

# Maths. Questions. (QMA2L)

8021)

$A =$

$$\begin{bmatrix} 1 & 2 & 3 & 0 \\ 2 & 4 & 3 & 2 \\ 3 & 2 & 4 & 3 \\ 6 & 8 & 7 & 5 \end{bmatrix}$$

find rank.

$$R_2 \rightarrow R_2 - 2R_1$$

$$R_3 \rightarrow R_3 - 3R_1$$

$$R_4 \rightarrow R_4 - 6R_1$$

$$\begin{bmatrix} 1 & 2 & 3 & 0 \\ 0 & 0 & -3 & 2 \\ 0 & -4 & -8 & 3 \\ 0 & -4 & -11 & 5 \end{bmatrix}$$

$$R_3 \rightarrow R_3 - R_4$$

$$\begin{bmatrix} 1 & 2 & 3 & 0 \\ 0 & 0 & -3 & 2 \\ 0 & 0 & 3 & -2 \\ 0 & -4 & -11 & 5 \end{bmatrix}$$

$$R_2 \leftrightarrow R_4$$

$$\begin{bmatrix} 1 & 2 & 3 & 0 \\ 0 & -4 & -11 & 5 \\ 0 & 0 & 3 & -2 \\ 0 & 0 & -3 & 2 \end{bmatrix}$$

$$R_4 \rightarrow R_4 + R_3$$

Rank = 3

$$\begin{bmatrix} 1 & 2 & 3 & 0 \\ 0 & -4 & -11 & 5 \\ 0 & 0 & 3 & -2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

No. of Non-zero rows  
= 3  
Hence Rank = 3



Soln)  $A = \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix}$

$\lambda$  form  $\rightarrow \begin{bmatrix} 2-\lambda & -1 \\ -1 & 2-\lambda \end{bmatrix}$

$$(2-\lambda)(2-\lambda) - [1]$$

$$(2-\lambda)^2 - 1 = 0$$

$$\cancel{4 + \lambda^2 - 2\lambda - 1} = 0$$

$$\lambda^2 - 2\lambda + 3 = 0$$

$$\lambda^2 - 3\lambda + \lambda + 3 = 0$$

$$4 + \lambda^2 - 4\lambda - 1 = 0$$

$$\lambda^2 - 4\lambda + 3 = 0$$

$$\lambda^2 - \lambda - 3\lambda + 3 = 0$$

$$\lambda(\lambda-1) - 3(\lambda-1) = 0$$

$$(\lambda-3)(\lambda-1) = 0$$

$$\lambda = 3 \text{ and } \lambda = 1$$

$\rightarrow$  These are the Eigen values

# For Eigen vectors

for  $\lambda = 3$

$$\begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = 0$$

$$x - y = 0$$

$$x = y$$

$$\begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = 0$$

Eigen vector  $\rightarrow \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

for  $\lambda = 1$

$$\begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = 0$$

$$-x - y = 0$$

$$-x - y = 0$$

$$x = -y$$

Eigen vector  $\rightarrow \begin{bmatrix} 1 \\ -1 \end{bmatrix}$



Q14) Gauss - Siedel Method. (Three ~~the~~ iterations)

$$\Rightarrow \begin{cases} 3x - 0.1y - 0.2z = 7.85 \\ 0.1x + 7y - 0.3z = -19.3 \\ 0.3x + 0.2y + 10z = 71.4 \end{cases}$$

with initial values.

$$x(0) = 0, y(0) = 0, z(0) = 0$$

$$x = \frac{7.85 + 0.2z + 0.1y}{3}$$

$$y = \frac{-19.3 + 0.3z - 0.1x}{7}$$

$$z = \frac{71.4 + 0.2y + 0.3x}{10}$$

1st Iteration:

$$x = \frac{7.85 + 0.2z + 0.1y}{3} = \frac{7.85 + 0.2(0) + 0.1(0)}{3} = 2.616$$

$$y = \frac{-19.3 + 0.3z - 0.1x}{7} = \frac{-19.3 + 0.3(0) - 0.1(2.616)}{7} = -2.816$$

$$z = \frac{71.4 + 0.2y + 0.3x}{10} = \frac{71.4 + 0.2(-2.816) + 0.3(2.616)}{10} = 7.14$$

$$x = 2.616$$

$$y = -2.816$$

$$z = 7.14$$



## # 2nd Iteration:

$$(x, y, z) = 2.616, 19.561, 6.670$$

$$x = 7.88 + 0.1(19.561) + 0.2(6.67)$$

$$x = 7.716$$

$$y = -19.31 - 0.1(7.716) + 0.3(6.670)$$

$$y = -2.36$$

$$z = 7.7 - 0.3(7.716) - 0.2(-2.36)$$

$$z = 6.956$$

## # 3rd Iteration

$$x = 8.002$$

$$y = -2.455$$

$$z = 7.099$$

Auss) Consistent  $\rightarrow$  System of Eq. where a sol<sup>n</sup> exists.

Inconsistent  $\rightarrow$  " " " " " " a sol<sup>n</sup> doesn't exist

$$x + 3y + 2z = 0$$

$$2x - y + 3z = 0$$

$$3x - 5y + 4z = 0$$

$$x + 17y + 4z = 0$$

$$\begin{bmatrix} 1 & 3 & 2 & 0 \\ 2 & -1 & 3 & 0 \\ 3 & -5 & 4 & 0 \\ 1 & 17 & 4 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 3 & 2 & 0 \\ 2 & -1 & 3 & 0 \\ 3 & -5 & 4 & 0 \\ 1 & 17 & 4 & 0 \end{bmatrix}$$

$$R_4 \rightarrow R_4 - R_1$$

$$R_2 \rightarrow R_2 - 2R_1$$

$$R_3 \rightarrow R_3 - 3R_1$$

$$\begin{bmatrix} 1 & 3 & 2 & 0 \\ 0 & -7 & -1 & 0 \\ 0 & -14 & -2 & 0 \\ 0 & 14 & 2 & 0 \end{bmatrix}$$

$$R_4 \rightarrow R_4 + R_3$$

$$R_3 \rightarrow R_3 + 2R_2$$

$$\begin{bmatrix} 1 & 3 & 2 & 0 \\ 0 & -7 & -1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\rho(A) = \rho(A|b) = 3$$

$$2 = 2 \neq 3$$

Inconsistent



Ans 8) Same method as Sol 4).

Ans 9) ~~Matrix~~ operation is used in Image Processing in linear transformations particularly when applying ~~filters~~ Filters to images.

Ans 10) Linear transformations, represented by matrices are imp. in computer vision as the manipulate spatial properties of image in a ~~the~~ systematic way.