

# Implementation & examples

# Gyroscope

- ▶  $\alpha$  • z axis •  $0^\circ$ - $360^\circ$
- ▶  $\beta$  • x axis •  $-180^\circ$ - $180^\circ$
- ▶  $\gamma$  • y axis •  $-90^\circ$ - $90^\circ$

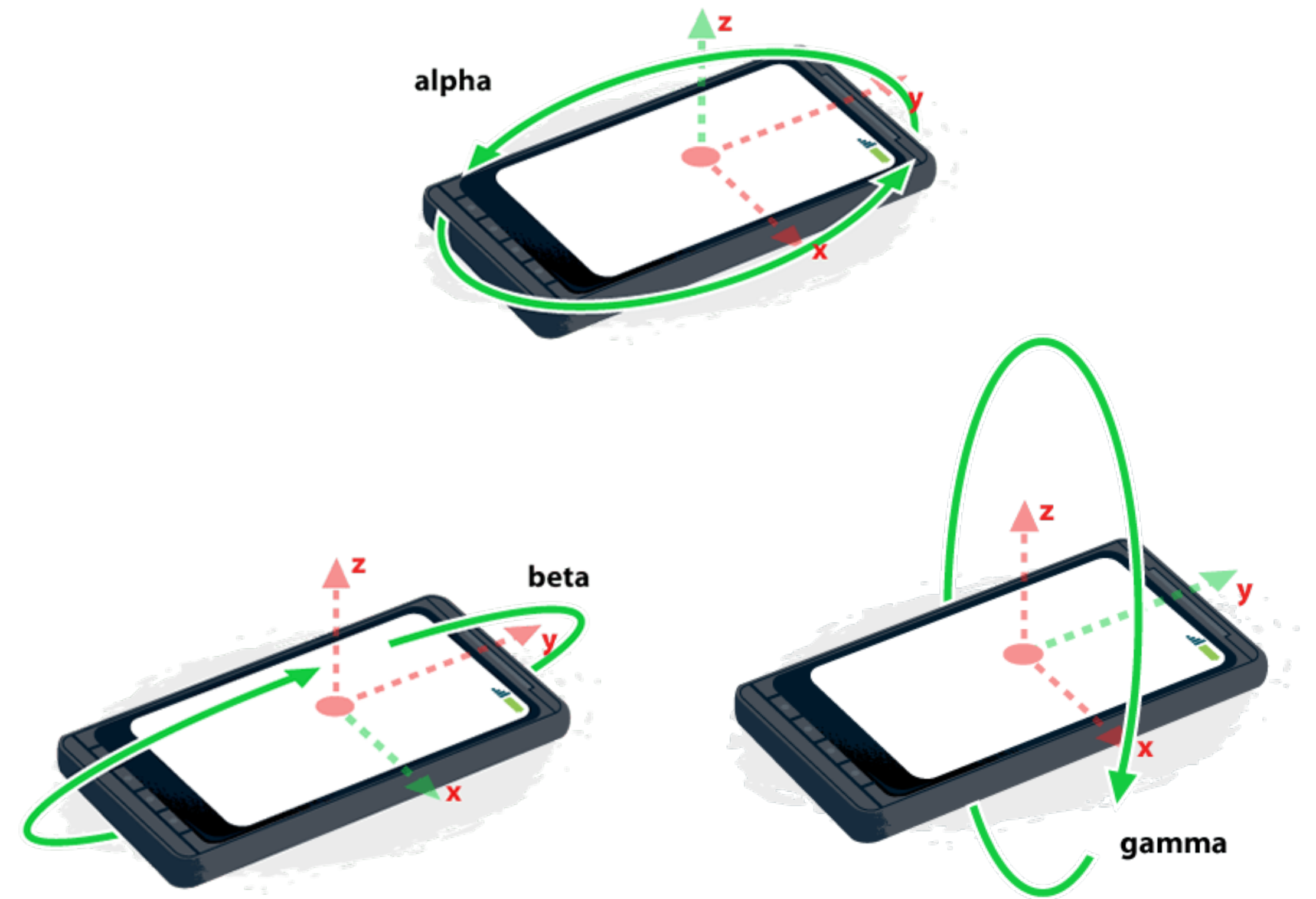


image source: <https://web.dev/generic-sensor/>