```
In [1]:
          import pyro
          import pyro.distributions as dist
          from pyro.infer import Importance, EmpiricalMarginal
          import matplotlib.pyplot as plt
          import torch
          import numpy as np
          import pandas as pd
          import random
In [2]:
         # Giving the alias and cpt tables for the model
         X_alias = ["promotion0", "promotion1"]
Y_alias = ["not-renewed", "renewed"]
          Z alias = ["unhappy", "happy"]
          Z \text{ prob} = \text{torch.tensor}([0.5092, 0.4908])
          X \text{ prob} = \text{torch.tensor}([[0.247, 0.753], [0.763, 0.237]])
          Y \text{ prob} = \text{torch.tensor}([[[0.068, 0.932], [0.267, 0.733]],
                                   [[0.131, 0.869], [0.313, 0.687]]])
```

2.1.a

Build the model with Pyro using the values in the table. Use pyro.condition to calculate the causal effect by adjusting for happiness. (5 points)

```
In [3]: def model():
    Z = pyro.sample("Z", dist.Categorical(probs=Z_prob))
    X = pyro.sample("X", dist.Categorical(probs=X_prob[Z]))
    Y = pyro.sample("Y", dist.Categorical(probs=Y_prob[X][Z]))
    return{'X': X, 'Y': Y, 'Z': Z}
```

You are interested in the average causal effect P(Y = 1|do(X = 0)) - P(Y = 1|do(X = 1))

```
In [4]: def adjustmentFormula(x_cond, z_probs):
    Z_conditons=[{'Z':torch.tensor(0)}, {'Z': torch.tensor(1)}]
    effect = 0.0
    for idx in range(len(z_probs)):
        data = {}
        data.update(x_cond)
        data.update(Z_conditons[idx])

        conditioned_model = pyro.condition(model, data= data)
        T_samples = [conditioned_model()['Y'] for _ in range(1000)]
        T_unique, T_counts = np.unique(T_samples, return_counts=True)
        Y_prob = T_counts[1]/ 1000
        effect += (Y_prob * z_probs[idx])
    return effect
```

```
In [5]: effect_Y1_X0 = adjustmentFormula({"X": torch.tensor(0)}, [0.5092, 0.4
908])

In [6]: effect_Y1_X1 = adjustmentFormula({"X": torch.tensor(1)}, [0.5092, 0.4
908])

In [7]: effect_Y1_X0 - effect_Y1_X1

Out[7]: 0.05323920000000004
```

2.1.b

Use pyro.do to calculate the causal effect by adjusting for happiness. (5 points)

```
In [8]: def interventionUsingDo(x_cond):
    intervention_model = pyro.do(model, data = x_cond)
    Y_posterior_intervened = pyro.infer.Importance(intervention_model
    , num_samples=10000).run()
    Y_marginal_intervened = EmpiricalMarginal(Y_posterior_intervened,
    "Y")
    Y_samples_intervened = [Y_marginal_intervened().item() for _ in r
    ange(10000)]
    Y_unique_intervened, Y_counts_intervened = np.unique(Y_samples_intervened, return_counts=True)
    return Y_counts_intervened[1]/len(Y_samples_intervened)

In [9]: effect_Y1_X0_do = interventionUsingDo({'X': torch.tensor(0)})

In [10]: effect_Y1_X1_do = interventionUsingDo({'X': torch.tensor(1)})

In [11]: effect_Y1_X0_do - effect_Y1_X1_do

Out[11]: 0.059599999999999986
```

Both the causal effect obtained in 2.1.a and 2.a.b are similar.

2.2

You are a data scientist investigating the effects of social media use on purchasing a product. You assume the dag shown below. User info here is unobserved. One of the team members argues that social media usage does not drive purchase based on Table 1. Only 15% social media user made the purchase, while 90.25% non social media users made the purchase. Moreover, within each group, no-adblock and adblock, social media users show a much lower rate of purchase than non social media users. However, another team member argues that social media usage increases purchases. When we look at each group, social media user and non social media user as show in Table 2 (Table 1 and Table 2 both represent the same dataset), advertisement increases purchases in both groups. Among social media users, purchases increases from 10% to 15% for people who have seen advertisement. Among non social media users, purchases increases from 90% to 95% for people who have seen advertisement. Which view is right?

```
In [12]: # Giving the alias and cpt tables for the model
X_alias = ["no-social", "social"]
Y_alias = ["no-ad", "ad"]
Z_alias = ["no-purchase", "purchase"]

X2_prob = torch.tensor([0.5, 0.5])
Z2_prob = torch.tensor([[0.95, 0.05], [0.05, 0.95]])
Y2_prob = torch.tensor([[0.14, 0.86], [0.81, 0.19]])

def socialMediaModel():
    X_2 = pyro.sample("X2", dist.Categorical(probs=X2_prob))
    Z_2 = pyro.sample("Z2", dist.Categorical(probs=Z2_prob[X_2]))
    Y_2 = pyro.sample("Y2", dist.Categorical(probs=Y2_prob[Z_2]))
    return{'X2': X_2, 'Y2': Y_2, 'Z2': Z_2}
```

2.2.a

User info is unobserved. Use <code>pyro.condition</code> to calculate the causal effect of social media on product purchase using front-door adjustment (Section 3.4 in Front Door Criterion (http://bayes.cs.ucla.edu/PRIMER/primer-ch3.pdf)).(5 points)

```
def frontDoorAdjustment(x conds, x prob, x idx):
              Z conditions = [{"Z2": torch.tensor(0)}, {"Z2": torch.tensor(1)}]
              cumProb = 0.0
              for idx in range(len(Z conditions)):
                  first condition = {}
                  first_condition.update(x_conds[x_idx])
                  z condition model = pyro.condition(fn=socialMediaModel, data
          = first condition)
                  Z_{samples} = [z_{condition_model()['Z2']} for _ in range(1000)]
                  Z_unique, Z_counts = np.unique(Z_samples, return_counts=True)
                  Z \text{ prob} = Z \text{ counts[idx]} / 1000
                  \# Finding the sum part for each z - iteration
                  innerProb = 0.0
                  for idx1 in range(len(x conds)):
                       second condition = {}
                       second condition.update(Z conditions[idx])
                       second condition.update(x conds[idx1])
                       y_condition_model = pyro.condition(socialMediaModel, data
          =second condition)
                      Y samples = [y condition model()['Y2'] for in range(100
          0)]
                      Y unique, Y counts = np.unique(Y samples, return counts=T
          rue)
                      Y \text{ prob} = Y \text{ counts}[1]/1000
                       innerProb += (Y_prob * x_prob[idx1])
                  cumProb += (Z prob * innerProb)
              return cumProb
In [14]: X_{\text{conds}} = [\{"X2": torch.tensor(0)\}, \{"X2": torch.tensor(1)\}]
          X \text{ prob } 1 = [0.5, 0.5]
         frontDoorAdjustment(X conds, X prob 1, 0) - frontDoorAdjustment(X co
In [15]:
          nds, X prob 1, 1)
```

2.2.b

Out[15]: 0.6186054999999999

Verify your result using do-calculus with pyro.do (P(Y = 1|do(X = 0)) - P(Y = 1|do(X = 1))) (5 points)

Both the causal effect obtained in 2.2.a and 2.2.b are similar

3.1 Defining the propensity function

```
In [18]: def propensity(x, z):
    return X_prob[z][x]

In [19]: propensity(0, 1)

Out[19]: tensor(0.7630)
```

3.2 Displaying the 10 samples generated for the model given in 2.1

```
In [20]:
         xs = []
          ys = []
          zs = []
          ps = []
          trace handler = pyro.poutine.trace(model)
          for i in range(1000):
              trace = trace handler.get trace()
              x = trace.nodes['X']['value']
              y = trace.nodes['Y']['value']
              z = trace.nodes['Z']['value']
              log prob = trace.log prob sum()
              p = np.exp(log prob)
              xs.append(int(x))
              vs.append(int(v))
              zs.append(int(z))
              ps.append(p)
          data = pd.DataFrame({"X": xs, "Y": ys, "Z": zs, "P": ps})
In [21]: data.head(10)
Out[21]:
             X Y Z
          0 1 1 0 tensor(0.3332)
          1 1 1 0 tensor(0.3332)
          2 0 1 1 tensor(0.2745)
            1 0 0 tensor(0.0502)
          4 1 1 0 tensor(0.3332)
          5 0 0 1 tensor(0.1000)
          6 1 1 0 tensor(0.3332)
          7 0 1 1 tensor(0.2745)
          8 1 1 1 tensor(0.0799)
```

3.3 Computing the inverse probability weighting using propensity score

9 0 1 1 tensor(0.2745)

```
In [22]: # Using the data generated above, i re-weight the joint probability b
y propensity.

data["inverse_weighted_prob"] = data.apply(lambda x: x["P"]/ (propens
ity(x["X"], x["Z"])), axis=1)
```

```
In [23]:
          data.drop_duplicates(subset=['X', 'Y', 'Z'], inplace=True)
           data.reset index(drop=True)
Out[23]:
              X Y Z
                                P inverse_weighted_prob
           0 1 1 0 tensor(0.3332)
                                          tensor(0.4425)
           1 0 1 1 tensor(0.2745)
                                          tensor(0.3598)
           2 1 0 0 tensor(0.0502)
                                          tensor(0.0667)
           3 0 0 1 tensor(0.1000)
                                          tensor(0.1310)
           4 1 1 1 tensor(0.0799)
                                          tensor(0.3372)
           5 0 1 0 tensor(0.1172)
                                          tensor(0.4746)
           6 1 0 1 tensor(0.0364)
                                          tensor(0.1536)
           7 0 0 0 tensor(0.0086)
                                          tensor(0.0346)
          combinations = data[['X', 'Y', 'Z']].apply(lambda x: x.to_dict(), axi
In [24]:
           s=1).values
In [25]: inv_weighted_prob = list(data["inverse_weighted_prob"])
```

3.4 Generating samples from the inverse weighting probability distribution

3.5 Checking whether the causal estimate is same as 2.1

```
In [28]: def filterIt(df, var, value):
    return df[df[var]==value]

In [29]: def computeProb(df, var, value):
    return sum(df[var]==value)/(df.shape[0])
```

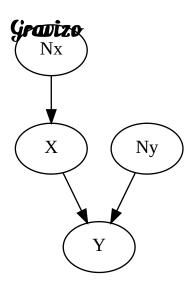
```
In [30]: def causalEffect(df, xval):
    cumProb = 0.0
    for z in range(df["Z"].nunique()):
        ydf = filterIt(filterIt(df, "Z", z), "X", xval)
        yprob = computeProb(ydf, "Y", 1)
        zprob = computeProb(df, "Z", z)
        cumProb+= (yprob * zprob)
    return cumProb
In [31]: causalEffect(weighted_samples, 0) - causalEffect(weighted_samples, 1)
Out[31]: 0.06200804901366552
```

The causal estimate is similar to what is obtained in 2.1

4.1 Defining the model and generating 10 samples

```
In [32]: def scm1():
             X = pyro.sample('X', dist.Normal(0.0, 1.0))
             Y = X ** 2 + pyro.sample('Ny', dist.Normal(0.0, 1.0))
             Y = pyro.sample('Y', dist.Normal(Y, 0.001))
             return X, Y
In [33]:
         trace scm = pyro.poutine.trace(scm1)
         for _{\rm in} range(10):
             trace = trace_scm.get_trace()
             x = trace.nodes['X']['value']
             y = trace.nodes['Y']['value']
             print(f' The value of x is \{x\} and the value of y is \{y\}')
          The value of x is -0.5521014332771301 and the value of y is 2.854936
         5997314453
          The value of x is -0.08818693459033966 and the value of y is 0.83122
         49183654785
          The value of x is 0.5461435317993164 and the value of y is 0.1130787
         804722786
          The value of x is -0.18929176032543182 and the value of y is -0.9127
         78913974762
          The value of x is 0.41813671588897705 and the value of y is -1.56906
         48555755615
          The value of x is -0.2518658936023712 and the value of y is -1.13973
         67715835571
          The value of x is 0.09925052523612976 and the value of y is 0.871267
         3783302307
          The value of x is 1.3132648468017578 and the value of y is 0.6808860
         898017883
          The value of x is 1.1282209157943726 and the value of y is 0.7220373
         749732971
          The value of x is -1.107576847076416 and the value of y is 1.1398751
         735687256
```

4.2.a The DAG can be represented as



4.2.b

- 1. The mean of the distribution P_Y^M is 0 2. The variance of the distribution P_Y^M is 17
- 3. Y = 4 * N(0,1) + N(0,1) --> The variance gets squared when there's a multiplicative factor. --> 16 + 1 --> 17

4.2.c

- 1. The mean of the distribution $P_Y^{M:do(X=2)}$ is 8 2. The variance of the distribution $P_Y^{M:do(X=2)}$ is 1
- 3. Y = 4 * 2 (setting the value of x = 2) + 0 --> Mean.

4.2.d

1. The distribution $P_Y^{M:X=2}$ doesn't differ from $P_Y^{M:do(X=2)}$ distribution because there isn't any other source that affects X. So, conditioning it or intervening on it doesn't make any difference.

4.2.e is answered in the end, as the image is attached separately.

4.2.f

1. The mean of the distribution $P_X^{M:do(Y=2)}\,$ is 0

In [34]: **def** scm2():

- 2. The variance of the distribution $P_X^{M:do(Y=2)}$ is 1
- 3. Since the sources of Y are removed. The values of X doesn't affect Y in any way. Hence the mean and variance of X remains same

4.2.g

```
X = pyro.sample('X', dist.Normal(0.0, 1.0))
    Y = 4 * X + pyro.sample('Ny', dist.Normal(0.0, 1.0))
    Y = pyro.sample('Y', dist.Normal(Y, 0.001))
    return X, Y
trace scm = pyro.poutine.trace(scm2)
for _{\rm in} range(10):
    trace = trace scm.get trace()
    x = trace.nodes['X']['value']
    y = trace.nodes['Y']['value']
    print(f' The value of x is \{x\} and the value of y is \{y\}')
The value of x is 1.3833633661270142 and the value of y is 5.7381381
98852539
The value of x is 0.07725183665752411 and the value of y is 0.390086
7700576782
The value of x is -0.7231635451316833 and the value of y is -3.64859
79557037354
The value of x is -1.0205142498016357 and the value of y is -3.05001
3542175293
The value of x is 0.13883854448795319 and the value of y is 0.666816
9498443604
The value of x is 0.6039068698883057 and the value of y is 1.5654387
474060059
The value of x is 1.5974762439727783 and the value of y is 7.4561481
47583008
The value of x is -0.814222514629364 and the value of y is -2.912876
844406128
The value of x is 0.9170505404472351 and the value of y is 2.8552155
49468994
The value of x is 0.5865408778190613 and the value of y is 2.7083709
239959717
```

```
In [35]: conditioned model = pyro.poutine.do(scm2, data={"X": torch.tensor(2.0)
         )})
In [36]: traced model = pyro.poutine.trace(conditioned model)
         y_vals = []
In [37]:
         for _ in range(100):
             trace = traced model.get trace()
             v = trace.nodes['Y']['value']
             y vals.append(y)
In [38]: plt.hist(y vals)
Out[38]: (array([ 5., 7., 9., 15., 21., 19., 12., 6.,
                                                           3., 3.]),
          array([ 5.6756163, 6.182397 , 6.6891775, 7.1959577, 7.7027383,
                  8.209518 , 8.716299 , 9.22308 , 9.72986 , 10.236641 ,
                 10.743422 ], dtype=float32),
          <a list of 10 Patch objects>)
          20.0
          17.5
          15.0
          12.5
          10.0
           7.5
           5.0
           2.5
           0.0
                                8
                                              10
In [39]: | np.mean(y_vals) #approximately around 8
```

Out[39]: 8.0432205

The mean is centered around 8, which is what we got for $P_Y^{M:do(X=2)}$ in 4.2.c and we stated in 4.2.d that the $P_Y^{M:(X=2)}$ distribution doesn't change much to $P_Y^{M:do(X=2)}$ distribution, which is what we see here

4.2.i

```
In [40]: conditioned_model_y = pyro.poutine.condition(scm2, data={"Y": torch.t
ensor(2.0)})
```