

# MANAN MADAN

## Projects

- **Learning Perspectives:**

- > Implemented K-Means, K-Modes clustering on real-world categorical data
- > Implemented NLP Techniques, such as chunking, chunking, etc.

- **VISTA:**

- > Implemented Web-Scraping using requests,urllib, and BeautifulSoup
- > Also implemented several graph algorithms to extract meaning information from structured data

- **OpenPi Bot:**

- > Coded a differential drive mobile robot in Gazebo
- > Implemented ROS Navigation Stack

- **Kinodynamic Path Planning**

- > Coded a Path Planner Inspired from the A \* Star Algorithm that takes into account robot's kinetic constraints
- > Simulated it in OpenCV

- **Lane Detection:**

- > Lane Detection using Canny Edge Detection, masking and contour detection from the footage of the DASH-CAM of the car

## Work Experience

### Research Intern

NSIT, Delhi

April 2020 - July 2022

- Implement several clustering algorithms for clustering real-world categorical data
- Studied and implemented different types of encoding and decoding techniques to process data
- Worked on several algorithms and tools for natural language processing and web-scraping such as chunking, chunking, regex parser, etc.

### Software Lead

Team ARES Robotics, Delhi

August 2018 - Present

- Implemented full ROS navigation stack on simulation as well as on hardware platform
- Implemented and Tested AMCL ( Adaptive Monte Carlo Localisation ) using ROS
- Implemented the Extended Kalman Filter for fusing the output of the various sensor in order to accurately localize the robot
- Coded an autonomous differential drive robot with various sensors such as Depth Camera, IMU, GPS, from scratch in Gazebo.

## Education

### Netaji Subash Institute of Technology, Delhi

University of Delhi

2018-2022

### BE Instrumentation and Control

CGPA - 7.52 (Upto 3rd sem)

## Contact

**Phone:** 8929250041

**Email:** madan.madan1@gmail.com

**Visit:** github.com/mananmadan

**LinkedIn:** manan-madan-646950167

## Skills

**Languages:** C,C++,Python

**Robotics:** ROS, GazeboSensor Fusion, Kalman Filters, OpenCV, Perception ( RANSAC, PointCloud Filtering, Object Detection) Path Planning

**Frameworks:** NLTK, Spacy, Pandas, Matplotlib, Networkx, BeautifulSoup, TextBlob, Regex

## Certifications

C++ and Data Structures

> By Coding Ninjas

Data Structures

> By UCSD

Algorithms and Data Structures

> By UCSD

Algorithms on Graph

> By UCSD

Arduino Programming

> By Udemy

## Achievements and Awards

> Came in 10th place in Indian Rover Championship

> Top 1% in JEE Advanced 2018