

$$i) P_x = \frac{1}{2T} \int_{-T}^T |x(t)|^2 dt$$

$T \rightarrow \infty$

$$ii) P_a = \frac{P_x}{R_a}$$

$P_a$  - actual power  
 $R_a$  - " resistance

iii) Power of DC sig

$$A \rightarrow A^2$$

$$iv) A \sin \omega t \\ A \cos \omega t \rightarrow \frac{A^2}{2}$$

$$v) A e^{j\omega t} \rightarrow A^2$$

$$vi) P_x = P_1 + P_2 + P_3 + \dots$$

[additive nature of power]

$$vii) X_{rms} = \sqrt{\text{Power}}$$

$$viii) \frac{\sin at}{\pi t} \xrightarrow{FT} \begin{cases} 1 & t=0 \\ 0 & t \neq 0 \end{cases}$$

$$ix) \cos \omega t \xrightarrow{FT} \frac{1}{2} [\delta(\omega - \omega_c) + \delta(\omega + \omega_c)]$$

$$x) \sin \omega t \xrightarrow{FT} \frac{1}{2j} [\delta(\omega - \omega_c) - \delta(\omega + \omega_c)]$$

$$xi) \cos \omega t + \xrightarrow{FT} \frac{1}{2} [\delta(f - f_c) + \delta(f + f_c)]$$

$$xii) \sin \omega t \xrightarrow{FT} \frac{1}{2j} [\delta(f - f_c) - \delta(f + f_c)]$$

$$xiii) x(t) \cos \omega t \xrightarrow{FT} \frac{1}{2} [X(\omega - \omega_c) + X(\omega + \omega_c)]$$

$$xiv) x(t) \sin \omega t \xrightarrow{FT} \frac{1}{2j} [X(f - f_c) + X(f + f_c)]$$

$$xv) \pi t \sin \omega t \xrightarrow{FT} \frac{1}{2j} [X(\omega - \omega_c) - X(\omega + \omega_c)]$$

$$XVii) \frac{1}{\pi t} \xleftarrow{\text{FT}} -j \operatorname{sgn}(\omega)$$

$$XViii) y(t) = x(t) \cdot p(t) \xleftarrow{\text{FT}} \frac{1}{T_s} \sum_{k=-\infty}^{\infty} x(\omega - k\omega_s)$$

## Communication

it is the basic process of exchanging information.

→ A communication process consists of three basic building blocks

- (1) Transmitter
- (2) channel
- (3) receiver



### Transmitter

→ It is a physical system that transmits the information

### Receiver

→ it is a physical system which receives the information

### Channel

It is the medium through which information exchange takes place. Depending upon type of channel used for information exchange, there are two types of communication

#### (i) Line or wire communication

In this type of communication, a physical channel is created b/w TX and RX through copper wires, coaxial cables, optical fibres etc. before the information exchange can take place.

ex

Basic telephone, telegraphy etc.

## II Radio or wireless communication

In this type of communication no. physical channel is created b/w TX and RX.  
the information exchange takes place through space as channel

ex

Mobile communication, broadcasting,  
wireless phones, satellite communication.

### Modulation

→ Modulation is the process of superimposing the information contents of a baseband modulating sig by altering the characteristics of a high freq. carrier wave- (amplitude, freq., phase.)

$$c(t) = A_c \cos(\omega_c t)$$

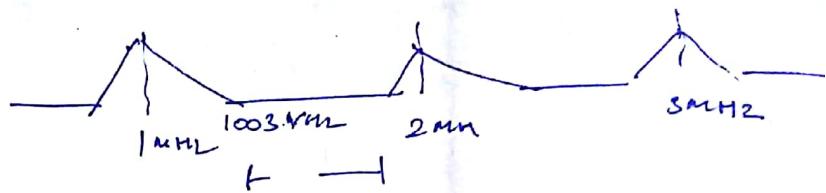
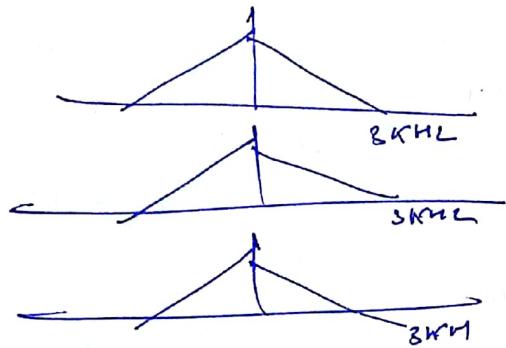
Amplitude      freq      Phase

→ Modulation process translates a low freq Baseband sig into a high freq. band pass sig

→ Since a linear system, can not provide the freq. translation so the modulation process can only be generated by a non-linear device

## Need of Modulation

### ① Avoid mixing of sig's



→ the modulation process translates different baseband sig's at different carrier freq's so that overlapping of spectrums can be avoided

### ② Allows multiplexing of sig's

→ multiplexing means transmission of two or more sig's simultaneously over same channel.

→ Once the overlapping of spectrum has been avoided so now they can be simultaneously transmitted over same channel

### ③ Reduces height of Antenna

$$\lambda = \frac{C}{f}$$

Practical Antenna height =  $\frac{\lambda}{4}$

(i) if  $f_1 = 15 \text{ KHz}$

$$\frac{\lambda}{4} = \frac{3 \times 10^8}{4 \times 15 \times 10^3} = 5 \text{ Km}$$

(2)  $f_2 \approx 15 \text{ MHz}$

$$\frac{\lambda}{4} = \frac{3 \times 10^8}{4 \times 15 \times 10^6} = 5 \text{ m}$$

The height of antenna required for transmission and reception of radio waves is a function of freq. used. the minimum height of antenna is given as  $\lambda/4$  so freq. of transmission must be increased to have practical height of antenna

### ④ Increases Range of communication

At low freq., the Radiation is poor and sig gets highly attenuated therefore baseband sig's can not be transmitted directly over longer distances.

modulation effectively increases the freq of sig to be radiated and

thus increases the distance over which sig can be transmitted faithfully

## ⑤ Improves quality of reception

The sig communication using modulation technique such as FM & PCM reduces the effect of noise to great extent.

→ reduction in noise improves quality of reception

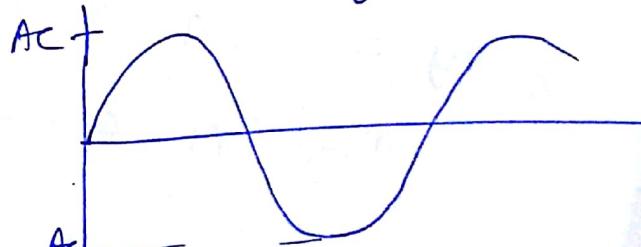
## Amplitude Modulation

- in AM, the amplitude of high freq. carrier sig is varied in accordance with instantaneous value of modulating sig keeping freq & phas constant
- AM translates a low freq baseband sig into a high freq narrow band sig

(1) amplitude

(2) Magnitude

(3) Instantaneous Value -  $A_t$  -



Amplitude - the amplitude of a sig is a vector quantity having magnitude as well as direction

Magnitude - magnitude of a sig is always +ve hence it is a scalar quantity having no direction associated

## Instantaneous value

The value of sig at any instant of time is known as instantaneous value  
it can be +ve as well as -ve  
i.e. vector quantity

## Equation for AM

Let  $m(t)$  = Arbitrary baseband modulating signal having max freq  $w_m$

$$c(t) = A \cos \omega t$$

$$X_{AM}(t) = A \cos \omega t$$

$$A = A_c + m(t)$$

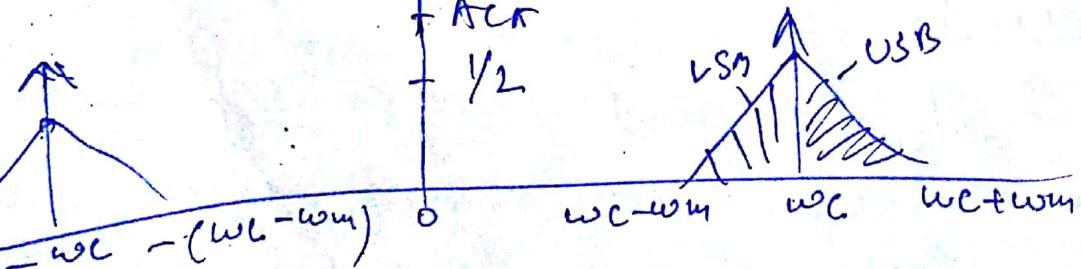
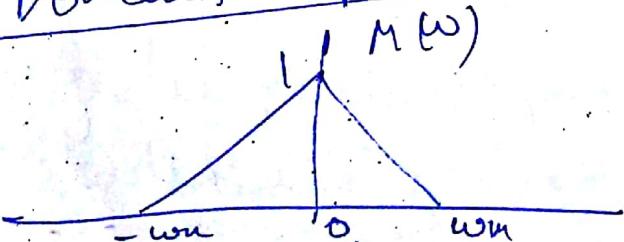
$$X_{AM}(t) = (A_c + m(t)) \cos \omega t$$

$$X_{AM}(t) = A_c \cos \omega t + m(t) \cos \omega t$$

$$X_{AM}(t) = A_c \pi [s(\omega - \omega_c) + s(\omega + \omega_c)] + \frac{1}{2} M (\omega - \omega_c) + M (\omega + \omega_c)]$$

## Freq. Domain representation

$$Bw = 2\omega_m \\ \text{or } 2f_m$$



$$\frac{\omega_m}{BW} = \frac{\omega_c + \omega_m}{2\omega_m} = \frac{1}{2} + \frac{\omega_c - \omega_m}{2\omega_m} = \frac{\omega_c}{2\omega_m} = \frac{\omega_c}{BW}$$

$\frac{\omega_m}{BW} \gg 1$   
so it is Narrowband S/I

### sinusoidal AM

$$m(t) = A_m \cos \omega_m t$$

$$c(t) = A_c \cos \omega_c t$$

$$x_{AM}(t) = A_c \cos \omega_c t$$

$$A = A_c + A_m \cos \omega_m t$$

$$x_{AM}(t) = (A_c + A_m \cos \omega_m t) \cos \omega_c t$$

$$= A_c \left( 1 + \frac{A_m \cos \omega_m t}{A_c} \right) \cos \omega_c t$$

$$\Rightarrow \frac{A_m}{A_c} = m = \text{modulation index}$$

$$x_{AM}(t) = A_c \left( 1 + m \cos \omega_m t \right) \cos \omega_c t$$

$$= A_c \cos \omega_c t + m A_c \cos \omega_m t \cos \omega_c t$$

$$2 \cos A \cos B = \cos(A+B) + \cos(A-B)$$

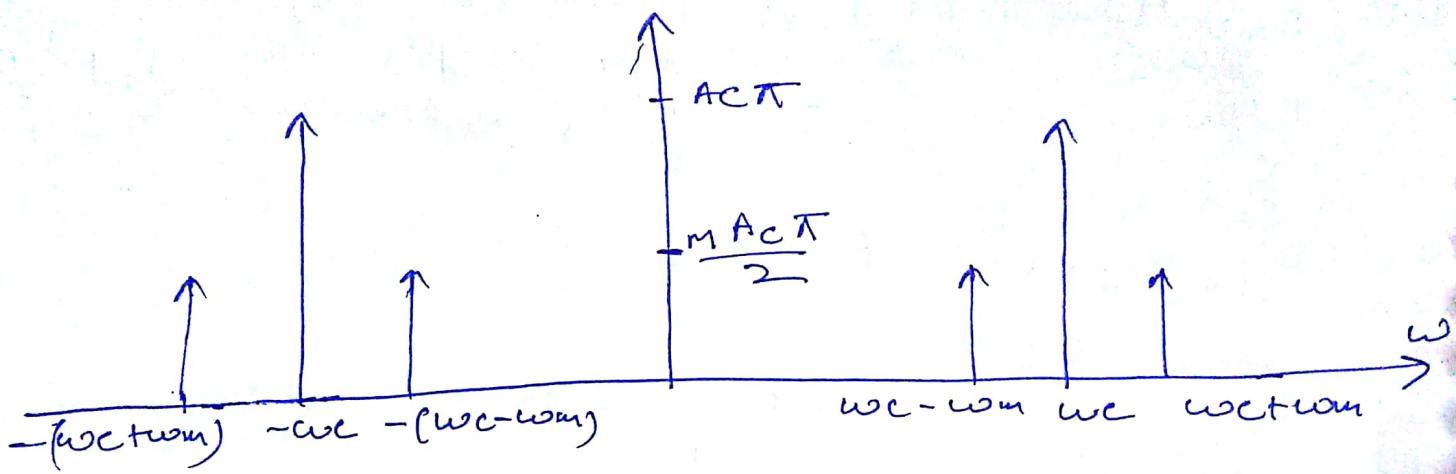
$$\begin{aligned} x_{AM}(t) &= A_c \cos \omega_c t + \frac{m A_c \cos(\omega_c + \omega_m)t}{2} \cancel{+ m A_c \cos(\omega_c - \omega_m)t} \\ &\quad \cancel{+ m A_c \cos \omega_c t} \end{aligned}$$

### Freq. domain

$$x_{AM}(\omega) = A_c \left[ \delta(\omega - \omega_c) + \delta(\omega + \omega_c) \right] +$$

$$\frac{m A_c \pi}{2} \left[ \delta(\omega - (\omega_c + \omega_m)) + \delta(\omega + (\omega_c + \omega_m)) \right]$$

$$+ \frac{m A_c \pi}{2} \left[ \delta(\omega - (\omega_c - \omega_m)) + \delta(\omega + (\omega_c - \omega_m)) \right]$$



### Power Relation in AM

$$X_{AM}(t) = A_c \cos \omega_c t + \frac{m A_c}{2} \cos(\omega_c - \omega_m)t + \frac{m A_c}{2} \cos(\omega_c + \omega_m)t$$

$$P_t = \frac{A_c^2}{2} + \frac{m^2 A_c^2}{8} + \frac{m^2 A_c^2}{8}$$

$$P_c = \frac{A_c^2}{2} \text{ (carrier power)}$$

$$P_{SSB} = \frac{m^2 A_c^2}{4} \text{ (Side band power)}$$

$$= \frac{m^2}{2} \frac{A_c^2}{2} = \frac{m^2}{2} P_c$$

$$P_t = P_c + \frac{m^2}{2} P_c$$

$$\boxed{P_t = P_c \left( 1 + \frac{m^2}{2} \right)}$$

## Current relation in AM

11

$$P = I^2 R$$

for normalised power

$$P_x = I^2$$

$$P_t = I_t^2$$

$$P_c = I_c^2$$

$$I_t^2 = I_c^2 \left( 1 + \frac{m^2}{2} \right)$$

$$I_t = I_c \sqrt{\left( 1 + \frac{m^2}{2} \right)}$$

## Transmission efficiency ( $\eta$ )

Transmission efficiency gives the percentage of useful power in the total transmitted power

$$\eta = \frac{\text{useful Power}}{\text{Total Tx. Power}} \times 100\%$$

$$\eta(\%) = \frac{P_c \frac{m^2}{2}}{P_c \left( 1 + \frac{m^2}{2} \right)} \times 100\%$$

$$\boxed{\eta(\%) = \frac{m^2}{2+m^2} \times 100\%}$$

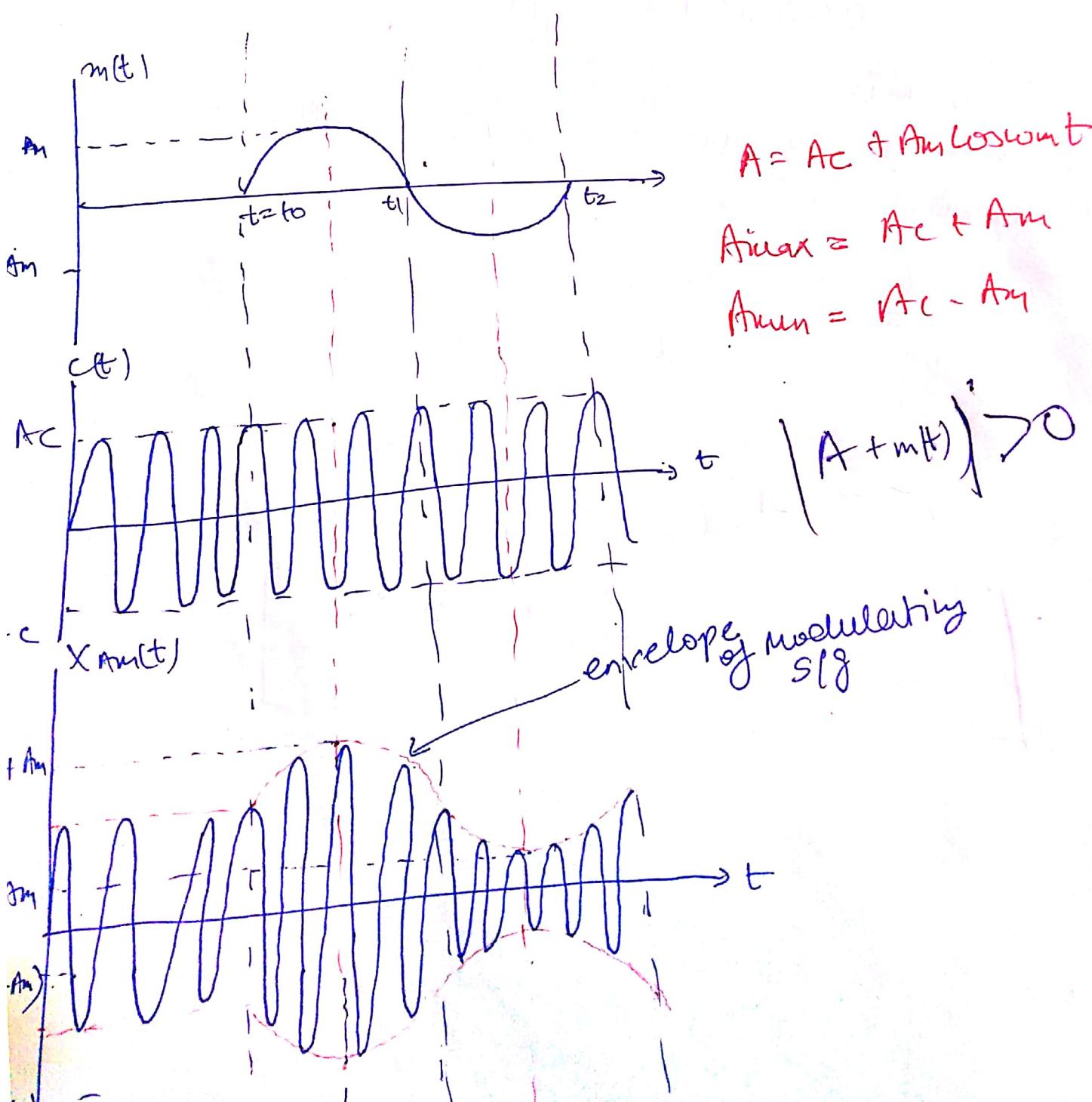
## Power efficiency

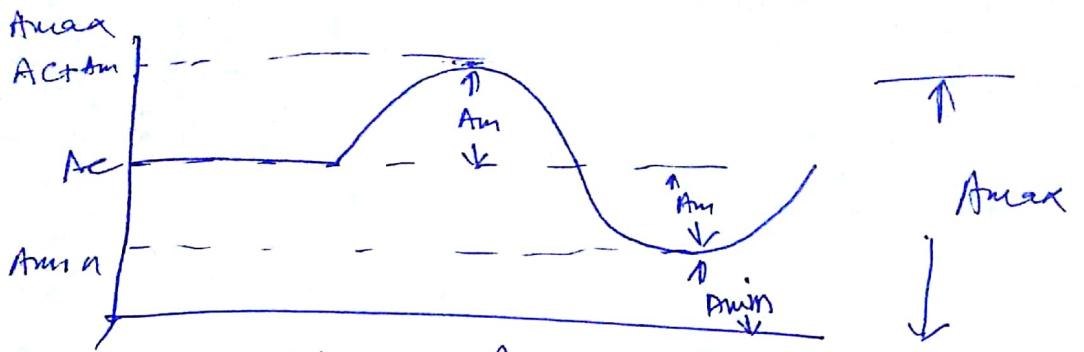
Power efficiency =  $\frac{\text{Carrier Power}}{\text{Total Tx. Power}} \times 100\%$ .

$$PE = \frac{P_c}{P_c(1+m^2)} \times 100\%$$

$$\boxed{PE = \frac{2}{2+m^2} \times 100\%}$$

## Time domain representation of AM sig.





$$2Am = A_{\max} - A_{\min}$$

$$\boxed{Am = \frac{A_{\max} - A_{\min}}{2}} \quad \text{--- (i)}$$

$$Ac = A_{\max} - Am$$

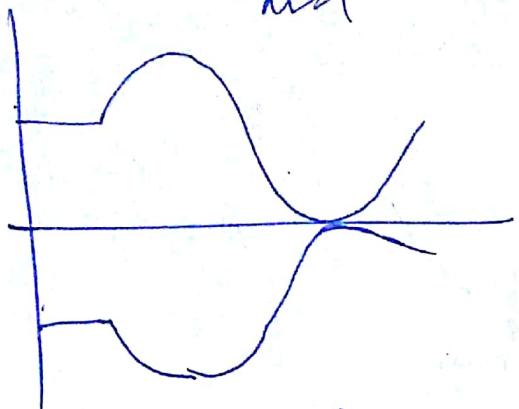
$$= A_{\max} - \frac{A_{\max} - A_{\min}}{2}$$

$$\boxed{Ac = \frac{A_{\max} + A_{\min}}{2}} \quad \text{--- (ii)}$$

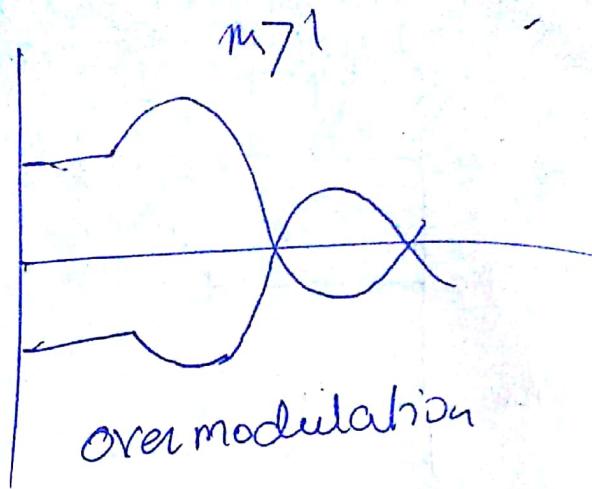
$$\boxed{M = \frac{Am}{Ac} = \frac{A_{\max} - A_{\min}}{A_{\max} + A_{\min}}}$$

### Concept of Modulation Index

- i) it gives the depth to which modulation has occurred when
- ii) when  $M=0$ , it represents no modulation
- iii) when  $M=1$ , max. modulation has occurred
- iv) for  $M > 1$ , overlapping of envelope take place. This is known as "Over modulation"



$$A_{min} = A_c - A_m \approx 0$$



over modulation

→ In Over modulation, The sig still can be detected but with the help of synchronous demodulation only

Q1 in an amplitude modulated system, if the total power is 600W and  $P_c = 400$  W then  $m = ?$

$$600 = 400 \left(1 + m^2\right)$$

$$1.5 = \frac{m^2}{2} \Rightarrow m = 1$$

$$\boxed{P_t = 1.5 P_c}$$

Q2 For an AM wave, Max voltage was found to be 10V and min. Voltage was found to be 5V then modulation index will be

$$m = \frac{10-5}{15} = \frac{1}{3} = 0.33$$

Q3 for an AM sig., BCS is 10 kHz and highest freq. component present is 705 kHz. The carrier freq. used is  $f_c = 700 \text{ kHz}$

In AM, the modulation envelope has a peak value which is double the unmodulated carrier value.  $m = ?$

$$\underline{m=1}$$

$$m = 100\%$$

Critical Modulation

$$2A_c = A_c + A_m$$

$$A_m = A_c$$

Q A given AM broadcast station transmits an average carrier power of 40KW and  $m = 0.707$  for sine wave modulation. What is max amp. of o/p. If antenna is represented by  $50\Omega$  resistive load.

$$P_a = \frac{A_c^2}{2R} \Rightarrow 2R \times 40 \text{ KW} = A_c^2$$

$$A_c = \sqrt{2 \times 40 \times 50 \times 10^3}$$

$$A_c = 2000 \text{ V}$$

$$A_m = m A_c = 2000 \times 0.707 \\ = 1414 \text{ V}$$

$$\boxed{A_{max} = A_c + A_m = 3414 \text{ V}}$$

Q A carrier voltage has a peak amplitude of 10V at a freq of 1MHz. A sinusoidal signal of 1KHz varies the amplitude of RF wave b/w 7.5 & 12.5V.

$$\underline{A_m = 2.5}$$

$$20(1 + 0.5 \cos 1000t) \quad (10^6 \text{ Hz})$$

## Simultaneous modulation by several sine waves

$$m_1(t) = A_{m1} \cos \omega_{m1} t$$
$$m_2(t) = A_{m2} \cos \omega_{m2} t$$

Let  $A_{m2} > A_{m1}$   
 $\omega_{m2} > \omega_{m1}$

$$m(t) = m_1(t) + m_2(t)$$

$$m(t) = A_{m1} \cos \omega_{m1} t + A_{m2} \cos \omega_{m2} t$$

$$c(t) = A \cos \omega_c t$$

$$X_{AM}(t) = A \cos \omega_c t$$

$$\Rightarrow A = Ac + A_{m1} \cos \omega_{m1} t + A_{m2} \cos \omega_{m2} t$$

$$X_{AM}(t) = [Ac + A_{m1} \cos \omega_{m1} t + A_{m2} \cos \omega_{m2} t] \cos \omega_c t$$
$$= Ac [1 + m_1 \cos \omega_{m1} t + m_2 \cos \omega_{m2} t] \cos \omega_c t$$

$$m_1 = \frac{A_{m1}}{Ac} \quad m_2 = \frac{A_{m2}}{Ac}$$

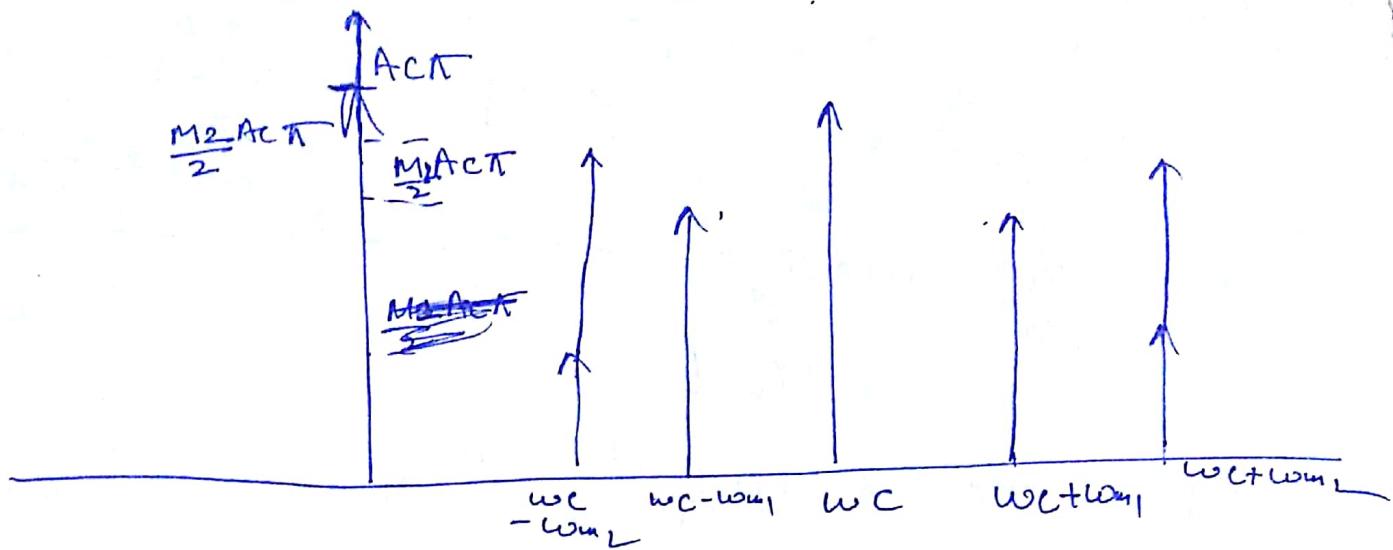
$$\therefore m_2 > m_1$$

$$X_{AM}(t) = Ac \cos \omega_c t + m_1 Ac \cos \omega_c t \cos \omega_{m1} t$$
$$+ m_2 Ac \cos \omega_c t \cos \omega_{m2} t$$

$$X_{AM}(t) = Ac \underbrace{\cos \omega_c t}_{\text{carrier}} + \frac{m_1 Ac}{2} \cos \left( \omega_c + \frac{\omega_{m1}}{2} \right) t$$
$$+ \frac{m_1 Ac}{2} \cos \left( \omega_c - \frac{\omega_{m1}}{2} \right) t +$$
$$\frac{m_2 Ac}{2} \cos \left( \omega_c + \frac{\omega_{m2}}{2} \right) t + \frac{m_2 Ac}{2} \cos \left( \omega_c - \frac{\omega_{m2}}{2} \right) t$$

USB1 LSB1 USB2 LSB2

## Frequency domain Representation



$$\text{BW} = w_c + w_{m_2} - (w_c - w_{m_2}) \\ = 2 w_{m_2}$$

for  $w_{m_1}, w_{m_2}, w_{m_3}, \dots$

$$\text{BW} = 2 \cdot \text{Max}[w_{m_1}, w_{m_2}, w_{m_3}, \dots]$$

- ① When a carrier signal is simultaneously modulated by several sine waves then for each addition of modulating sig a pair of side band gets added in the resultant AM sig. That is why AM is also known as "linear modulation".
  - ② The BW of resultant modulated sig is given by
- $$\text{BW} = 2 \cdot \text{Max}[w_{m_1}, w_{m_2}, w_{m_3}, \dots]$$

## Power Relation

$$P_t = P_c \left( 1 + \frac{M_T^2}{2} \right)$$

$$P_t = \frac{A c^2}{2} + \frac{m_1^2 A c^2}{8} + \frac{m_2^2 A c^2}{8} + \frac{m_3^2 A c^2}{8}$$

$$P_t = \frac{A c^2}{2} + \frac{m_1^2 A c^2}{4} + \frac{m_2^2 A c^2}{4}$$

$$P_c = \frac{A c^2}{2}$$

$$P_{SB1} = \frac{m_1^2}{4} A c^2 = \frac{m_1^2}{2} \frac{A c^2}{2} = \frac{m_1^2}{2} P_c$$

$$P_{SB2} = \frac{m_2^2}{2} P_c$$

$$P_t = P_c \left( 1 + \frac{m_1^2 + m_2^2}{2} \right)$$

$$P_t = P_c \left( 1 + \frac{M_T^2}{2} \right)$$

$$M_T^2 = m_1^2 + m_2^2 + m_3^2 + \dots$$

$$\text{Q6 } \underline{x(t)} = 50C_1 + 0.89 \cos(2000t + 0.3) \sin(9000t)$$

$$\omega_C = 6\pi \times 10^6$$

$$\omega_{M_1} = 5000$$

$$\omega_{M_2} = 9000$$

$$\omega_C \pm \omega_{M_1} = 6000 \times 10^3 \pm 5 \times 10^3 \\ = 6005 \times 10^3, 5995 \times 10^3$$

$$\omega_C \pm \omega_{M_2} = 6009 \times 10^3, 5991 \times 10^3$$

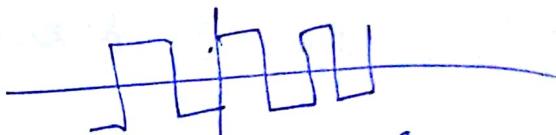
⑧ d

$$\frac{1}{100 \times 10^{-6}} \text{ sec} = \underline{10 \text{ kHz}}$$

$$f_1 = \frac{10 \text{ kHz}}{100 \pm 10}$$

$$f_2 = 30 \text{ kHz} \quad 100 \pm 30$$

$$f_3 = 50 \text{ kHz}$$



for square wave  
odd & half wave sym.  
1, 3, 5, 7 odd harmonics exist only

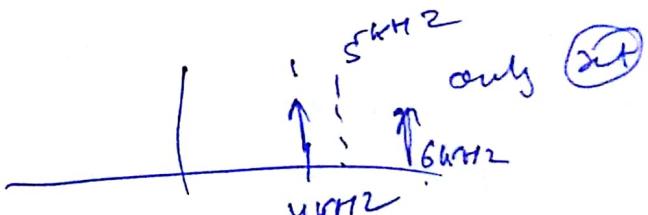
⑨

$$T_S = 100 \mu\text{sec}$$

$$f_S = 10 \text{ kHz}$$

$$x(t) \rightarrow 4 \text{ kHz}$$

$$y(\omega) \approx \frac{1}{T_S} \sum_{n=-\infty}^{\infty} X_n (\omega - n\omega_S)$$



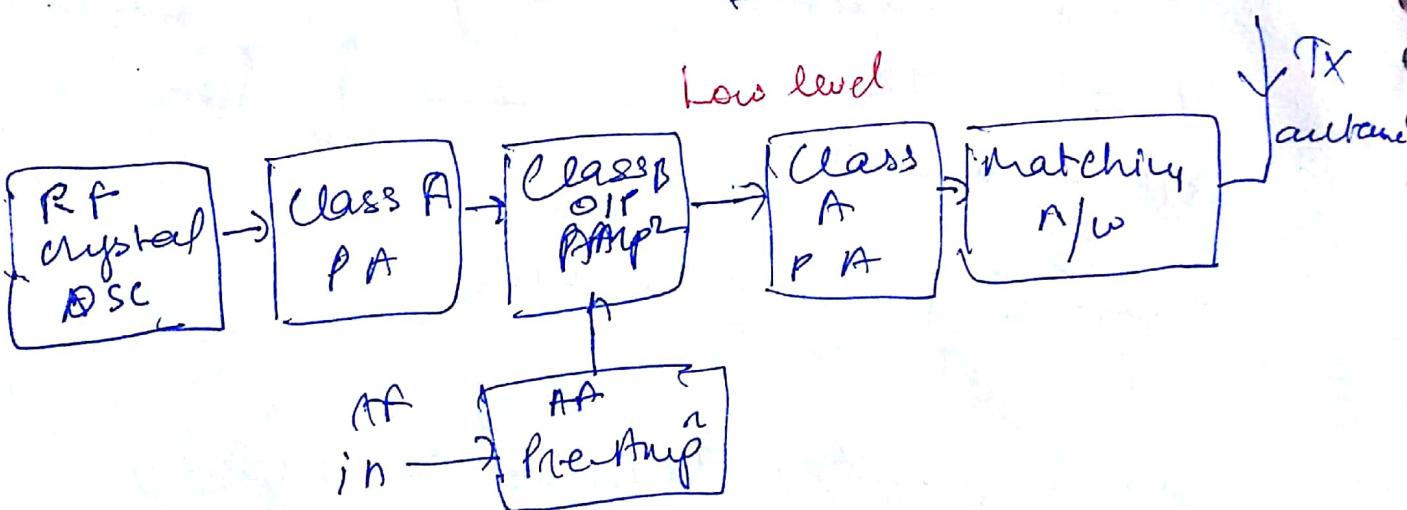
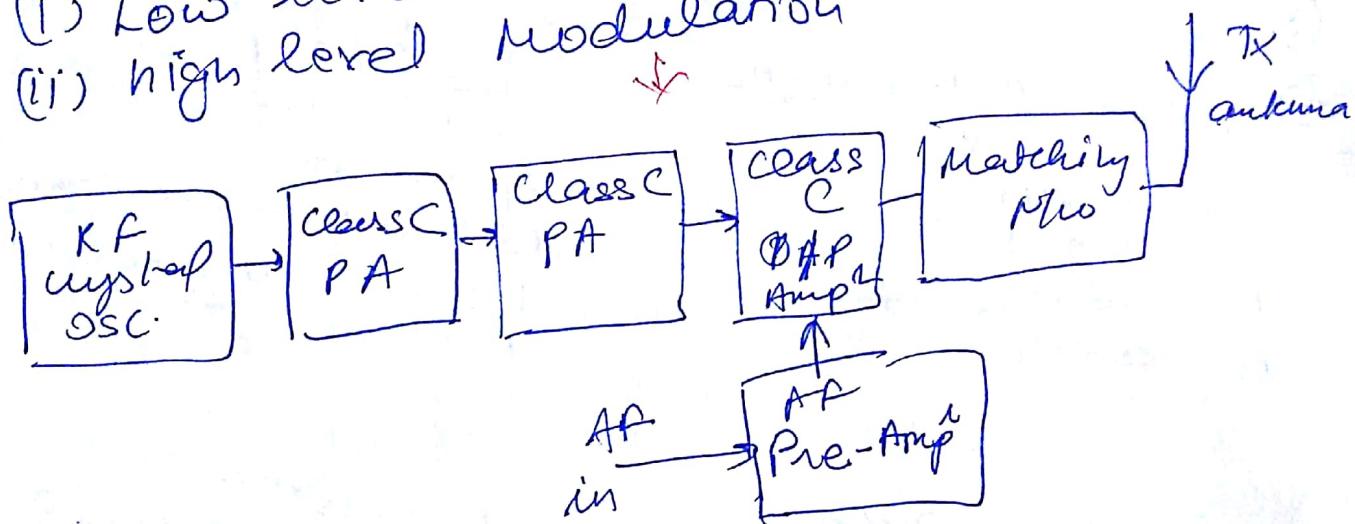
$$y(t) = 5 \times 10^{-6} \times 10^{14} \times 10 \cos(2\pi \times 10^3 t)$$

⑩

## Generation of AM sig

Depending upon the carrier power level at which the modulation takes place there are two methods for generation of AM wave

- (i) Low level Modulation
- (ii) high level Modulation



Modulation is translation of freq. which can only be generated by a non-linear device. That is why class A power Amp can not be used for generation of modulation.

② Once a sig. is modulated only a linear PA can be used for Amplification purpose bcoz a nonlinear power Amp will try to distort the information.

### Comparison b/w low level & high level modulation

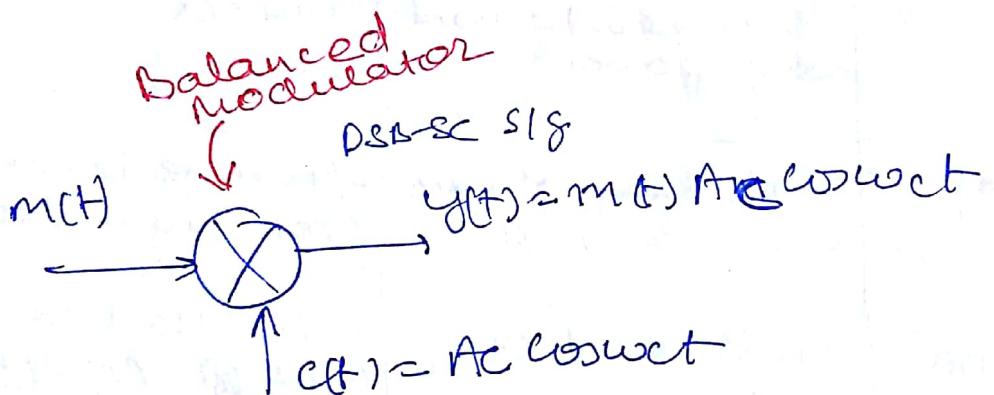
SNO	Parameter	Low level modulation	High level modulation
1	Pt. at which mod. take place	mod. takes place in initial stages of Amplification	mod. takes place in final stages of Amplification
2	Power level handling	mod. circuitry has to handle low power	mod. circuitry has to handle high power
3	Complexity	mod. ckt is simple as it has to handle low power	mod. ckt is quite complex
4	Range of Transmission	In this, range of transmission is small.	Sig can be transmitted over longer distance
5	Application	This is used only for lab's purposes	This is used in practical AM system

## DSB-SC

Double side band - Suppressed carrier  
Transmission of full AM sig is not advisable

because

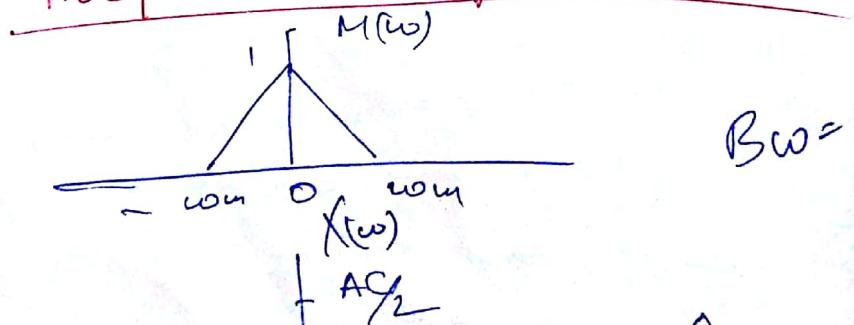
- ① Since carrier is also transmitted which does not contain any information
- ② For  $m=1$ ,  $\frac{2}{3}$ rd of total transmitted power appears in the carrier which is a complete wasteage
- ③ So, instead of transmitting full AM sig the carrier is suppressed before transmission and such type of modulation is known as DSB-SC modulation



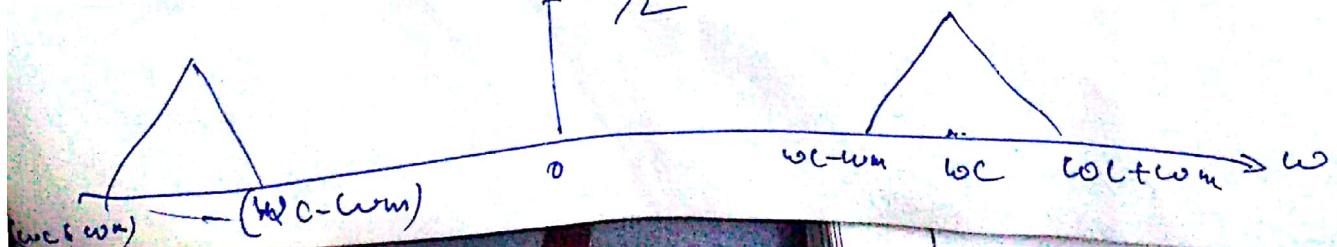
$$y(t) = m(t) Ac \cos(\omega_0 t)$$

$$Y(\omega) = \frac{Ac}{2} [M(\omega - \omega_0) + M(\omega + \omega_0)]$$

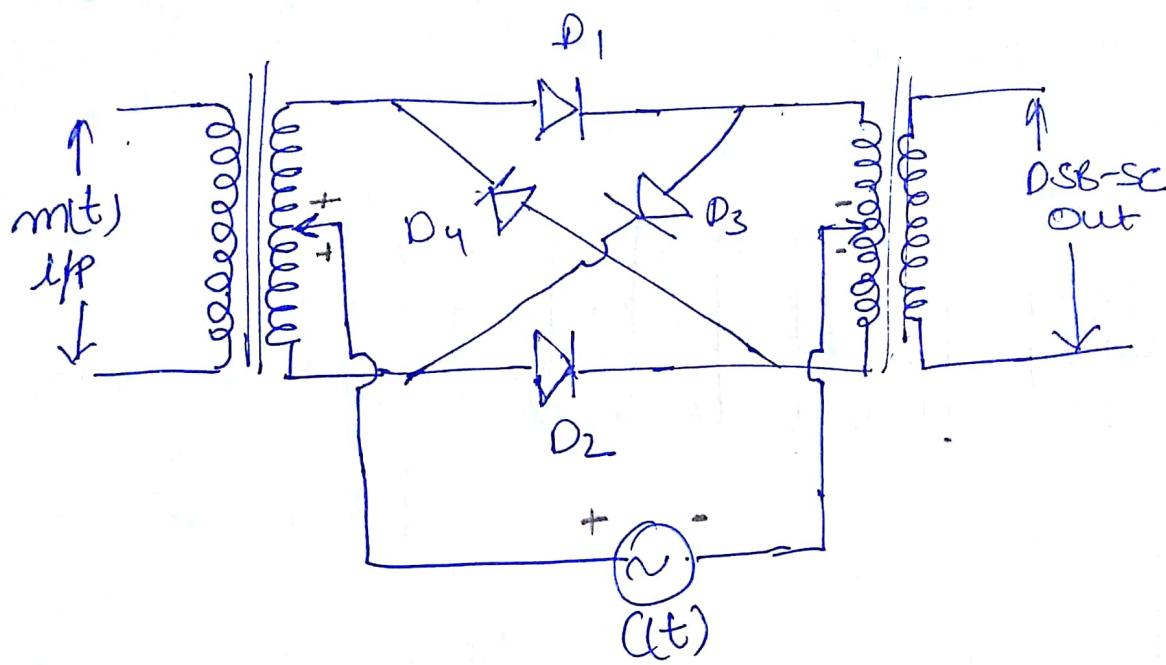
freq domain representation



$$BW = 2\omega_m$$

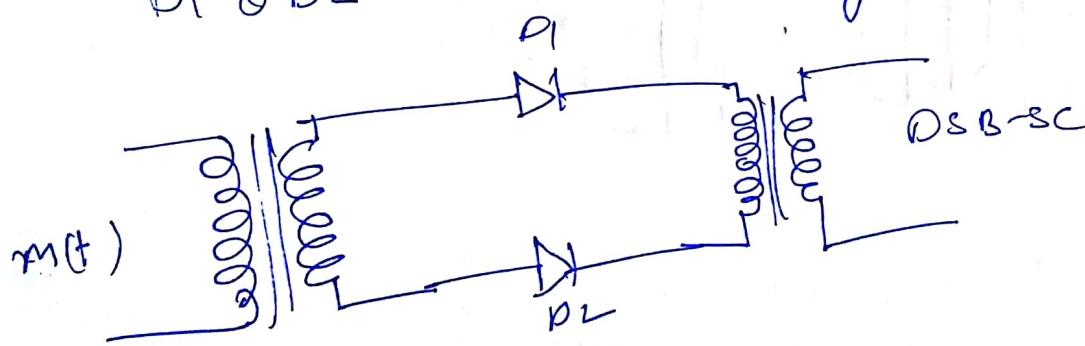


## Ring Modulator

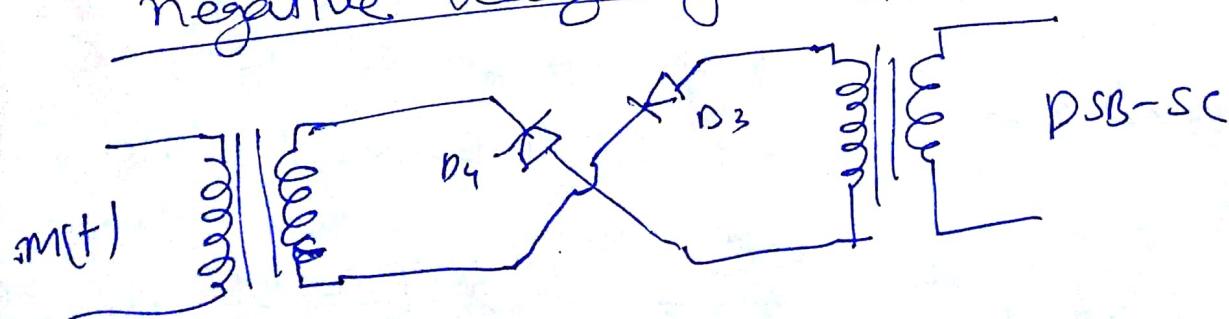


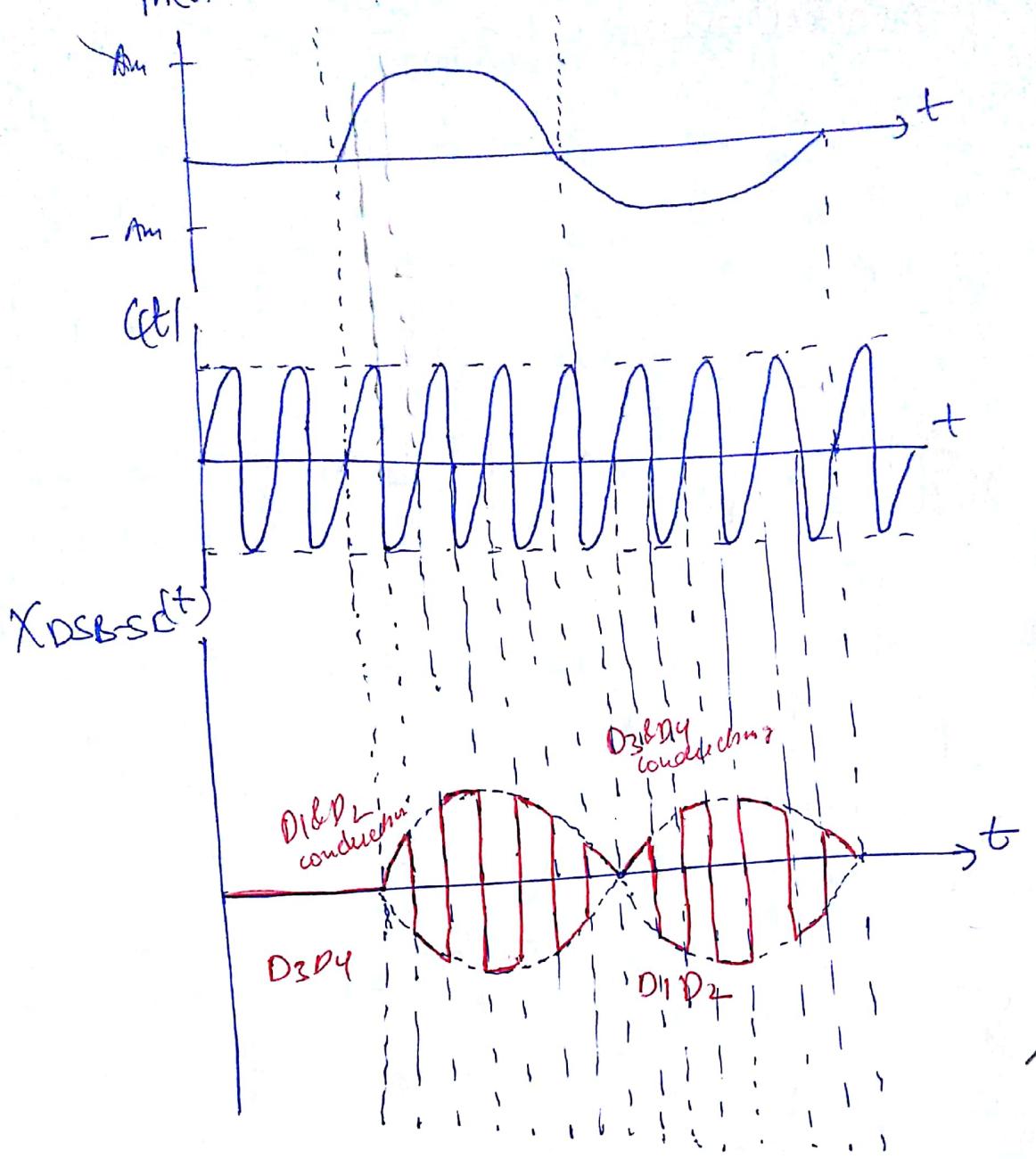
Positive half cycle

D<sub>1</sub> & D<sub>2</sub> are conducting



negative half cycle





### Power saving in DSB-SC Modulation

$$P_t = P_c + \frac{P_m^2}{2}$$

$$\% \text{ Power Saving} = \frac{\text{Total power saved}}{\text{Total Tx. Power}} \times 100\%.$$

$$= \frac{P_c}{P_c(1 + \frac{P_m^2}{2})} \times 100\%$$

$$\boxed{\% \text{ Power Saving} = \frac{2}{2 + m^2} \times 100\%}$$

$$\text{For } m=1 ; \rightarrow \frac{2}{2+1} \times 100\% = 66.67\%.$$

$$m=0.5; \rightarrow \frac{2}{2+2} \times 100\% = 88.88\%.$$

25

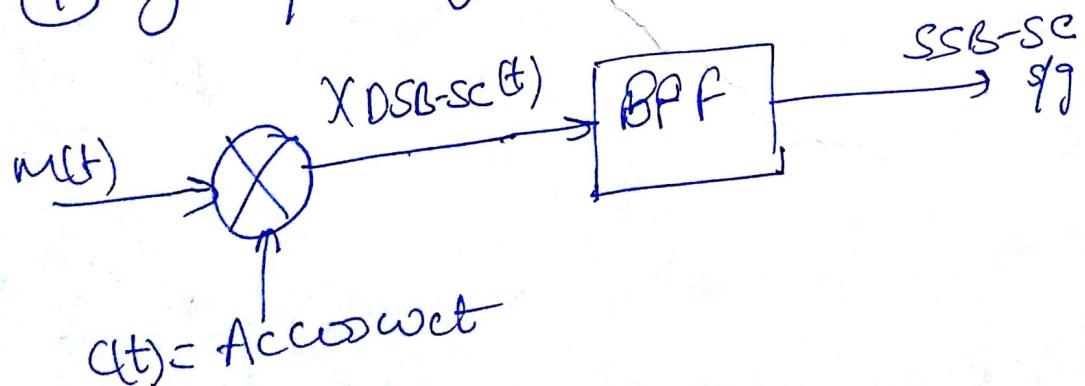
### SSB-SC Modulation

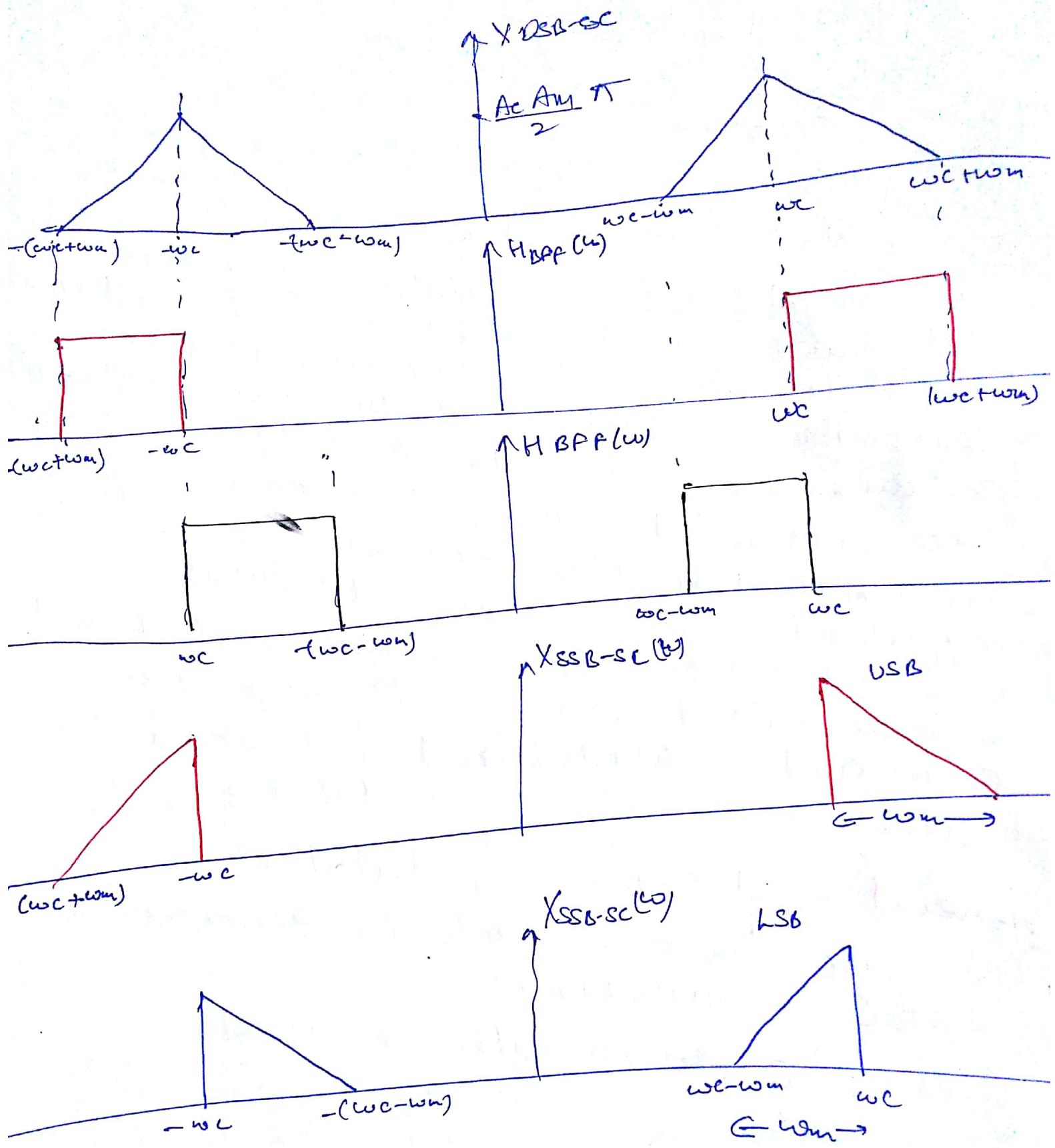
In case of DSB-SC modulation, the two side bands are transmitted which contains the same information. So the DSB-SC transmission is further redundant. Instead of transmitting both the side bands, only one side band either UCB or LCB is transmitted while another one is suppressed. Such type of modulation in which either upper or lower side band is transmitted while suppressing the carrier and ~~unwanted~~ side band is known as SSB-SC modulation.

### Generation of SSB-SC modulation

There are two methods for generation of SSB-SC modulation.

① Frequency discrimination method





## Disadvantage of freq discrimination method

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The freq discrimination method can be used only when there is definite gap b/w upper and lower SB.  
If gap is very very small or both are meeting at carrier freq. then this method can not be used.

## ② Phase discrimination method

### Hilbert transform

It is a method of separating the sig's wth same phase contents. The easiest phase generation is  $\pi$  ( $180^\circ$ ).

Hilbert transformer is a special type of transfer that separates the signal with a phase difference of  $\pi/2$  b/w them. The hilbert transform of sig  $x(t)$  is given by

$$\bar{x}(t) = \int_{-\infty}^t \frac{x(z)}{\pi(t-z)} dz$$

$$\bar{x}(t) = x(t) * \frac{1}{\pi t}$$

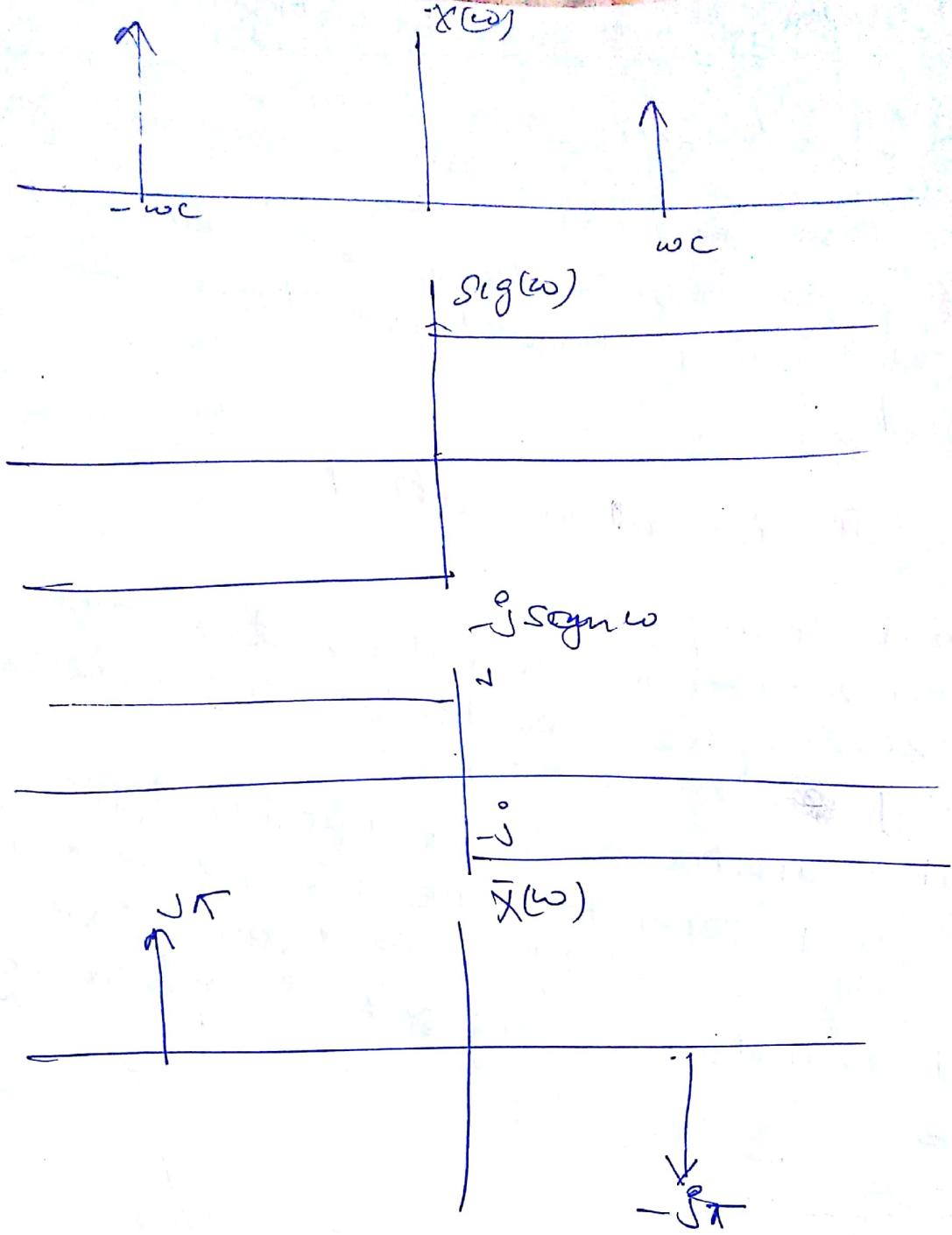
$$\bar{x}(\omega) = X(\omega)(-j \operatorname{sgn}(\omega))$$

Q  $x(t) = \cos \omega t \xrightarrow{HT} \sin \omega t$

$$X(\omega) = \pi (\delta(\omega - \omega_c) + \delta(\omega + \omega_c))$$

$$\bar{x}(\omega) = \pi (\delta(\omega - \omega_c) + \delta(\omega + \omega_c))(-j \operatorname{sgn}(\omega))$$

$$= -j \pi$$

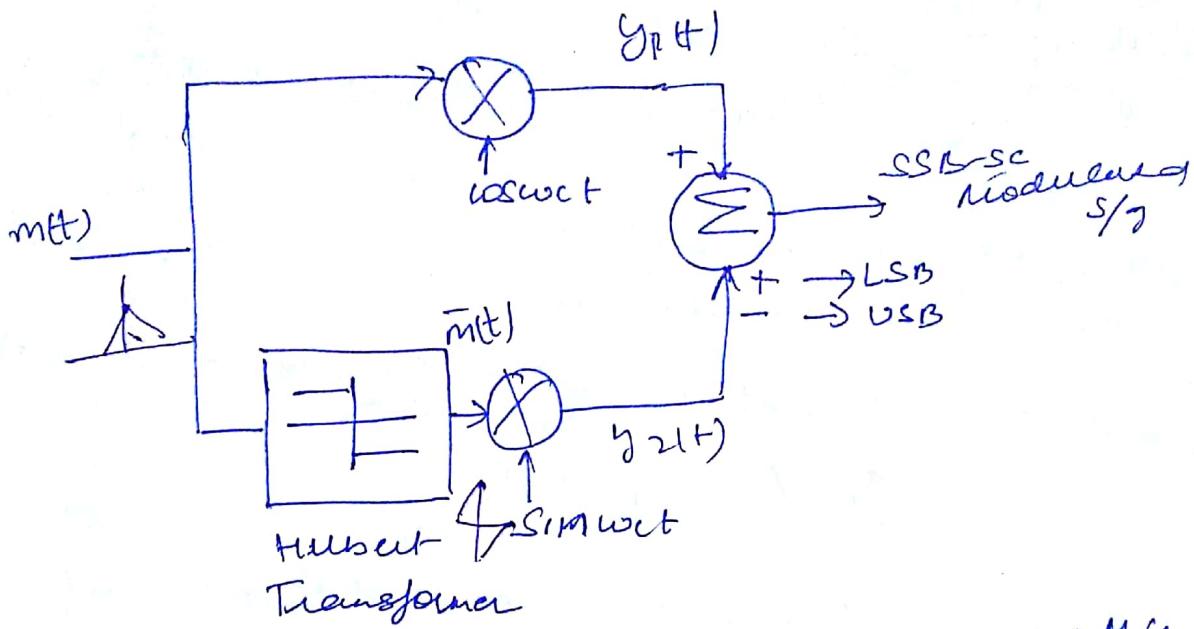


$$j\pi (\delta(\omega + \omega_c) - \delta(\omega - \omega_c))$$

$$\bar{x}(\omega) = \frac{1}{j} (\delta(\omega - \omega_c) - \delta(\omega + \omega_c))$$

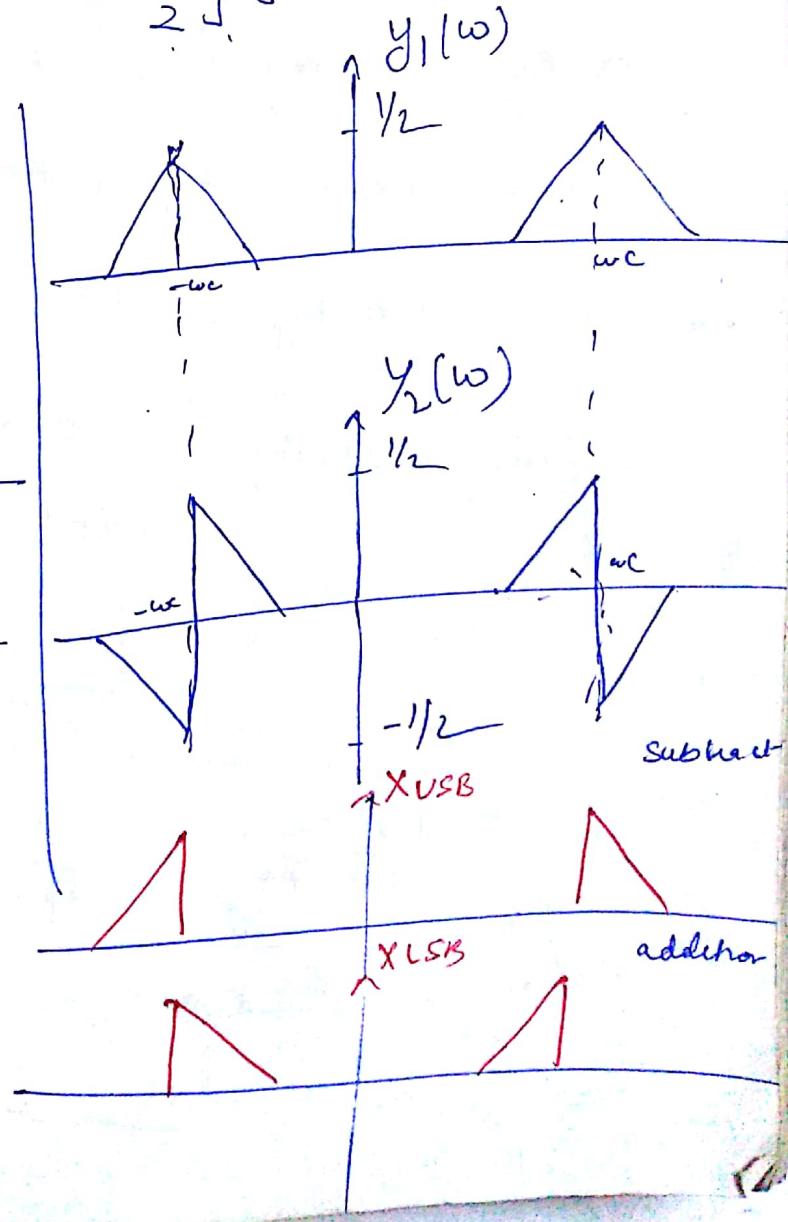
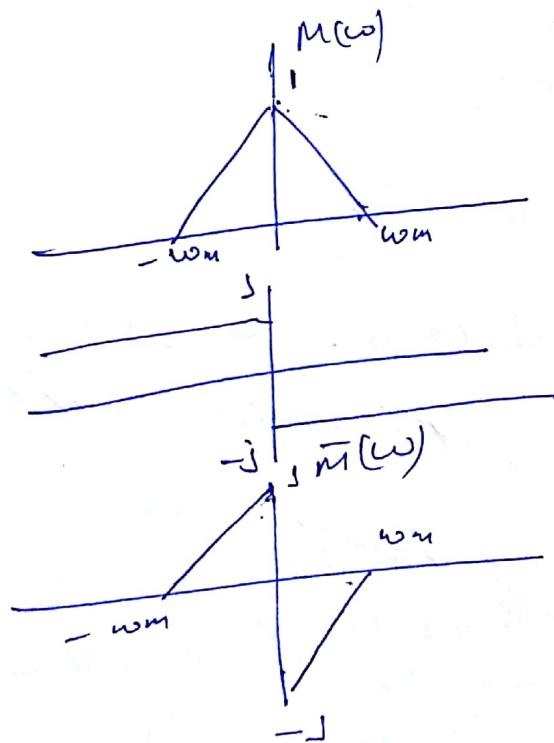
$$\bar{x}(t) = \sin \omega t$$

Assignment  
Struct  $\rightarrow$  -Coswt



$$y_1(t) = m(t) \cos\omega_{ct} \xrightarrow{FT} \frac{1}{2} [M(\omega - \omega_c) + M(\omega + \omega_c)]$$

$$y_2(t) = \bar{m}(t) \sin\omega_{ct} \xrightarrow{FT} \frac{1}{2} j [M(\omega - \omega_c) - \bar{M}(\omega + \omega_c)]$$



$$X_{SSB-SC} = m(t) \cos \omega t + \hat{m}(t) \sin \omega t$$

$$m(t) = A_m \cos \omega t \xrightarrow{HT} A_m \sin \omega t$$

$$X_{SSB-SC}(t) = A_m \cos \omega t \cos \omega t$$

$$\pm A_m \sin \omega t \sin \omega t$$

$$X_{SSB-SC}(t) = \text{Coswt Coswt} \pm \begin{matrix} \text{Sinwt Sinwt} \\ \text{SSB} \end{matrix}$$

$$= \cos(\omega_c - \omega_m)t$$

$\cos(\omega_c - \omega_m)t \rightarrow \text{lower side band}$

$\cos(\omega_c + \omega_m)t \rightarrow \text{upper side band}$

## Power Saving in SSB-SC Modulation

$$P_t = P_c + P_c \frac{m^2}{4} + P_c \frac{m^2}{4}$$

$$\therefore \text{Total Power saving} = P_c \left( 1 + \frac{m^2}{4} \right)$$

$$\% \text{ Power saving} = \frac{\text{Total Power saved}}{\text{Total Tx power}} \times 100\%$$

$$= P_c \left( 1 + \frac{m^2}{4} \right) \frac{4 + m^2}{4 + 2m^2}$$

$$\boxed{\% \text{ Power saving} = \frac{4 + m^2}{4 + 2m^2} \times 100\%}$$

$$m=1 \Rightarrow \frac{4+1}{4+2} \times 100\% = 83.33\%$$

$$m=0.6 \Rightarrow \frac{4.25}{4.5} = 94.4\%$$

## Advantage of SSB-SC mod. over DSB-SC & Full-AM 31

- ① The spectrum space occupied by the SSB-SC s/g is only ~~fm~~ fm which is only half that of AM & DSB-SC s/g. So. SSB-SC modulation requires only half the transmission BW as compared to AM & DSB-SC s/g. That is why SSB-SC modulation is standard for FDM

100KHz → Total available spectrum

for DSB-SC & Full-AM  
 $f_m = 5KHz$   
 $BW = 10KHz$

total no. of channel  
 $= \frac{100}{10} = 10$

for SSB-SC  
 $f_m = 5KHz$   
 $BW = 5KHz$   
Total no. of channel = 20

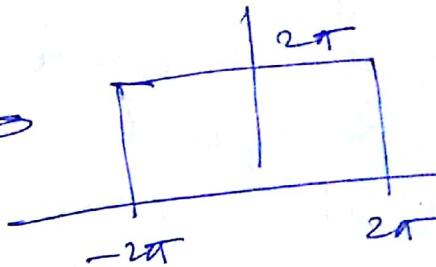
- ② due to suppression of carrier and one side band, more power is saved and saved power can be used to produce a stronger s/g that will carry further and it will be reliably received at greater distances

Q(4) Page 116

$$\left( \frac{2 \sin 2\pi t}{t} \cos 200\pi t + \frac{\sin 199\pi t}{t} \right) \cos 200\pi t$$

$$2 \frac{\sin 2\pi t}{t} \cos^2 200\pi t + \frac{\sin 199\pi t}{t} \cos 200\pi t$$

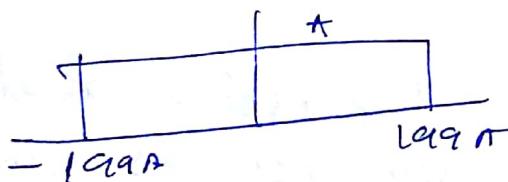
$$m(t) = \pi \frac{2 \sin 2\pi t}{At} \xrightarrow{\text{FT}}$$



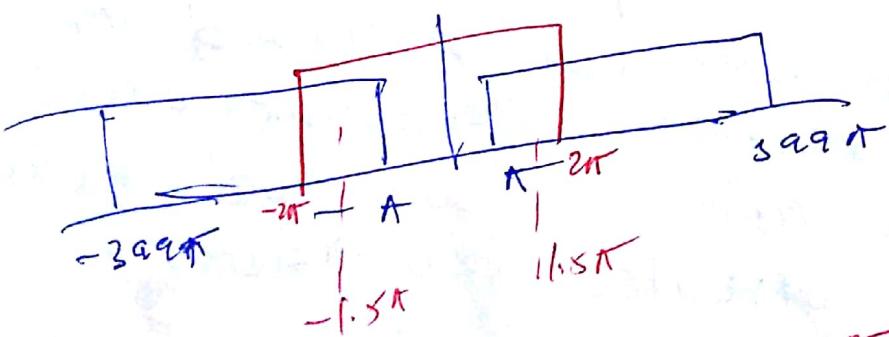
$$m(t) \left( 1 + \frac{\cos 400\pi t}{2} \right)$$

$$\frac{m_t}{2} + \frac{m_t \cos 400\pi t}{2} \quad \text{not pass}$$

$$\frac{\sin 199\pi t}{t} \cos 200\pi t + \frac{1}{2} (n(\omega=200\pi) + n(\omega+200\pi))$$



$$\frac{1}{2} \sin$$



$$\times \cos 1.5\pi$$

$$K \sin 0.5\pi$$

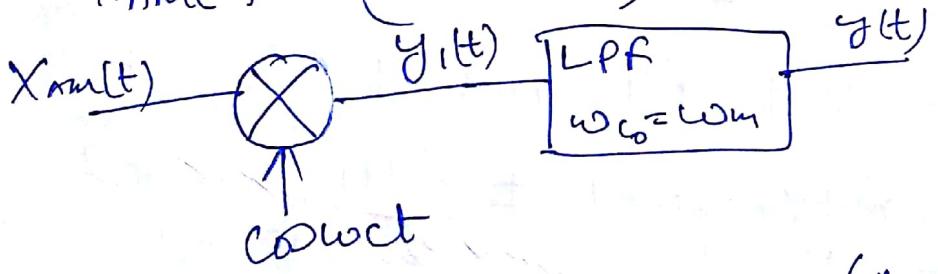
# Detection of AM waves

- The recovery of Baseband signal from the modulated signal is known as demodulation or detection of waves.
- there are two methods for detection of AM sig. I synchronous detection

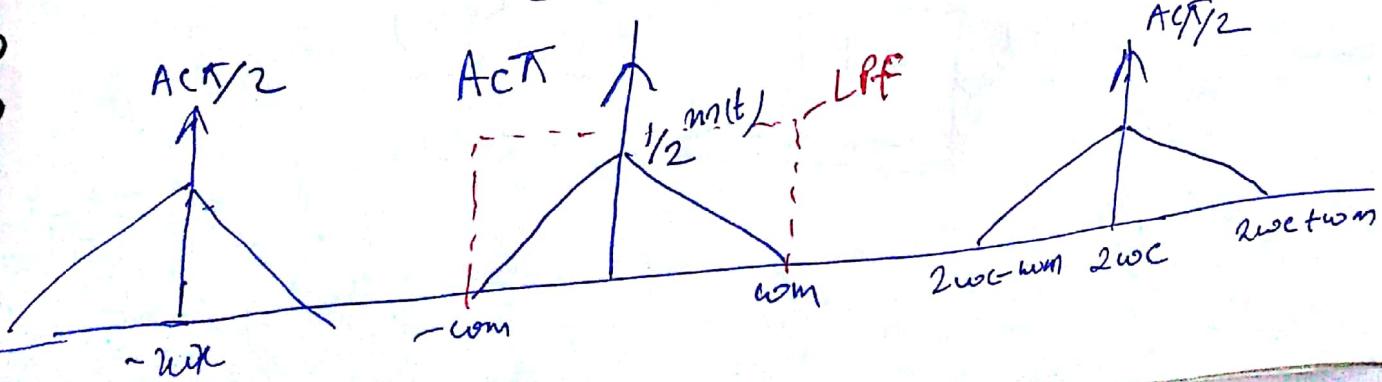
in this method of detection, a local carrier is generated at the receiving end whose phase is exactly synchronized with the Txed carrier sig. phase. This locally generated carrier is multiplied by the Rxed sig and the product is passed through a LPF to recover the original baseband sig.

## 1. detection of full AM wave

$$x_{AM}(t) = (A_c + m(t)) \cos \omega_c t$$



$$\begin{aligned} y_1(t) &= (A_c + m(t)) \cos^2 \omega_c t = (A_c + m(t)) \frac{1 + \cos 2\omega_c t}{2} \\ &= A_c \cdot \frac{A_c}{2} + \frac{m(t)}{2} + \frac{A_c}{2} \cos 2\omega_c t + \frac{m(t)}{2} \cos 2\omega_c t \end{aligned}$$



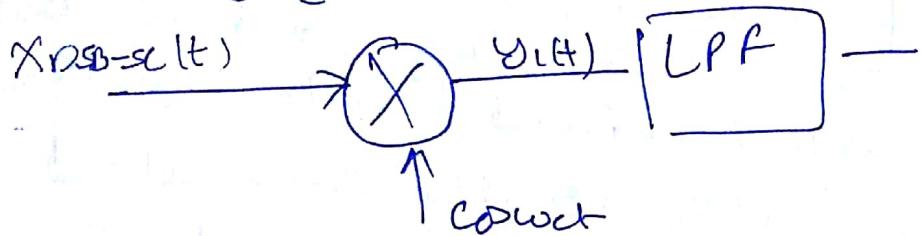
$$y(t) = \frac{A_c}{2} + \frac{1}{2} m(t)$$

$\frac{A_c}{2}$  can be removed by passing this sig. to capacitor

$y(t) = \frac{1}{2} m(t)$

## 2. Detection of DSB-SC wave

$$x_{DSB-SC}(t) = A_c m(t) \cos \omega_c t$$



$$\begin{aligned} y_1(t) &= A_c m(t) \cos^2 \omega_c t = A_c m(t) \left( \frac{1 + \cos 2\omega_c t}{2} \right) \\ &= \frac{A_c m(t)}{2} + \frac{A_c m(t) \cos 2\omega_c t}{2} \end{aligned}$$

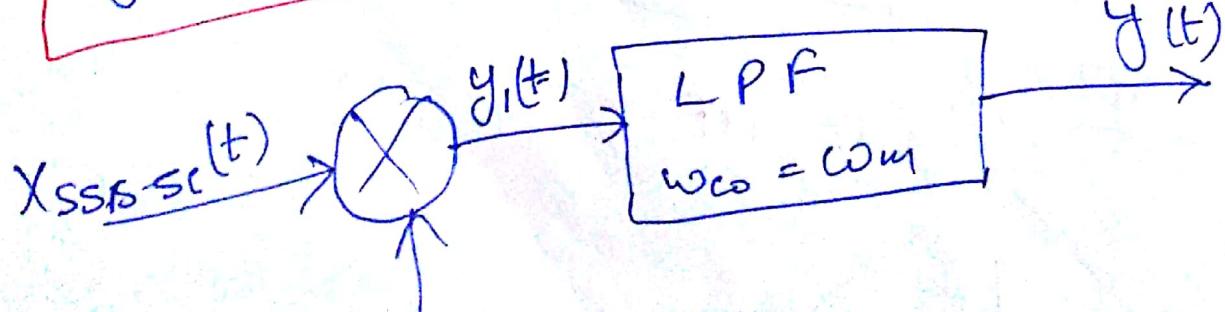
$$y(t) = \frac{A_c}{2} m(t)$$

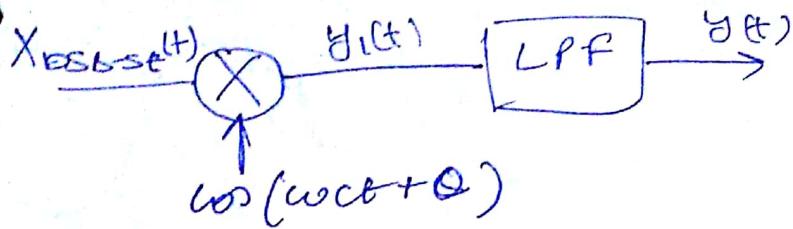
## 3. Detection of SSB-SC wave

$$x_{SSB-SC}(t) = m(t) \cos(\omega_c t) \pm \hat{m}(t) \sin \omega_c t$$

$$\begin{aligned} y_1(t) &= m(t) \cos^2 \omega_c t \pm \hat{m}(t) \sin \omega_c t \cos \omega_c t \\ y_1(t) &= \frac{1}{2} m(t) + \frac{1}{2} m(t) \cos 2\omega_c t \pm \frac{\hat{m}(t)}{2} \sin 2\omega_c t \end{aligned}$$

$y(t) = \frac{1}{2} m(t)$





$$Y_1(t) = A_c m(t) \cos wct \cos(wct + \theta)$$

$$\begin{aligned} Y_1(t) &= A_c m(t) \cos wct \cos(wct + \theta) \\ &= \frac{A_c m(t)}{2} [\cos(2wct + \theta) + \cos \theta] \end{aligned}$$

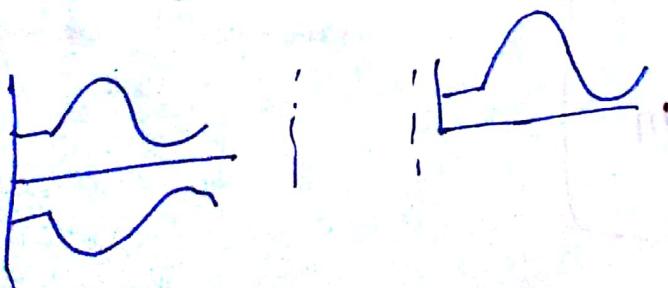
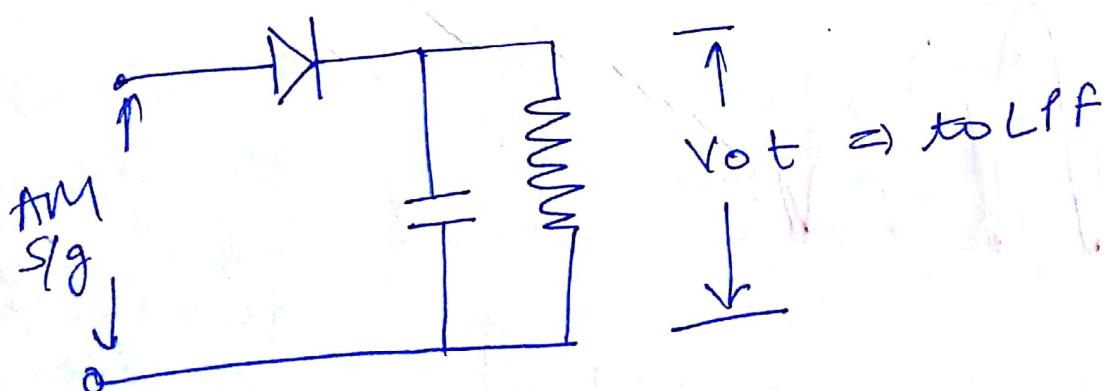
$$Y_2(t) = \frac{A_c m(t) \cos \theta}{2}$$

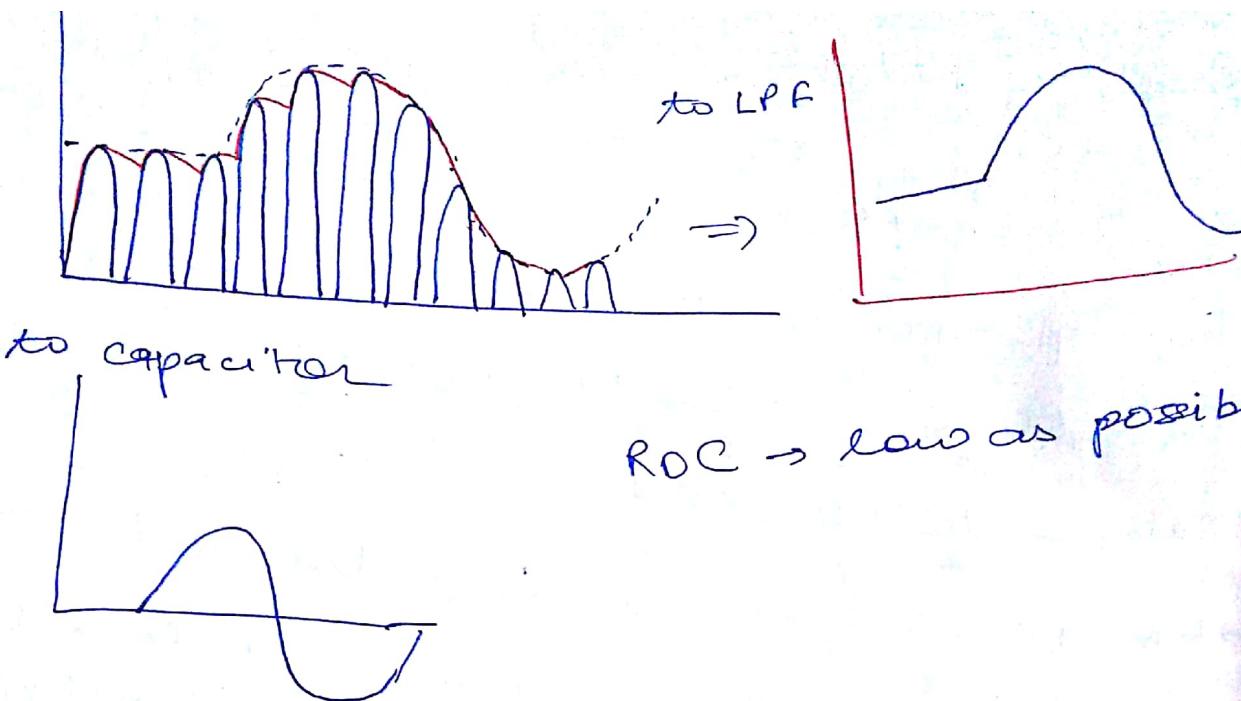
at  $\theta = 90^\circ \Rightarrow Y_2(t) = 0 \Rightarrow \text{Quadrature Null effect}$

→ When the txed carrier phase and locally generated carrier phase are not synchronised, we always obtain a distorted sig at the O/P and when  $\theta = 90^\circ$   $Y_2(t) = 0$ , This effect is known as Quadrature Null effect

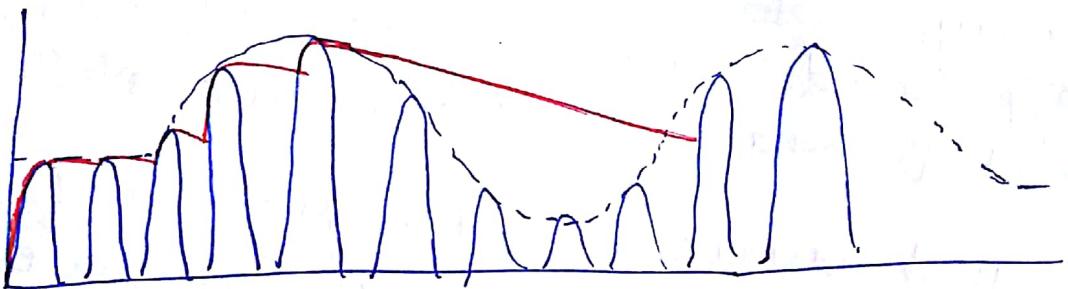
## II Asynchronous Detection Method

This method is also known as Envelope detector or diode detector.

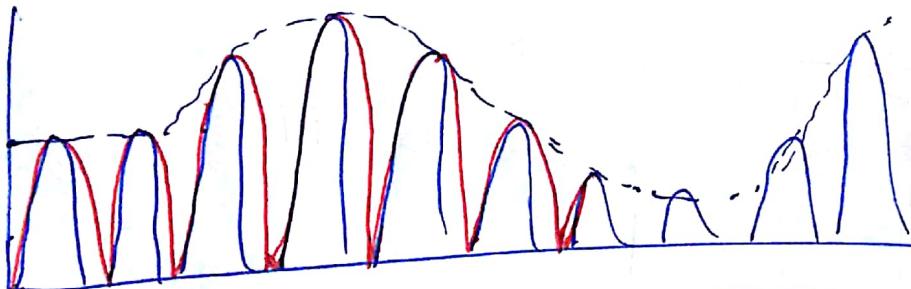




case 1  $\text{RC}$  is very high



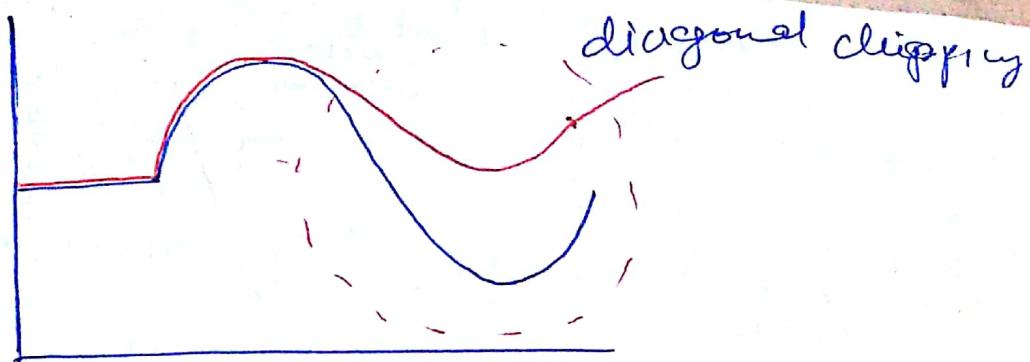
case 2  $\text{RC}$  is very low



$f_c \rightarrow \frac{1}{f_c}$  very low

$f_m \rightarrow \frac{1}{f_m}$  high

$$\checkmark \quad \frac{1}{f_c} \ll \text{RC} \ll \frac{1}{f_m}$$



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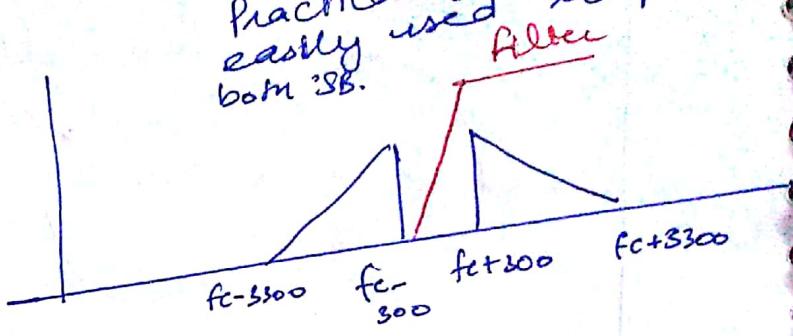
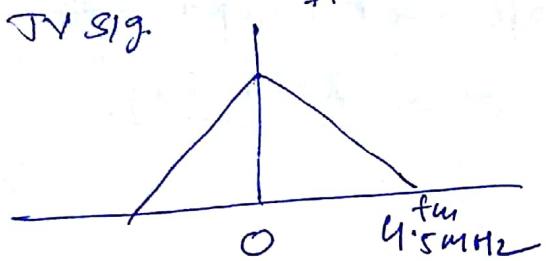
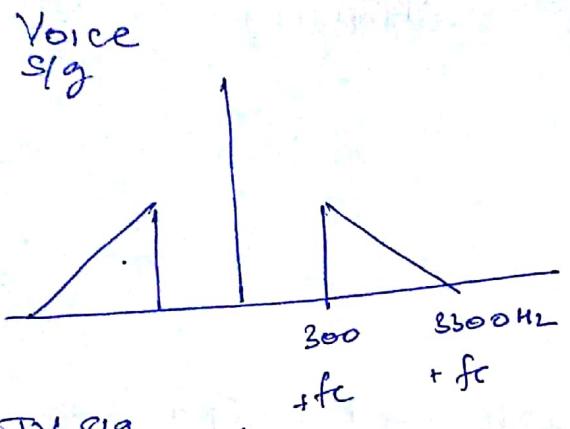
Condition to avoid diagonal clipping

when RC is high

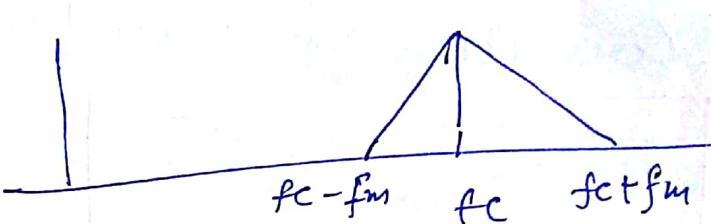
$$RC \leq \frac{1}{\omega_m} \frac{\sqrt{f_m^2 - m^2}}{m}$$

### Vestigial Side Band Modulation

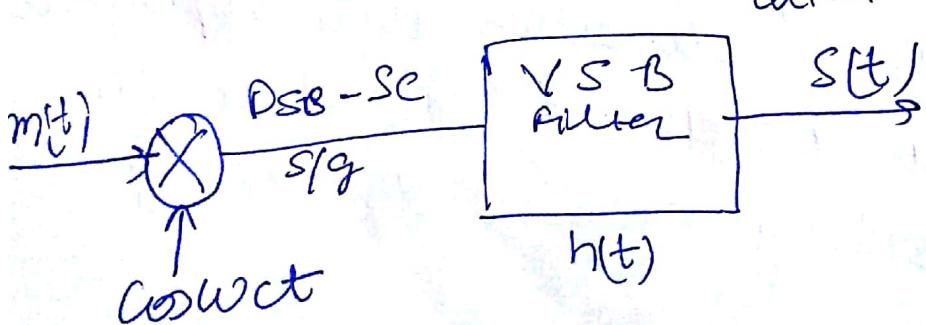
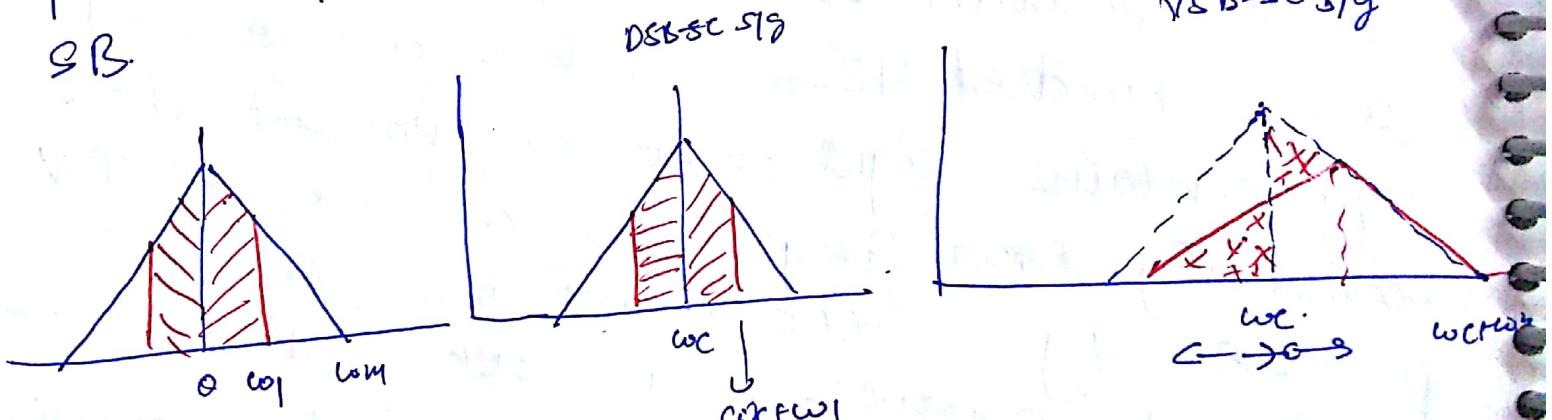
SSB modulation is well suited for transmission of voice because of freq. gap that exist in the spectrum of voice sigs b/w 0 and a few hundred Hz's. When a baseband sig contains significant component at extremely low freq's as in case of TV picture sig's, the lower & upper SB meet at carrier freq. This means that use of SSB modulation is inappropriate for transmission of such baseband sig due to difficulty of isolating one side band.



not easy to separate



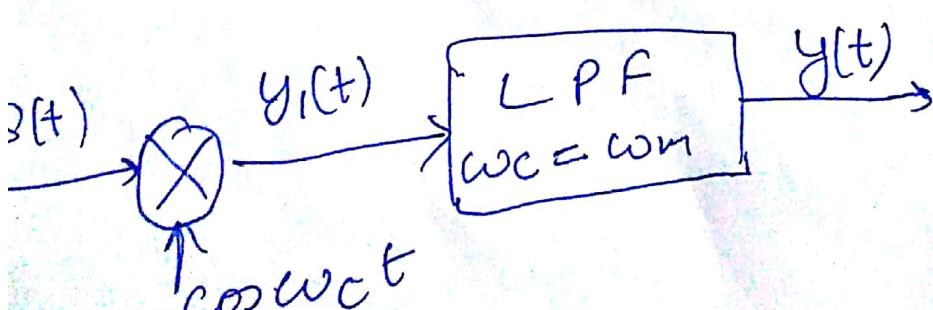
In VSB Modulation, one side band is passed almost completely whereas just a trace or vestige of unwanted SB is retained. Specifically the vestige part of unwanted SB compensates for the part removed from the desired SB.



$$x_{DSB-SC}(t) = m(t) \cos \omega t$$

$$s(t) = m(t) \cos \omega t * h(t)$$

$$s(\omega) = \frac{1}{2} [M(\omega - \omega_c) + M(\omega + \omega_c)] \times h(\omega)$$



$$y(t) = s(t) \cdot \cos \omega t$$

$$y_1(\omega) = \frac{1}{2} [s(\omega - \omega_c) + s(\omega + \omega_c)]$$

$$S(\omega) = \frac{1}{2} [M(\omega - \omega_c) + M(\omega + \omega_c)] \cdot H(\omega)$$

$$Y_1(\omega) = \frac{1}{2} [S(\omega - \omega_c) + S(\omega + \omega_c)]$$

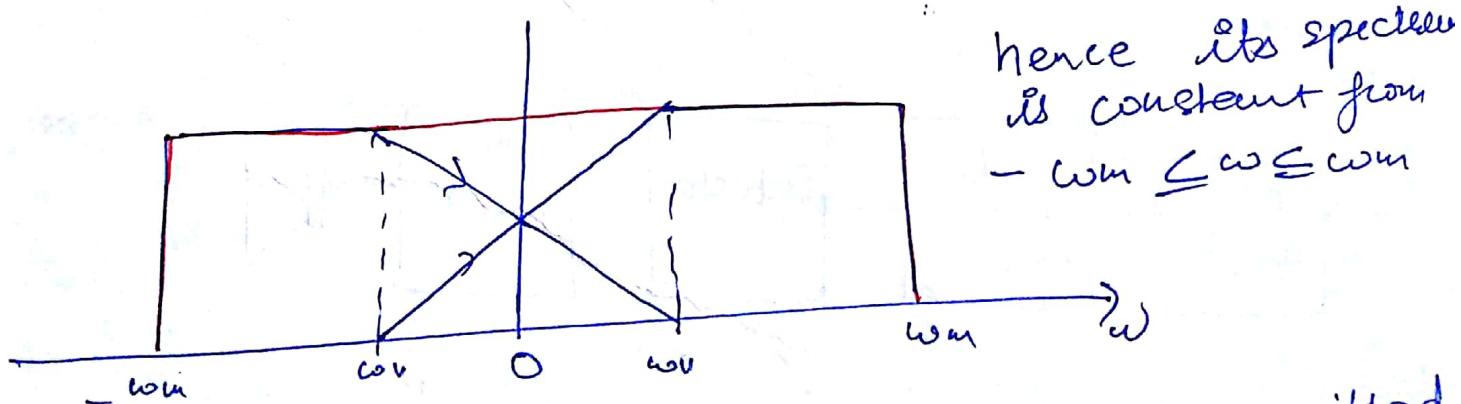
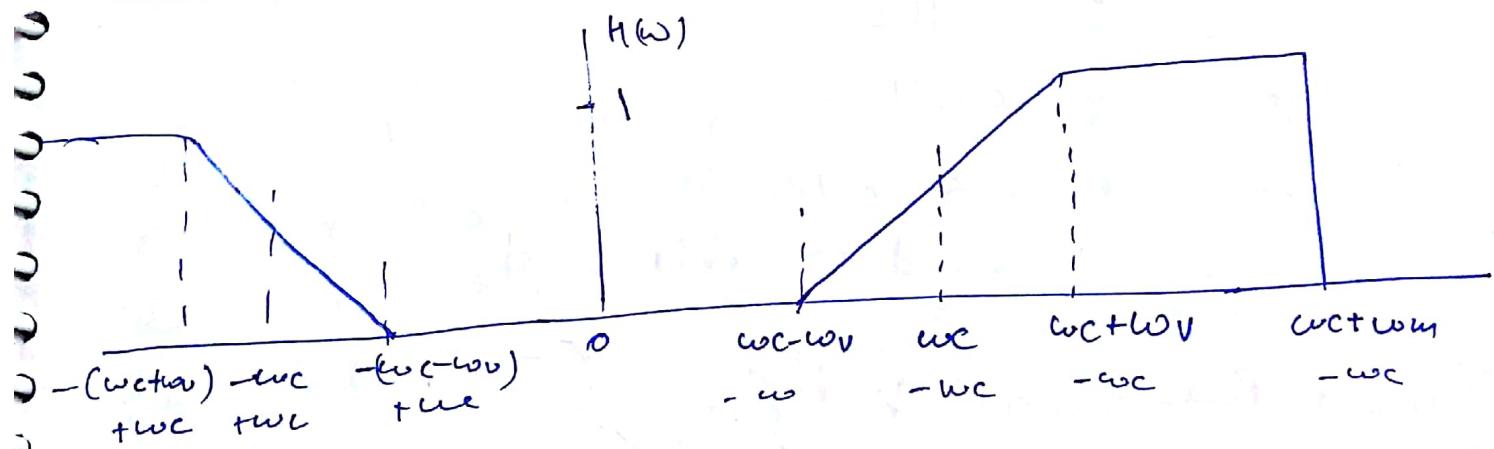
$$Y_1(\omega) = \frac{1}{4} [M(\omega - \omega_c - \omega_c) + M(\omega + \omega_c - \omega_c)] \cdot H(\omega - \omega_c)$$

$$+ \frac{1}{4} [M(\omega + \omega_c + \omega_c) + M(\omega - \omega_c + \omega_c)] \cdot H(\omega + \omega_c)$$

$$Y(\omega) = \frac{1}{4} m(\omega) [H(\omega - \omega_c) + H(\omega + \omega_c)]$$

for  $-\omega_m \leq \omega \leq \omega_m$

$$[H(\omega - \omega_c) + H(\omega + \omega_c)] = \text{constant } ) \quad -\omega_m \leq \omega \leq \omega_m$$



hence its spectrum is constant from  $-\omega_m \leq \omega \leq \omega_m$

in TV transmission, the picture sig is transmitted using VSB modulation.

sound sig is transmitted using FM, and total transmission BW is 6 MHz

$$0.098m^2 = \frac{m^2}{1-m^2}$$

$$1.098m^2 = 1.$$

$$m^2 = 0.95$$

## ANGLE Modulation

In angle Modulation the phase angle of high freq. carrier sig is varied in accordance with instantaneous value of modulating sig keeping amplitude constant.

$$C(t) = A_c \cos \underbrace{\omega_c t}_{\text{angle}}$$

$$\theta(t) = \omega_c t$$

$$\omega = \frac{d\theta}{dt}$$

## Frequency Modulation (FM) $\theta = \int \omega dt$

In FM, the freq of high freq carrier sig is varied in accordance with instantaneous value of modulating sig keeping Amplitude constant, phase is varied indirectly.

## Phase Modulation (PM)

In PM, the phase angle of high freq carrier sig is varied directly in accordance with instantaneous value of modulating sig Keeping Amplitude constant.  
Freq is varied indirectly.

$m(t)$  = Arbitrary modulating sig  
 $\max \text{ freq} = \omega_m$

$$c(t) = A_c \cos \omega_c t$$

$$c(t) = A_c \cos \Omega_c(t)$$

$$\Omega_c(t) = \omega t$$

FM

$$x_{fm}(t) = A_c \cos \Omega_i(t)$$

$$\omega_i = \omega_c + K_f m(t)$$

$$\Omega_i(t) = \int_0^t \omega_i dt$$

$$\Omega_i(t) = \left[ \omega_c + K_f \int_0^t m(t) dt \right]$$

$$\Omega_i(t) = \omega_c t + K_f \int_0^t m(t) dt$$

$$x_{fm}(t) = A_c \cos \left[ \omega_c t + K_f \int_0^t m(t) dt \right]$$

PM

$$x_{pm}(t) = A_c \cos \Omega_i(t)$$

$$\Omega_i(t) = \Omega_c(t) + K_p m(t)$$

$$x_{pm}(t) = A_c \cos(\Omega_c(t) + K_p m(t))$$

$$= A_c \cos(\omega_c t + K_p m(t))$$

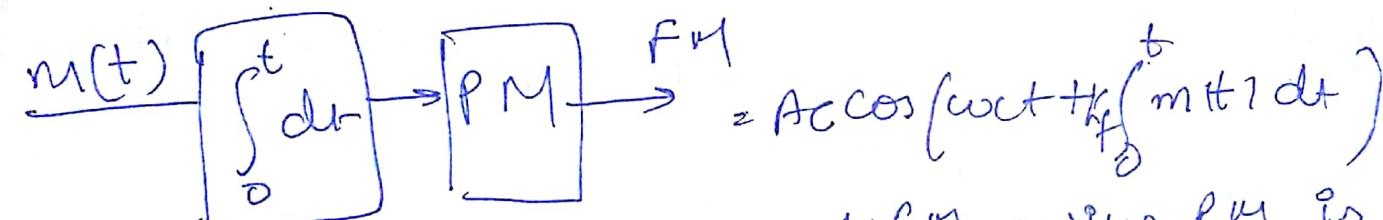
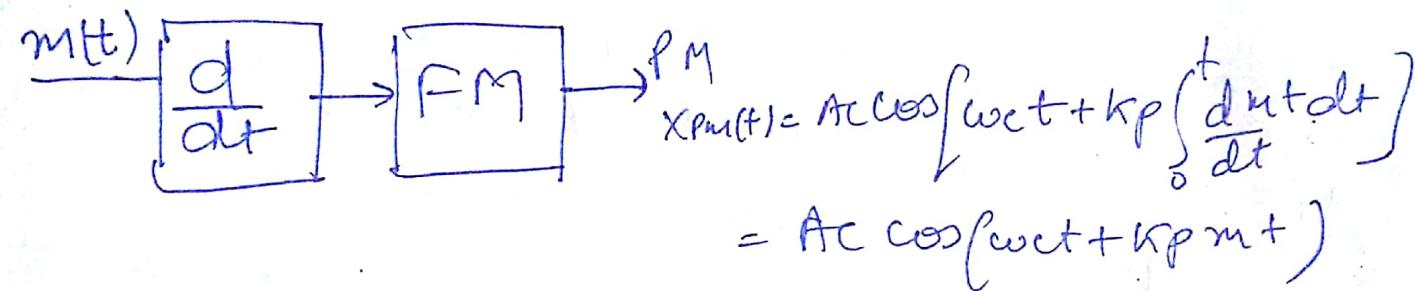
$$x_{pm}(t) = A_c \cos \left[ \omega_c t + K_f \int_0^t m(t) dt \right]$$

$$x_{pm}(t) = A_c \cos \left[ \omega_c t + K_p m(t) \right]$$

# Relation b/w FM & PM signal

$$X_{FM}(t) = Ac \cos [wct + K_f \int_0^t m(t) dt]$$

$$X_{PM}(t) = Ac \cos [wct + K_p m(t)]$$



this method of generation of FM using PM is used, worldwide.

## Sinusoidal FM

$$m(t) = Am \cos \omega_m t$$

$$c(t) = Ac \cos \omega_c t$$

$$\Omega(t) = \omega_c t$$

$$X_{FM}(t) = Ac \cos \Omega(t)$$

$$\omega_i = \omega_c + K_f A_m \cos \omega_m t$$

$$\text{peak freq deviation } \Delta \omega = K_f A_m$$

$$\omega_i = \omega_c + \Delta \omega \cos \omega_m t$$

$$\Omega_i(t) = \int_0^t \omega_i dt$$

$$\Omega_i(t) = \int_0^t (\omega_c + \Delta \omega \cos \omega_m t) dt$$

... constant

## PM

$$m(t) = Am \cos \omega_m t$$

$$\Omega(t) = \omega_c t$$

$$X_{PM}(t) = Ac \cos \Omega(t)$$

$$\Omega_i(t) = \Omega(t) + K_p A_m \cos \omega_m t$$

$$\text{Peak freq deviation } (\beta_{PM}) = K_p A_m$$

$$\Omega_i(t) = \omega_c t + \beta_{PM} \cos \omega_m t$$

$$X_{PM}(t) = Ac \cos(\omega_c t + \beta_{PM} \cos \omega_m t)$$

$$\boxed{\text{Modulation index } (\beta_{FM}) = \frac{\Delta\omega}{\omega_m} = \frac{\Delta f}{f_m}}$$

$$Q_i(t) = \omega_c t + \beta_{FM} \sin \omega_m t$$

$$\boxed{X_{FM}(t) = A_c \cos(\omega_c t + \beta_{FM} \sin \omega_m t)}$$

$$\boxed{X_{PM}(t) = A_c \cos(\omega_c t + \beta_{PM} \cos \omega_m t)}$$

Difference b/w FM & PM S/g

$$Q_i(t) \Big|_{FM} = \omega_c t + \frac{\Delta\omega}{\omega_m} \sin \omega_m t$$

$$\omega_i = \frac{d Q_i(t)}{dt} = \omega_c + \Delta\omega \cos \omega_m t$$

$$\boxed{\frac{\Delta\omega}{\omega_m} = K_f A_m}$$

$$Q_i(t) \Big|_{PM} = \omega_c t + K_p A_m \cos \omega_m t$$

$$\omega_i \Big|_{PM} = \omega_c - K_p A_m \omega_m \sin \omega_m t$$

$$\boxed{\frac{\Delta\omega}{\omega_m} = K_p A_m \omega_m}$$

$$\Delta\omega = K_p A_m \omega_m$$

$$\boxed{\frac{\Delta\omega}{\omega_m} = \beta_{PM} = K_p A_m}$$

$$10) S(t) = \cos[2\pi(2 \times 10^6 t + 30 \sin 150t + 40 \cos 150t)]$$

$$\Omega^2 = 2\pi(2 \times 10^6 t + 30 \sin 150t + 40 \cos 150t)$$

$$= 2\pi(2 \times 10^6 t + \sqrt{2^2 + 5^2} \cos(150t + \theta))$$

$$= 2\pi(2 \times 10^6 t + 50 \cos(150t + \theta))$$

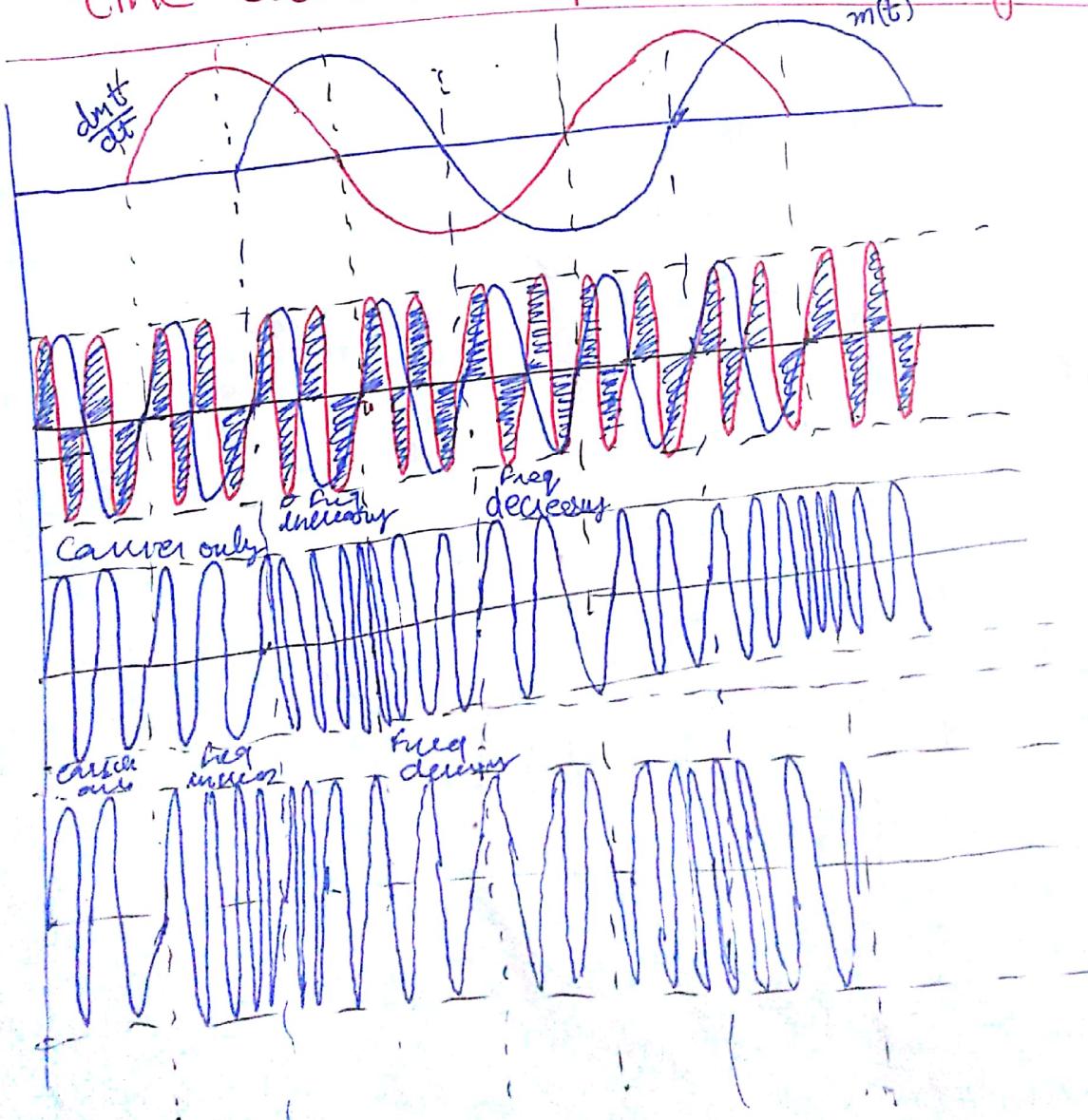
Peak phase deviation =  $100\pi$

$$\omega_1^2 = 4\pi \times 10^6 + 2\pi \times 50 \times 150 \sin(150t + \theta)$$

$$\Delta f = -\frac{\Delta \omega}{2\pi} = \frac{2\pi \times 50 \times 150}{2\pi} = 7500$$

$$= 7.5 \text{ kHz}$$

time domain Representation of AM & PM



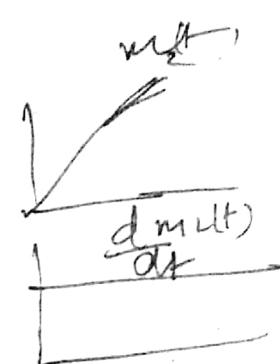
if  $m(t)$  is step sig  
 $f_1$  +  $\sim$

$$\omega_i = \omega_0 + K_f m(t)$$

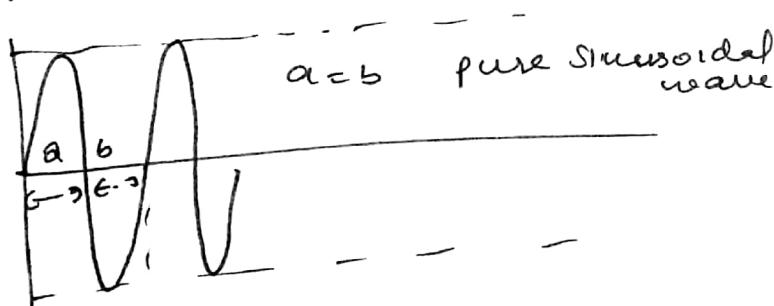
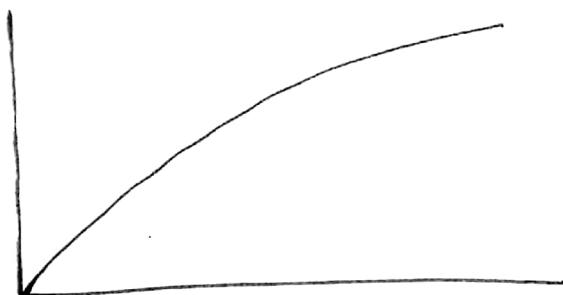
$$\omega_i = \omega_0 + K_f$$



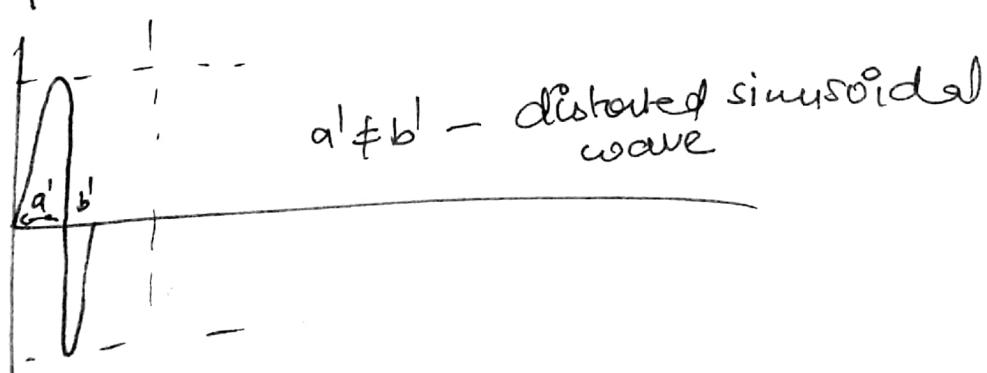
freq. modulation



phase modul.



$$a > a'$$



## TYPES OF FREQ. MODULATION

→ depending upon the value of  $\beta$ , there are two types of freq. modulation

$$X_{fm}(t) = A_c \cos(\omega_c t + \beta \sin \omega_m t)$$

$$X_{fm}(t) = A_c \left[ \cos \omega_c t \cos(\beta \sin \omega_m t) - \right. \\ \left. \sin \omega_c t \sin(\beta \sin \omega_m t) \right]$$

### ① Narrow band FM

→ when  $\beta$  is very very small

$$\cos \theta = 1 \quad \theta \rightarrow 0 \quad \sin \theta = 0 \quad \theta \rightarrow 0$$

$$\cos(\beta \sin \omega_m t) \approx 1 \quad \beta \rightarrow 0$$

$$\sin(\beta \sin \omega_m t) \approx \beta \sin \omega_m t \quad \beta \rightarrow 0$$

$$X_{NBFM}(t) = A_c \cos \omega_c t + A_c \beta \sin \omega_m t \sin \omega_c t$$

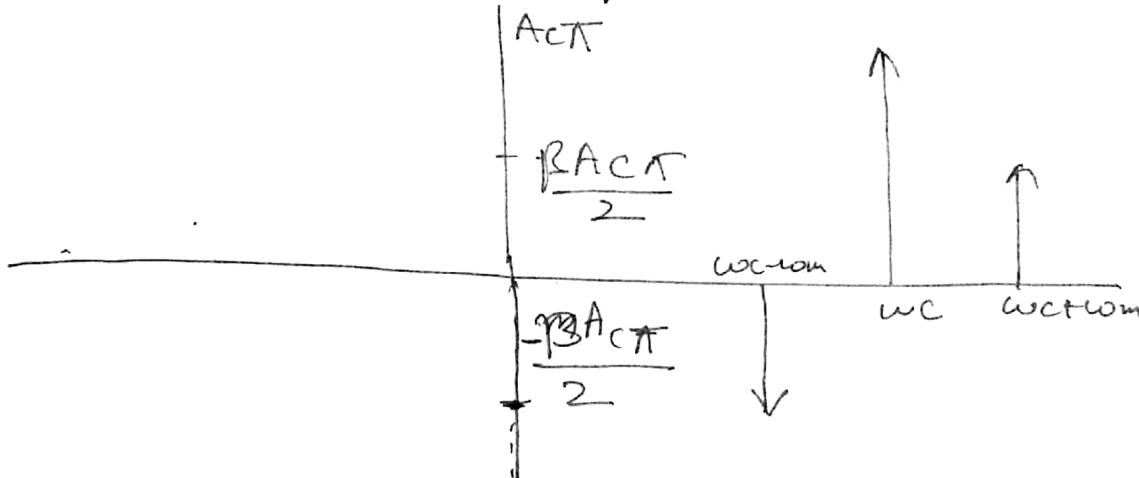
$$= A_c \cos \omega_c t - \frac{A_c \beta}{2} \cos(\omega_c - \omega_m)t + \frac{A_c \beta}{2} \cos(\omega_c + \omega_m)t$$

$$X_{AM}(t) = A_c \cos \omega_c t + \frac{m A_c}{2} \cos(\omega_c - \omega_m)t + \frac{m A_c}{2} \cos(\omega_c + \omega_m)t$$

⇒ the NBFM is similar to AM except that in AM, all the three components i.e., carrier, VSB & LSB are in phase but in NBFM, the LSB is  $180^\circ$  out of phase wrt carrier & VSB

# freq. domain representation

55



$$B = 2\omega_m$$

~~Please~~ in NBFM, transmission BW does not effected

## ② Wide band FM

Since change in freq causes the time required to complete one half of a cycle to differ from the time required to complete the next half cycle, the actual wave is a distorted sinusoidal oscillations. The higher mathematical analysis using Bessel's function shows that the distorted oscillations corresponding to a wave with sinusoidal freq modulation is made up of infinite no. of freq components spaced by modulating freq.

here  $\cos(\beta \sin \omega_m t) \leftrightarrow \cos \omega_m t$  &  $\sin(\beta \sin \omega_m t) \leftrightarrow \sin \omega_m t$  are periodic s/g's with fundamental freq  $\omega_m$ .

Thus the Fourier transform of each of these sig is an impulse train with impulses at integer multiple of  $\omega_m$  and amplitude  $\propto$  to Bessel's function of 1st kind

WBPM

$$\cos(\beta \sin \omega_m t) = J_0(\beta) + 2 J_2 \cos 2\omega_m t + 2 J_4 \cos 4\omega_m t + \dots$$

$$\sin(\beta \sin \omega_m t) = 2 J_1(\beta) \sin \omega_m t + 2 J_3(\beta) \sin 3\omega_m t + \cancel{2 J_5(\beta) \sin 5\omega_m t} + \dots$$

$$\cos \omega_c t \cos(\beta \sin \omega_m t) = J_0(\beta) \cos \omega_c t + 2 J_2(\beta) \frac{\cos \omega_c t}{\cos 2\omega_m t}$$

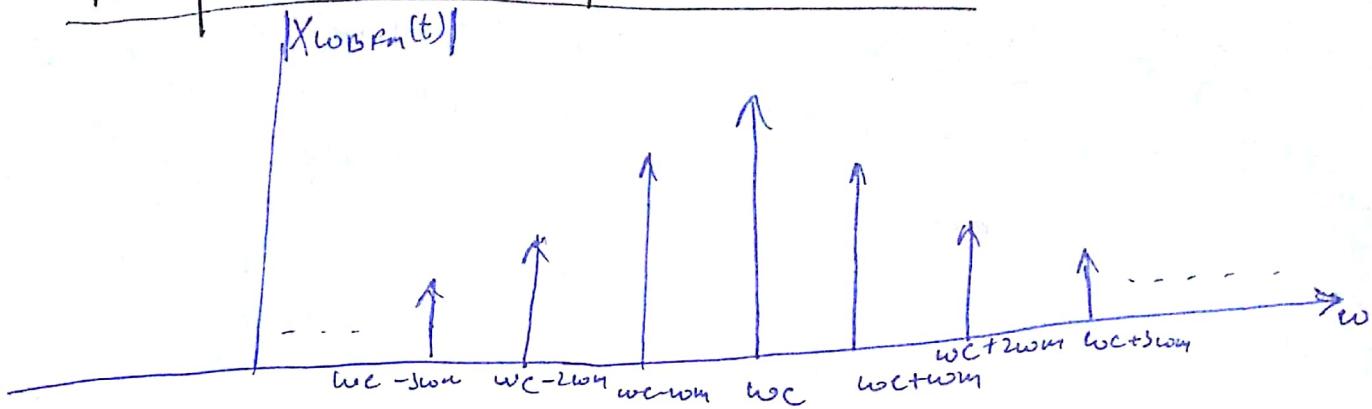
$$+ 2 J_4(\beta) \cos \omega_c t \cdot \cos 4\omega_m t + \dots$$

$$\sin \omega_c t \sin(\beta \sin \omega_m t) = 2 J_1(\beta) \sin \omega_c t \sin \omega_m t + \\ 2 J_3(\beta) \sin \omega_c t \sin 3\omega_m t + 2 J_5(\beta) \sin \omega_c t \sin 5\omega_m t + \dots$$

$$X_{WBPM}(t) = \begin{cases} J_0(\beta) \cos \omega_c t + J_1(\beta) [\cos(\omega_c + \omega_m)t - \cos(\omega_c - \omega_m)t] & \\ + J_2 \beta [\cos(\omega_c + 2\omega_m)t + \cos(\omega_c - 2\omega_m)t] & \\ + J_3 \beta [\cos(\omega_c + 3\omega_m)t - \cos(\omega_c - 3\omega_m)t] & \end{cases}$$

$$+ J_4 \beta [\cos(\omega_c + 4\omega_m)t - \cos(\omega_c - 4\omega_m)t] + \dots$$

## Freq. domain Representation



① the spectrum of WBFM sig contains infinite no. of side band component centre around carrier freq.  $w_c [f_c]$  and the spacing b/w each spectral component is maximum modulating sig freq  $w_m [f_m]$

② the bessel's function  $A_c J_n(\beta)$   
 $\downarrow$  modulation index  
 $\uparrow n^{\text{th}} \text{ pair of SB.}$

③ since the spectrum of WBFM sig contains infinite SB's so the actual transmission BW required for the transmission of WBFM is infinite. But as we move away from the carrier freq, the significant amplitude of Sidebands go on decreasing & decreasing so if higher SB's components are neglected, it does not effect the quality of transmission. So the approximate BW for transmission in WBFM and WBFM sig's are given by Carson's rule

$$\checkmark \quad \text{BW} = 2(\Delta\omega + \omega_m) \text{ rad/sec}$$

$$= 2(\Delta f + f_m) \text{ Hz}$$

$$= 2(\beta + 1)f_m$$

$$(BW)_{FM} = (BW)_{PM} = 2(75+5) = 160 \text{ kHz}$$

$$f_m = 15 \text{ kHz}$$

$$\Delta f = 75 \text{ kHz}$$

$$(BW)_{FM} = 2(75+15) \\ = 180 \text{ kHz}$$

PM

$$\Delta f = 75 \times 3 = 225$$

$$(BW)_{PM} = 2(225+5) \\ = 480 \text{ kHz}$$

$$\Delta f = K_f A_m f_m - fm$$

$$\frac{\Delta f}{fm} = K_f A_m = 15$$

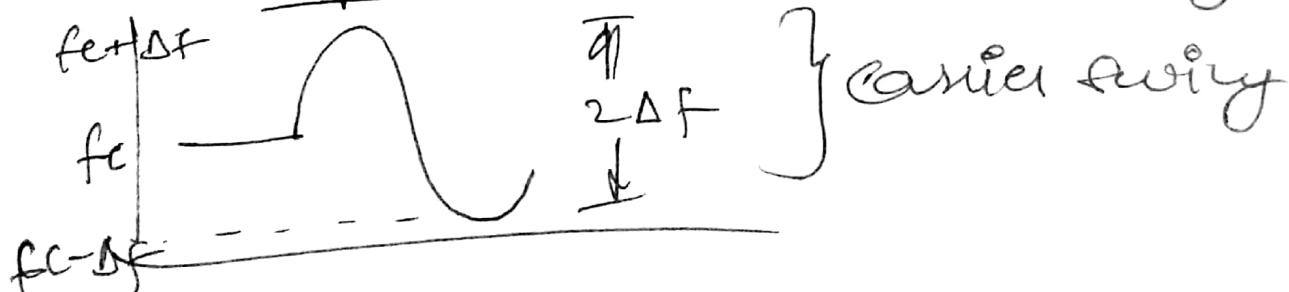
$$\Delta f' = K_f A_m f_m = 10 \times 15 = \underline{225}$$

### Approximated BW

~~BW~~  $BW = 2(\Delta f + f_m)$

$$\Delta f > f_m$$

$$BW \approx 2\Delta f \rightarrow \text{Carrier Swinging}$$



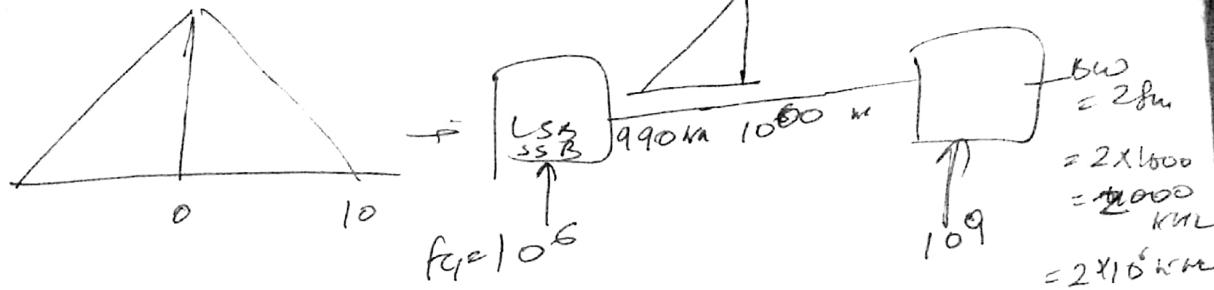
### % Modulation

$$\% \text{ modulation} = \frac{\Delta f_{\text{actual}}}{\Delta f_{\text{max}}} \times 100\%$$

$$\Delta f_{\text{actual}} = 25 \text{ kHz}$$

$$\% \text{ mod.} = \frac{25}{75} \times 100\% = 33.33\%$$

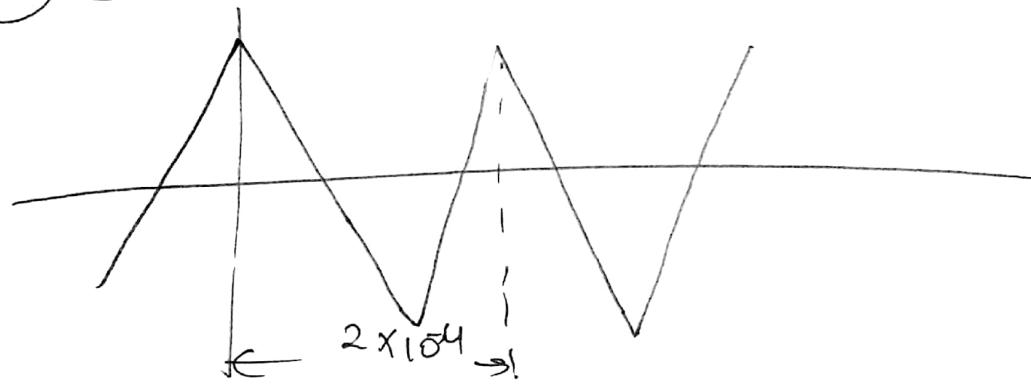
(16)



$$\frac{\Delta f'}{\Delta f''} = \frac{K_F A_m}{K_F A_m} = \frac{1}{1}$$

$$\begin{aligned} b_w &= 2d_m \\ &= 2 \times 600 \\ &= 1200 \text{ km} \\ &= 2 \times 10^6 \text{ m} \end{aligned}$$

(22) (23) (24)



$$f_0 = \frac{1}{T_0} = \frac{10^4}{2} \text{ c } 5 \text{ kHz}$$

$$3f_0 = \underline{15 \text{ kHz}}$$

$$X_{\text{full}}(t) = A_c \cos \left( \omega_c t + K_f \int_0^t m(t) dt \right)$$

$$\Omega(t) = \omega_c t + K_f \int_0^t m(t) dt$$

$$\omega(t) = \omega_c + K_f m(t)$$

$$\Delta \omega = K_f m(t) / \omega_c$$

$$\Delta \omega \leq 2\pi \times 10^5$$

$$\begin{aligned} \Delta f &= 100 \text{ km} \\ \Delta \omega &= 2(100 + 15) \\ &= 230 \text{ km} \end{aligned}$$

$$x_{pm}(t) = A \cos(\omega_c t + \omega_p m t)$$

$$\Theta_1(t) = \omega_c t + \omega_p m t$$

~~$\Delta\omega = \omega_p \Delta m \times 10^6$~~

~~$= 5\pi \times 10^6 \times 10^6$~~

~~$= 2\pi \times 10^{12}$~~

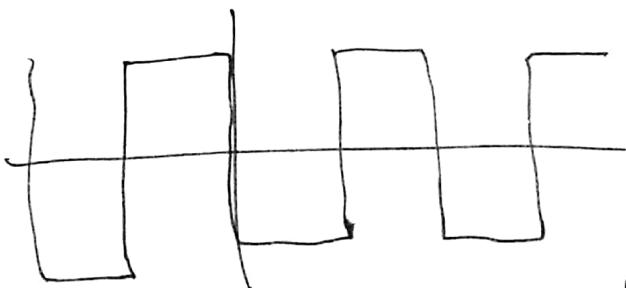
~~$\Delta f = \frac{150 \text{ MHz}}{2\pi} = 7.5 \text{ GHz}$~~

~~$2(\Delta f + \Delta m) = 2(7.5 \text{ GHz})$~~

$$\omega(t) = \frac{d\Theta_1}{dt} = \omega_c + \omega_p \frac{dm}{dt}$$

$$\Delta\omega = \omega_p \frac{dm}{dt} \Big|_{\max}$$

$$\frac{dm}{dt}$$



$$\text{slope of } \omega(t) = -\frac{2}{10^{-4}} = -2 \times 10^4$$

$$\text{slope} = 2 \times 10^4$$

$$= 5\pi \times 2 \times 10^4$$

$$\Delta\omega = 10\pi \times 10^4$$

$$\Delta f = 50 \text{ kHz}$$

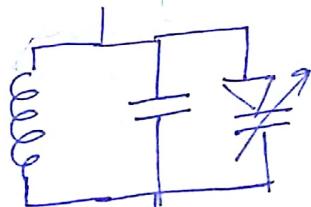
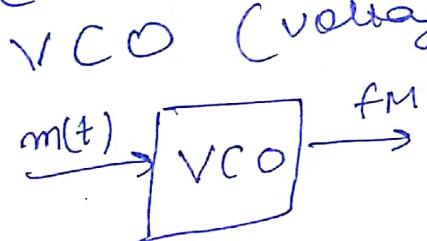
$$\beta_{BW} = 2(80 + 15) = 130 \text{ kHz}$$

## Generation of FM waves

there are two methods for generation of FM waves

### ① Direct Method

The basic concept of FM is to vary the carrier freq in accordance with the modulating sig. The carrier is generated by an LC oscillator. In an LC oscillator the carrier freq is fixed by components of tank ckt. The carrier freq can be varied by varying either L or C of tank ckt. The oscillator whose freq is varied in accordance with voltage (modulating sig in case of FM) is known as (modulating controlled oscillator)



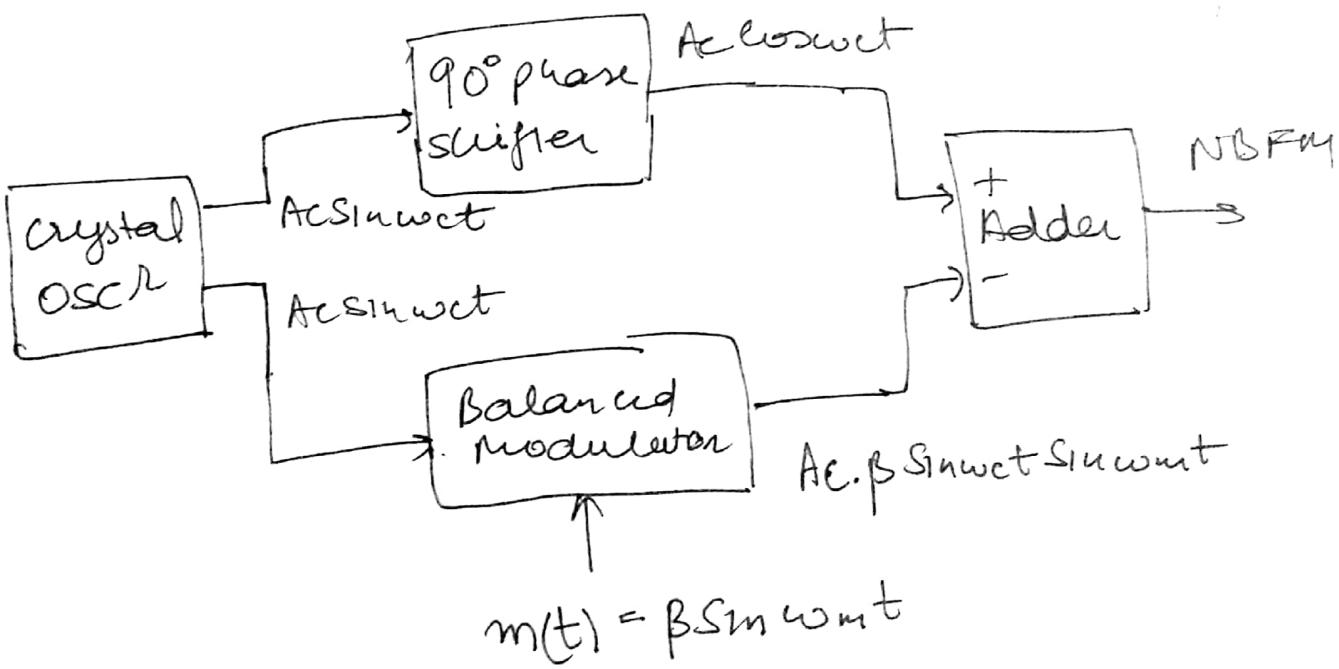
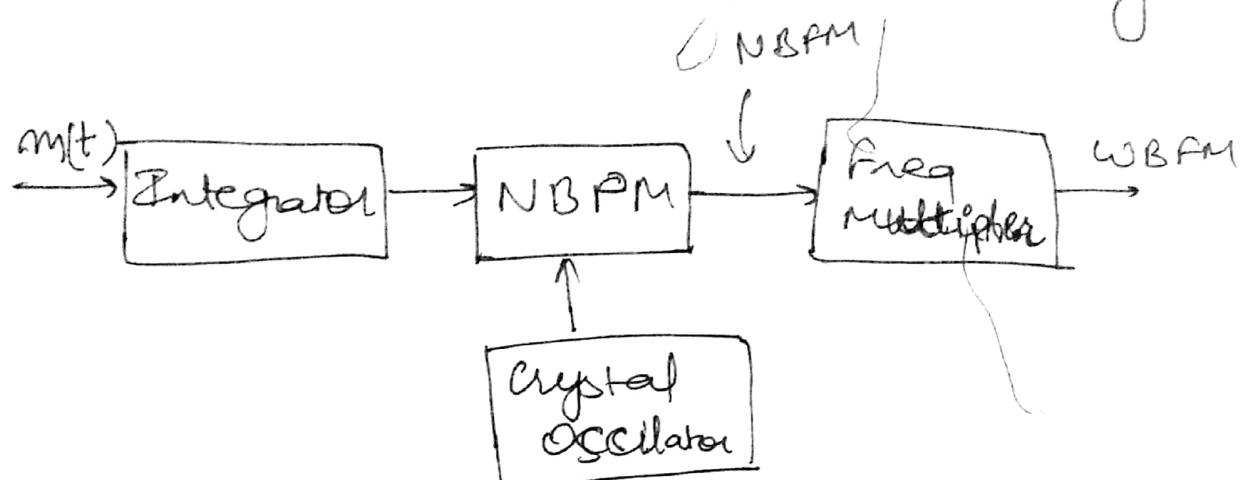
$$f_c = \frac{1}{2\pi\sqrt{LC}}$$

### Disadvantage of Direct method

- ① Most LC oscillators are not stable enough to provide a carrier sig. The carrier freq usually vary due to temperature variation, humidity, aging of component etc.
- So instead of using LC oscillators, a crystal oscillator must be used.
- But since they provide highly stable carrier freq so. only a very small freq deviation is possible.

what is why, indirect method of PM generation is used.

## ② Indirect method (Armstrong Method)



$$X_{NBFM}(t) = A_c \cos \omega_c t - A_c \beta \sin \omega_c t \sin \omega_m t$$

frequency multiply

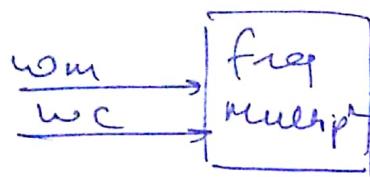
$$y(t) = x^h(t)$$

$$\text{here } y(t) = x^h(t)$$

$$x_{FM}(t) = A_c \cos(\omega_c t + \beta \sin \omega_m t)$$

$$y(t) = A_c^2 \left( \frac{1}{2} + \cos(\omega_c t + 2\beta \sin \omega_m t) \right)$$

$$\left. \begin{array}{l} w_c \rightarrow 2w_c \\ w_m \rightarrow w_m \\ \beta \rightarrow 2\beta \\ \Delta \omega \rightarrow 2\Delta \omega \end{array} \right\}$$

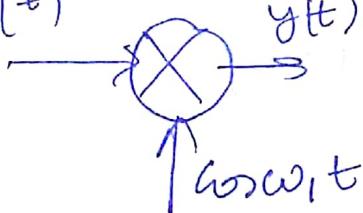


generalised.

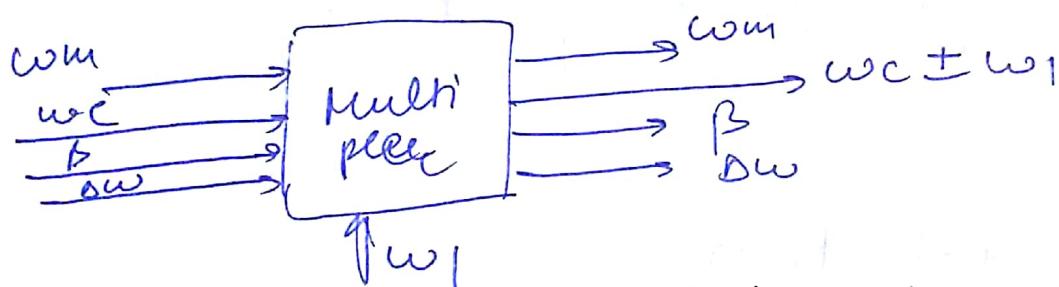
$$\left. \begin{array}{l} y(t) = s \cdot h(t) \\ w_c \rightarrow n w_c \\ w_m \rightarrow c w_m \\ \beta \rightarrow n \beta \\ \Delta \omega \rightarrow n \Delta \omega \end{array} \right.$$

in PBS, there is no change in  $w_m$

$$x_{pm}(t) \quad y(t) = A e \cos(w_c t + \beta \sin \omega_m t) \cos \omega_1 t$$



$$\frac{Ae}{2} \left[ \cos((w_c + \omega_1)t + \beta \sin \omega_m t) + \cos((w_c - \omega_1)t + \beta \sin \omega_m t) \right]$$



only carrier freq is translated by  $w_1$

Q. 21       $\phi(t) = 10 \cos(w_c t + 5 \sin 3000 t + 10 \sin 2000 \pi t)$

$$\phi_i(t) = w_c t + 5 \sin 3000 t + 10 \sin 2000 \pi t$$

$$w_i(t) = w_c + 15000 \cos 3000 t + 20000 \pi \cos 2000 \pi t$$

$$\Delta \omega_{max} = 15000 + 20000 \pi$$

$$\beta = \frac{\Delta \omega}{w_m}$$

$$\text{Deviation ratio } D = \frac{\Delta \omega}{w_m(\text{max})}$$

when there are more than

one modulating signal then

we calculate  $D = \frac{15000 + 20000 \pi}{2000 \pi}$

$$D = \frac{15000 + 20000 \pi}{2000 \pi} = 10 + \frac{40000 \pi^2}{2000 \pi} = 10 + 10^{10}$$

# Detection of FM wave

frequency

$f_c + \Delta f$

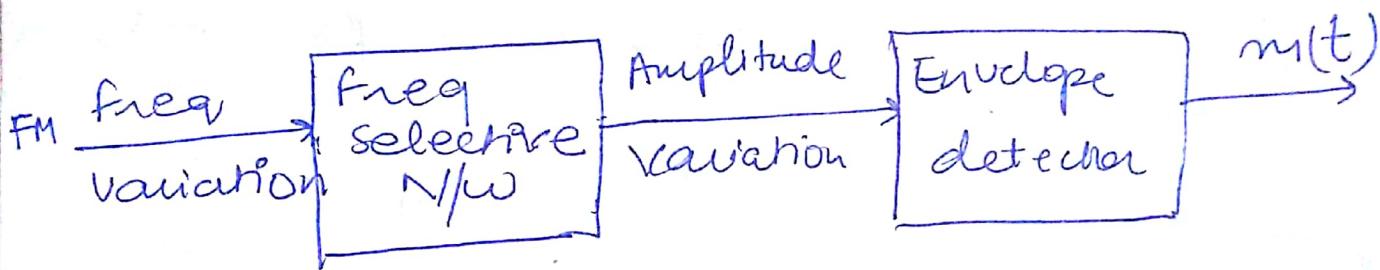
$f_c$

$f_c - \Delta f$

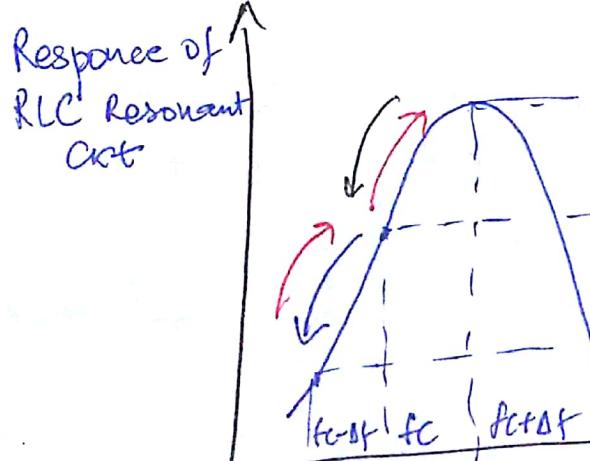
$A_m$

$-A_m$

Voltage



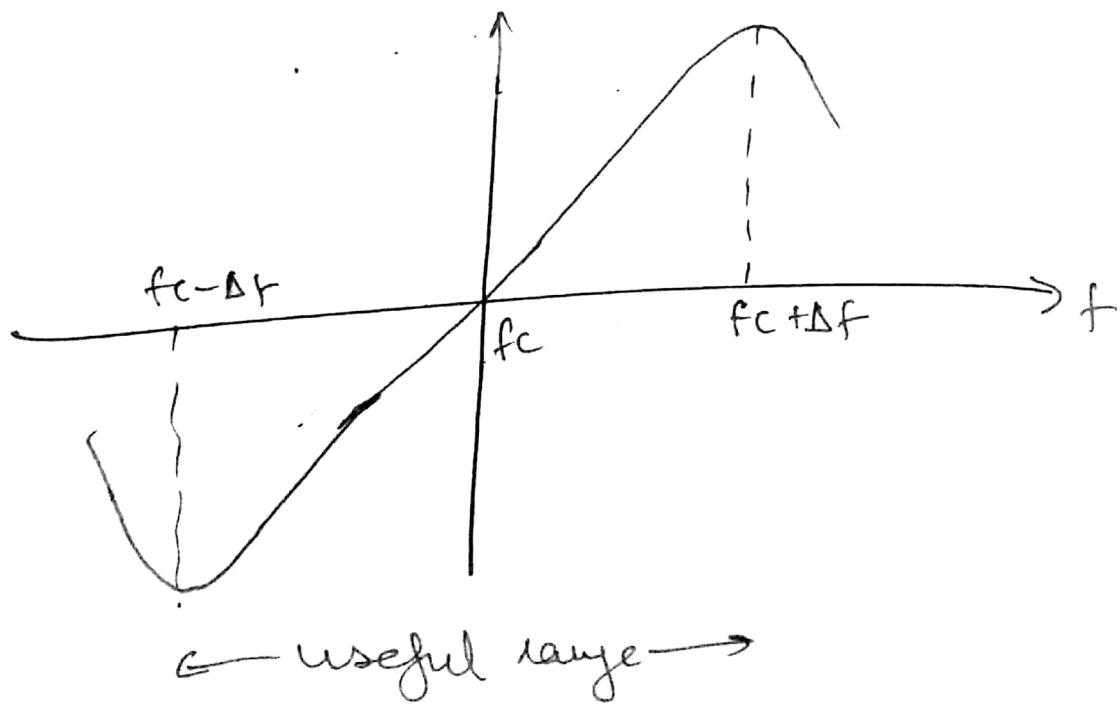
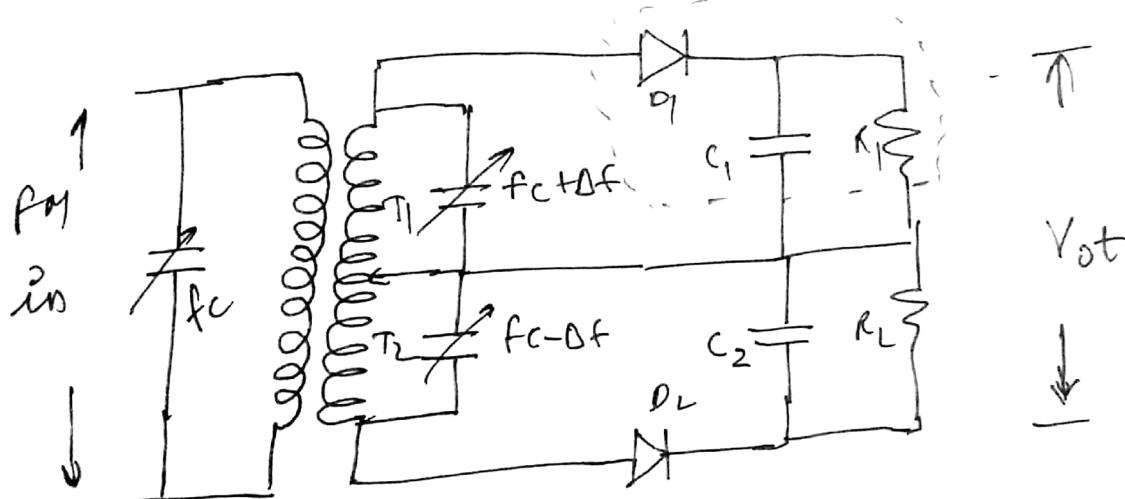
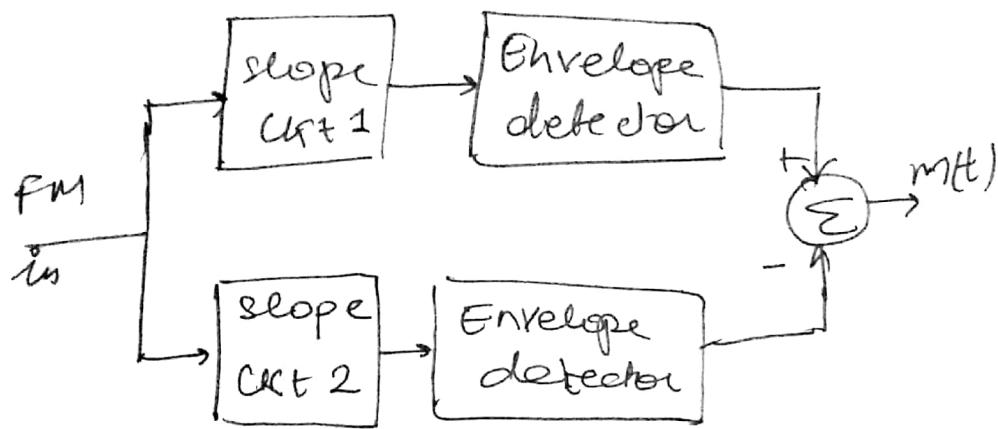
## ① Shape detection



freq variation in PM

## ② Balanced slope detector

55

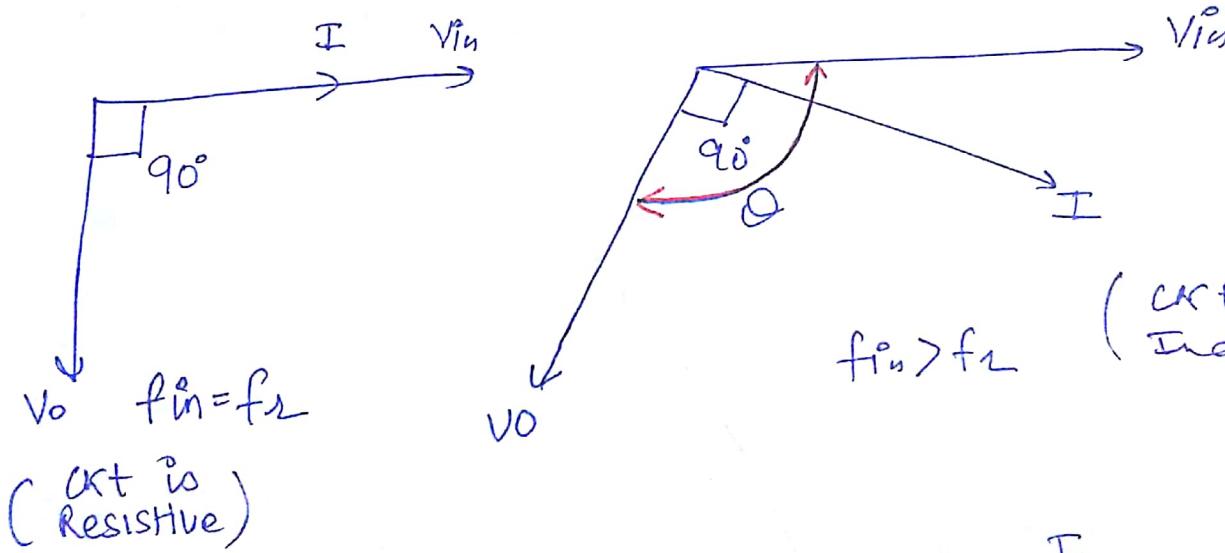
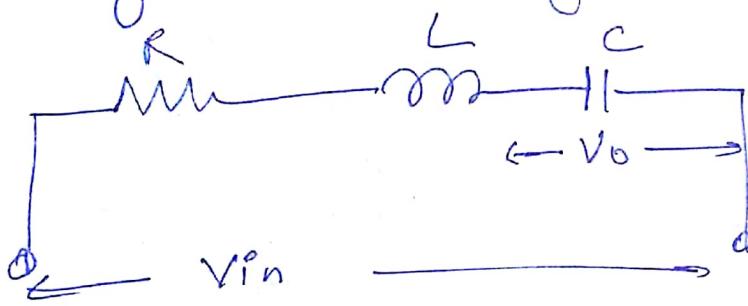


- Balanced slope detector is also known as triple tuned CKT as 3 tuned ckt are used. The O/P is tuned as carrier freq  $f_c$ ,  $t_1$  at  $f_c + \Delta f$  and  $t_2$  at  $f_c - \Delta f$
- When  $f_{in} = f_c$ , the gain provided by  $t_1$  &  $t_2$  will be same so the O/P of both tuned CKT will be same but in phase opposition. So the net O/P is 0.
- When  $f_{in}$  is closer to  $f_c + \Delta f$ , the O/P of  $t_1$  will be positive large as compared to -ve voltage of  $t_2$  so the net O/P voltage will be in +ve direction.
- When  $f_{in}$  is closer to  $f_c - \Delta f$ , the O/P of  $t_2$  will be more positive as compared to  $t_1$  and net O/P will be in the -ve direction  
 $t_2$  will provide more gain

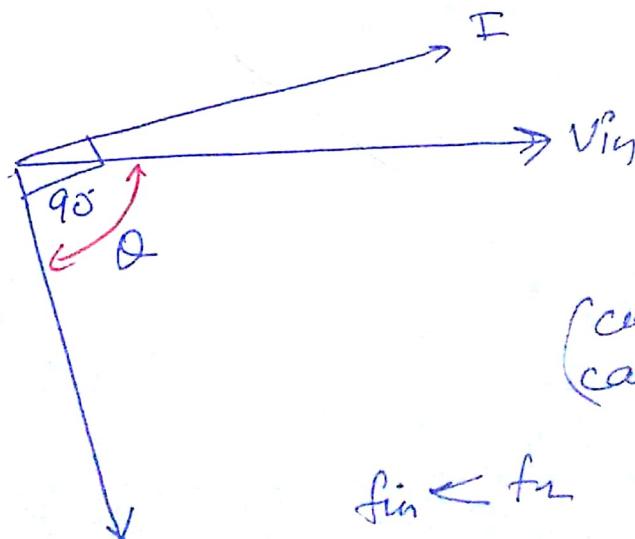
## FOSTER Seeley discriminator

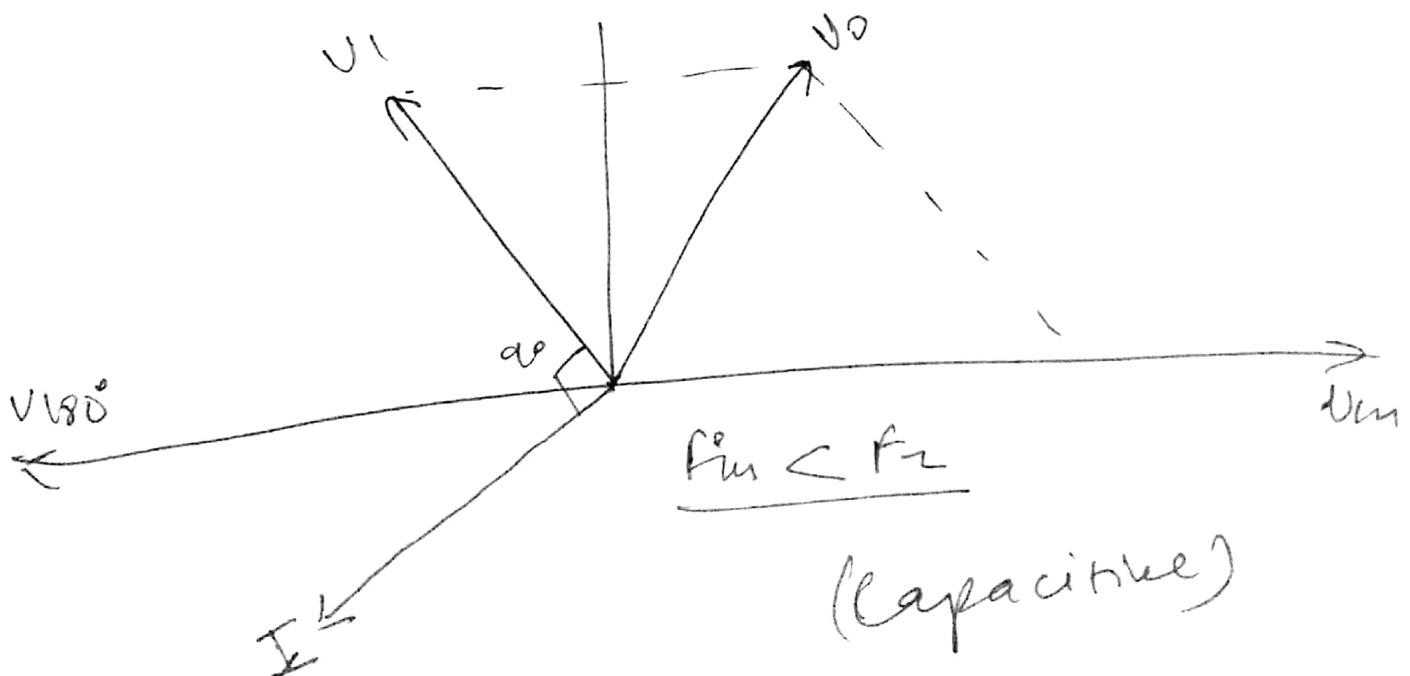
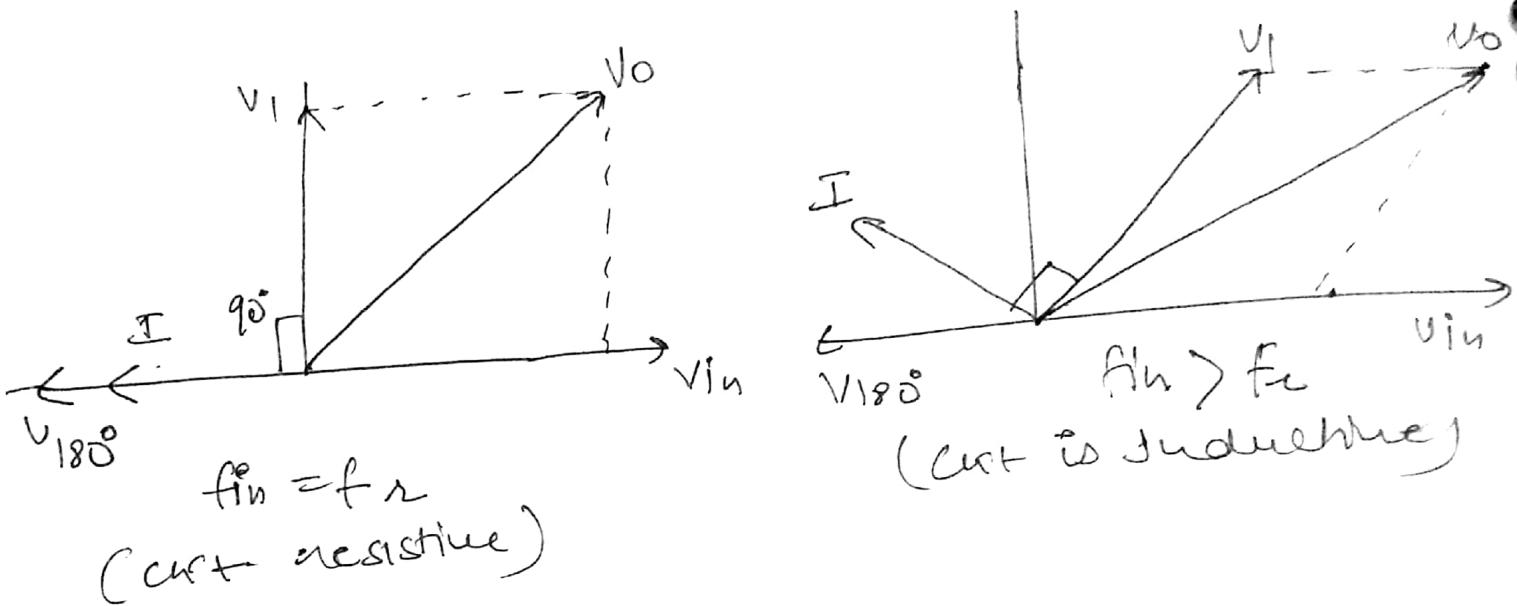
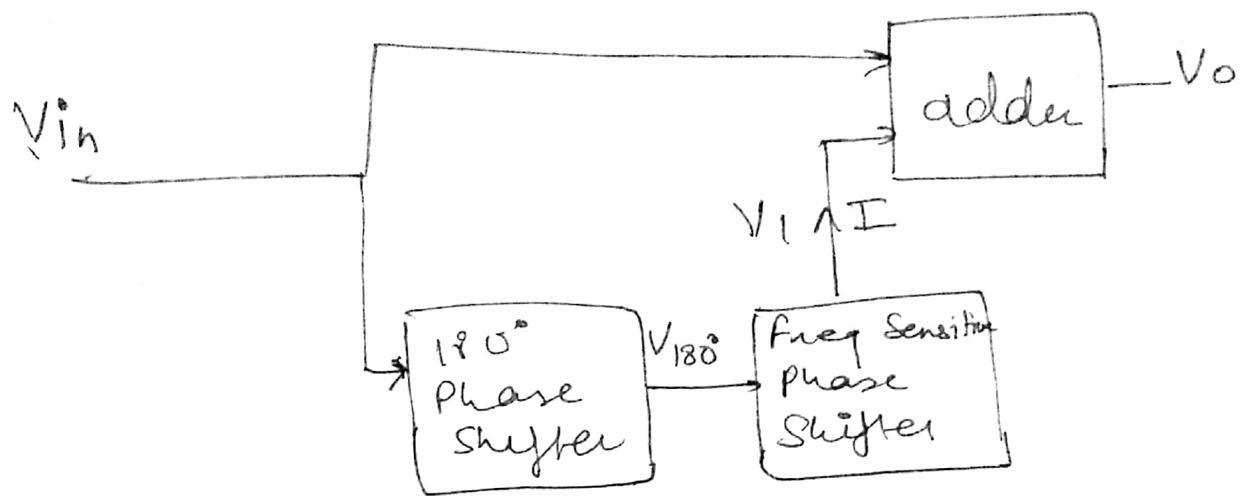
(Phase shift discriminator)

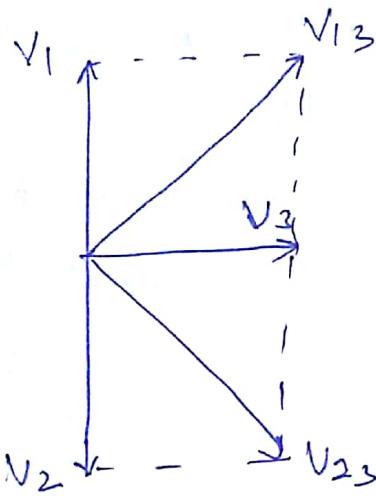
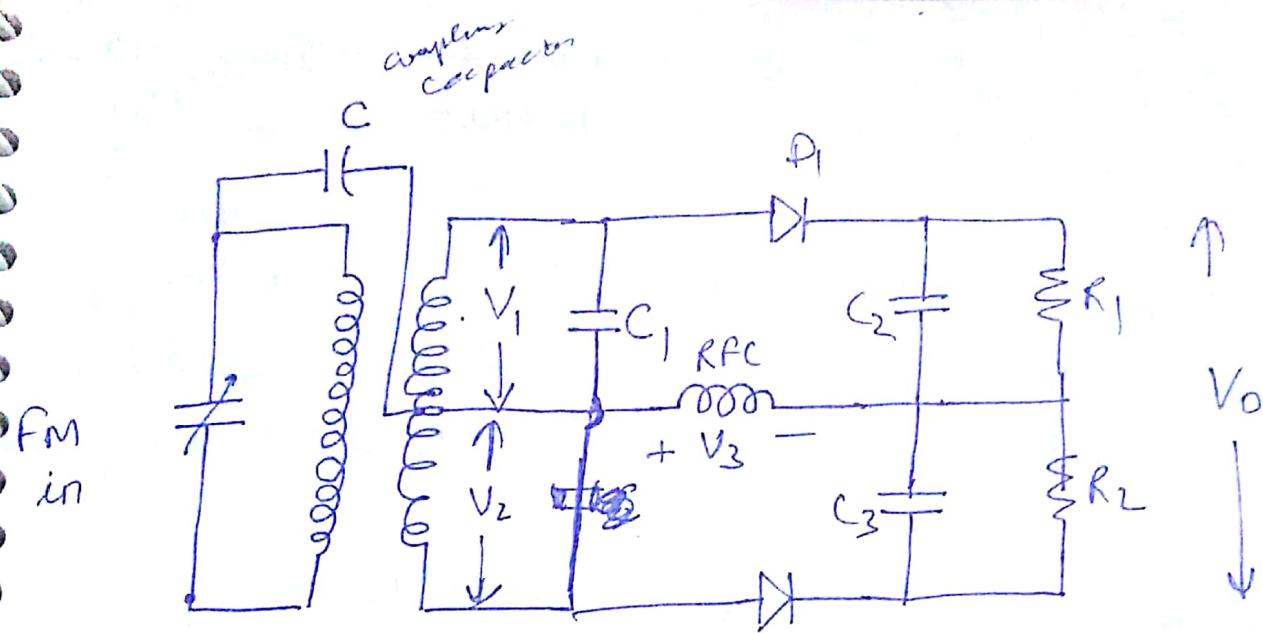
→ This method make use of freq. sensitive nature of ~~B~~ Series RLC resonant Ckt and provides a freq. dependent phase shifting of the modulated sig. When the phase shifted sig is added to the portion of original sig, the resultant sig will have a magnitude varying with freq.



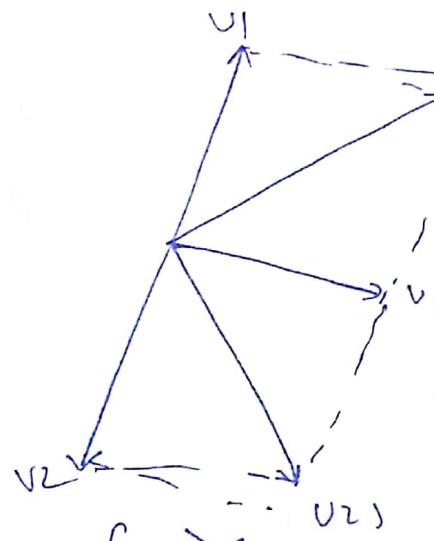
$f_{in} > f_r$       (Ckt is Inductive)



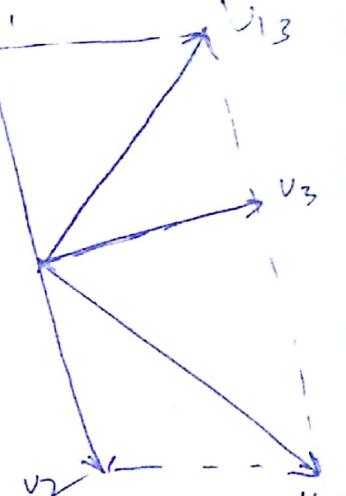




$f_{in} = f_c$   
(resistive)



$f_{in} > f_c$   
(inductive)



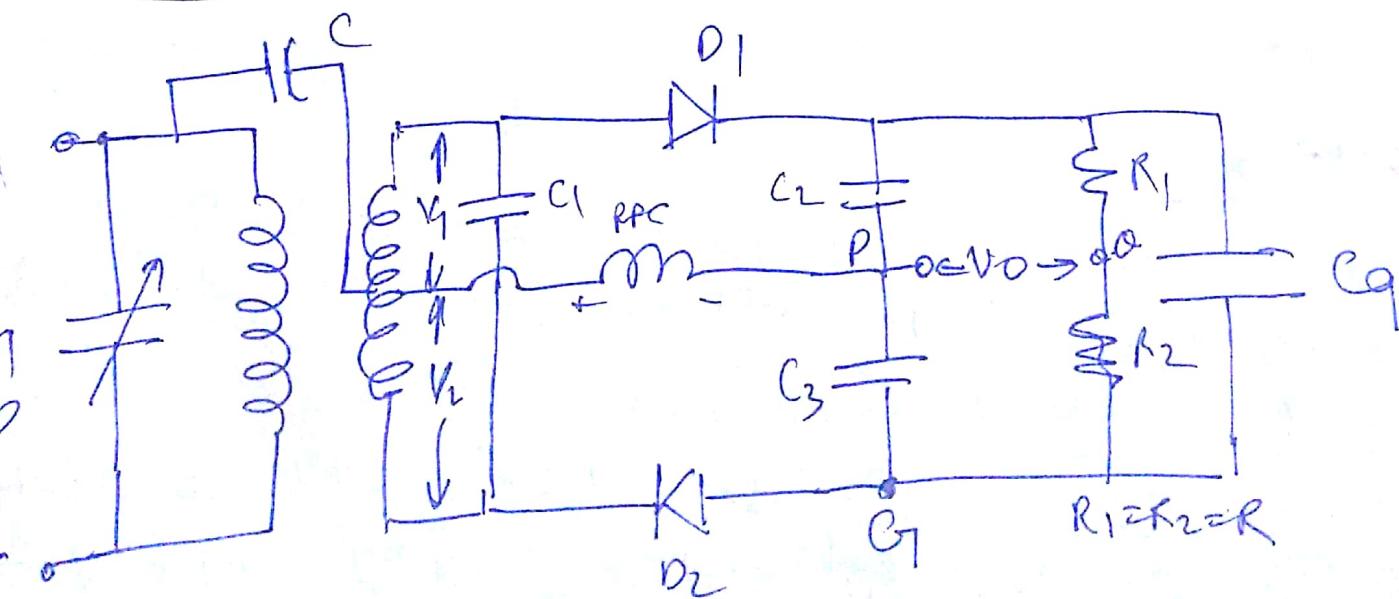
$f_{in} < f_c$   
(capacitive)

### Working

- ① → the coupling capacitor  $C$  is used to couple the input voltage to the secondary of centre tap transformer
- ② → capacitor  $C_1$  is so chosen that voltage  $V_3$  is exactly  $90^\circ$  out of phase w.r.t to voltage  $V_1$  &  $V_2$  at  $f_{in} = f_c$
- ③ → with the help of centre tap arrangement voltage  $V_1$  &  $V_2$  are always  $180^\circ$  out of phase

- (4) the resonant freq of phase shifting n/w is adjusted to carrier frequency of FM sig. when the freq of i/p sig increases and becomes more than carrier freq  $f_c$ , the resultant of  $V_1$  &  $V_3$  becomes greater than resultant of  $V_2$  &  $V_3$ . and Net o/p is in +ve direction.
- (5) when  $f_{in} < f_c$ , the resultant of  $V_2$  &  $V_3$  becomes greater than resultant of  $V_1$  &  $V_3$  and net o/p voltage is in -ve direction.
6. when  $f_{in} = f_c$ , both the resultants become same but in phase opposition the net o/p voltage is zero.

### Ratio detector



The Ratio detector differ from the Foster Seeley discriminator in 3 ways 69

- ① direction of  $D_2$  has been Reversed
- ② Method of taking o/p voltage  $V_{out}$
- ③ A large value capacitance  $C_9$  has been included

$C_9$  the capacitor  $C_9$  provides Amplitude limiting, when  $V_{in}$  is const. &  $C_9$  is charged upto max. value then there is no current to charge or discharge  $C_9$ . If any short duration noise effects the i/p sig then it will not cause any harm to the detected s/g as the capacitor  $C_9$  will take large time to charge upto this voltage. Generally RC time constant is kept at a value 0.2 sec.

### Working of EKT

lrb  $V_{C_9} = 10V$ . since  $R_1 = R_2 = R$  so  $V_{og}$  is always maintained at 5V.

① When  $f_{in} = f_c$ , the resultant of  $V_1$  &  $V_2$  is same as resultant of  $V_2$  &  $V_3$  so two diodes conducts equally well and  $V_{C_2} = V_{C_3} = 5V$  and Net o/p voltage is 0.

② When  $f_{in} > f_c$ , Resultant of  $V_1 \oplus V_3$

becomes greater than resultant of  $V_2$  &  $V_3$   
 so diode  $D_1$  conducts more heavily  
 as compared to  $D_2$  and  $\underline{V_{C2} > V_{C3}}$   
 So. net o/p is in +ve direction

③ when  $f_m < f_c$ , Diode  $D_2$  conducts  
 more heavily as compared to  $D_1$   
 and  $\underline{V_{C3} > V_{C2}}$  and Net o/p voltage  
 is in -ve direction. Depending upon  
 the i/p freq, the ratio of capacitor  
 Voltage  $C_2$  &  $C_3$  changes. This  
 ratio change is detected by the O/T  
 hence the name ratio detector.

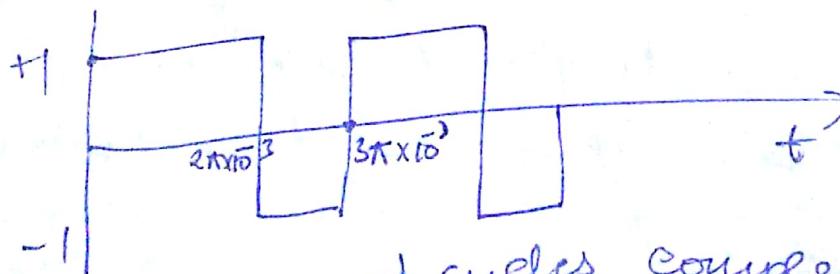
Q Consider a sig  $x(t)$  given by  $\cos(50t + \sin 5t)$   
 calculate its instantaneous freq.  $\text{rad/sec}$   
 at  $t=0$

$$\theta = 50t + \sin 5t$$

$$\omega_i = 50 + 5 \cos 5t$$

$$\omega_i|_{t=0} = 50 + 5 \quad \text{(55)}$$

Q a modulating sig  $m(t)$  is shown below



$$\begin{aligned} \text{assume the constant} \\ K_f = 1000 \text{ rad/sec/V} \\ \omega_c = 3000 \text{ rad/sec} \end{aligned}$$

④ the no. of cycles completed by resultant  
 fm wave (when mt is +1) are equal to

$$f_m = \frac{1}{3\pi \times 10^3} = \frac{10^3}{3\pi}$$

$$\omega_m = \frac{2}{3} \times 10^3$$

~~soff wct + k f m t~~)

$$\cos(\omega_c t + \omega_f m t)$$

~~$$\omega_i = 3000t + 1000mt$$~~  
~~$$\omega_i = 3000 + 1000 \frac{\text{dwt}}{\text{dt}}$$~~

$$\begin{aligned}\omega_i &= \omega_c + \omega_f m t \\ &= 3000 + 1000(1) \\ &= 4000\end{aligned}$$

$$T_f = \frac{2\pi}{4000} \text{ sec} \quad 1 \text{ cycle}$$

$$1 \text{ sec} \longrightarrow \frac{4000}{2\pi}$$

$$2\pi \times 10^{-3} \longrightarrow \frac{4000 \times 2\pi \times 10^{-3}}{2\pi} = 4 \text{ cycles}$$

$$\begin{aligned}\omega_i &= 3000 - 1000 \\ \omega_{eff} &= 2000\end{aligned}$$

$$T_i = \frac{2\pi}{2000}$$

$$\pi \times 10^{-3} = \frac{\pi \times 10^{-3} \times 2000}{2 \times \pi} = 1 \text{ cycles}$$

The following waveform is received

$$x(t) = 5 \cos[2\pi \times 10^5 t + 200 \sin(2\pi \times 500t)]$$

If sig represents an FM wave

then modulating sig m(t) is given by

assume kf = 10<sup>5</sup> Hz/V

$$\beta = \frac{\Delta f}{f_m} = \frac{k_f A_m}{f_m} = 200$$

$$\frac{A_m \times 10^5}{500} = 200$$

$$A_m = \frac{200 \times 500}{10^5} = 1$$

$$m(t) = 500 \sin(2\pi \times 500t)$$

$$(wct + k_f \int_{0}^{t} m(t) dt)$$

$$\underline{k_f \int_{0}^{t} m(t) dt} = 200 \sin(2\pi \times 500t)$$

Q a ~~fm~~ sig is given by  $\cos(wct + \phi(t))$

The FM sig is generated using the Armstrong method. The modulating sig m(t) = 3 cos(2π × 3000)t if the

final carrier freq is 100 MHz  
and max phase deviation is 10 rad.

calculate the integer value n by which  
carrier freq fc is multiplied assume  
 $k_f = 20\pi \text{ rad/sec/volt}$

$$\omega_i^o = \omega_c + K_f m t$$

$$\omega_i^o = \omega_c + K_f \times 3 \cos(2\pi \times 3000) t$$

$$\phi_i^o = \omega_c t + \phi_i(t)$$

$$\omega_i^o = \omega_c + \frac{d \phi_i(t)}{dt}$$

$$K_f \times 3 \cos(2\pi 3000 t) = \frac{d \phi_i}{dt}$$

$$\frac{3 K_f \sin(2\pi 3000 t)}{2\pi 3000} = \phi_i +$$

$$\frac{3 \times 20 \pi n}{2\pi \times 3000} \quad t_{\text{req}} = 10$$

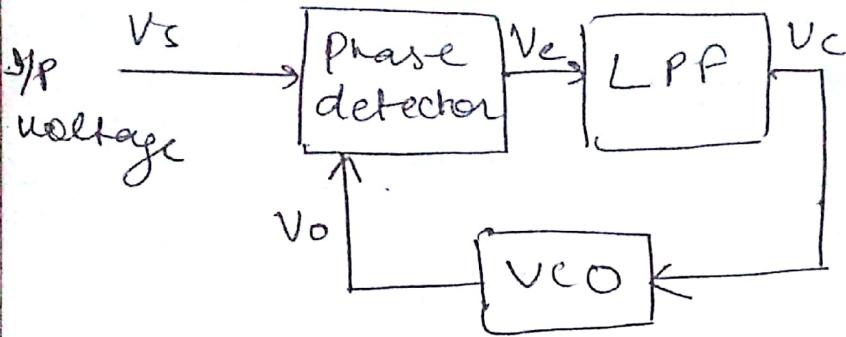
$$\frac{1}{100} \sin(2\pi 3000 t) = \phi_i t$$

$$n = 1000$$

$$\phi_i(t)_{\text{max}} = \frac{1}{100}$$

$$N = \frac{10}{\frac{1}{100}} = 1000$$

# PLL (Phase locked loop)



Phase locked loop is essentially a feed-back system that consists of three essential components

- ① Phase detector
- ② LPF
- ③ VCO (Voltage control oscillator)

If an ip sig  $V_s$  of freq  $f_s$  is applied to the PLL, the phase detector compares the phase and freq of incoming sig to that of op  $V_o$  of VCO. If the two sig differ in freq &/or phase, an error voltage is generated, the phase detector is basically a multiplier and produces the sum & difference components at its op. The high freq component is removed by the LPF and the difference freq component is amplified and then applied as control voltage  $V_c$  to VCO.

$$V_s(t) = A \cos \omega_s t$$

$$V_o(t) = B \cos(\omega_o t + \phi)$$

$$V_E(t) = V_s(t) V_o(t) = AB \cos \omega_s t \cos(\omega_o t + \phi)$$

$$= \frac{AB}{2} [\cos((\omega_s + \omega_o)t + \phi) - \cos((\omega_s - \omega_o)t - \phi)]$$

then LPF block  $(\omega_s + \omega_o)t$

$$V_c(t) = \cos[(\omega_s - \omega_o)t - \phi]$$

at  $\omega_s = \omega_o$  or  $\omega_s - \omega_o = 0 \Rightarrow$  at synchronization

$$V_c(t) = \cos(-\phi) = \cos \phi$$

at  $\phi = 90^\circ$

$V_c(t) = 0$  at exact synchronization  
at this condition exact locking occurs

→ The sig  $V_c$  shifts the VCO freq. in a direction to reduce the freq difference b/w  $f_s$  &  $f_o$ . Once this action starts, we say that the sig is in capture mode. → The VCO continues to change freq till its O/P freq is exactly the same as the i/p sig freq, the ckt is then said to be locked.

→ Exact locking is achieved when the two sig are having same freq but a phase difference of  $90^\circ$ .

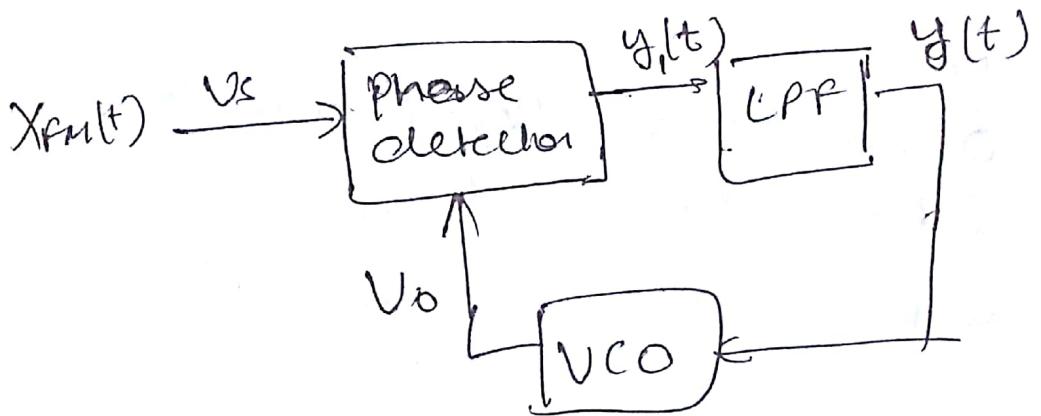
→ The LPF controls the capture range. If VCO freq is far away the difference freq will be too high to pass through the filter and PLL will not respond.

We say that sig is off of capture band  
 However once locked, the filter no longer restricts the PLL. the VCO can track the sig well beyond the capture band

"thus the capture range is always less than or equal to the locking range"

### Detection of FM sig using PLL

$$X_{FM}(t) = A \cos(wct + K_f \int_0^t m(t) dt)$$



$$X_{FM}(t) = A \cos wct$$

$$V_O(t) = B \cos(wct + \phi)$$

$$y_i(t) = AB \cos(wct + \phi) \cos wct$$

$$y(t) = 0.5 AB \cos \phi$$

$\phi \approx 90^\circ ; y(t) = 0$

$$V_O(t) = B \cos(wct + 90^\circ) = -B \sin wct$$

$$X_{FM}(t) = A \cos(wct + \phi \delta t);$$

$$\phi \delta t = K_f \int_0^t m(t) dt$$

$$\phi(s) = K_f \frac{m(s)}{s}$$

$$V_o(t) = -B \sin(\omega_c t + \phi_0 + \phi_i)$$

$$\phi_0(t) = K_1 \int_0^t y(t) dt$$

$$\frac{d\phi_0(t)}{dt} = K_1 y(t)$$

$$s \phi_0(s) = K_1 Y(s)$$

$$y_i(t) = -AB \cos(\omega_c t + \phi_i^*(t)) \sin(\omega_c t + \phi_0(t))$$

$$= -\frac{AB}{2} \left[ \sin(2\omega_c t + \cancel{\phi_i^*(t)} + \phi_0(t)) \right. \\ \left. + \sin(\phi_0(t) - \phi_i^*(t)) \right]$$

$$y(t) = -\frac{AB}{2} \sin(\phi_0(t) - \phi_i^*(t))$$

$$y(t) = \frac{AB}{2} [\sin(\phi_0(t) - \phi_i^*(t))]$$

$$\frac{1}{K_1} \frac{d\phi_0(t)}{dt} = \frac{AB}{2} [\phi_i^*(t) - \phi_0(t)]$$

$$s \phi_0(s) = K [\phi_i^*(s) - \phi_0(s)]$$

$$\phi_0(s) = \frac{K}{s+K} \phi_i^*(s)$$

$$\frac{K_1}{s} Y(s) = \frac{K}{s+K} \frac{K_F}{s} M(s)$$

as  $K$  is large  
so using dominant pole concept

$$\frac{1}{s+K} \Rightarrow \frac{1}{K}$$

$$Y(s) = \frac{K_F}{K_1} M(s)$$

$(\phi_i^*(t) - \phi_0(t))$   
is very low  
 $\sin \theta = 0$   
 $\theta \rightarrow 0$

FM detection method	Parameter	slope detector	Balanced slope detector	Foster Seeley discriminators	Karo detector	PLL
No of tuned circuits	1	3		2	2	1
Linearity	very poor	poor		Very good	good	Excellent
Sensitivity to Noise & amplitude variation	sensitive	sensitive		sensitive	Insensitive	sensitive
Application	Never used in practice	Never used in practice		Used in applications where linearity is critical ex Reception of TV sound carrier	Used where linearity is not critical as compared to sensitivity to noise variation ex Satellite Station RX	Nowadays in every application PLL is used for reception of FM sig

(P7)  $\text{Q} \odot$ 

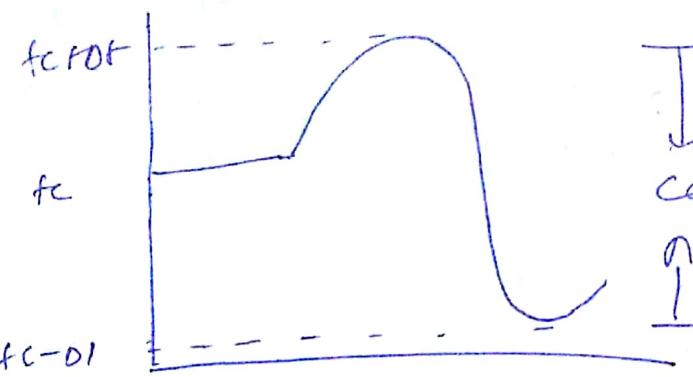
79

$$\text{fm} = 500 \text{ Hz}$$

$$f_{\text{oc}} = 10 \text{ MHz}$$

$$\Delta f_1 = 5 \text{ kHz}$$

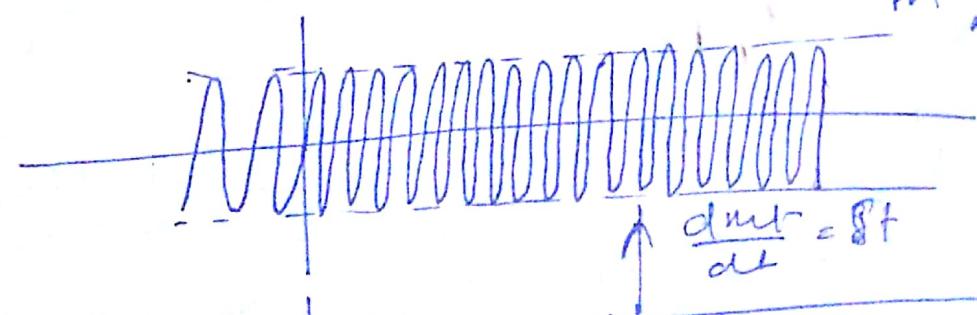
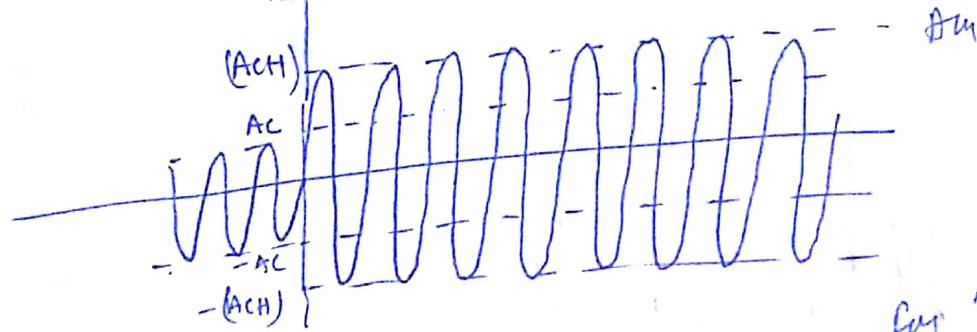
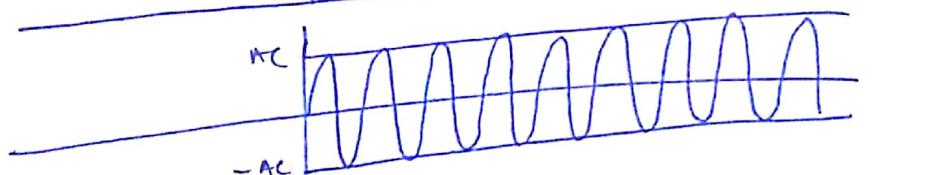
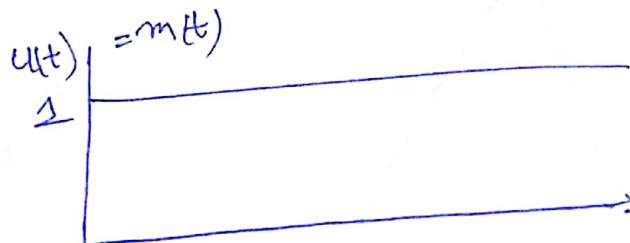
$$\beta = \frac{\Delta f}{f_{\text{m}}} = \frac{5 \times 10^3}{500} < 10$$



$$\begin{aligned}\text{Capture Range} &= \text{Capture Supply} \\ &= 2\Delta f \\ &= 10 \text{ kHz}\end{aligned}$$

(P19) Prove  $y(t) = m(t)$ 

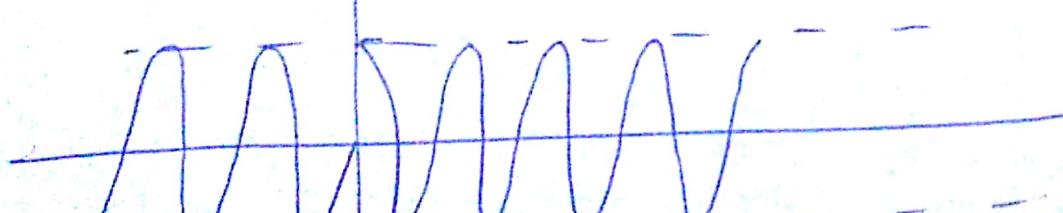
$$\Delta f = k_f m(t) \Big|_{\text{max}}$$



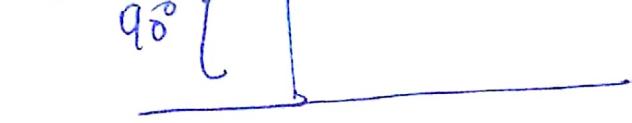
$$\begin{aligned}(A_c + m(t)) \cos \omega_c t \\ m(t)=0; A_c \cos \omega_c t \\ m(t)=1; (A(t)) \cos \omega_c t\end{aligned}$$

$$\begin{aligned}\omega_p = \omega_c + k_f m(t) \\ m(t)=0 \quad \omega_p = \omega_c \\ m(t)=1 \quad \omega_p = \omega_c + k_f\end{aligned}$$

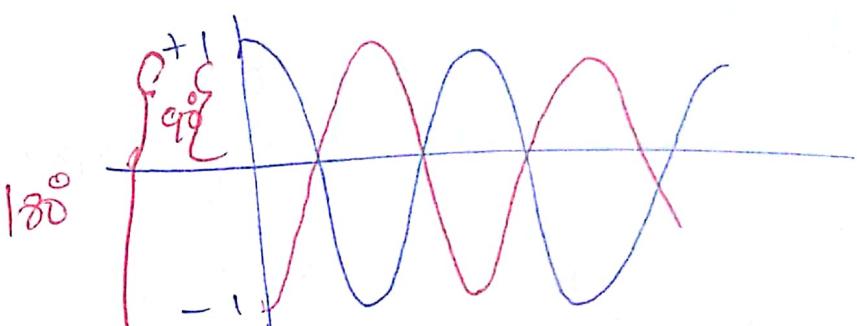
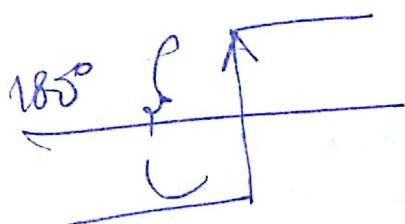
so only phase change occur by  $90^\circ$   
freq remains same.



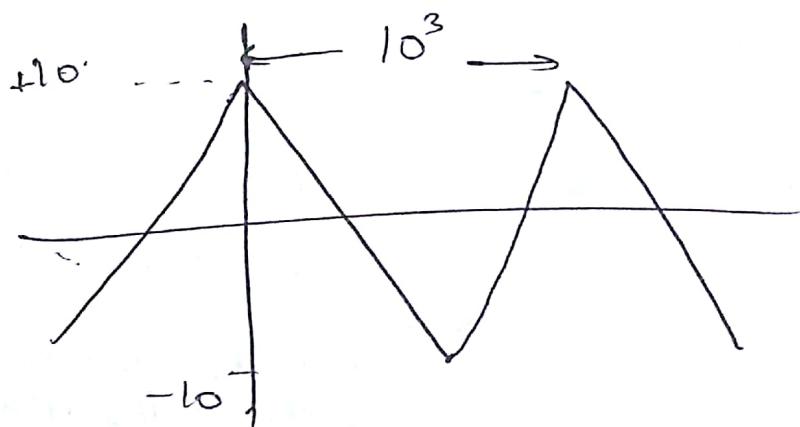
in case of abrupt discontinuity  
if  $90^\circ$



- if abrupt discontinuity is  
from 0 to  $\pi$   
then phase change by  
 $180^\circ$

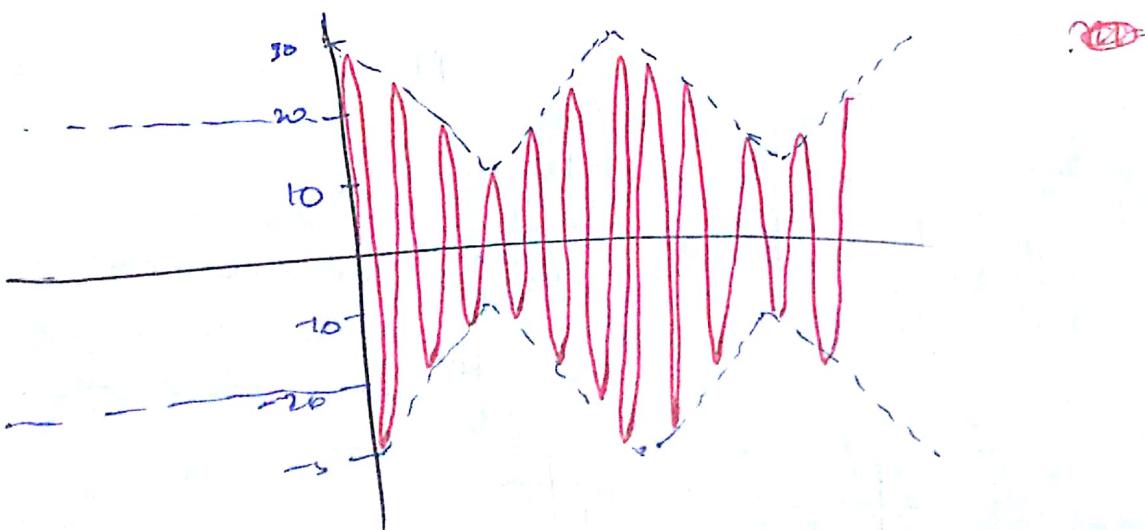


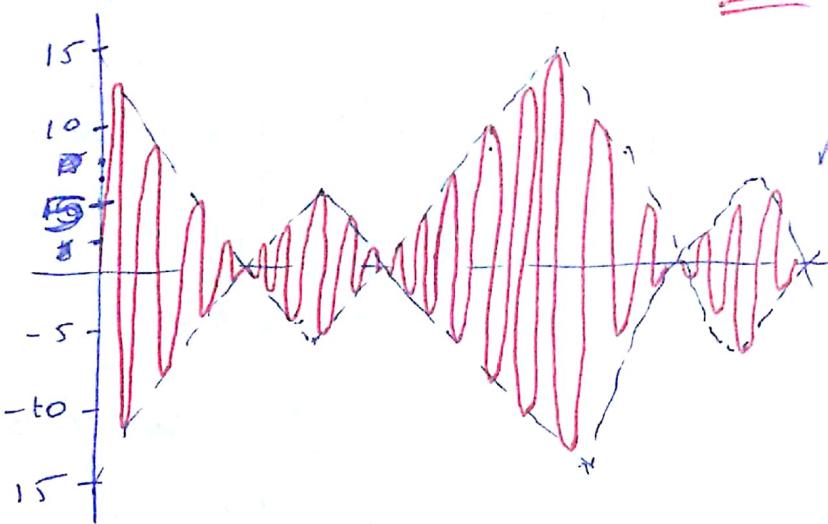
CQ Pg 121



$$m = 0.5 \\ Am = 10 \\ AC = 20$$

$$AC + Am = 30 \\ AC - Am = 10$$



 $m = 2$ 

$\underline{Am = 10}$

$AC = 5V$

$Am + AC = 15V$

$AC - Am = -5V$

$m = \infty = \frac{AC}{Am}$

$AC = \frac{Am}{\infty} = 0$

$Am + AC = 10$

$AC - Am = -10$

 $m = \infty$ no modulation

When  $m = \infty$ , no carrier is present only the baseband s/g is transmitted which represents no modulation

(2)

$$\textcircled{a} \quad AC = \frac{10}{0.8} = \frac{100}{8} = \underline{\underline{12.5}}$$

$$P_C = \frac{(12.5)^2}{2} = \frac{156.25}{2} = \underline{\underline{78.125}}$$

$\frac{15}{156} \Omega$

(b)

$$m(t) \cos \omega_c t = \frac{1}{2} \cdot P_m = \frac{1}{2} \times \frac{10^2}{3} = \frac{100}{6} = \frac{50}{3} = 16.67W$$

$$P_{m^2} = \frac{1}{2} \left( \int_0^{T/4} \frac{16A^2}{T^2} \cdot t^2 + A^2 - \frac{8A^2}{T} + \right] dt$$

$$= \frac{1}{2} \left[ \frac{16A^2}{T^2} \cdot \frac{T^3}{36} + A^2 T - \frac{8A^2}{T} \times \frac{T^2}{216} \right]$$

$$= \frac{16}{3} A^2 + A^2 - \frac{4A^2}{3} = \underline{\underline{-\frac{A^2}{3}}}$$

$$N = \frac{16.67}{78.125 + 16.67} \times 100\% = 17.5\%$$

## Random Variable & Noise

Experiment - An experiment is a process conducted to get some results

Outcome - An outcome is the result obtained after performing the experiment

Event - An event is combination of outcome

Sample space - The set of all possible outcomes of an experiment is called as sample space. It is also known as Ensemble space (not a function of time)

## Random variable (X)

- It is a numerical description of the outcomes
- A random variable is a numerically valued function defined over sample space
- There are two types of Random Variable
  - ① Discrete Random Variable (DRV)  
If X takes only a countable no. of distinct values then X is called a DRV

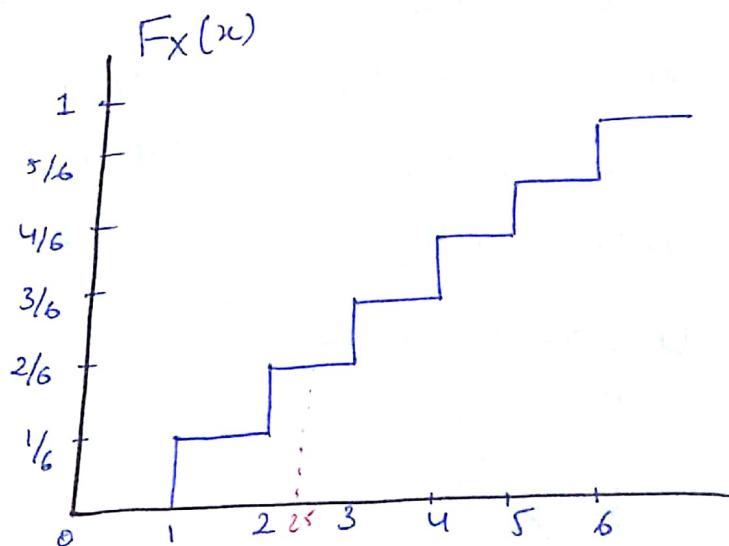
## (2) Continuous Random Variable (CRV)

→ If  $X$  can assume any value then it is called a continuous random variable. For ex. - Noise Voltage generated in an electronic amp<sup>2</sup> has a continuous amplitude.

### Cumulative distribution function (CDF)

CDF is the probability of all possible values in the total available range it contains all probabilistic information of random variable and is given by

$$F_X(x) = P\{X \leq x\} ; -\infty \leq x \leq \infty$$



$$F_X(2.5) = P\{X \leq 2.5\} = \frac{2}{6}$$

$$F_X(3.8) = P\{X \leq 3.8\} = \frac{3}{6}$$

$$F_X(5) = P\{X \leq 5\} = \frac{5}{6}$$

$$F_X(6.2) = P\{X \leq 6.2\} = 1 \Rightarrow \text{all possible event}$$

$$F_X(0.8) = P\{X \leq 0.8\} = 0 \Rightarrow \text{no. possible event}$$

## Properties of CDF

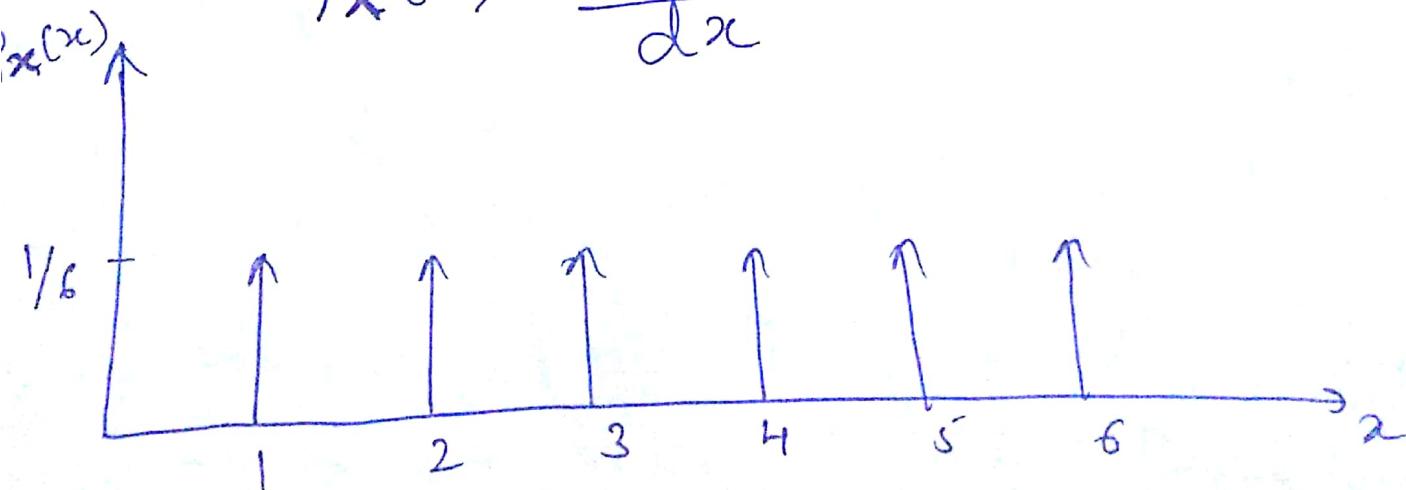
- ①  $0 \leq F_X(x) \leq 1$
  - ②  $F_X(-\infty) = P\{X \leq -\infty\} = 0$
  - ③  $f_X(\infty) = 1$
  - ④  $F_X(x_1) \leq F_X(x_2)$  ; if  $x_2 > x_1$   
it is always a Non decreasing function  
of  $x$
- $\Rightarrow$  CDF is non decreasing fn of  $x$

## PDF

Probability density or distribution function

$\rightarrow$  A CRV can't be described by any mathematical eq. but we can definitely describe the probability of CRV lying within an range around any possible value by a Mathematical function. This Analytical function is known as PDF and is given by

$$P_X(x) = \frac{dF_X(x)}{dx}$$



PDF of outcomes of Dice

## Property of PDF

85

$$(1) f_x(x) \geq 0$$

Since CDF is a non decreasing fn. of  $x$  so its differentiation will be always  $\geq 0$

(2) Area under the PDF curve is always equal to 1

$$\int_{-\infty}^{\infty} f_x(x) dx = 1$$

$$\int_{-\infty}^{\infty} \frac{df_x(x)}{dx} dx = F_x(\infty) - F_x(-\infty) = 1 - 0 = 1$$

$$(3) F_x(x) = \int_{-\infty}^{\infty} f_x(x) dx$$

$$(4) \boxed{P\{x_1 \leq X \leq x_2\} = \int_{x_1}^{x_2} f_x(x) dx}$$

Q Consider a Random variable  $X$  having CDF given by  $F_x(x) = 1 - e^{-0.01x}$ ;  $x \geq 0$

Compute probability that random variable has  $P\{X \geq 100\}$

$$f_x(x) = 0.01 e^{-0.01x}$$

$$P(X \geq 100) = \int_{100}^{\infty} 0.01 e^{-0.01x} dx$$

$$= -\frac{0.01}{0.01} \left\{ e^{-0.01x} \right\}_{100}^{\infty}$$

$$= -e^{-1}$$

METHOD @

$$\begin{aligned}
 P\{X \geq 100\} &= \int_{100}^{\infty} f_X(x) dx \\
 &= \int_{100}^{\infty} \frac{d}{dx} F_X(x) dx \\
 &= F_X(x) \Big|_{100}^{\infty} = F(100) - F(100) \\
 &\approx 1 - (1 - e^{-1}) \\
 &\approx e^{-1} = \left(\frac{1}{e}\right)
 \end{aligned}$$

Q Consider a random variable  $X$  whose PDF is given by  $f_X(x) = a e^{-bx}$ . Calculate

- (a) Relation b/w  $a$  &  $b$
- (b) Value of CDF for  $x < 0$
- (c) Value of CDF for  $x > 0$

$$f_X(x) = \begin{cases} ae^{-bx} & ; x < 0 \\ a e^{-bx} & ; x > 0 \end{cases}$$

area under curve

$$\int_{-\infty}^{\infty} ae^{-bx} dx + \int_0^{\infty} ae^{-bx} dx = 1$$

$$\frac{a}{b}(1) + \left(-\frac{a}{b}\right)(-1) = 1$$

$$2\frac{a}{b} = 1$$

$$\underline{2a = b}$$

③

$$\int_{-\infty}^0 \frac{a}{b} e^{-bx} dx = \frac{a}{b} \left[ -e^{-bx} \right]_{-\infty}^0 = \frac{a}{b} (1 - 0) = \frac{a}{b}$$

④

$$\int_0^{\infty} \frac{a}{b} e^{-bx} dx = \frac{a}{b} \left[ -e^{-bx} \right]_0^{\infty} = \frac{a}{b} (0 - 1) = -\frac{a}{b}$$

$$\textcircled{b} \quad f_X(x) = \int_{-\infty}^x ae^{bx} dx \quad ; x < 0$$

$$= \frac{a}{b} e^{bx}$$

$$\textcircled{c} \quad f_X(x) = \int_{-\infty}^0 ae^{bx} dx + \int_0^x ae^{-bx} dx \quad ; x \geq 0$$

$$= \frac{a}{b} + \frac{a}{b} \left( e^{-bx} - 1 \right)$$

$$= \frac{a}{b} + \frac{a}{b} \left( 1 - e^{-bx} \right)$$

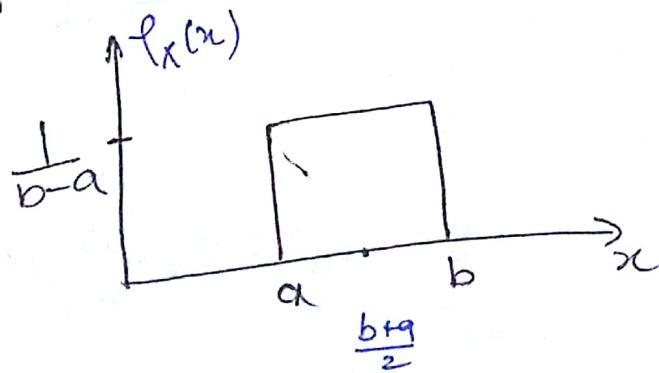
$$= \frac{a}{b} \left( 2 - e^{-bx} \right)$$

## Statistical Averages

### ① Mean or First Moment

mean is a measure of where distribution curve is centered and is given by expectation of  $X$

$$E[X] = m_x = \int_{-\infty}^{\infty} x \cdot f_X(x) dx$$



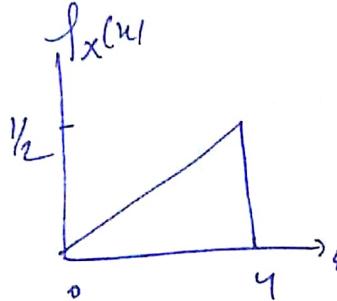
$$m_x = \frac{1}{b-a} \int_a^b x dx =$$

$$= \frac{1}{b-a} \left[ \frac{x^2}{2} \right]_a^b$$

$$= \frac{b+a}{2}$$

② Mean square value or second moment  
the mean square value or second moment  
is given by expectation of  $X^2$

$$E[X^2] = \int_{-\infty}^{\infty} x^2 f_x(x) dx$$

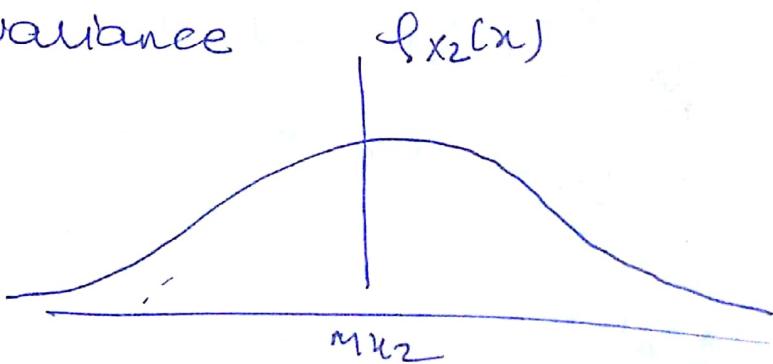
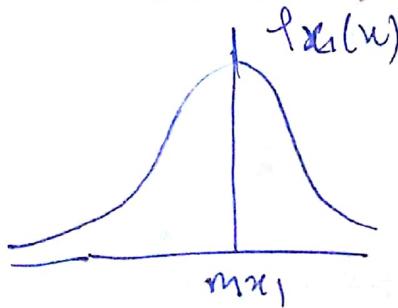


$$f_x(x) = \frac{1}{8}x$$

$$E(X^2) = \frac{1}{8} \int_0^4 x^3 dx = \frac{1}{8} \left[ \frac{x^4}{4} \right]_0^4 = 8$$

③ Variance or second central moment

→ It measures the spread of distribution about its mean. The less the spreading, smaller is the variance.



$$\sigma_x^2 = E[(X - \mu_x)^2] = \int_{-\infty}^{\infty} (x - \mu_x)^2 \cdot f_x(x) dx$$

# Properties of Expectation operator $E[\cdot]$

① Expectation of a constant is constant itself eg  $\rightarrow E[C] = C$

$$E[C] = \int_{-\infty}^{\infty} C f_x(x) dx = C \underbrace{\int_{-\infty}^{\infty} f_x(x) dx}_{\text{area under the curve} = 1}$$

② Expectation of a constant times random variable is equal to the constant times the expectation of Random Variable

$$\boxed{E[Cx] = C E[x]}$$

$$E[Cx] = \int_{-\infty}^{\infty} C x f_x(x) dx = C E(x)$$

— homogeneity property

③ Expectation of sum of random variable is equal to sum of expectation

$$E\left[\sum_i x_i\right] = \sum_i E[x_i]$$

$$= \int_{-\infty}^{\infty} \sum_i x_i f_x(x) dx$$

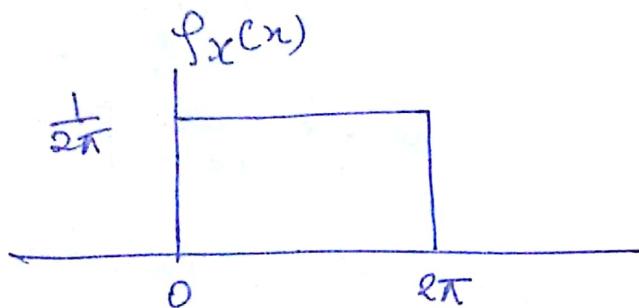
$$= \sum_i \int_{-\infty}^{\infty} x_i f_x(x) dx$$

— additivity

$$= \sum_i E[x_i]$$

"expectation operator is a Linear operator"

- Q Consider a random variable  $X$  uniformly distributed b/w  $0$  &  $2\pi$  calculate
- mean value
  - mean sq. value
  - Variance
  - $E[\cos x]$



$$(a) \text{ mean} = \pi$$

$$(b) \text{ mean sq. val} = \frac{1}{2\pi} \int_0^{2\pi} u^2 du = \left[ \frac{u^3}{3} \right]_0^{2\pi} = \frac{(8\pi^3)}{3} + \frac{1}{2\pi} = \frac{4\pi^2}{3}$$

$$(c) \text{ Variance} = \frac{1}{2\pi} \int_0^{2\pi} \left( \frac{x-\pi}{2\pi} \right)^2 du = \frac{1}{2\pi} \left[ \frac{(x-\pi)^3}{3} \right]_0^{2\pi}$$

$$= \cancel{\frac{1}{2\pi} \left[ \left( \frac{2\pi - \pi}{3} \right)^3 \right]} + \frac{1}{2\pi} \left( \frac{\pi}{3} \right)^3$$

$$\begin{aligned} &= \frac{1}{2\pi} \left( \frac{\pi^3}{3} \right) \\ &= \frac{\pi^2}{3} \end{aligned}$$

$$(d) E[\cos x] = \frac{1}{2\pi} \int_0^{2\pi} \cos u du = 0$$

## Random Process [X(t)]

- The time domain representation of Random variable is known as Random process
- The time description of Random variable is called as Random process
- There are two types of Random processes

### ① Stationary Random processes

a random process is said to be stationary if its statistical properties are not function of time

→ it is further of two types

#### (i) Strictly stationary Random process

→ if the R.P. has the same statistical properties that is mean, pdf, autocorrelation function(ACF) etc. at any instant of time then  $X(t)$  is stationary in strict sense.

#### (ii) Wide sense stationary R.P. (WSS)

→ if only mean & auto correlation fn. are stationary then  $X(t)$  is said to be WSS.

"ALL strictly stationary R.P. are WSS  
but converse is not true"

## ② Non stationary Random process

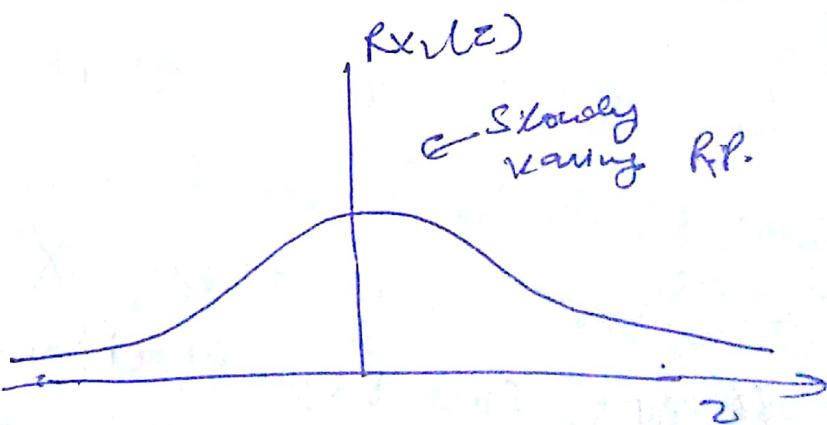
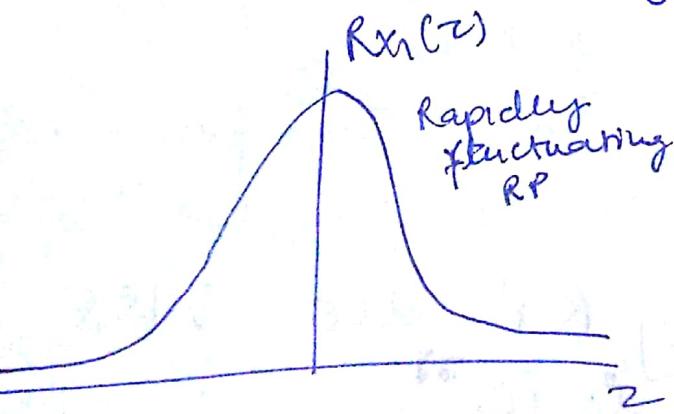
if statistical properties are function of time then the process is non-stationary

## Auto correlation function (ACF)

→ it is also known as Ensemble ACF.  
the ACF of a random process  $X(t)$  is given by  $R_X(\tau) = E[X(t) \cdot X(t+\tau)]$

## Physical significance

The physical significance of ACF is that it provides the mean of describing the interdependence of R.P. at time  $\tau$  sec. apart. It is therefore clear that more rapidly the random process changes with time, more rapidly will the ACF decrease from its max. value.



Q consider a Random process  $x(t)$  given by  $A \cos(2\pi f_c t + \theta)$  where  $\theta$  is a uniformly distributed random variable b/w 0 and  $2\pi$ . calculate its autocorrelation

$$X(t) = A \cos(2\pi f_c t + \theta)$$

$$R_X(z) = E[A \cos(2\pi f_c t + \theta) \cdot A \cos(2\pi f_c t + 2\pi f_c z + \theta)]$$

$$= E\left[\frac{A^2}{2} (\cos(4\pi f_c t + 2\pi f_c z + 2\theta) + \cos(2\pi f_c z))\right]$$

$$R_X(z) = E\left[\underbrace{\frac{A^2}{2} \cos(4\pi f_c t + 2\pi f_c z + 2\theta)}_{=} + E\left[\underbrace{\frac{A^2}{2} \cos(2\pi f_c z)}_{\text{const}}\right]\right]$$

$$R_X(z) = \frac{A^2}{2} \cos(2\pi f_c z)$$

### Properties of ACF

→ Correlation has its max value ~~at z=0~~ at  $z=0$

→  $R_X(0) \geq R_X(z)$

→ the auto correlation func. is always a even function of time  $t$

$R_X(-z) = R_X(z)$

→ the mean square value of Random process may be obtained from  $R_X(z)$  by simply putting  $z=0$

$$R_X(0) = E[X^2(t)] = \text{mean square value of R.P.}$$

if  $R_x(z)$  is auto-correlation func. of a zero mean WSS R.P.  $X(t)$  then which one of the following is not true

- (a)  $R_x(z) = R_x(-z)$
- (b)  $R_x(z) = -R_x(-z)$
- (c)  $\boxed{R_x^2 = R_x(0)}$
- (d)  $|R_x(z)| \leq R_x(0)$

### Ergodic Random process

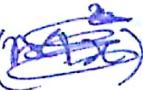
A R.P. is said to be ergodic, when time average of a random process becomes equals to ensemble mean.

$$\frac{1}{2T} \int_{-T}^T x(t) dt = m_x$$

When time averaged auto-correlation function becomes equal to ensemble ACF

$$\frac{1}{2T} \int_{-T}^T x(t)x(t+z) dt = R_x(z) = -E[x(t)x(t+z)]$$

## Properties of Ergodic RP

- ① The ensemble mean  $m_x$  gives the dc component of a Random Process
- ②   $(m_x)^2$  is the dc power of ergodic random process
- ③ mean square value of random process is the total average power of ergodic R.P. at  $R_x(z)$   $\forall z \in \mathbb{C}$

$$R_x(0) = E[X^2(t)] = \frac{1}{2T} \int_{-T}^T X^2(t) dt$$

$$\begin{aligned} \sigma_x^2 &= E[(X - m_x)^2] = \int_{-\infty}^{\infty} (x - m_x)^2 f_x(x) dx \\ &= \int_{-\infty}^{\infty} x^2 f_x(x) dx + \int_{-\infty}^{\infty} m_x^2 f_x(x) dx - 2 \int_{-\infty}^{\infty} m_x x f_x(x) dx \\ &= \int_{-\infty}^{\infty} x^2 f_x(x) dx + m_x^2 \int_{-\infty}^{\infty} f_x(x) dx - 2m_x \int_{-\infty}^{\infty} x f_x(x) dx \\ &= E[X^2] + m_x^2 - 2m_x E[X] \end{aligned}$$

$$\sigma_x^2 = E[X^2] - m_x^2$$

↓  
 ac  
power  
  
 ↓  
 Total  
average  
power  
  
 ↓  
 dc  
power

at  $m_x = 0$

$$\sigma_x^2 = E[X^2]$$

Q a stationary RP  $X(t)$  has a d.c power given by  $R_x(t) = 20 + 5 \cos 2\pi t + 10e^{-4t}$   
 calculate ⑥ Total average power ⑦ d.c power  
 ⑧ ac power ⑨ mean ⑩ variance  
 ⑪ rms value of random process.

⑥ -  $\int_{-\infty}^{\infty} R_x(t) dt = 35$

⑦ 20

⑧ 15

⑨  $\sqrt{20}$

⑩ 15

⑪  $\sqrt{35}$

Q.  $x(n) \xrightarrow{\text{variance}} \sigma_x^2$   
 $\delta(n) \xrightarrow{\text{"}} \frac{\sigma_x^2}{10}$

$$E[\delta^2(n)] = E[(x(n) - x(n-1))^2]$$

$$= E[x^2(n)] + E[x^2(n-1)] - 2 E[x(n) \cdot x(n-1)]$$

$$\frac{\sigma_x^2}{10} = \sigma_x^2 + \sigma_n^2 - 2(R_x(1))$$

$$\frac{\sigma_x^2}{10} - \frac{20\sigma_x^2}{10} = 2R_x(1)$$

$$\frac{11\sigma_x^2}{10} = 2R_x(1)$$

$$R_x(1) = \frac{19}{20}\sigma_x^2$$

## Wener - Khinchine theorem

It states that auto correlation function & Power spectral density (PSD) forms the Fourier transform pair

$$R_X(z) \xrightarrow{\text{FT}} \text{PSD}$$

$$S_X(\omega) = \int_{-\infty}^{\infty} R_X(z) e^{-j\omega z} dz$$

$$= \int_{-\infty}^{\infty} R_X(z) e^{-j2\pi f z} dz$$

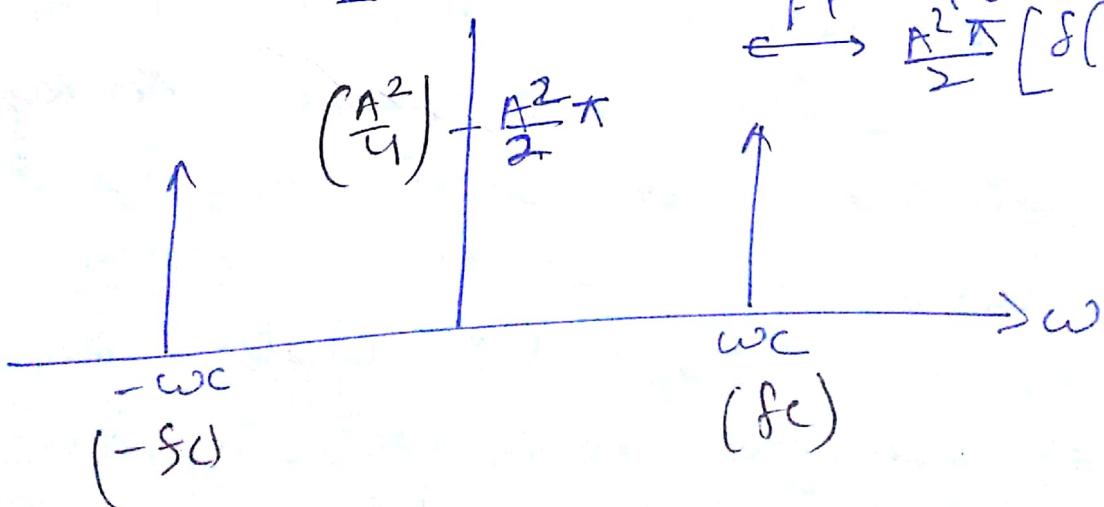
$$R_X(z) = \frac{1}{2\pi} \int_{-\infty}^{\infty} S_X(\omega) e^{j\omega z} d\omega$$

$$= \int_{-\infty}^{\infty} S_X(f) e^{j2\pi f z} df$$

$$X(t) = A \cos(2\pi f_c t + \Theta)$$

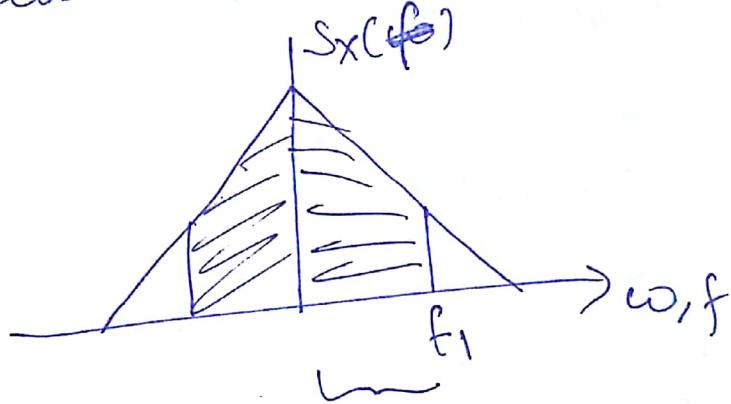
$$R_X(z) = \frac{A^2}{2} \cos 2\pi f_c z \xrightarrow{\text{FT}} \frac{A^2}{4} [\delta(f-f_c) + \delta(f+f_c)]$$

$$\xrightarrow{\text{FT}} \frac{A^2 \pi}{2} [\delta(\omega-\omega_c) + \delta(\omega+\omega_c)]$$



## Power spectral density PSD

Power spectral density is a measure of how total average power is distributed with freq. & is defined as "power/unit Bw" in watt/Hz or watt/rad/sec  
→ It is also called as power spectrum



Let us consider a random process  $x(t)$  whose power spectral density curve is shown above as it can be clearly seen that the max. noise power is concentrated with in low freq and as we go higher on freq's, the effect of noise go on reducing & Reducing & after a freq.  $f_1$ , the noise completely disappear so system can be optimised accordingly. If it has to be used at lower freq's, the sig power should be high but if the system can be used at higher freq, only a small amount of sig power can be used to have high SNR.

## Properties of PSD

① the zero freq value of PSD of a WSS R.P. equals the total area under the graph of auto correlation function.

(Central ordinate theorem)

$$S_x(0) = \int_{-\infty}^{\infty} R_x(z) dz$$

total area under the curve.

② ✓ the mean square value of wss R.P. equals the total area under the graph of power spectral density

$$\begin{aligned} E[X^2(t)] &= R_x(0) = \frac{1}{2\pi} \int_{-\infty}^{\infty} S_x(\omega) d\omega \\ &= \int_{-\infty}^{\infty} S_x(f) df \end{aligned}$$

③ the PSD is always non-negative

$$S_x(\omega) \geq 0$$

$$\text{PSD} = \frac{\text{Power}}{\text{BW}}$$

$$S_x(f) \geq 0$$

④ PSD is always an even function of freq.

i.e.  $S_x(-\omega) = S_x(\omega)$

$$S_x(-f) = S_x(f)$$

Since ACF is an even fn<sup>t</sup> of time  $z$  so its FT is also a even fn<sup>t</sup>

Q a WSS R.P.  $x(t)$  has power spectrum given by

$$S_x(\omega) = \frac{4}{\omega^2 + 3}$$

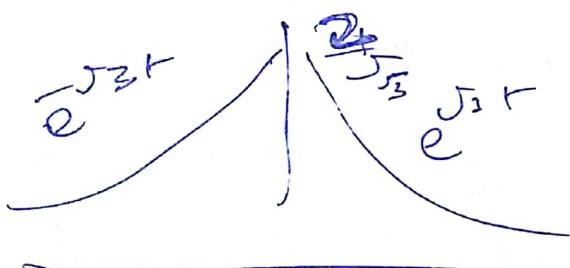
calculate ~~(1) ACF~~ ~~(2) total average power~~

$$\hat{e}^{-at|t|} = \frac{2a}{\omega^2 + a^2}$$

①

$$= \frac{\int_{-\infty}^{\infty} x(t)x(t+\tau) dt}{\int_{-\infty}^{\infty} x(t)^2 dt}$$

$$= \frac{1}{\sqrt{3}}$$



②



$$R_x(0) = \frac{2}{\sqrt{3}}$$

$$\frac{\delta t - \Delta}{2\pi \pm 2\Delta}$$

Q given the following power spectrum of a R.P.  $X(t)$

$$S_x(\omega) = 8\pi \cdot 8(\omega) + 1 \cdot 2\pi \delta(\omega - 2\cdot 3\pi) \\ + 1 \cdot 2\pi \delta(\omega + 2\cdot 3\pi) \\ + 4\pi \delta(\omega - 5) + 4\pi \delta(\omega + 5)$$

Calculate

①  $R_x(t) = 1 \cdot 2 \cos 2 \cdot 3\pi t + 4 \cos 5\pi t + 4$

② Total average power, DC, AC power  
 9.2                  4                  5.2

Q Consider the two spectrums given by  
 $S_1(\omega) = \frac{(\omega-2)^2}{\omega^2} \Rightarrow$  No. It is not even func of freq.  
 $S_2(\omega) = \frac{\omega^2}{1+2\omega^2+j\omega^4} \Rightarrow$  No, it is not power spectrum function  
 since  $S_2(\omega)$  has an imaginary part so it can't be PSD because PSD is always a real function

Q  $S_1(\omega) = \frac{\cos(2\omega)}{1+2\omega^2+\omega^4} = \frac{\cos(2\omega)}{(\omega^2+1)^2}$

Since  $\cos 2\omega$  can be negative so it can't be PSD

$$S_2(\omega) = \frac{\omega^2+5}{(\omega^2+1)(\omega^2+3)}$$

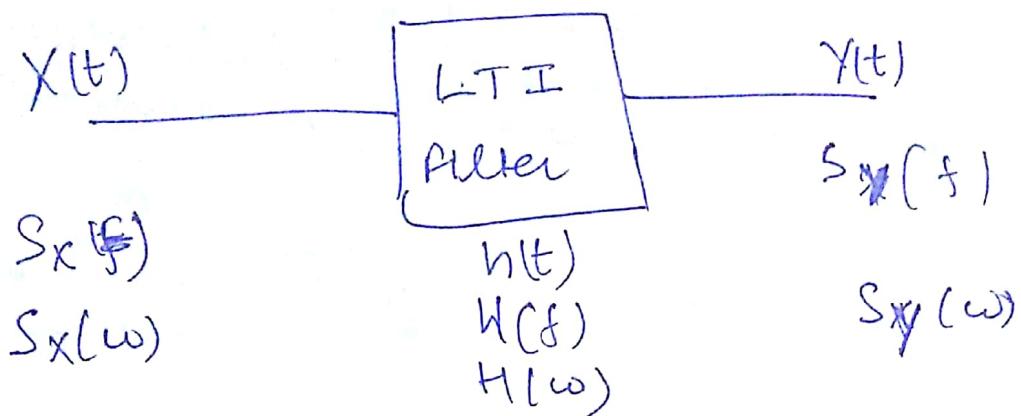
it is real, non negative and even also  
 so it is PSD

Assignment  
 a R.P.  $x(t)$  has a power spectrum given by  
 $S_x(\omega) = \frac{\omega^2+4}{(\omega^2+8\omega^2+7)}$

Total average power

calculate ④ ACF ⑤ Inverse Fourier of  $S_x(\omega)$

# Transmission of a Random Process through linear filter



it states that mean square value of the opp of stable LTI filter in response to WSS process is equal to the integral over all freq. of the PSD of input random process multiplied by square magnitude of freq. Response of filter

$$E[Y^2(t)] = \int_{-\infty}^{\infty} S_x(f) \cdot |H(f)|^2 df$$

$$E[Y^2(t)] = \int_{-\infty}^{\infty} S_x(f) df$$

$$S_y(f) = S_x(f) |H(f)|^2$$

$$E[Y^2(t)] = \frac{1}{2\pi} \int_{-\infty}^{\infty} S_x(\omega) |H(\omega)|^2 d\omega$$

$$E[Y^2(t)] = \frac{1}{2\pi} \int_{-\infty}^{\infty} S_y(\omega) d\omega$$

$$S_y(\omega) = S_x(\omega) |H(\omega)|^2$$

$\Leftrightarrow$  a R.P.  $x(t)$  with PSD  $\rightarrow$

$$S_x(f) = \frac{1}{2} \left[ \delta\left(f - \frac{1}{2\pi}\right) + \delta\left(f + \frac{1}{2\pi}\right) \right]$$

is the input to a linear system having freq. response  $H(f) = \frac{1}{1 + j2\pi f}$

calculate the average power of O/P random process.

$$= \int_{-\infty}^{\infty} \frac{1}{2} \left[ \delta\left(f - \frac{1}{2\pi}\right) + \delta\left(f + \frac{1}{2\pi}\right) \right] \left| \frac{1}{1 + j2\pi f} \right|^2 df$$

$$= \int_{-\infty}^{\infty} \frac{1}{2} \left[ \delta\left(f - \frac{1}{2\pi}\right) + \delta\left(f + \frac{1}{2\pi}\right) \right] \frac{1}{1 + 4\pi^2 f^2} dt$$

$$= \frac{1}{2} \left[ \frac{1}{1 + 4\pi^2 \left(\frac{1}{2\pi}\right)^2} + \frac{1}{1 + 4\pi^2 \left(-\frac{1}{2\pi}\right)^2} \right]$$

$$= \frac{1}{1+1} = \boxed{\frac{1}{2}}$$

$\Leftrightarrow$  consider a random process  $x(t)$  with ACF  $R_x(\tau) = e^{-\alpha|\tau|}$  with  $\alpha \ll \omega$

the process is passed through an ideal differentiator the approximate PSD at O/P  $y(t)$

$$\boxed{\frac{d}{dt}}$$

$$S_x(f) = \frac{2\alpha}{\omega^2 + \alpha^2} = \frac{2\alpha}{\omega^2} = \cancel{\frac{2\alpha^2}{\omega^3}} = \cancel{\frac{2\alpha^2}{\omega^3}} \quad \text{circled}$$

$$\frac{2\alpha}{\omega^2} |\omega|^2 d\omega = \frac{2\alpha \omega^2}{\omega^2 + \alpha^2} d\omega$$

$$S = 2\alpha$$

$$\boxed{H(\omega) = j\omega} \quad |H(\omega)|^2 = \omega^2$$

$$S_y(\omega) = S_x(\omega) |H(\omega)|^2$$

$$= \frac{2a}{\omega^2 + a^2} \omega^2 = (2a)$$

Assignment

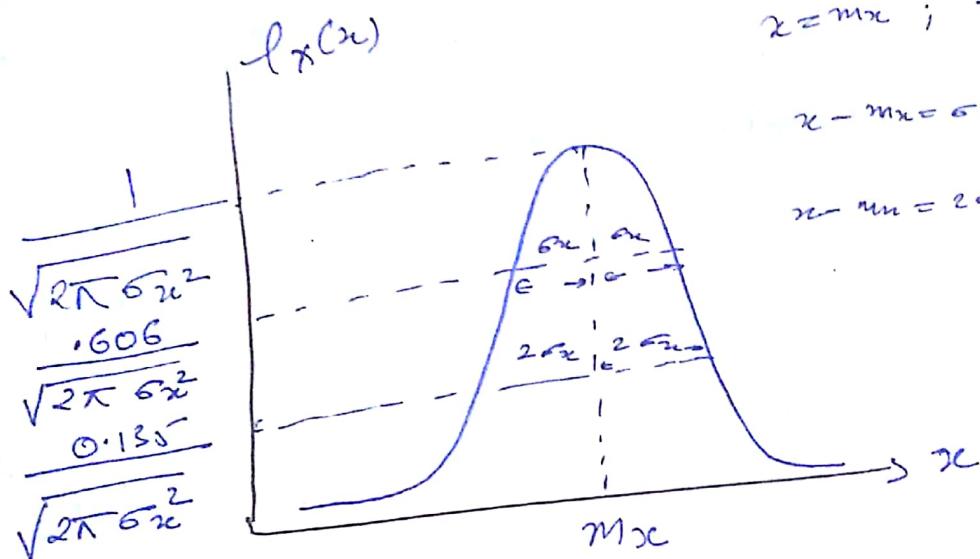
Q a system with TF  $H(s) = \frac{s-1}{s^2 + 3s + 2}$  is excited

by a random process having uniform power spectral density No. the ACF of O/P process  $Y(t)$  is given by - - - - -

## Gaussian PDF

Gaussian PDF provides a good mathematical model for various physically observed random phenomena and is given by

$$f_x(x) = \frac{1}{\sqrt{2\pi\sigma_x^2}} \exp\left[-\frac{(x - m_x)^2}{2\sigma_x^2}\right]$$

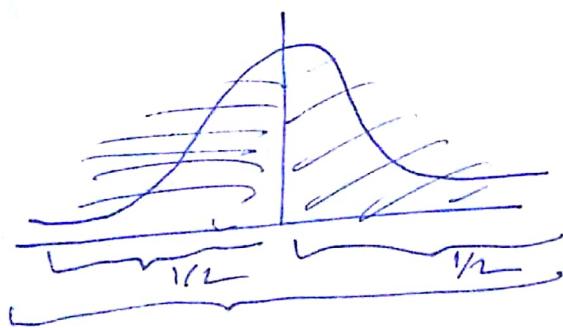


$$x = m_x ; f_x(x) = \frac{1}{\sqrt{2\pi\sigma_x^2}}$$

$$x - m_x = \sigma_x ; f_x(x) = \frac{0.606}{\sqrt{2\pi\sigma_x^2}}$$

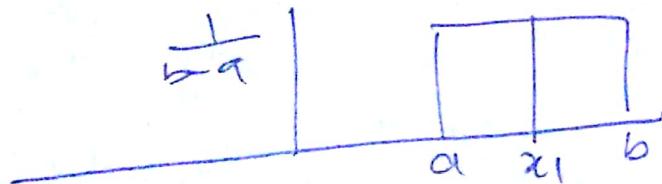
$$m - m_x = 2\sigma_x ; f_x(x) = \frac{0.135}{\sqrt{2\pi\sigma_x^2}}$$

Q For a zero mean gaussian random variable, the probability  $P\{X \geq 0\}$  will be.  $\frac{1}{2}$



1 (area)

Q



$$P\{X = x_1\} = \frac{1}{b-a} \int_{x_1}^{x_1} du$$

$$= \frac{1}{b-a} (x_1 - a)$$

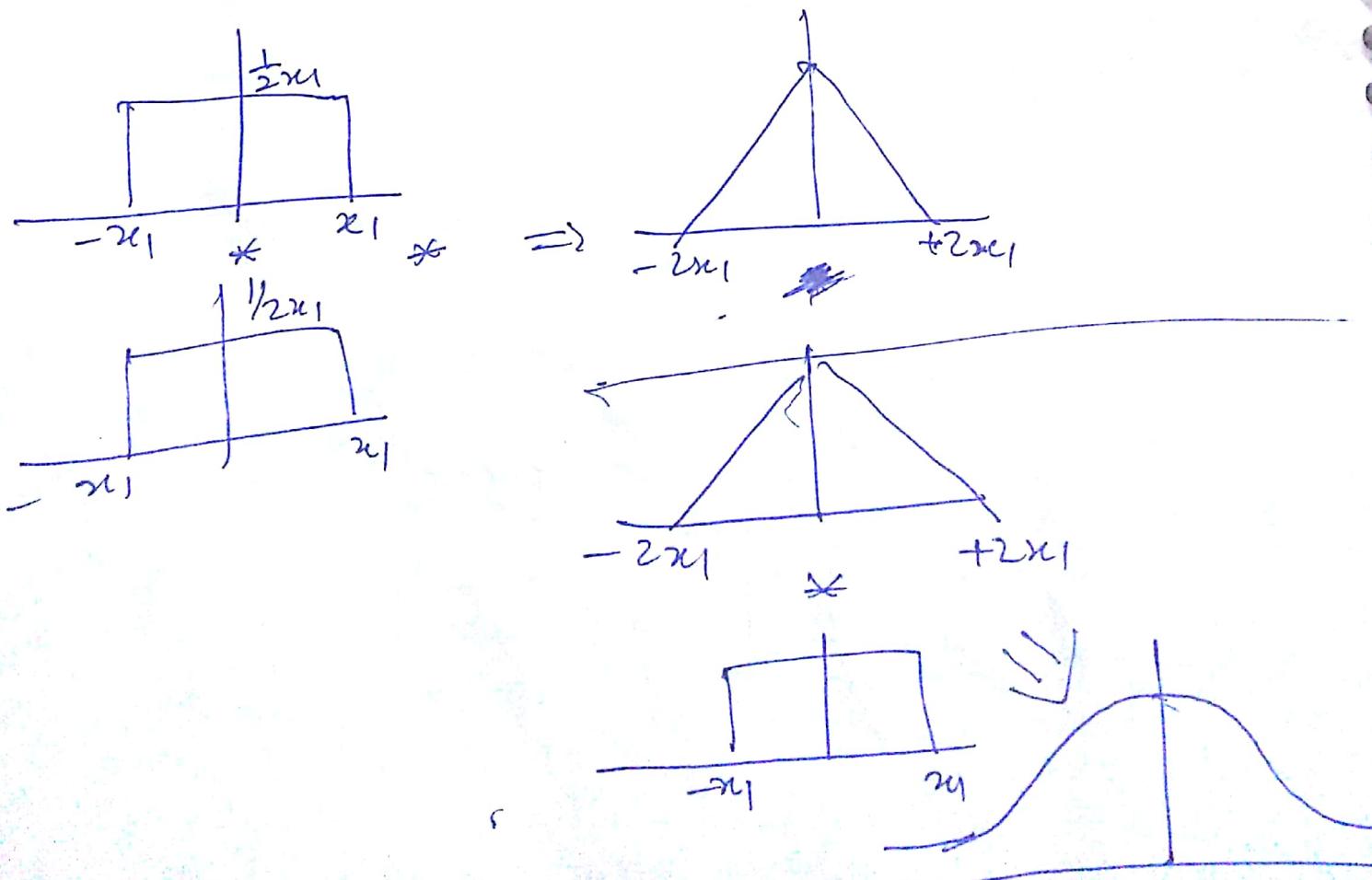
Q

For a continuous R.V., the probability at a single pt is always equal to zero  
Not for Discrete + 1177

## Central Limit theorem

It states that the P.D. function of a sum of 'N' independent random variables tend to approach a gaussian density as the no. N increases. This theorem applies even ~~when~~ individual R.V. are not gaussian

$$\sum_{i=1}^N X_i = X_1 + X_2 + X_3 + \dots + X_N = \text{Gaussian R.V.}$$
$$f_{X_1}(x) * f_{X_2}(x) * f_{X_3}(x) \dots * f_{X_N}(x) = \text{Gaussian PDF}$$



Q A voltage  $V(t)$  which is a gaussian ergodic R.P. with a mean zero and a variance of  $4V^2$ , is measured by
 

- (a) a dc meter
- (b) a true RMS meter
- (c) a meter which squares  $V(t)$  and reads its dc component.

 Calculate the opf of each meter

$$E|V(t)| = \sigma_u^2 = 4V^2$$

- (a) 0
- (b)  $2V$
- (c)  $4V^2$

$$\overline{V^2 t} = \text{total average power}$$

$$|\overline{V(t)}|^2 = \text{dc power}$$

square of mean