

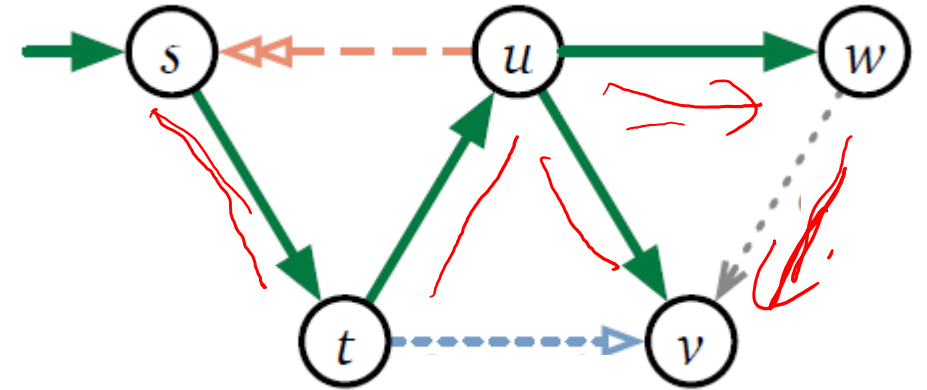
DFS

Sridhar Alagar

DFS in a directed Graph

Use stack for DFS

```
wfs(s) {  
    put s into bag  
    while bag not empty  
        take v from bag  
        if v is unmarked  
            mark v  
            for each (v, w) in G do  
                put w in bag  
}
```

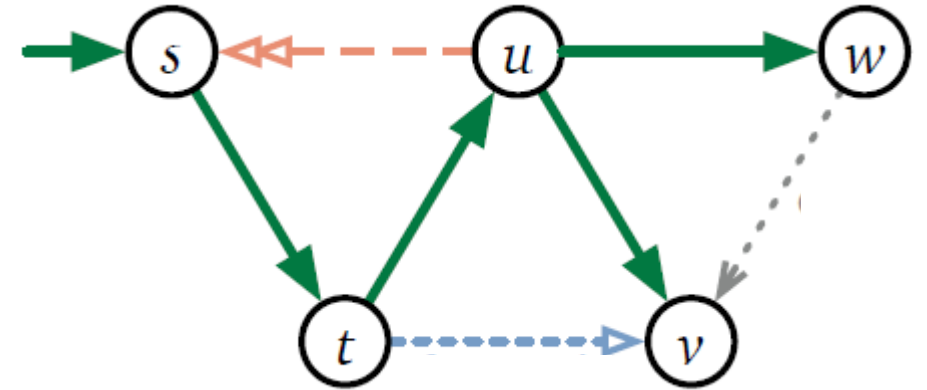


```
dfs(v) {  
    if v is unmarked  
        mark v  
        for each (v, w) in G do  
            dfs(w)  
}
```

DFS

Wrapper method to visit all nodes

```
dfsAll(G) {  
    initialize(G)  
    for each v in G do  
        unmark v  
    for each v in G do  
        if v is unmarked  
            dfs(v)  
}
```



```
dfs(v) {  
    mark v  
    pre(v)  
    for each (v, w) in G do  
        if w is unmarked  
            w.parent = v  
            dfs(w)  
    post(v)  
}
```

Preorder and postorder traversal of DFS Forest

Record when a node entered and left stack

```
dfsAll(G) {  
    initialize(G)  
    for each v in G do  
        unmark v  
    for each v in G do  
        if v is unmarked  
            dfs(v)  
}
```

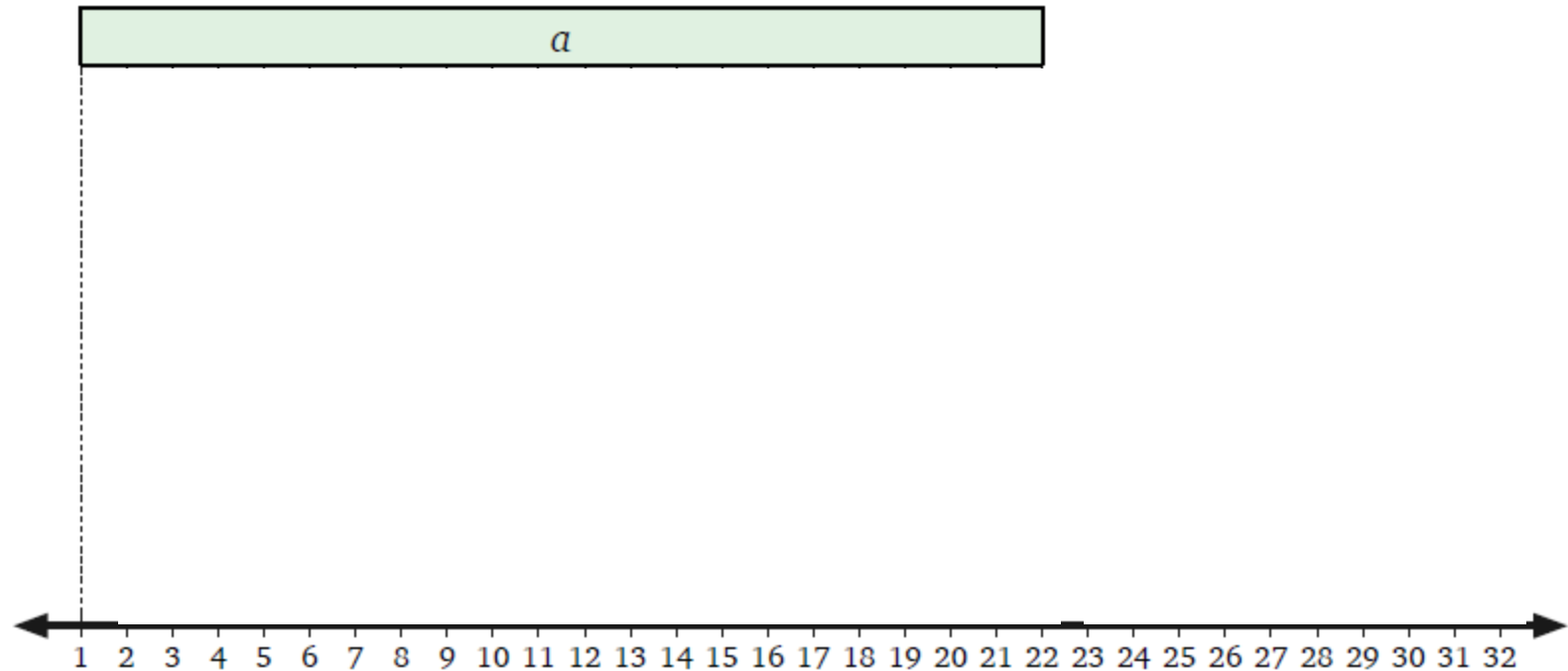
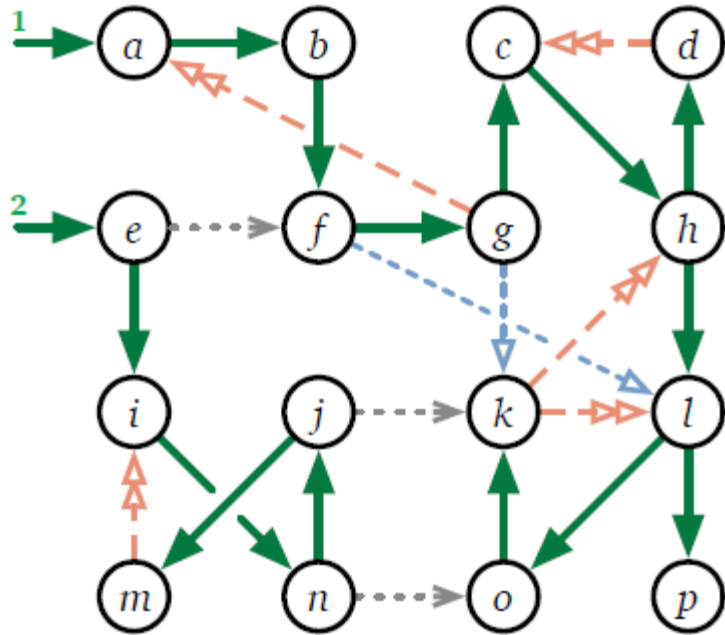
```
initialize(G)  
    clock = 0
```

```
pre(v)  
    clock++  
    v.start = clock
```

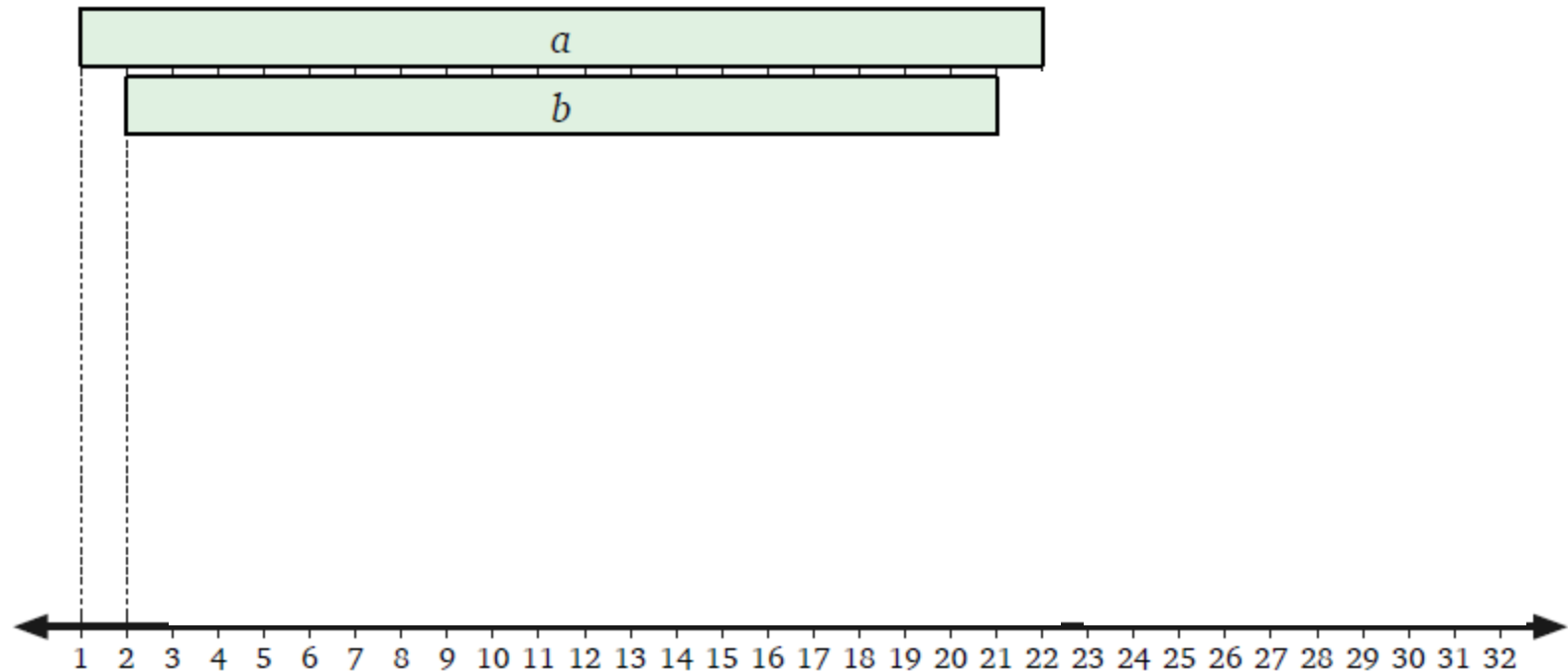
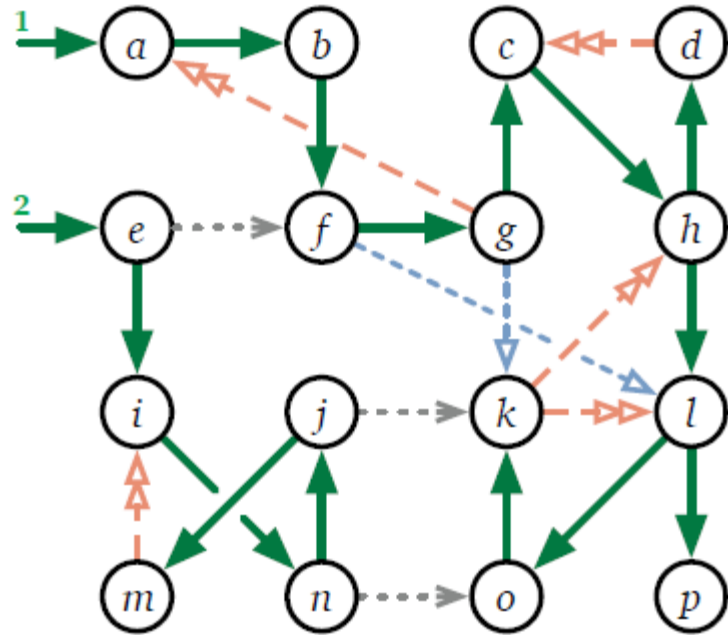
```
dfs(v) {  
    mark v  
    pre(v)  
    for each (v, w) in G do  
        if v is unmarked  
            w.parent = v  
            dfs(w)  
    post(v)  
}
```

```
post(v)  
    clock++  
    v.finish = clock
```

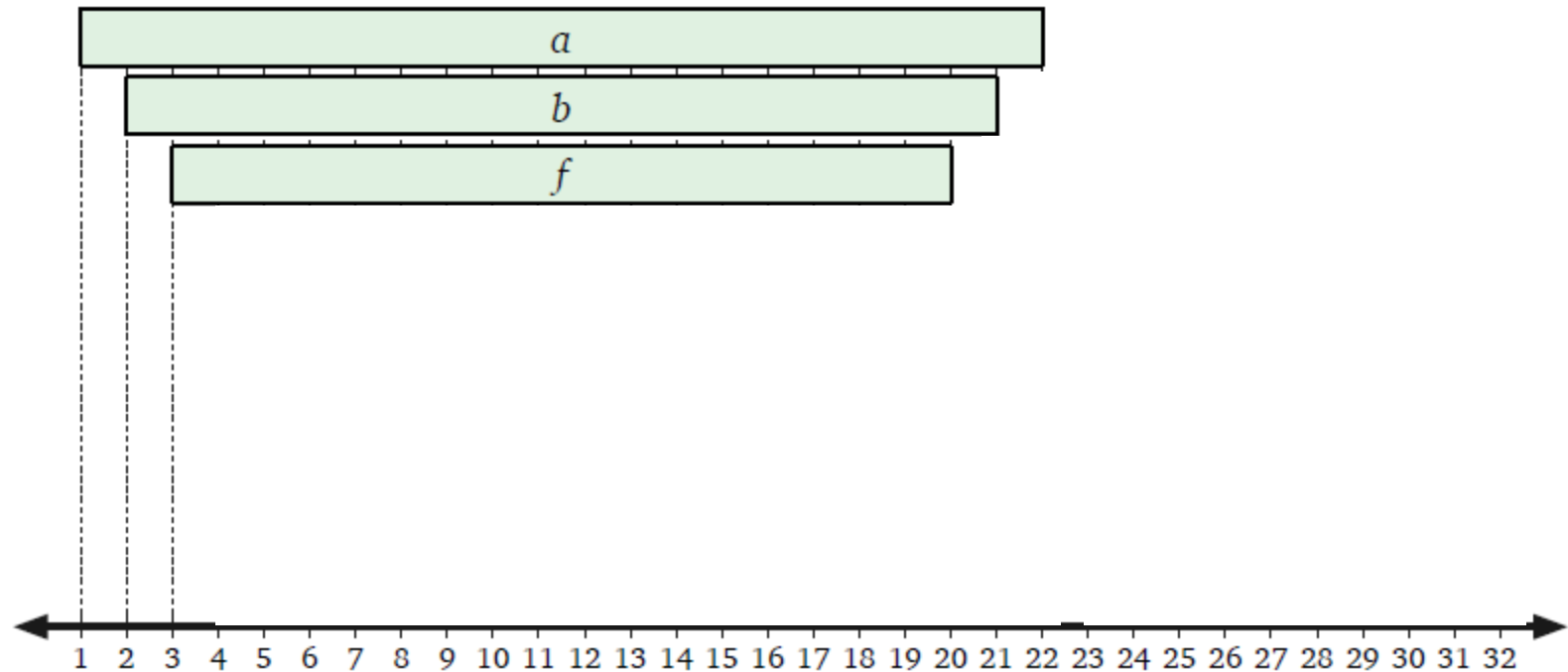
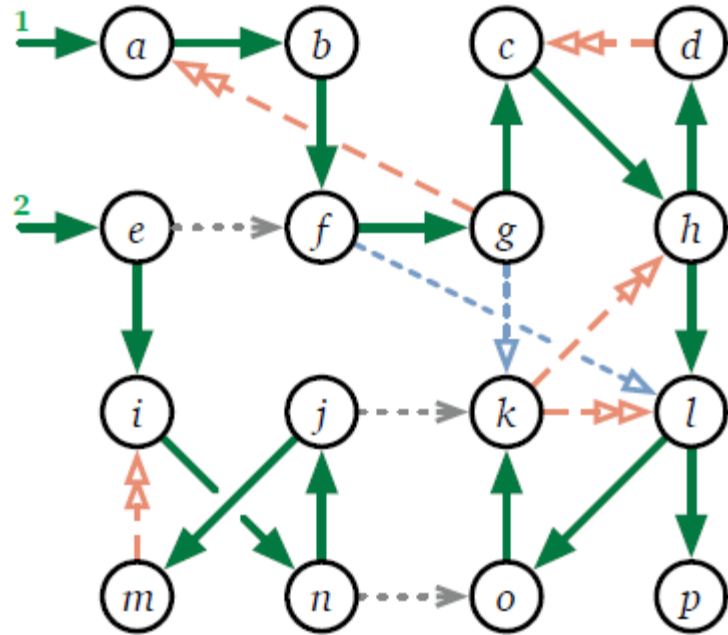
Recursion Stack - Time diagram



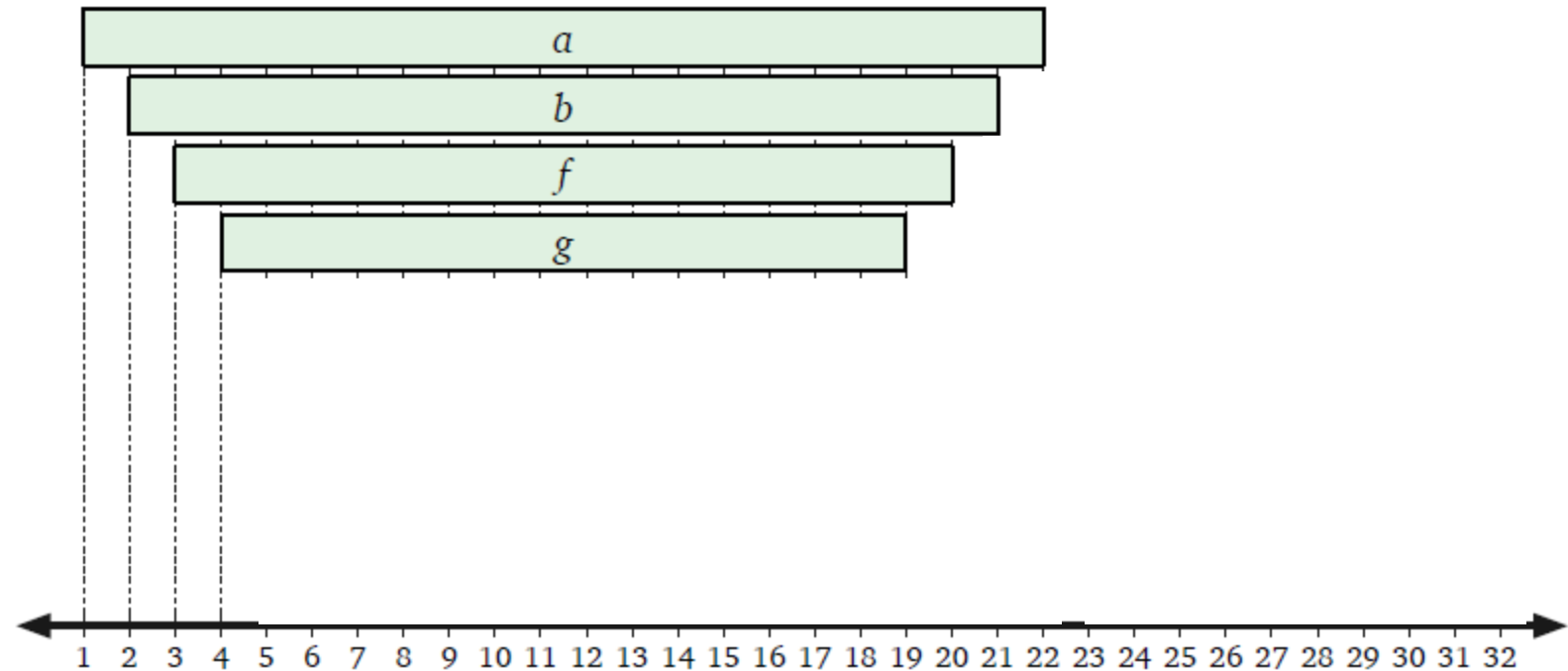
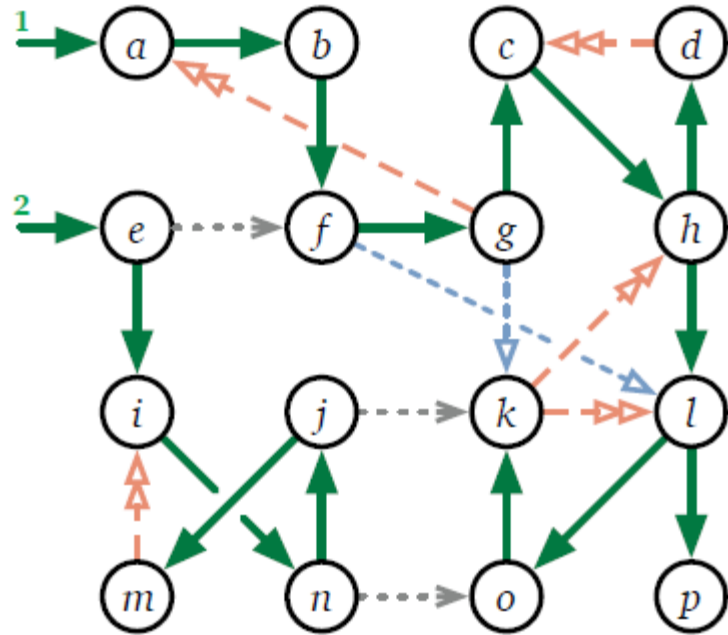
Stack - Time diagram



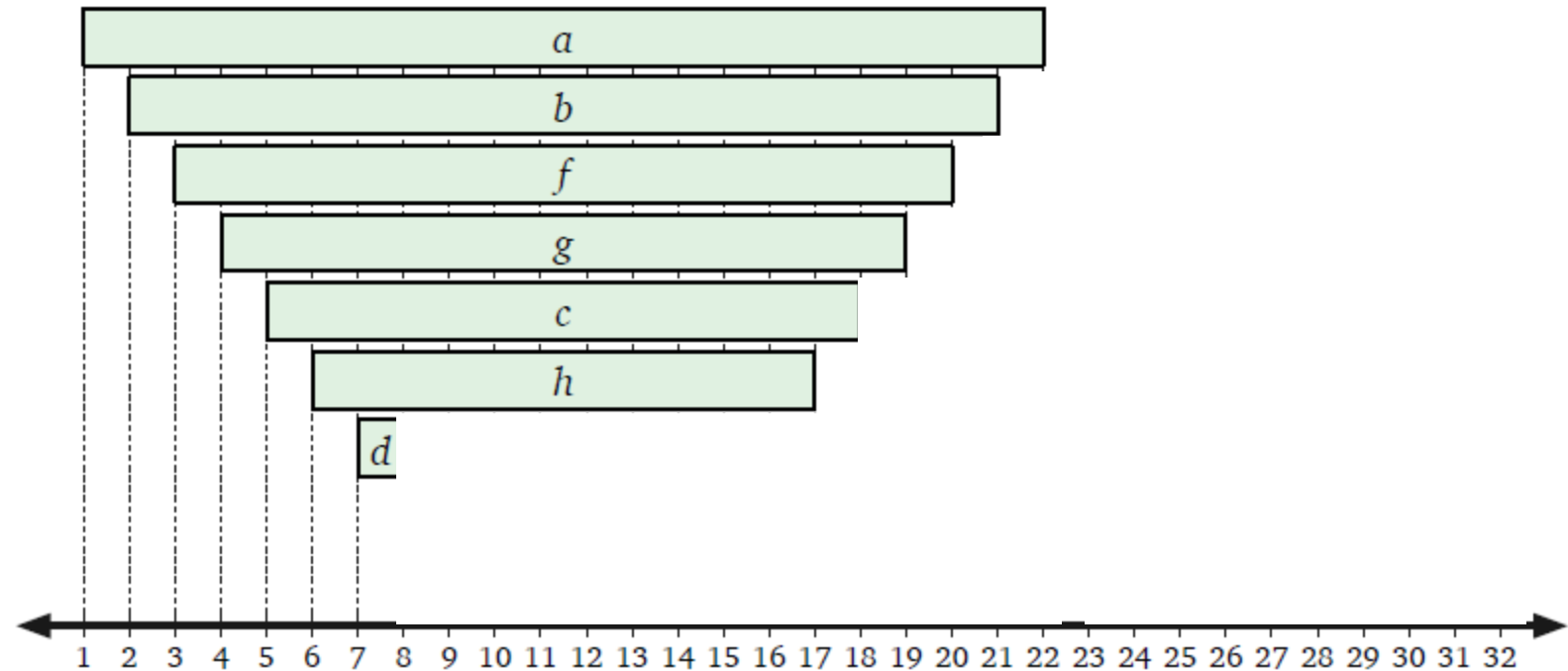
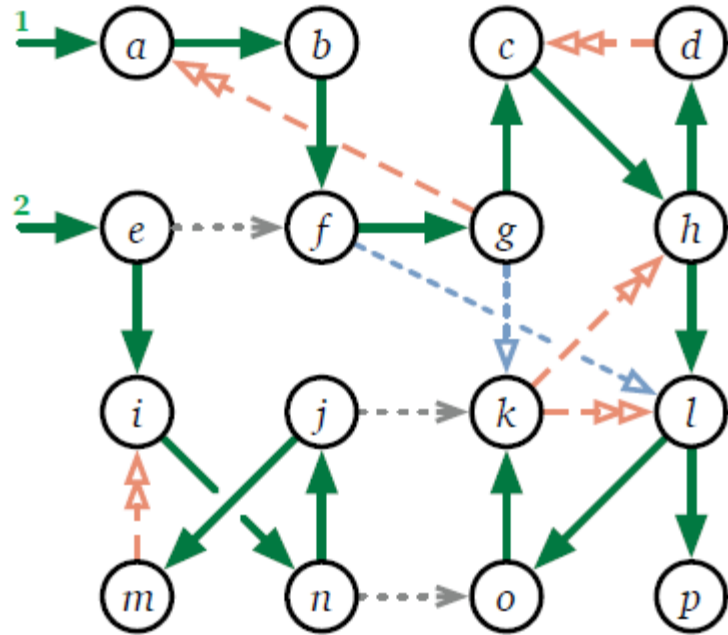
Stack - Time diagram



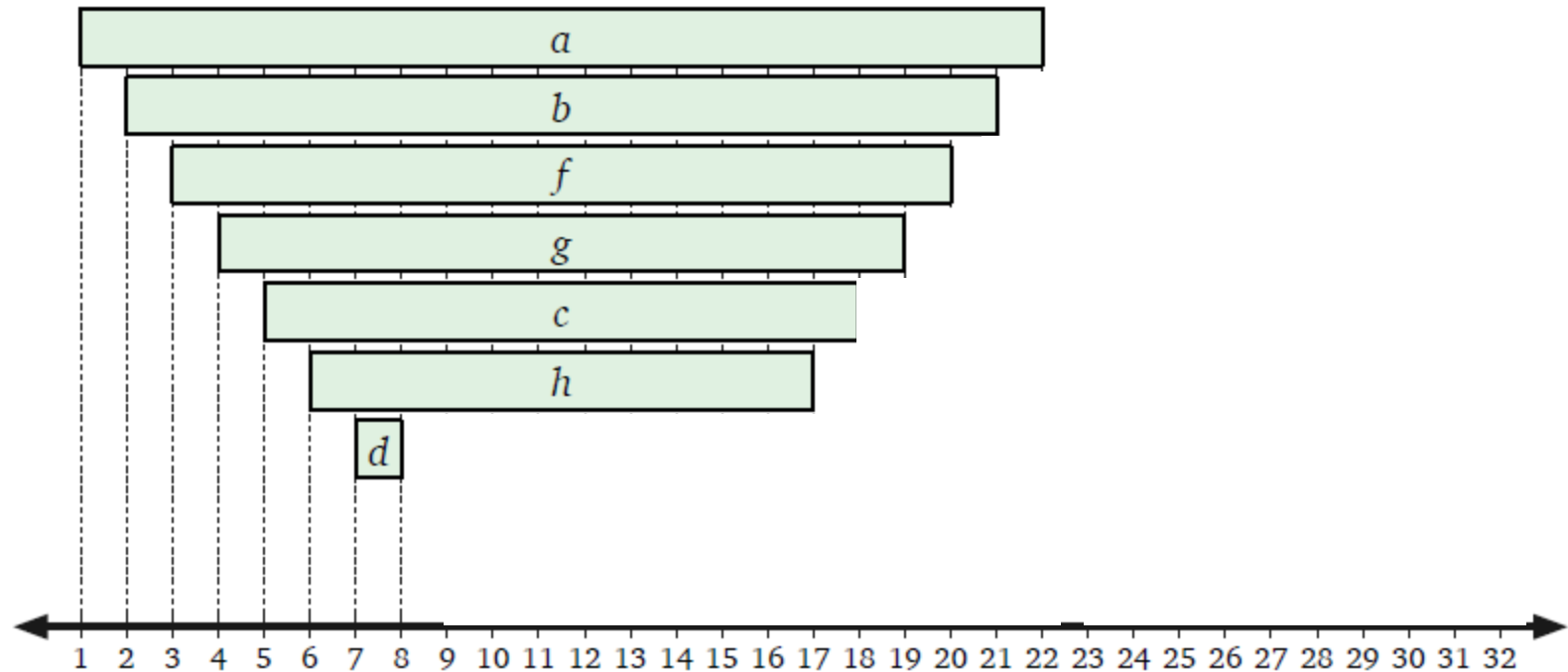
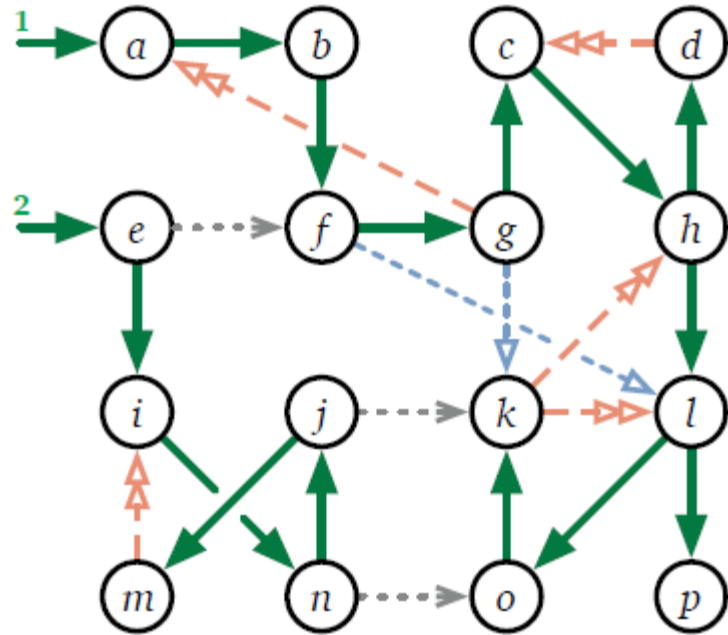
Stack - Time diagram



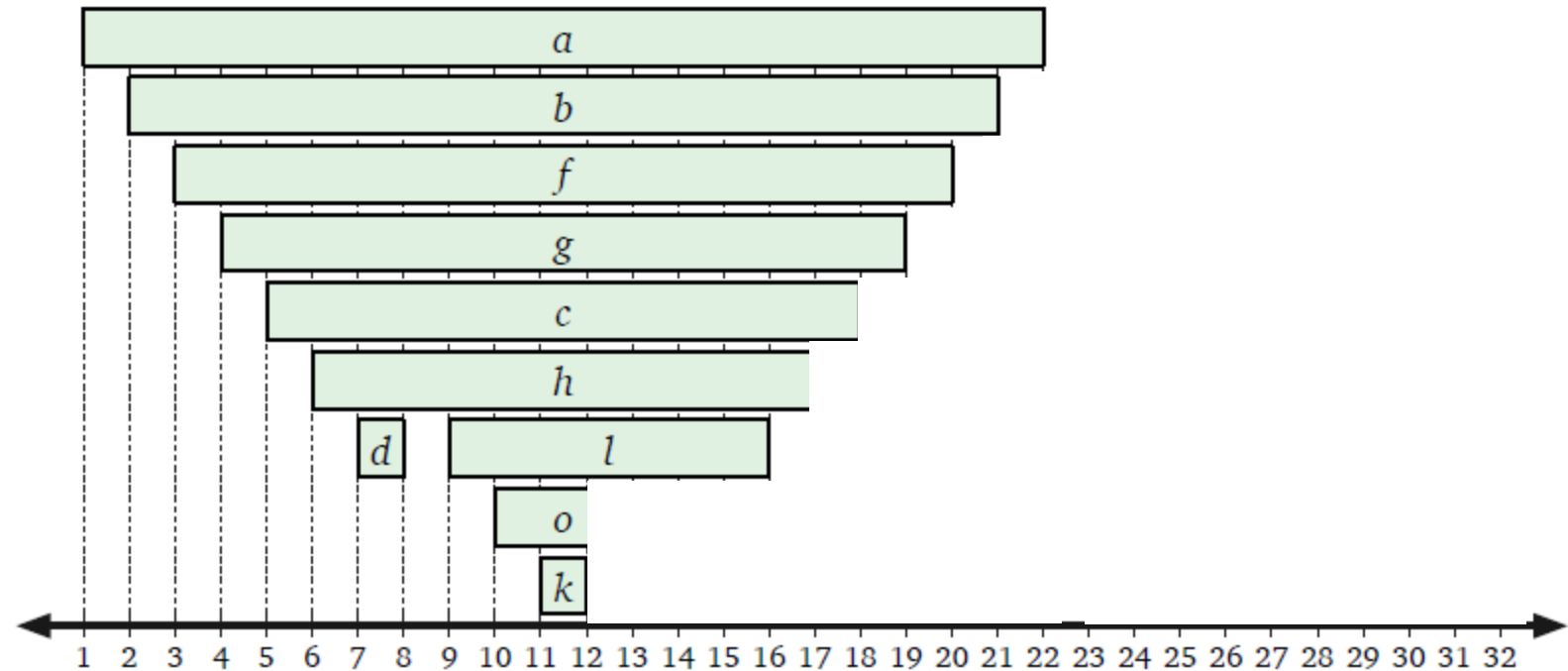
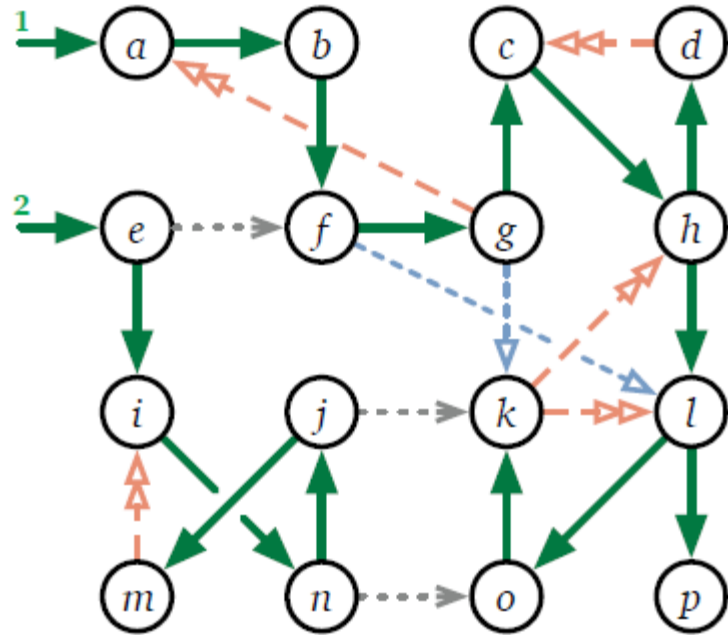
Stack - Time diagram



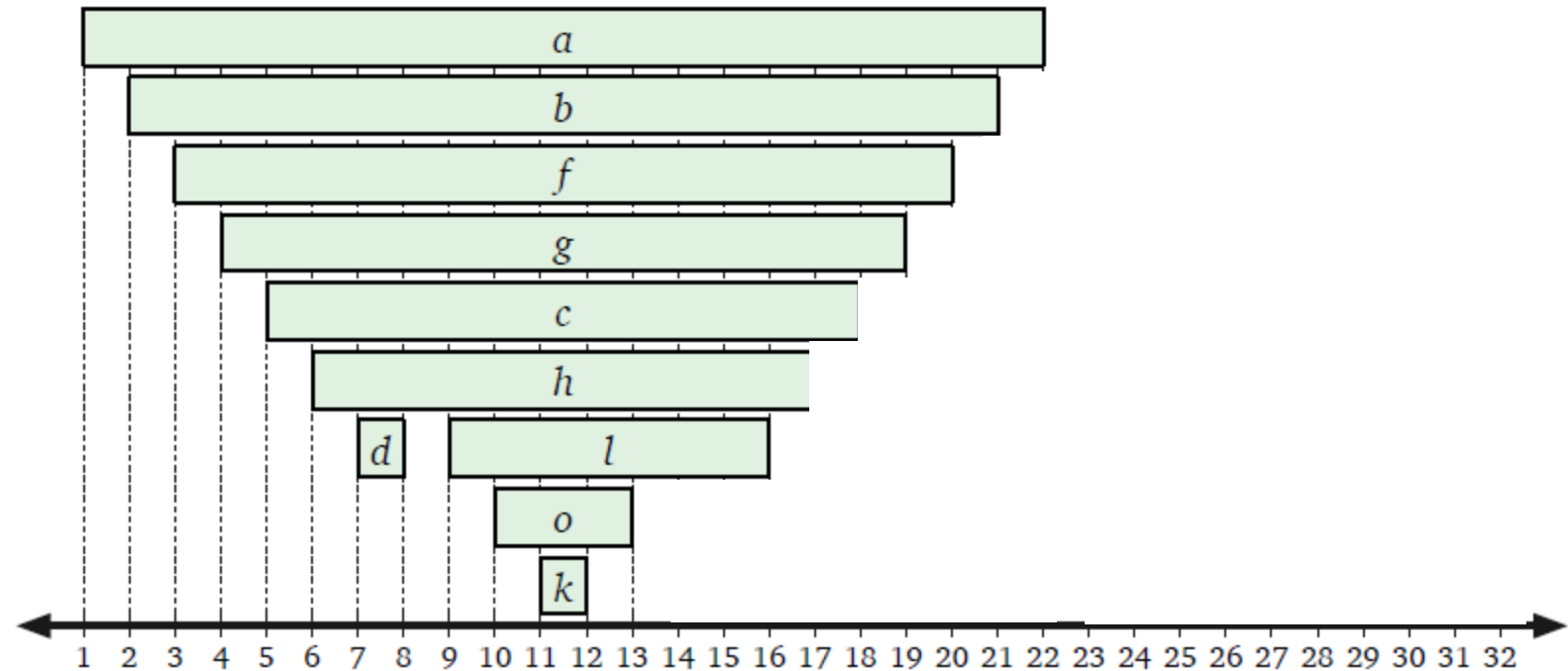
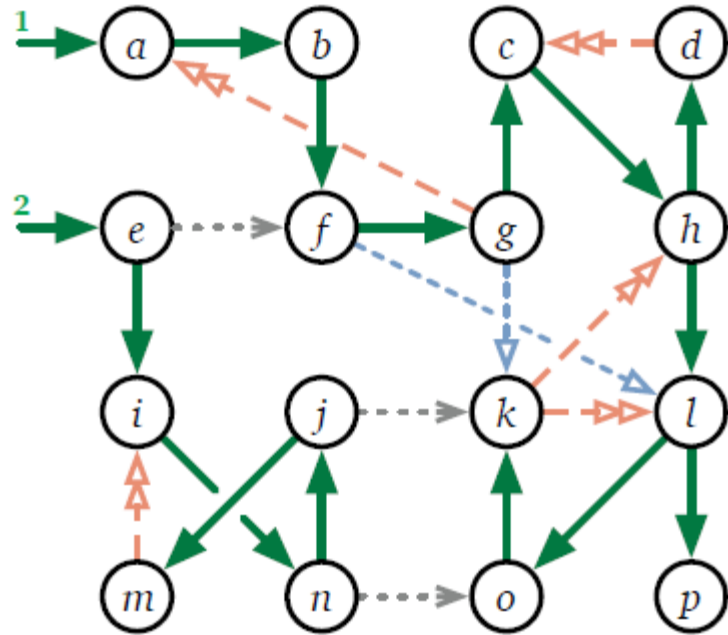
Stack - Time diagram



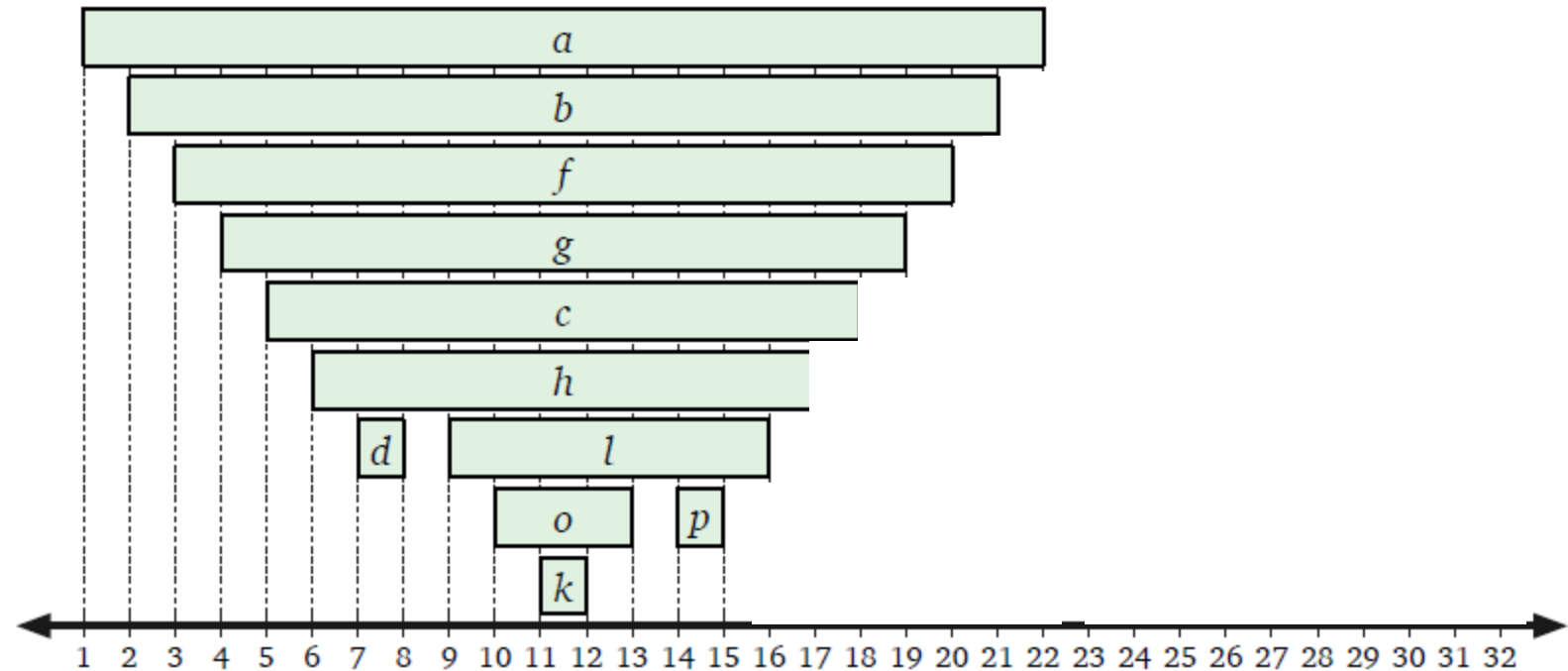
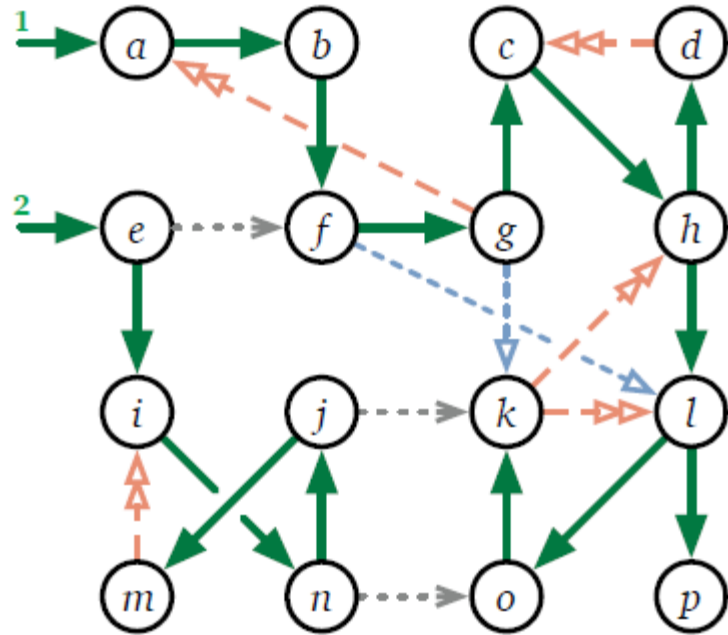
Stack - Time diagram



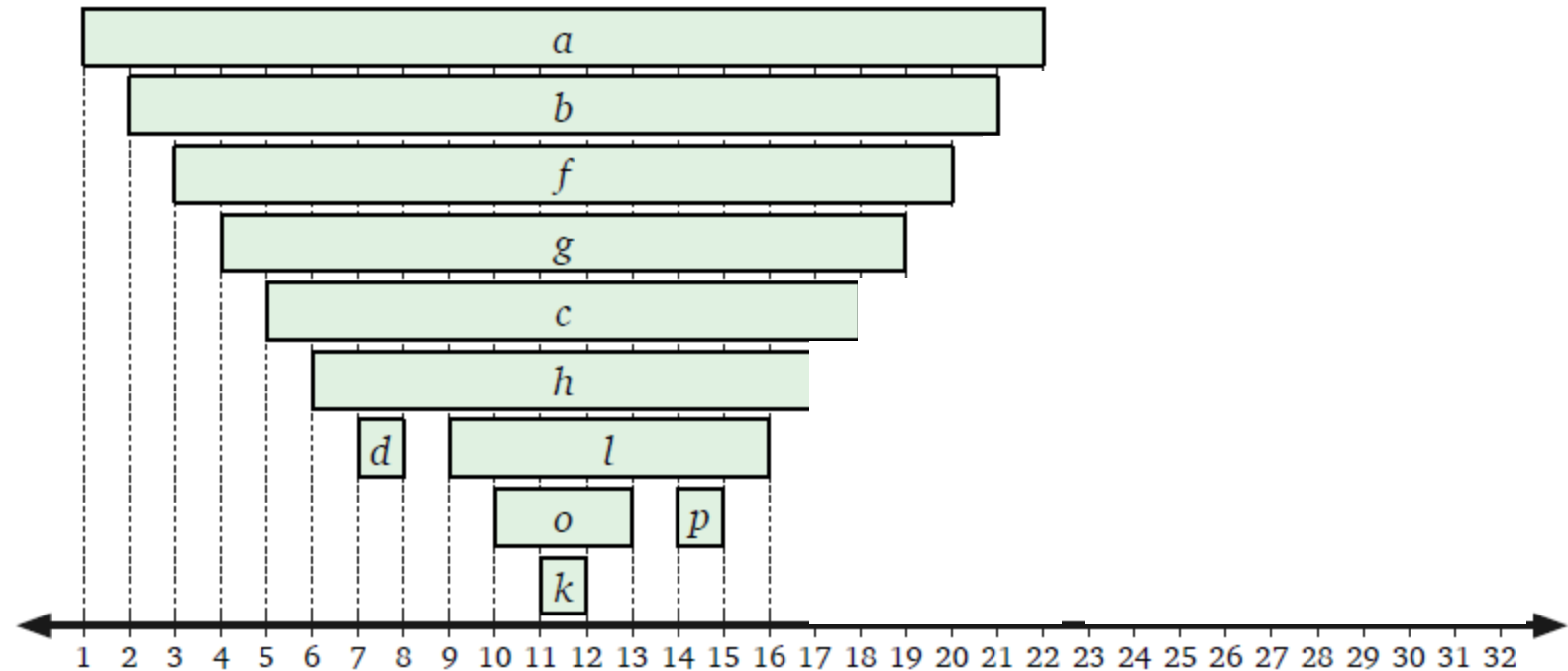
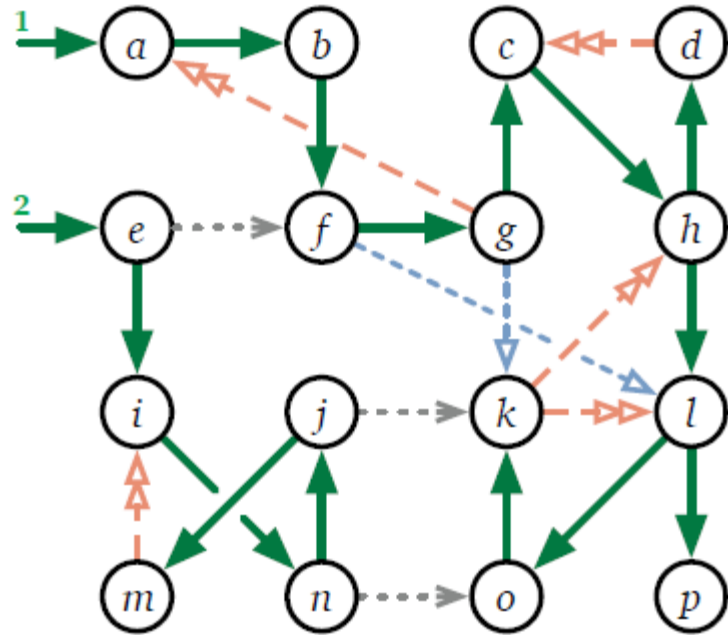
Stack - Time diagram



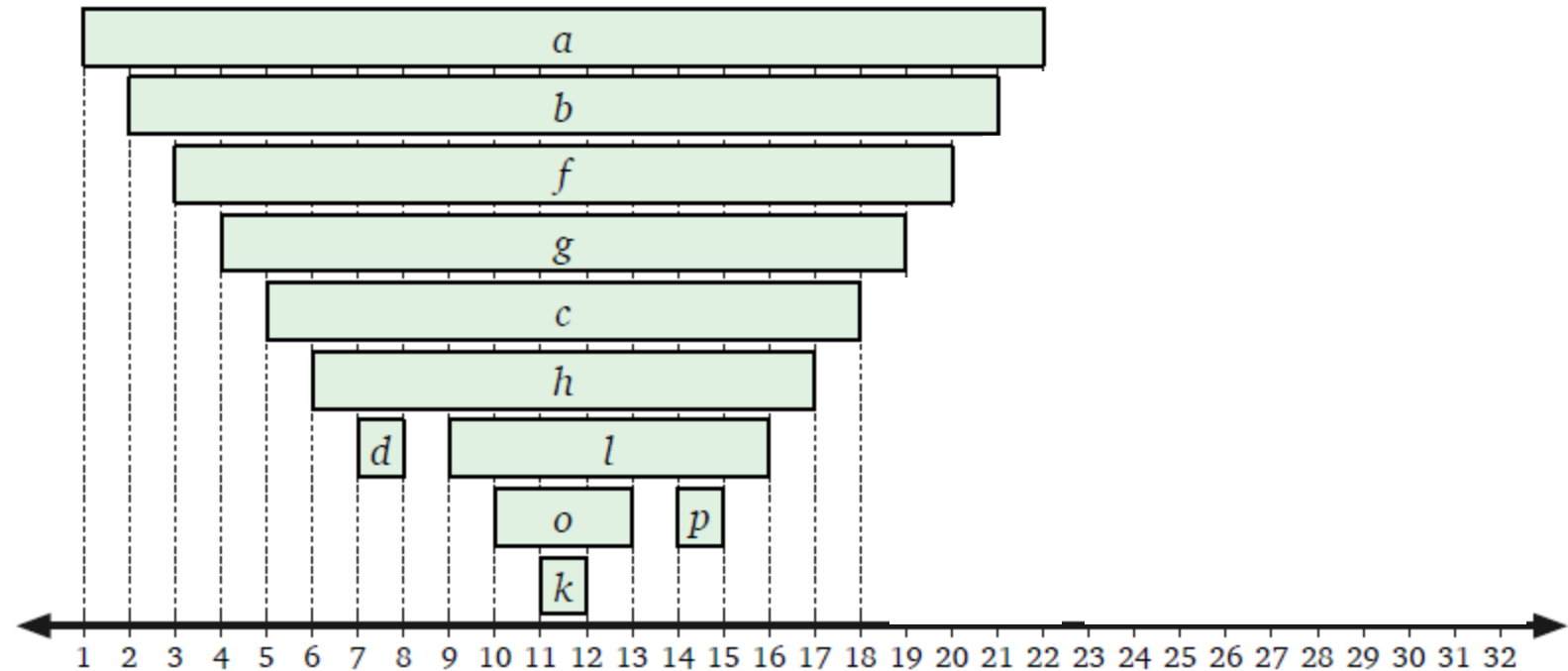
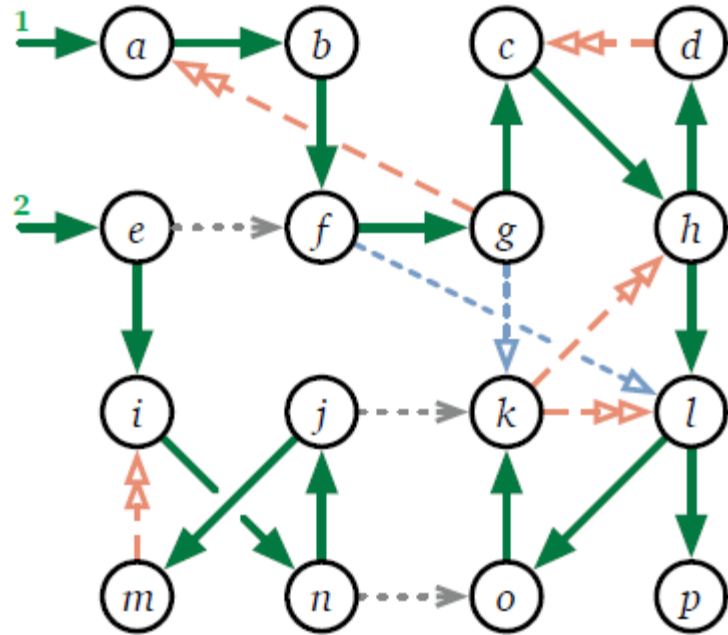
Stack - Time diagram



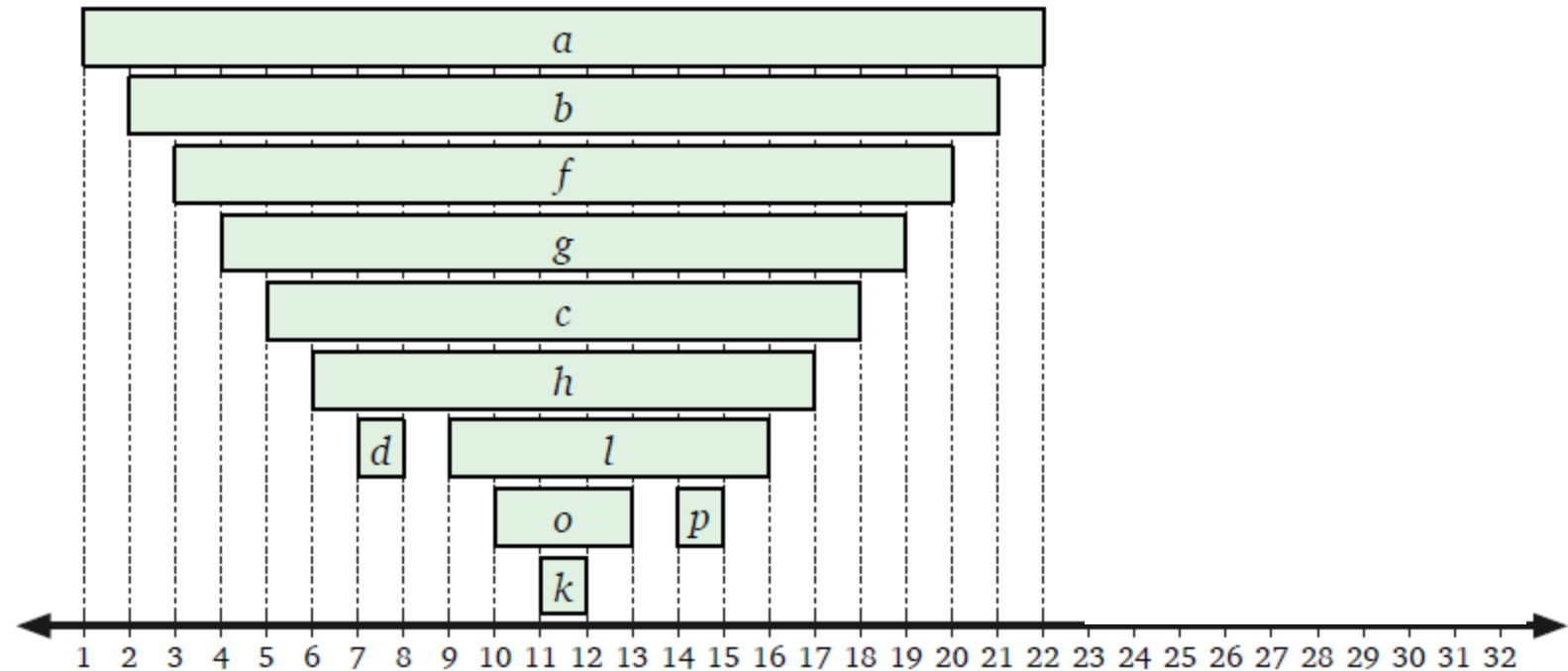
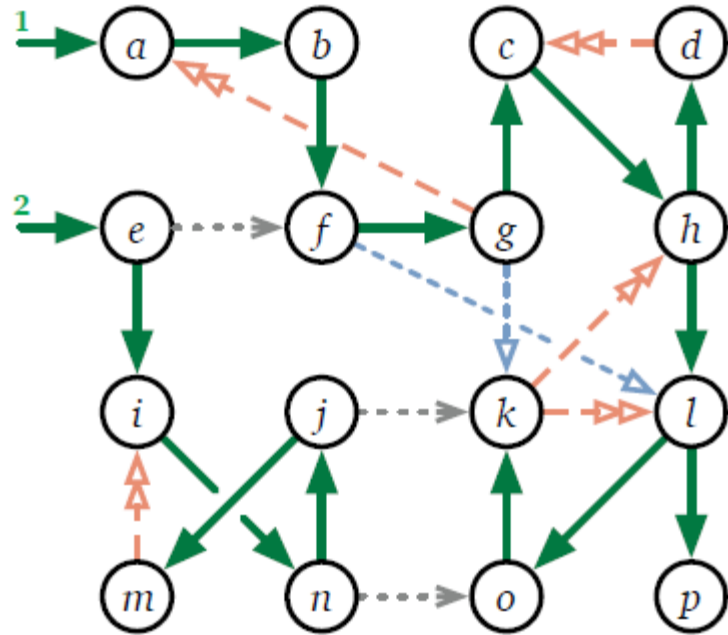
Stack - Time diagram



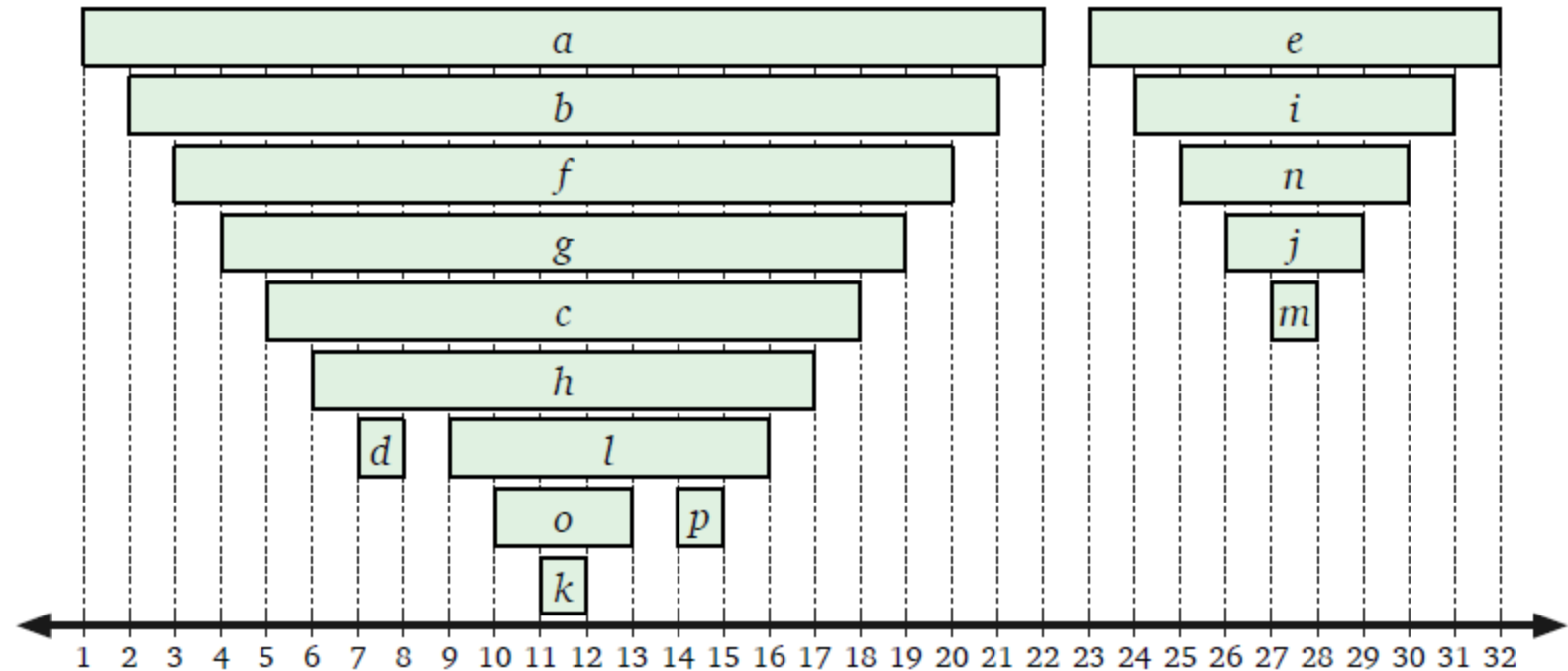
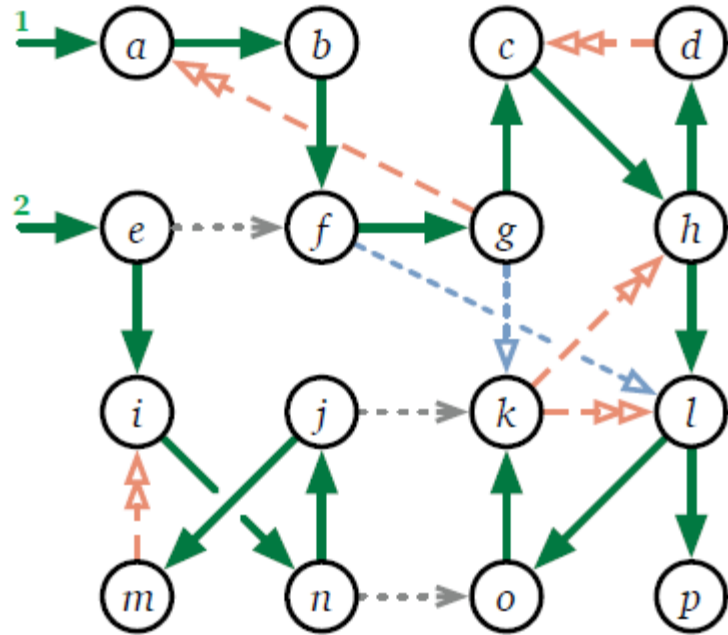
Stack - Time diagram



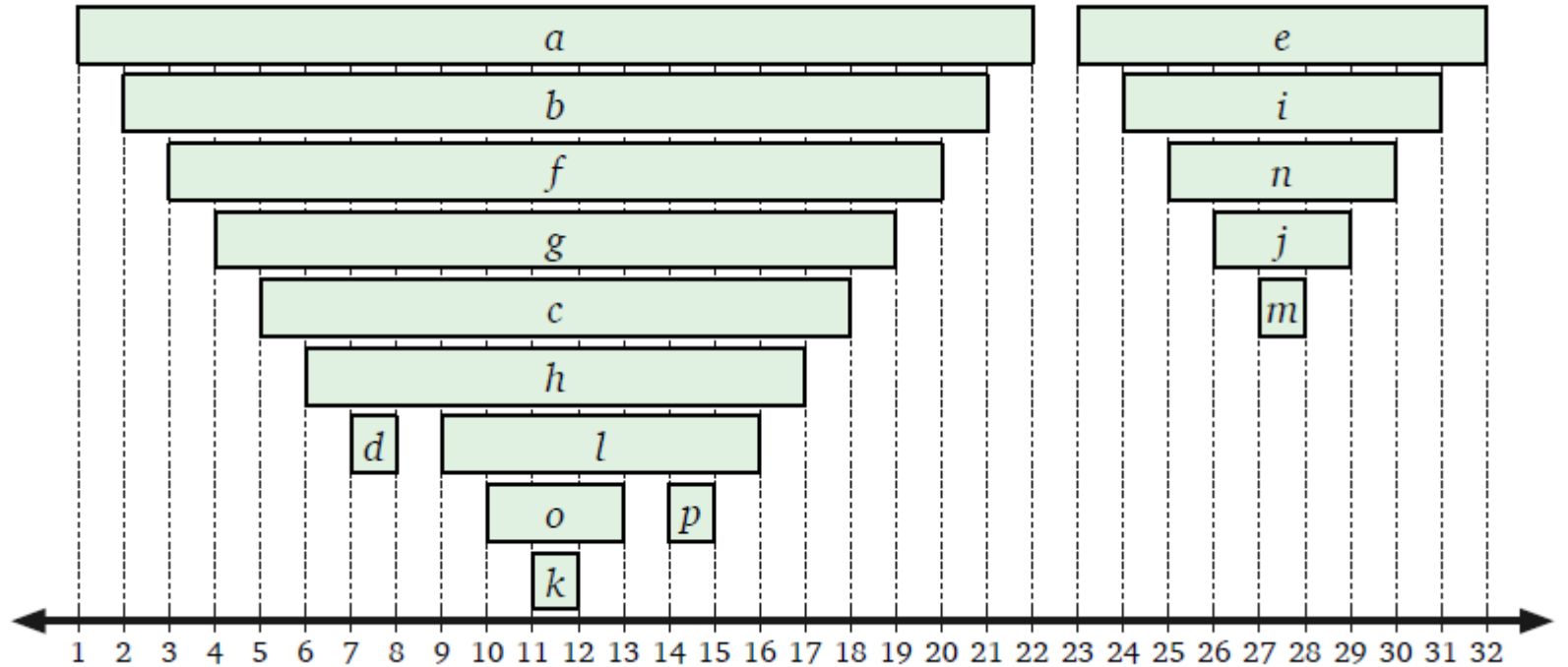
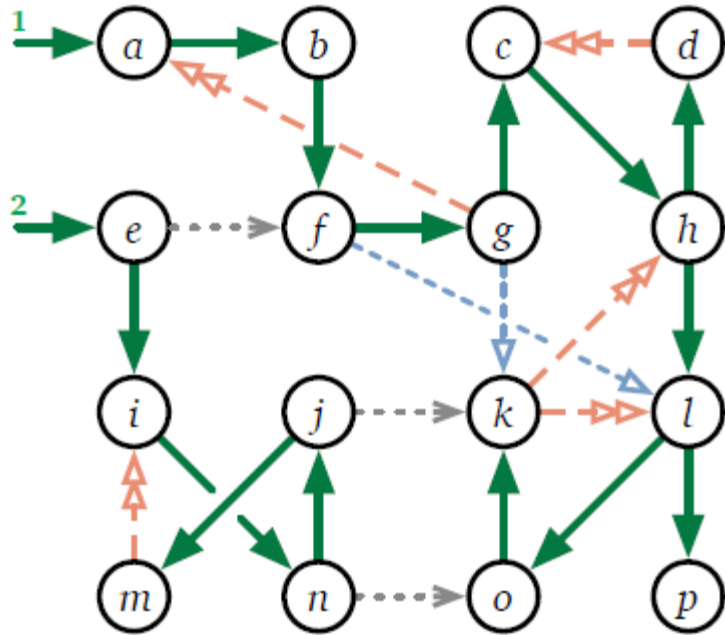
Stack - Time diagram



Stack - Time diagram



Preorder and postorder traversal of DFS Forest



Preorder

a b f g c h d l o k p e i n j m

pre(v)

post(v)

startList.add(v)

finishList.add(v)

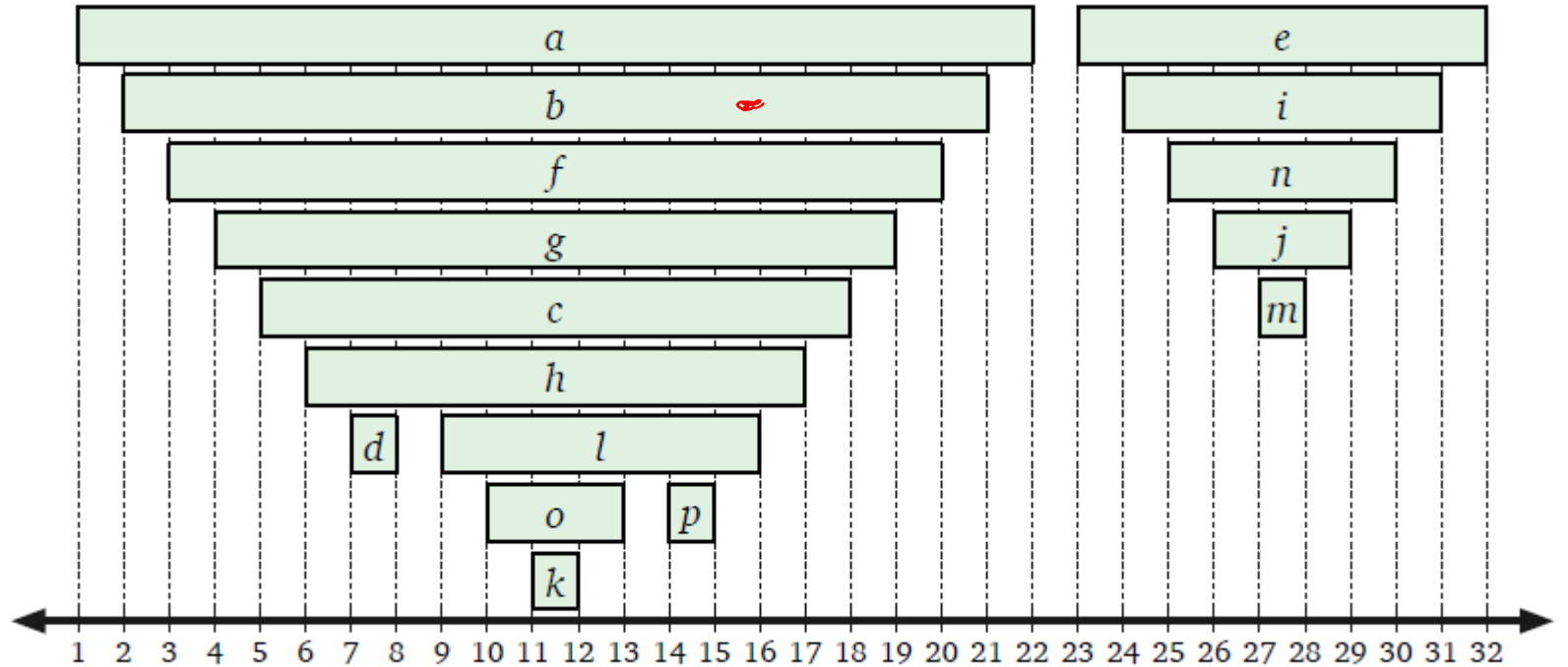
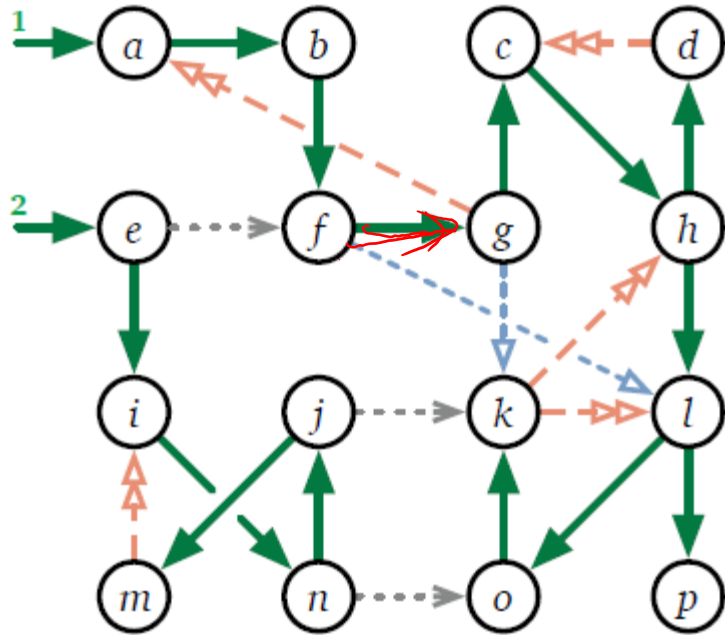
postorder

d o p l

Classifying Vertices

- v is **new** if $\text{DFS}(v)$ is not called
 - $\text{clock} < \underline{v.\text{start}}$
- v is **active** if $\text{DFS}(v)$ is called but not returned
 - $\underline{v.\text{start}} \leq \underline{\text{clock}} < \underline{v.\text{finish}}$
- v is **finished** if $\text{DFS}(v)$ has returned
 - $\underline{v.\text{finish}} \leq \text{clock}$

Classify Edges

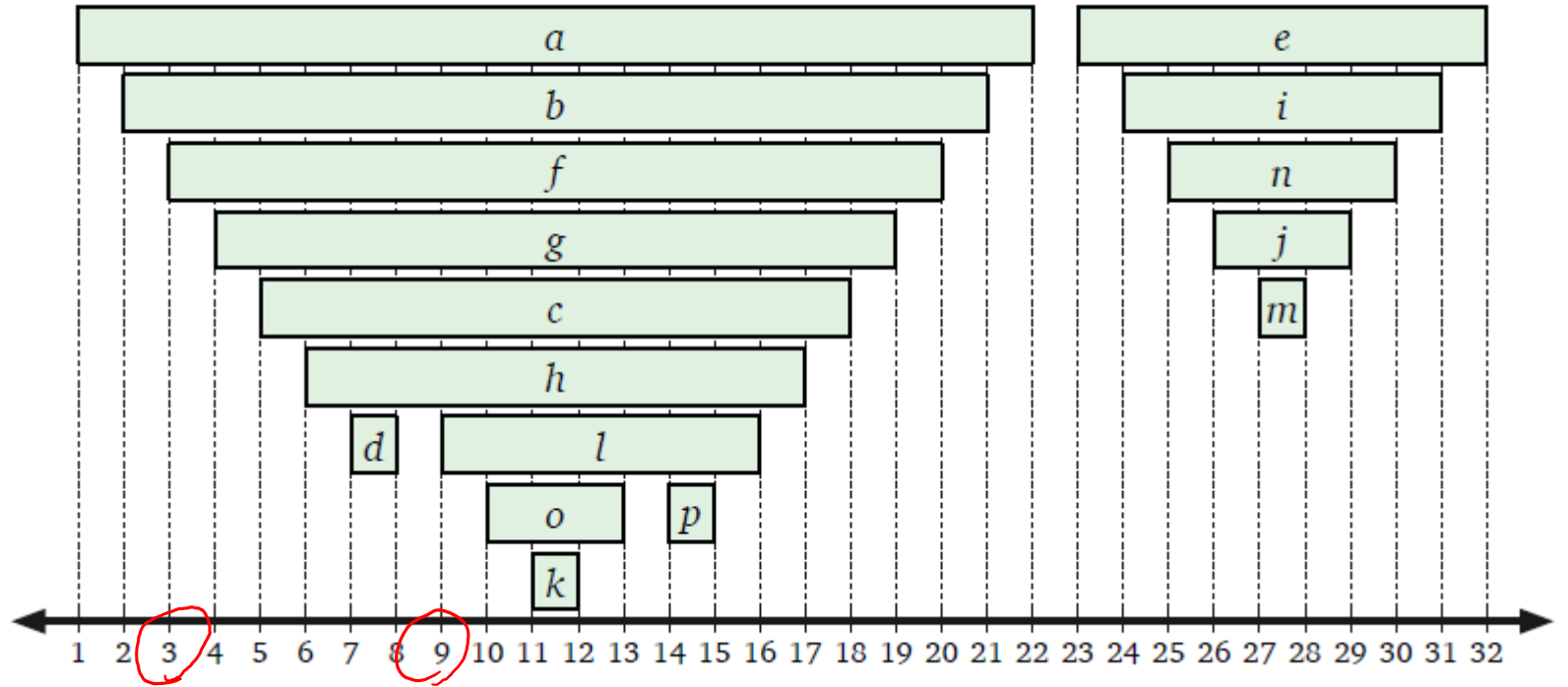
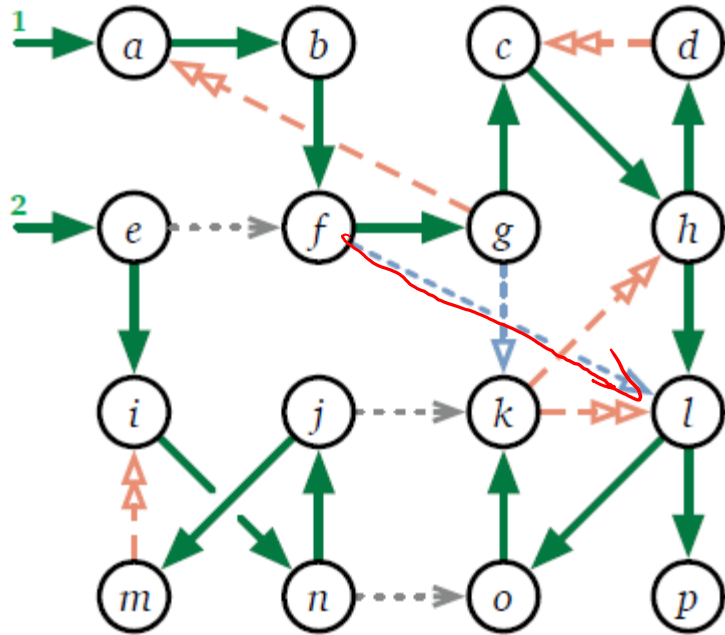


- $u.start < \underline{v.start} < \underline{v.finish} < u.finish$
 - v is reachable from u
 - u is an ancestor of v in DFS tree

v is on top of u on the stack

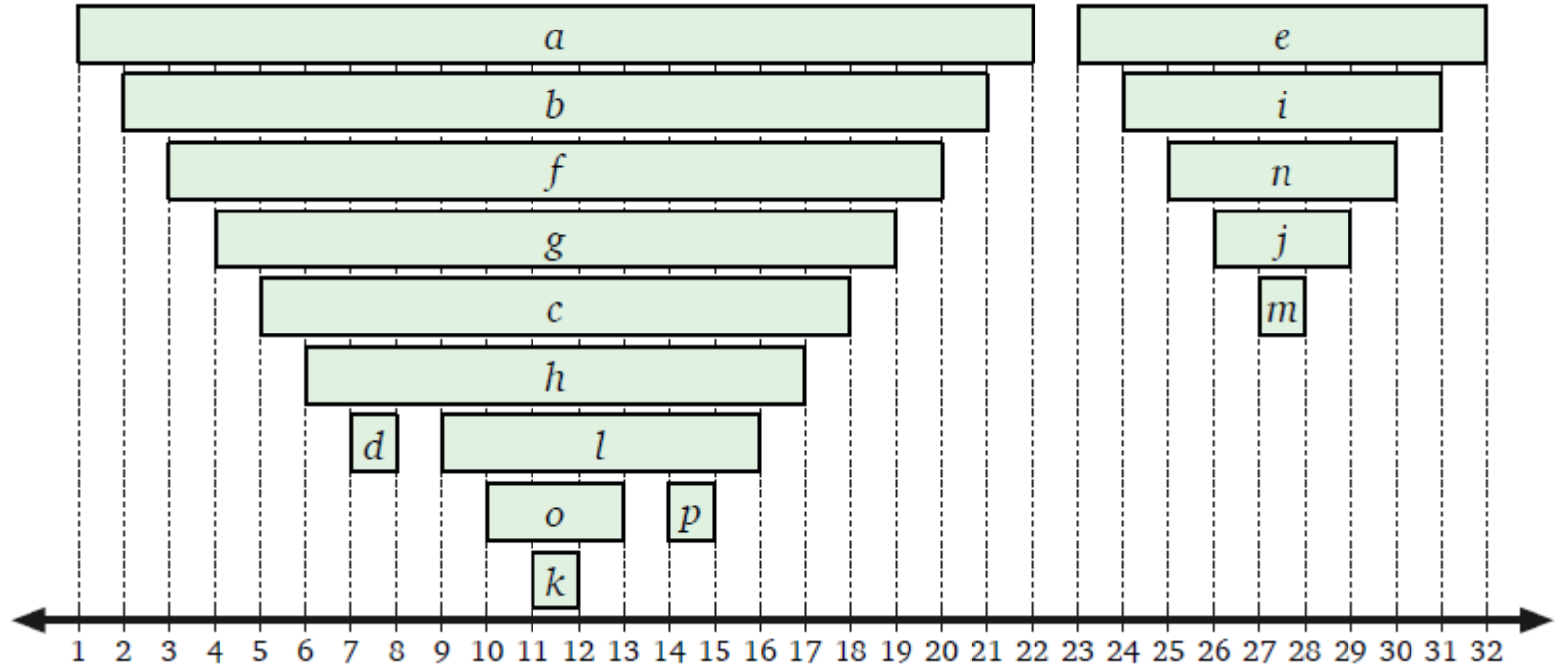
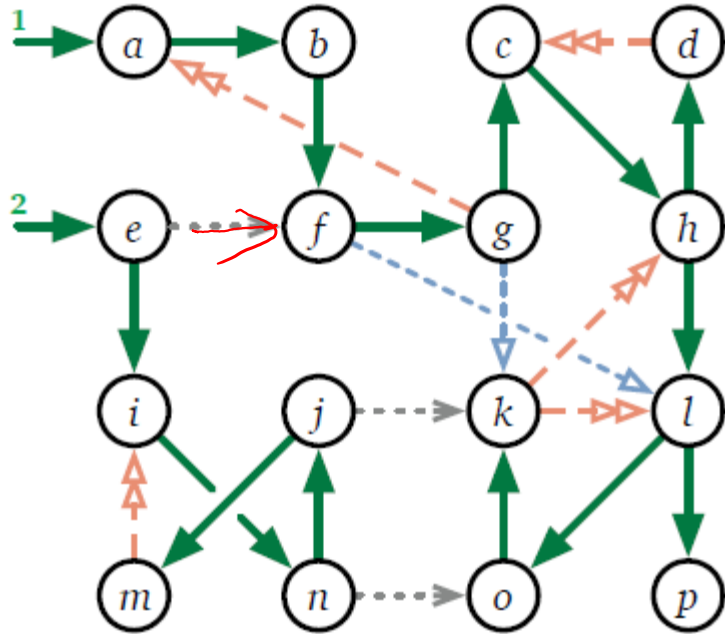
Classify Edges

$(F, 0)$ $3 < 9 < 16 < 20$



- consider $u \rightarrow v$ and suppose v is new when $\text{DFS}(u)$ begins
 - $u.\text{start} < v.\text{start} < v.\text{finish} < u.\text{finish}$ ✓
 - If $\text{DFS}(u)$ calls $\text{DFS}(v)$ directly, then $u \rightarrow v$ is a tree edge
 - Otherwise $u \rightarrow v$ is a forward edge

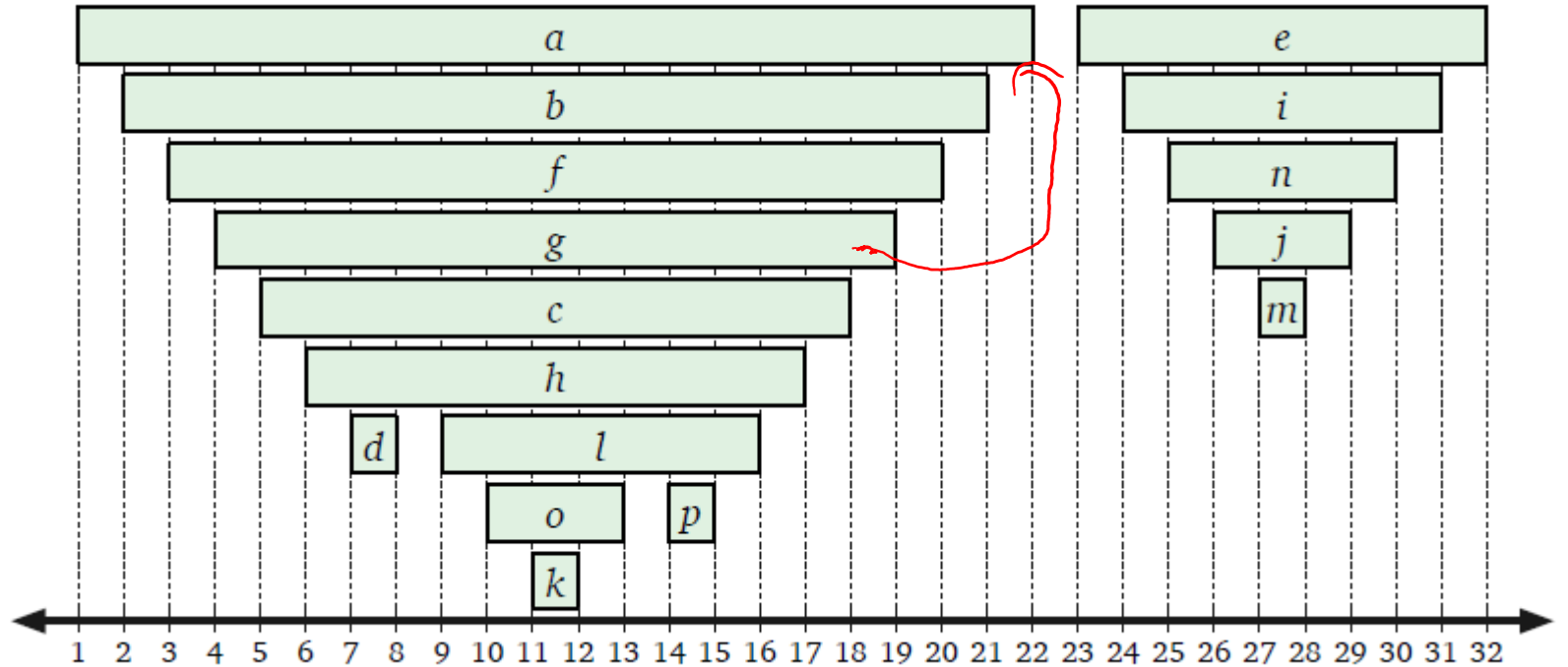
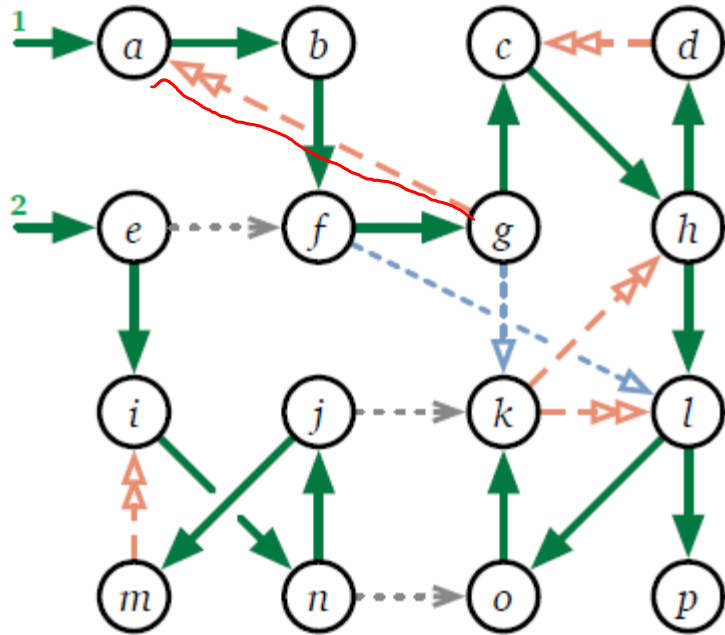
Classify Edges



$$3^f < 2^o < 2^s < 3^2$$

- consider $u \rightarrow v$ and v is finished when DFS(u) begins
 - $v.start < \overline{v.finish} < \overline{u.start} < \overline{u.finish}$, then $u \rightarrow v$ is a cross edge

Classify Edges

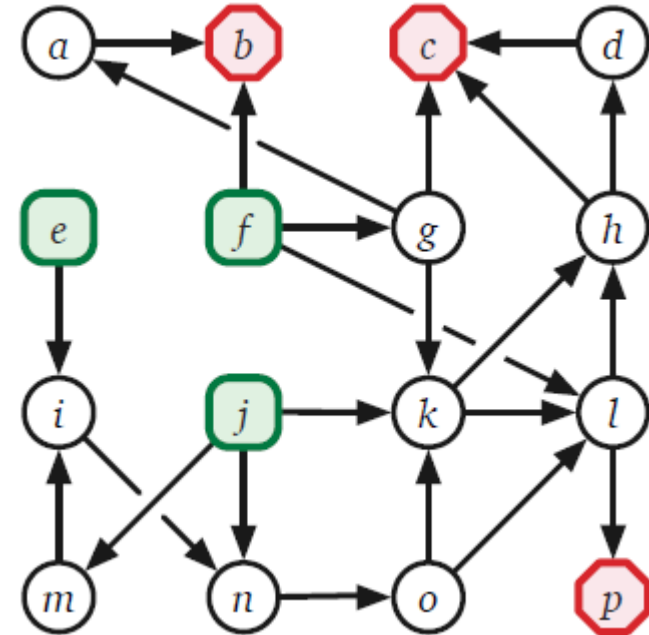


$$1 < 4 < 19 < 22$$

- consider $u \rightarrow v$ and v is active when $\text{DFS}(u)$ begins
 - $v.\text{start} < u.\text{start} < u.\text{finish} < v.\text{finish}$,
 - $u \rightarrow v$ is a back edge

Directed Acyclic Graph

- Source vertices have no incoming edges
- Sink vertices have no outgoing vertices
- DAG has at least one source vertex and one sink vertex
- Is G a DAG?



Is G a DAG?

What would you change to the code below?

```
dfsAll(G) {  
    initialize(G)  
    for each v in G do  
        unmark v  
    for each v in G do  
        if v is unmarked  
            dfs(v)  
}
```

```
dfs(v) {  
    mark v  
    pre(v)  
    for each (v, w) in G do  
        if w is unmarked  
            w.parent = v  
            dfs(w)  
    post(v)  
}
```

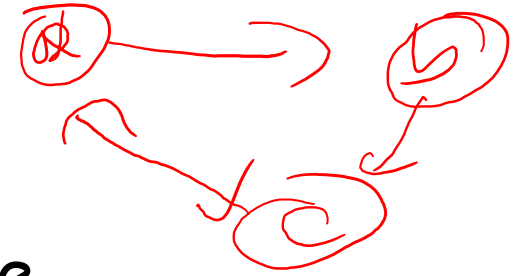
Is G a DAG?

A linear time algorithm:

```
isDAGAll(G) {  
    for each v in G do  
        v.status = new  
    for each v in G do  
        if v.status is new  
            if (!isDAG(v)) return false  
    return true  
}
```

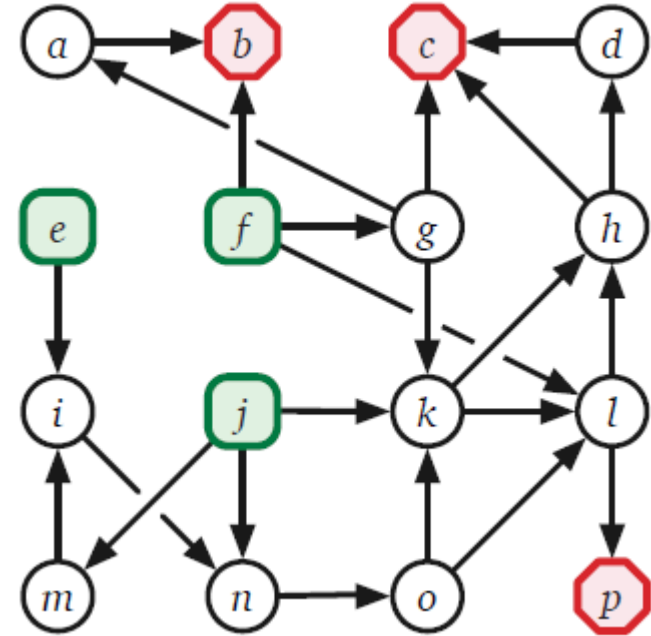
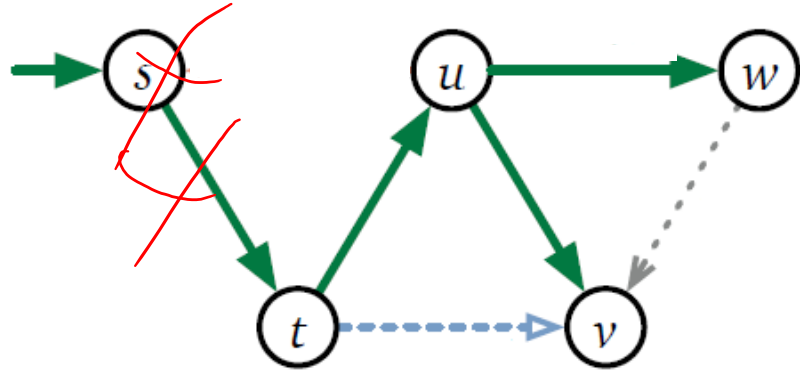
```
isDAG(v) {  
    v.status = active  
    for each (v, w) in G do  
        if w.status is active  
            return false  
        else if w.status is new  
            if (!isDAG(w))  
                return false  
    v.status = finished  
    return true  
}
```

Topological Ordering

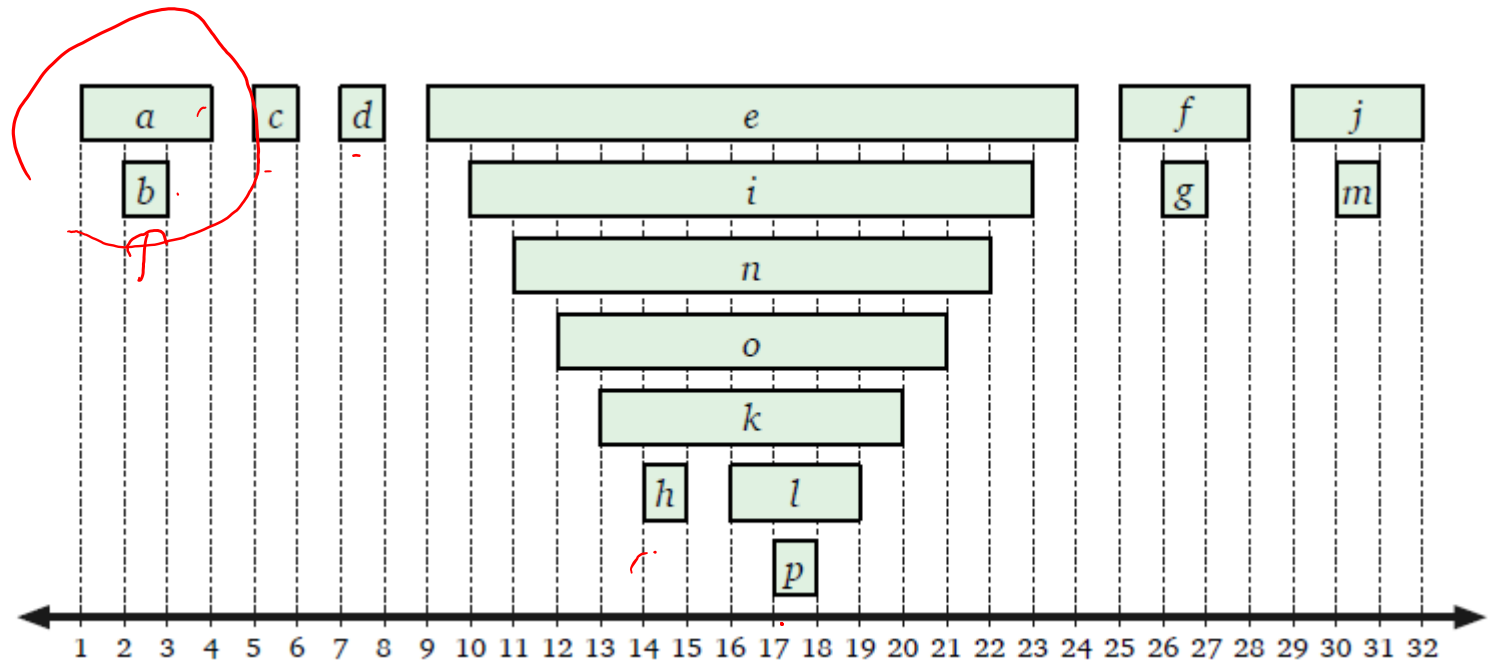
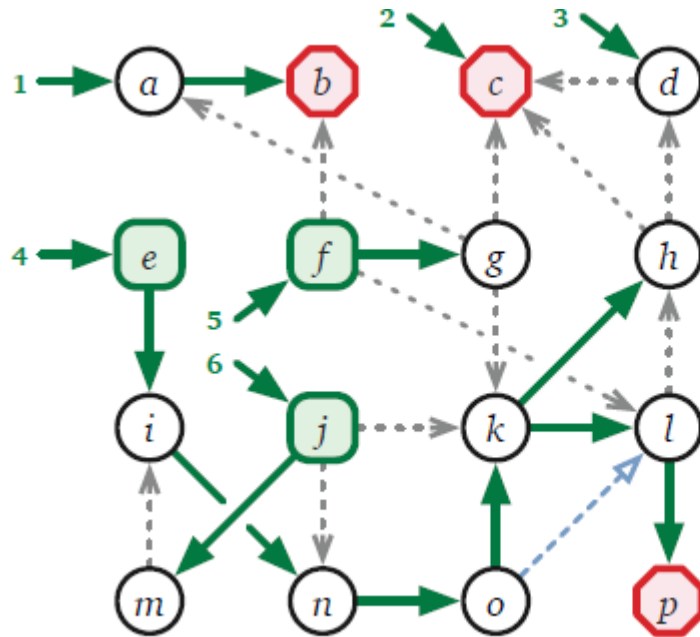


- Informally, place all vertices in a horizontal line such that edges go only from left to right
- Topological ordering of G is a total order $<$, on vertices such that
 - $u < v$ for every edge $u \rightarrow v$
- Topological ordering is only possible if G is a DAG

Topological Sort



Topological Sort



Cab

Topological Sort Algorithm

Reverse of post order traversal

```
dfsAll(G) {  
    initialize(G)  
    for each v in G do  
        unmark v  
    for each v in G do  
        if v is unmarked  
            dfs(v)  
}
```

initialize(G)

pre(v)

```
dfs(v) {  
    mark v  
    pre(v)  
    for each (v, w) in G do  
        if v is unmarked  
            w.parent = v  
            dfs(w)  
    post(v)  
}
```

post(v)

topList.addFirst(v)

Problem of the day

Let G be an undirected graph. Suppose we start with two coins on two arbitrarily chosen vertices of G . At every step, each coin *must* move to an adjacent vertex. Describe and analyze an efficient algorithm to compute the minimum number of steps to reach a configuration where both coins are on the same vertex, or to report correctly that no such configuration is reachable. The input to your algorithm consists of a graph $G = (V, E)$ and two vertices $u, v \in V$ (which may or may not be distinct).