

Experiments

AIM: To determine the Velocity ratio of worm gear screw machine.

APPARATUS: worm-gear screw jack.

Description: It is an apparatus consisting of worm and gear wheel.

THEORY AND FORMULA:

Consider a worm gear screw jack.

Distance travelled by worm gear = $\frac{\pi D}{2}$

Distance travelled by screw = $\frac{\pi D}{2} \times n$

Distance travelled by load = $\frac{\pi D}{2} \times n$

Distance travelled by load = $\frac{\pi D}{2} \times n$

Distance travelled by load = $\frac{\pi D}{2} \times n$

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Distance travelled by load = $\frac{\pi D}{2} \times n$

Distance travelled by load = $\frac{\pi D}{2} \times n$

K
D
M
C
S
m

EXPERIMENT NO. - 6

AIM: To determine the Velocity Ratio, Mechanical Advantage and Efficiency and law of machines of worm-gear screw jack.

APPARATUS: worm-gear screw jack, weight box, and a meter scale.

Description: It is an improved form of screw jack in which the screw is lifted with the help of worm and gear wheel, instead of effort at the end of a pulley.

THEORY AND FORMULAE USED:

Consider a worm geared screw jack.
Let

$$\begin{aligned} p &= \text{pitch of screw (p = 4 mm)} \rightarrow 4 \times 10^{-3} \\ t &= \text{no. of teeth in gear wheel (t = 40)} \end{aligned}$$

$$\text{Number of revolutions made by the gear wheel and screw of jack} = \frac{pT}{\pi d}$$

$$\text{Distance moved by load} = pT$$

$$\text{Distance moved by effort} = \frac{pT}{\pi R}$$

$$\begin{aligned} \text{Circumference} &= 46 \\ \pi d &= 46 \\ d &= 46 \\ \pi &= \cancel{p/T} \end{aligned}$$

$$2\pi r = 46$$

$$T = P$$

$$l = \infty$$

$$n = P/T$$

$$1) \text{Velocity Ratio (V.R.)} = \frac{2\pi R}{\pi l} \quad \text{where } R \text{ is radius of effort pulley.}$$

$$\text{Effort} = 2\pi l$$

$$\text{lead} = P/T$$

$$2) \text{Mech. Adv. (M.A.)} = \frac{\text{Load lifted}}{\text{Effort applied}} = \frac{W}{P}$$

$$\begin{aligned} 1 \text{ rev} &= P \\ \frac{1}{T} &= \left(\frac{P}{l} \right) \end{aligned}$$

$$3) \text{Efficiency} (\eta) = \frac{\text{M.A.}}{\text{V.R.}}$$

$$4) \text{Ideal effort (P}_i\text{)} = \frac{W}{\text{V.R.}}$$

$$5) \text{Effort lost in friction } P_f = \text{Actual Effort} - \text{Ideal Effort} = P - P_i$$

$$6) \text{Ideal load (W}_i\text{)} = \text{Actual effort} \times \text{Velocity ratio} = P \times \text{V.R.}$$

$$7) \text{Load lost in friction } W_f = \text{Ideal load} - \text{Actual load} = W_i - W$$

$$8) \text{Law of machine} = P = mW + C \quad (Y = mX + C)$$

where m = Slope of St. line. & C = Intercept of St. line on Y axis.

$$9) M.A_{\max} = \frac{l}{m} \quad \& \quad \text{Max. efficiency of machine} = \eta_{\max} = \frac{l}{m \times \text{V.R.}}$$

PROCEDURE:

- 1) Note down the diameter of effort pulley and pitch of screw jack
- 2) Known weight W was tested at loading point and effort P was applied at driving point and note down.
- 3) Determine the Velocity Ratio(V.R.)
- 4) Determine the M.A
- 5) Calculate effort lost in friction
- 6) Calculate load lost in friction
- 7) Calculate efficiency (η)

GRAPHS:

- 8) Plot curves for.
 - a. Load Vs Effort
 - b. Load Vs Mechanical Advantage
 - c. Load Vs Efficiency
- 9) Calculate m & C from graph Load Vs Effort
- 10) Calculate law of machine
- 11) Max.efficiency of machine

OBSERVATION TABLE:

S. No.	LOAD W in Kg	EFFORT P in Kg	Ideal effort (P_i)	Effort lost in friction P_f	Load lost in friction W_f	Mechanical Advantage $MA = \frac{W}{P}$	Efficiency η %
1.	10	0.160	6.25	0.160	0.160	62.5	1.357
2.	9	0.180	5.00	0.180	0.180	75	1.631
3.	8	0.160	5.00	0.160	0.160	50	1.731
4.	7	0.090	7.78	0.090	0.090	77.78	1.682
5.	6	0.080	7.50	0.080	0.080	75.0	1.641
6.	5	0.075	6.67	0.075	0.075	66.67	1.44

RESULTS:

1. The Velocity Ratio (VR) for the machine
2. The max. mechanical Advantage ($M.A_{max}$) for the machine
3. The max.efficiency (η_{max}) of the machine
4. Law of machine =

PRECAUTIONS AND SOURCES OF ERROR:

1. The effort should be applied accurately at suitable situation
2. The pitch of the screw jack should be measured accurately

EXPERIMENT NO. 7.

TITLE	WHEEL & AXLE		
DATE OF PERFORMING	DATE OF SUBMISSION	REMARKS	
SIGNATURE OF PROFESSOR			

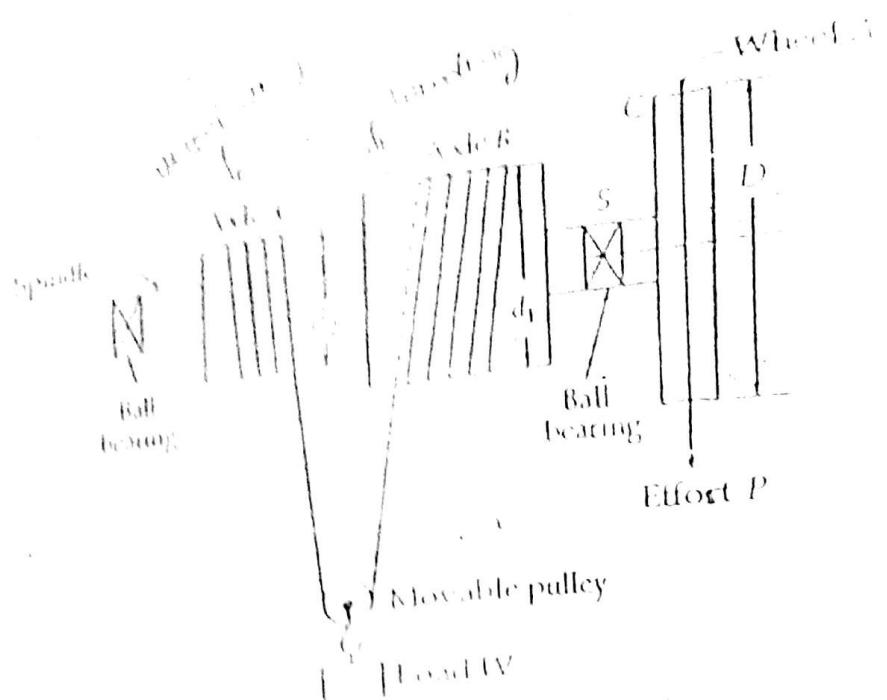


Fig 1 Differential wheel and axle

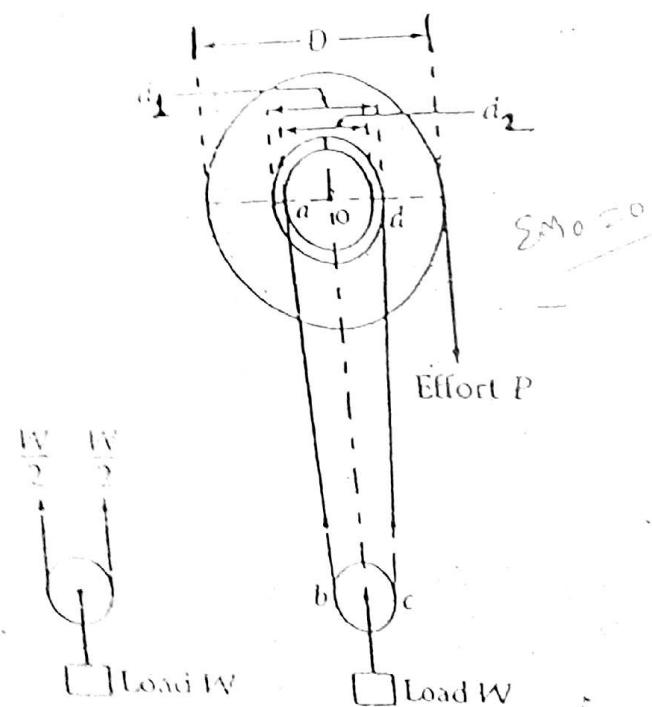


Fig 2

EXPERIMENT NO. 7

EXPERIMENT NO. 7

AIM: To determine the Velocity Ratio, Mechanical Advantage and Efficiency of Differential wheel and Axle.

APPARATUS: One set of slotited wheel and axle.

APPARATUS: One set of slotted weights, weight box, thread and a meter scale.

The unit consists of a wheel A and two axles B and C. The wheel and the two axles are keyed to the same shaft (spindle) which is supported in ball bearings. The effort is applied to the string which is wound round the wheel. Another string is wound on the two axles and it carries the load through a pulley. The strings on the wheel and smaller axle are wound in the same direction whereas winding of string on the bigger axle is in the opposite direction.

When the effort P is applied in the downward direction, there is unwinding of the strings on the wheel and smaller axle. The string winds on the bigger axle at the same times and the load W is lifted upwards.

length of string that winds on the pulley = πD (downward)

length of string that winds on bigger axle = πD (downward)
length of string that winds on smaller axle = πd_1

Therefore, Net length of string = πd

Therefore, Net length of string which will get wound on bigger axle = $\pi d_1 - \pi d_2$
 Since the string carries the load through pulley, the load will get lifted by distance
 ~~$\frac{1}{2}(\pi d_1 - \pi d_2)$~~ = $(\pi d_1 - \pi d_2)/2 = \frac{1}{2}\pi(d_1 - d_2)$

therefore, Velocity ratio (VR) = distance moved by effort / distance moved by load

Therefore, Velocity ratio (VR) = distance moved by effort/distance moved by load

$$VR = \frac{\pi D}{2} \times \frac{1}{\pi(d_1 - d_2)} = \frac{D}{d_1 - d_2}$$

$$VR = \frac{\pi D}{\frac{1}{2} \pi (d_1 - d_2)} = \frac{2D}{d_1 - d_2}$$

(9 d)

Neglecting friction, μ_1 and μ_2 are made nearly equal.)

Neglecting friction at the contact surfaces, the forces acting on the system are shown in Fig. Let it be assumed that segments ab and cd of the string supporting the load to be vertical. Then from equilibrium condition $\sum V = 0$, the tension in each of the segments equals $W/2$. Further, from moment equilibrium $\sum M = 0$.

Taking moments of all forces about o, we get

$$P \times D/2 - W/2 \times d_1/2 + W/2 \times d_2/2 = 0$$

or

$$P \propto D = W/2(d_1+d_2)$$

$\text{Efficiency } \eta = \frac{\text{Work output}}{\text{Work input}}$

$$\text{Therefore Mechanical advantage (MA)} = \frac{W/P'}{W/P} = \frac{2D}{(d_1-d_2)}$$

The mechanical advantage is equal to velocity ratio. This has to be so because friction has been neglected. Obviously then efficiency of the system will be 100 per cent.

Effect of friction

Let P' be the effort required to lift the load W when friction is taken into account. Then for one revolution of the wheel and axles,

$$\text{Work input (work done by the effort)} = P' \times \pi D$$

$$\text{Work output (work done by the load)} = W \times \pi/2(d_1-d_2)$$

$$\begin{aligned}\checkmark \text{Efficiency of machine } \eta &= \frac{\text{work output}}{\text{work input}} \\ &= \frac{W \times \pi/2(d_1-d_2)}{P' \times \pi D} = \frac{W \times (d_1-d_2)}{P' \times 2D}\end{aligned}$$

From the above expression,

$$P' = W \frac{(d_1-d_2)}{2D} \times \frac{1}{\eta}$$

$$\text{and MA (actual)} = \frac{W}{P'} = \frac{2D}{d_1-d_2} \times \eta$$

PROCEDURE:

1. Measure and note down the circumference of all drums in order to calculate their diameters.
2. Apply the measured load and slowly apply the effort weights on the larger drum. When the load starts to lift, note down the reading of the effort weight.
3. For taking next reading, increase the load and repeat step 2 again.
4. Tabulate the readings and calculate the results.

OBSERVATION TABLE

Table - I

All readings are in cm

Circumference of wheel	94	Diameter of the wheel (D)	
Circumference of the bigger axle	47	Diameter of the bigger axle (d_1)	
Circumference of the smaller axle	22	Diameter of the smaller axle (d_2)	

Table - II

All readings of effort and load are in kg

S No	LOAD W in Kg	EFFORT F in Kg	Mechanical Advantage MA	Efficiency η
1				
2				
3				
4				
5				

CALCULATIONS:

1. Write the calculations for any one set of readings.
2. Draw the graphs
 - (a) Load Vs Effort.
 - (b) Load Vs Mechanical Advantage.
 - (c) Load Vs Efficiency.

RESULTS:

1. The Velocity Ratio (VR) for the machine =
2. The Mechanical Advantage (MA) for the machine =
3. The Efficiency (η) of the machine =

PRECAUTIONS AND SOURCES OF ERROR:

- i. The differential wheel and axle must be properly oiled so that friction is negligibly small.
2. Make sure that the strings on the wheel and smaller axle are wound in the same direction.
3. The string used should have negligible diameter.
4. The string should be wound tightly over the wheel and axle drums.

1.5 → 0.23

1 → 0.23

15

1 → 0.17

1.5 → 0.17 × 65

2 →

EXPERIMENT - 8

Worm and worm WHEEL

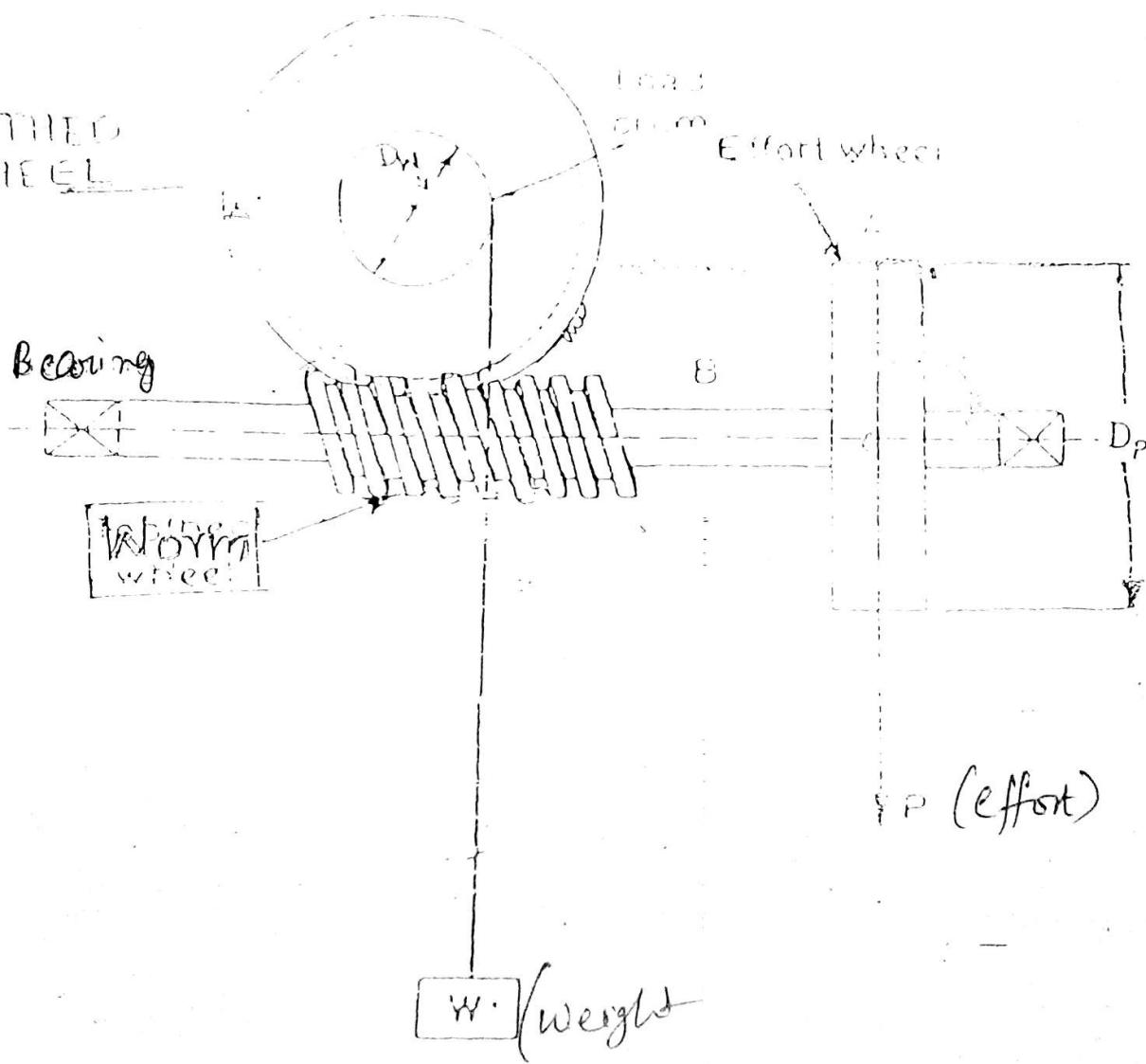
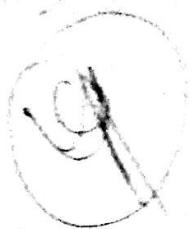


Fig:- WORM AND WORM WHEEL



EXPERIMENT NO

Q1 Aim To determine the velocity ratio, mechanical advantage and efficiency of Worm and Gear apparatus.

APPARATUS Worm box, slotted univeral stand, Vernier calliper.

THEORY

In worm gear system if two intermeshed teeth with equal nos. of engaged teeth (Worm wheel) is geared together and their axes at right angles to each other. A weight or load is attached to worm over which paper passes. A load drum is centrally mounted on worm wheel. To find the Velocity ratio of machine if D_p be the diameter of the effort pulley and D_w that of load drum and T be the number of teeth on worm wheel and P be the pitch of teeth then for one revolution of effort pulley the distance travelled by effort is πD_p . Now worm has revolved through one revolution that one half tooth in the worm wheel has moved through a distance of P and load is raised by distance $\frac{P}{T}$ then

$$V.R = \frac{\pi D_p}{\frac{P}{T}}$$



NOTE For three start apparatus in one revolution of worm distance travelled by worm wheel is three teeth.

For half start apparatus in one revolution of worm distance travelled by worm wheel is half teeth

FORMULA USED

1) For three start

$$\underline{\underline{V.R. = \frac{D_p \times T}{D_w \times 3}}}$$

2) For half start

$$\underline{\underline{V.R. = \frac{D_p \times T \times 2}{D_w}}}$$

$$V.R. = \frac{\text{Effort}}{\text{Load}}$$

→ Effort

$$\rightarrow V.R. = \frac{D_p \times T \times 2}{D_w}$$

$D_p \rightarrow$ Load

PROCEDURE

- 1) Measure and note the circumference of effort and load pulleys so as to calculate their diameters.
- 2) Load the machine and find the effort just capable to raise the load
- 3) Repeat the process for changing loads

dist moved by effort = πD_p .

for 1 rev of effort wheel $\frac{N_2}{N_1} \cdot \frac{T}{1}$

rev turned by load wheel $= \frac{1}{T}$

$$\frac{N_2}{N_1} \cdot \frac{1}{T}$$

$$\frac{N_1}{N_2} \cdot \frac{1}{T} \text{ (simpl)}$$

for 1 rev of load wheel load dist moved = πD_w

$\frac{1}{T} \cdot \pi D_w = \pi D_w$

$$\frac{N_2}{N_1} \cdot \frac{1}{T}$$

$V.R. = \frac{\text{dist moved by eff}}{\text{dist moved by load}}$

$$\frac{1}{T} \cdot \pi D_p = \frac{D_p \times T}{D_w}$$

$\therefore V.R. = \frac{\pi D_p}{\pi D_w}$

1. What is the difference between wheel and axle and worm and worm wheel mechanisms?
2. Give any two practical applications of both mechanisms?
3. What is simple machine and compound machine?

POSSIBLE QUESTIONS

1. Movement of worm and worm wheel should be inextensible.
2. String used should be very smooth and very hard.

PREGATIION AND SOURCE OF ERRORS:

Mention the values of M_A , V_R , and Efficiency of the machine

$$d = 11.62$$

(Dp)

$$d = 36.5$$

$$d = 36.5 = 11d$$

$$d = 3.65$$

$$d = 3.65 = 11d$$

$$d = 3.65$$

EXPERIMENT NO. 10 & 9

AIM: To find bending moment in a simply supported beam under loading and draw the SFD & BMD

APPARATUS

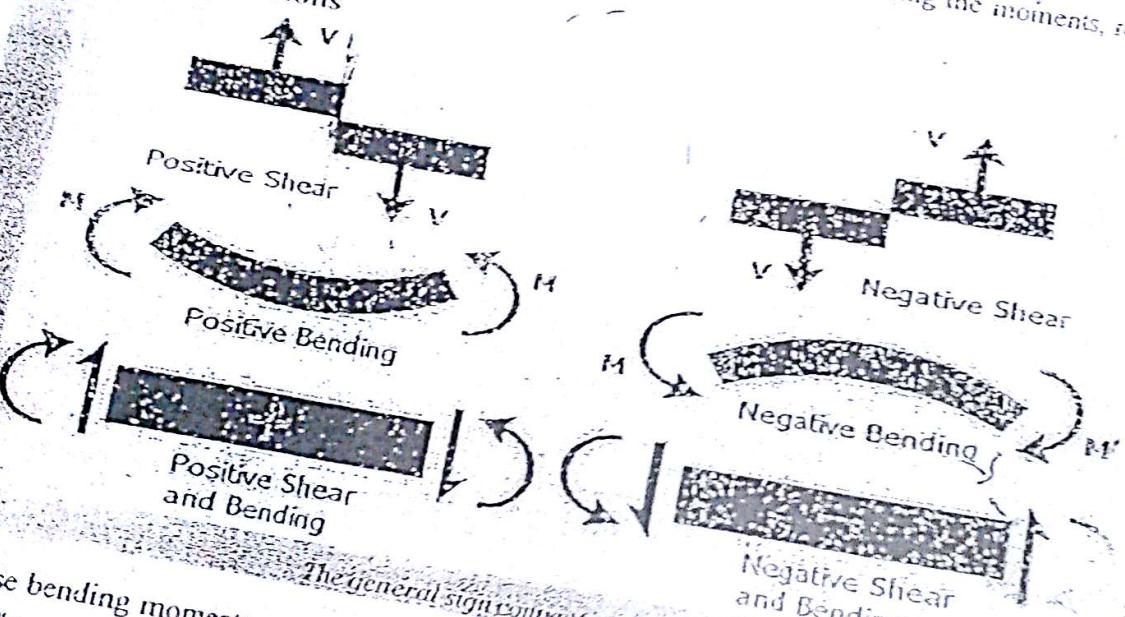
Simply supported beam, weights, scale

THEORY

A bending moment exists in a structural element when a moment is applied to the element so that the element bends. Moments and torques are measured as a force multiplied by a distance so they have as unit newton metres (N m), or foot-pounds force (ft lbs).

The bending moment at a section through a structural element may be defined as "the sum of the moments about that section of all external forces acting to one side of that section". The forces and moments on either side of the section must be equal in order to counteract each other and maintain a state of equilibrium so the same bending moment will result from summing the moments, regardless of which side of the section is selected.

The Sign Conventions



The general sign convention of a beam.

lockwise bending moments are taken as negative, then a negative bending moment within a beam cause "sagging", and a positive moment will cause "hogging". It is therefore clear that a point of bending moment within a beam is a point of contraflexure—that is the point of transition from sagging or vice versa.

It is common to use the convention that a clockwise bending moment to the left of the point under consideration is taken as positive. This then corresponds to the second derivative of a function which, if positive, indicates a curvature that is lower at the centre i.e. sagging.

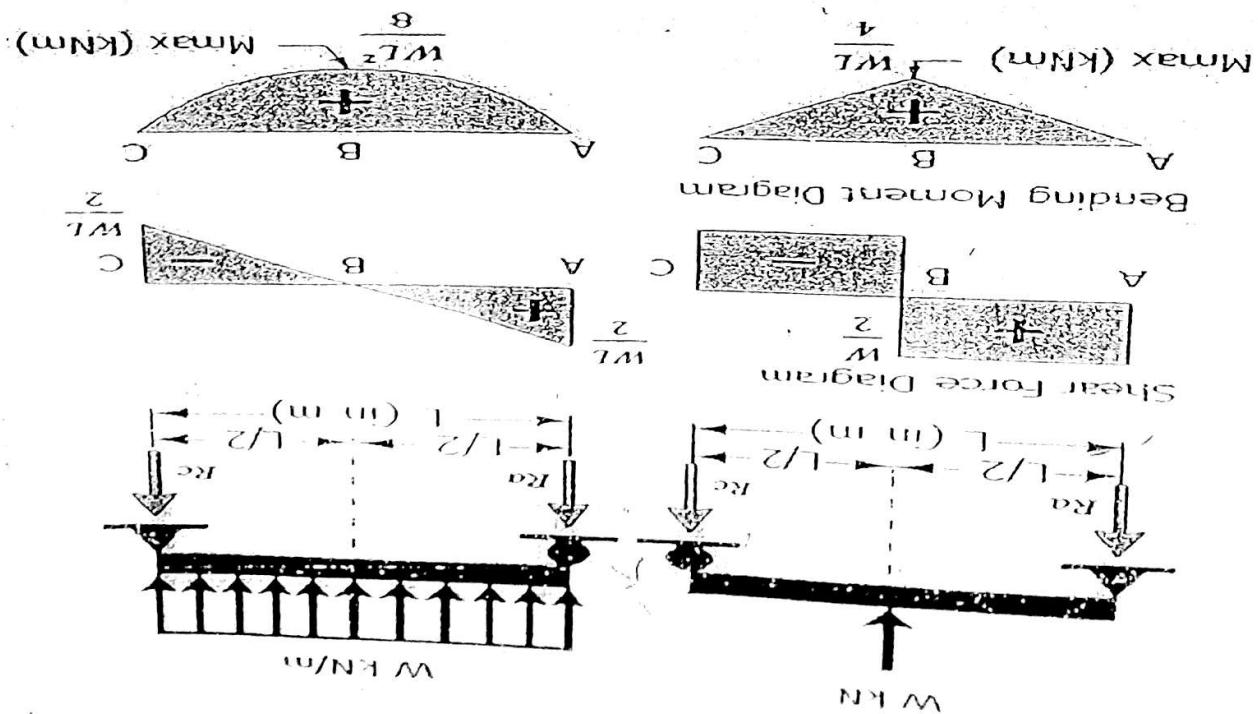
The shear force diagram indicates the shear force will be resisted by the beam section along the length of the beam. The bending moment diagram indicates the bending moment will be resisted by the beam section along the length of the beam.

Shear Force and Bending Moment Diagrams

- Bending reaction (clockwise or anti-clockwise), $\Sigma M = 0$
- Vertical reaction respect to y-axis, $\Sigma F_y = 0$
- Horizontal reaction respect to x-axis, $\Sigma F_x = 0$

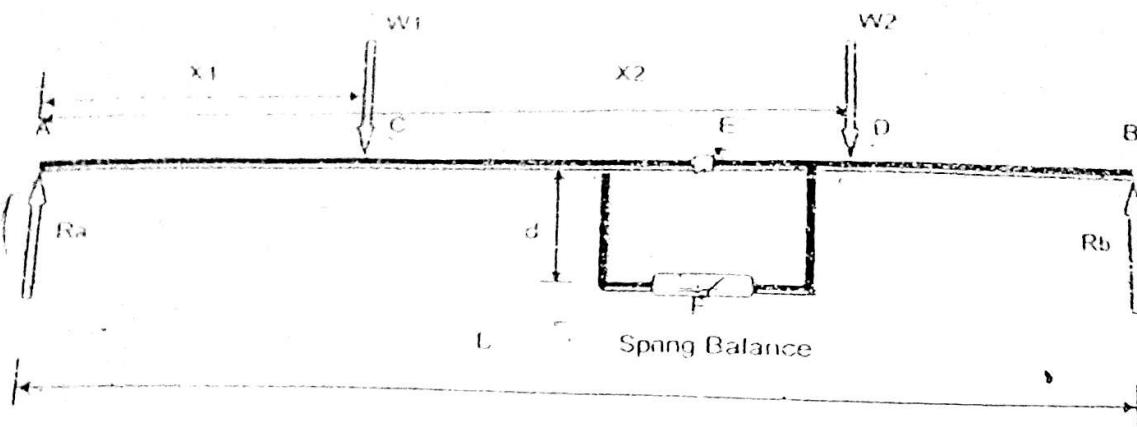
Equilibrium:
The unknown forces (generally the support reactions) are then determined using the Equilibrium of

Shear Force and Bending Moment Diagrams in simply supported beam with two different loads.



For a simply supported beam, the reactions are generally simple terms. When the beam is built in the ground position, it is able to provide a free body diagram with the shear diagram and bending moment diagram.

Shear Force and Bending Moment in Simply Supported Beam
negative diagrams are plotted to side above a horizontal line and positive below. Bending moment values increase linearly over undulated sections and parabolically over undulated sections.



Simple calculation of determine the reactions

Taking $\Sigma F_y = 0$, we get

$$R_A + R_B = W_1 + W_2 \quad \text{--- (i)}$$

$\Sigma M_A = 0$ (taking clockwise as +ve at point A)

$$(W_1 \times X_1) + (W_2 \times X_2) - (R_B \times L) = 0 \quad \text{--- (ii)}$$

0.55

Using eqn. (i) and (ii), we find value of R_A and R_B .

The shear force diagram (SFD) is simply constructed by moving a section along the beam from the left origin and summing the forces to the left of the section. The equilibrium condition states that the forces on either side of a section balance and therefore the resisting shear force of the section is obtained by this simple operation.

$$\begin{aligned} F_{A(\text{left})} &= 0, F_{A(\text{right})} = +R_A, F_{C(\text{left})} = +R_A, F_{C(\text{right})} = +R_A - W_1, F_{E(\text{left})} = +R_A - W_1, F_{E(\text{right})} = +R_A - W_1, \\ F_{D(\text{left})} &= -R_B + W_2, F_{D(\text{right})} = -R_B, F_{B(\text{left})} = -R_B, F_{B(\text{right})} = 0. \end{aligned}$$

On the other hand, bending moment diagram (BMD) is obtained in the same way except that the moment is the sum of the product of each force and its distance of x from the section either left or right. Distributed loads are calculated by summing the product of the total force (to the left of the section) and the x distance of the distributed load centroid.

$$M_A = 0, M_C = +R_A \times X_1, M_E = +R_A \times AE - W_1 \times CE, M_D = +R_B \times BD, M_B = 0 \quad (\text{all in Nm})$$

Also $M_E = F \times d$ (Spring balance reading \times length of arm)

The basic procedure for determining the shear and moment is to determine the values of Shear Force and Bending Moment at various sections along the beam and plotting the results from point to point. By doing so, we will be able to determine critical sections within the beam where a critical or maximum stress might occurs.

- Section of Maximum Shear - Since the shear at any transverse section of the beam is the algebraic sum of the transverse forces to the left of the section, the shear, in most cases can be estimated at a glance.
- Section of Maximum Moment - It can be obtained mathematically, that when the shear force is zero or changes sign, the bending moment, M will be either a maximum or relative maximum.

PROCEDURE

- Bring the unloaded beam to the horizontal position by adjusting the screw on the spring balance.
- Place the two loads at some distance on the beam.
- Again bring the beam to horizontal position by adjusting the screw on spring balance.
- Note down the distance of the loads on the beam from any end and the reading on spring balance.
- Repeat step 2 to 4 for taking five readings.

OBSERVATION TABLE

S.No.	Distance of W ₁ from left end X ₁ (m)	Distance of W ₂ from left end X ₂ (m)	Load W ₁ (N)	Load W ₂ (N)	Reading in spring balance (N)	Length of arm d (m)	Experimental Bending Moment (Nm)	Analytical Bending Moment (Nm)
1.	0.40	1.60	9.8	9.8	30	0.32	2.88	
2.	0.50	1.50	9.8	9.8	33	0.32	3.84	(33-2) x 0.32 = 10.08

Initial $\Rightarrow 21 \text{ N}$

$\frac{3.84}{3.70}$
 0.14

RESULTS AND CALCULATIONS

DISCUSSION

Comment on sources of error and random variation in recorded data.
Comment on possible explanation of differences between recorded data and theoretical predictions.

$$\cancel{R_A + R_B = w_1 + w_2}$$

$$(w_1 \times x_1) + (w_2 \times x_2) = (q_1 b)^2$$

$$(9.8 \times 0.4) + (9.8 \times 1.6) = (9.8)L$$

$$9.8(0.50 + 1.50) =$$

$$19.6$$

$$10.3$$

$$8.8$$

$$0.8$$

$$9.8$$

$$R_A + R_B = w_1 + w_2$$

$$10$$

$$9.8(0.50 + 1.50) =$$