GENERATIVE ADVERSARIAL NETWORKS

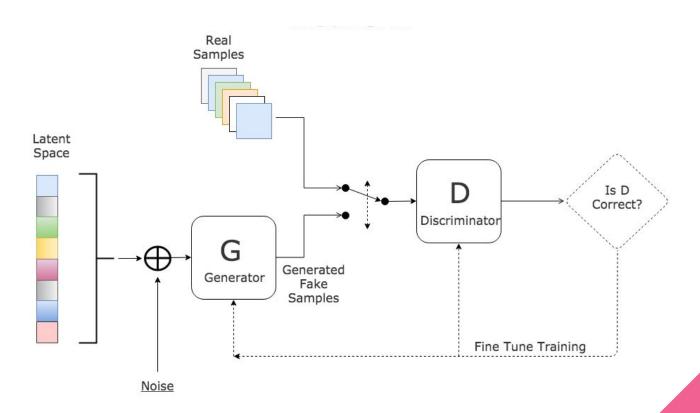
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INTRO

- Proposed by Prof. Ian Goodfellow in 2014.
- A Generative Adversarial Network (GAN) is used to create data that looks at least to superficially similar to original to human observers, having many realistic characteristics (though in tests people can tell real from generated in many cases).
- They produce photorealistic images and find application in data augmentation, reconstruction as well as feature mapping.
- Common applications include Medical Imaging, Superresolution and Domain Transfer

VISUALIZING THE STRUCTURE

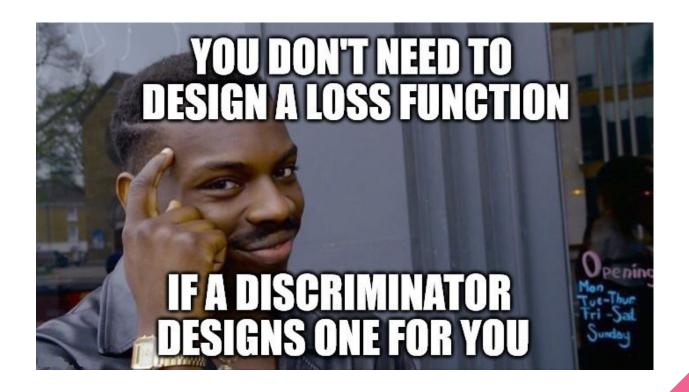


IDEA OF ADVERSARIAL TRAINING

- 1. Generator generates fake data based on the training set.
- 2. Discriminator tells if it is fake or not.
- 3. If fake, modify the Generator
- 4. Else, your network is ready!

Implemented by a Minimax loss function where the change in gradient is determined by how badly the discriminator accepts or rejects generated data.

IDEA OF ADVERSARIAL TRAINING



IDEA



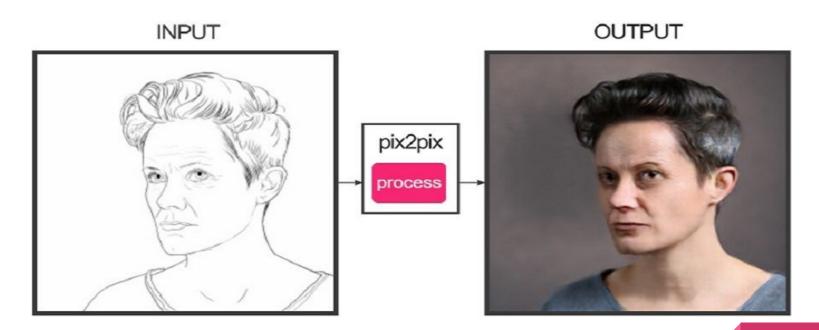
VISUALIZING GANS



IDEA



PIX2PIX



SUPER RESOLUTION (SRGAN)



Input

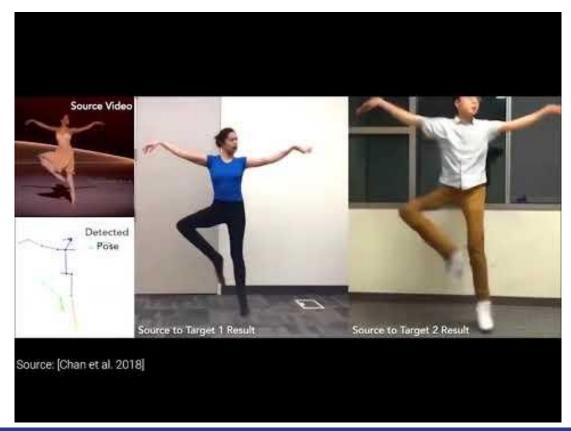


Output



Ground Truth

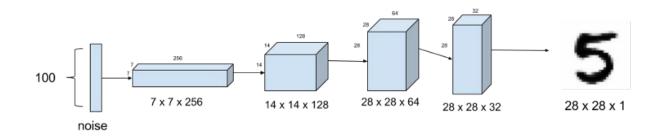
Dense Pose Transfer

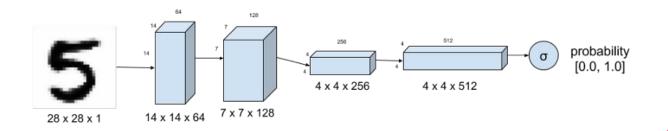


SCENE GENERATION



GENERATING A NUMBER FROM NOISE





CODE - DISCRIMINATOR

```
self.D - Sequential()
depth - 64
dropout = 0.4
# In: 28 x 28 x 1, depth = 1
# Out: 14 x 14 x 1, depth-64
input shape = (self.img rows, self.img cols, self.channel)
self.D.add(Conv2D(depth*1, 5, strides=2, input shape=input shape, \
padding='same', activation=LeakyReLU(alpha=0.2)))
self.D.add(Dropout(dropout))
self.D.add(Conv2D(depth*2, 5, strides=2, padding='same', \
activation=LeakyReLU(alpha=0.2)))
```

```
self.D.add(Dropout(dropout))
self.D.add(Conv2D(depth*4, 5, strides=2, padding='same', \
activation=LeakyReLU(alpha=0.2)))
self.D.add(Dropout(dropout))
self.D.add(Conv2D(depth*B, 5, strides=1, padding='same', \
activation=LeakyReLU(alpha=0.2)))
self.D.add (Dropout (dropout))
# Out: 1-dim probability
self.D.add(Flatten())
self.D.add(Dense(1))
self.D.add(Activation('sigmoid'))
```

CODE - GENERATOR

```
self.G = Sequential()
dropout = 0.4
depth = 64+64+64+64
dim = 7
# In: 100
# Out: dim x dim x depth
self.G.add(Dense(dim*dim*depth, input dim=100))
self.G.add(BatchNormalization(momentum=0.9))
self.G.add(Activation('relu'))
self.G.add(Reshape((dim, dim, depth)))
self.G.add(Dropout(dropout))
# In: dim x dim x depth
# Out: 2*dim x 2*dim x depth/2
```

```
self.G.add(UpSampling2D())
self.G.add(Conv2DTranspose(int(depth/2), 5, padding='same'))
self.G.add(BatchNormalization(momentum=0.9))
self.G.add(Activation('relu'))
self.G.add(UpSampling2D())
self.G.add(Conv2DTranspose(int(depth/4), 5, padding='same'))
self.G.add(BatchNormalization(momentum=0.9))
self.G.add(Activation('relu'))
self.G.add(Conv2DTranspose(int(depth/8), 5, padding='same'))
self.G.add(BatchNormalization(momentum=0.9))
self.G.add(Activation('relu'))
# Out: 28 x 28 x 1 grayscale image [0.0,1.0] per pix
self.G.add(Conv2DTranspose(1, 5, padding='same'))
self.G.add(Activation('sigmoid'))
self.G.summary()
return self.G
```

CODE - COMBINING

- * Compile individual models of Generator and Discriminator with hyperparameters
- Training can can be done individually initially or the entire stack can be combined as well!
- Combining the models to make a complete GAN

```
optimizer = RMSprop(lr=0.0004, clipvalue=1.0, decay=3e-8)
self.AM = Sequential()
self.AM.add(self.generator())
self.AM.add(self.discriminator())
self.AM.compile(loss='binary crossentropy', optimizer=optimizer,\
metrics=['accuracy'])
```

LEARNING RESOURCES

- ♦ Mother Paper https://arxiv.org/abs/1406.2661
- Talk by Ian Goodfellow https://www.youtube.com/watch?v=9JpdAg6uMXs
- http://cs231n.stanford.edu/slides/2017/cs231n 2017 lecture13.pdf
- https://www.quora.com/What-are-good-resources-to-learn-about-Generative-adversar ial-networks

Fun Links

- https://reiinakano.github.io/gan-playground/
- https://dena.com/intl/anime-generation/
- https://cs.stanford.edu/people/karpathy/gan/

And many more ...

THANK YOU