



# MANAN MADAN

## Projects

### LEARNING PERSPECTIVES | GROUPING STUDENTS BASED ON NOTES [\[link\]](#)

- Keyword extraction using POS Tagging and Chunking
- Used K-Means, K-Modes clustering of categorical data (keywords)
- Used one-hot encoding to encode the keywords.

### LANE DETECTION | LANE DETECTION USING DASH-CAM FOOTAGE [\[link\]](#)

- Lane Detection using Canny Edge Detection, masking, and contour detection from the footage of the DASH-CAM of the car using OpenCV.

### UNSUPERVISED TEST | AI-PROCTORING SYSTEM [\[link\]](#)

- Implemented User authentication using Face Verification System
- Developed a GUI for taking a test using Tkinter
- Implemented features like mouse tracking for fraud detection

### WIKIGRAPH | TURNING WIKIDATA INTO BEAUTIFUL GRAPHS [\[link\]](#)

- Implemented Web Scraping on Wiki Data using requests
- Learned SPARQL for interacting with wiki data's database
- Graph Manipulation using networkx

### KINO-PLANNING | PATH PLANNING ALGORITHM [\[link\]](#)

- Implemented a path planner inspired from A\*path planning algorithm, but considers robot's kinodynamic constraints while planning a path from point A to point B.
- Implemented it on Team ARES Rover, to achieve stable navigation b/w obstacles

## Work Experience

### NSIT, Delhi | Research Intern

May 2020 - July 2020

- Implement several clustering algorithms for clustering real-world categorical data
- Studied and implemented different types of encoding and decoding techniques to process data
- Worked on several algorithms and tools for natural language processing and web-scraping such as chunking, chunking, regex parser, etc.

### Team ARES Robotics, Delhi | Software Lead

August 2018 - Present

- Implemented full ROS navigation stack on simulation as well as on hardware platform
- Coded an autonomous differential drive robot with various sensors such as Depth Camera, IMU, GPS, from scratch in Gazebo.

## Education

### Netaji Subhas Institute of Technology, Delhi

University of Delhi  
2018-2022

### BE Instrumentation and Control

CGPA - 7.67 (Upto 4th sem)

## Contact

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## Skills

**Languages:** C, C++, Python

**Robotics:** ROS, Gazebo, Sensor Fusion, Kalman Filters, OpenCV, Perception, Path Planning

**Frameworks:** NLTK, Spacy, Pandas, Matplotlib, Networkx, BeautifulSoup, TextBlob, Regex

## Certifications

**C++ and Data Structures:** Coding Ninjas

**Competitive Programming:** Coding Blocks

**Algorithmic Toolbox:** UCSD

**Algorithms and Data Structure:** UCSD

**Algorithms on Graph :** UCSD

**Arduino Programming :** Udemy

**Machine Learning :** Stanford

**Deep Learning :** deeplearning.ai

## Achievements and Awards

- > Came in 10th place in Indian Rover Championship 2019
- > Qualified for European rover championship 2019
- > Top 1% in JEE Advanced 2018

