

Lab Report

Course Title: Machine Learning Lab Course Code: CSE432

Project Title: Vehicle Type Classification Project

Submitted To:

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Vehicle Type Classification Project Report

i. Introduction

The advancement of computer vision and machine learning technologies has enabled the automation of complex visual tasks like vehicle type classification. This project aims to classify vehicles from images into predefined categories, leveraging two distinct approaches: traditional machine learning using Support Vector Machines (SVM) and deep learning through Convolutional Neural Networks (CNNs). The objective is to evaluate the performance of these methods in terms of accuracy, scalability, and efficiency.

ii. Dataset Description

The dataset for this project was sourced from the Kaggle repository, "Vehicle Type Recognition." It consists of diverse vehicle images, organized by type, offering a rich dataset for training and testing classification models.

- Classes: The dataset contains images categorized into various vehicle types, such as cars, trucks, and bikes.
- **Image Resolution**: Original image dimensions vary, but all were resized to 128x128 pixels.
- Size: The dataset includes approximately 400 images.
- Preprocessing:
 - Normalization: Pixel values were scaled to fall between 0 and 1.
 - Label Conversion: Labels were encoded into numerical values for machine learning and one-hot encoded for deep learning models.

iii. Methodology

Data Preprocessing:

- 1. Resized all images to 128x128 pixels to ensure uniform input dimensions.
- 2. Normalized pixel intensity values to improve model convergence.
- 3. Divided the dataset into an 80:20 training-to-testing ratio.
- 4. Converted labels into numerical or categorical representations for compatibility with respective models.

Traditional Machine Learning (SVM)

- Feature Extraction: Flattened images into one-dimensional arrays to serve as input features.
- **Model**: Implemented an SVM classifier with a linear kernel.
- Training: The SVM model was trained on flattened feature vectors, optimizing for classification boundaries.

Deep Learning (CNN)

CNN Architecture:

- o **Input Layer**: Accepts resized RGB images of shape 128x128x3.
- Convolutional Layers: Applied 32 and 64 filters in two layers, each followed by ReLU activation.
- Pooling Layers: Used MaxPooling to downsample feature maps and reduce spatial dimensions.
- Fully Connected Layers: Integrated dense layers with 128 neurons and ReLU activation, culminating in a softmax output layer for multi-class classification.
- Augmentation: Employed techniques like rotation, shift, and flipping to increase training data diversity.
- Optimization: Used Adam optimizer with categorical cross-entropy loss for training over 10 epochs.

iv. Code

```
y
<sub>26a</sub> [1] from google.colab import drive
       drive.mount('/content/drive')

→ Mounted at /content/drive

import os
       import cv2
        import numpy as np
        from sklearn.model_selection import train_test_split
        from sklearn.svm import SVC
        from sklearn.metrics import classification_report
        from tensorflow.keras.models import Sequential
        from tensorflow.keras.layers import Conv2D, MaxPooling2D, Flatten, Dense
        from tensorflow.keras.utils import to_categorical
        from tensorflow.keras.preprocessing.image import ImageDataGenerator
        # Path to dataset
        DATASET_DIR = '/content/drive/MyDrive/7A/Machine Learning Lab/Dataset'
        # Load dataset
        def load_images_and_labels(dataset_dir):
           images = []
            labels = []
            label map = \{\}
            for label, category in enumerate(os.listdir(dataset_dir)):
               label_map[label] = category
                category_dir = os.path.join(dataset_dir, category)
                for file in os.listdir(category_dir):
                   img_path = os.path.join(category_dir, file)
                    img = cv2.imread(img_path)
                    if img is not None:
                        img = cv2.resize(img, (128, 128)) # Resize images to 128x128
                        images.append(img)
                        labels.append(label)
            return np.array(images), np.array(labels), label_map
        images, labels, label_map = load_images_and_labels(DATASET_DIR)
        # Normalize images
        images = images / 255.0
        # Train-test split
        X_train, X_test, y_train, y_test = train_test_split(images, labels, test_size=0.2, random_state=42)
        # Convert labels to categorical for CNN
        y_train_categorical = to_categorical(y_train)
        y_test_categorical = to_categorical(y_test)
        # 1. Conventional Classification
        def extract_features(images):
            return images.reshape(len(images), -1) # Flatten images
```

```
X_train_flat = extract_features(X_train)
X_test_flat = extract_features(X_test)
svm = SVC(kernel='linear')
svm.fit(X_train_flat, y_train)
y_pred_svm = svm.predict(X_test_flat)
print("SVM Classification Report:")
print(classification_report(y_test, y_pred_svm, target_names=label_map.values()))
# 2. CNN Model
cnn_model = Sequential([
   Conv2D(32, (3, 3), activation='relu', input_shape=(128, 128, 3)),
    MaxPooling2D((2, 2)),
   Conv2D(64, (3, 3), activation='relu'),
   MaxPooling2D((2, 2)),
   Flatten(),
   Dense(128, activation='relu'),
   Dense(len(label_map), activation='softmax')
1)
cnn_model.compile(optimizer='adam', loss='categorical_crossentropy', metrics=['accuracy'])
# Data augmentation
datagen = ImageDataGenerator(rotation_range=15, width_shift_range=0.1, height_shift_range=0.1, horizontal_flip=True)
datagen.fit(X_train)
cnn_model.fit(datagen.flow(X_train, y_train_categorical, batch_size=32),
              validation_data=(X_test, y_test_categorical), epochs=10)
# Evaluate CNN
cnn_loss, cnn_accuracy = cnn_model.evaluate(X_test, y_test_categorical)
print(f"CNN Accuracy: {cnn_accuracy * 100:.2f}%")
```

```
→ SVM Classification Report:
                                recall f1-score support
                                  0.69
      motorcycle
                                             0.65
                        0 45
                                   0 50
                                             a 47
                                                          18
                                             0.48
0.47
                                                          18
18
           Truck
        accuracy
                                             0.54
                                                          80
                        0.53
0.54
                                  0.52
0.54
    macro avg
weighted avg
                                              0.52
    /usr/local/lib/python3.10/dist-packages/keras/src/layers/convolutional/base_conv.py:107: Userwarning: Do not pass an `input_shape`/`input_dim` argument to a layer. When super().__init__(activity_regularizer=activity_regularizer, **kwargs)

Epoch 1/10
     /usr/local/lib/python3.10/dist-packages/keras/src/trainers/data_adapters/py_dataset_adapter.py:122: UserWarning: Your `PyDataset` class should call `super().__init__(**
      10/10 -----
Epoch 2/10
                              — 20s 983ms/step - accuracy: 0.2875 - loss: 1.3769 - val accuracy: 0.3625 - val loss: 1.3249
     10/10 -
     Epoch 3/10
    10/10 ----
Epoch 4/10
                              -- 10s 778ms/step - accuracy: 0.3072 - loss: 1.3439 - val_accuracy: 0.4375 - val_loss: 1.1971
                              - 11s 1s/step - accuracy: 0.4395 - loss: 1.2019 - val_accuracy: 0.5500 - val_loss: 1.0491
     10/10 -
     Epoch 5/10
     10/10
                              -- 12s 1s/step - accuracy: 0.5530 - loss: 1.0706 - val_accuracy: 0.6125 - val_loss: 0.8640
                              - 20s 1s/step - accuracy: 0.5756 - loss: 1.0185 - val_accuracy: 0.6250 - val_loss: 0.9002
     10/10 -
     Epoch 7/10
     10/10
                              -- 19s 766ms/step - accuracy: 0.6016 - loss: 0.9400 - val_accuracy: 0.6375 - val_loss: 0.9038
     Epoch 8/10
                              - 12s 980ms/step - accuracy: 0.5715 - loss: 0.9543 - val accuracy: 0.7250 - val loss: 0.7114
     10/10
     Epoch 9/10
     10/10

    18s 765ms/step - accuracy: 0.6678 - loss: 0.8094 - val_accuracy: 0.7250 - val_loss: 0.7023

     Epoch 10/10
                            —— 13s 908ms/step - accuracy: 0.7180 - loss: 0.7691 - val_accuracy: 0.7250 - val_loss: 0.7560
— 1s 139ms/step - accuracy: 0.7297 - loss: 0.7643
    CNN Accuracy: 72.50%
```

v. Results and Discussion

SVM Results:

- Accuracy: Achieved an accuracy of approximately 53.75%.
- Analysis: The SVM model's performance was hindered by the flattened representation of image data, which fails to capture spatial relationships critical for classification tasks.

CNN Results:

- Accuracy: Achieved an accuracy of approximately 72.50%.
- Key Insights:
 - Validation loss stabilized within 10 epochs, reflecting effective training.
 - Hierarchical feature extraction by CNN layers enabled superior classification performance.

Comparison Table:

Metric	SVM	CNN
Accuracy	53.75%	72.50%
Training Time	Low	High
Feature Design	Manual	Automatic

v. Conclusion

This project successfully demonstrated the strengths and limitations of conventional and deep learning techniques in vehicle type classification. While the SVM provided baseline performance, the CNN significantly outperformed it due to its ability to learn complex spatial features from images.

Future enhancements could include employing transfer learning with pretrained models like ResNet or VGG for improved accuracy and efficiency. Additionally, deploying the model in real-world scenarios can help evaluate its reliability and scalability.