



Advanced Control

MECH70026

Manab Shrestha

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Chapter 1

Analogue Control Systems

1.1 Mathematical Modelling Signals and Linear Dynamic Systems

1.1.1 System Models Using Differential Equations

1.1.2 Signal Representation in the Frequency Domain and Transfer Functions

1.2 Frequency Response Analysis and Design

1.2.1 System Models Using Differential Equations

1.2.2 Signal Representation in the Frequency Domain and Transfer Functions

1.2.3 Bode Diagrams

1.2.4 Design of Compensation

1.3 Complex Frequency Analysis and Design

1.3.1 Laplace Transforms and Complex Frequency Concepts

1.3.2 Signal Representation in the Frequency Domain and Transfer Functions

1.3.3 Root Locus Design Method

Chapter 2

Digital Control Systems

2.1 Design of a Digital Controller Using Continuous System Theory: CNC Controller Case Study

2.1.1 CNC System Modelling

2.1.2 CNC Controller Design for Transients, Disturbance Rejection and Multi-Axis Contouring

2.1.3 Effects of Sampling

2.2 Discrete System Analysis Using Z-Transforms

2.2.1 Z-Transforms of Sampled Data Signals, Modified Z-Transforms and Fractional Time Delays

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Chapter 3

Introduction to State Variable Analysis

3.1 State Variable Analysis of Continuous Systems

3.1.1 State Variable Modelling in Relation to Block Diagrams

3.1.2 Eigenvalues, Eigenvectors and Characteristic Equation, Stability of State Variable Models

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3.3 Non-examinable Material

3.3.1 Kalman Filtering

3.3.2 Optimal Control

Random Examples

Definition 3.3.1: Limit of Sequence in \mathbb{R}

Let $\{s_n\}$ be a sequence in \mathbb{R} . We say

$$\lim_{n \rightarrow \infty} s_n = s$$

where $s \in \mathbb{R}$ if \forall real numbers $\epsilon > 0 \exists$ natural number N such that for $n > N$

$$s - \epsilon < s_n < s + \epsilon \text{ i.e. } |s - s_n| < \epsilon$$

Question 1

Is the set $x\text{-axis} \setminus \{\text{Origin}\}$ a closed set

Solution: We have to take its complement and check whether that set is a open set i.e. if it is a union of open balls

Note:-

We will do topology in Normed Linear Space (Mainly \mathbb{R}^n and occasionally \mathbb{C}^n) using the language of Metric Space

Claim 3.3.1 Topology

Topology is cool

Example 3.3.1 (Open Set and Close Set)

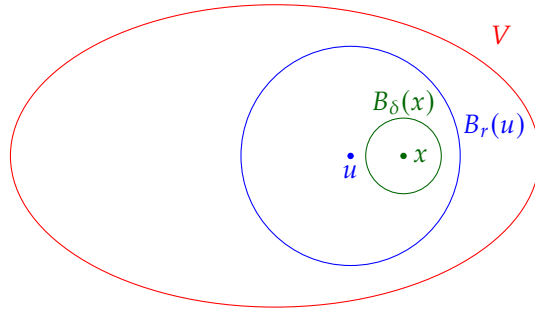
- Open Set:
- ϕ
 - $\bigcup_{x \in X} B_r(x)$ (Any $r > 0$ will do)

- Closed Set:
- X, ϕ
 - $\overline{B_r(x)}$
- $x\text{-axis} \cup y\text{-axis}$

Theorem 3.3.1

If $x \in$ open set V then $\exists \delta > 0$ such that $B_\delta(x) \subset V$

Proof: By openness of V , $x \in B_r(u) \subset V$



Given $x \in B_r(u) \subset V$, we want $\delta > 0$ such that $x \in B_\delta(x) \subset B_r(u) \subset V$. Let $d = d(u, x)$. Choose δ such that $d + \delta < r$ (e.g. $\delta < \frac{r-d}{2}$)

If $y \in B_\delta(x)$ we will be done by showing that $d(u, y) < r$ but

$$d(u, y) \leq d(u, x) + d(x, y) < d + \delta < r$$

☺

Corollary 3.3.1

By the result of the proof, we can then show...

Lemma 3.3.1

Suppose $\vec{v}_1, \dots, \vec{v}_n \in \mathbb{R}^n$ is subspace of \mathbb{R}^n .

Proposition 3.3.1

$1 + 1 = 2$.

Random

Definition 3.3.2: Normed Linear Space and Norm $\|\cdot\|$

Let V be a vector space over \mathbb{R} (or \mathbb{C}). A norm on V is function $\|\cdot\| : V \rightarrow \mathbb{R}_{\geq 0}$ satisfying

- ① $\|x\| = 0 \iff x = 0 \forall x \in V$
- ② $\|\lambda x\| = |\lambda| \|x\| \forall \lambda \in \mathbb{R}(\text{or } \mathbb{C}), x \in V$
- ③ $\|x + y\| \leq \|x\| + \|y\| \forall x, y \in V$ (Triangle Inequality/Subadditivity)

And V is called a normed linear space.

• Same definition works with V a vector space over \mathbb{C} (again $\|\cdot\| \rightarrow \mathbb{R}_{\geq 0}$) where ② becomes $\|\lambda x\| = |\lambda| \|x\| \forall \lambda \in \mathbb{C}, x \in V$, where for $\lambda = a + ib, |\lambda| = \sqrt{a^2 + b^2}$

Example 3.3.2 (p -Norm)

$V = \mathbb{R}^m, p \in \mathbb{R}_{\geq 0}$. Define for $x = (x_1, x_2, \dots, x_m) \in \mathbb{R}^m$

$$\|x\|_p = \left(|x_1|^p + |x_2|^p + \dots + |x_m|^p \right)^{\frac{1}{p}}$$

(In school $p = 2$)

Special Case $p = 1$: $\|x\|_1 = |x_1| + |x_2| + \dots + |x_m|$ is clearly a norm by usual triangle inequality.

Special Case $p \rightarrow \infty$ (\mathbb{R}^m with $\|\cdot\|_\infty$): $\|x\|_\infty = \max\{|x_1|, |x_2|, \dots, |x_m|\}$

For $m = 1$ these p -norms are nothing but $|x|$. Now exercise

Question 2

Prove that triangle inequality is true if $p \geq 1$ for p -norms. (What goes wrong for $p < 1$?)

Solution: For Property ③ for norm-2

When field is \mathbb{R} :

We have to show

$$\begin{aligned}\sum_i (x_i + y_i)^2 &\leq \left(\sqrt{\sum_i x_i^2} + \sqrt{\sum_i y_i^2} \right)^2 \\ \Rightarrow \sum_i (x_i^2 + 2x_i y_i + y_i^2) &\leq \sum_i x_i^2 + 2\sqrt{\left[\sum_i x_i^2 \right] \left[\sum_i y_i^2 \right]} + \sum_i y_i^2 \\ \Rightarrow \left[\sum_i x_i y_i \right]^2 &\leq \left[\sum_i x_i^2 \right] \left[\sum_i y_i^2 \right]\end{aligned}$$

So in other words prove $\langle x, y \rangle^2 \leq \langle x, x \rangle \langle y, y \rangle$ where

$$\langle x, y \rangle = \sum_i x_i y_i$$

Note:-

- $\|x\|^2 = \langle x, x \rangle$
- $\langle x, y \rangle = \langle y, x \rangle$
- $\langle \cdot, \cdot \rangle$ is \mathbb{R} -linear in each slot i.e.

$$\langle rx + x', y \rangle = r\langle x, y \rangle + \langle x', y \rangle \text{ and similarly for second slot}$$

Here in $\langle x, y \rangle$ x is in first slot and y is in second slot.

Now the statement is just the Cauchy-Schwartz Inequality. For proof

$$\langle x, y \rangle^2 \leq \langle x, x \rangle \langle y, y \rangle$$

expand everything of $\langle x - \lambda y, x - \lambda y \rangle$ which is going to give a quadratic equation in variable λ

$$\begin{aligned}\langle x - \lambda y, x - \lambda y \rangle &= \langle x, x - \lambda y \rangle - \lambda \langle y, x - \lambda y \rangle \\ &= \langle x, x \rangle - \lambda \langle x, y \rangle - \lambda \langle y, x \rangle + \lambda^2 \langle y, y \rangle \\ &= \langle x, x \rangle - 2\lambda \langle x, y \rangle + \lambda^2 \langle y, y \rangle\end{aligned}$$

Now unless $x = \lambda y$ we have $\langle x - \lambda y, x - \lambda y \rangle > 0$ Hence the quadratic equation has no root therefore the discriminant is greater than zero.

When field is \mathbb{C} :

Modify the definition by

$$\langle x, y \rangle = \sum_i \bar{x}_i y_i$$

Then we still have $\langle x, x \rangle \geq 0$

Algorithms

Algorithm 1: what

Input: This is some input

Output: This is some output

/ This is a comment */*

```
1 some code here;
2  $x \leftarrow 0$ ;
3  $y \leftarrow 0$ ;
4 if  $x > 5$  then
5   |  $x$  is greater than 5 ;                                // This is also a comment
6 else
7   |  $x$  is less than or equal to 5;
8 end
9 foreach  $y$  in 0..5 do
10  |  $y \leftarrow y + 1$ ;
11 end
12 for  $y$  in 0..5 do
13  |  $y \leftarrow y - 1$ ;
14 end
15 while  $x > 5$  do
16  |  $x \leftarrow x - 1$ ;
17 end
18 return Return something here;
```
