



BIRLA INSTITUTE OF TECHNOLOGY AND SCIENCE, Pilani
Pilani Campus
AUGS/ AGSR Division

SECOND SEMESTER 2020-21
COURSE HANDOUT (New student)

Date: 10.03.2021

In addition to part I (General Handout for all courses appended to the Time table) this portion gives further specific details regarding the course.

Course No : PHY F111

Course Title : Mechanics, Oscillations and Waves

Instructor-in-Charge: Srijata Dey

Instructor(s): Rishikesh Vaidya, D. Bandyopadhyay, Kaushar Vaidya

Tutorial Instructors: Anshuman Dalvi, Biswanath Layek, D. Bandyopadhyay, D.D. Pant, Kaushar Vaidya, V. Manjuladevi, Niladri Sarkar, Tapomoy G. Sarkar, Sandipan Dutta, Srijata Dey.

1. Course Description: The first half of the course deals with the applications of Newton's laws to the systems of particles and the study of linear and rotational motion using polar coordinates and physics of non-inertial reference frames. The second half deals with oscillatory motion, coupled oscillations and waves. There will be three lecture hours and one tutorial hour per week. Whereas the lectures would mostly focus on concepts and illustrative examples tutorial hour will be used to discuss representative problems from the chapters. Tutorial will follow the lectures as closely as possible.

2. Scope and Objective of the Course: Mechanics, Oscillations and Waves is a foundation course in Physics that is mandatory for all the first degree students.

3. Text Books:

T1: An Introduction to Mechanics by Kleppner & Kolenkow, Tata McGraw-Hill Indian Edition, 1999

T2: Vibrations and Waves, by A.P. French, CBS Publishers and Distributors, Inc., first Indian edition 1987.

4. Reference Books:

(a) Physics, Vol.1, by Halliday, Resnick, & Krane, 5th Edition, John Wiley & Sons, Inc., 2002

(b) The Physics of Waves and Oscillations by N K Bajaj, Tata McGraw-Hill 1984.



5. Course Plan:

| Topics from Text Book 1 (T1) : Kleppner & Kolenkow | | | |
|---|---|---|---|
| Module Number | Lecture /Tutorial Session. | Reference | Learning Outcome |
| 1. Foundations of Newtonian Mechanics and Polar Coordinates. | L1: Critical overview of Newton's laws L2: Introduction to motion in plane polar coordinates L3: Illustrative examples on polar coordinates | T1: Sec. 1.9 in Chapter 1; Chapter 2 and problems related to polar coordinates in Chapter 2. | 1. Critical appreciation of Newton's laws 2. Given a motion of a body involving circular geometry identify the radial and tangential components of forces and draw a free body diagram. 3. Solve second order linear differential equation with constant coefficients through simple guess work. |
| 2.Momentum | L4: Extended systems and motion of center of mass L5: Conservation of momentum its applications and impulse L6: Mass varying systems and their applications | T1: Chapter 3 | 1. Description of an extended system (discrete or continuous) in terms of motion of center of mass. 2. Formulating momentum conservation (when applicable) with appropriate velocity components referring to inertial systems. 3. Formulating and solving the equation of motion of a mass varying system. |
| 3.Work and Energy | L7: Work energy theorem and concept of potential energy L8: Conservative and non-conservative forces. L9: Physics from energy diagrams L10: Oscillatory systems and stability analysis | T1: Chapter 4 (except section 4.14 and problems related to section 4.14) | 1. Application of work energy theorem for conservative systems. 2. Calculation of power for non-conservative system 3. Constructing energy diagrams and extracting physical insights. 4. Stability analysis and finding frequency of small oscillations. |
| 4.Angular Momentum and Fixed Axis Rotation | L11: Angular Momentum and Torque in a fixed axis rotation L12: Momentum of inertia and dynamics of pure rotation. L13: Dynamics of Rotation and translation L14: Conservation of Angular Momentum L15: Angular Oscillations and stability analysis | T1: Chapter 6 | 1. Finding angular momentum and torque about various choices of fixed axis. 2. Examining and exploiting conservation of angular momentum to find quantity of interest. 3. Solving problems involving rotational and translational motion about fixed axis. 4. Finding frequency of small angular oscillations. |
| 5.Non-inertial Frames | L16: Galilean transformations, uniformly accelerated frames and pseudo forces L17: Principle of equivalence L18: Physics in rotating coordinate system L19: Illustrative problems | T1: Chapter 8 | 1. Learning to formulate and solve a problem from both inertial and non-inertial reference frames. 2. Understanding the relevance of non-inertial frames, principle of equivalence and their connection to physics of tides. |



Topics from Text Book 2 (T2) : A.P. French

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| 6. The Free Vibrations of Physical System. | L20: Simple harmonic motion (SHM) for different physical systems L21: SHM equation L22: The decay of free vibrations L23: Effect of very large damping | T2: Chapter 3 | 1. Finding angular frequency of different oscillating systems. 2. Solving SHM equation using complex exponential. 3. How the free vibrations get modified by including the dissipative effects. 4. Calculating the quality and amplitude of damped systems. |
| 7. Forced Oscillator and Resonance | L24: Undamped oscillator with harmonic forcing L25: Forced oscillator with damping L26: Effect of varying the resistive term L27: Power absorbed by a driven oscillator L28: Velocity and power resonance | T2: Chapter 4 | 1. Distinguish between natural and driving frequencies. 2. Finding the amplitude of a forced oscillator as a function of driving frequency. 3. Finding average and maximum power input to maintain the oscillations. |
| 8. Coupled Oscillators and Normal Modes | L29: Two coupled pendulums L30: Normal coordinates, Normal modes, normal frequencies. L31: Illustrative problems L32: Forced oscillations of two coupled oscillators L33: Many coupled oscillators | T2: Chapter 5 | 1. Finding equation of motion of coupled free systems. 2. Calculation of normal mode frequencies. 3. Finding equation of motion of coupled forced systems 4. Determining normal modes and their frequencies for N coupled oscillators. |
| 9. Normal Modes of Continuous Systems | L34: The free oscillations of stretched strings L35: Normal modes of a stretched string, forced oscillations of a stretched string | T2: Chapter 6 | 1. Calculating linear density of a uniform string 2. Finding the permitted frequencies for the free vibrations in strings. 3. Finding the driving frequency for the amplitude resonance of vibrating string. |
| 10. Progressive Waves | L36: Progressive waves in one dimension L37: Superposition, motion of wave pulses of constant shape L38: Phase and group velocity L39: Energy and its transportation by a wave | T2: Chapter 7 | 1. Identifying different types of waves. 2. Distinguish particle, phase and group velocities in wave motion. 3. Applying the relationship between phase velocity and group velocity. Finding the energy transported by a wave. |



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6. Evaluation Scheme:

| Component | Duration | Weightage (%) | Date & Time | Nature of component (Close / Open Book) |
|---------------------------|-----------------|----------------------|------------------------|--|
| Mid-Semester Examination | 90 Min. | 33.33 | TBA | Open/ Closed |
| Comprehensive Examination | 2 hrs. | 40 | TBA | Open/ Closed |
| Tutorial tests | 15 min. | 26.66 | TBA | Open/ Closed |

Each student must accept the invitation to join the Google classroom for his/her Lecture section and Tutorial sec. The Tutorial Tests will be conducted in the classroom of each Tut. Section and not in any lecture section.

7. Online Consultation Hour: To be announced in the tutorial class.

8. Notices: Streamed on the classrooms of lecture classes/Tutorial sections.

9. Make-up Policy: As per Institute rules.

Instructor-in-charge
Course No. PHY F111