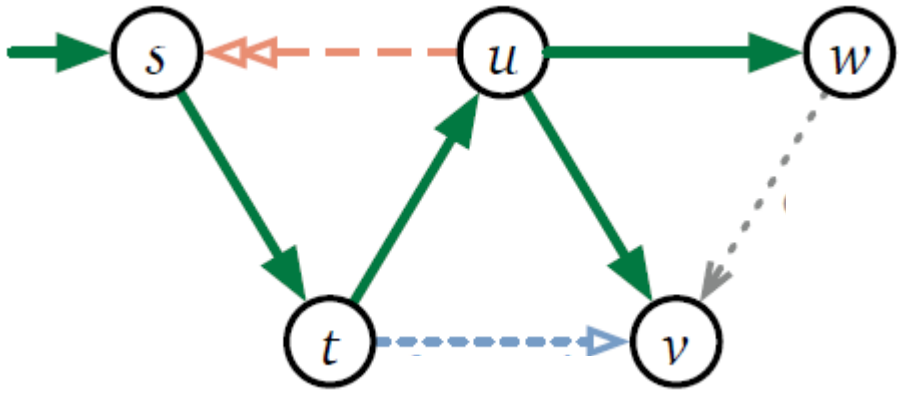
DFS

Sridhar Alagar

DFS in a directed Graph



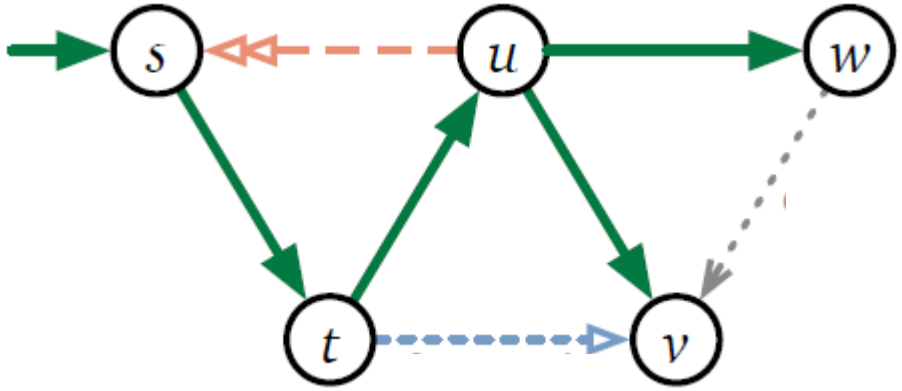
Use stack for DFS

```
wfs(s){
    put s into bag
    while bag not empty
          take v from bag
          if v is unmarked
             mark v
             for each (v, w) in G do
                put w in bag
}
```

```
dfs(v){
    if v is unmarked
       mark v
       for each (v, w) in G do
             dfs(w)
}
```

DFS

Wrapper method to visit all nodes




```
dfsAll(G){
    initialize(G)
    for each v in G do
      unmark v
    for each v in G do
      if v is unmarked
          dfs(v)
}
```

```
dfs(v){
  mark v
  pre(v)
  for each (v, w) in G do
      if w is unmarked
            w.parent = v
            dfs(w)
  post(v)
}
```

Preorder and postorder traversal of DFS Forest

Record when a node entered and left stack

```
dfsAll(G){
    initialize(G)
    for each v in G do
      unmark v
    for each v in G d0
      if v is unmarked
          dfs(v)
}
```

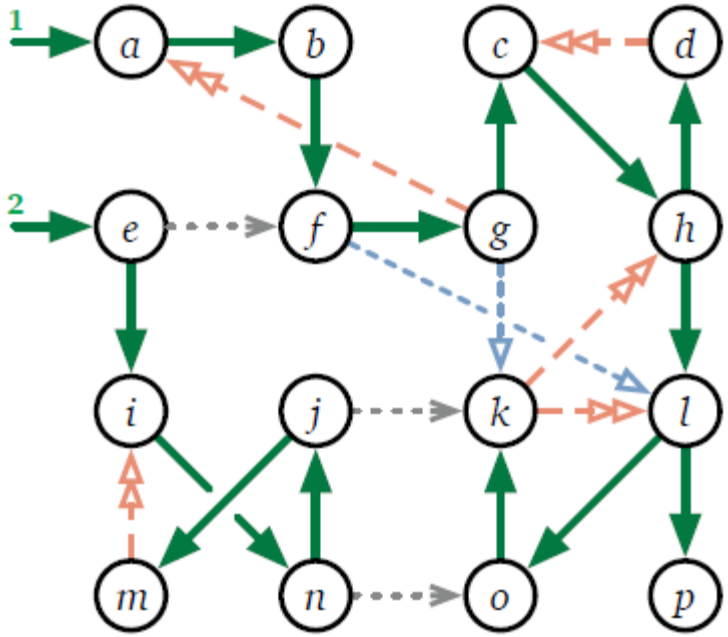
```
dfs(v){
  mark v
  pre(v)
  for each (v, w) in G do
      if v is unmarked
          w.parent = v
          dfs(w)
  post(v)
}
```

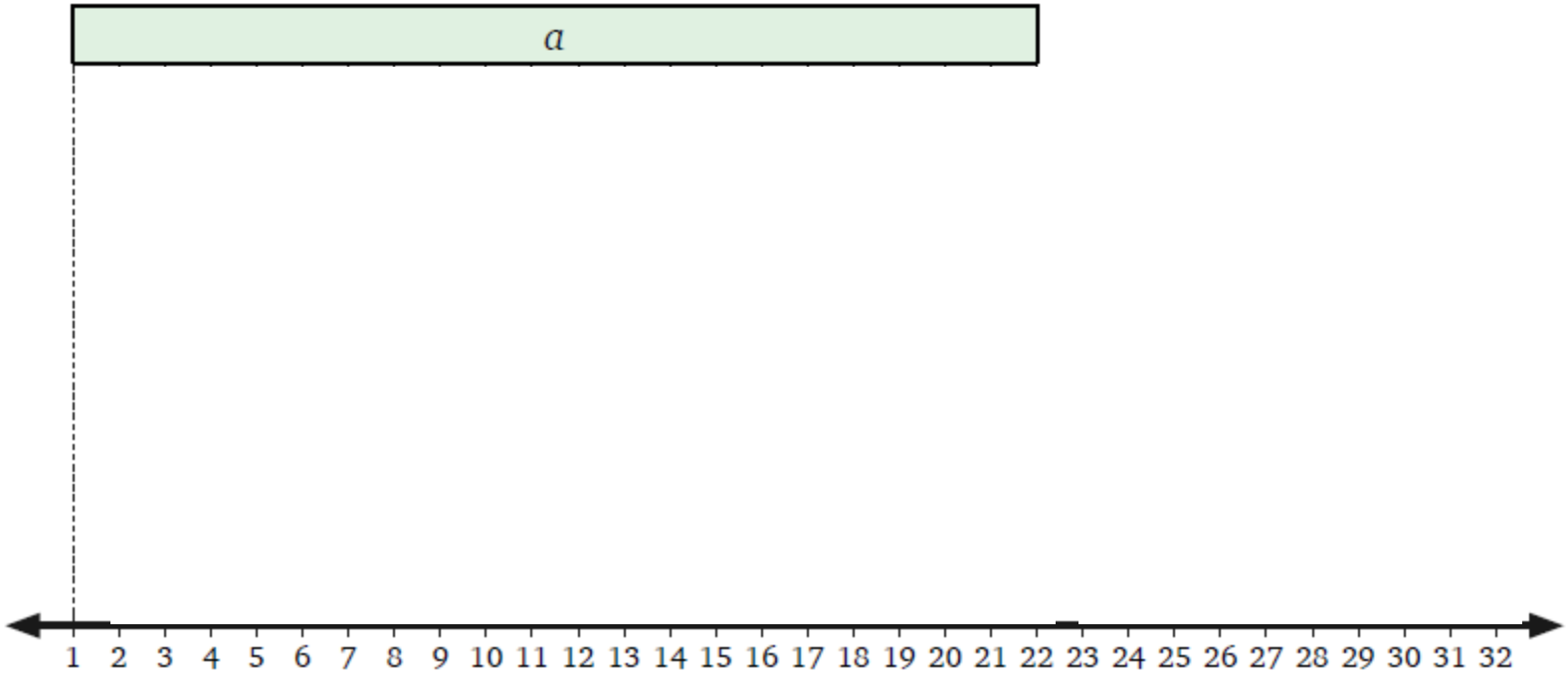
```
initialize(G)
  clock = 0
```

```
pre(v)
  clock++
  v.start = clock
```

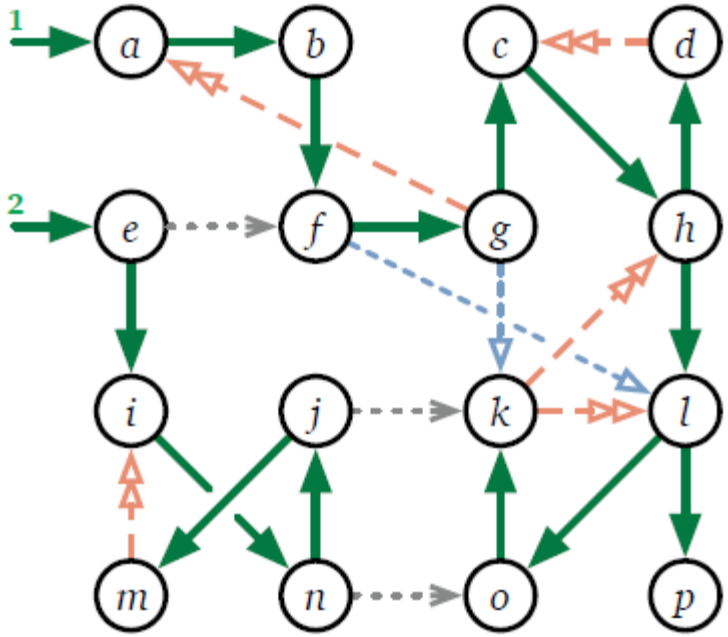
```
post(v)
  clock++
  v.finish = clock
```

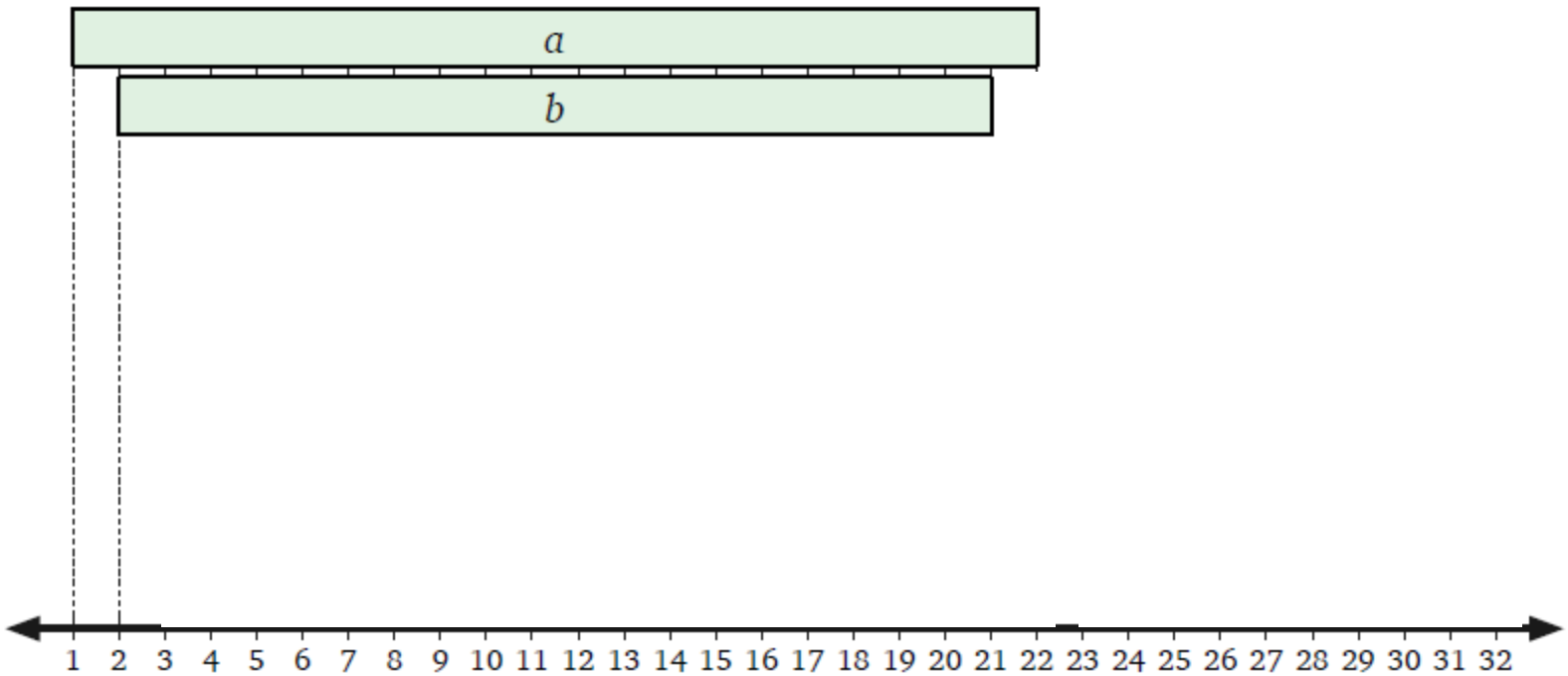
Recursion Stack – Time diagram



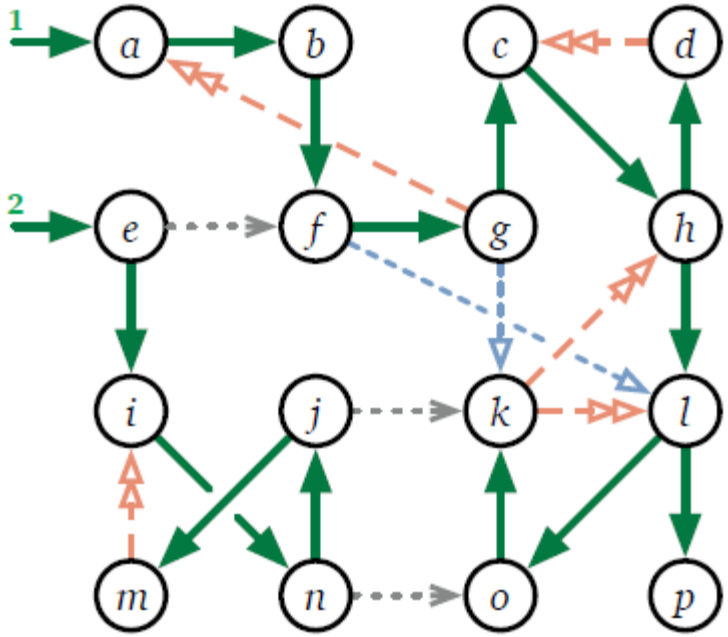


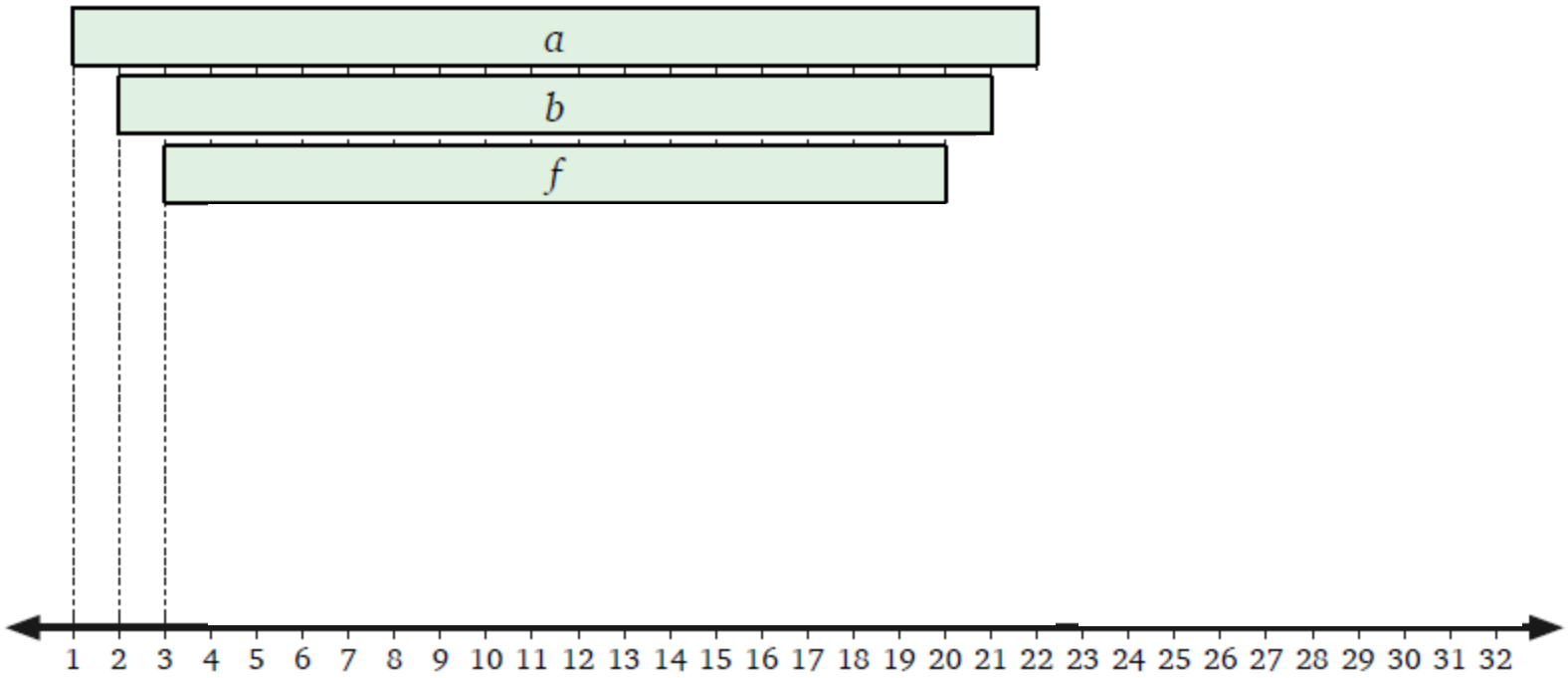
Stack – Time diagram



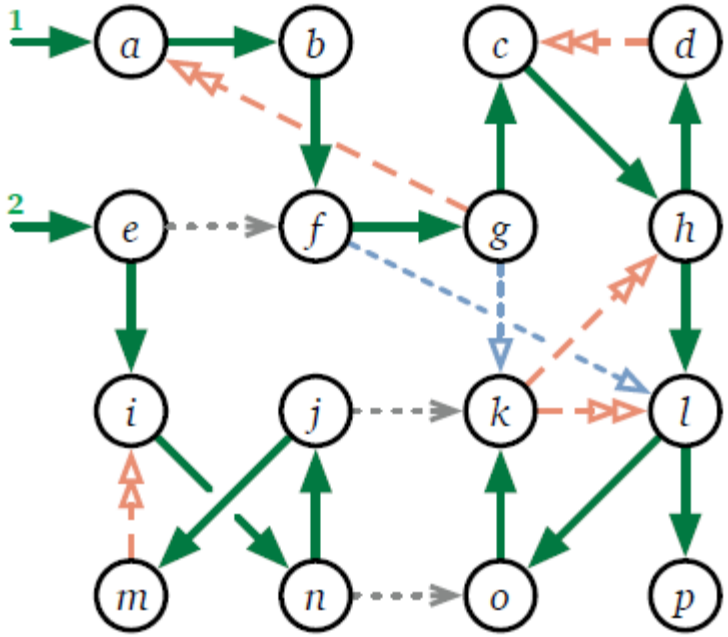


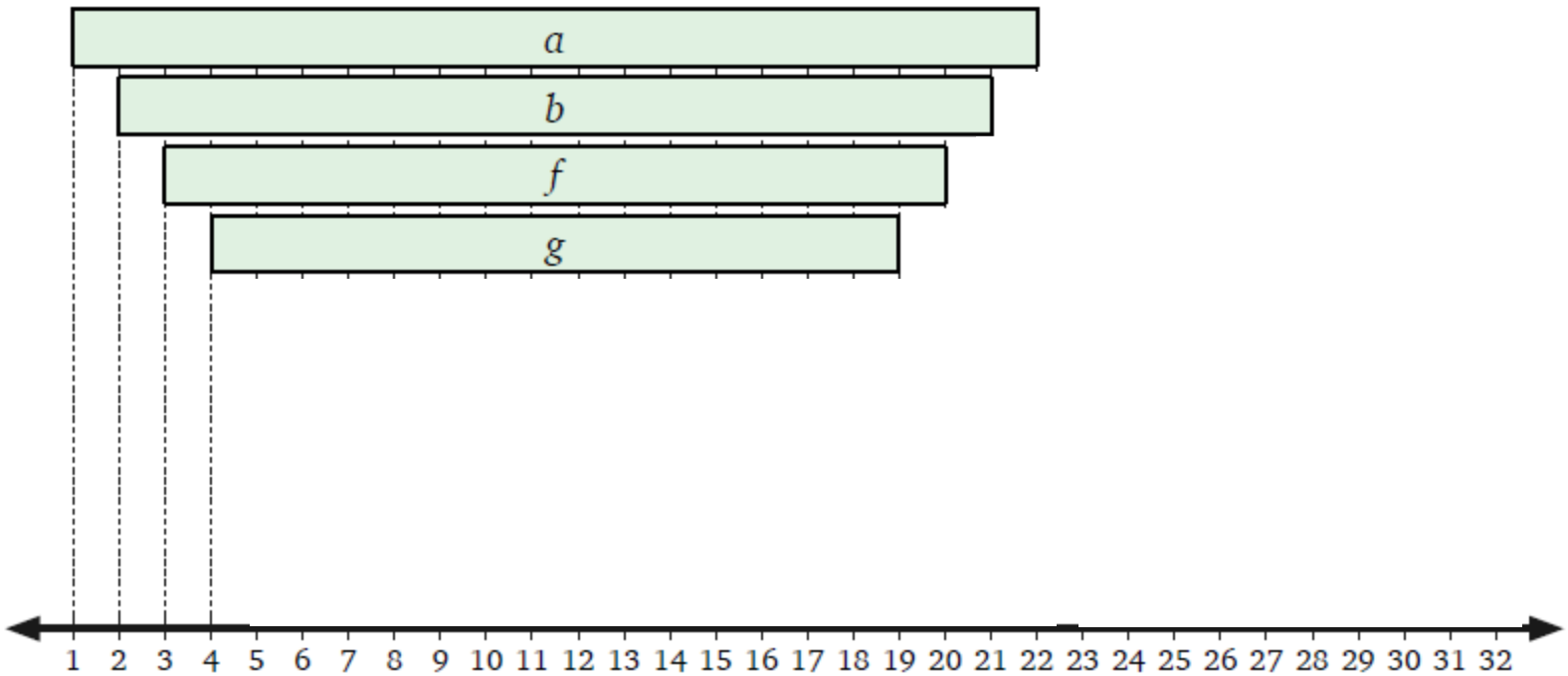
Stack – Time diagram



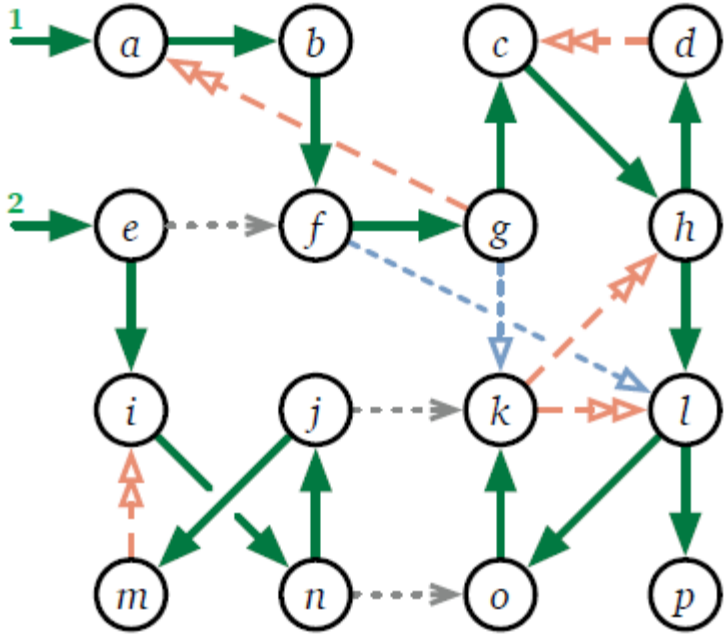


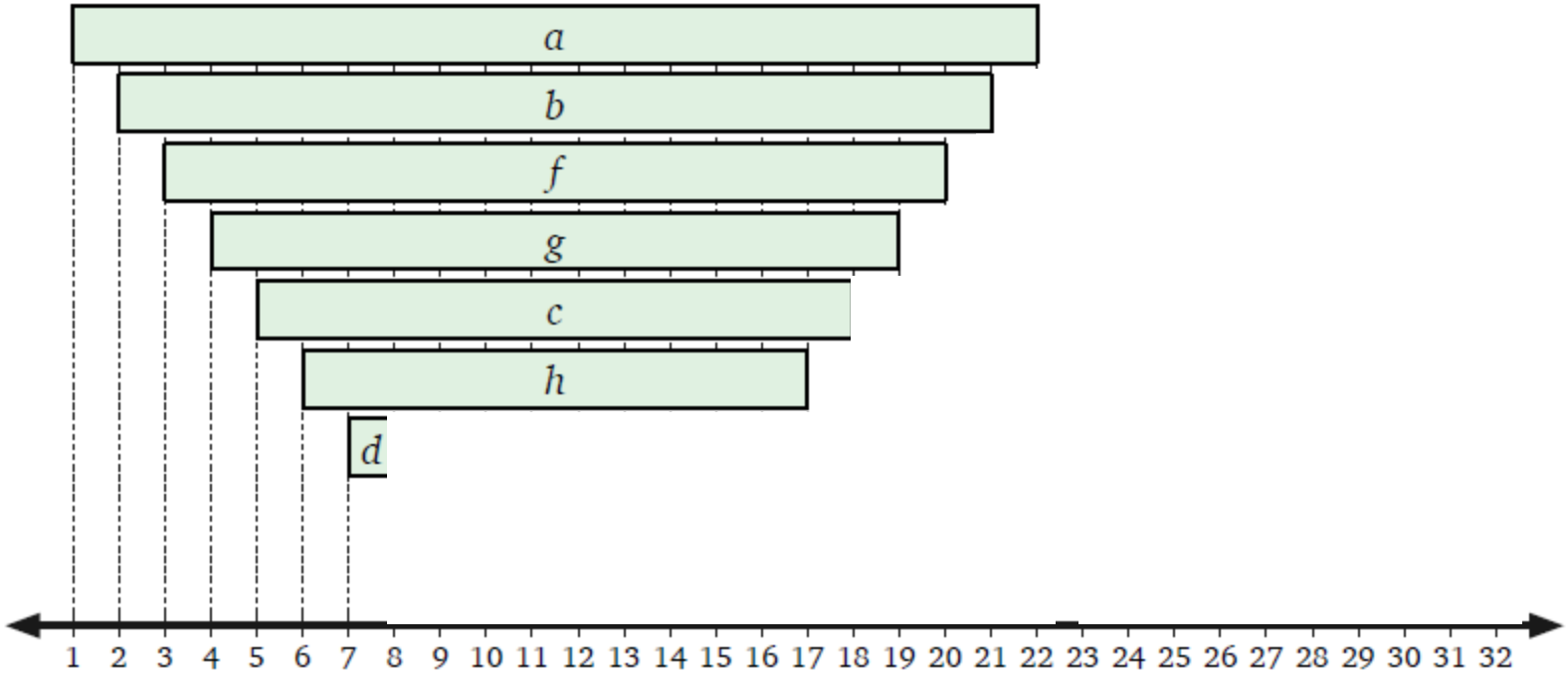
Stack – Time diagram



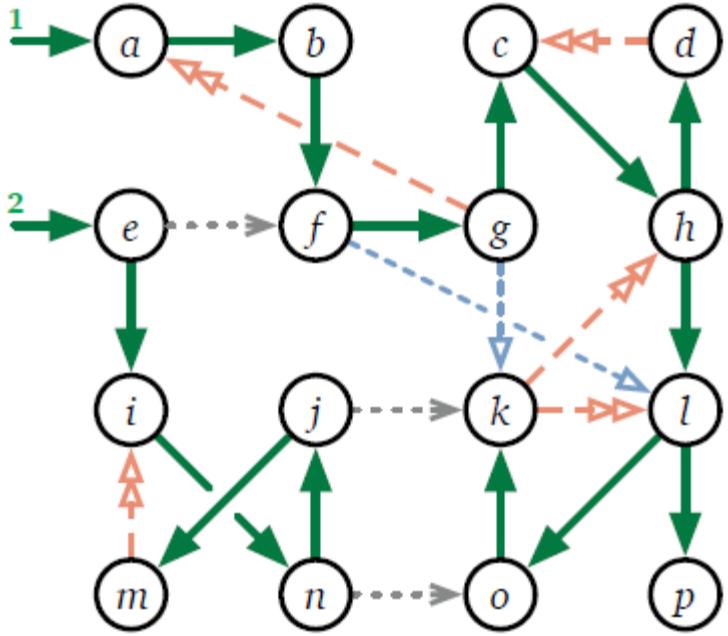


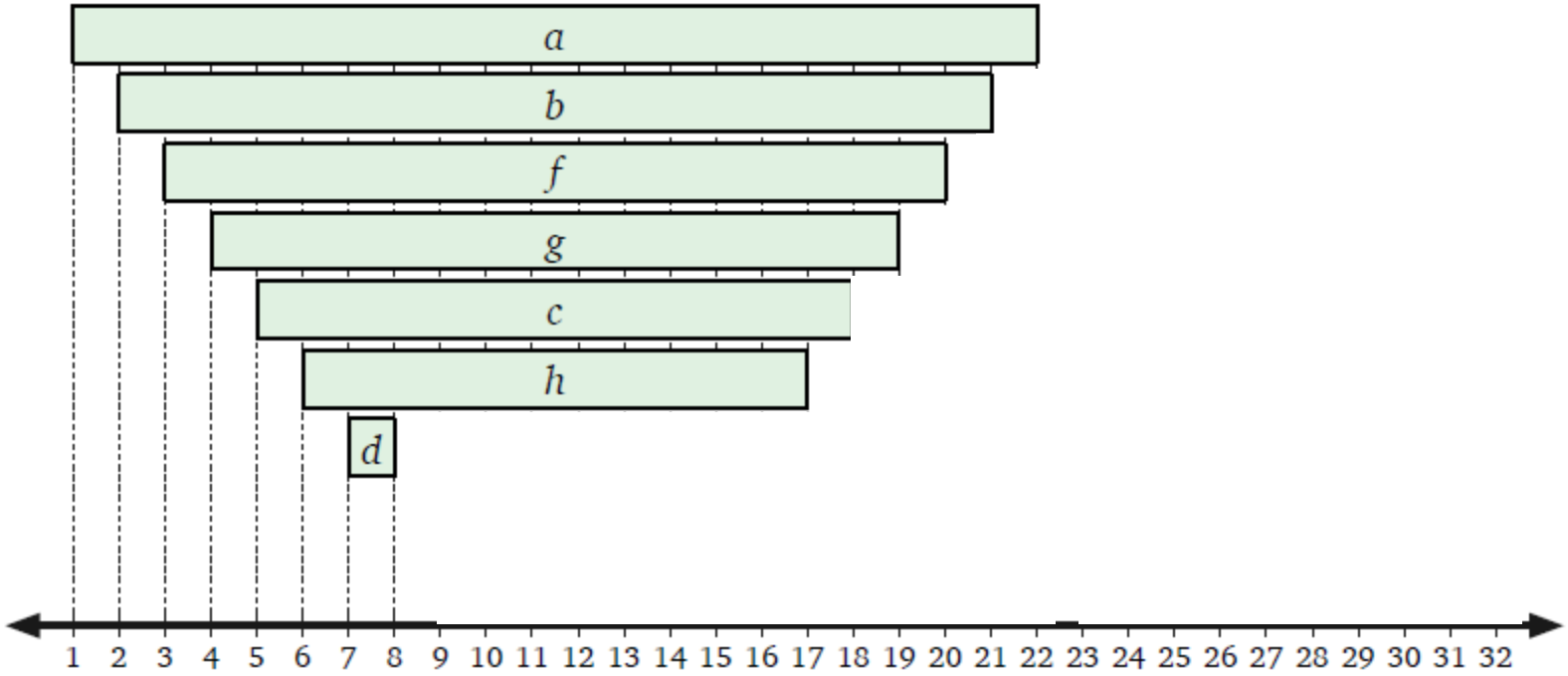
Stack – Time diagram



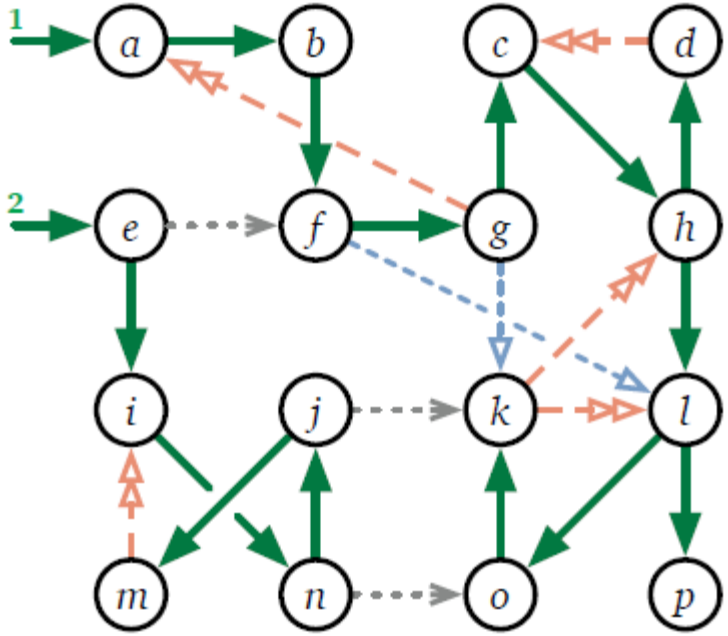


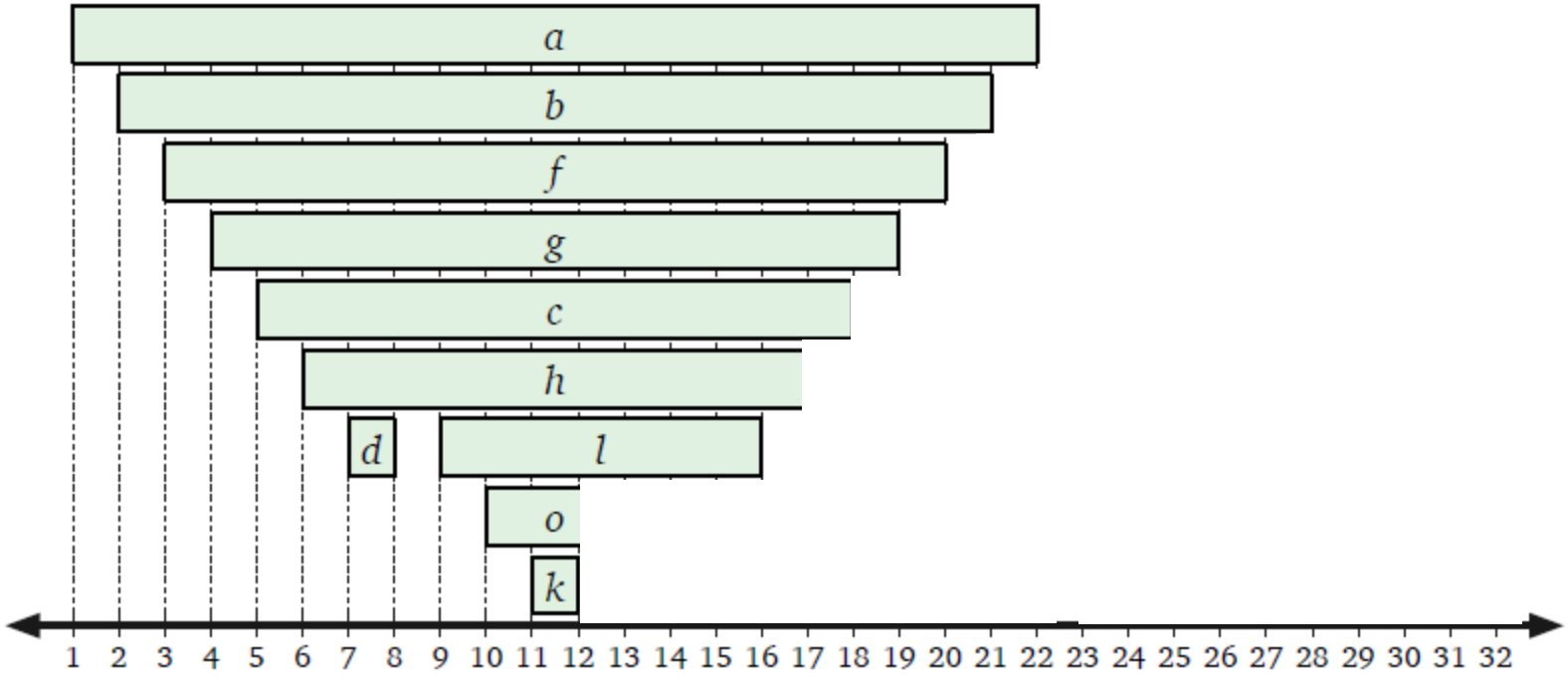
Stack – Time diagram



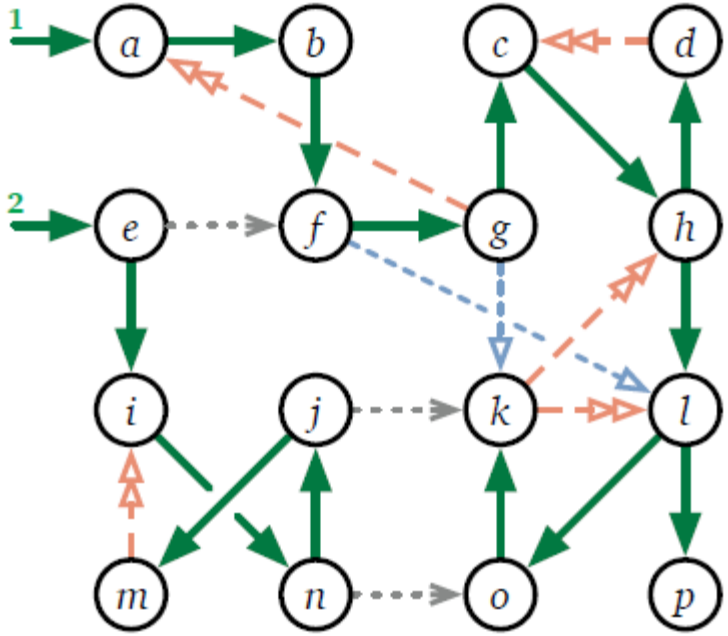


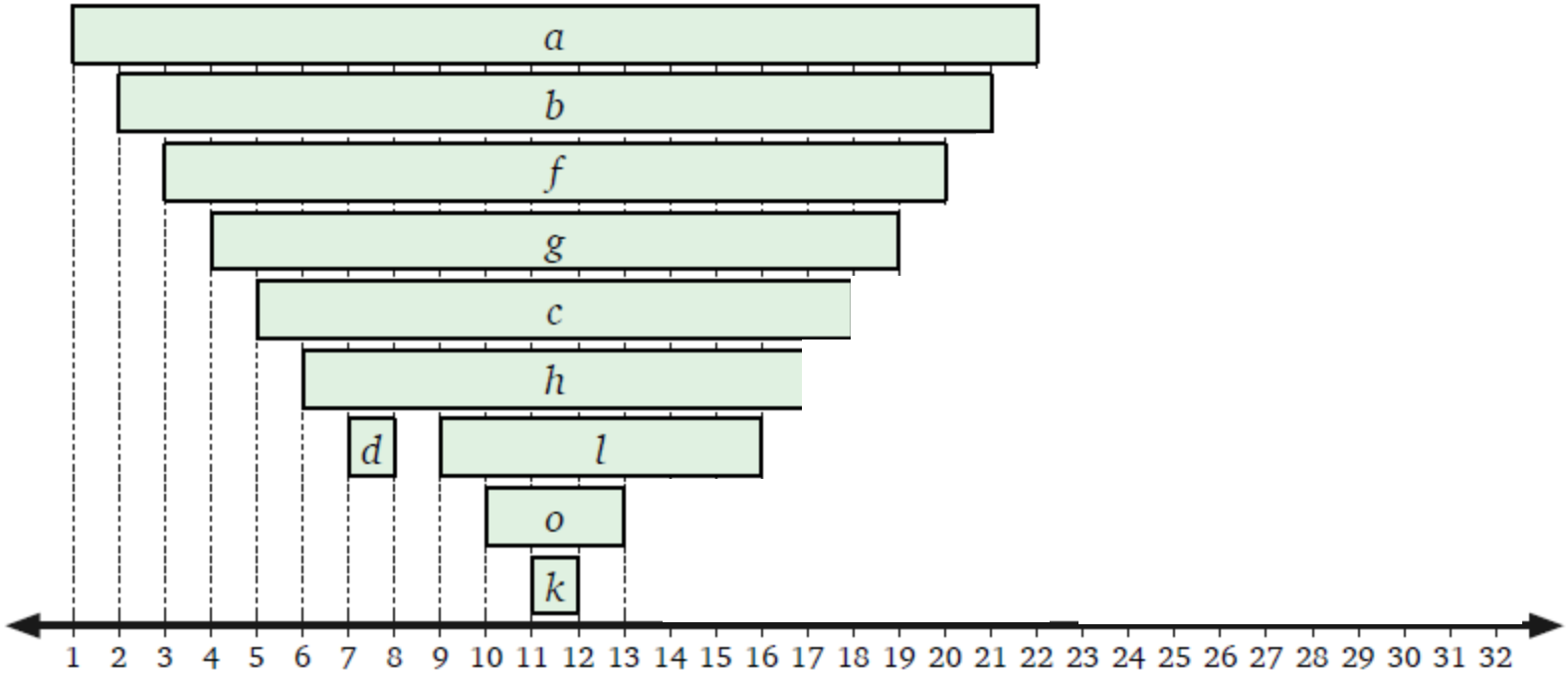
Stack – Time diagram



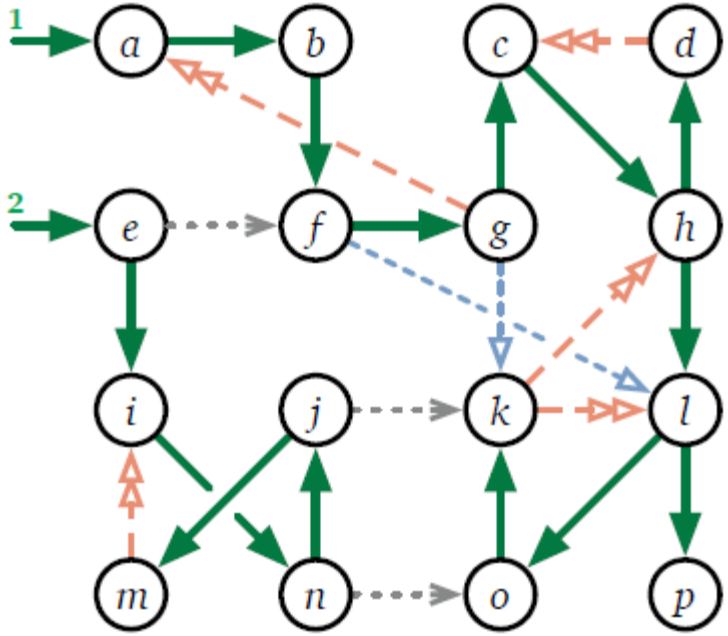


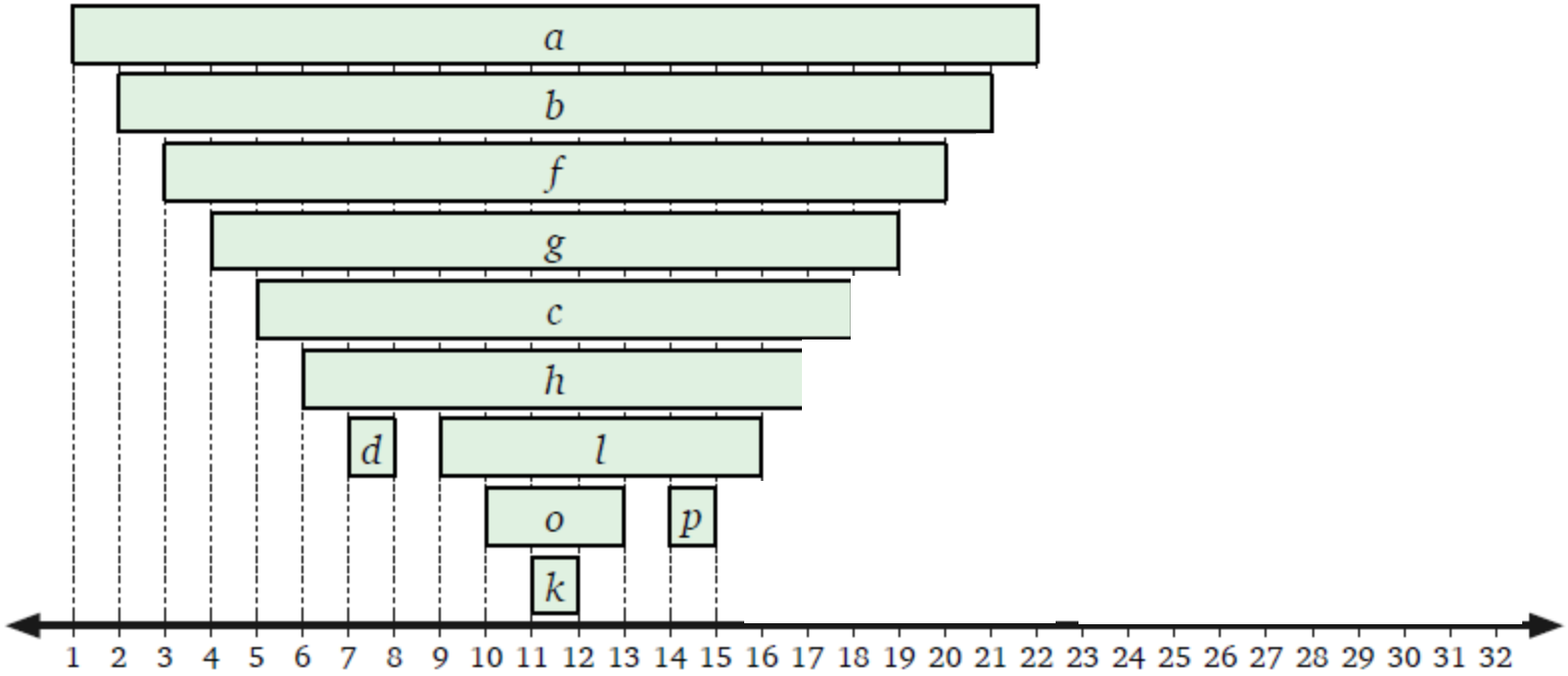
Stack – Time diagram



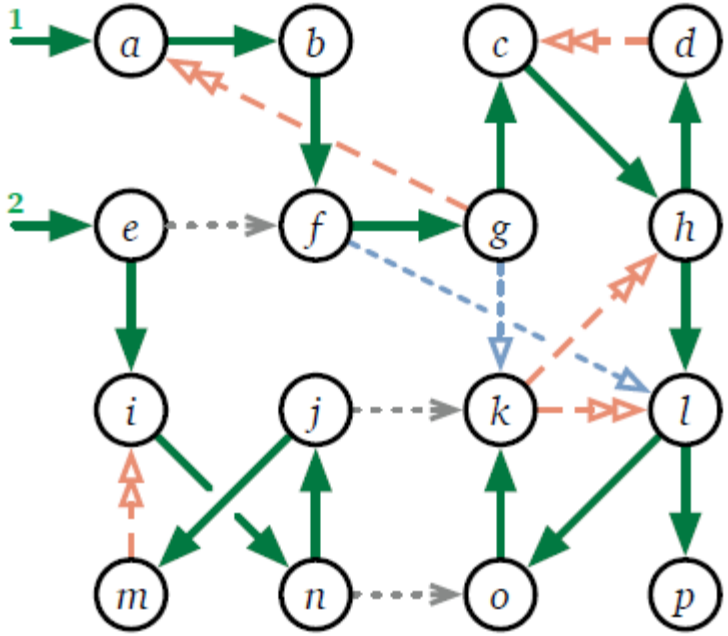


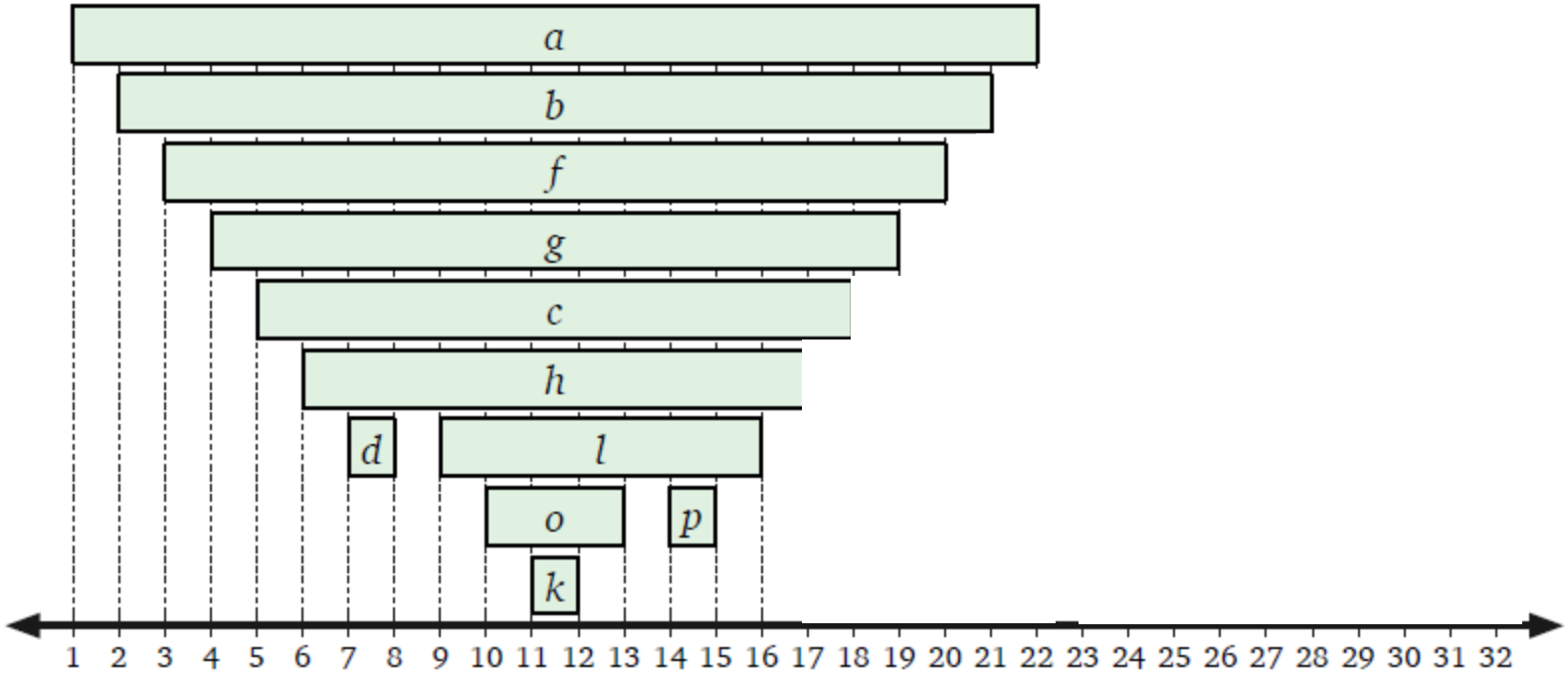
Stack – Time diagram



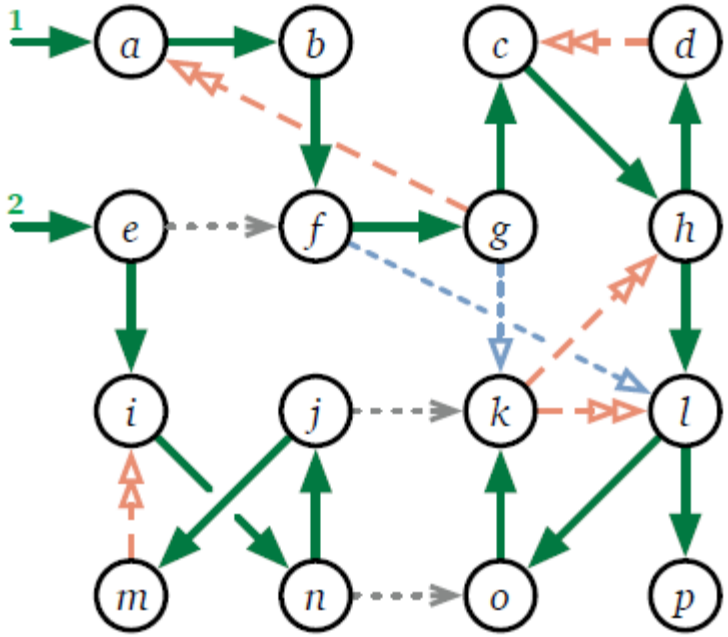


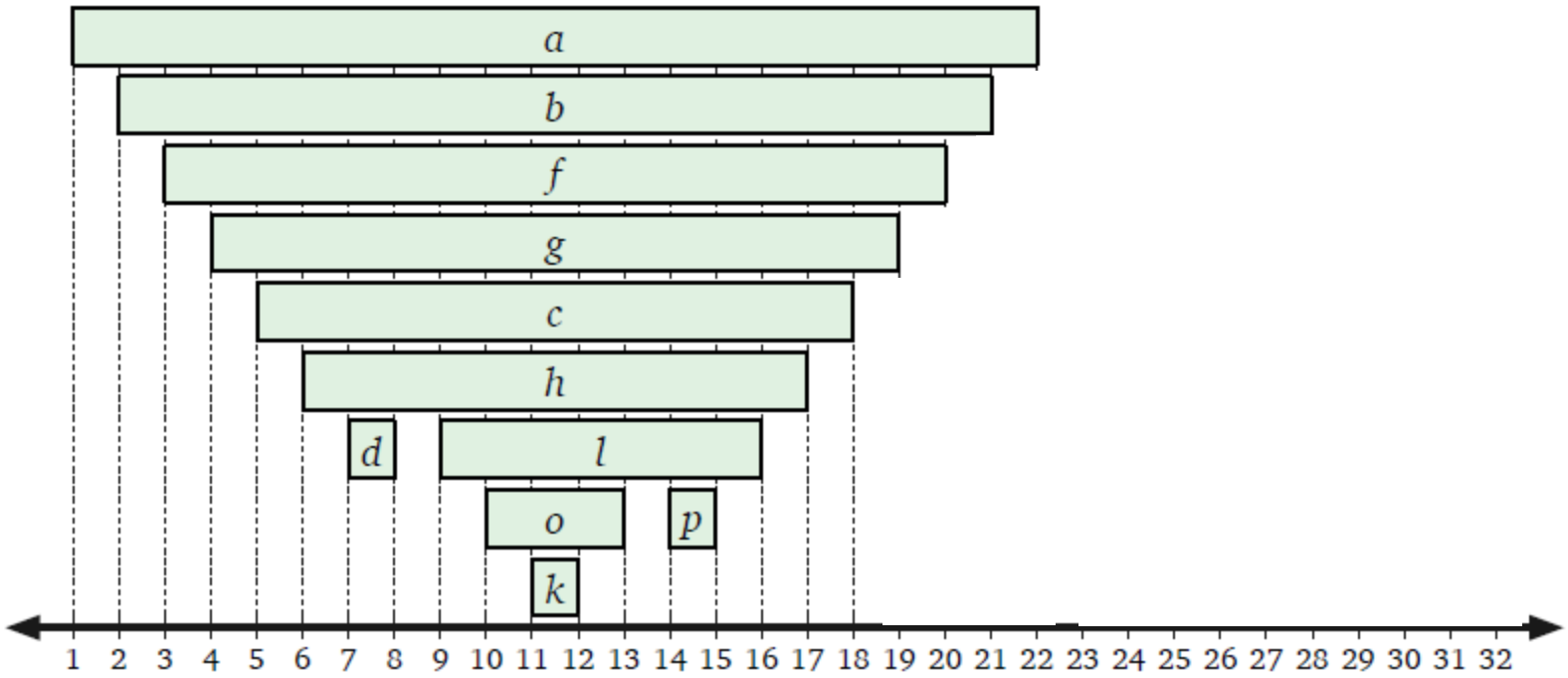
Stack – Time diagram





Stack – Time diagram





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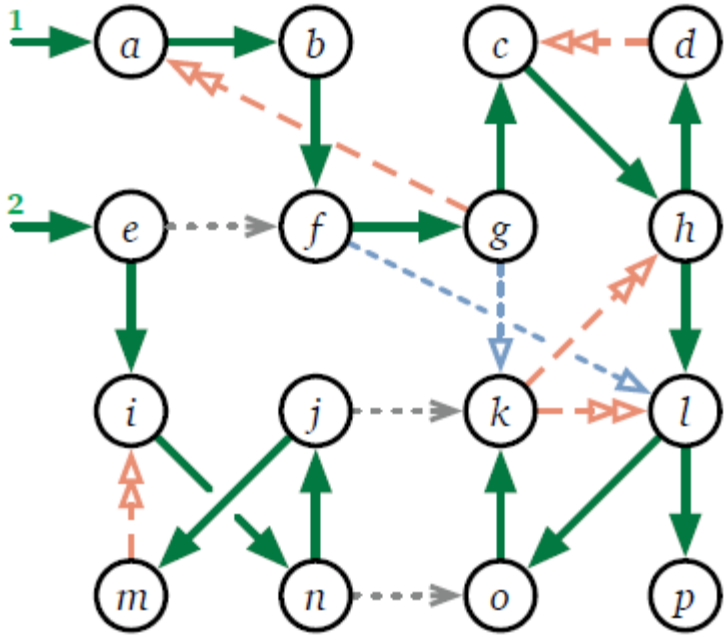
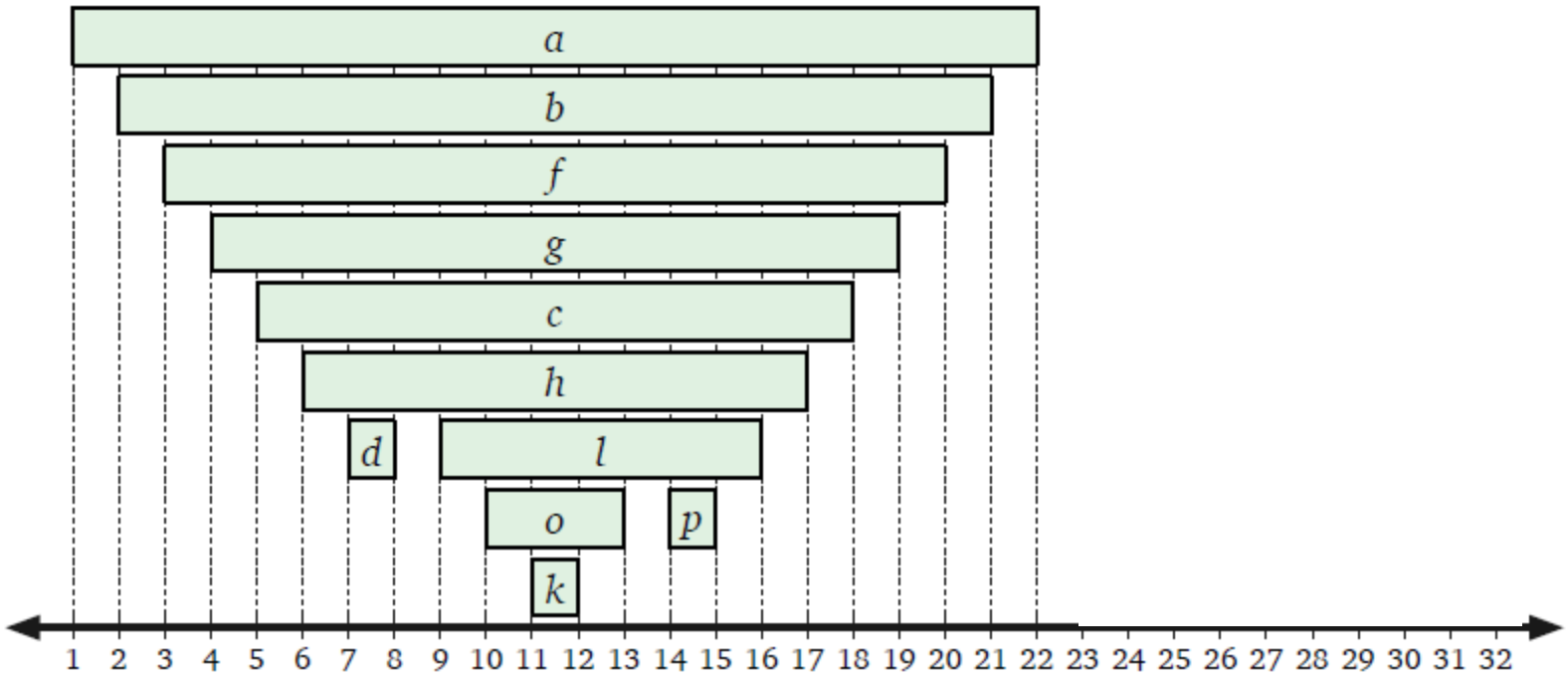
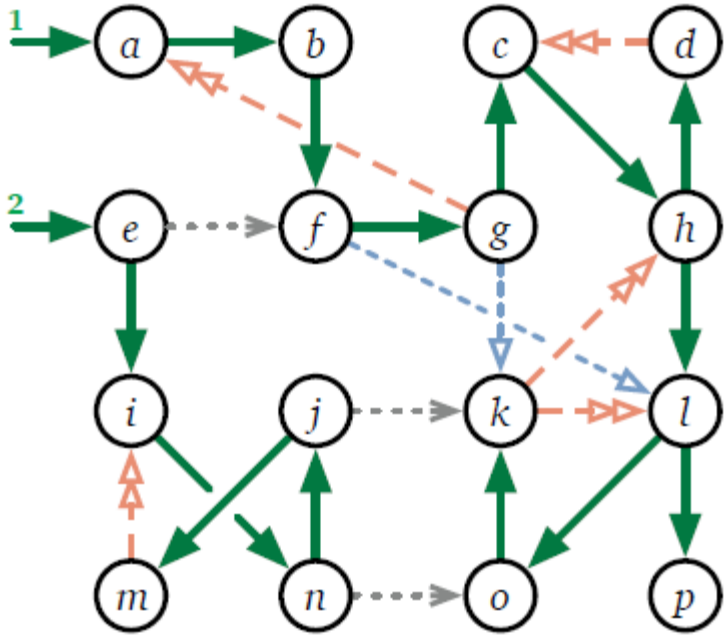
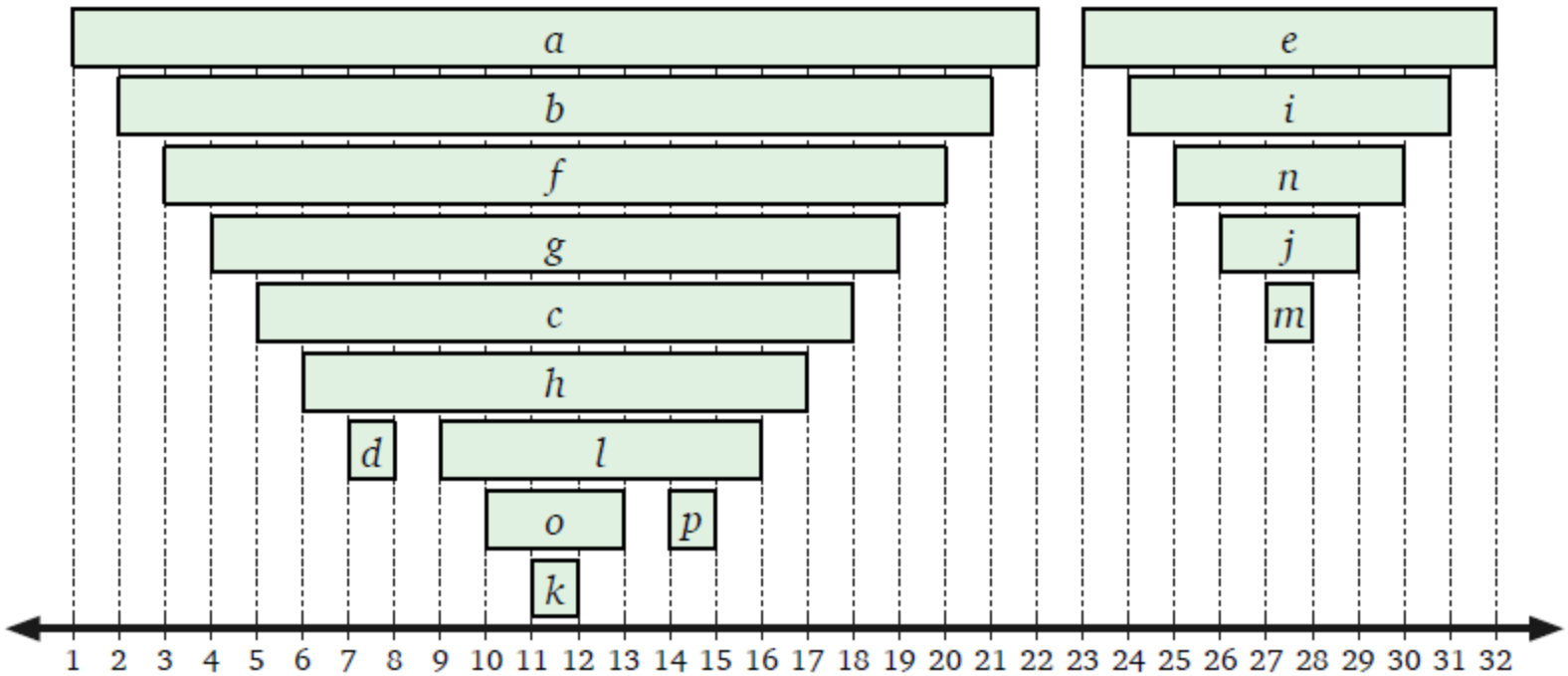


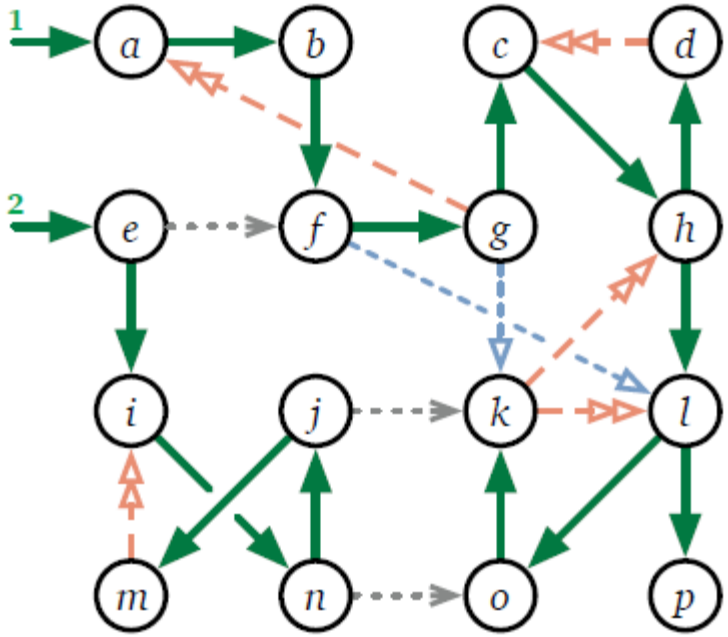


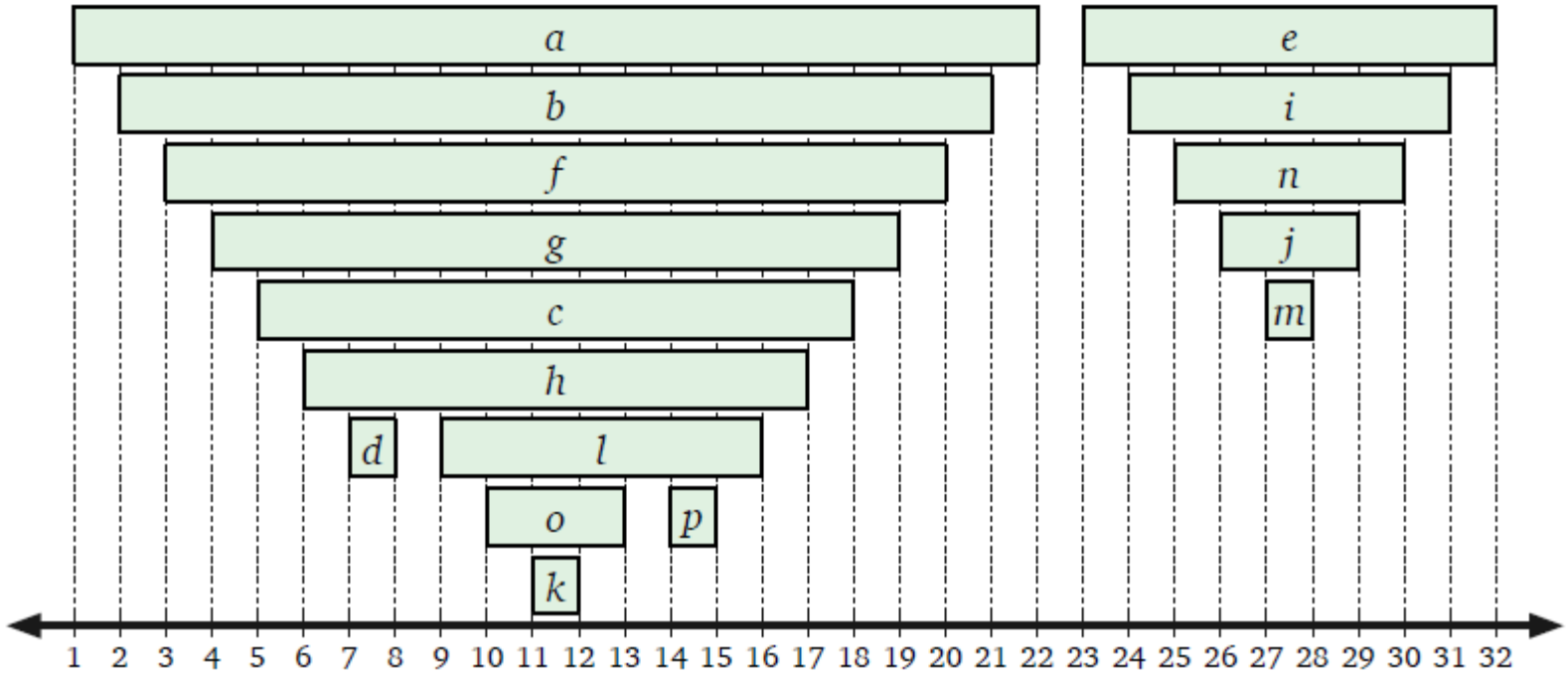
Stack – Time diagram





Preorder and postorder traversal of DFS Forest





Preorder

```
pre(v)
  startList.add(v)
```

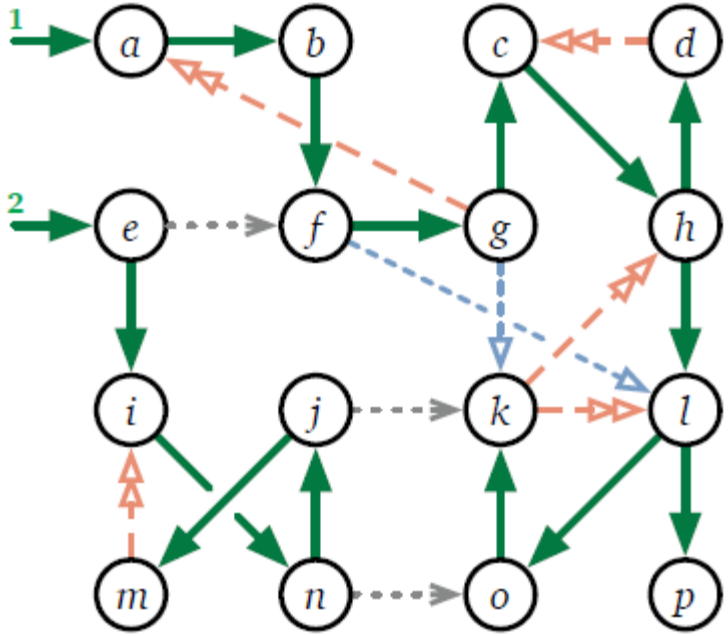
postorder

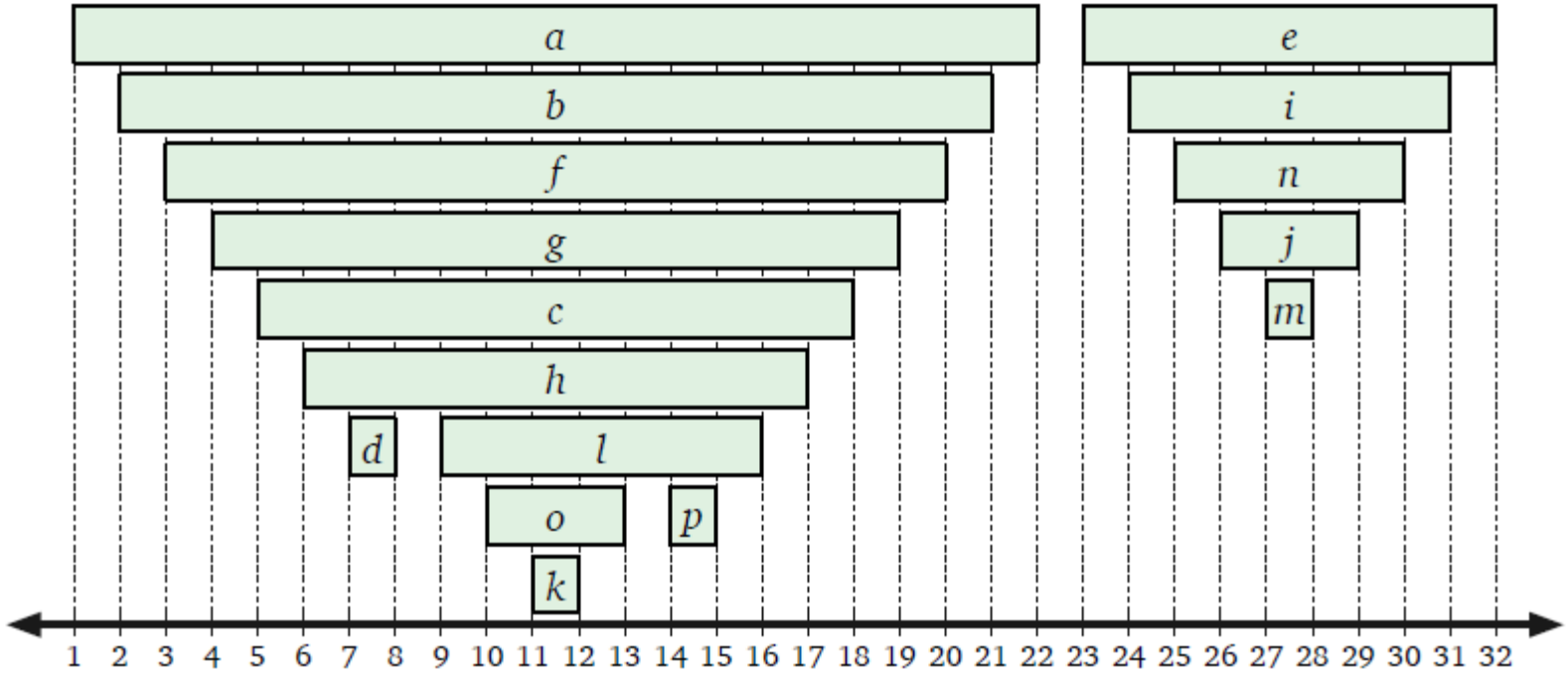
```
post(v)
  finishList.add(v)
```

Classifying Vertices

- v is new if DFS(v) is not called
  - clock < v.start
- v is active if DFS(v) is called but not returned
  - v.start <= clock < v.finish
- v is finished if DFS(v) has returned
  - v.finish <= clock

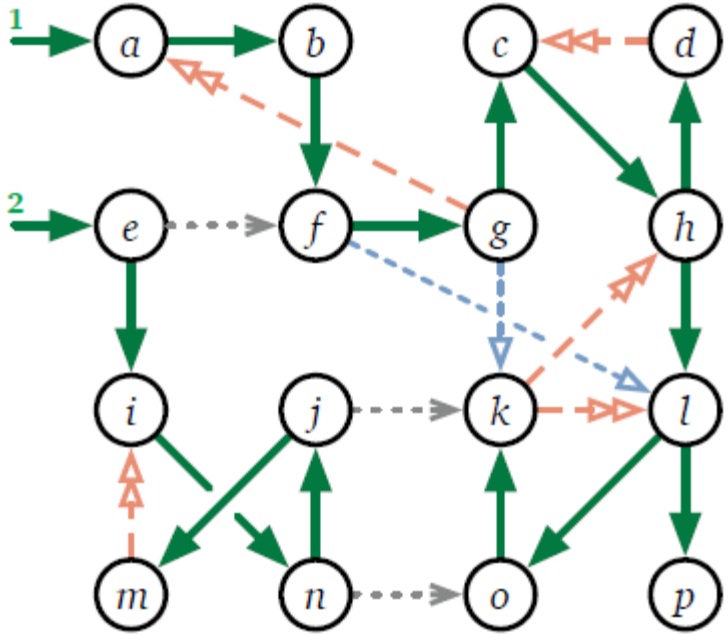
Classify Edges

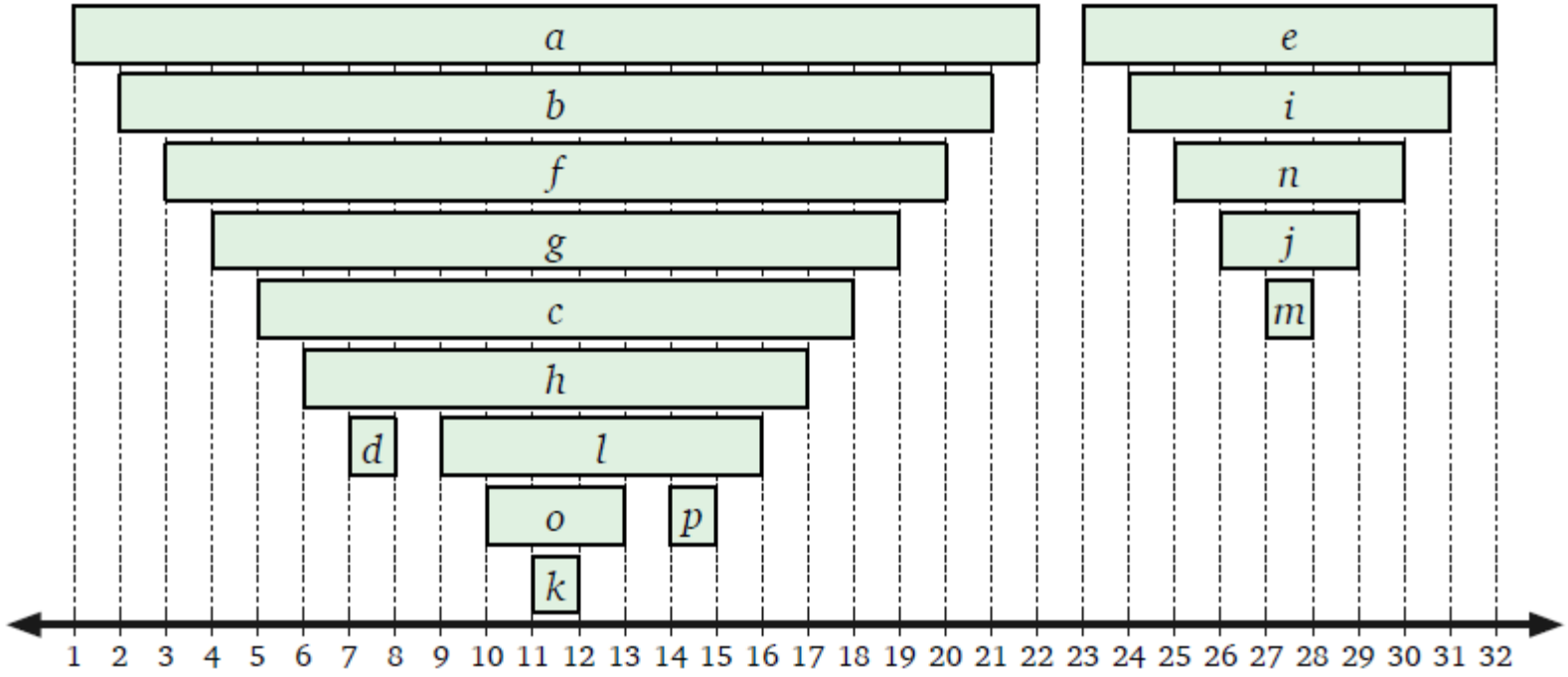




- u.start < v.start < v.finish < u.finish
  - v is reachable from u
  - u is an ancestor of v in DFS tree

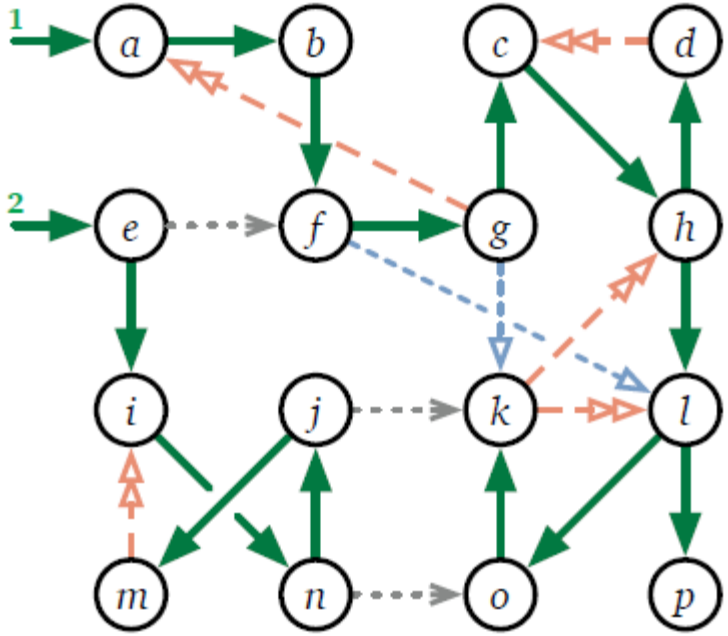
Classify Edges

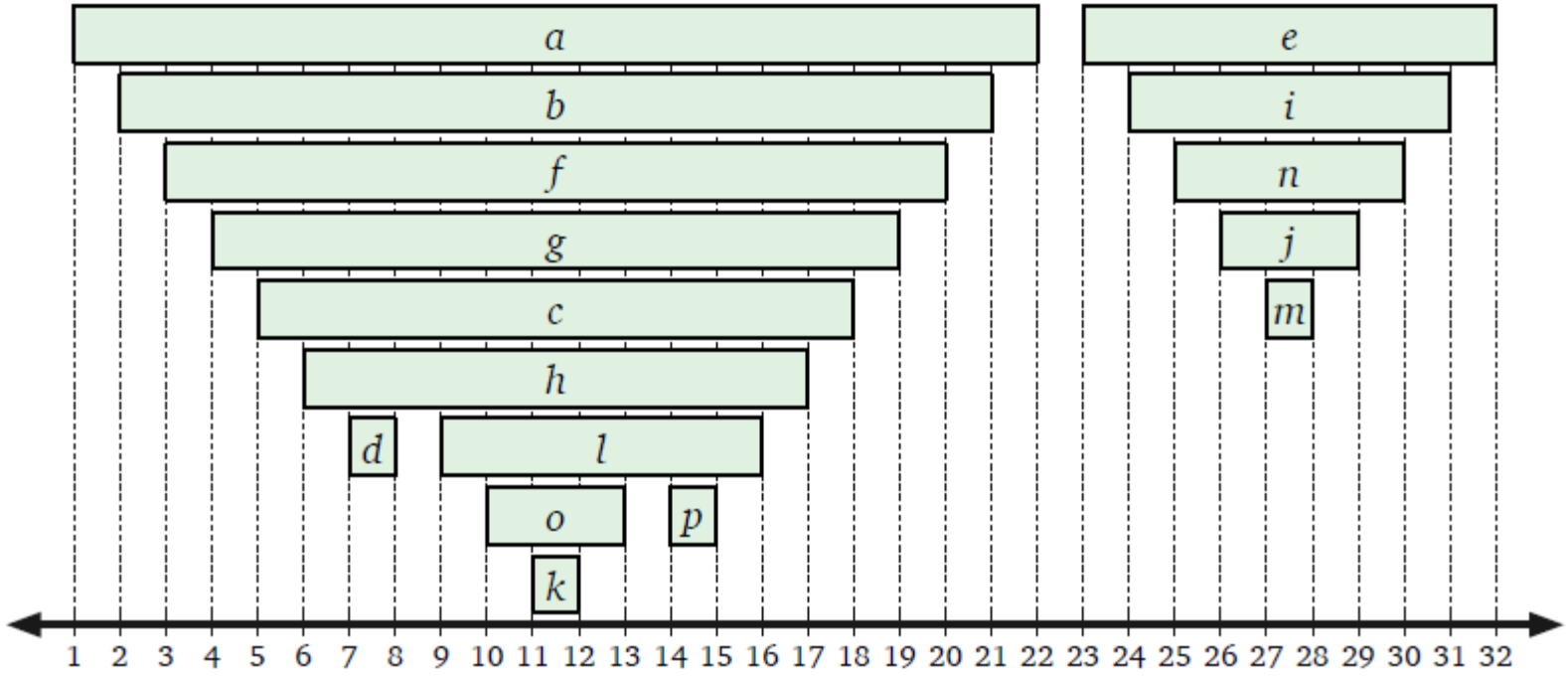




- consider u->v and suppose v is new when DFS(u) begins
  - u.start < v.start < v.finish < u.finish
  - If DFS(u) calls DFS(v) directly, then u->v is a tree edge
  - Otherwise u->v is a forward edge

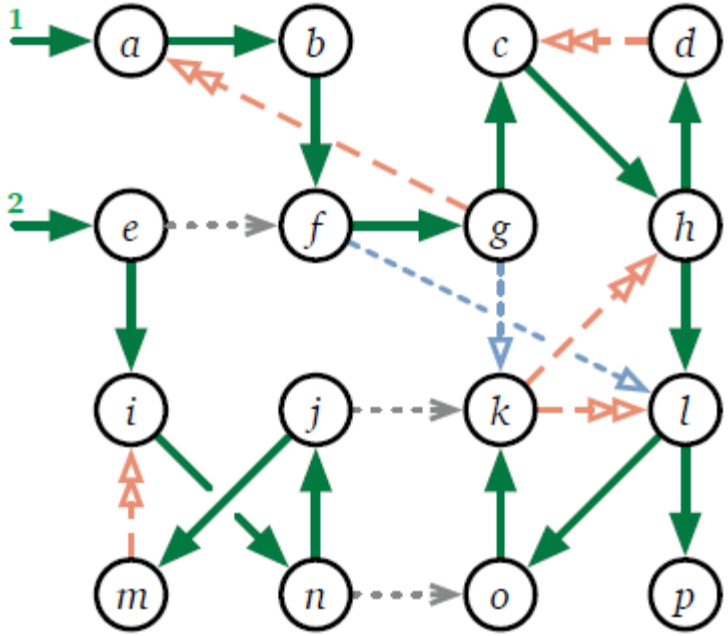
Classify Edges

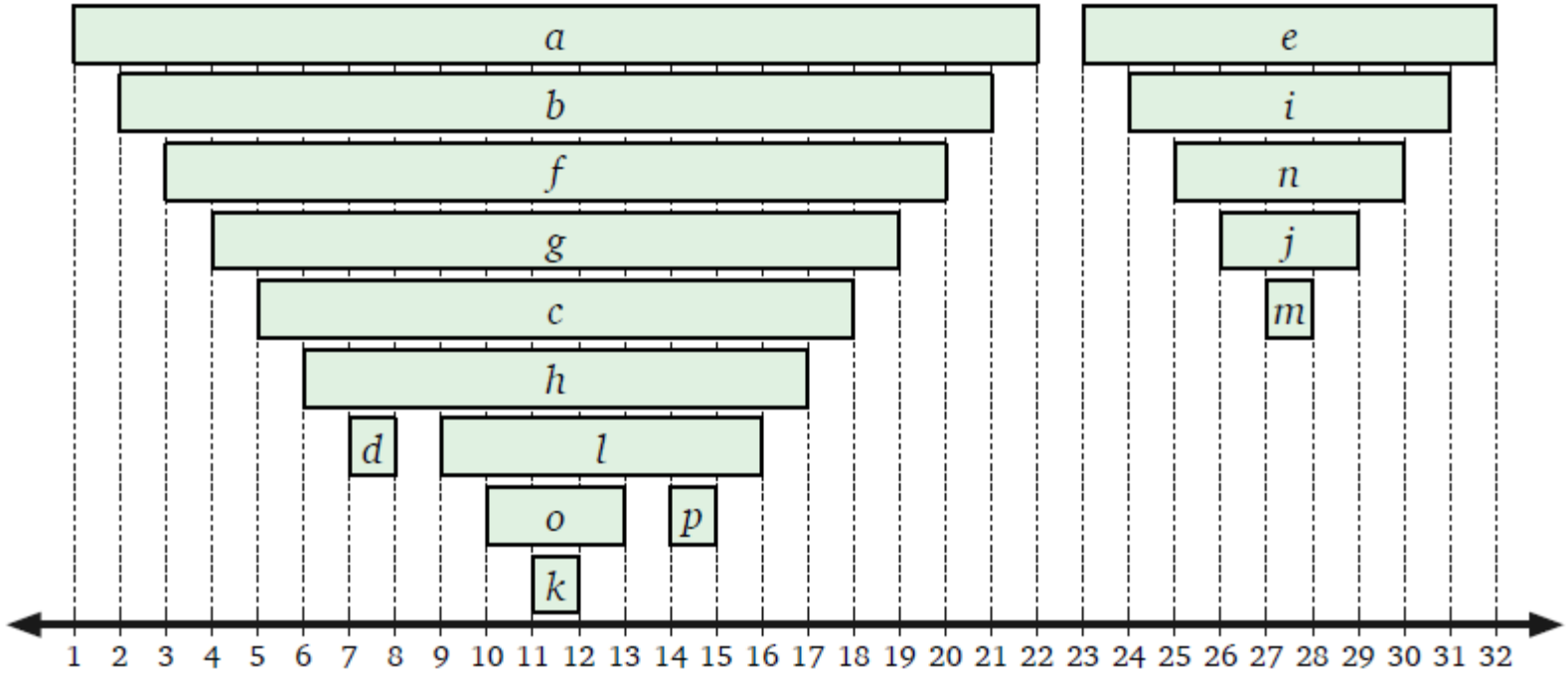




- consider u->v and v is finished when DFS(u) begins
  - v.start < v.finish < u.start < u.finish, then u->v is a cross edge

Classify Edges

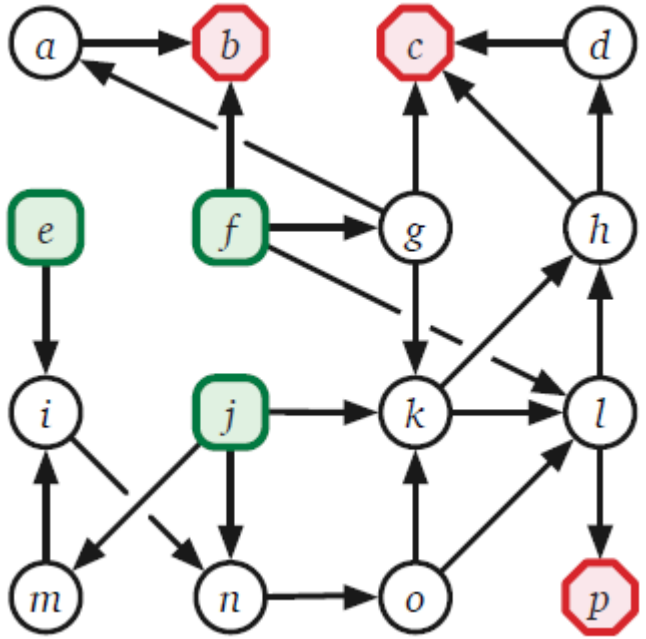




- consider u->v and v is active when DFS(u) begins
  - v.start < u.start < u.finish < v.finish ,
  - u->v is a back edge

Directed Acyclic Graph

- Source vertices have no incoming edges
- Sink vertices have no outgoing vertices
- DAG has at least one source vertex and one sink vertex
- Is G a DAG?



Is G a DAG?

What would you change to the code below?

```
dfsAll(G){
    initialize(G)
    for each v in G do
      unmark v
    for each v in G d0
      if v is unmarked
          dfs(v)
}
```

```
dfs(v){
  mark v
  pre(v)
  for each (v, w) in G do
      if w is unmarked
           w.parent = v
           dfs(w)
  post(v)
}
```

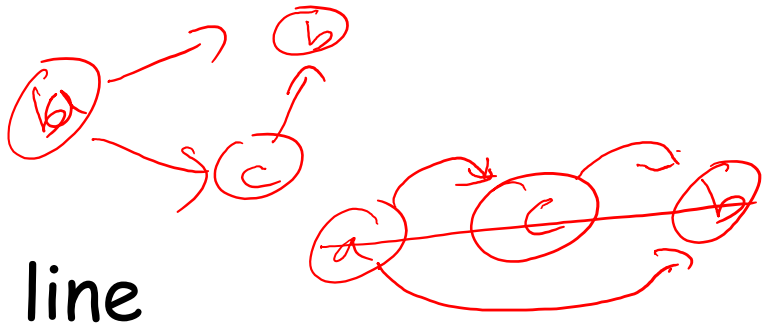
Is G a DAG?

A linear time algorithm:

```
isDAGAll(G){
    for each v in G do
      v.status = new
    for each v in G d0
      if v.status is new
          if(!isDAG(v)) return false
    return true
}
```

```
isDAG(v){
  v.status = active
  for each (v, w) in G do
      if w.status is active
            return false
      else if w.status is new
            if (!isDAG(w))
                  return false
  v.status = finished
  return true
}
```

Topological Ordering

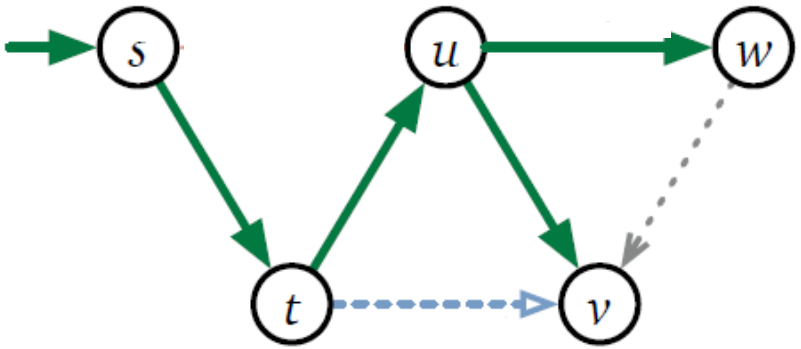


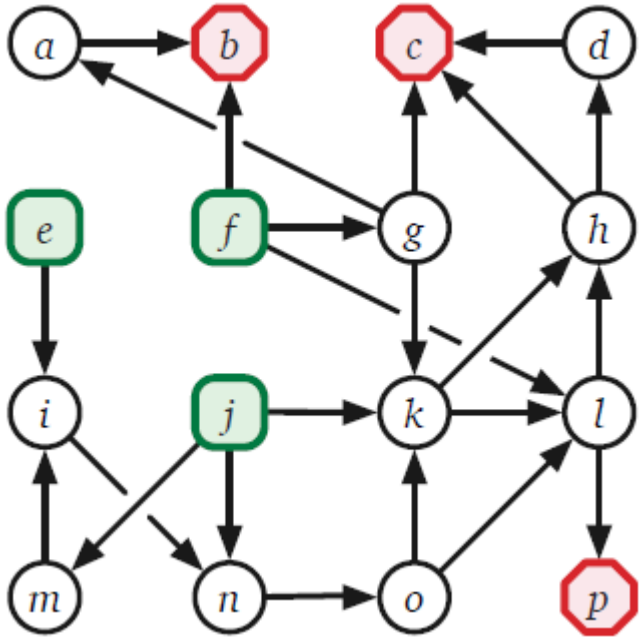
- Informally, place all vertices in a horizontal line such that edges go only from left to right

- Topological ordering of G is a total order $<$, on vertices such that
  - $u < v$ for every edge $u \rightarrow v$

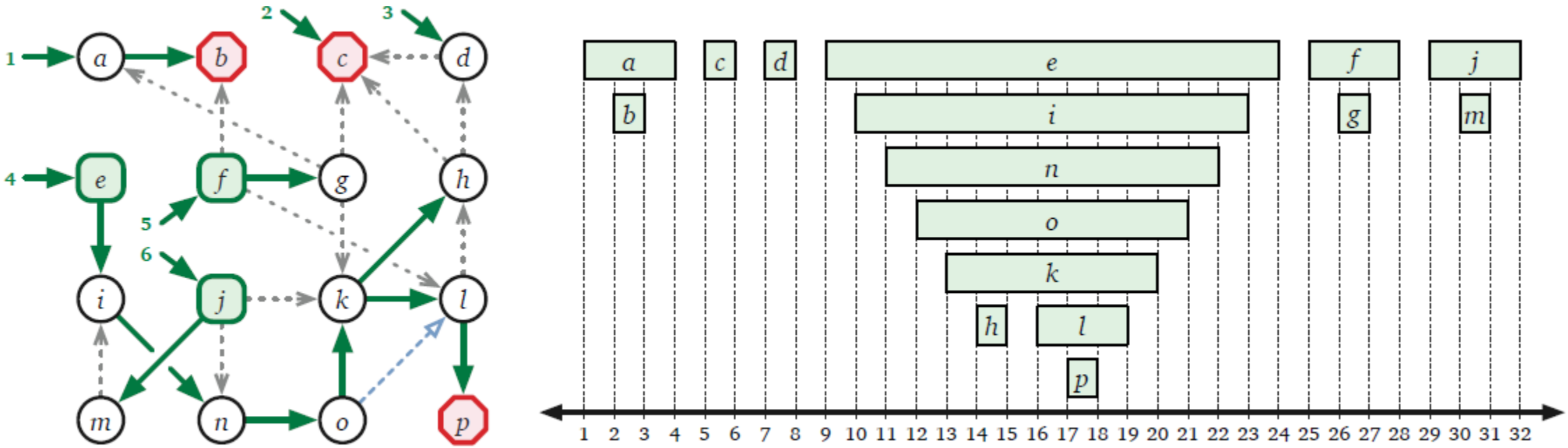
- Topological ordering is only possible if G is a DAG

Topological Sort





Topological Sort



Topological Sort Algorithm

Reverse of post order traversal

```
dfsAll(G){
    initialize(G)
    for each v in G do
      unmark v
    for each v in G d0
      if v is unmarked
          dfs(v)
}
```

```
dfs(v){
  mark v
  pre(v)
  for each (v, w) in G do
      if v is unmarked
          w.parent = v
          dfs(w)
  post(v)
}
```

initialize(G)

pre(v)

post(v)

```
topList.addFirst(v)
```

Problem of the day

Let G be an undirected graph. Suppose we start with two coins on two arbitrarily chosen vertices of G. At every step, each coin ***must*** move to an adjacent vertex. Describe and analyze an efficient algorithm to compute the minimum number of steps to reach a configuration where both coins are on the same vertex, or to report correctly that no such configuration is reachable. The input to your algorithm consists of a graph $G = (V, E)$ and two vertices $u, v \in V$ (which may or may not be distinct).