Control System-1

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ICE-2

M-Circles (constant magnitude Loci)

* M- Circles are used to determine the magnitude

* Applicable only for unity feedback systems.

 $M(j\omega) = G(j\omega)/1 + G(j\omega)$

 $G(j\omega) = \kappa + jy$

|M(gω)|= \n2+y2/\(C++v3+y2)

 $M^2(1+\kappa)^2 + M^2y^2 = \kappa^2 + y^2$

 $\kappa^2 (1-M^2) + (1-M^2)y^2 - 2M^2x = M^2$

 $\kappa^2 + \gamma^2 - 2M^2 \kappa = M^2$ $I - M^2$

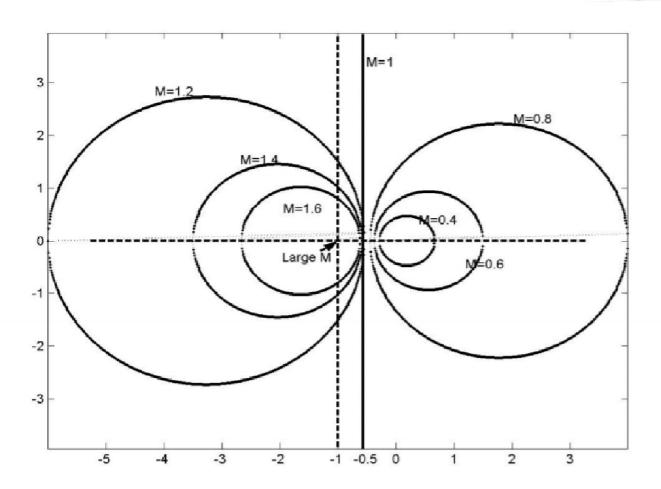
adding $(\frac{M^2}{1-M^2})^2$ in Both sides, we get

 $\left(K - \frac{M^2}{1 - M^2}\right)^2 + y^2 = \left(\frac{M}{1 - M^2}\right)^2$

The above equation represents a family of circles with its center at $(\frac{M^2}{I-M^2}, 0)$ and radius $|\frac{M}{I-M^2}|$.

* Family of M-Circles.

Family of M-circles coresponding to the close loop magnitudes CM) of aunit feedback system, constant M-circles for unity feedback system.



N Circles-(Constant Bhase angles loci)

*N-circles are used to determine the Bhase response of a closed loop system using open-loop transfer-function.

G(jw) = x+jy

 $C(j\omega)/R(j\omega) = G(j\omega)/1 + G(j\omega)$

= x+gy/1+x+gy

9= tan-'(y/n) - tan- (y/1+n)

Consider tans
tan \$\phi = \tan (\tan^{-1}(\gamma/\w) - \tan^{-1}(\gamma/\left!+\w))

tan $\phi = \frac{\tan(\tan'(y/n) - (\tan'(y/1+n))}{1 + \tan(\tan'(y/n))} \tan(\tan'(y/1+n))}$

 $tan \phi = ((y/n) - (y/1+n)) = y/n^2 + x + y^2$ 1 + (y/n)(y/1+n)

let N=tan \$

N= y/n2+x+y2

=> x2+x+y2-y/N=0

Add 1/4+1/4N on both side

 $\kappa^2 + \kappa + \frac{1}{4} + y^2 - y/N + y/4N = \frac{1}{4} + \frac{1}{4N}$

$$(x+42)^2+(y-4/2N)^2=(4+4/4N)^2$$

Radious =
$$\sqrt{\frac{1}{4} + \frac{1}{4N^2}}$$

