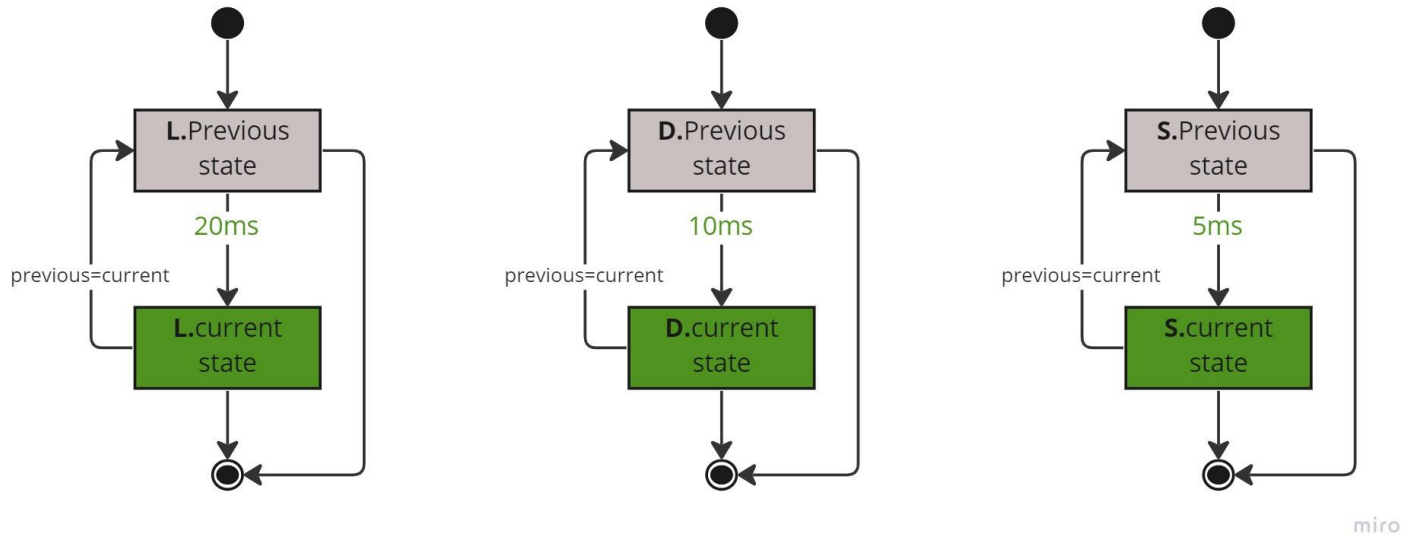


[AUTOMOTIVE DOOR CONTROL SYSTEM DESIGN]

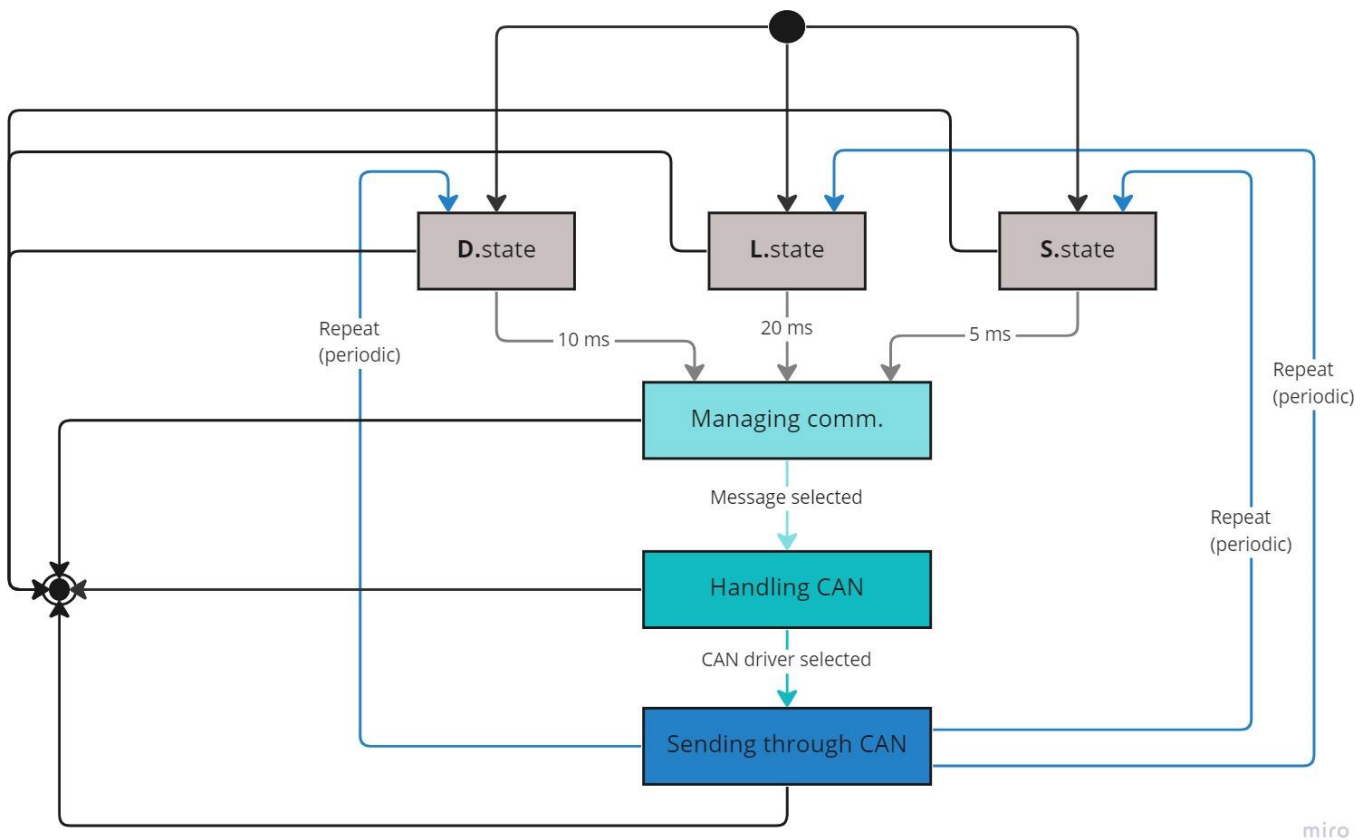
*Dynamic
Design*

ECU1

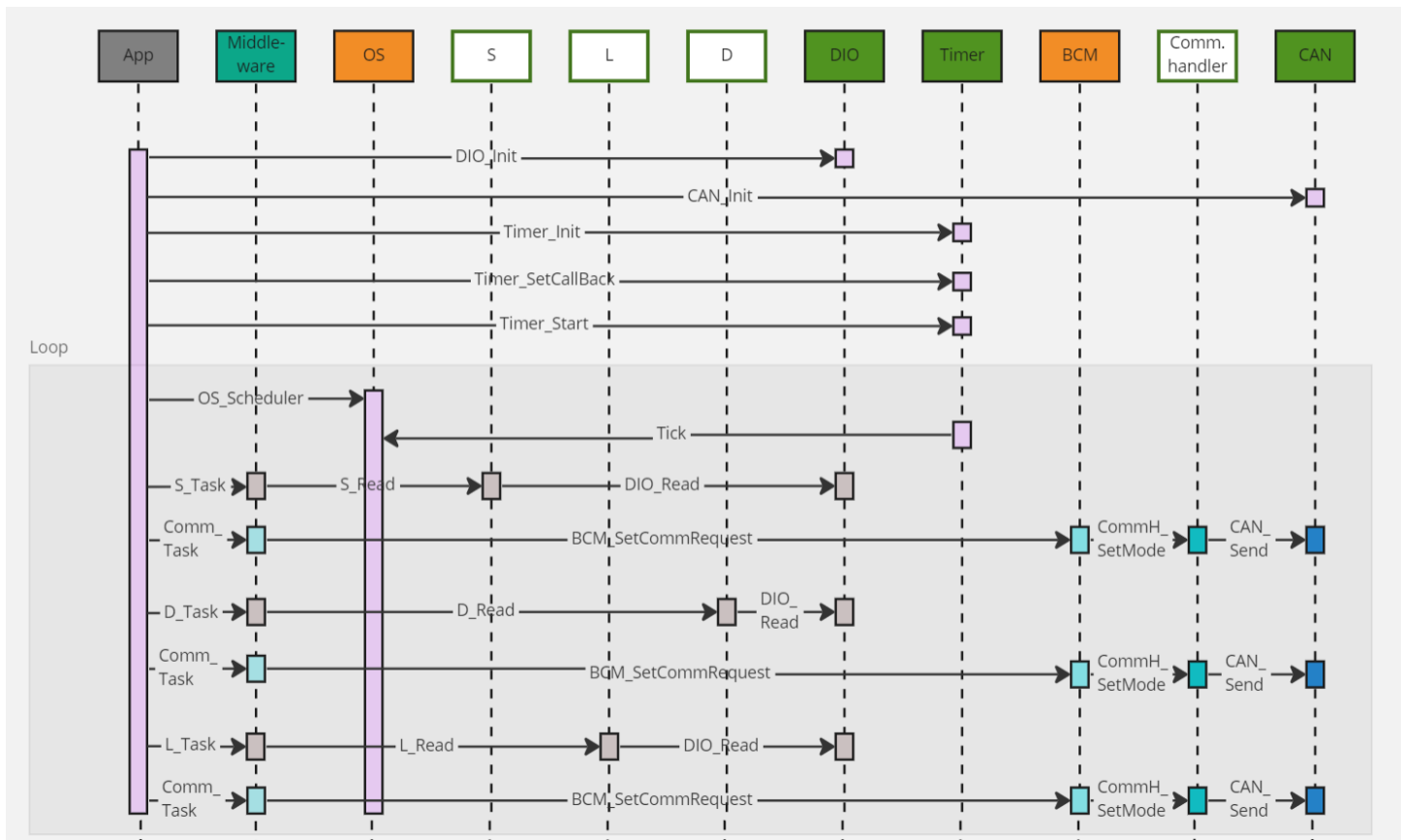
- A state machine diagram for each component:



- A state machine diagram for the ECU operation:



- A sequence diagram for the ECU:



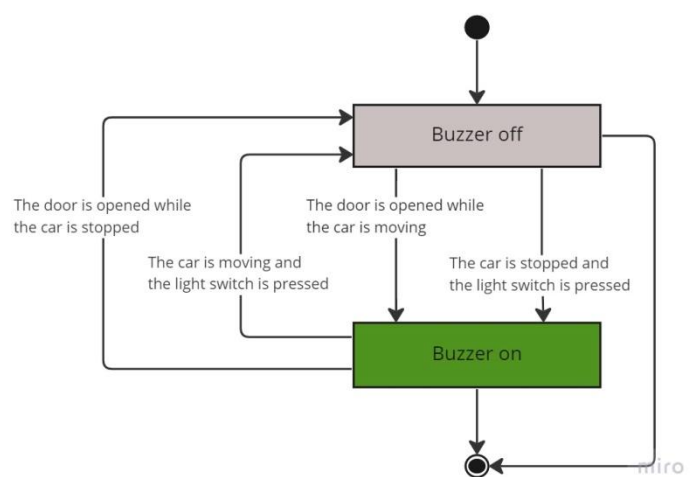
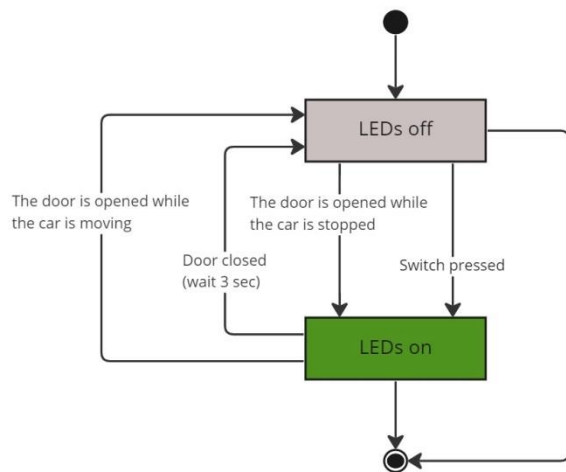
- CPU load for the ECU:

Cpu load = total execution time / hyperperiod (assume 0.5 ms execution time for each task)

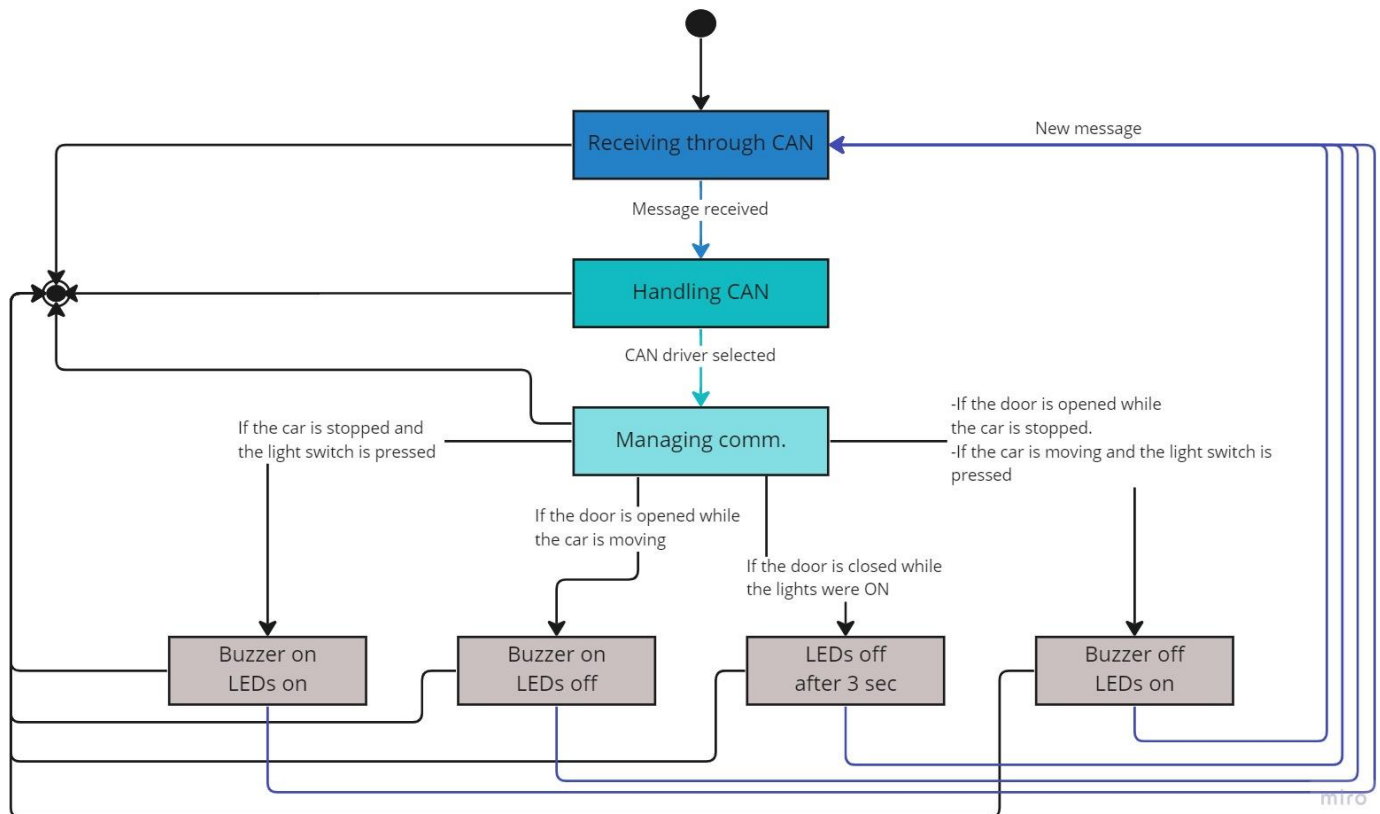
$$= (.5*1)+(.5*2)+(.5*4)/20 = 0.175*100 = 17.5\%$$

ECU2

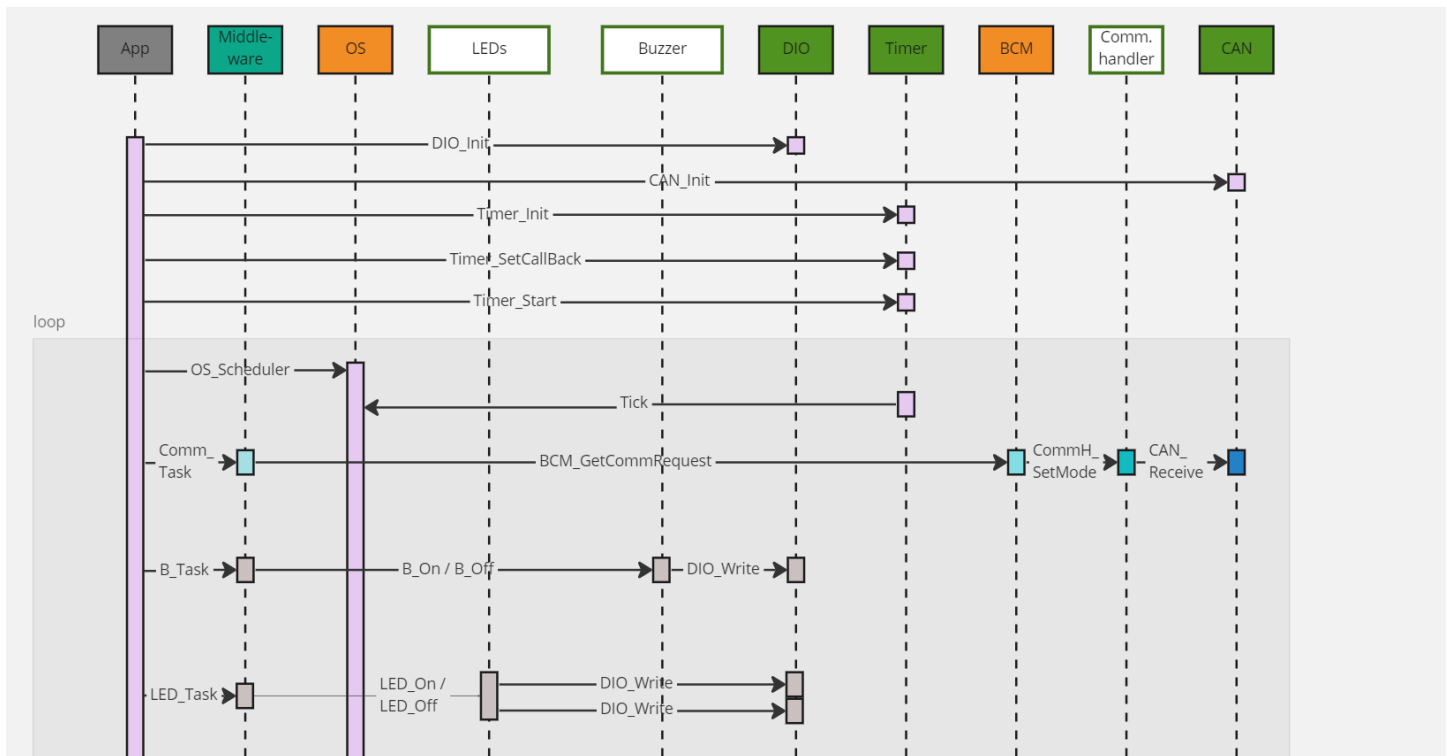
- A state machine diagram for each component:



- A state machine diagram for the ECU operation:



- A sequence diagram for the ECU:



- CPU load for the ECU:

$$\begin{aligned} \text{Cpu load} &= \text{total execution time} / \text{hyperperiod} \\ &= (.5 * 4) + (.5 * 4) / 20 = 0.2 * 100 = 20\% \end{aligned}$$

(assume 0.5 ms execution time for each task)

➤ Bus load

1 CAN frame contain approximately 125 bit.

bit time = $1 / \text{bit rate} = 1 / (500 * 1000\text{s}) = 2\mu$

1 bit will take 2μ o transfer

Time to transfer 1 frame = $2 * 125 = 250$

1 frame every 5ms = 200 frame every 1000ms

1 frame every 10ms = 100 frame every 1000ms

1 frame every 20ms = 50 frame every 1000ms

Total 350 frame = $((350 * 250)\mu / (1000 * 1000)) * 100 = 8.75\%$