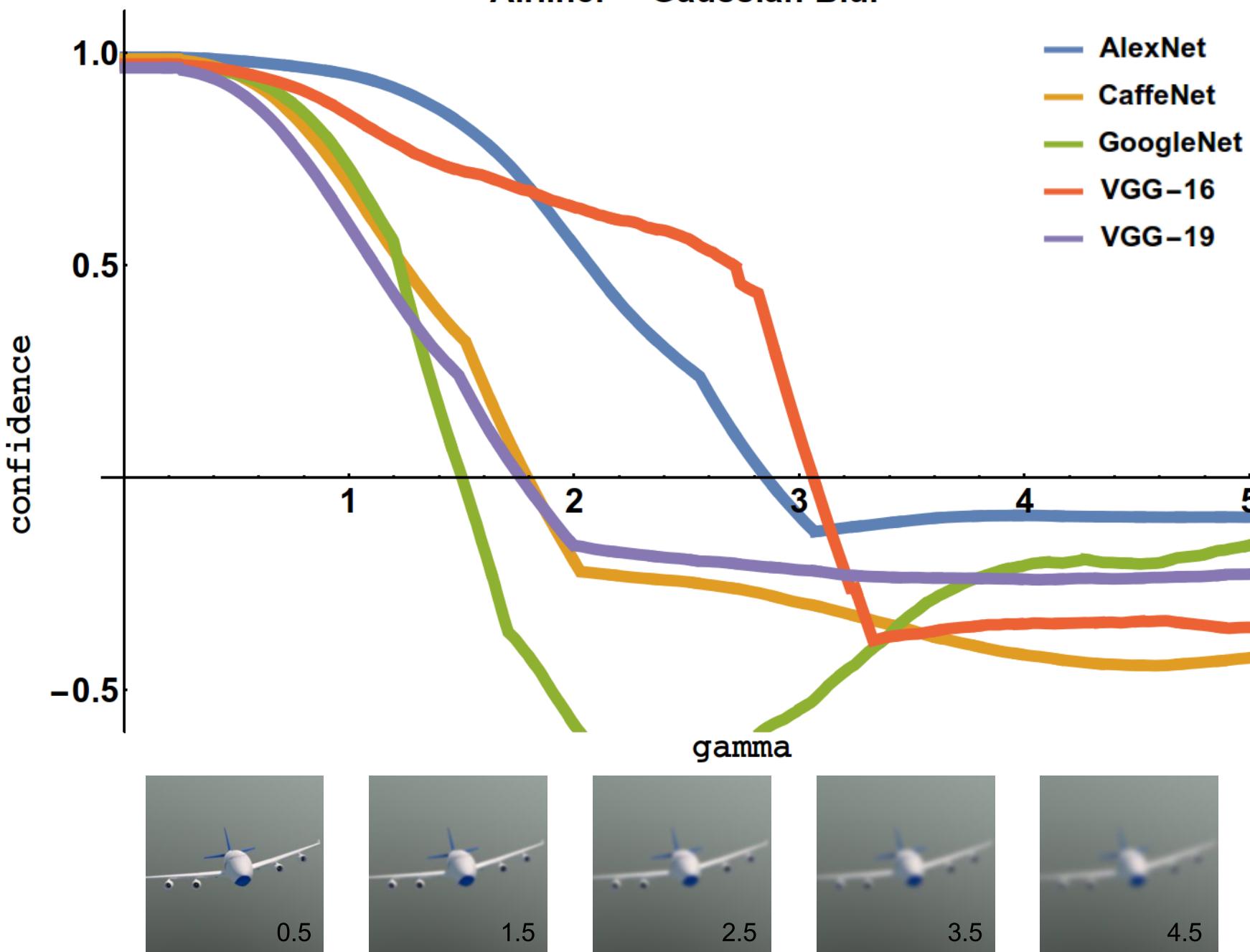


5. Generate
Psychometric Curve

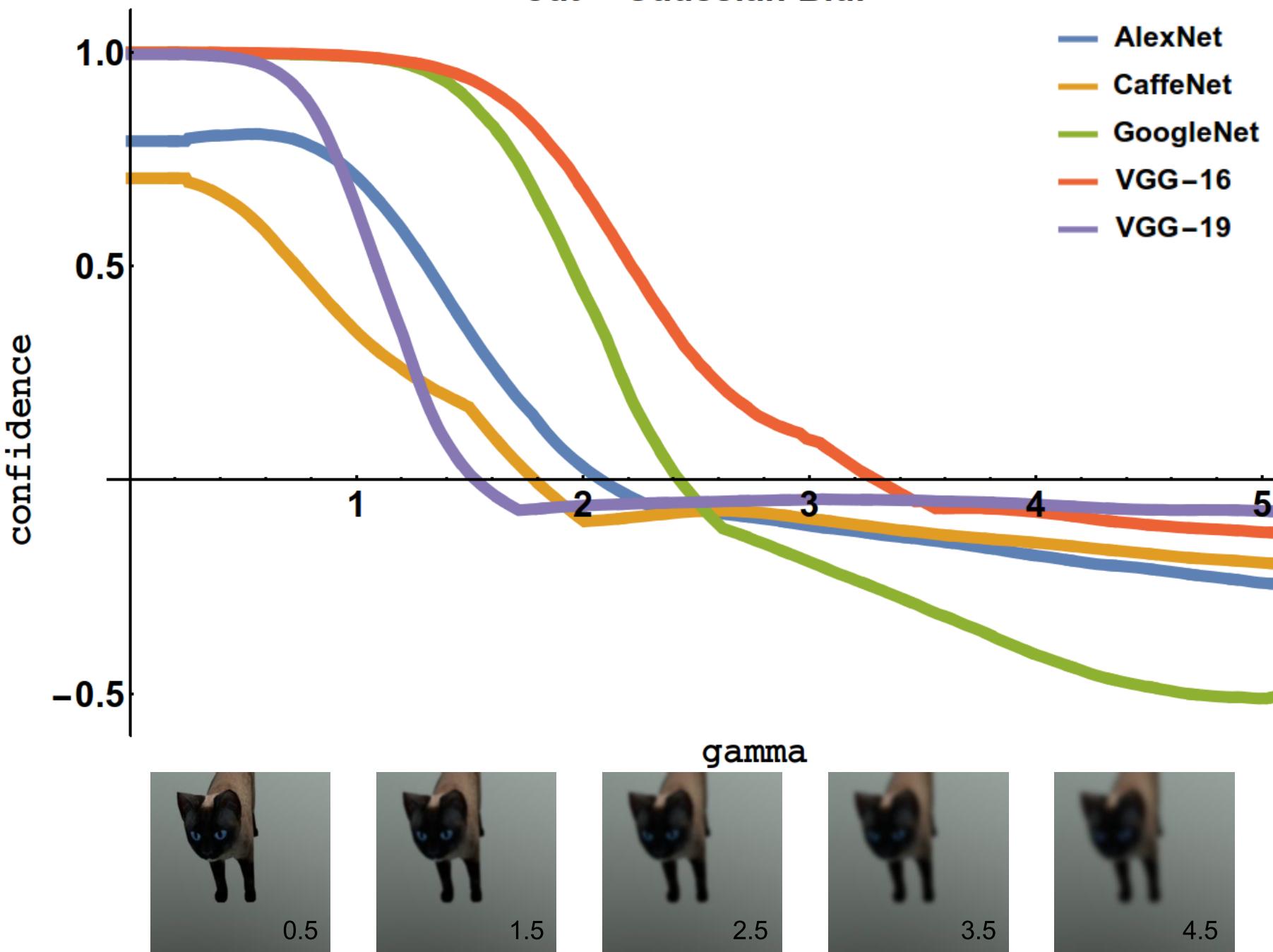


Brandon
Richard Webster

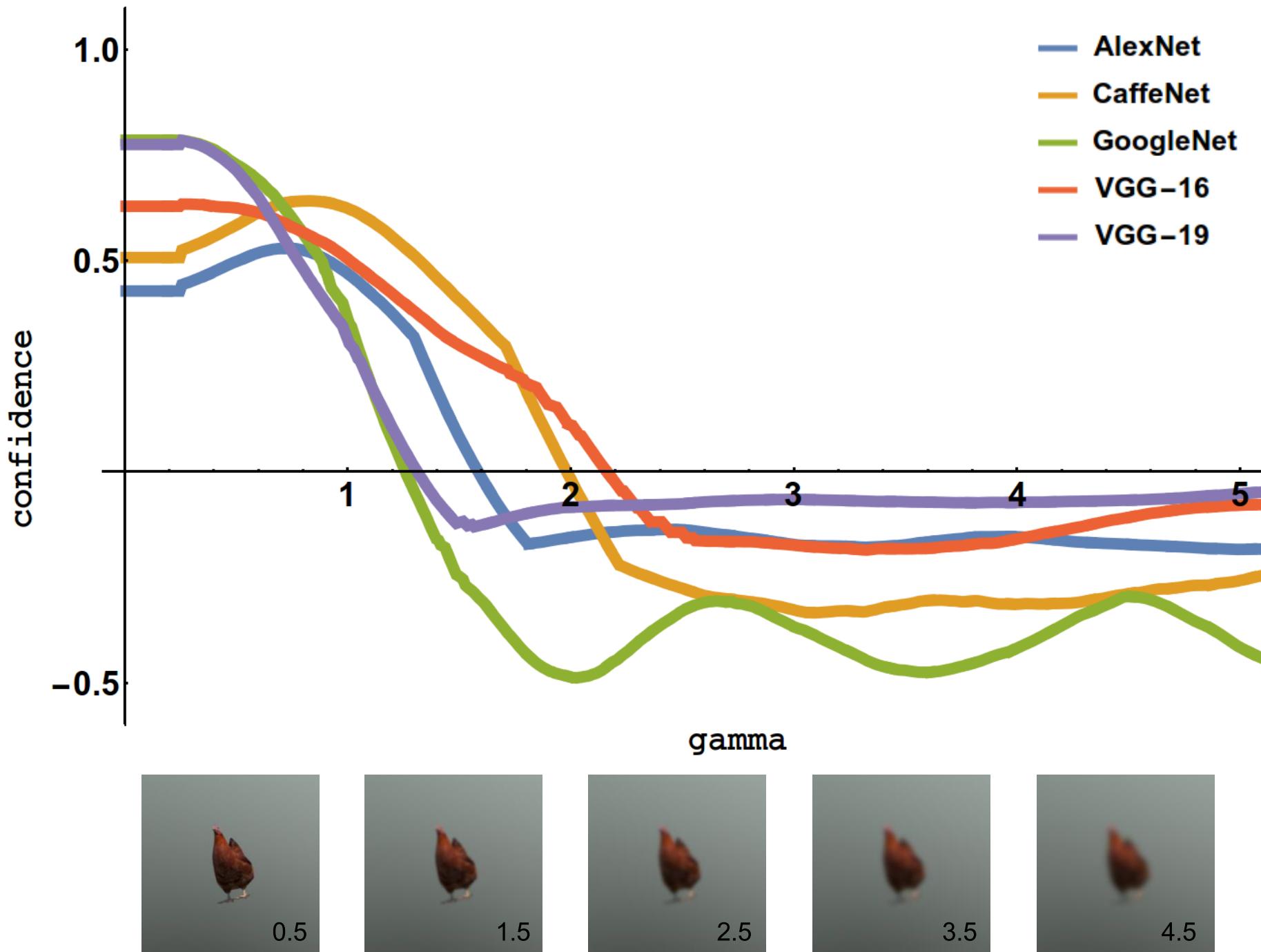
Airliner – Gaussian Blur



Cat – Gaussian Blur



Chicken – Gaussian Blur



Practical implications

FUTURE TENSE THE CITIZEN'S GUIDE TO THE FUTURE. MARCH 1 2016 12:23 PM

FROM SLATE, NEW AMERICA, AND ASU

The Trollable Self-Driving Car

Humans are pretty good at guessing what others on the road will do. Driverless cars are not—and that can be exploited.

By *Samuel English Anthony*



770 234 155

<http://goo.gl/78fglb>

Thank you!

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