Short-Step Interior Point Algorithm A Primal Barrier Newton-Iteration Technique

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Overview

The proof outlined in the next slides will depend on several important steps:

- Self-concordant local analogues for strong convexity and Lipschitz hessian properties.
- Bound self-concordant function deviation from its quadratic approximation.
- Bound the magnitude of a Newton step as a function of the magnitude of the previous step.
- Bound for the distance to the minimizer as a function of the magnitude of the Newton step.
- Define a set of barrier parameters that will convergence to the optimal.

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Definitions

$$H(x) := \text{hessian evaluated at } x$$

Definition 1 (Intrinsic Inner Product)

The intrinsic inner product over a function f, denoted $\langle \cdot, \cdot \rangle_{\times}$, is the weighted inner product, such that

$$\langle u, v \rangle_{x} = \langle u, H(x)v \rangle$$

Definition 2 (Induced Norm)

The induced norm, denoted $\|\cdot\|_{x}$, represents the norm induced by the intrinsic inner product,

$$||v||_x = ||v||_{H(x)} = \langle v, H(x)v \rangle$$

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Self-Concordant Functions

 D_f : open convex set (i.e. $\{x > 0\}$)

 $B_x(y,r)$: open ball of radius r, centered at y, measured with $\|\cdot\|_x$

Definition 3 (Self-Concordance)

A function, f, is said to be self-concordant if for all $x \in D_f$ we have that $B_x(x,1) \subseteq D_f$ and if $\forall y \in B_x(x,1)$ we have,

$$1 - \|y - x\|_{x} \le \frac{\|v\|_{y}}{\|v\|_{x}} \le \frac{1}{1 - \|y - x\|_{x}}$$

Hessian Bound L

$$H_{\mathsf{x}}(y) = H(\mathsf{x})^{-1}H(y)$$

Theorem 4

Assume that the function f has the property that $B_x(x,1) \subseteq D_f$ for all $x \in D_f$. Then f is self-concordant iff for all $x \in D_f$ and $y \in B_x(x,1)$,

$$||H_{x}(y)||_{x}, ||H_{x}(y)^{-1}||_{x} \le \frac{1}{(1-||y-x||)^{2}}$$
 (1)

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and likewise iff.

$$||I - H_x(y)||_x, ||I - H_x(y)^{-1}||_x \le \frac{1}{(1 - ||y - x||_x)^2} - 1$$
 (2)

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Hessian Bound II

proof. Let $\lambda_1 \leq \ldots \leq \lambda_n$ denote the eigenvalues of $H_x(y)$. Since,

$$\max_{v} \frac{\|v\|_{y}^{2}}{\|v\|_{x}^{2}} = \max_{v} \frac{\langle v, H_{x}(y)v \rangle_{x}}{\|v\|_{x}^{2}} = \lambda_{n} = \|H_{x}(y)\|_{x}$$

and similarly,

$$\min_{v} \frac{\|v\|_{y}^{2}}{\|v\|_{x}^{2}} = \min_{v} \frac{\langle v, H_{x}(y)v \rangle_{x}}{\|v\|_{x}^{2}} = \lambda_{1} = \frac{1}{\|H_{x}(y)^{-1}\|_{x}}$$

from the definition of self-concordance,

$$||H_x(y)||_x = \max_v \frac{||v||_y^2}{||v||_x^2} \le \frac{1}{(1-||y-x||)^2}$$

Hessian Bound III

and similarly,

$$\frac{1}{\|H_{x}(y)^{-1}\|_{x}} = \min_{v} \frac{\|v\|_{y}^{2}}{\|v\|_{x}^{2}} \ge (1 - \|y - x\|)^{2}$$

$$\implies \|H_{x}(y)^{-1}\|_{x} \le \frac{1}{(1 - \|y - x\|)^{2}}$$

Recall the eigenvalues of $I - H_x(y)$ are $1 - \lambda_i$, so

$$\begin{split} \|I - H_x(y)\|_x &= \max\{\lambda_n - 1, 1 - \lambda_1\} \\ &\leq \max\left\{\lambda_n - 1, \frac{1}{\lambda_1} - 1\right\} \\ &= \max\{\|H_x(y)\|_x - 1, \|H_x(y)^{-1}\|_x - 1\} \end{split}$$

Recall $H_X(x) = I$, so bounding $||I - H_X(y)||_X$ has essentially given us local analogues for Lipschitz continuity and strong convexity.

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Log-Barrier

g(x): gradient of function self-concordant function f.

$$g_{\mathsf{x}}(y) = H_{\mathsf{x}}(^{-1}g(y))$$

Recall, g(x) for the log-barrier is the vector with the j-th entry $-1/x_j$ and H(x) is the diagonal matrix with the j-th diagonal entry $1/x_j^2$. So,

$$||g_x(x)||_x^2 = \langle g(x), H(x)^{-1}g(x) \rangle = n$$

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Problem Definition

The problem which we aim to solve is the following linear program,

minimize
$$c^T x$$

subject to $Ax = b$
 $x \ge 0$

In the augmented form,

minimize
$$\eta c^T x - \sum_{i=1}^n \ln(x_i)$$

subject to $Ax = b$

Quadratic Approximation I

$$q_x(y) := f(x) + \langle g(x), y - x \rangle + \frac{1}{2} \langle y - x, H(x)(y - x) \rangle$$

Theorem 5

If f is a self-concordant function, $x \in D_f$ and $y \in B_x(x,1)$ then

$$||f(y)-q_x(y)|| \le \frac{||y-x||_x^3}{3(1-||y-x||_x)}$$

proof. From the fundamental theorem of calculus,

$$\phi(1) = \phi(0) + \phi'(0) + rac{1}{2}\phi''(0) + \int_0^1 \int_0^t \phi''(s) - \phi''(0) ds dt$$

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Quadratic Approximation II

So,

$$f(y) = f(x) + \langle g(x), y - x \rangle + \frac{1}{2} \langle y - x, H(x)(y - x) \rangle$$

$$+ \int_{0}^{1} \int_{0}^{t} \langle y - x, [H(x + s(y - x)) - H(x)](y - x) \rangle dsdt$$

$$\|f(y) - q_{x}(y)\| \leq \|y - x\|_{x}^{2} \int_{0}^{1} \int_{0}^{t} \|I - H_{x}(x + s(y - x))\|_{x} dsdt$$

$$\leq \|y - x\|_{x}^{2} \int_{0}^{1} \int_{0}^{t} \frac{1}{(1 - s\|y - x\|_{x})^{2}} - 1 dsdt$$

$$= \|y - x\|_{x}^{3} \int_{0}^{1} \frac{t^{2}}{1 - t\|y - x\|_{x}} dt$$

$$\leq \frac{\|y - x\|_{x}^{3}}{1 - \|y - x\|_{x}} \int_{0}^{1} t^{2} dt$$

$$= \frac{\|y - x\|_{x}^{3}}{3(1 - \|y - x\|_{x})}$$

Newton Step Bound I

$$n(x) := -H(x)^{-1}g(x) = -g_x(x)$$
$$x_+ := x + n(x)$$

Theorem 6

Assume f is self-concordant. If $||n(x)||_x < 1$, then

$$||n(x_{+})||_{x_{+}} \le \left(\frac{||n(x)||_{x}}{1 - ||n(x)||_{x}}\right)^{2}$$

Newton Step Bound II

proof.

$$||n(x_{+})||_{x_{+}}^{2} = ||H_{x}(x_{+})^{-1}g_{x}(x_{+})||_{x_{+}}^{2}$$

$$= \langle H_{x}(x_{+})^{-1}g_{x}(x_{+}), H_{x}(x_{+})^{-1}g_{x}(x_{+})\rangle_{x_{+}}$$

$$= \langle H_{x}(x_{+})^{-1}g_{x}(x_{+}), g_{x}(x_{+})\rangle_{x}$$

$$\leq ||H_{x}(x_{+})^{-1}||_{x}||g_{x}(x_{+})||_{x}^{2}$$

From 1,

$$||H_x(x_+)^{-1}||_x \le \frac{1}{(1-||n(x)||_x)^2}$$

Therefore,

$$||n(x_+)||_{x_+} \le \frac{||g_x(x_+)||_x}{1 - ||n(x)||_x}$$

Newton Step Bound III

Recall
$$g_x(x) = -n(x)$$
,
$$\|g_x(x_+)\|_x = \|g_x(x_+) - g(x) - n(x)\|_x$$

$$= \left\| \int_0^1 [H_x(x + tn(x)) - I] n(x) dt \right\|_x$$

$$\leq \|n(x)\|_x \int_0^1 \|I - H_x(x + tn(x))\|_x dt$$

$$\leq \|n(x)\|_x \int_0^1 \frac{1}{(1 - t\|n(x)\|_x)^2} - 1 dt$$

$$= \frac{\|n(x)\|_x^2}{1 - \|n(x)\|_x^2}$$



Convergence to Minimizer I

Theorem 7

Assume f is self-concordant. If $||n(x)||_x \le \frac{1}{4}$ for some $x \in D_f$, then f has a minimizer z and

$$||z - x_+||_x \le \frac{3||n(x)||_x^2}{(1 - ||n(x)||_x)^3}$$

proof. We first prove the weaker result, if $\|n(x)\|_x \le \frac{1}{9}$, then f has a minimizer z and $\|x - z\|_x \le 3\|n(x)\|_x$. From Theorem 5, for all $y \in \bar{B}_x(x, \frac{1}{3})$,

$$||f(y) - q_x(y)|| \le \frac{1}{6} ||y - x||_x^2$$

$$f(y) \ge f(x) - ||n(x)||_x ||y - x||_x + \frac{1}{2} ||y - x||_x^2 - \frac{1}{6} ||y - x||^2$$

$$= f(x) - ||n(x)||_x ||y - x||_x + \frac{1}{3} ||y - x||_x^2$$

Convergence to Minimizer II

So if $\|n(x)\|_x \le \frac{1}{9}$ and $\|y - x\|_x = 3\|n(x)\|_x \le \frac{1}{3}$, then $f(y) \ge f(x)$. Assuming a minimizer, z, in S exists, then $\|x - z\|_x \le 3\|n(x)\|_x$. Now, assume $\|n(x)\|_x \le \frac{1}{4}$. Then from 6

$$||n(x+)||_{x+} \le \left(\frac{||n(x)||_x}{1-||n(x)||_x}\right)^2 \le \frac{1}{9}$$

Using the previous conclusion $||z - x_+||_{x_+} \le 3||n(x_+)||_{x_+}$. Thus

$$||z - x_{+}||_{x} \leq \frac{||z - x_{+}||_{x_{+}}}{1 - ||n(x)||_{x}}$$

$$\leq \frac{3||n(x_{+})||_{x_{+}}}{1 - ||n(x)||_{x}}$$

$$\leq \frac{3||n(x)||_{x}^{2}}{(1 - ||n(x)||_{x})^{3}}$$

The Algorithm I

$$n_{\eta}(x) := -H(x)^{-1}(\eta c + g(x)) = -(\eta c_{x} + g_{x}(x))$$

 $x_{2} := x_{1} + n_{\eta_{2}}(x_{1})$

Lemma 8

For the step defined above, $\|n_{\eta_2}\|_{\mathsf{x}} \leq rac{\eta_2}{\eta_1} \|n_{\eta_1}(\mathsf{x})\| + |rac{\eta_2}{\eta_1} - 1|\sqrt{n}$

The Algorithm II

proof.

$$\frac{1}{\eta_{2}}(n_{\eta_{2}}(x) + g_{x}(x)) = \frac{1}{\eta_{1}}(n_{\eta_{1}}(x) + g_{x}(x))$$

$$n_{\eta_{2}}(x) = \frac{\eta_{2}}{\eta_{1}}n_{\eta_{1}}(x) + \left(\frac{\eta_{2}}{\eta_{1}} - 1\right)g_{x}(x)$$

$$\Rightarrow \qquad \|n_{\eta_{2}}(x)\|_{x} \leq \frac{\eta_{2}}{\eta_{1}}\|n_{\eta_{1}}(x)\|_{x} + \left|\frac{\eta_{2}}{\eta_{1}} - 1\right|\|g_{x}(x)\|_{x}$$

$$\leq \frac{\eta_{2}}{\eta_{1}}\|n_{\eta_{1}}(x)\|_{x} + \left|\frac{\eta_{2}}{\eta_{1}} - 1\right|\sqrt{n}$$

The Algorithm III

Lemma 9

For
$$\beta := \frac{\eta_2}{\eta_1} = 1 + \frac{1}{8\sqrt{n}},$$

$$\|n_{\eta_1}(x_1)\|_{x_1} \le \frac{1}{9} \implies \|n_{\eta_2}(x_2)\|_{x_2} \le \frac{1}{9}$$

proof.

$$\begin{split} \|n_{\eta_{2}}(x_{1})\|_{x_{1}} &\leq \beta \|n_{\eta_{1}}(x_{1})\|_{x_{1}} + |\beta - 1|\sqrt{n} \\ &\leq \frac{1}{9} \left(1 + \frac{1}{8\sqrt{n}}\right) + \left|\left(1 + \frac{1}{8\sqrt{n}}\right) - 1\right|\sqrt{n} \\ &= \frac{1}{9} + \frac{1}{8} + \frac{1}{72\sqrt{n}} \\ &\leq \frac{1}{9} + \frac{1}{8} + \frac{1}{72} \\ &= \frac{1}{-} \end{split}$$

The Algorithm IV

By applying Theorem 6,

$$\|n_{\eta_2}(x_2)\|_{x_2} \le \left(\frac{\|n_{\eta_2}(x_1)\|_{x_1}}{1 - \|n_{\eta_2}(x_1)\|_{x_1}}\right)^2$$

 $\le \frac{1}{9}$

By applying Theorem 7,

$$||x - z(\eta)||_{x} \le \frac{3||n(x)||_{x}^{2}}{(1 - ||n(x)||_{x})^{3}}$$

$$\le \frac{3\left(\frac{1}{9}\right)^{2}}{\left(1 - \frac{1}{9}\right)^{3}}$$

$$\le \frac{1}{6}$$

The Algorithm V

By applying the definition of self-concordance,

$$||x - z(\eta)||_{z(\eta)} \le \frac{||x - z(\eta)||_x}{1 - ||x - z(\eta)||_x}$$

 $\le \frac{1}{5}$

Thus, all points generated are within distance $\frac{1}{5}$ of the central path.



Additional Points

• For convergence to a desired η_f , from an initial η_0 , we require

$$k := \frac{\log(\frac{\eta_f}{\eta_0})}{\log(\beta)}$$

iterations.

• In practice the step is assigned as

$$n_{\mu}(x) := -H(x)^{-1}(c + \mu g(x)) = -(c_x + \mu g_x(x))$$

 $x_2 := x_1 + n_{\mu_2}(x_1)$

where $\mu := \eta^{-1}$. Note this means that $\mu_2 = \beta^{-1}\mu_1$.

Example

minimize
$$2x_1 + x_2$$

subject to $-x_1 + x_2 \le 1$
 $x_1 + x_2 \ge 2$
 $x_1 - 2x_2 \le 4$
 $x_2 \ge 0$

We attempt to solve this problem using the short-step technique outlined above. 3 slack variables are introduced to replace the first three inequality constraints. The solver parameters are,

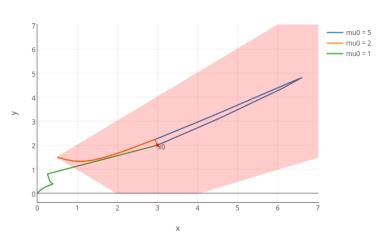
$$x_0 = \begin{bmatrix} 3 \\ 2 \end{bmatrix}$$
 $\mu_0 \in \{1, 2, 5\}$

with the slack variables assigned to ensure feasibility.



Visualization

Convergence of Short-Step Interior Point Method



References I

James Renegar. A mathematical view of interior-point methods in convex optimization. SIAM, 2001.