SystemC AMS Extensions – The Language

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Outline

SystemC-AMS Language Composition

SystemC-AMS Model of Computation

- Timed Dataflow (TDF)
- Linear Signalflow (LSF)
- Electrical Linear Networks (ELN)

Types of analysis

- Time domain simulation
- Frequency / Noise domain simulation

Simulation Control and Debugging

- Testbenches / sc_main
- Tracing
- Postprocessing / Wave viewing

Proof-of-Concept Implementation

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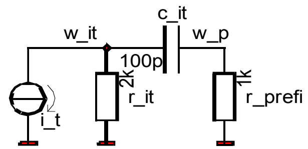
SystemC-AMS Language Composition

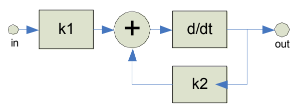
What’s different between analog and digital ?

- Analog equation cannot be solved by the communication and synchronization of processes



$$0 = i\_t + \frac{v(w\_it)}{r\_it} + c\_it \bullet \frac{d(v(w\_it) - v(w\_p))}{dt}$$

$$0 = \frac{v(w\_p)}{r\_prefi} - c\_it \bullet \frac{d(v(w\_it) - v(w\_p))}{dt}$$



$$out = \frac{d}{dt}(k1 \bullet in + k2 \bullet out)$$

->in general an **equation system must be setup**

- The analog **system state changes continuously**
  - the value between solution points is continuous (linear is a first order approximation only)
  - -> the value of a time point between two solution points can be estimated only after the second point has been calculated (otherwise instable extrapolation)

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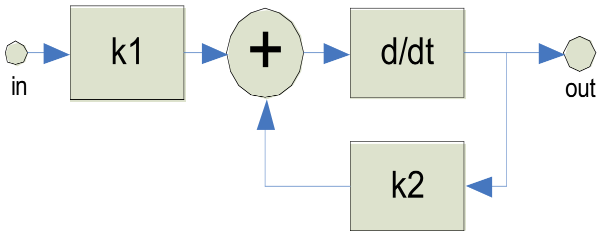
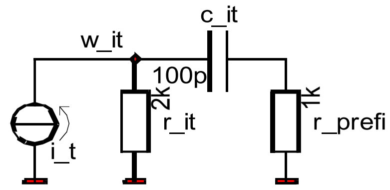
Non Conservative vs. Conservative

Non Conservative



- Abstract representation of analog behavior
- The graph represents a continuous time (implicit) equation (system)

Conservative



- Represents topological structure of the modeled system
- Nodes are characterized by two quantities – the across value (e.g. voltage) and the through value (e.g. current)
- For electrical systems, Kirchhoff's laws applied (KCL, KVL)
- For other physical domains generalized versions of Kirchhoffs's laws applied

SystemC-AMS Language Basics

- A primitive **Module** represents a **contribution** of equations to a model of computation (MoC)
  - ->primitives of each MoC must be derived from a specific base class

- A **channel** represents in general an edge or variable of the equation system – thus not necessarily a communication channel

- SystemC-AMS modules/channels are **derived** from the SystemC base classes (*sc_module*, *sc_prim_channel/sc_interface*)

- There is no difference compared to SystemC for hierarchical descriptions – they are using *SC_MODULE / SC_CTOR*

Symbol Names and Namespaces

- All SystemC-AMS symbols have the prefix ***sca_*** and macros the prefix ***SCA_***
- All SystemC-AMS symbols are embedded in a **namespace** – the concept permits extensibility
- Symbols assigned to a certain **MoC** are in the corresponding namespace
  - ***sca_tdf, sca_lsf, sca_eln***
- Symbols relating to core functionality or general base classes embedded in the namespace ***sca_core***
- Symbols of utilities like tracing and datatypes are in the namespace ***sca_util***
- Symbols related to small-signal frequency-domain analysis
  - ***sca_ac_analysis***

SystemC-AMS Modules

- AMS modules are derived from ***sca_core::sca_module*** which is derived from sc_core::sc_module
  - Note: not all sc_core::sc_module member functions can be used

- **AMS modules are always primitive modules**
  - an AMS module can not contain other modules and/or channels
- Hierarchical descriptions still use sc_core::sc_module (or *SC_MODULE* macro)

- Depending on the MoC, AMS modules are pre-defined or user- defined
- Language constructs
  - *sca_MoC::sca_module* (or *SCA_MoC_MODULE* macro)
  - e.g. *sca_tdf::sca_module* (or *SCA_TDF_MODULE* macro)

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SystemC AMS channels

- AMS channels are derived from *sca_core::sca_interface* which is derived from *sc_core:sc_interface*
- AMS channels for Time Data Flow and Linear Signal Flow
  - based on directed connection
  - used for non-conservative AMS model of computation
  - Language constructs:
    - *sca_MoC::sca_signal*
    - e.g. *sca_lsf::sca_signal*, *sca_tdf::sca_signal<T>*
- AMS channels for Electrical Linear Networks
  - conservative, non-directed connection
  - characterized by an across (voltage) and through (current) value
  - Language constructs:
    - *sca_MoC::sca_node* / *sca_MoC::sca_node_ref*
    - e.g. *sca_eln::sca_node*, *sca_eln::sca_node_ref*

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SystemC AMS Language Composition - Summarize

- *sca_module* – base class for SystemC AMS primitive
- *sca_in* / *sca_out* – non-conservative (directed in/outport)
- *sca_terminal* – conservative terminal
- *sca_signal* – non-conservative (directed) signal
- *sca_node* / *sca_node_ref* – conservative node

- The MoC is assigned by the namespace e.g.:
  - *sca_tdf::sca:module* - base class for timed dataflow primitives modules
  - *sca_lsf::sca_in* - a linear signalflow inport
  - *sca_tdf:sca_in<int>* - a TDF inport
  - *sca_eln::sca_terminal* - an electrical linear network terminal
  - *sca_eln::sca_node* - an electrical linear network node

SystemC AMS Language Element Composition - Converter

- Converter elements are composed by the namespaces of booth domains:

  - ***sca_tdf::sca_de::sca_in***<*T*> - is a port of a TDF primitive module, which can be connected to an *sc_core::sc_signal*<*T*> or to a *sc_core::sc_in*<*T*>
    - Abbreviation: ***sca_tdf::sc_in***<*T*>

  - ***sca_eln::sca_tdf::sca_voltage*** – is a voltage source which is controlled by a TDF input
    - Abbreviation: ***sca_eln::sca_tdf_voltage***

  - ***sca_lsf::sca_de::sca_source*** – is a linear signal flow source controlled by a SystemC signal (*sc_core::sc_signal*<*double*>)
    - Abbreviation: ***sca_lsf::sca_de_source***

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Include systemc-ams versus systemc-ams.h

- ***systemc-ams*** includes *systemc* and all SystemC-AMS class, symbol and macro definitions

- ***systemc-ams.h*** includes *systemc-ams* and *systemc.h* and adds all symbols of the following namespaces to the global namespace (by e.g. use *sca_util::sca_complex*;)
  - *sca_ac_analysis*
  - *sca_core*
  - *sca_util*

- *Note: Symbols of MoC related namespaces are not added*

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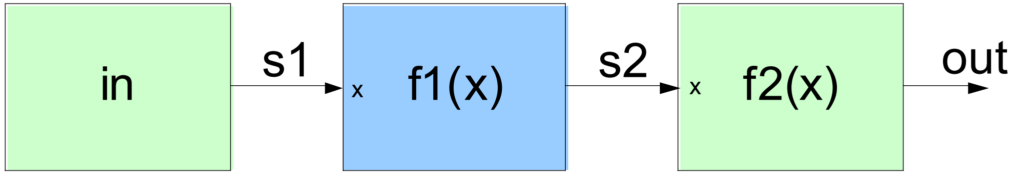
Timed Dataflow - TDF

Dataflow Basics



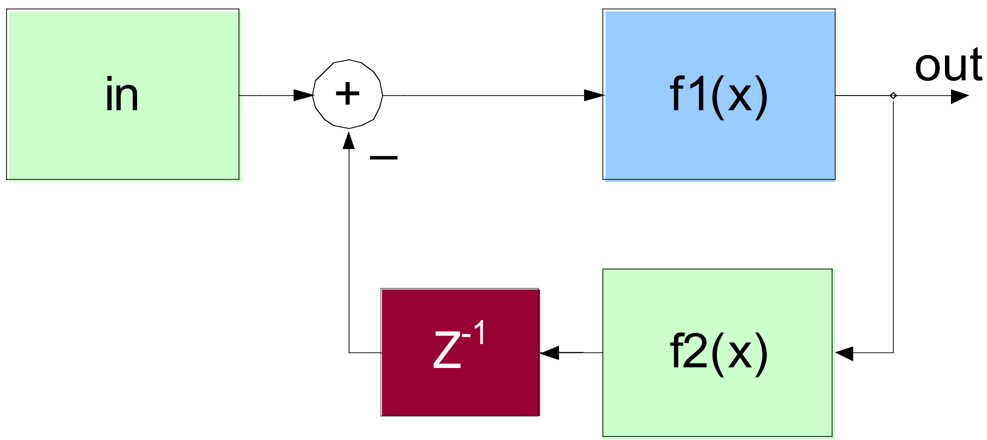
equation system:

s1 = in
s2 = f1(s1)
out = f2(s2)

out = f2(f1(in))

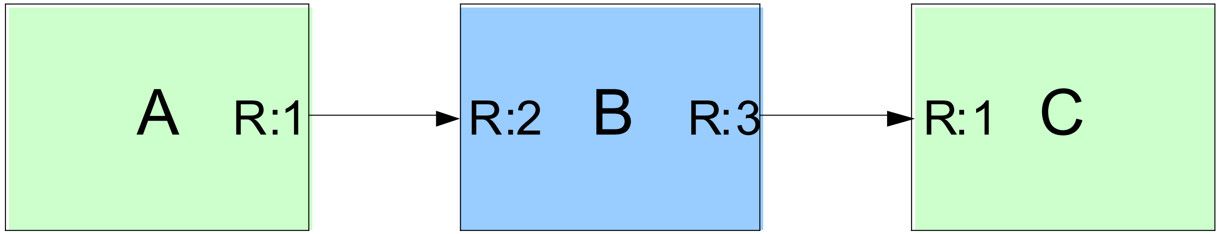
- Simple firing rule: A module is executed if enough samples available at its input ports
- The function of a module is performed by
  - reading from the input ports (thus consuming samples),
  - processing the calculations and
  - writing the results to the output ports.
- For synchronous dataflow (SDF) the numbers of read/written samples are constant for each module activation.
- The scheduling order follows the signal flow direction.

Loops in Dataflow Graphs



- Graphs with loops require a delay to become schedulable
- A delay inserts a sample in the initialization phase

Multi Rate Dataflow Graphs



A A B C C C

- The number of read/write sample (rate) is for at least one port >1 -> multi rate

- The rates in loops must be consistent

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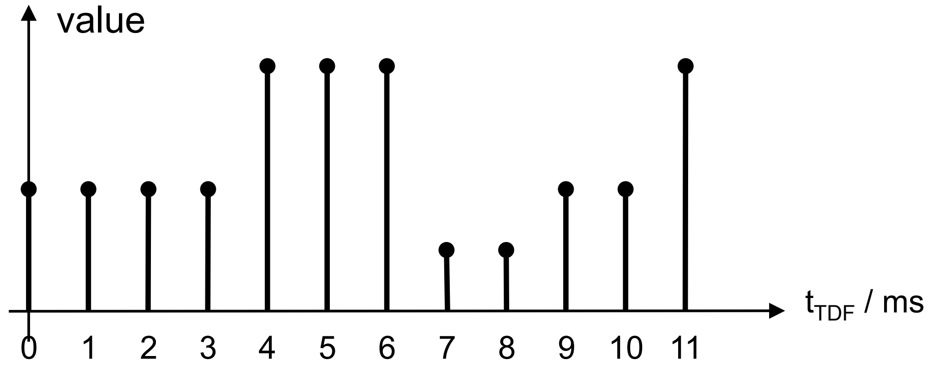
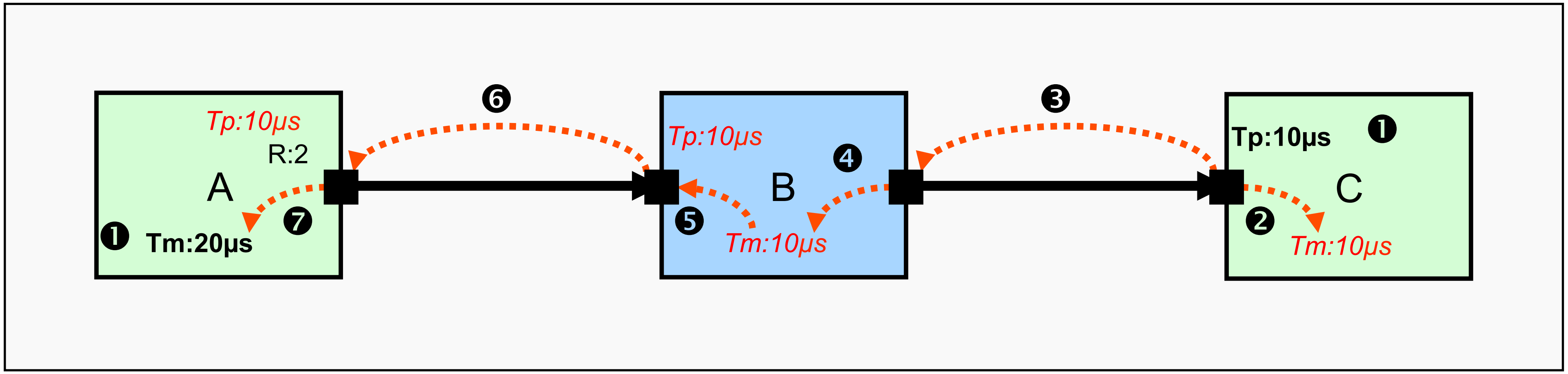
Timed Dataflow



- Dataflow is an untimed MoC
- Timed dataflow tags each sample and each module execution with an absolute time point
- Therefore the time distance (timestep) between two sample/two executions is assumed as constant
- This time distance has to be specified
- Enables synchronization with time driven MoC like SystemC discrete event and embedding of time dependent functions like a continous time transfer function

TDF – Timestep Propagation



- If more than one timestep assigned consistency will be checked

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TDF Attributes - Summarize

rate	Port attribute – number of sample for reading / writing during one module execution
delay	Port attribute – number of sample delay, number of samples to be inserted while initializing
timestep	Port and module attribute – time distance between two samples or two module activations

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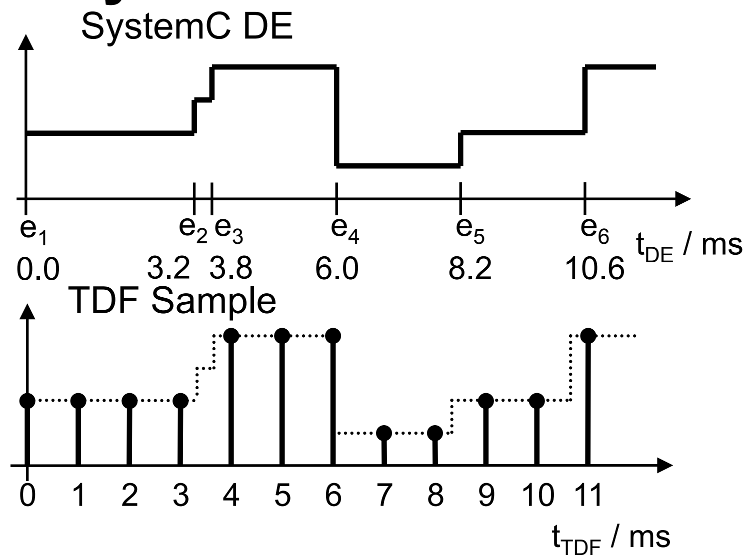
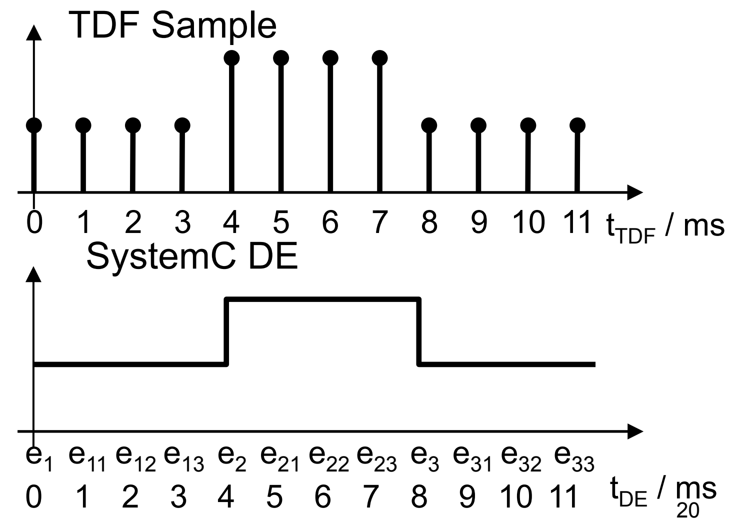
Synchronization between TDF and SystemC DE

- Synchronization between SystemC discrete event (DE) is done by converter ports
- They have the same attributes and access methods like usual TDF ports
- SystemC (DE) signals are sampled at the first Δ of the tagged TDF time point
- TDF samples are scheduled at the first Δ of the tagged TDF time (and thus valid at least at Δ=1).





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TDF Elaboration and Simulation

TDF module attribute settings:
Execute all **set_attributes** methods

↓

TDF time step calculation and propagation:
Define time step and check consistency

↓

TDF cluster computability check:
Define and check cluster schedule

TDF elaboration phase

↓

TDF module initialization:
Execute all **initialize** methods once

↓

TDF module activation and processing:
Continuously execute all **processing** methods

↓

TDF module post processing:
Execute all **end_of_simulation** methods once

TDF simulation phase

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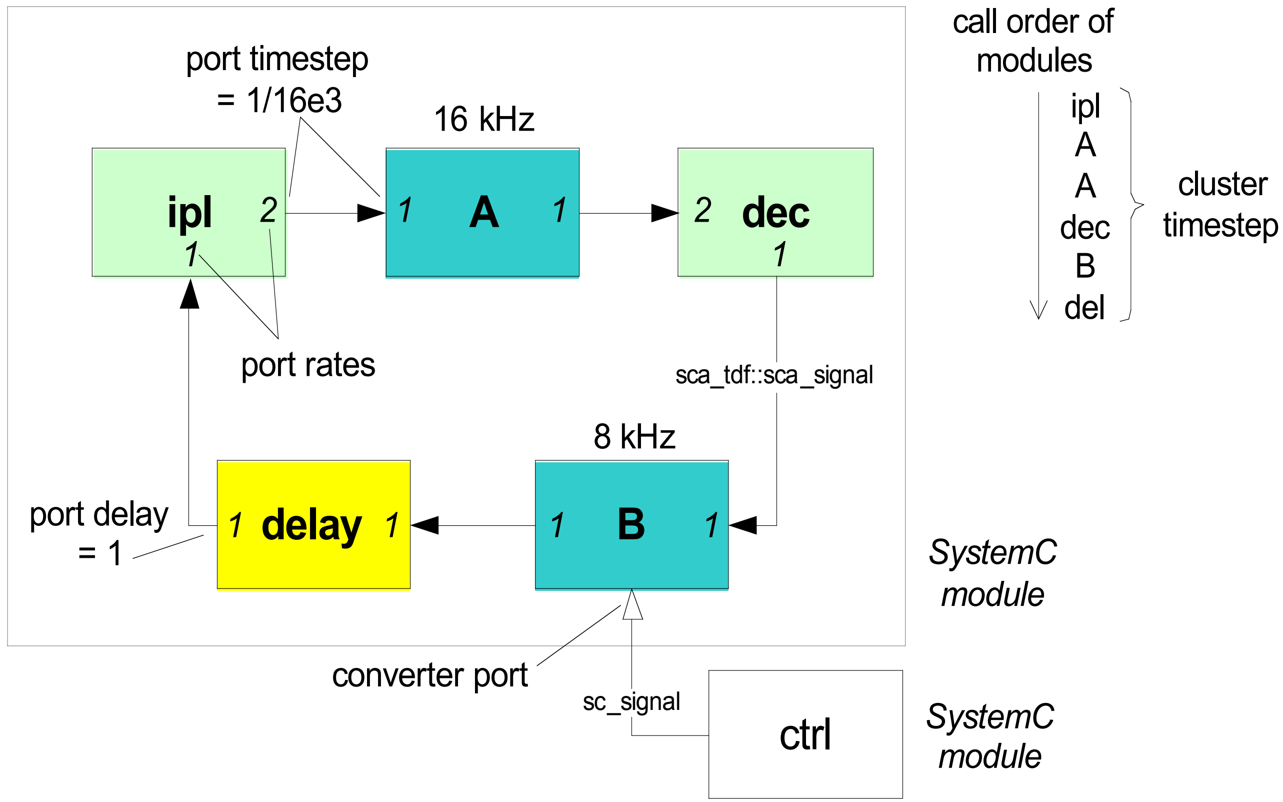
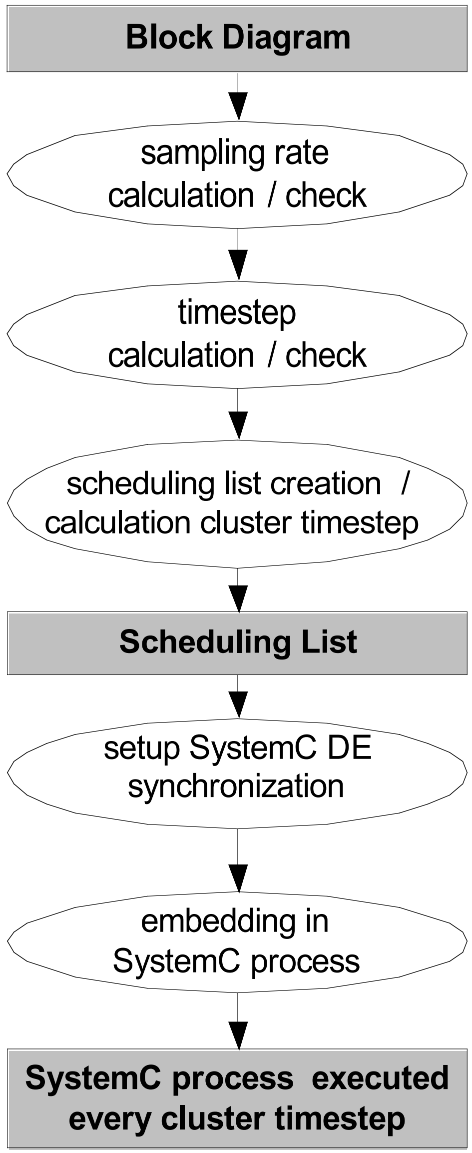
Summarize TDF MoC

cluster = set of connected TDF modules





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Timed Dataflow (TDF) Primitive Module

- Module declaration macros

```
SCA_TDF_MODULE(<name>)
struct <name>:
        public sca_tdf::sca_module
```

- Port declarations dataflow ports

```
sca_tdf::sca_in< <T> >,
sca_tdf_sca_out< <T> >
```

- Port declaration converter ports (for TDF primitives only)

```
sca_tdf::sc_in< <T> >,
sca_tdf::sc_out< <T> >
```

- Virtual primitive methods called by the simulation kernel – overloaded by the user defined tdf primitive

```
void set_attributes()
void initialize()
void processing()
void ac_processing()
```

- Methods for set/get module activation timestep

```
void set_timestep(const sca_time&);
sca_time get_time()
```

- Constructor macro / constructor

```
SCA_CTOR(<name>)
<name>(sc_module_name nm)
```


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Structure Timed Dataflow User defined Primitive

```
SCA_TDF_MODULE(mytdfmodel)    // create your own TDF primitive module
{
  sca_tdf::sca_in<double>  in1, in2;  // TDF input ports
  sca_tdf::sca_out<double> out;       // TDF output port

  void set_attributes()
  {
    // placeholder for simulation attributes
    // e.g. rate: in1.set_rate(2); or delay: in1.set_delay(1);
  }

  void initialize()
  {
    // put your initial values here e.g. in1.initialize(0.0);
  }

  void processing()
  {
    // put your signal processing or algorithm here
  }

  SCA_CTOR(mytdfmodel) {}
};
```

Set and get TDF Port Attributes

- Set methods can only be called in *set_attributes()*
- Get methods can be called in *initialize()* and *processing()*

- Sets / gets port rate (number of samples read/write per execution)

```
void set_rate(unsigned long rate)
unsigned long get_rate()
```

- Set/get number of sample delay

```
void set_delay(unsigned long nsamples)
unsigned long get_delay()
```

- Set time distance of samples get calculated/propagated time distance

```
void set_timestep(const sca_time&)
sca_time get_time_step()
```

- Get absolute sample time

```
sca_time get_time(unsigned long sample)
```

TDF Port read and write Methods

- Writes initial value to delay buffer
  - only allowed in *initialize()*
  - sample_id must be smaller than the number of delays
  - available for all in- and outports

```
void initialize(
        const T& value,
        unsigned long sample_id=0)
```

- Reads value from inport
  - only allowed in *processing()*
  - *sca_tdf::sca_in<T>* or *sca_tdf::sca_de::sca_in<T>*

```
const T& read(
             unsigned long sample_id=0)
operator const T&() const
const T& operator[]
       (unsigned long sample_id) const
```

- Writes value to outport
  - only allowed in *processing()*
  - *sca_tdf::sca_out<T>* or *sca_tdf::sca_de::sca_out<T>*

```
void write( const T& value,
            unsigned long sample_id=0)
… operator= (const T&)
… operator[](unsigned long sample_id)
```

First complete TDF Primitive Module

```
SCA_TDF_MODULE(mixer) // TDF primitive module definition
{
  sca_tdf::sca_in<double>  rf_in, lo_in; // TDF in ports
  sca_tdf::sca_out<double> if_out;       // TDF out ports

  void set_attributes()
  {
    set_timestep(1.0, SC_US); // time between activations
    if_out.set_delay(5);      // 5 sample delay at port if_out
  }

  void initialize()
  {  //initialize delay buffer (first 5 sample read by the
     //following connected module inport)
     for(unsigned int i=0; i<5; i++) if_out.initialize(0.0,i);
  }

  void processing()
  {
    if_out.write( rf_in.read() * lo_in.read() );
  }

  SCA_CTOR(mixer) {}
};
```

Linear Dynamic Behavior for TDF Models 1/2

- TDF Models can embed linear equation systems provided in the following three forms:

$$H(s) = \frac{b_n \cdot s^n + b_{n-1} \cdot s^{n-1} + \ldots + b_0}{a_m \cdot s^m + a_{m-1} \cdot s^{m-1} + \ldots + a_0}$$

- Linear transfer function in numerator / denumerator representation

$$H(s) = k \cdot \frac{(s - z_0) \cdot (s - z_1) \cdot \ldots \cdot (s - z_n)}{(s - p_0) \cdot (s - p_1) \cdot \ldots \cdot (s - p_n)}$$

- Linear transfer function in pole-zero representation

$$\dot{x} = Ax + Bu$$
$$y = Cx + Du$$

- State Space equations

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Linear Dynamic Behavior for TDF Models 2/2

- The equation systems will be represented and calculated by objects:
  - ***sca_tdf::sca_ltf_nd*** - Numerator / denumerator representation
  - ***sca_tdf::sca_ltf_zp*** - Pole-zero representation
  - ***sca_tdf::sca_ss*** - State space equations

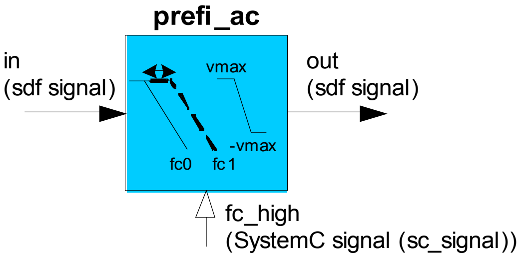
- The result is a continuous time signal represented by a “artificial” object (*sca_tdf::sca_ct_proxy* or *sca_tdf::sca_ct_vector_proxy*)
  - This object performs the time discretization (sampling) in dependency of the context – this makes the usage more comfortable and increases the accuracy
  - This mechanism permits additionally a very fast calculation for multi-rate systems

TDF Module – Example with LTF

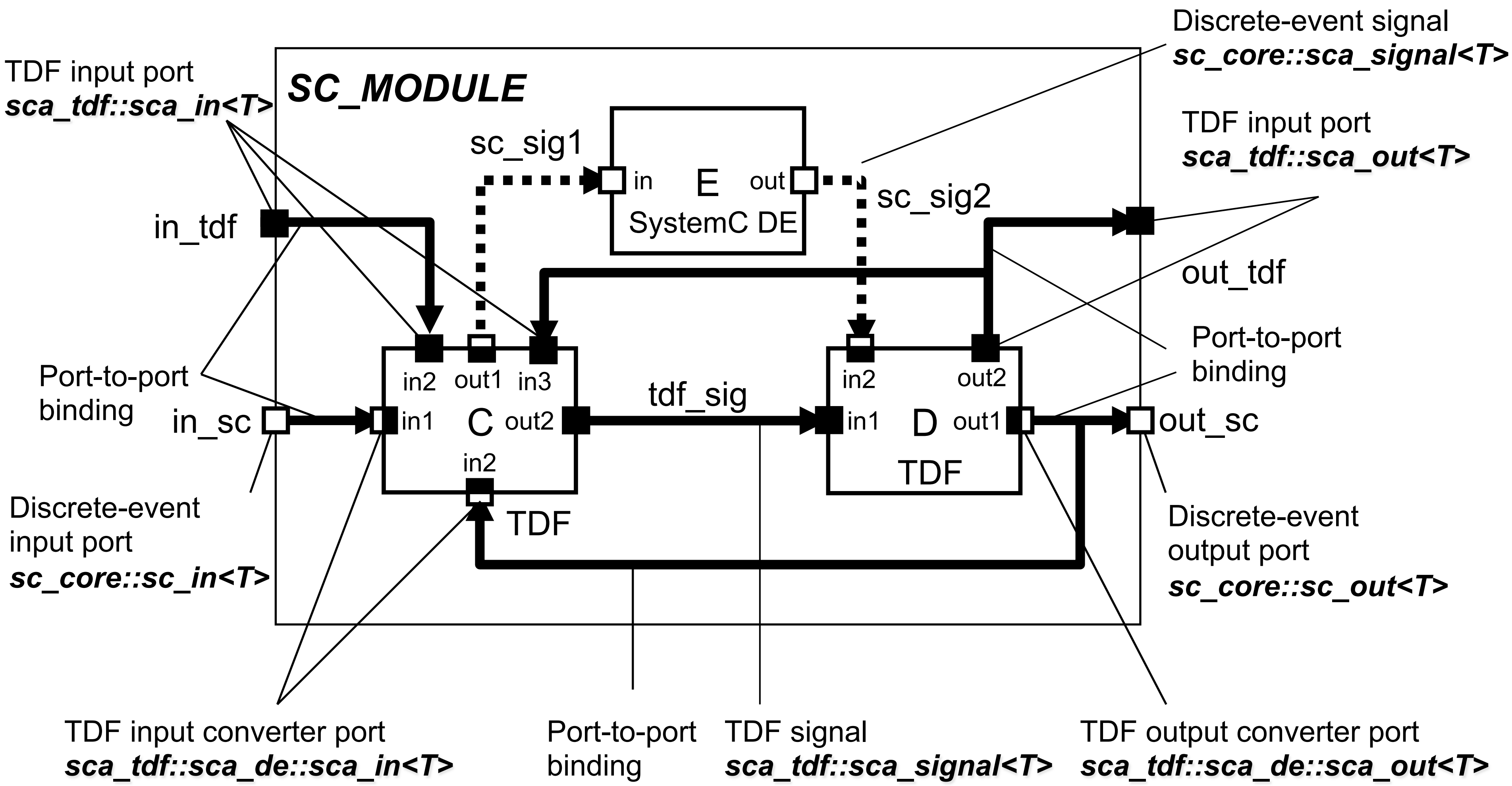
```
SCA_TDF_MODULE(prefi_ac)
{
  sca_tdf::sca_in<double>  in;
  sca_tdf::sca_out<double> out;

  //control / DE signal from SystemC
  //(connected to sc_signal<bool>)
  sca_tdf::sc_in<bool>   fc_high;

   double fc0, fc1, v_max;

    //filter equation objects
   sca_tdf::sca_ltf_nd ltf_0, ltf_1;
   sca_util::sca_vector<double> a0,a1,b;
   sca_util::sca_vector<double> s;

  void initialize()
  {
    const double r2pi = M_1_PI * 0.5;
    b(0) = 1.0;      a1(0)=a0(0)= 1.0;
    a0(1)= r2pi/fc0; a1(1) = r2pi/fc1;
  }
```

```
void processing()
{
  double tmp;
  //high or low cut-off freq.
  if(fc_high)   tmp = ltf_1(b,a1,s,in);
  else          tmp = ltf_0(b,a0,s,in);

  //output value limitation
  if      (tmp >  v_max)  tmp =  v_max;
  else if (tmp < -v_max)  tmp = -v_max;

    out.write(tmp);
 }

  SCA_CTOR(prefi_ac)
  {  //default parameter values
   fc0 = 1.0e3; fc1=1.0e5; v_max=1.0;
  }
};
```

$$H(s) = \frac{1}{1 + \frac{1}{2\pi f_c} s}$$



TDF Model Composition



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Hierarchical Module

```
SC_MODULE(my_hierarchical)
{
  sca_tdf::sca_in<int>      in_tdf;
  sca_tdf::sca_out<double> out_tdf;

  sc_in<double>  in_sc;
  sc_out<bool>   out_sc;

  sc_signal<double>    sc_sig1;
  sc_signal<sc_logic> sc_sig2;

  sca_tdf::sca_signal<bool> tdf_sig;


  module_tdf_c* tdf_c;
  module_tdf_d* tdf_d;
  module_sc_e*  e_sc;
```

```
SC_CTOR(my_hierarchical)
{
 tdf_c=new module_tdf_c(“tdf_c”);
   tdf_c->in1(in_sc);
   tdf_c->in2(in_tdf);
   tdf_c->in3(out_tdf);
   tdf_c->out1(sc_sig1);
   tdf_c->out2(tdf_sig);
 tdf_d=new module_tdf_d(“tdf_d”);
   tdf_d->in1(tdf_sig);
   tdf_d->in2(sc_sig2);
   tdf_d->out1(out_sc);
   tdf_d->out2(out_tdf);
 e_sc = new module_sc_e(“e_sc”);
   e_sc->in(sc_sig1);
   e_sc->out(sc_sig2);
}
};
```

Linear Signalflow - LSF

Linear Signalflow (LSF) Modeling

- Library of predefined elements
- Permits the description of arbitrary linear equation systems
- Several converter modules to/from TDF and SystemC (*sc_core::sc_signal*)
- Models for switching behavior like mux / demux

- LSF models are always hierarchical models

- Ports:
  - *sca_lsf::sca_in* - input port
  - *sca_lsf::sca_out* - output port
- Channel / Signal:
  - *sca_lsf::sca_signal*

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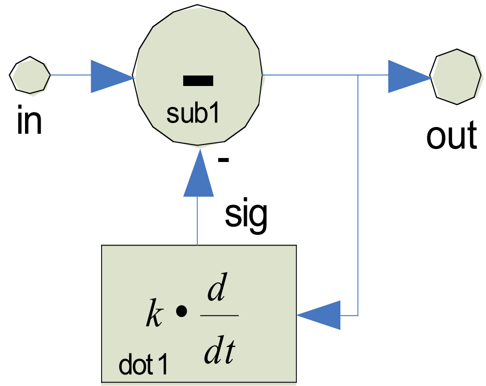
LSF predefined modules

- *sca_lsf::sca_add*
- *sca_lsf::sca_sub*
- *sca_lsf::sca_gain*
- *sca_lsf::sca_dot*
- *sca_lsf::sca_integ*
- *sca_lsf::sca_delay*
- *sca_lsf::sca_source*
- *sca_lsf::sca_ltf_nd*
- *sca_lsf::sca_ltf_zp*
- *sca_lsf::sca_ss*

- *sca_lsf::sca_tdf::sca_source (sca_lsf::sca_tdf_source)*
- *sca_lsf::sca_tdf::sca_gain (sca_lsf::sca_tdf_gain)*
- *sca_lsf::sca_tdf::sca_mux (sca_lsf::sca_tdf_mux)*
- *sca_lsf::sca_tdf::sca_demux (sca_lsf::sca_tdf_demux)*
- *sca_lsf::sca_tdf::sca_sink (sca_lsf::sca_tdf_sink)*
- *sca_lsf::sca_de::sca_source (sca_lsf::sca_de_source)*
- *sca_lsf::sca_de::sca_gain (sca_lsf::sca_de_gain)*
- *sca_lsf::sca_de::sca_mux (sca_lsf::sca_de_mux)*
- *sca_lsf::sca_de::sca_demux (sca_lsf::sca_de_demux)*
- *sca_lsf::sca_de::sca_sink (sca_lsf::sca_de_sink)*

Example: LSF language constructs

```
SC_MODULE(mylsfmodel)   // create a model using LSF primitive modules
{
  sca_lsf::sca_in  in;    // LSF input port
  sca_lsf::sca_out out;   // LSF output port

  sca_lsf::sca_signal sig;    // LSF signal

  sca_lsf::sca_dot* dot1;  //declare module instances
  sca_lsf::sca_sub* sub1;

  mylsfmodel(sc_module_name, double fc=1.0e3)
  {
    // instantiate predefined primitives
    dot1 = new sca_lsf::sca_dot("dot1", 1.0/(2.0*M_PI*fc) );
    dot1->x(out);
    dot1->y(sig); // parameters

    sub1 = new sca_lsf::sca_sub("sub1");
    sub1->x1(in);
    sub1->x2(sig);
    sub1->y(out);

  } };
```



Electrical Linear Networks - ELN

Electrical Linear Network (ELN) Modeling

- Library of predefined elements
- Permits the description of arbitrary linear electrical network
- Several converter modules to/from TDF and SystemC (*sc_core::sc_signal*)
- Models for switching behavior like switches

- ELN models are always hierarchical models

- Ports:
  - *sca_eln::sca_terminal* - conservative terminal
- Channel / Node:
  - *sca_eln::sca_node* – conservative node
  - *sca_eln::sca_node_ref* – reference node, node voltage is always zero

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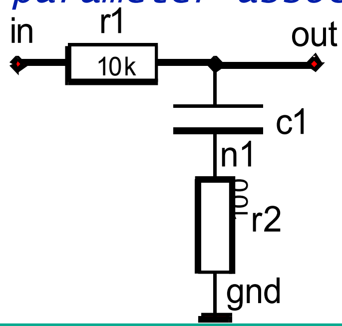
ELN predefined elements

- *sca_eln::sca_r*
- *sca_eln::sca_l*
- *sca_eln::sca_c*
- *sca_eln::sca_vcvs*
- *sca_eln::sca_vccs*
- *sca_eln::sca_ccvs*
- *sca_eln::sca_cccs*
- *sca_eln::sca_nullor*
- *sca_eln::sca_gyrator*
- *sca_eln::sca_ideal_transformer*
- *sca_eln::sca_transmission_line*
- *sca_eln::sca_vsource*
- *sca_eln::isource*

- *sca_eln::sca_tdf::sca_vsink*
  - *sca_eln::sca_tdf_vsink*
- *sca_eln::sca_tdf::sca_vsource*
  - *sca_eln::sca_tdf_vsource*
- *sca_eln::sca_tdf::sca_isource*
  - *sca_eln::sca_tdf_isource*
- *sca_eln::sca_de::sca_vsource*
  - *sca_eln::sca_de_vsource*
- *sca_eln::sca_de::sca_isource …*
- *sca_eln::sca_tdf::sca_r …*
- *sca_eln::sca_tdf::sca_l …*
- *sca_eln::sca_tdf::sca_c …*
- *sca_eln::sca_de::sca_r …*
- *sca_eln::sca_de::sca_l …*
- *sca_eln::sca_de::sca_c …*
- *...*

Example: ELN language constructs

```
SC_MODULE(myelnmodel)              // model using ELN primitive modules
{
  sca_eln::sca_terminal in, out; // ELN terminal (input and output)

  sca_eln::sca_node     n1;      // ELN node
  sca_eln::sca_node_ref gnd;     // ELN reference node

  sca_eln::sca_r *r1, *r2;
  sca_eln::sca_c *c1;

  SC_CTOR(myelnmodel)                   // standard constructor
  {
    r1 = new sca_eln::sca_r(“r1”);  // instantiate predefined
    r1->p(in);                      // primitive here (resistor)
    r1->n(out);
    r1->value = 10e3;               //named parameter association

    c1 = new sca_eln::sca_c(“c1”, 100e-6); //positional parameter association
    c1->p(out);
    c1->n(n1);

    r2 = new sca_eln::sca_r(“r2”,100.0);
    r2->p(n1);
    r2->n(gnd);
}};
```



Types of Analysis

Analysis Types

- Transient time domain is driven by the SystemC kernel
  - thus the SystemC ***sc_core::sc_start*** command controls the simulation

- Two different kinds of small-signal frequency-domain analysis (AC analysis) are available
  - AC-analysis
  - AC-noise-analysis

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Small Signal Frequency Domain Analysis (AC-Analysis)

- AC-analysis:
  - Calculates linear complex equation system stimulated by AC-sources
- AC noise domain
  - solves the linear complex equation system for each noise source contribution (other source contributions will be neglected)
  - adds the results arithmetically
- ELN and LSF description are specified in the frequency domain
- TDF description must specify the linear complex transfer function of the module inside the method *ac_processing* (otherwise the out values assumed as zero)
- This transfer function can depend on the current time domain state (e.g. the setting of a control signal)

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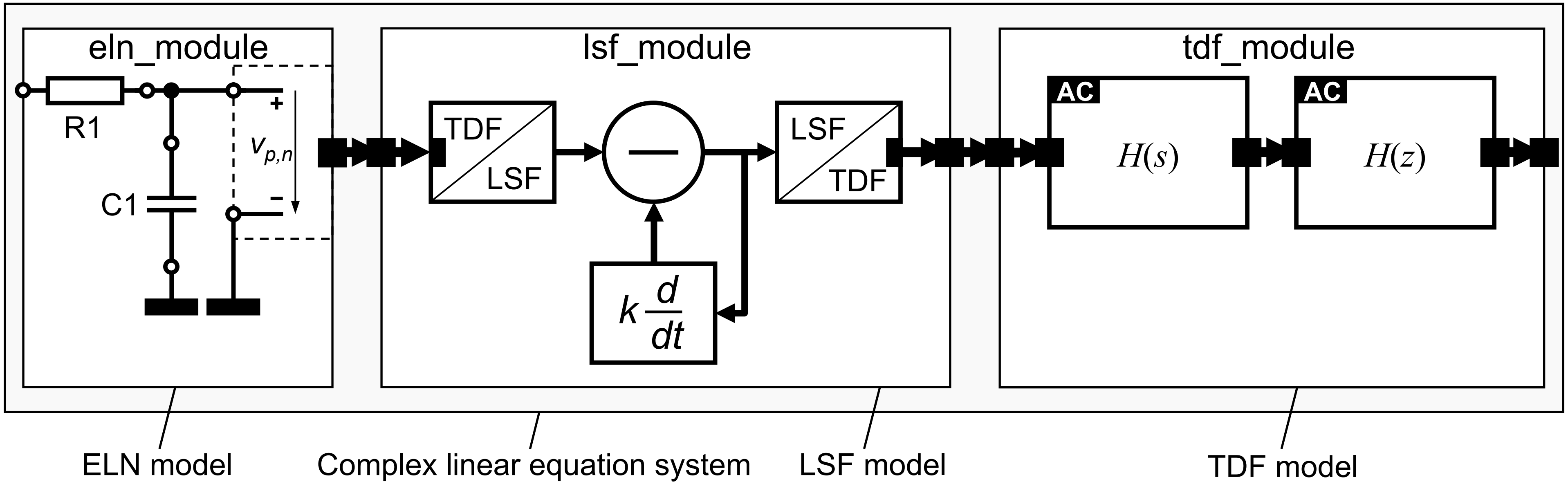
Small-Signal Frequency-Domain Analysis



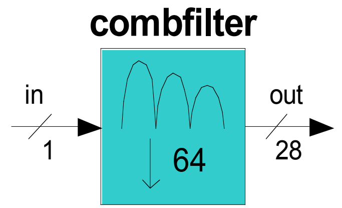
Linear equation system contribution for LSF/ELN:

$$q(t) = Adx + Bx \;\; \text{->} \;\; q(f) = Ajwx(f) + Bx(f)$$

Sources

Frequency Domain Description for TDF Models

```
SCA_TDF_MODULE(combfilter)
{
  sca_tdf::sca_in<bool>          in;
  sca_tdf::sca_out<sc_int<28> > out;

  void set_attributes()
  {
    in.set_rate(64);   // 16 MHz
    out.set_rate(1);   // 256 kHz
  }

  void ac_processing()
  {
    double      k  = 64.0;
    double      n  =   3.0;

    // complex transfer function:
    sca_complex h;
    h = pow( (1.0 - sca_ac_z(-k)) /
             (1.0 - sca_ac_z(-1)),n);

    sca_ac(out) = h * sca_ac(in) ;
  }

void processing()
{
      int x, y, i;
      for (i=0; i<64; ++i) {
          x = in.read(i);
      …
      out.write(y);
}

  SCA_CTOR(combfilter)
  {
      …
  }
};
```



$$H(z) = \left(\frac{1 - z^{-k}}{1 - z^{-1}}\right)^n \qquad z = e^{j2\pi f / f_s}$$

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Simulation Control and Debugging

Tracing of analog Signals

- SystemC AMS has a own trace mechanism:
  - Analog / Digital timescales are not always synchronized
  - Note: the VCD file format is in general inefficient for analog
- Traceable are:
  - all *sca_<moc>::sca_signal*'s, *sca_eln::sca_node* (voltage) and sc_core::sc_signals
  - Most ELN modules – the current through the module
  - ports and terminals (traces the connected node or signal)
  - for TDF a traceable variable to trace internal model states

- Two formats supported:
  - Tabular trace file format - ***sca_util::sca_create_tabular_trace_file***
  - VCD trace file format - ***sca_util::sca_create_vcd_trace_file***

- Features to reduce amount of trace data:
  - enable / disable tracing for certain time periods, redirect to different files
  - different trace modes like: sampling / decimation

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Viewing Wave Files

- Simple Tabular Format:

```
%time name1 name2  ...
   0.0     1           2.1    …
   0.1     1e2       0.3    …
    :          :            :       :
```

- A lot of tools like gwave or gaw can read this format
- Can be load directly into Matlab/Octave by the load command:

  load result.dat
  plot(result(:,1), result(:,2));   %plot the first trace versus time
  plot(result(:,1), result(:,2:end)); %plot all waves versus time

- For compatibility with SystemC the vcd Format is available
  - however it is not well suited to store analogue waves
  - VCD waveform viewers usually handle analogue waves badly

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Simulation Control

- Time domain – no difference to SystemC
  - **sc_start(10.0,SC_MS);** *// run simulation for 10 ms*
  - **sc_start();** *//run simulation forever or sc_stop() is called*

- AC-domain / AC-noise-domain
  - Run simulation from 1Hz to 100kHz, calculate 1000 points logarithmically spaced:
    - ***sca_ac_start(1.0,100e3,1000,SCA_LOG);*** // ac-domain
    - ***sca_ac_noise_start(1.0,100e3,1000,SCA_LOG);*** //ac-noise domain
  - Run simulation at frequency points given by a std::vector<double>:
    - ***sca_ac_start(frequencies);*** *// ac-domain*
    - ***sca_ac_noise_start(frequencies);*** *//ac-noise domain*

SystemC AMS Testbench 1/2

```
#include <systemc-ams.h>
           :
int sc_main(int argn,char* argc)
{
  //instantiate signals, modules, … from arbitrary domains e.g.:
  sca_tdf::sca_signal<double> s1;
  sca_eln::sca_node           n1;
  sca_lsf::sca_signal         slsf1;
  sca_core::sca_signal<bool>  scsig1;
                 :
  dut i_dut("i_dut");
    i_dut->inp(s1);
    u_dut->ctrl(scsig1);
            :
sc_trace_file* sctf=sc_create_vcd_trace_file("sctr");
   sc_trace(sctf,scsig1,"scsig1"); …
```

SystemC AMS Testbench 2/2

```
sca_trace_file* satf=sca_create_tabular_trace_file("tr.dat");
 sca_trace(satf,n1,"n1"); …

 sc_start(2.0,SC_MS); //start time domain simulation for 2ms
 satf->disable();     //stop writing
 sc_start(2.0,SC_MS); //continue 2ms
 satf->enable();      //continue writing
 sc_start(2.0,SC_MS); //continue 2ms

 //close time domain file, open ac-file
 satf->reopen("my_tr_ac.dat");

 sca_ac_start(1.0,1e6,1000,SCA_LOG); //calculate ac at current op

 //reopen transient file, append
 satf->reopen("mytr.dat",std::ios::app);

 //sample results with 1us time distance
 satf->set_mode(sca_sampling(1.0,SC_US));

 sc_start(100.0,SC_MS); //continue time domain

 sc_close_vcd_trace_file(sctf);       //close SystemC vcd trace file
 sca_close_tabular_trace_file(satf);  //close tabular trace file

}
```

Proof-of-Concept Implementation

Getting Started

1. Download systemc from www.systemc.org and the SystemC-AMS proof-of-concept from http://systemc-ams.eas.iis.fraunhofer.de
2. Install the libraries for Linux, Solaris, Windows/MinGW or Windows/cygwin (preferable 32 Bit) , and preferable gcc > 4.x required (read readme for details)
   - tar –xzvf systemc.tar.gz
   - cd systemc
   - configure
   - make; make install
   - setenv SYSTEMC_PATH <your install dir> -> may insert in your .cshrc

   - tar –xzvf systemc_ams.tar.gz
   - cd systemc_ams
   - configure
   - make; make install
   - setenv SYSTEMC_AMS_PATH <your install dir> -> may insert in your .cshrc

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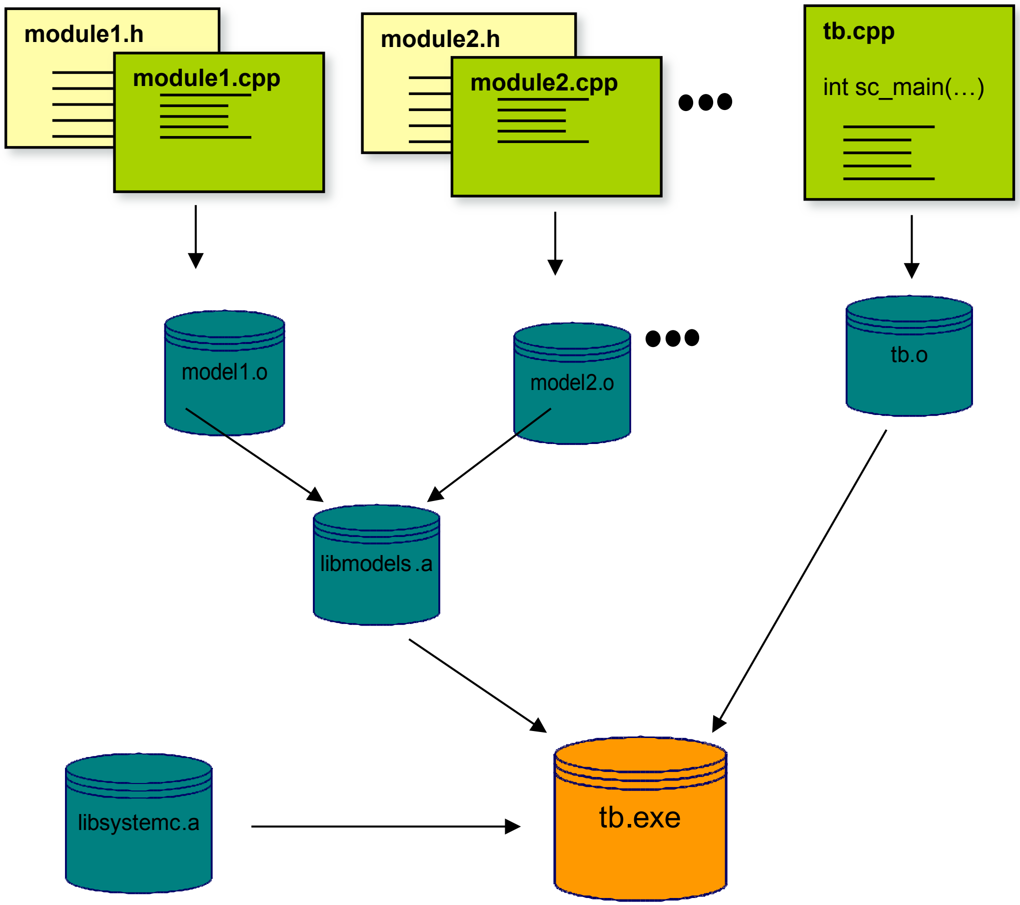
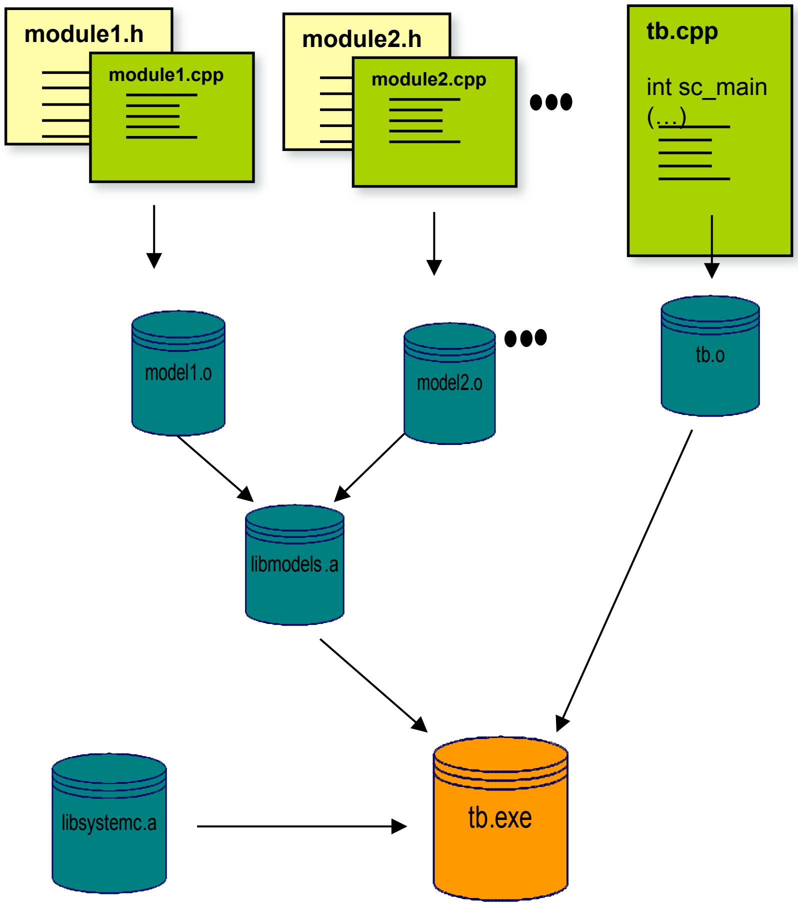
Getting Started SystemC Files



Recommendations:

- Split the module description into a header and a cpp implementation file
- Only one module per header / cpp file
- The name of the module shall be equal to the header / cpp file name
- Do not use capital letters and special characters (like ä,%,&, space, …)

SystemC / SystemC-AMS Compilation



g++ -c module1.cpp –I${SYSTEMC_PATH}/include \
–I${SYSTEMC_AMS_PATH}/include

g++ -c module2.cpp –I${SYSTEMC_PATH}/include \
–I${SYSTEMC_AMS_PATH}/include

ar –rcs libmodels.a module1.o module2.o

g++ -c tb.cpp –I${SYSTEMC_PATH}/include \
–I${SYSTEMC_AMS_PATH}/include

uppercase i

g++ tb.o –L${SYSTEMC_PATH}/lib-{TARGET_ARCH} \
–L${SYSTEMC_AMS_PATH}/lib-{TARGET_ARCH}
-L. –o tb.exe –lmodels –lsystemc-ams -lsystemc

lowercase L !!! Library order Important !!!

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More …

- www.systemc.org
- www.systemc-ams.org
- www.systemc-ams.eas.iis.fraunhofer.de

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